

Interpretability and Visualization of Deep Neural Networks

Aude Oliva
MIT

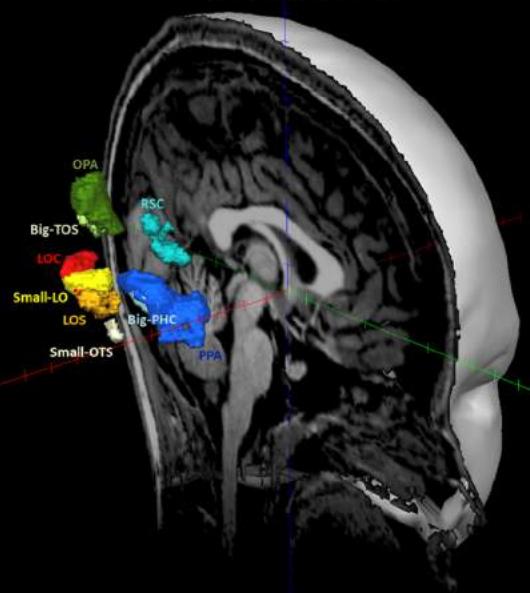


MIT-IBM Watson AI Lab

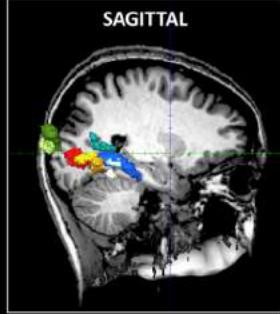




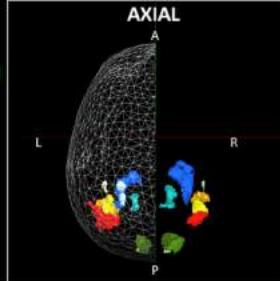
RIGHT ISOMETRIC VIEW



SAGITTAL



AXIAL



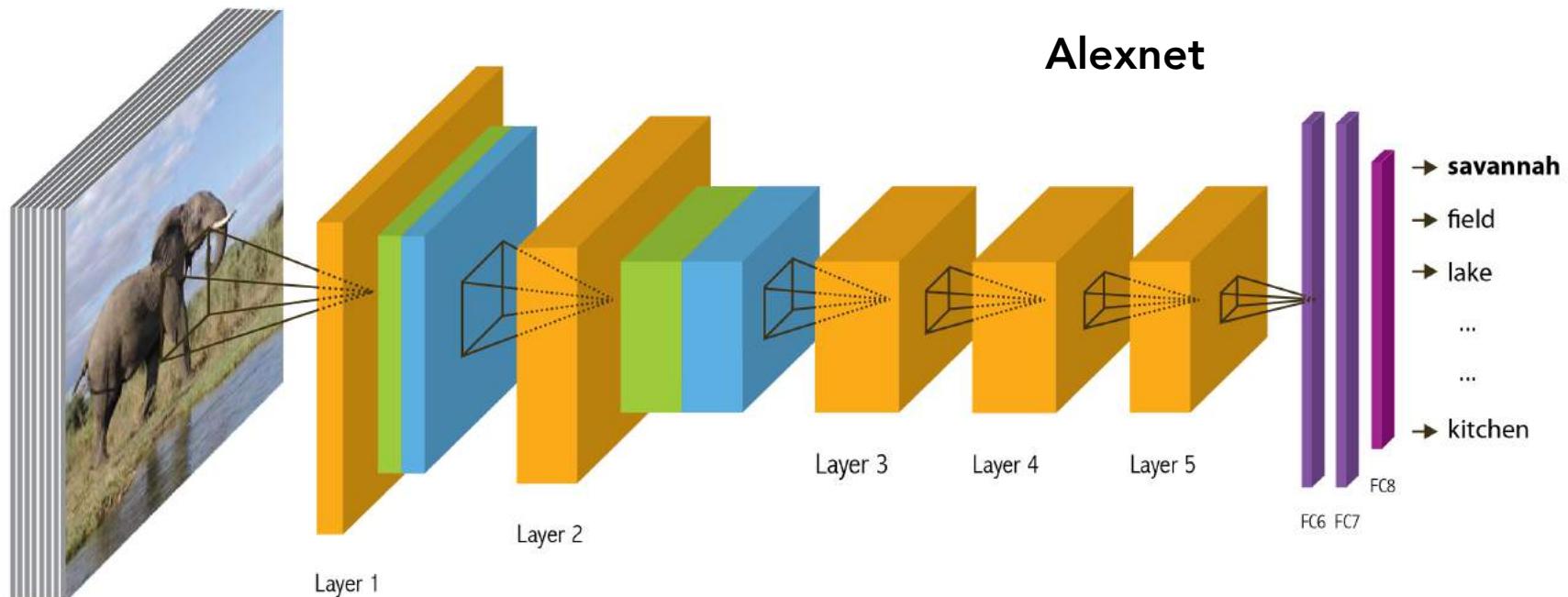


IMAGENET

places

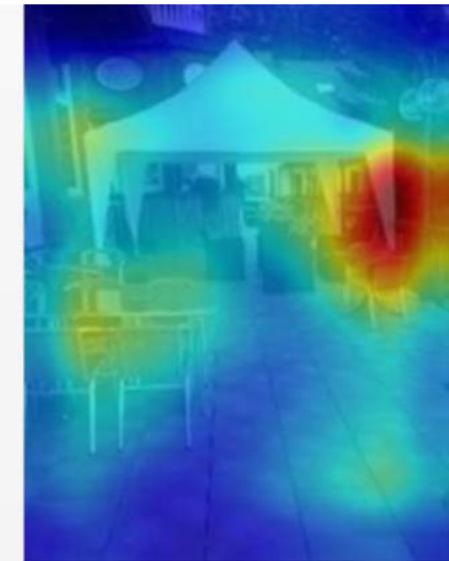
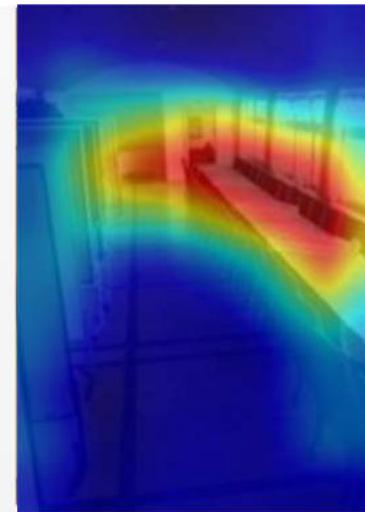
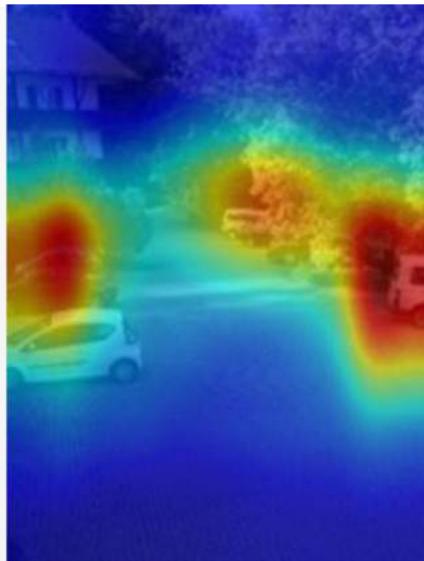
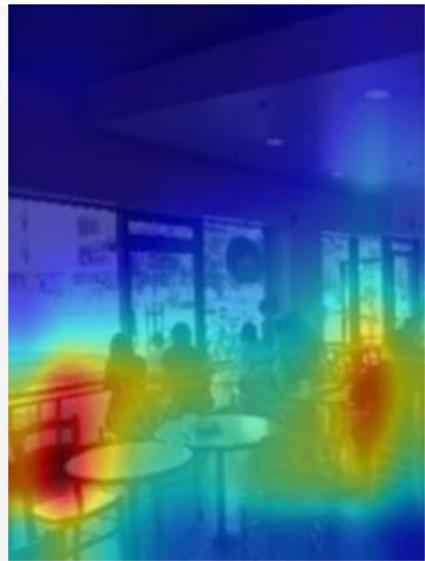
Convolutional Neural Networks

convolution max-pooling normalization full connected



Each layer learns progressively more complex features

places

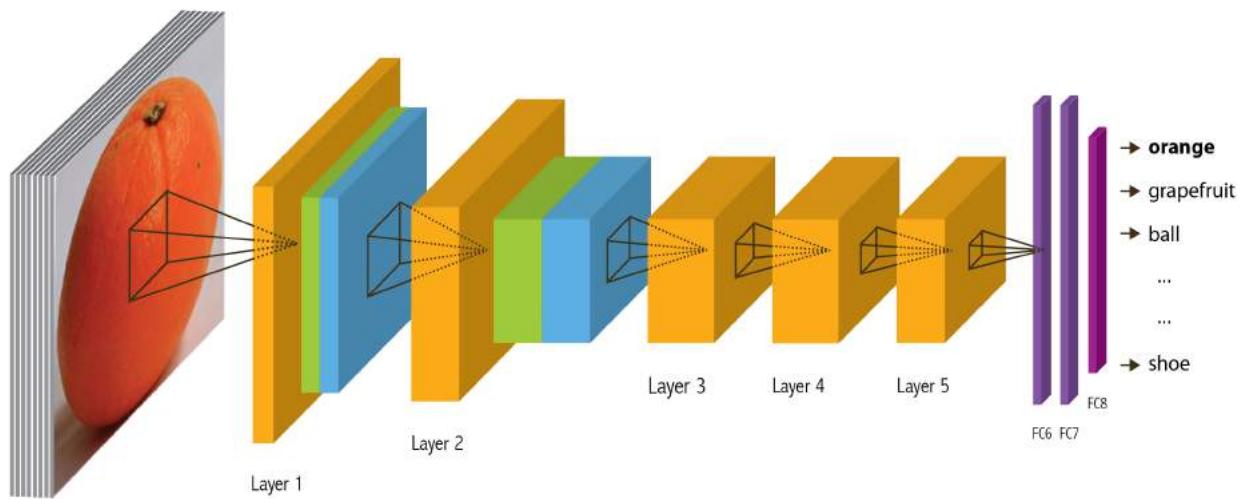


What did the network learn ?

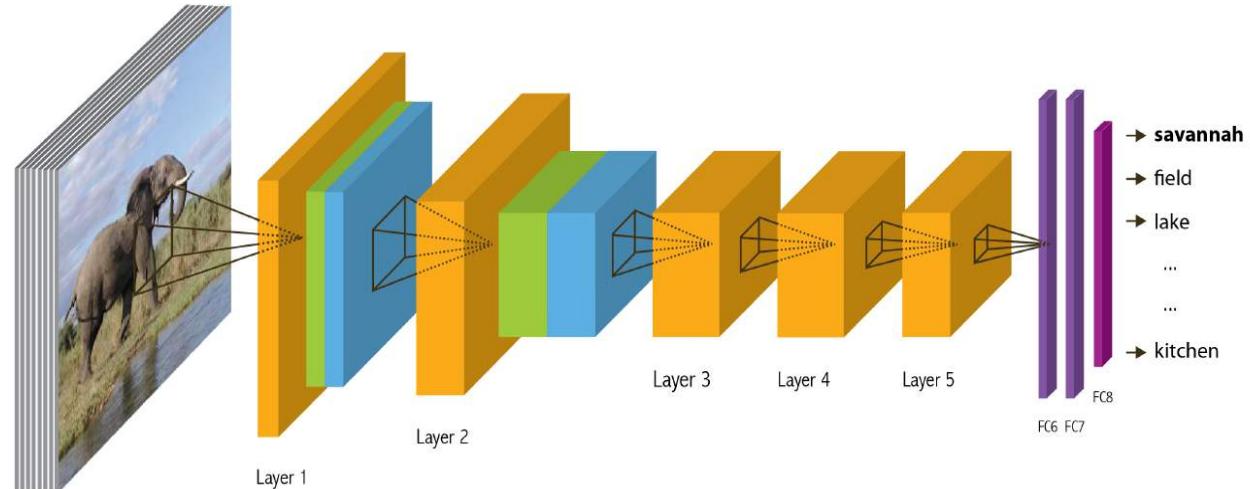
Comparing Object and Scenes CNNs



IMAGENET



places



Data driven approach inspired by Neuroscience: Empirical receptive field



Pipeline for estimating the Receptive Fields:

Goal is to identify which regions of the image lead to the high unit activations.



sliding-window stimuli

5000 occluded versions

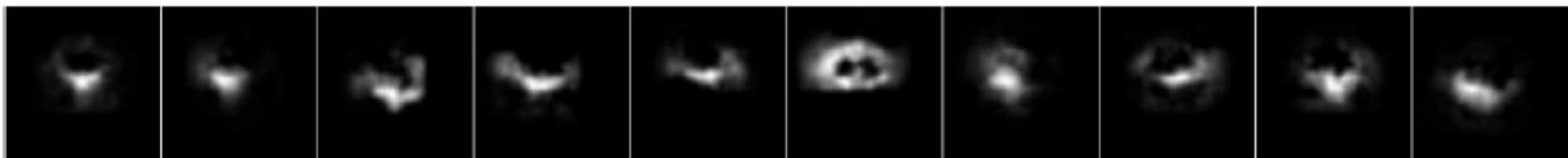
Discrepancy map per unit



Pipeline for estimating the Receptive Fields



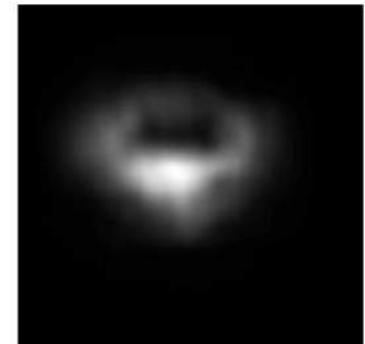
discrepancy maps for top 10 images



calibrated discrepancy maps

To consolidate the information from several images, we center the discrepancy map around the spatial location of the unit that caused the maximum activation for the given image.

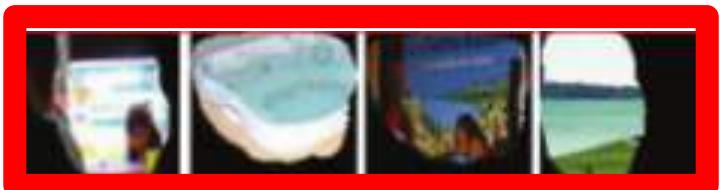
Then we average the re-centered discrepancy maps to generate the final receptive field of each given unit.



receptive field

Annotating the Semantics of Units

Pool5, unit 76; Label: ocean; Type: scene; Precision: 93%



Annotating the Semantics of Units

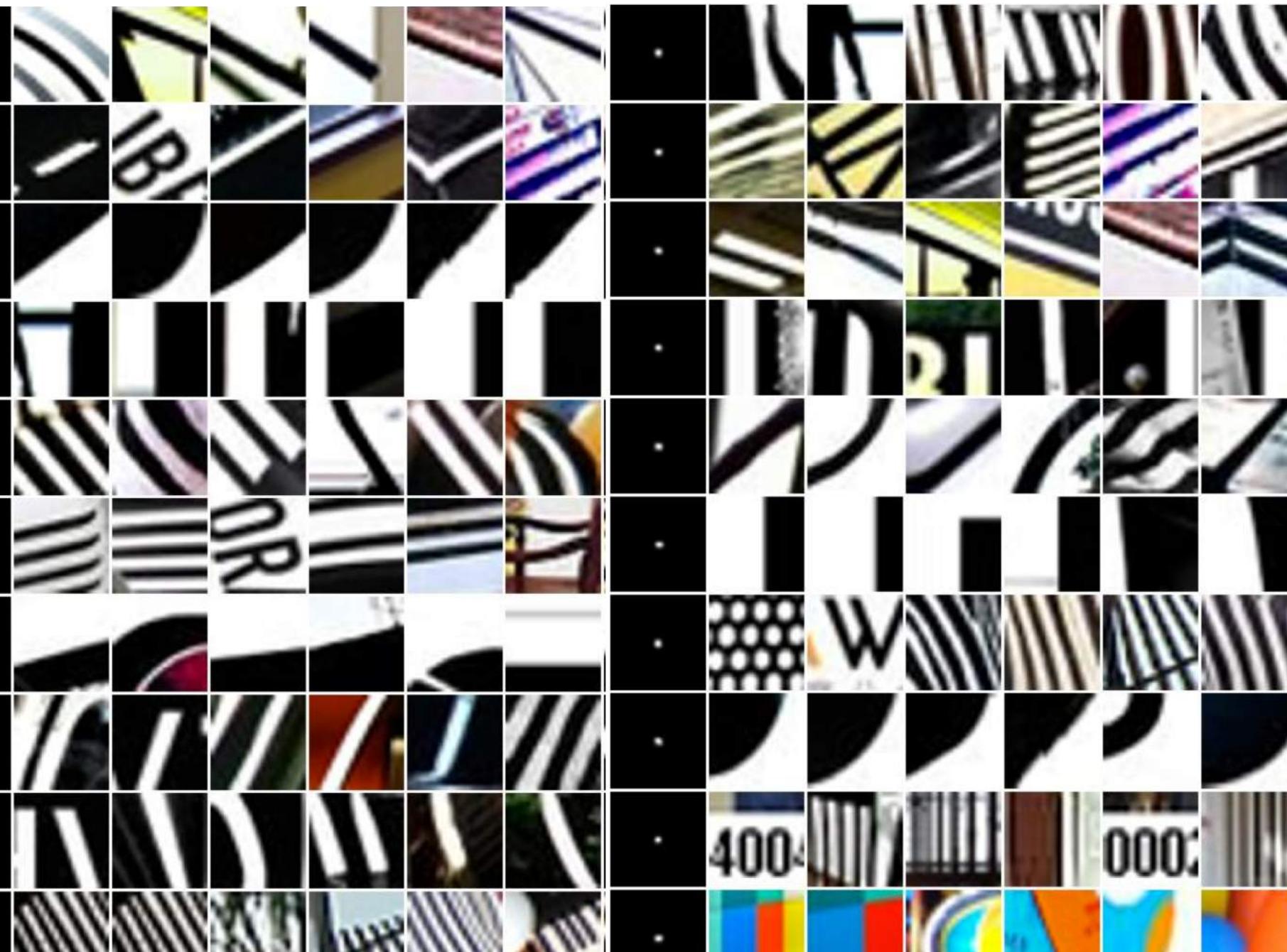
Pool5, unit 13; Label: Lamps; Type: object; Precision: 84%

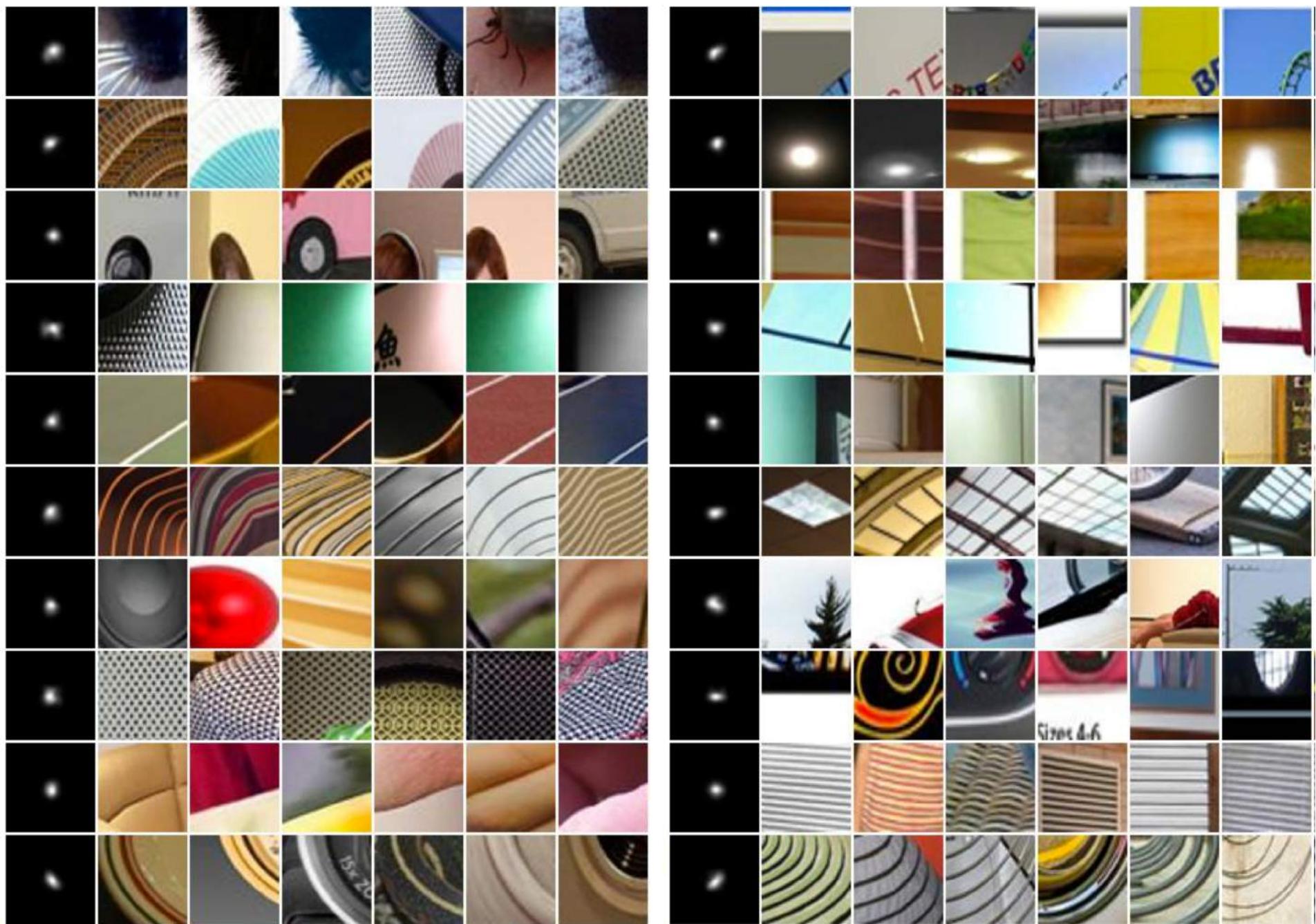


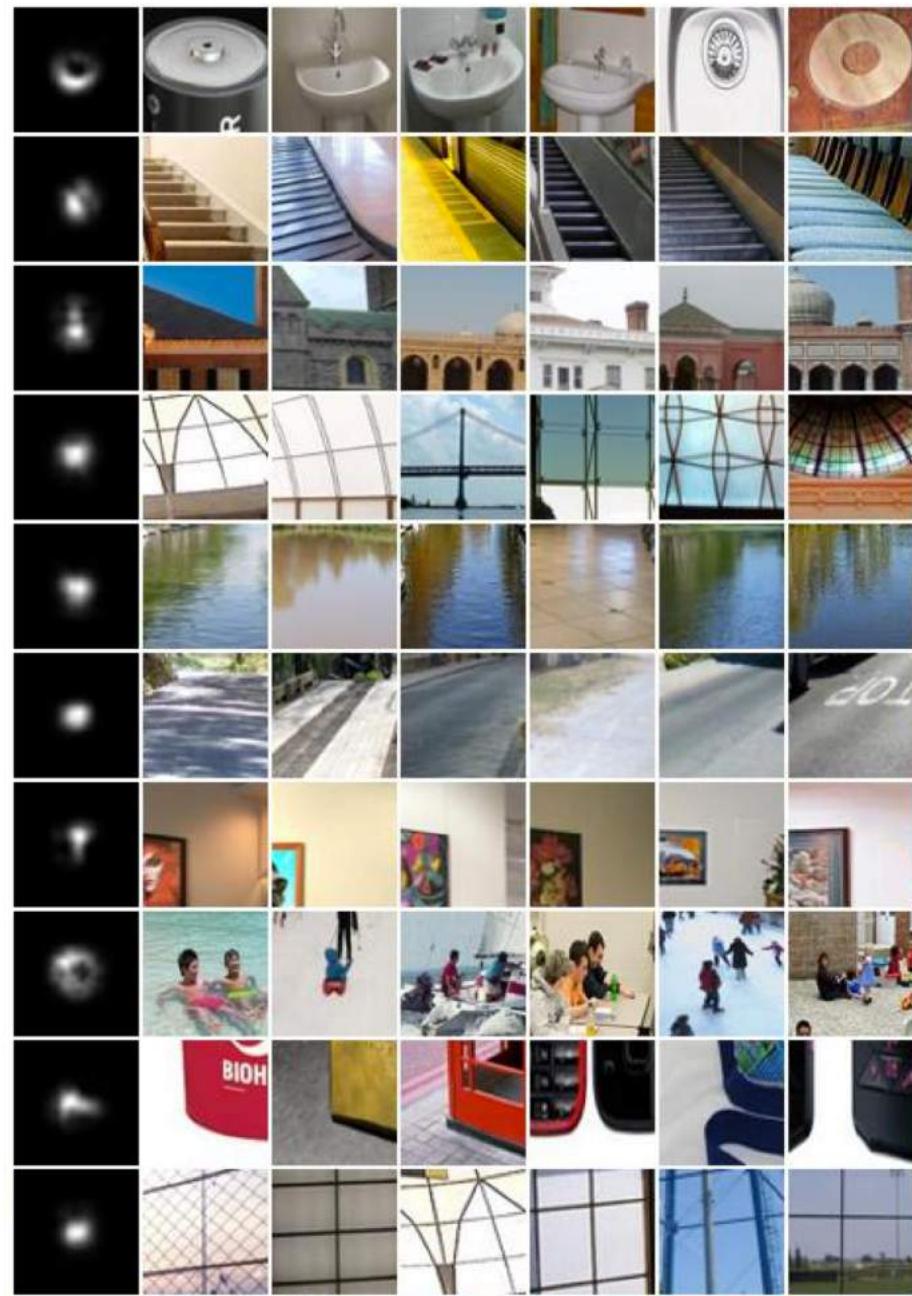
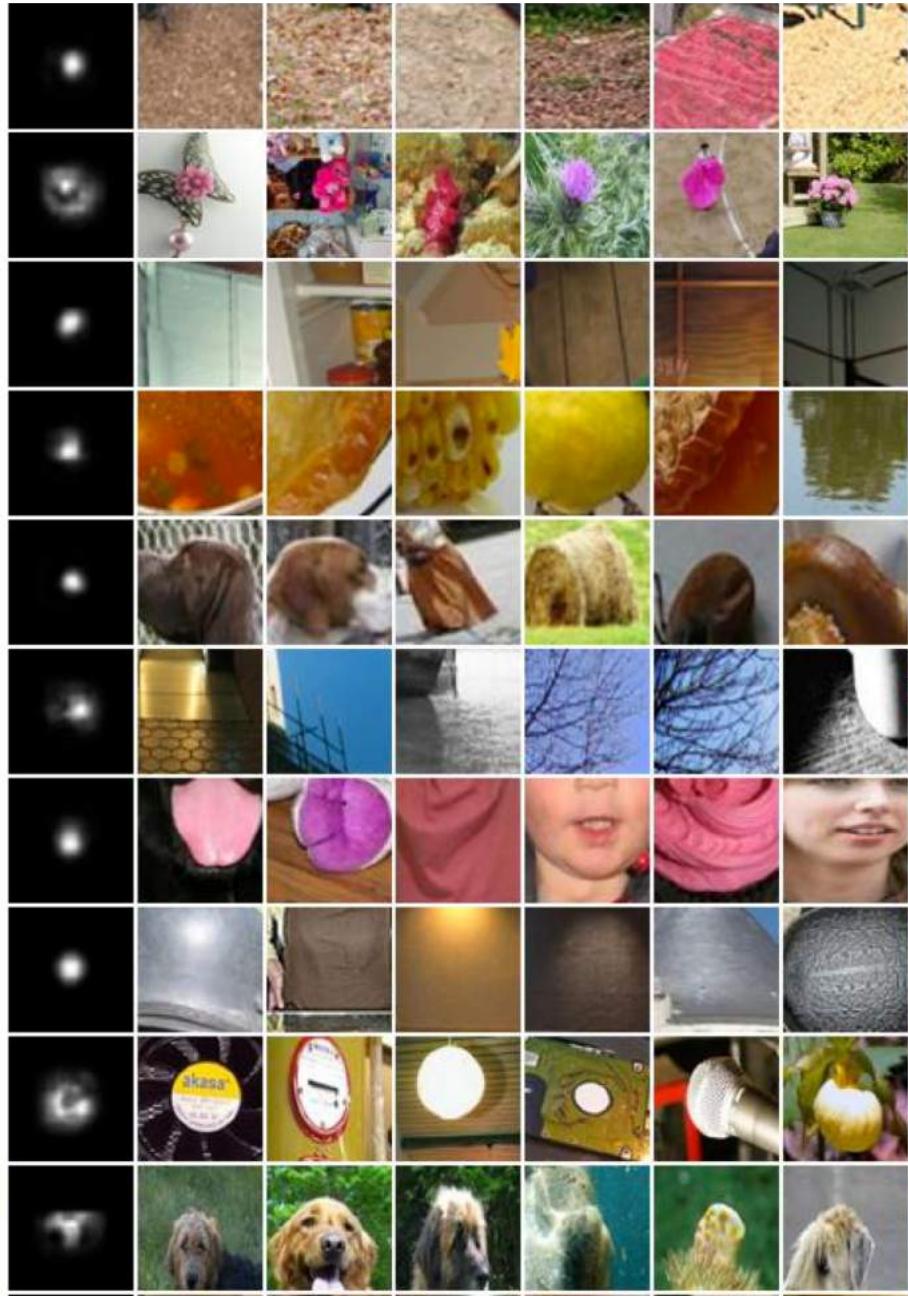
Annotating the Semantics of Units

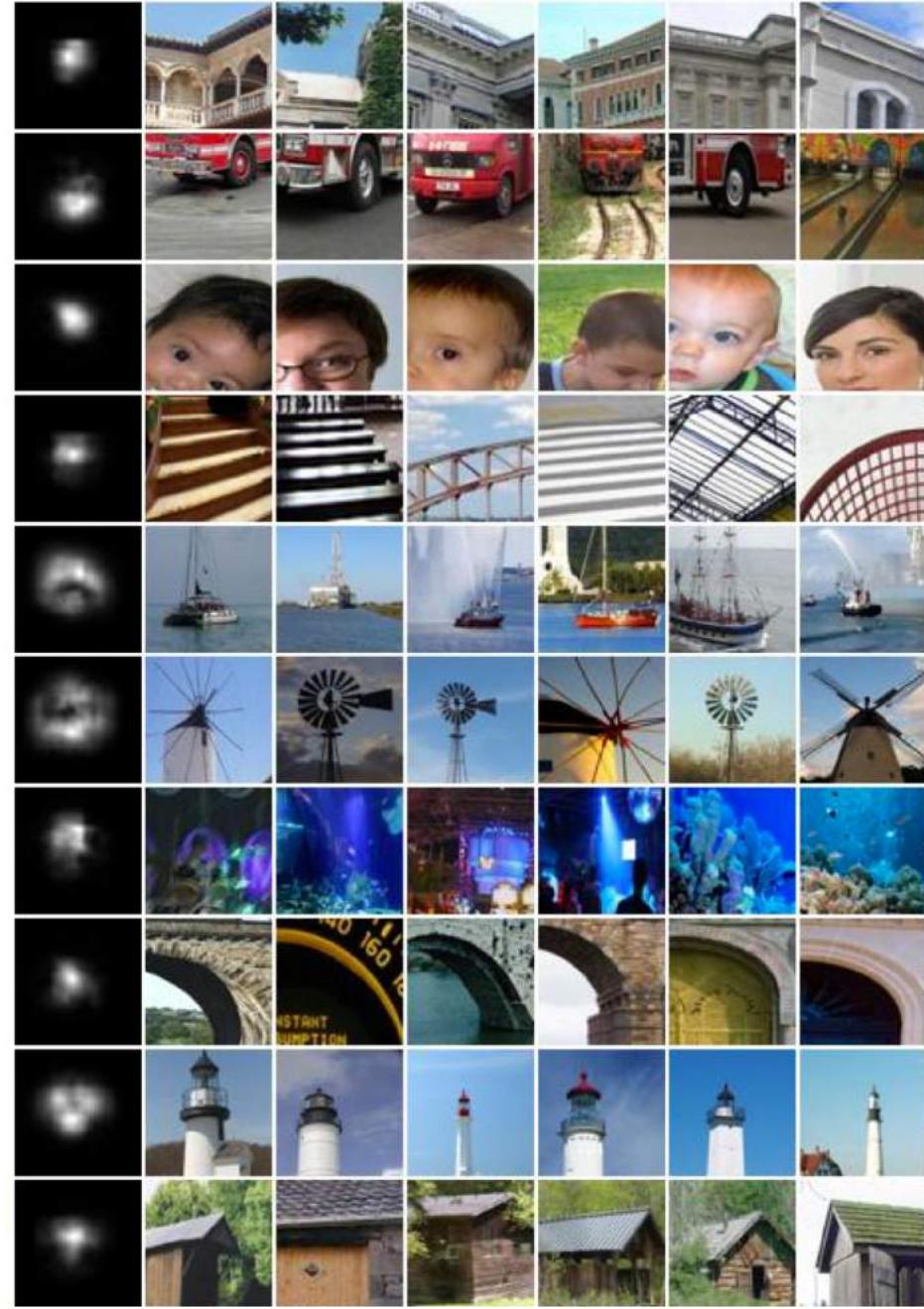
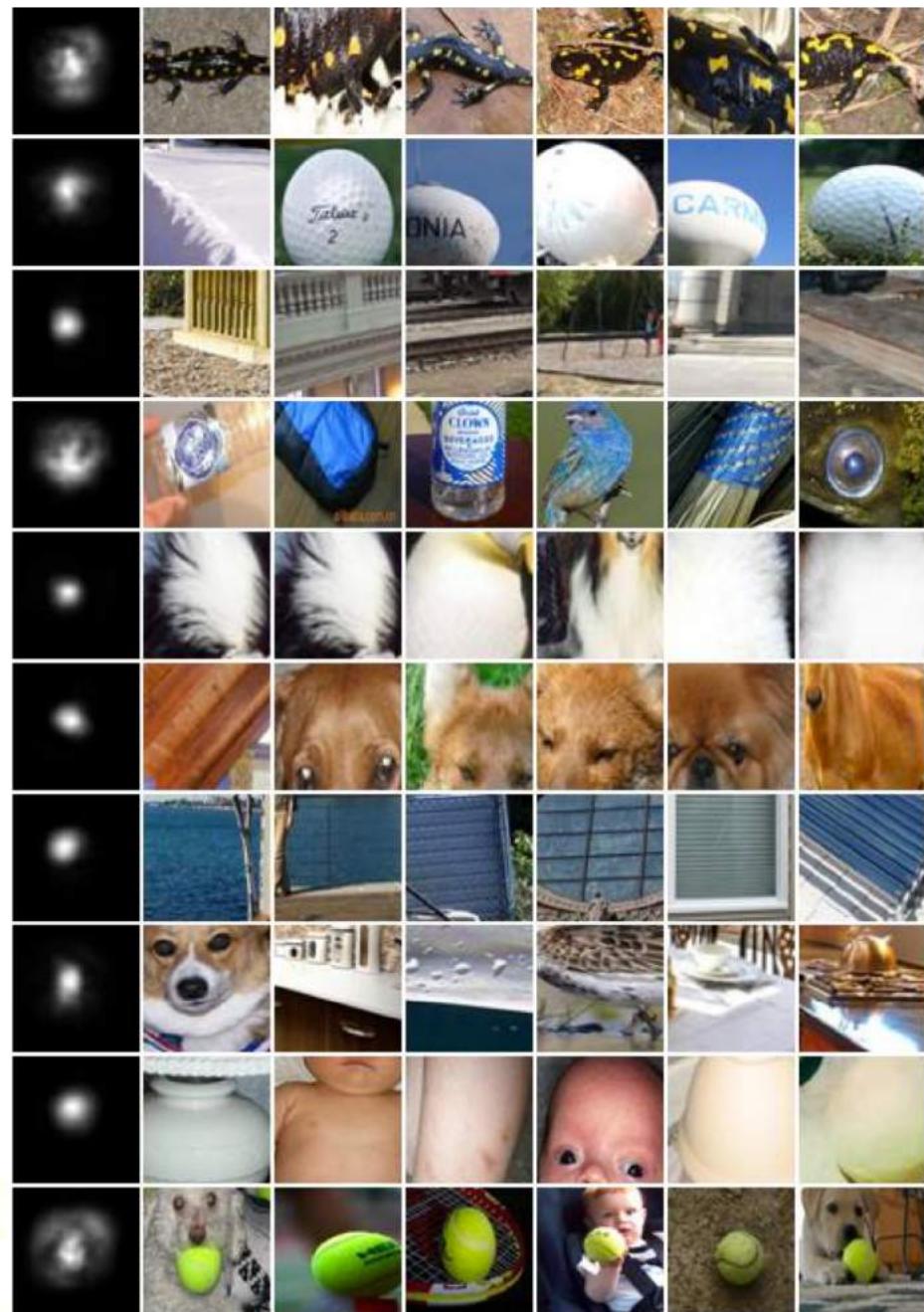
Pool5, unit 77; Label: legs; Type: object part; Precision: 96%



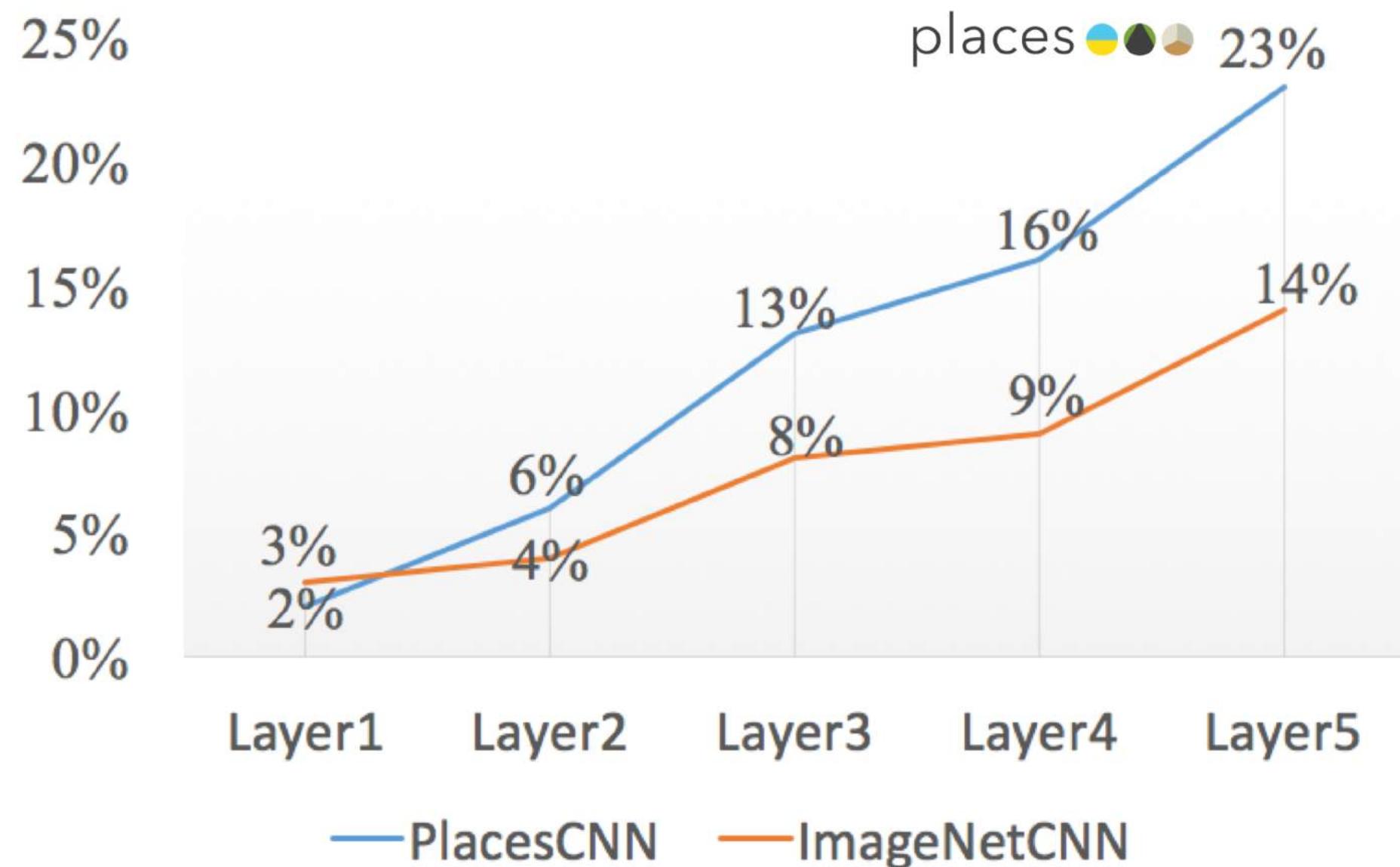








% Units as Detectors for Objects

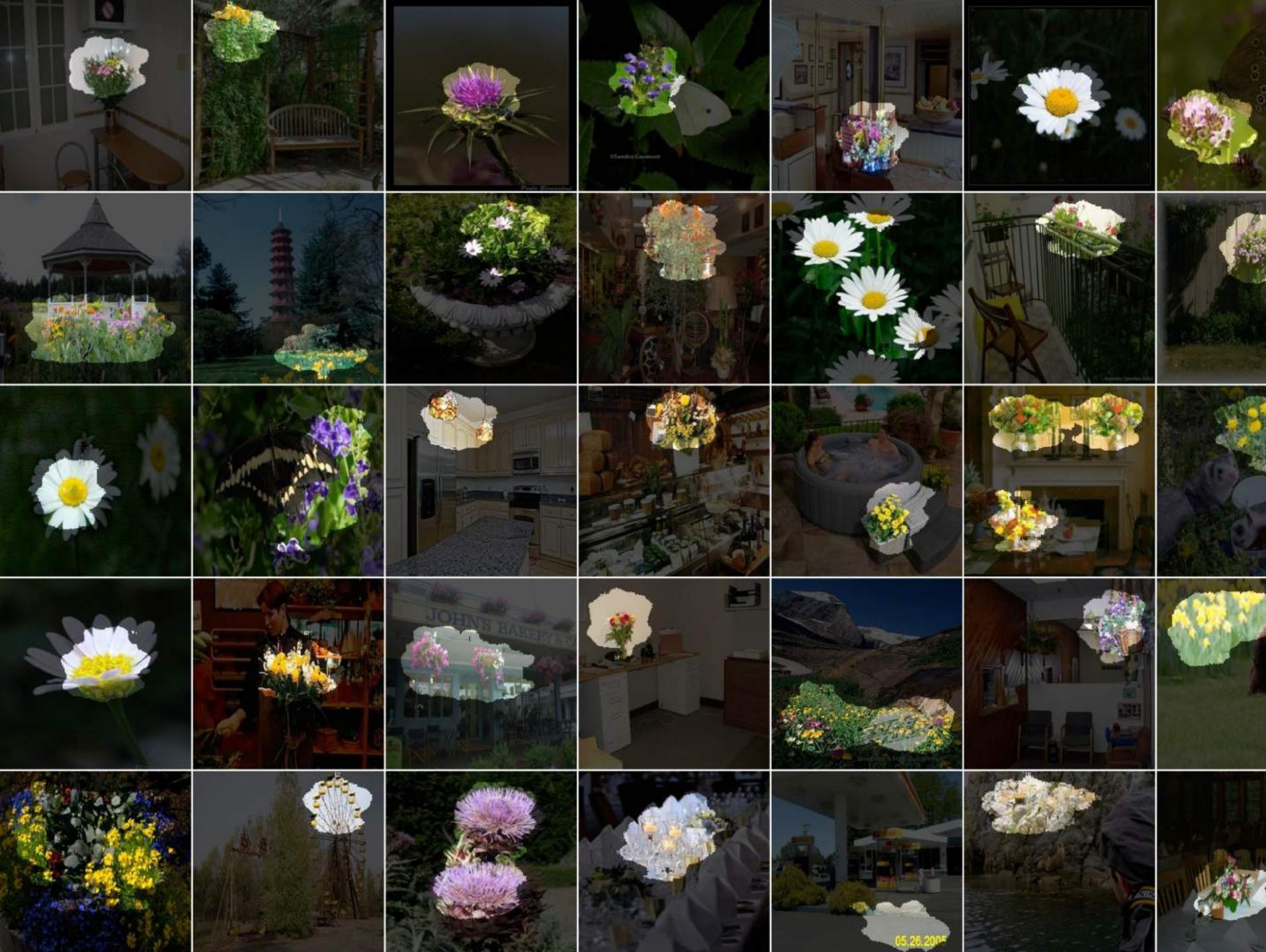






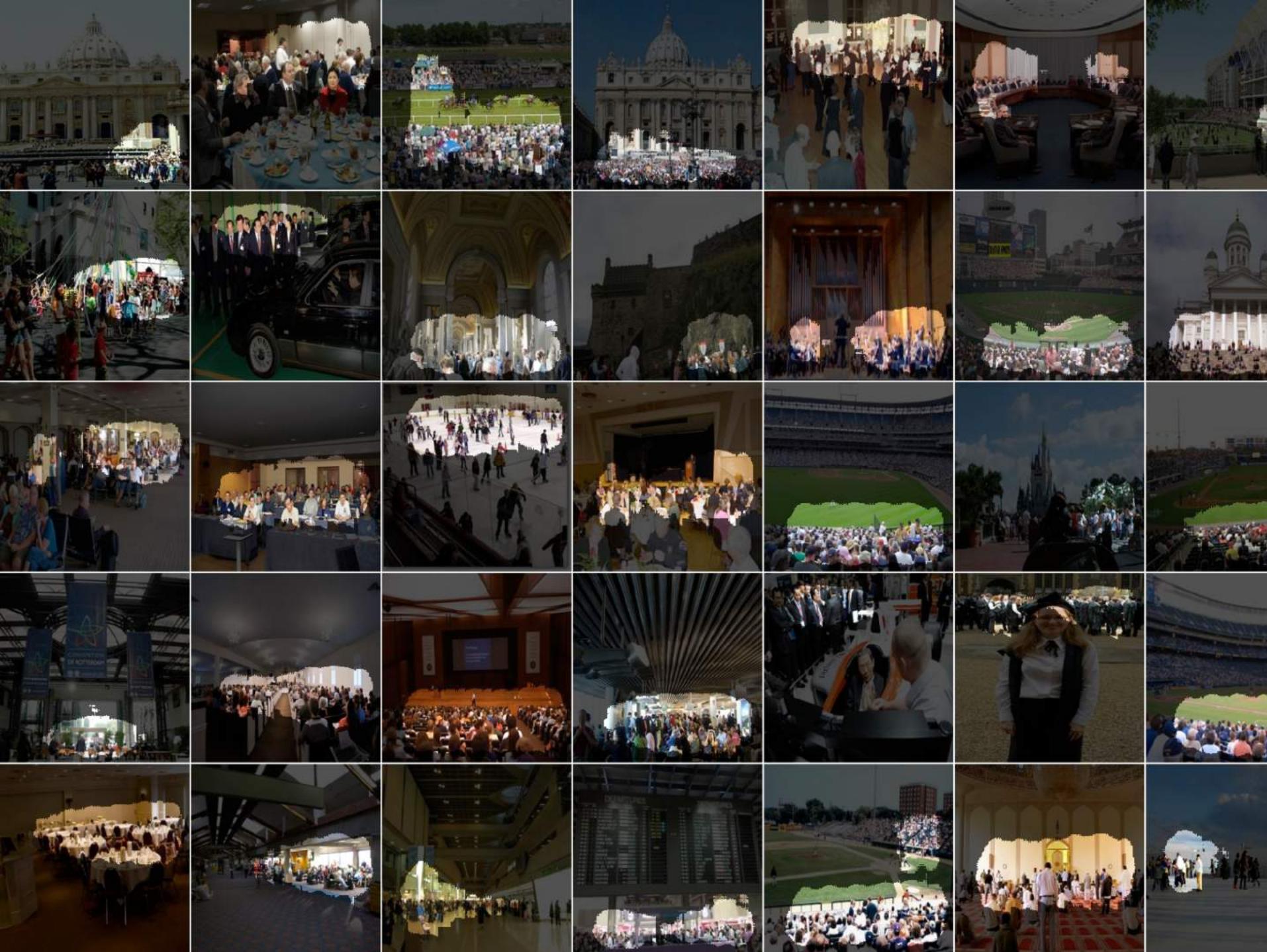


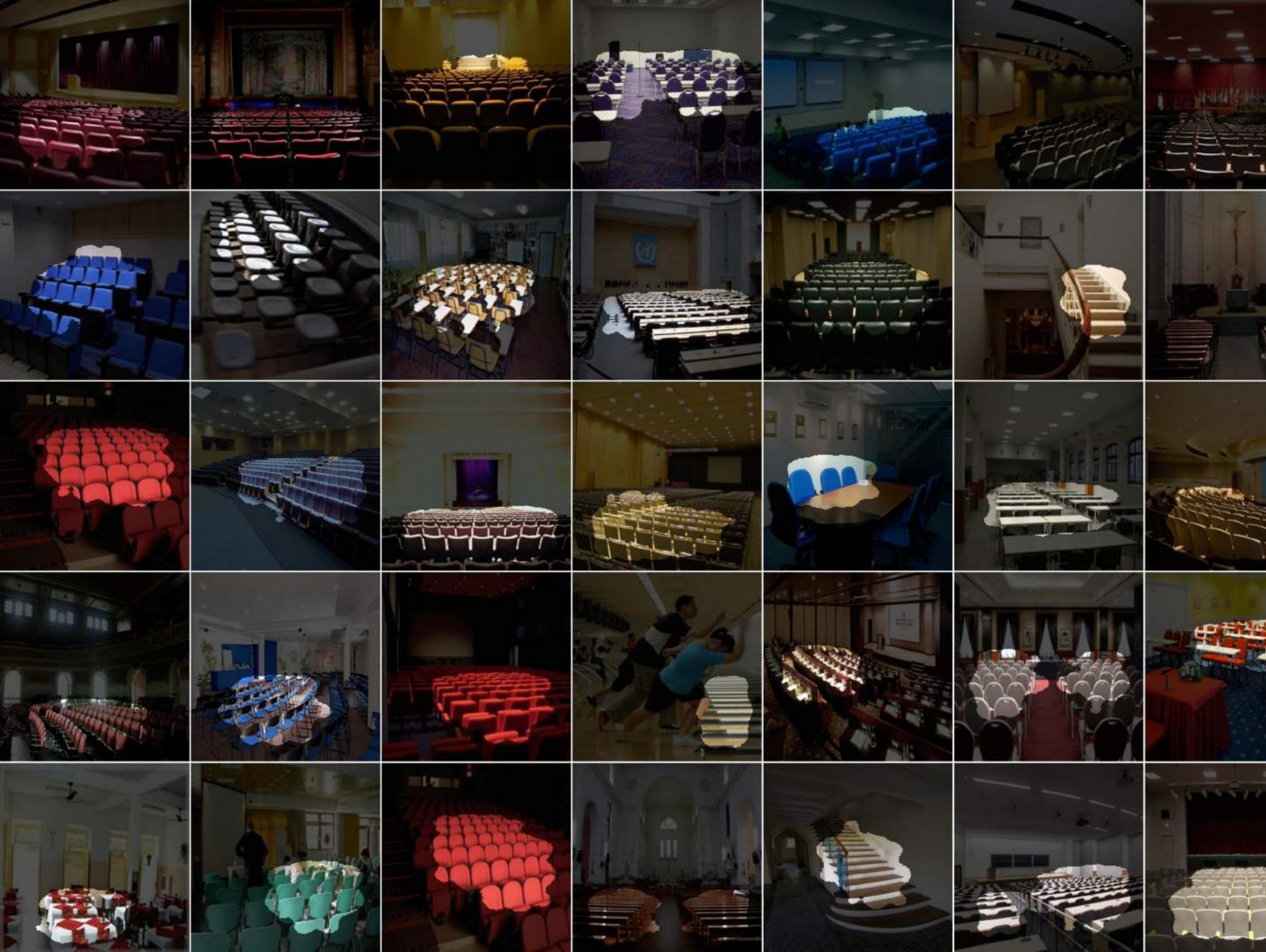












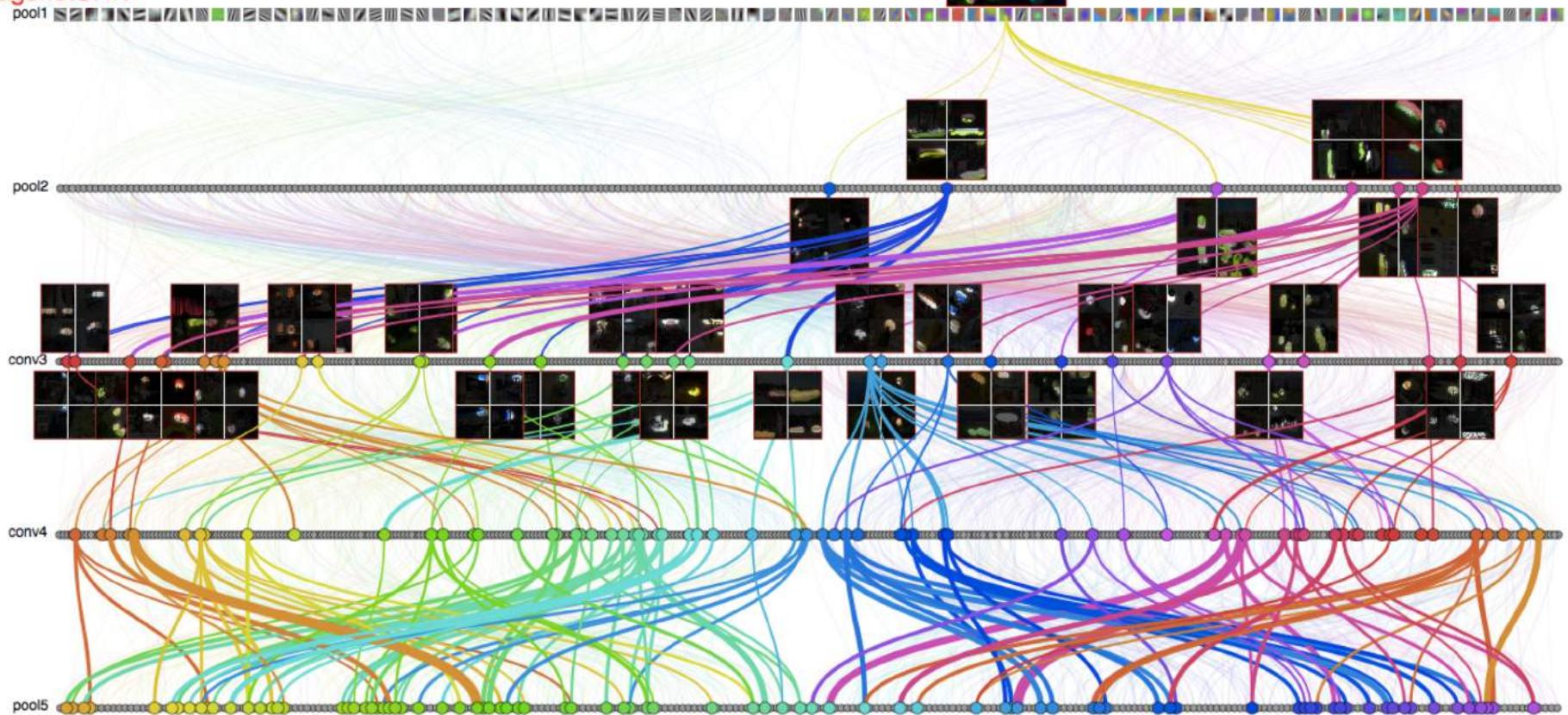




Visualizing Units & Connections

drawNet

imagenetCNN



<http://people.csail.mit.edu/torralba/research/drawCNN/drawNet.html>

Network Dissection: Quantifying Interpretability of Deep Visual Representations

David Bau*, Bolei Zhou*, Aditya Khosla, Aude Oliva, Antonio Torralba

Massachusetts Institute of Technology

<http://netdissect.csail.mit.edu/>



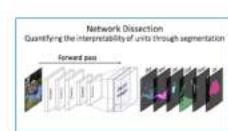
Code and Data



CVPR 2017 paper



CVPR 2017 poster



CVPR 2017 slides

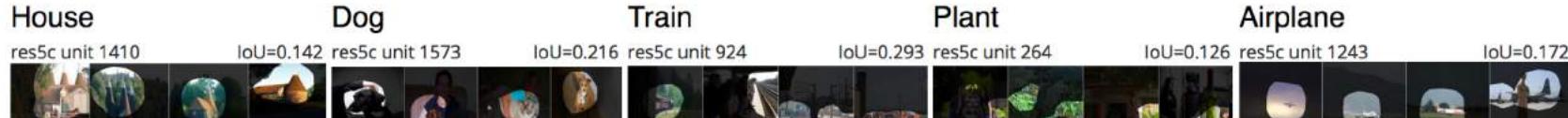


CVPR 2017 oral



Extended paper

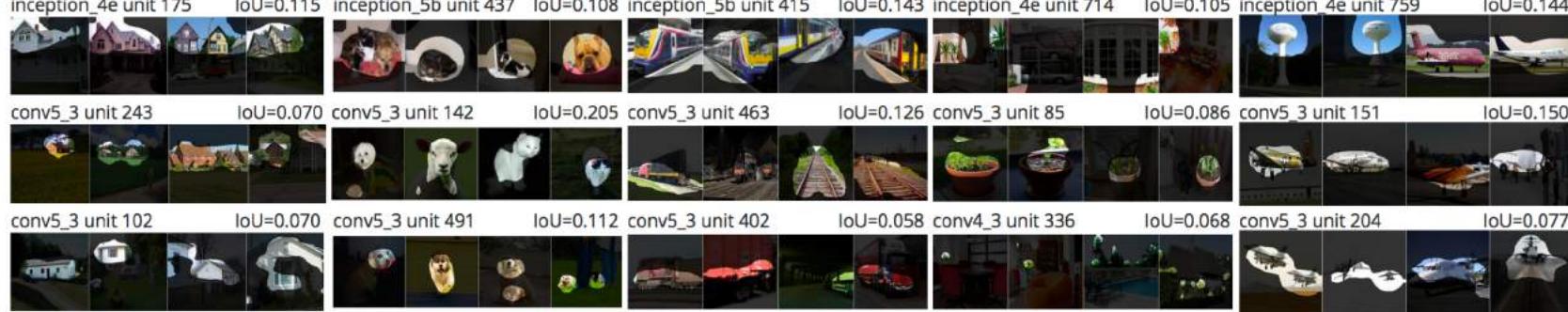
ResNet-152



GoogLeNet

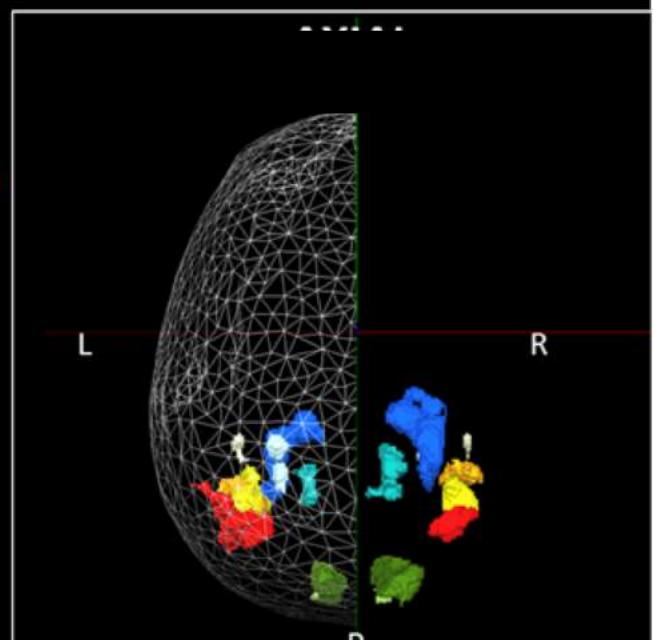
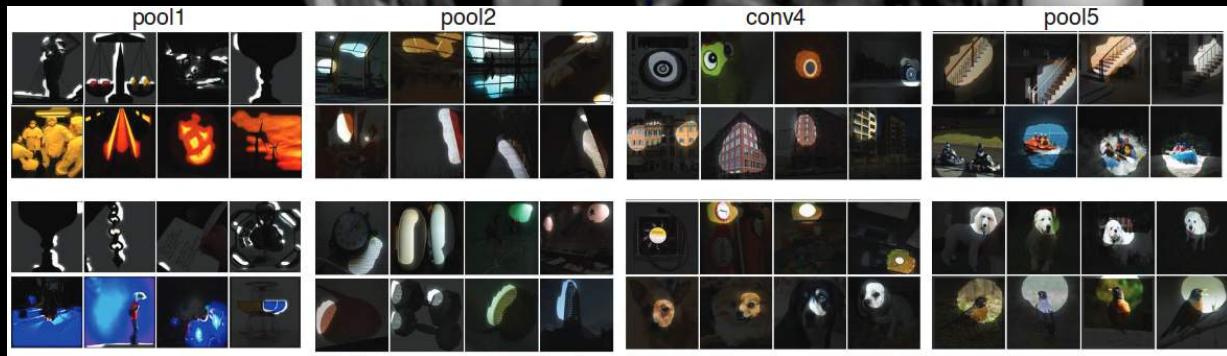
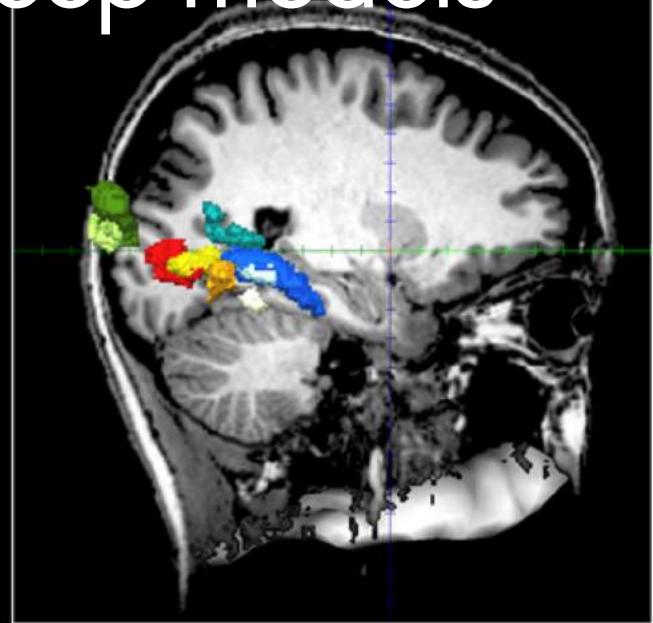
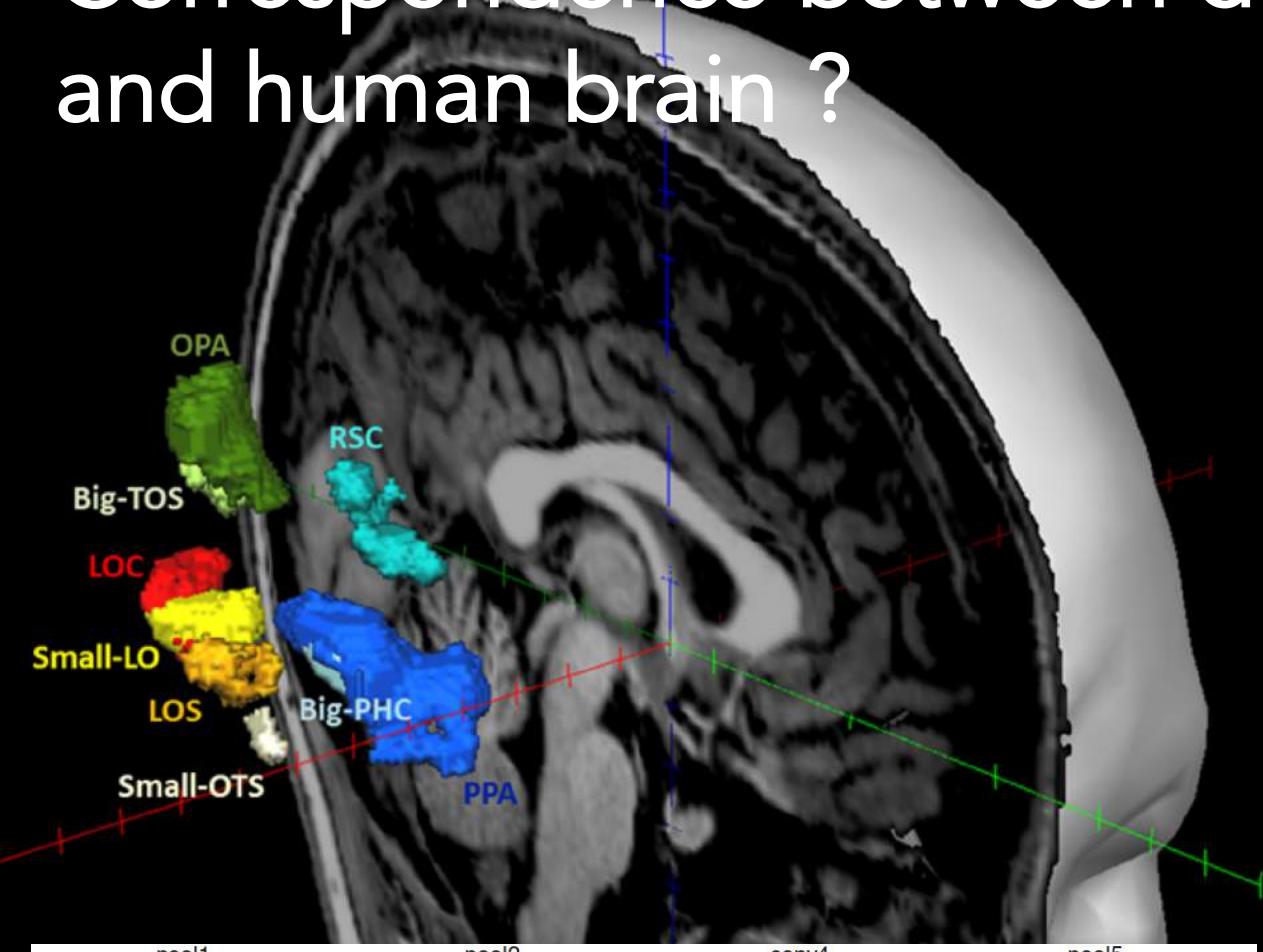


VGG-16



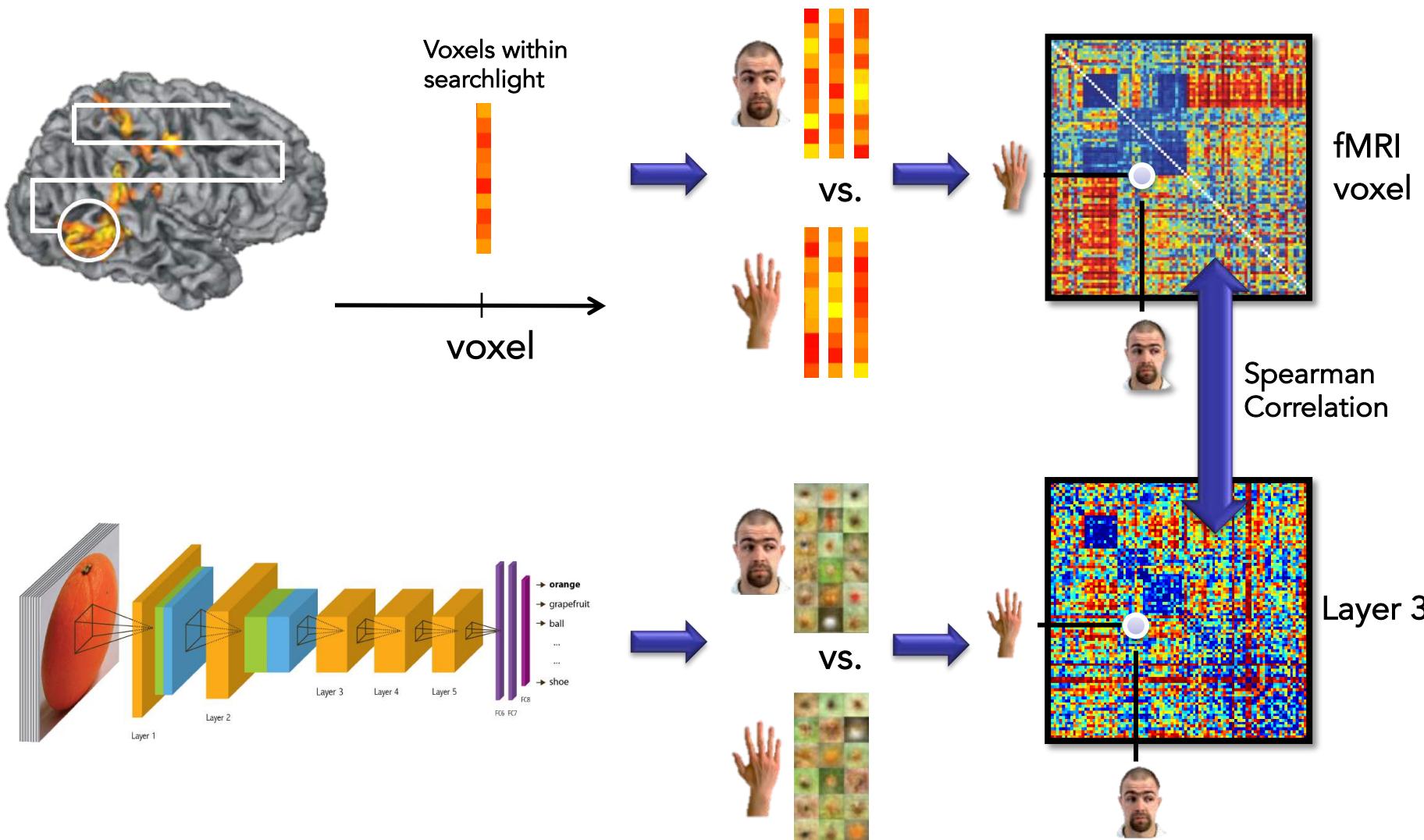
Selected units are shown from three state-of-the-art network architectures when trained to classify images of places ([places-365](#)). Many individual units respond to specific high-level concepts (object segmentations) that are not directly represented in the training set (scene classifications).

Correspondence between deep models and human brain ?



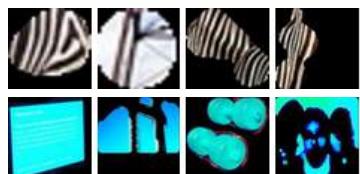
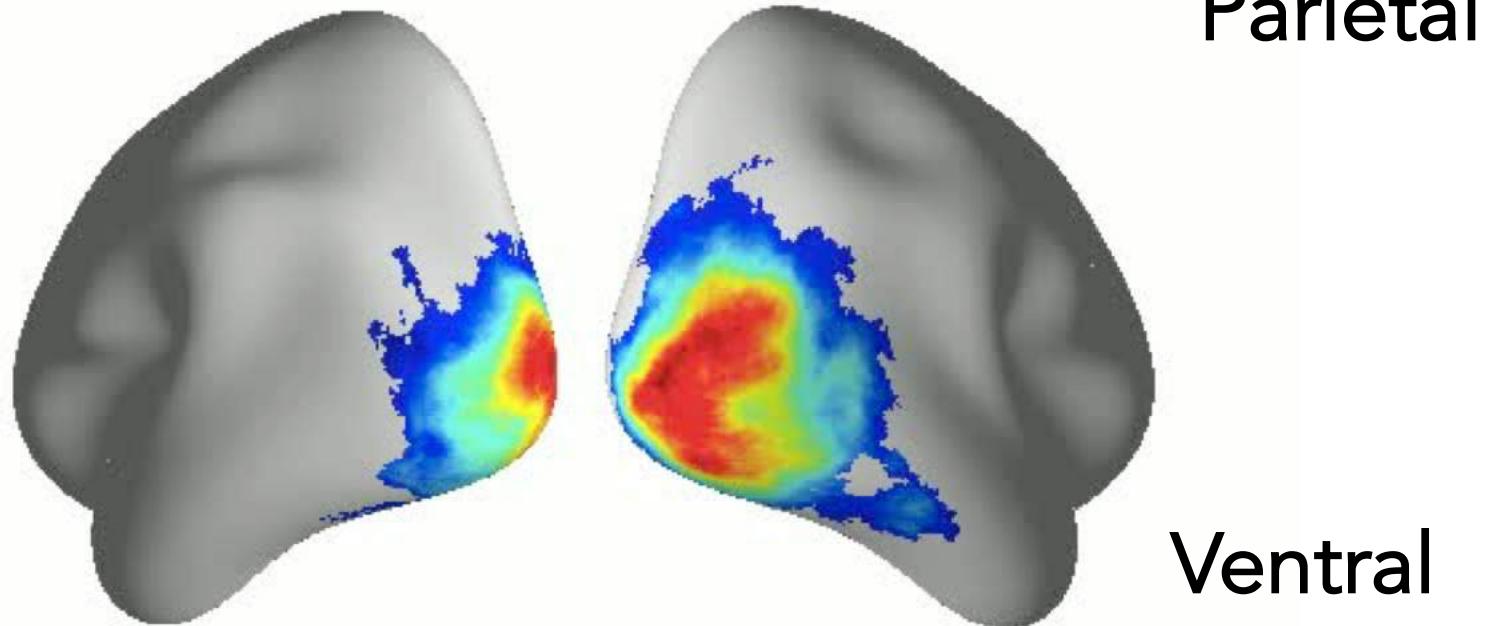
Algorithmic-specific fMRI searchlight analysis

A spatially unbiased view of the relations in similarity structure
between models and fMRI



Spatiotemporal maps of correlations between human brain and model layers

Layer 1



Layers 1-2



Layers 2-4



Layers 5-8

Comparing Natural and Artificial Deep Neural Networks

- New fields of expertise: Cognitive / Clinical / Social / Perceptual Computational Experimentalist
- Studying the implementation that works best for performing specific tasks
- Characterizing the network behavior when it is adapting, compromised or enhanced
- Exploring the alternatives that have not been taken by biological systems



Bolei
Zhou



David
Bau



Aditya
Khosla



Radoslaw
Cichy



Antonio
Torralba