

QUESTION 1

(a) GOLDEN SECTION METHOD-MINIMIZATION

```
syms x
figure; hold on;
a=0; % start of interval
b=2; % end of interval
epsilon=0.000001; % accuracy value
iter= 50; % maximum number of iterations
tau=double((sqrt(5)-1)/2); % golden proportion coefficient, around 0.618
k=0; % number of iterations
f = @(x) x^.2 + x.^3 % The assumed function I used
x1=a+(1-tau)*(b-a); % computing x values
x2=a+tau*(b-a);

f_x1=f(x1); % computing values in x points
f_x2=f(x2);

plot(x1,f_x1, '*') % plotting the function with x_min
plot(x2,f_x2, '*')
while ((abs(b-a)>epsilon) && (k<iter))
    k=k+1;
    if(f_x1<f_x2)
        b=x2;
        x2=x1;
        x1=a+(1-tau)*(b-a);

        f_x1=f(x1);
        f_x2=f(x2);

        plot(x1,f_x1, '*');
    else
        a=x1;
        x1=x2;
        x2=a+tau*(b-a);

        f_x1=f(x1);
        f_x2=f(x2);

        plot(x2,f_x2, '*')
    end
    k=k+1;
end
```

```

% chooses minimum point
if(f_x1<f_x2)
    sprintf('x_min=% f', x1)
    sprintf('f(x_min)=% f ', f_x1)
    plot(x1,f_x1,'ro')
else
    sprintf('x_min=% f', x2)
    sprintf('f(x_min)=% f ', f_x2)
    plot(x2,f_x2,'ro')
end

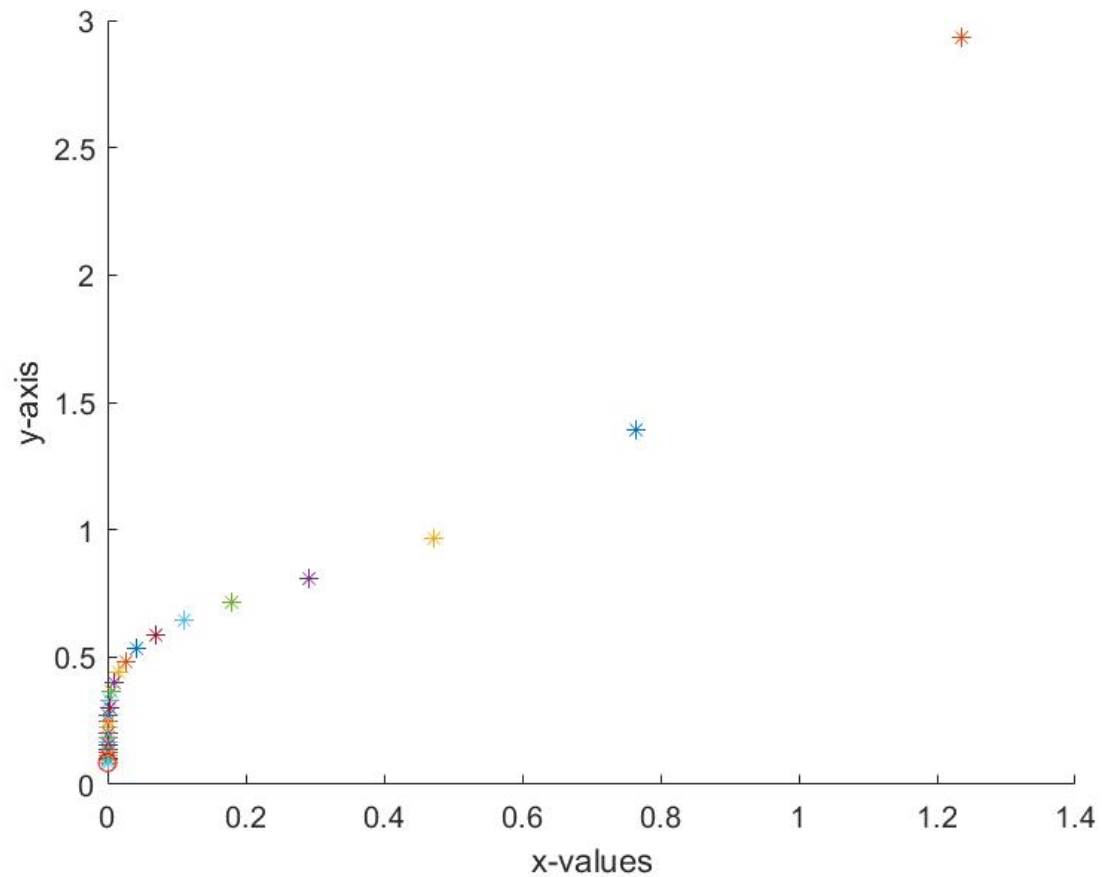
```

OUTPUT

```

ans = 'x_min= 0.000005'
ans = 'f(x_min)= 0.085442 '

```



(b) QUADRATIC INTERPOLATION METHOD

```
clear all

f = @(x)(x^2 + x^3) % The same function as in part A
% The x-points values
x1 = 1;
x2 = -0.5;
x3 = 2;
tol = 10^-6;

% Invoking function
quadratic_interpolation(f, x1, x2, x3, tol)
```

I created a function below

```
function quadratic_interpolation(f, x1, x2, x3, tol)
fx1 = f(x1);
fx2 = f(x2);
fx3 = f(x3);
if (fx1 > fx2 && fx2 < fx3)
    cond = true;
    iterations = 1;
    while(cond)
        syms a b c
        fx1 = f(x1);
        fx2 = f(x2);
        fx3 = f(x3);

        % Quadratic interpolation in the form of a second-order polynomial
        y(x) = a + bx + cx^2

        % a, b, c is calculated from the following linear equations
        eq1 = a + x1*b + x1^2 * c == fx1;
```

```

eq2 = a + x2*b + x2^2 * c == fx2;
eq3 = a + x3*b + x3^2 * c == fx3;
sol = solve([eq1, eq2, eq3], [a, b, c]);
aS = sol.a;
bS = sol.b;
cS = sol.c;

xOpt = -(bS/(2*cS));
parabolaOpt = aS + bS*xOpt + cS*(xOpt^2);
fxOpt = f(xOpt);
vars = [x1 x2 x3 xOpt];

cond = (abs(fxOpt - parabolaOpt) > tol);
    if (cond)
        iterations = iterations + 1;
        % Calculating new points
        vSorted = sort(vars);
        vSIndice = find(vSorted==xOpt);
        vSortedLeft = vSorted(:,1:(vSIndice-1));
        vSortedRight = vSorted(:, (vSIndice+1:end));
        x1 = max(vSortedLeft);
        x2 = xOpt;
        x3 = min(vSortedRight);
    end
end
fprintf('Optimal x* = %.4f \n', x2)
fprintf('No. of iterations = %d \n', iterations)
else
    disp('f(x1) > f(x2) && f(x2) < f(x3) not satisfied')
end
end
end

```

OUTPUT

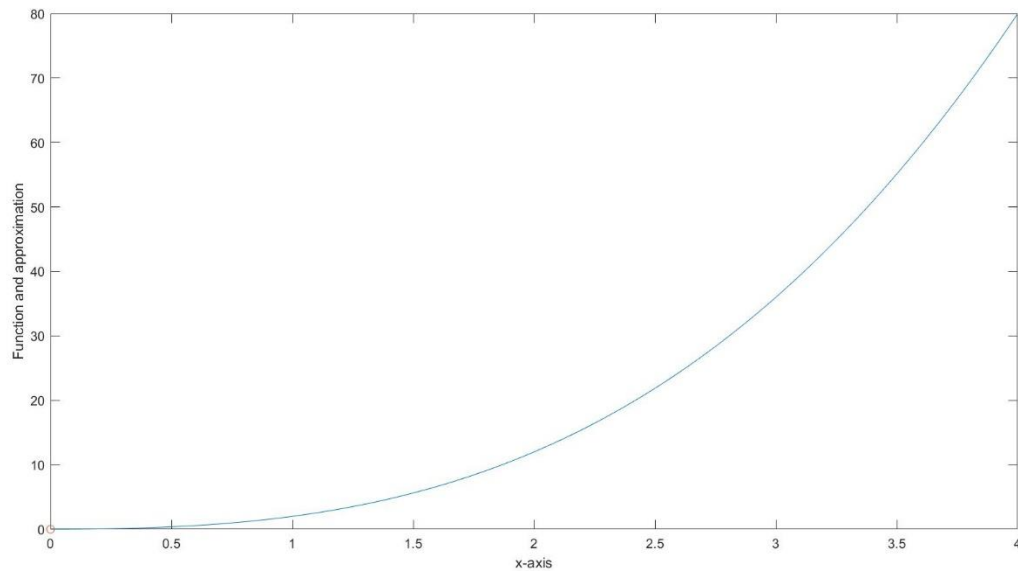
```
f = function_handle with value:  
    @(x) (x^2+x^3)  
Optimal x* = -0.0023  
No. of iterations = 6
```

(c) NEWTON METHOD

```
f = @(x) (x^2 + x^3);  
% x_(n+1) = x_(n) - f'(x_n)/f''(x_n)  
f1 = @(x) 3*x^2 + 2*x; % first derivative  
f2 = @(x) 6*x + 2; % second derivative  
x = 0.1; % inntial guess  
xx(1) = x;  
err = 0.01; % tolerance  
N= 100 ; % number of Iterations  
for i = 1:N  
    x =x - f1(x)/f2(x) ;  
    j = i +1 ;  
    xx(j) = x; ii = i;  
    Err = abs(xx(j) - xx(j-1));  
    if Err<err , break  
end  
end  
FF = f(x);  
disp(['The Mininum Value at : ' num2str(x) ', is: ' num2str(FF) ', No of  
Iterations: ' num2str(ii)])  
xvalues = 0:0.01:4;  
F = xvalues.^2 + xvalues.^3 ;  
plot(xvalues,F); % plot the given function  
hold on  
plot(x,FF,"o")
```

OUTPUT

```
The Mininum Value at: 5.5854e-08, is: 3.1197e-15, No of Iterations: 3
```



(d) PLOTTING

This is given above already for each methods.

(e) Testing Part a and b

```
% part a
fun = @(x) (x.^2 + x.^3);
x1 = 0;
x2 = 2;
options = optimset("Display","Iter");
x_min = fminbnd(fun,x1,x2,options)
```

OUTOUT

Func-count	x	f(x)	Procedure
1	0.763932	1.02942	initial
2	1.23607	3.41641	golden
3	0.472136	0.328157	golden
4	0.271957	0.0940748	parabolic
5	0.138921	0.0219803	parabolic
6	0.0615426	0.00402058	parabolic
7	0.0214162	0.000468475	parabolic
8	0.00525533	2.77636e-05	parabolic
9	0.000805899	6.49997e-07	parabolic
10	0.000839233	7.04902e-07	parabolic
11	0.000772566	5.97319e-07	parabolic
12	0.000477472	2.28088e-07	golden
13	0.000295094	8.71061e-08	golden

14	0.000182378	3.32678e-08	golden
15	0.000112716	1.27063e-08	golden
16	6.96622e-05	4.85316e-09	golden
17	3.63289e-05	1.31984e-09	golden

Optimization terminated:

the current x satisfies the termination criteria using OPTIONS.TolX of 1.000000e-04

x_min = 3.6329e-05

```
% part b
x = [1 -0.5 2];
y = x.^2 + x.^3 % the function
y_inter = polyfit(x,y,2); % quadratic interpolation
f1 = @(x1) 2*x1.^2 + 0.125*x1 + 12; % The new quadratic function
x_min = fminbnd(f1,0,2)
```

OUTPUT

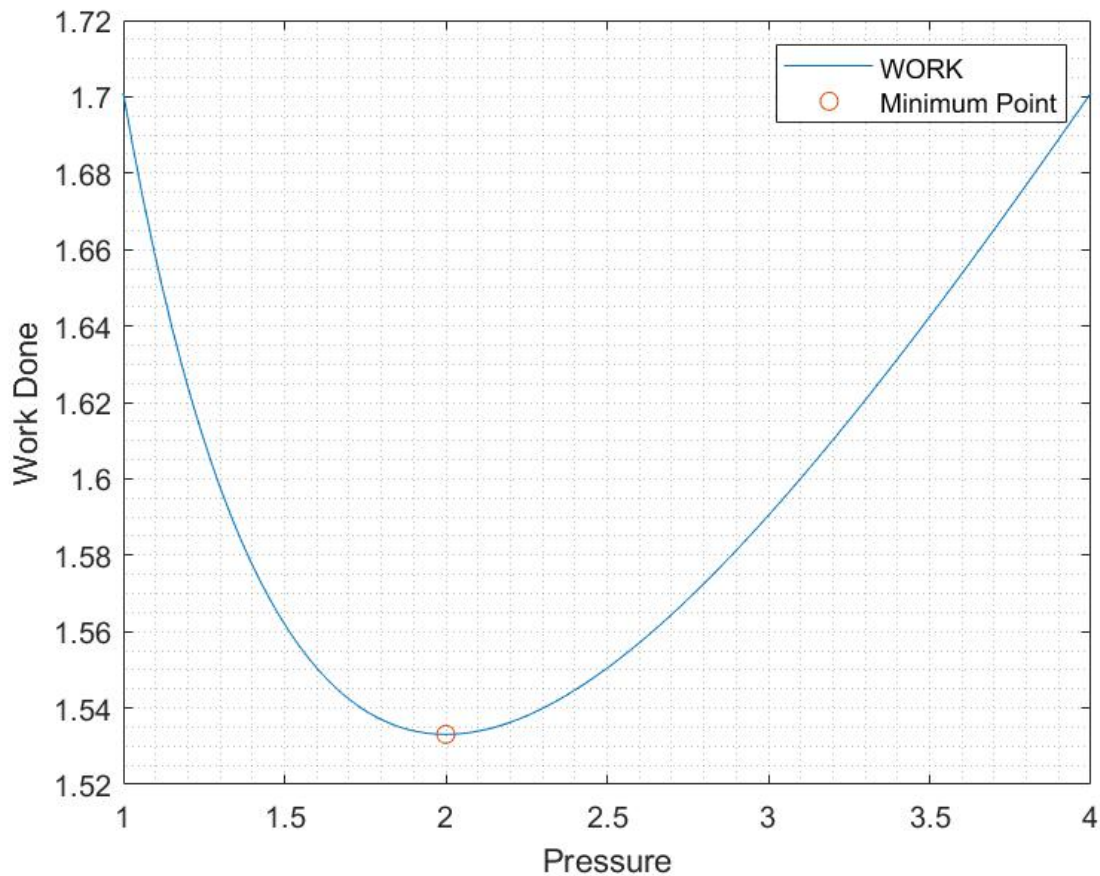
```
y = 1x3
    2.0000    0.1250   12.0000
x_min = 4.8379e-05
```

QUESTION 2

QUESTION a

```
p1 = 1;
p3 = 4;
gamma = 1.4 % gas
V1 = 1;
p = linspace(p1,p3);
f = ((gamma*p1*V1)./(gamma-1))*(((p./p1)).^((gamma-1)./(gamma)) - 2 + ...
    (p3./p).^((gamma-1)./(gamma)));
plot(p,f);
hold on
i=find(f(1,:)==min(f)); % find the point where W is minimum
j = p(1,34); % return the value of p in which W is minimum
plot(p(1,34),f(1,34),'o') % mark the minimum point
xlabel('Pressure'),ylabel('Work Done');
grid minor
legend('WORK','Minimum Point')
hold off
```

OUTPUT



Question b

```
% Let x = p
figure; hold on;
a=0; % start of interval
b=2; % end of interval
epsilon=0.00001; % accuracy value
iter= 50; % maximum number of iterations
tau=double((sqrt(5)-1)/2); % golden proportion coefficient, around 0.618
k=0; % number of iterations
f = @(x) ((gamma*p1*V1)./(gamma-1))*(((x./p1)).^((gamma-1)./(gamma)) -2 + ...
        (p3./x).^((gamma-1)./(gamma)));
x1=a+(1-tau)*(b-a); % computing x values
x2=a+tau*(b-a);
```



```

f_x1=f(x1);                                % computing values in x points
f_x2=f(x2);

plot(x1,f_x1, '*')                         % plotting the function with x_min
plot(x2,f_x2, '*')

xlabel("p-values"), ylabel("W-axis");

while ((abs(b-a)>epsilon) && (k<iter))
    k=k+1;
    if(f_x1<f_x2)
        b=x2;
        x2=x1;
        x1=a+(1-tau)*(b-a);

        f_x1=f(x1);
        f_x2=f(x2);

        plot(x1,f_x1, '*');
    else
        a=x1;
        x1=x2;
        x2=a+tau*(b-a);

        f_x1=f(x1);
        f_x2=f(x2);

        plot(x2,f_x2, '*')
    end

    k=k+1;
end

```

```

% chooses minimum point
if(f_x1<f_x2)
    sprintf('p_min=% f', x1)
    sprintf('W(x_min)=% f ', f_x1)
    plot(x1,f_x1,'ro')
else
    sprintf('p_min=% f', x2)
    sprintf('W(p_min)=% f ', f_x2)
    plot(x2,f_x2,'ro')
end
disp("50 Iterations")

```

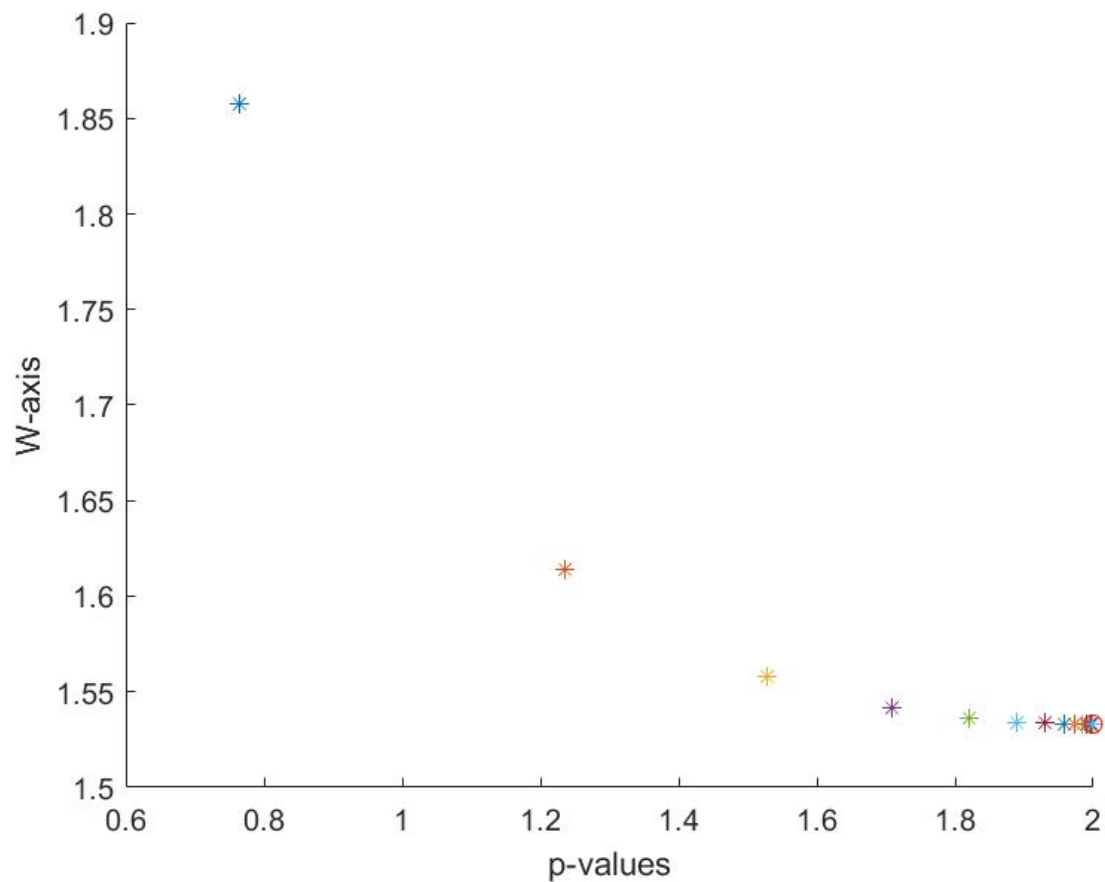
OUTPUT

gamma = 1.4000

```

ans = 'p_min= 1.999995'
ans = 'W(p_min)= 1.533096 '

```



50 Iterations

Question c

```
f = @(x) ((gamma*p1*v1)./(gamma-1))*(((x./p1)).^((gamma-1)./(gamma)) - 2 + ...
    (p3./x).^((gamma-1)./(gamma)));
% The x-points values
x1 = 1;
x2 = -0.5;
x3 = 2;
tol = 10^-6;

% Invoking function
quadratic_interpolation(f, x1, x2, x3, tol)
```

I created a function below

```
function quadratic_interpolation(f, x1, x2, x3, tol)
fx1 = f(x1);
fx2 = f(x2);
fx3 = f(x3);
if (fx1 > fx2 && fx2 < fx3)
    cond = true;
    iterations = 1;
    while(cond)
        syms a b c
        fx1 = f(x1);
        fx2 = f(x2);
        fx3 = f(x3);
        % Quadratic interpolation in the form of a second-order polynomial
        y(x) = a + bx + cx^2
        % a, b, c is calculated from the following linear equations
        eq1 = a + x1*b + x1.^2 * c == fx1;
        eq2 = a + x2*b + x2.^2 * c == fx2;
        eq3 = a + x3*b + x3.^2 * c == fx3;
        sol = solve([eq1, eq2, eq3], [a, b, c]);
        aS = sol.a;
```

```

bS = sol.b;
cS = sol.c;

xOpt = -(bS/(2*cS));
parabolaOpt = aS + bS*xOpt + cS*(xOpt^2);
fxOpt = f(xOpt);
vars = [x1 x2 x3 xOpt];

cond = (abs(fxOpt - parabolaOpt) > tol);
    if (cond)
        iterations = iterations + 1;
        % Calculating new points
        vSorted = sort(vars);
        vSIndice = find(vSorted==xOpt);
        vSortedLeft = vSorted(:,1:(vSIndice-1));
        vSortedRight = vSorted(:, (vSIndice+1:end));
        x1 = max(vSortedLeft);
        x2 = xOpt;
        x3 = min(vSortedRight);
    end
end

fprintf('Optimal x* = %.4f \n', x2)
fprintf('No. of iterations = %d \n', iterations)
else
    disp('f(x1) > f(x2) && f(x2) < f(x3) not satisfied')
end
end
end

```

OUTPUT

```

Optimal P* = 1.4837
No. of iterations = 2

```

Question d- Using An Appropriate Method

```
fun =@(x) ((gamma*p1*v1)./(gamma-1))*(((x./p1)).^((gamma-1)./(gamma)) -2 + ...
    (p3./x).^((gamma-1)./(gamma))) ;
x1 = 0;
x2 = 2;
options = optimset("Display","Iter");
p_min = fminbnd(fun,x1,x2,options)
% Plot the Optimal Solution on The Curve in part A
fplot(fun,[0,10]);
hold on
plot(p_min,f(p_min),"V") % mark the minimum point
xlabel("Pressure"),ylabel("Work Done");
grid minor
legend("WORK","Minimum Point Plot on It")
hold off
```

OUTPUT

Func-count	x	f(x)	Procedure
1	0.763932	1.85774	initial
2	1.23607	1.61387	golden
3	1.52786	1.55836	golden
4	1.60468	1.54999	parabolic
5	1.75568	1.53901	golden
6	1.90894	1.53385	parabolic
7	1.96325	1.53322	parabolic
8	1.99157	1.5331	parabolic
9	1.9989	1.5331	parabolic
10	1.99991	1.5331	parabolic
11	1.99988	1.5331	parabolic
12	1.99994	1.5331	parabolic

Optimization terminated:
the current x satisfies the termination criteria using OPTIONS.TolX of
1.000000e-04
p_min = 1.9999

