

10.3 Non-linear Dimensionality Reduction

Machine Learning 1: Foundations

Marius Kloft (TUK)

- Non-linear Dimensionality Reduction
 - Kernel PCA
 - Autoencoders

To Kernelize PCA ...

... we apply the representer theorem (see kernel lecture) to the PCA solution $W_* = (\mathbf{w}_1^*, \dots, \mathbf{w}_k^*)$:

$$\forall j = 1, \dots, k \quad \exists \alpha_j = (\alpha_{1j}, \dots, \alpha_{nj})^\top \in \mathbb{R}^n :$$

$$\mathbf{w}_j^* = \sum_{i=1}^n \alpha_{ij} \phi(\mathbf{x}_i) = \phi(X) \alpha_j,$$

or, more compactly:

$$W_* = \phi(X)\alpha,$$

where we employ the notation:



So the data in the dimensionality-reduced coordinate system is:

$$\widetilde{X} := W_*^\top \phi(X) = \alpha_*^\top K$$

Since the data lies in a high-dim. space, the original coord. sys. is not interesting here, unless we use a lin. kernel.

Thus, using $\mathbf{w}_i = \phi(X)\alpha_i$, we have:

$$\max_{W \in \mathbb{R}^{d \times k}} \sum_{j=1}^k \mathbf{w}_j^\top \phi(X) \phi(X)^\top \mathbf{w}_j$$



Thus, using $\mathbf{w}_j = \phi(X)\alpha_j$, we have:

$$\max_{W \in \mathbb{R}^{d \times k}} \sum_{j=1}^{k} \mathbf{w}_{j}^{\top} \phi(X) \phi(X)^{\top} \mathbf{w}_{j}$$

$$= \max_{\alpha \in \mathbb{R}^{n \times k}} \sum_{j=1}^{k} \alpha_{j}^{\top} \underbrace{\phi(X)^{\top} \phi(X) \phi(X)^{\top} \phi(X)}_{=K^{2}} \alpha_{j}$$

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What is actually the centered kernel matrix?

PCA requires that the data is centered as a preprocessing step:

$$\hat{\boldsymbol{\mu}} := \frac{1}{n} \sum_{i=1}^{n} \mathbf{x}_i, \quad \forall i: \mathbf{x}_i \leftarrow \mathbf{x}_i - \hat{\boldsymbol{\mu}}$$

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Similar, KPCA requires data that is centered in feature space:

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The centered kernel matrix \widetilde{K} can be computed from the (uncentered) kernel matrix K by:

$$\widetilde{K} = (I - \frac{\mathbf{1}\mathbf{1}^{\top}}{n})K(I - \frac{\mathbf{1}\mathbf{1}^{\top}}{n})$$

KPCA Algorithm

```
1: function KPCA(parameter K, kernel matrix K \in \mathbb{R}^{n \times n})
2: center the kernel matrix: K \leftarrow (I - \frac{\mathbf{1}\mathbf{1}^\top}{n})K(I - \frac{\mathbf{1}\mathbf{1}^\top}{n})
3: compute K largest eigenvectors \mathbf{\alpha} = (\alpha_1, \dots, \alpha_k) of K (e.g., in MATLAB: [foo, \alpha] = eig(K))
4: compute: \widetilde{X} := \mathbf{\alpha}^\top K 1
5: return dimensionality-reduced data: \widetilde{X} \in \mathbb{R}^{k \times n} (6: end function
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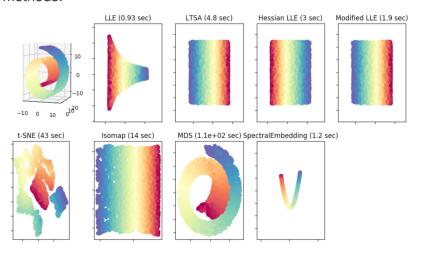
Note:

- ► KPCA can be even useful for linear kernels, when d > n
- ► In this case, the projected data in the original coordinate system is (assuming centered X and K):

$$\hat{X} = W_* \widetilde{X} = \phi(X) \alpha_* \alpha_*^\top K,$$

Outlook

There are many other non-linear dimensionality reduction methods:



Next, we will look into one of them: autoencoders

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How deep can we go in dimensionality reduction?

The default method for dimensionality reduction in DL is:

autoencoders (AEs)

Autoencoders (AEs)

Definition

An autoencoder (AE) is defined as:

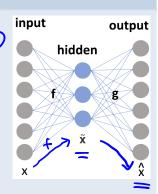
$$\min_{W,\tilde{W}} \sum_{i=1}^{n} \left\| \mathbf{x}_{i} - g_{\tilde{W}}(f_{W}(\mathbf{x}_{i})) \right\|^{2},$$



- ► $f_W : \mathbb{R}^d \to \mathbb{R}^k$ is a neural network (called **encoder**)
- $g_{\tilde{W}}: \mathbb{R}^k \to \mathbb{R}^d$ is a neural network (called **decoder**)

The dimensionality-reduced data is:

- ▶ in original coord. system:
- ▶ in *k*-dim. coordinate system:



$$\hat{X} := g_{\tilde{W}}(f_{W}(X)) \in \mathbb{R}^{d \times n}$$

$$\widetilde{X} := f_W(X) \in \mathbb{R}^{k \times n}$$

 $\tilde{\mathbf{x}}:=f_W(\mathbf{x})$ is the **code** and $\hat{\mathbf{x}}:=g_{\tilde{W}}(f_W(\mathbf{x}))$ the **reconstruction** of \mathbf{x} .

We denote here $f_W(X) := (f_W(\mathbf{x}_1), \dots, f_W(\mathbf{x}_n))$ and analogue for $g_{\tilde{W}} \circ f_W$.

Consider a linear encoder and a linear decoder:

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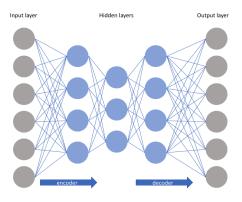
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Note, however:

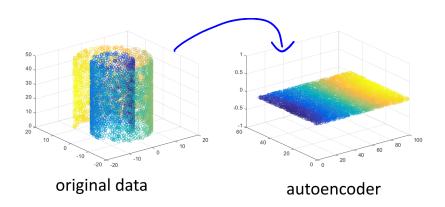
- An AE does not enforce orthonormality of W
- So the solution W_*^{AE} of an AE will be similar to—but not exactly the same as—the solution W_*^{PCA} of PCA

Deep Autoencoders

Of course, we can use multiple hidden layers...



Example: Swiss Role



Outlook

Introducing a bottleneck k < d is only one option to achieve a dimensionality reduction / compression in autoencoders

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▶ another one is **regularization** (can have k > d then)

There are various regularization techniques for autoencoders:

- Frobenius norm regularization
- Sparse autoencoders
- Denoising autoencoders
- Contractive autoencoders

Unifying View of Regr., Classif., and Dim. Reduction

$$\min_{[W,] b, \mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^{n} I(\underline{f(\mathbf{x}_i)} [, y_i]) \left[+ \frac{1}{2} \sum_{l=1}^{L} \|W_l\|_{\text{Fro}}^2 \right],$$

with model /

- $f(\mathbf{x}) = \langle \mathbf{w}, \phi(\mathbf{x}) \rangle + b$ for regression and classification
- $f(\mathbf{x}) = \|\phi(\mathbf{x}) \mathbf{w}\mathbf{w}^{\top}\phi(\mathbf{x})\|^2$ for dimensionality reduction

and loss

- $I(t, y) := \max(0, 1 yt)$ for SVM ("hinge loss")
- ▶ I(t, y) := In(1 + exp(-yt)) for LR and ANN ("logistic loss")
- $I(t, y) := (t y)^2$ for regression
- ightharpoonup I(t) := t for dimensionality reduction

and feature map

- $ightharpoonup \phi := id$ for linear SVM, linear LR, RR, and PCA.
- $\phi := \phi_k$ for kernel SVM, kernel LR, KRR, and KPCA.
- $ightharpoonup \phi := \phi_W$ for ANN, DR, and AE.

The terms in gray brackets apply only to ANN, DR, and AE. The term in blue brackets applies only to dimensionality reduction.

Conclusion

- Unsupervised learning
 - this week: dimensionality reduction
- Most famous method: principal component analysis (PCA)
 - **b** boils down to computing eigenvalues of scatter matrix XX^{\top}
 - can be generalized to KPCA and autoencoders
- Outlook: more dimensionality reduction methods
 - optimizing different measures of closeness of the projected data to the original data
 - e.g., multidimensional scaling (MDS): tries to preserve distances among projected inputs
- Dimensionality reduction also possible in a supervised fashion (ML2: Fisher's discriminant analysis)
- Further reading: Goodfellow et al 2016, Deep Learning -Chapter: 14 Autoencoders