

2.1 Linear Classifiers

Machine Learning 1: Foundations

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Recap

Machine learning

- ▶ computers learning from data
how to make accurate predictions

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Formal problem setting and terminology

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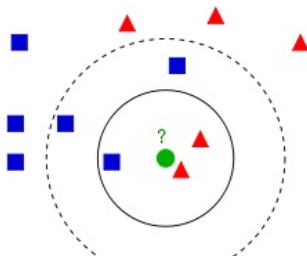
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- ▶ Example: k -nearest neighbor algorithm



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2 Linear Classifiers

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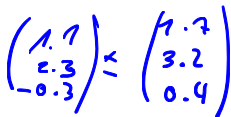
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- ▶ $\mathbf{v} \leq \mathbf{w}$ means $\forall i = 1, \dots, d : \underline{v_i \leq w_i}$



Handwritten example of vector inequality: $\begin{pmatrix} 1.7 \\ 2.3 \\ -0.3 \end{pmatrix} \leq \begin{pmatrix} 4.7 \\ 3.2 \\ 0.4 \end{pmatrix}$. The inequality is shown with a less-than-or-equal-to symbol between two column vectors. The first vector has entries 1.7, 2.3, and -0.3. The second vector has entries 4.7, 3.2, and 0.4.

Math Notation

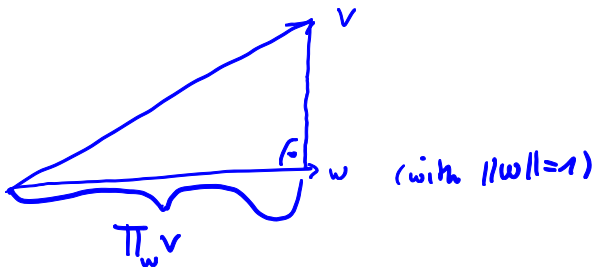
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- ▶ The cardinality of a set S is denoted $|S|$

Math Recap: Projections

Recall from linear algebra:

Definition

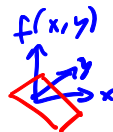
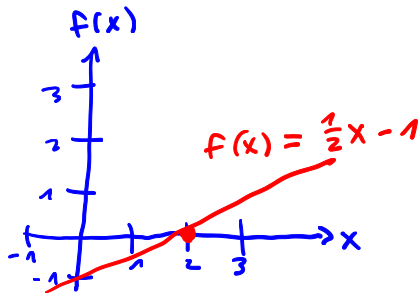
The **scalar projection** of a vector $\mathbf{v} \in \mathbb{R}^d$ onto a vector $\mathbf{w} \in \mathbb{R}^d$ is $\Pi_{\mathbf{w}}\mathbf{v} = \mathbf{v}^\top \frac{\mathbf{w}}{\|\mathbf{w}\|}$.



Math Recap: Hyperplanes

Definitions

- ▶ An (affine-) **linear function** is a function $f : \mathbb{R}^d \rightarrow \mathbb{R}$ of the form $f(\mathbf{x}) = \mathbf{w}^\top \mathbf{x} + b$, where $\mathbf{w} \in \mathbb{R}^d$ and $b \in \mathbb{R}$.
- ▶ A **hyperplane** is a subset $H \subset \mathbb{R}^d$ defined as $H := \{\mathbf{x} \in \mathbb{R}^d : f(\mathbf{x}) = 0\}$.



$$H = \{2\}$$

Math Recap: Signed Distance

We define the sign here as positive if and only if $f(\mathbf{x}) \geq 0$.

Math Recap: Signed Distance

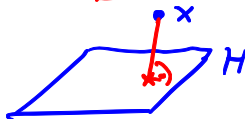
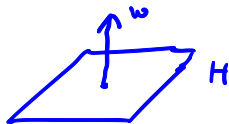
Proved on exercise sheet:

Proposition (properties of hyperplanes)

Let H be a hyperplane defined by the affine-linear function $f(\mathbf{x}) = \mathbf{w}^\top \mathbf{x} + b$. It holds:

- 1 The vector \mathbf{w} is **orthogonal** to H , meaning that: for all $\mathbf{x}_1, \mathbf{x}_2 \in H$ it is $\mathbf{w}^\top (\mathbf{x}_1 - \mathbf{x}_2) = 0$.
- 2 The **signed distance** of a point \mathbf{x} to H is given by

$$d(\mathbf{x}, H) \stackrel{\text{def.}}{=} \pm \min_{\tilde{\mathbf{x}} \in H} \|\mathbf{x} - \tilde{\mathbf{x}}\| \stackrel{\text{prop.}}{=} \frac{1}{\|\mathbf{w}\|} (\mathbf{w}^\top \mathbf{x} + b)$$



We define the sign here as positive if and only if $f(\mathbf{x}) \geq 0$.

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Definition

A classifier of the form $f(\mathbf{x}) = \text{sign}(\underline{\mathbf{w}^\top \mathbf{x} + b})$ is called **linear classifier**.

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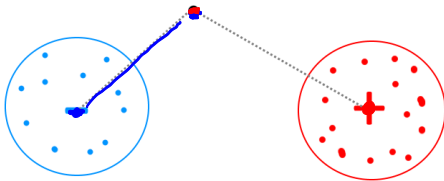
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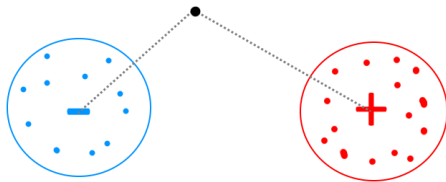
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Please **pause** your video here and think about this question for a few minutes...

The Nearest Centroid Classifier



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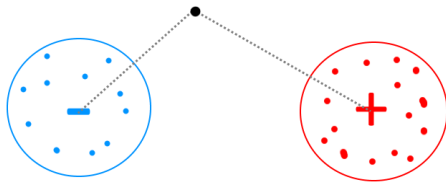


Let I_- and I_+ denote the indices of the data points labeled -1 and +1.

Training

- ▶ Compute $n_- = |I_-|$ and $n_+ = |I_+|$
- ▶ Compute $c_- = \frac{1}{n_-} \sum_{i \in I_-} x_i$ and $c_+ = \frac{1}{n_+} \sum_{i \in I_+} x_i$

The Nearest Centroid Classifier



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Prediction

- ▶ Given new x predict $\arg \min_{y \in \{-, +\}} \|x - c_y\|$

NCC is a Linear Classifier

Theorem

NCC is a linear classifier $f(\mathbf{x}) = \text{sign}(\mathbf{w}^\top \mathbf{x} + b)$ with $\mathbf{w} := 2(\mathbf{c}_+ - \mathbf{c}_-)$ and $b = \|\mathbf{c}_-\|^2 - \|\mathbf{c}_+\|^2$.

proof: Decision boundary: $H = \{ \mathbf{x} \in \mathbb{R}^d : \underbrace{\|\mathbf{x} - \mathbf{c}_-\| = \|\mathbf{x} - \mathbf{c}_+\|}_{(\mathbf{x})} \}$

$$\Leftrightarrow \|\mathbf{x} - \mathbf{c}_-\|^2 = \|\mathbf{x} - \mathbf{c}_+\|^2$$

$$\Leftrightarrow \cancel{\|\mathbf{x}\|^2} - 2\mathbf{c}_-^\top \mathbf{x} + \|\mathbf{c}_-\|^2 = \cancel{\|\mathbf{x}\|^2} - 2\mathbf{c}_+^\top \mathbf{x} + \|\mathbf{c}_+\|^2$$

$$\Leftrightarrow \underbrace{2(\mathbf{c}_+ - \mathbf{c}_-)}_{=: \mathbf{w}}^\top \mathbf{x} + \underbrace{(\|\mathbf{c}_-\|^2 - \|\mathbf{c}_+\|^2)}_{=: b} = 0$$

$$\Leftrightarrow \mathbf{w}^\top \mathbf{x} + b = 0$$

$$\text{Thus: } H = \{ \mathbf{x} \in \mathbb{R}^d : \mathbf{w}^\top \mathbf{x} + b = 0 \}$$

□

Conclusion

Linear Classifier: $f(\mathbf{x}) = \text{sign}(\mathbf{w}^\top \mathbf{x} + b)$

- ▶ Fast and easy to understand

Example: NCC

- ▶ $f(\mathbf{x}) = \arg \min_{y \in \{-, +\}} \|\mathbf{x} - \mathbf{c}_y\|$

