

8.3 Non-linear Regression

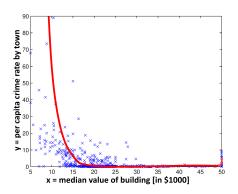
Machine Learning 1: Foundations

Marius Kloft (TUK)

- Linear Regression
- 2 LOOCV
- Non-linear Regression
 - Kernel Ridge Regression
 - Deep Regression
- Unifying Loss View of Regression and Classification
 - Kernel Ridge Regression
 - Deep Regression

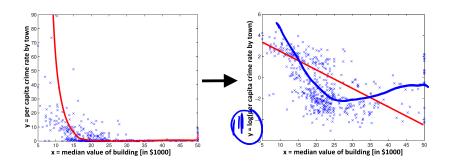
Non-linear Regression

Motivation:

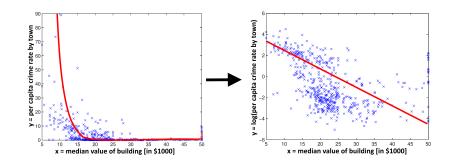


Linear regression not adequate if ground truth is non-linear

Trick: Apply a Log Transformation to the Label

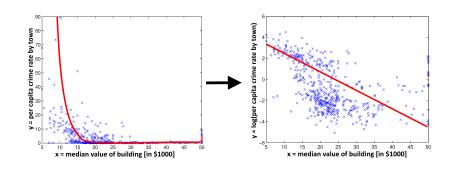


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The fit looks better now...

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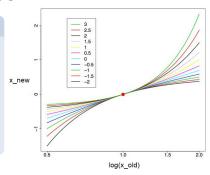
... but is still not optimal.

Trick: Box-Cox Transformation

Definition

The **Box-Cox transformation** (or 'power transformation') with parameter λ is:

$$x_{\text{new}} \leftarrow \begin{cases} \log(x_{\text{old}}) & \text{if } \lambda = 0 \\ \frac{x_{\text{old}}^{\lambda} - 1}{\lambda} & \text{if } \lambda \neq 0 \end{cases}$$

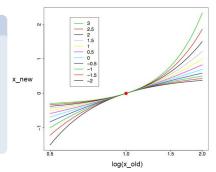


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Interpretation:

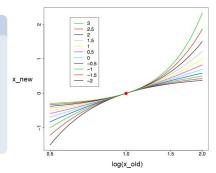
 $\text{for} \begin{cases} \lambda > 1: & \text{data is stretched} \\ 0 < \lambda < 1: & \text{data is concentrated (e.g. } \lambda = \text{2: quadratically)} \\ \lambda = 0: & \text{log transform} \\ \lambda < 0: & \text{analogously, with the order of data reversed} \end{cases}$

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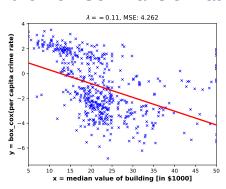


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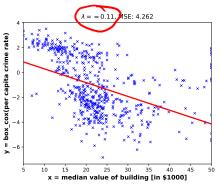
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The optimal parameter λ can be chosen automatically (omitted)

Our Data After the Box-Cox Transformation:



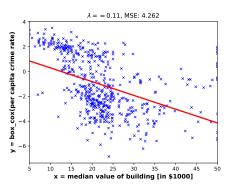
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If this still not helps or the number of features is high, we need a **non-linear regression** method.

Non-linear Regression

We will discuss two powerful **non-linear** regression methods:

- 1 Kernel ridge regression
- 2 Deep regression

Kernel Ridge Regression (KRR)

KRR is just the kernelized version of linear regression:

Definition

Let k be a kernel with associated feature map $\phi: \mathbb{R}^d \to \mathcal{H}$, i.e., $k(\mathbf{x}, \tilde{\mathbf{x}}) = \langle \phi(\mathbf{x}), \phi(\tilde{\mathbf{x}}) \rangle$. Then **kernel ridge regression (KRR)** is defined as:

$$\mathbf{w}_{KRR} := \underset{\mathbf{w} \in \mathcal{H}}{\text{arg min}} \quad \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^n \|y_i - \langle \mathbf{w}, \underline{\phi}(x_i) \rangle \|^2.$$

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Recall the kernel trick:

- re-formulate the problem in terms of inner products between data points
- replace inner products by kernel

To Formulate KRR in Terms of Inner Products...

... we apply the representer theorem (see kernel lecture):

$$\exists \alpha \in \mathbb{R}^n : \quad \mathbf{w}_{KRR} = \sum_{i=1}^n \alpha_i \phi(\mathbf{x}_i) = \phi(X) \alpha,$$

where we employ the notation:

Using the representer theorem, we can write:

$$\min_{\mathbf{w} \in \mathbb{R}^d} \frac{1}{2} \|\mathbf{w}\|^2 + C \|\mathbf{y} - \phi(X)^\top \mathbf{w}\|^2$$

Using the representer theorem, we can write:

$$\min_{\mathbf{w} \in \mathbb{R}^{d}} \frac{1}{2} \|\mathbf{\underline{w}}\|^{2} + C \|\mathbf{y} - \phi(X)^{\top}\mathbf{w}\|^{2}$$

$$= \min_{\alpha \in \mathbb{R}^{n}} \frac{1}{2} \underbrace{\|\phi(X)\alpha\|^{2}}_{\alpha^{\top}} + C \|\mathbf{y} - \underbrace{\phi(X)^{\top}\phi(X)}_{=K}\alpha\|^{2}$$

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One can show (homework) that the optimal solution α^* is:

$$\alpha^* = \left(K + \frac{1}{2C}I_{n \times n}\right)^{-1}y$$

Theorem

The solution of KRR is given by

$$f(\mathbf{x}) = \sum_{i=1}^{n} \alpha_i k(\mathbf{x}_i, \mathbf{x})$$
 with $\alpha = (K + \frac{1}{2C} I_{n \times n})^{-1} y$.

It can thus be computed in $O(n^3)$.

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Usually we use KRR together with a Gaussian kernel, but sometimes it can make sense to use a linear kernel:

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Note that the LOOCV trick can be adapted to KRR

▶ thus we can compute the LOOCV RMSE of KRR in $O(n^3)$

Now Say In Addition to Our Housing Data ...

... we are given images of the houses:



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... we are given images of the houses:



How to estimate the value of such a house from the image (and maybe additional other features)?

Deep Regression

State of the art in image processing: deep CNNs

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How can we use ANNs (such as deep CNNs) for regression?

Just take our classification ANN and change the loss to least squares:

Deep Regression (DR)

Predict $f(\mathbf{x}) = \mathbf{w}_*^{\top} \phi_{W_*}(\mathbf{x})$, where:

$$(\mathbf{w}_{*}, W_{*}) := \underbrace{\min_{\mathbf{w}, W} \frac{1}{2} \|\mathbf{w}\|^{2} + \sum_{l=1}^{L} \|W_{l}\|_{Fro}^{2} + C \sum_{i=1}^{n} (y_{i} - \mathbf{w}^{\top} \phi_{W}(\mathbf{x}_{i}))^{2}}_{}$$