

eciación
$$\frac{Vi(s)-Vacs}{R_1} + \frac{Vz(s)-Va(s)}{R_2} = \varphi$$

$$\frac{V_1(s)}{R_1} + \frac{V_2(s)}{R_2} = V_A(s) \left(\frac{1}{R_1} + \frac{1}{R_2}\right)$$

$$VA(s) \left(SC + \frac{1}{R3}\right) - Vi(s) SC = 0 \rightarrow \frac{VA(s)}{Vi(s)} - \frac{SC}{SC + \frac{1}{R3}} = \frac{SC}{R3}$$

$$= 0$$

$$VA(s) \left(SC + \frac{1}{R3}\right) - Vi(s) SC = 0 \rightarrow \frac{VA(s)}{Vi(s)} - \frac{SC}{SC + \frac{1}{R3}} = \frac{SC}{R3} = \frac{SC}{R3} = 0$$

$$\frac{A}{R_1} + \frac{V_{2(s)}}{R_2} = \frac{V_{A(s)}}{V_{1(s)}} \left(\frac{1}{R_1} + \frac{1}{R_2}\right)$$

$$\frac{V_{1}(s)}{R_{1}} + \frac{V_{2}(s)}{R_{2}} = \frac{V_{1}(s)}{s \cdot c \cdot R_{3}} \left(\frac{1}{R_{1}} + \frac{1}{R_{2}}\right)$$

$$\frac{V_2(s)}{R_2} = V_1(s) \left[\frac{S \cdot c \cdot R_3}{S \cdot c \cdot R_3 + 1} \left(\frac{1}{R_1} + \frac{1}{R_2} \right) - \frac{1}{R_1} \right]$$

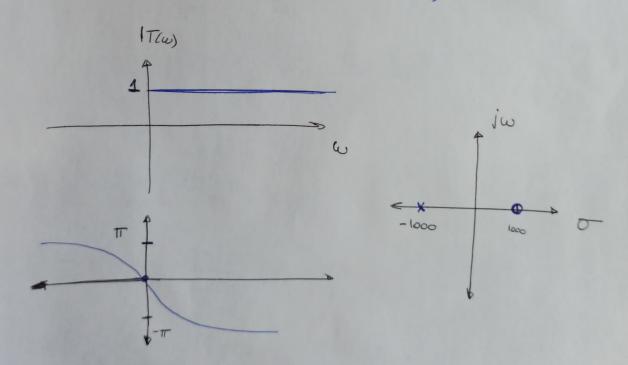
$$T(s) = \frac{S - 1000}{S + 1000} = T(s) |_{S = Ju} = \frac{j\omega - 1000}{j\omega + 1000}$$

$$|T(w)| = \sqrt{w^2 + |aoo^2|} = 1$$
; $\forall T(w) = i \frac{2r(eq)(w/iooo)}{e^{i \frac{2r(eq)(w/iooo)}{2r(eq)}}}$

$$T(\omega) = |T(\omega)| e^{\int \Theta(\omega)} = 1 e^{\int (\operatorname{arctg}(\omega/\log \omega) - \operatorname{arctg}(\omega/\log \omega))}$$

$$= \int e^{\int (-\operatorname{arctg}(\omega/\log \omega) - \operatorname{arctg}(\omega/\log \omega))}$$

$$= \int e^{\int -2\operatorname{arctg}(\omega/\log \omega)}$$



Retormed
$$T(S) = S - P2/cR123$$
; $R2=R1$

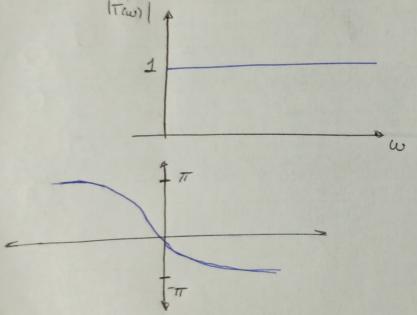
$$S + VcR3$$

$$S + VcR3 = S - Wc$$

$$S + VcR3 = S + Up, Wc=up$$

$$S + Up$$

$$S$$



=> Vero go si hibier => VEO que el normalizar no modifica la sespenza