Algorithms and Data Structures Open Addressing, Priority Queue

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Structure

Hashing

Recapitulation Treatment of hash collisions Open Addressing Summary

Priority Queue Introduction

Recapitulation

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- Then the random keys make sure that it is distributed evenly
- To find a good hash function for every key set, universal hashing is needed
 - Then however, for a fixed set of keys not every hash function is suitable, but only some

Recapitulation

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How to rehash?

▶ New hash table with a new random hash function

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- Copy elements into the new table
 - Expensive but does not happen often
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 - Look at amortized analysis in the next lecture

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Open Addressing Summary

Priority Queue Introduction

Linked List

Buckets as linked list:

Linked List

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Linked List

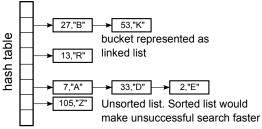
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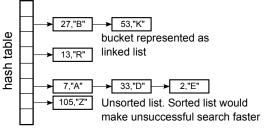
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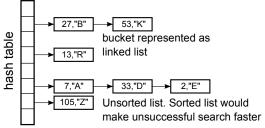


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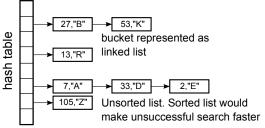


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- Operations in O(1) are possible if a suitable table size and hash function is selected
- ▶ Worst case O(n), e.g. table size of 1
- Dynamic number of elements is possible

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Hashing Open Addressing

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 - ► If an entry is already occupied, then iteratively the following entry is checked. If a free entry is found the element is inserted

Hashing Open Addressing

- For colliding keys we choose a new free entry
- Static, fixed number of elements
- The probe sequence determines for each key, in which sequence all hash table entries are searched for a free bucket
 - ► If an entry is already occupied, then iteratively the following entry is checked. If a free entry is found the element is inserted
 - ▶ If element is not found at the corresponding table entry, even if the entry is occupied, then probing has to be performed until the element or a free entry has been found

Open Addressing

Definitions:

Open Addressing

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h(s) Hash function for key s

Open Addressing

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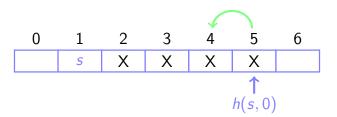
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Definitions:

- h(s) Hash function for key s
- g(s,j) Probing function for key s with overflow positions $j \in \{0, \dots, m-1\}$ e.g. g(s,j)=j
 - ► The **probe sequence** is calculated by

$$h(s,j) = (h(s) - g(s,j)) \mod m \in \{0,\ldots,m-1\}$$



Open Addressing - Python

Open Addressing - Python

```
def lookup(s):
    i = 0
    while t[(h(s) - g(s, j)) \mod m] \setminus
             is not None:
        if t[(h(s) - g(s, j)) \mod m][0] != s:
                          j += 1
        if t[(h(s) - g(s, j)) \mod m][0] == s:
             return t[(h(s) - g(s, j)) \mod m]
    return None
```

Open Addressing - Linear Probing

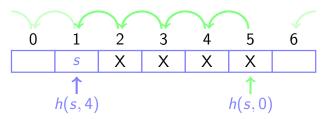


Figure: Linear probe sequence

Open Addressing - Linear Probing

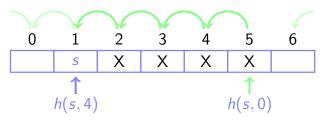


Figure: Linear probe sequence

► Check the element with lower index: g(s,j) := j⇒ Hash function: $h(s,j) = (h(s) - j) \mod m$

Open Addressing - Linear Probing

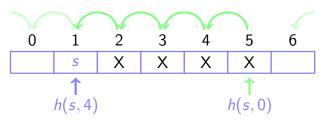


Figure: Linear probe sequence

- ► Check the element with lower index: g(s,j) := j⇒ Hash function: $h(s,j) = (h(s) - j) \mod m$
- ► This leads to the following probe sequence

$$h(s), h(s) - 1, h(s) - 2, \dots, \underbrace{0, m - 1}_{\text{clipping}}, m - 2, \dots, h(s) + 1$$

Open Addressing - Linear Probing

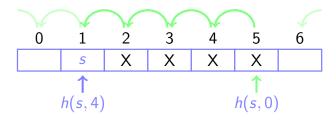


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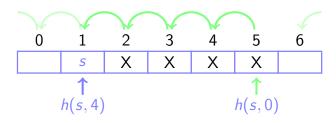


Figure: Linear probe sequence

► Can result in primary clustering

Open Addressing - Linear Probing

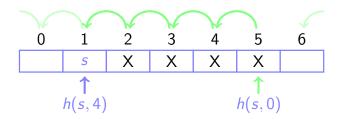


Figure: Linear probe sequence

- Can result in primary clustering
- ▶ Dealing with a hash collision will result in a higher probability of hash collisions in close entries

Open Addressing - Linear Probing

Example:

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Example:

► Keys: {12,53,5,15,2,19}

Open Addressing - Linear Probing

Example:

► Keys: {12, 53, 5, 15, 2, 19}

► Hash function: $h(s,j) = (s \mod 7 - j) \mod 7$

Open Addressing - Linear Probing

Example:

- ► Keys: {12, 53, 5, 15, 2, 19}
- ► Hash function: $h(s,j) = (s \mod 7 j) \mod 7$
- \blacktriangleright t. insert (12, "A"), h(12,0) = 5

0	1	2	3	4	5	6
				12, A		

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Example:

- ► Keys: {12, 53, 5, 15, 2, 19}
- ► Hash function: $h(s,j) = (s \mod 7 j) \mod 7$
- ▶ t. insert (12, "A"), h(12,0) = 5

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▶ t. insert (53, "B"), h(53,0) = 4



Figure: Probe/Insertion sequence on a hash map

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Open Addressing - Linear Probing

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▶ t. insert (5, "C"),
$$h(5,0) = 5$$
, $h(5,1) = 4$, $h(5,2) = 3$

0 1 2 3 4 5 6

5, C 53, B 12, A

Open Addressing - Linear Probing

Example:

► Hash function: $h(s,j) = (s \mod 7 - j) \mod 7$

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$$h(5,0) = 5$$
, $h(5,1) = 4$, $h(5,2) = 3$

0 1 2 3 4 5 6

5, C 53, B 12, A

▶ t. insert (15, "D"),
$$h(15,0) = 1$$

15, D 5, C 53, B 12, A

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- ► Hash function: $h(s,j) = (s \mod 7 j) \mod 7$
- ▶ t. insert (2, "E"), h(2,0) = 2

0	1	2	3	4	5	6
	15, D	2, E	5, C	53, B	12, A	

Open Addressing - Linear Probing

Example:

- ► Hash function: $h(s,j) = (s \mod 7 j) \mod 7$
- t. insert (2, "E"), h(2,0) = 2

▶ t. insert (19, "F"),
$$h(19,0) = 5$$
, $h(19,1) = 4$, $h(19,2) = 3$, $h(19,3) = 2$, $h(19,4) = 1$, $h(19,5) = 0$

19, F | 15, D | 2, E | 5, C | 53, B | 12, A

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Open Addressing - Squared Probing Squared probing:

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Squared probing:

► Motivation: avoid local clustering

$$g(s,j) := (-1)^j \left\lceil \frac{j}{2} \right\rceil^2$$

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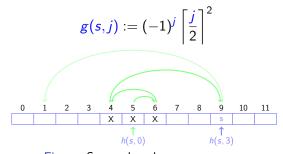


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$$g(s,j) := (-1)^{j} \left\lceil \frac{j}{2} \right\rceil^{2}$$

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Figure: Squared probe sequence

This leads to the following probe sequence

$$h(s)$$
, $h(s) + 1$, $h(s) - 1$, $h(s) + 4$, $h(s) - 4$, $h(s) + 9$, $h(s) - 9$, ...

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- If m is a prime number for which $m = 4 \cdot k + 3$ then the probe sequence is a permutation of the indices of the hash tables
- ► Alternatively: $h(s,j) := (h(s) c_1 \cdot j + c_2 \cdot j^2) \mod m$

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- ► Alternatively: $h(s,j) := (h(s) c_1 \cdot j + c_2 \cdot j^2) \mod m$
- Problem of secondary clustering:
 No local clustering anymore, but keys with same hash value have similar probe sequence

Hashing Open Addressing - Uniform Probing

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- ► Advantage: prevents clustering because different keys with the same hash value do not produce the same probe sequence
- ▶ **Disadvantage:** hard to implement

Open Addressing - Double Hashing

Double Hashing:

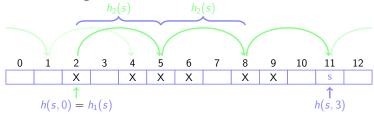


Figure: double hashing probe sequence

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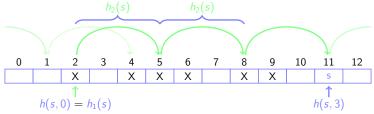


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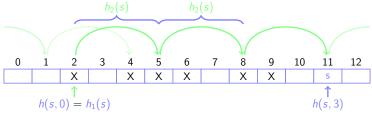


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- ▶ Use two independent hash functions $h_1(s)$, $h_2(s)$

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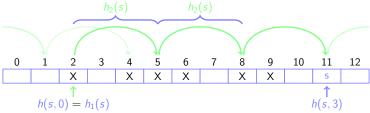


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- ► Motivation: consider key *s* in probe sequence
- Use two independent hash functions $h_1(s), h_2(s)$
- ► Hash function: $h(s,j) = (h_1(s) + j \cdot h_2(s)) \mod m$

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$$h_1(s), h_1(s) + h_2(s), h_1(s) + 2 \cdot h_2(s), h_1(s) + 3 \cdot h_2(s), \ldots$$

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- ► Works well in practical use
- This method is an approximation of uniform probing

Open Addressing - Double Hashing - Example

Open Addressing - Double Hashing - Example

$$h_1(s) = s \mod 7$$

 $h_2(s) = (s \mod 5) + 1$
 $h(s,j) = h_1(s) + j \cdot h_2(s) \mod 7$

Open Addressing - Double Hashing - Example

Example:

$$h_1(s) = s \mod 7$$

 $h_2(s) = (s \mod 5) + 1$
 $h(s,j) = h_1(s) + j \cdot h_2(s) \mod 7$

Table: comparing both hash functions

s
 10
 19
 31
 22
 14
 16

$$h_1(s)$$
 3
 5
 3
 1
 0
 2

 $h_2(s)$
 1
 5
 2
 3
 5
 2

► The efficiency of double hashing is dependent on $h_1(s) \neq h_2(s)$

Open Addressing - Double Hashing - Optimization

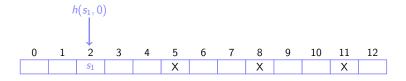


Figure: double hashing

Double hashing by Brent:

Open Addressing - Double Hashing - Optimization

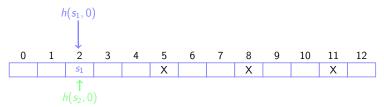


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Double hashing by Brent:

Motivation:

Because different keys have different probe sequences, the sequence of the insertions has impact on efficiency of a sucessful search

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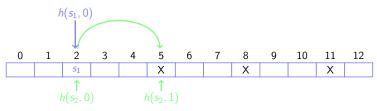


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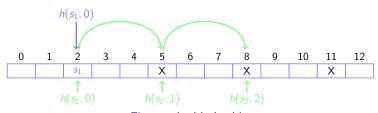


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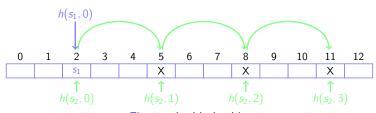


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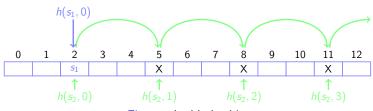


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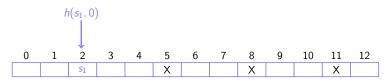


Figure: double hashing

Example:

▶ The key s_1 is inserted at position $p_1 = h(s_1, 0)$

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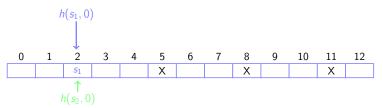


Figure: double hashing

- ▶ The key s_1 is inserted at position $p_1 = h(s_1, 0)$
- ▶ The hash function for s_2 also results in $p_2 = h(s_2, 0) = p_1$

Open Addressing - Double Hashing - Optimization

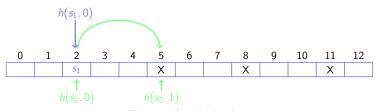


Figure: double hashing

- ▶ The key s_1 is inserted at position $p_1 = h(s_1, 0)$
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Open Addressing - Double Hashing - Optimization

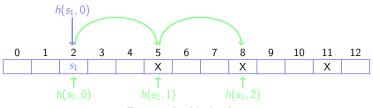


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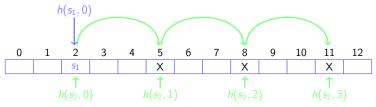


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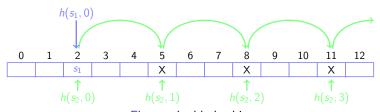


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- If we insert s_2 at position $h(s_2, n+1)$ the search will be inefficient



Figure: double hashing by Brent

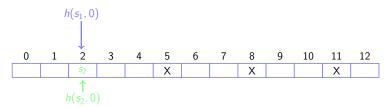


Figure: double hashing by Brent

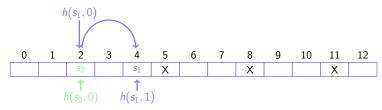


Figure: double hashing by Brent

Open Addressing - Double Hashing - Optimization

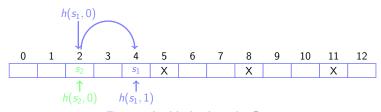


Figure: double hashing by Brent

Reversed sequence of keys would have been better

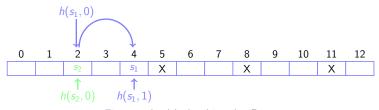


Figure: double hashing by Brent

- Reversed sequence of keys would have been better
- Brent's idea:

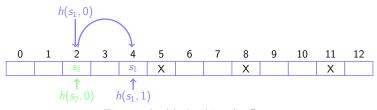
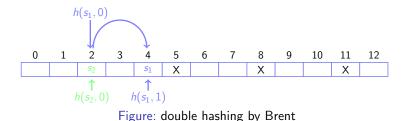


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 - ▶ Test if location $h(s_1, 1)$ is free



- Reversed sequence of keys would have been better
- Brent's idea:
 - ► Test if location $h(s_1, 1)$ is free
 - ▶ If yes, move s_1 from $h(s_1, 0)$ to $h(s_1, 1)$ and insert s_2 at $h(s_2, 0)$

Open Addressing - Ordered Hashing

Idea:

- Motivation: colliding elements are inserted in the hash table sorted.
- ► Therefore, in case of an unsuccessful search of elements in combination with linear probing or double hashing, aborting is possible earlier because single probing steps have a fixed length

Implementation:

- Compare both keys if a collision occurs
- ▶ Insert the smaller key at p₁
- Search a position based on the diversion order for the bigger key

Open Addressing - Ordered Hashing

- ▶ The key 12 is saved at position $p_1 = h(12, 0)$
- We insert the key 5 into the hash map
- We assume h(5,0) results in location p_1
- ▶ Because 5 < 12 we insert the key 5 at position p_1
- ► For the key 12 we iterate through the sequence

$$h(12,1), h(12,2), h(12,3), \ldots$$

Open Addressing - Robin-Hood Hashing

Motivation:

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Having similiar length of probe sequences for all elements. Total costs stay the same, but they are distributed evenly. Results in approximately similar search times for all elements

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Having similiar length of probe sequences for all elements.
 Total costs stay the same, but they are distributed evenly.
 Results in approximately similar search times for all elements

Implementation:

If two keys s_1, s_2 collide $(p_1 = h(s_1, j_1) = h(s_2, j_2))$ we compare the length of the sequence $(j_1 \text{ or } j_2)$

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Implementation:

- If two keys s_1 , s_2 collide $(p_1 = h(s_1, j_1) = h(s_2, j_2))$ we compare the length of the sequence $(j_1 \text{ or } j_2)$
- ▶ The key with the bigger search sequence is inserted at p_1 . The other key is assigned to a new location based on the sequence

Open Addressing - Robin-Hood Hashing

- ▶ The key 12 is saved at position $p_1 = h(12,7)$
- ▶ We insert the key 5 into the hash map
- We assume h(5,0) results in location p_1
- ▶ Because $j_1 < j_2$ (0 < 7) key 12 stays at position p_1
- For key 5 we iterate through the sequence

$$h(5,1), h(5,2), h(5,3), \ldots$$

Open Addressing - Implement Insert / Remove

Problem:

- ▶ The key s_1 is inserted at position p_1
- ▶ The key s_2 returns the same hash value, but is inserted at position p_2 because of the probing order
- ▶ If s_1 is removed, it is impossible to find s_2

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Solution:

Open Addressing - Implement Insert / Remove

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Solution:

Remove: elements are marked as removed, but not deleted

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- ▶ If s_1 is removed, it is impossible to find s_2

Solution:

- Remove: elements are marked as removed, but not deleted
- Inserting: elements marked as removed will we overwritten

Structure

Hashing

Recapitulation
Treatment of hash collisions
Open Addressing
Summary

Priority Queue Introduction

Open Addressing - Summary Collision Handling

Bucket as linked list: (dynamic, number of elements variable)

Save colliding elements as linked list

Open hashing: (static, number of elements fixed)

- Determine a probe sequence, permutation of all hash values
- Linear, quadratic probing:
 - Easy to implement
 - Raises the probability of collisions because probing order does not depend on the key

Open Addressing - Summary Collision Handling

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 - Avoids clustering of elements

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Improving efficiency: (Brent, Ordered Hashing)

- Improve search efficiency by sorting colliding insertions
 - Abortion of unsuccessfull search
 - Search sequence length balancing

Open Addressing - Summary Hashing

Hashing:

Open Addressing - Summary Hashing

Hashing:

Efficiency of dictionary operations:

Insert: $O(1) \dots O(n)$ Search: $O(1) \dots O(n)$ Remove: $O(1) \dots O(n)$

Open Addressing - Summary Hashing

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Hashing:

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- ▶ Direct access oto all elements in a hash table
- Using a hash function to find the position (hash value) in the hash table
- Hash function, size of the hash table and strategy to avoid hash collisions all influence the efficiency of the data structure

Structure

Hashing

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Priority Queue Introduction

Introduction

Introduction

Definition:

► A priority queue saves a set of elements

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- Each element contains a key and a value like a map

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- Each element contains a key and a value like a map
- ► There is a total order (like ≤) defined on the keys

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The priority queue supports the following operations:

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▶ Sometimes additional operations are defined:

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changeKey(item, key): changes the key of the element
remove(item): removes the element from the queue
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Introduction

Introduction

Special features:

► Multiple elements with the same key

Introduction

- Multiple elements with the same key
 - No problem and for many applications necessary
 - If there is more than one element with the smallest key
 getMin():
 returns just one of the possible elements
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- ► Argument of changeKey and remove operations

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 - No problem and for many applications necessary
 - If there is more than one element with the smallest key
 getMin():
 returns just one of the possible elements
 deleteMin(): deletes the element returned by getMin
- Argument of changeKey and remove operations
 - ► There is no **quick access** to an element in the queue
 - That is why insert and getMin return a reference (handle, accessor object)
 - changeKey and remove take this reference as argument
 - Therefore each element has to store its current position in the heap.

Python

```
from queue import PriorityQueue

q = PriorityQueue()

e1 = (5, "A") # element with priority 5
q.put(e1); # insert element e1

# remove and return the lowest item
e2 = q.get()
```

Application Example

Example 1:

 Calculation of the sorted union of k sorted lists (multi-way merge or k-way merge)

 $L_1: \boxed{3} \boxed{5} \boxed{8} \boxed{12} \boxed{\ldots} \qquad L_3: \boxed{1} \boxed{10} \boxed{11} \boxed{24} \boxed{\ldots}$

 $L_2:$ $\begin{bmatrix} 4 & 5 & 6 & 7 & \dots \end{bmatrix}$

Application Example

Example 1:

 Calculation of the sorted union of k sorted lists (multi-way merge or k-way merge)

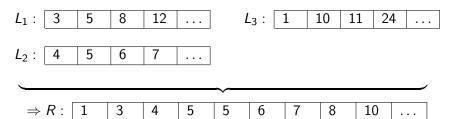


Figure: 3-way merge

Priority Queue Application Example

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Application Example

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► For example Dijkstra's algorithm for computing the shortest path (following lecture)

Application Example

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Example 2:

- ► For example Dijkstra's algorithm for computing the shortest path (following lecture)
- Among other applications it can be used for sorting

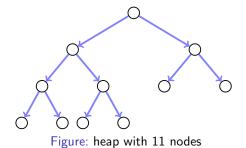
Implementation

Idea:

Implementation

Idea:

► Save elements as tuples in a binary heap



Implementation

Idea:

- Save elements as tuples in a binary heap
- ► Summary from lecture 1 (*HeapSort*):
 - Nearly complete binary tree
 - ► Heap condition:

The key of each node \leq the keys of the children

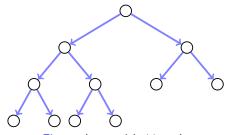


Figure: heap with 11 nodes

Implementation

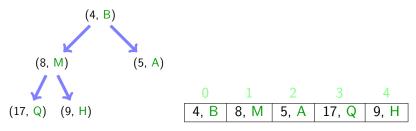


Figure: min heap stored in array

Implementation

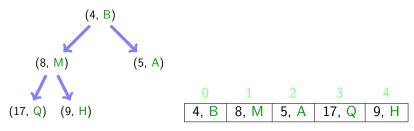


Figure: min heap stored in array

Storing a binary heap:

Implementation

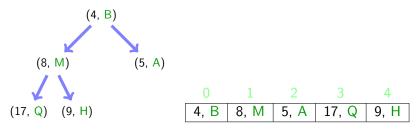


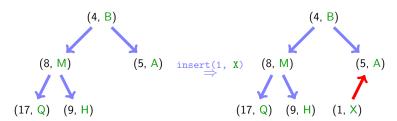
Figure: min heap stored in array

Storing a binary heap:

- ► Number nodes from top to bottom and left to right starting with 0 and store entries in array
- ► Children of node *i* are the nodes 2i + 1 and 2i + 2
- ▶ Parent node of node *i* is floor((i-1)/2)

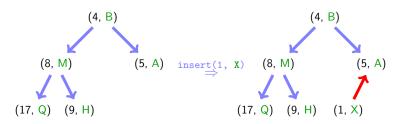
Implementation - Insertion

Inserting an element: insert(key, item)



Implementation - Insertion

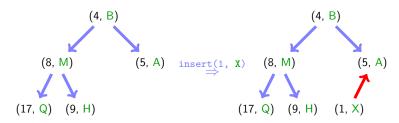
Inserting an element: insert(key, item)



Append the element at the end of the array

Implementation - Insertion

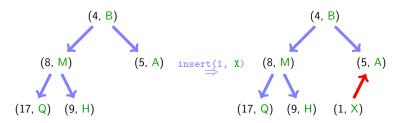
Inserting an element: insert(key, item)



- ► Append the element at the end of the array
- ► The heap condition may be violated, but only at the last index

Implementation - Insertion

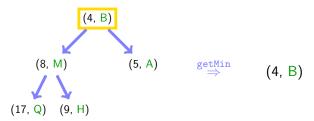
Inserting an element: insert(key, item)



- ► Append the element at the end of the array
- ▶ The heap condition may be violated, but only at the last index
- ▶ Repair heap condition ⇒ We will see later how to do this

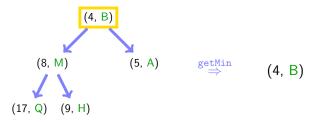
Implementation

Returning the minimum: getMin()



Implementation

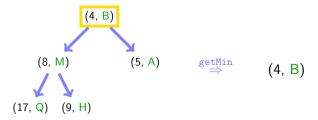
Returning the minimum: getMin()



► Else return the first element

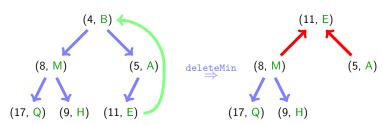
Implementation

Returning the minimum: getMin()



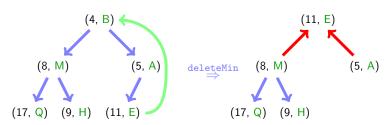
- ► Else return the first element
- ► If the heap is empty return None

Implementation



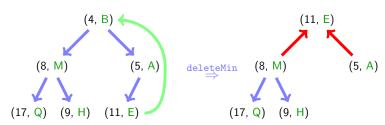
Implementation

Removing the minimum: deleteMin()



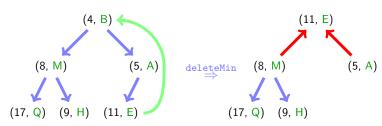
Deleting the element with the lowest key

Implementation



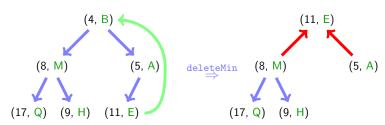
- Deleting the element with the lowest key
- Swap the last element with the first element and shrink the heap by one

Implementation



- Deleting the element with the lowest key
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- ► The heap condition may be violated, but only at the first index

Implementation

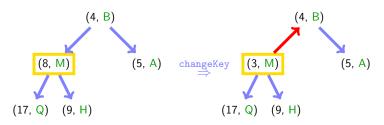


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Implementation

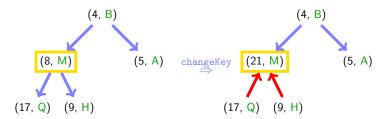
Changing the key (priority): changeKey(item, key)

- ▶ The element (queue item) is given as argument
- ► Replace the key of the element
- ► The heap condition may be violated, but only at the element index and only in one direction (up / down)
- ► Repair heap condition



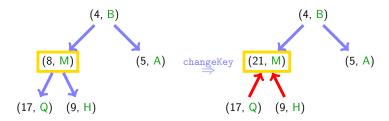
Implementation

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Implementation

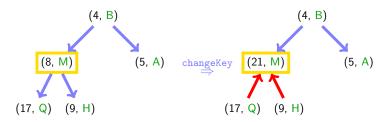
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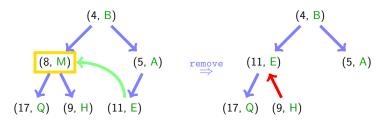
Implementation

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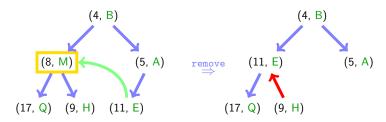
- ► The heap condition may be violated, but only at the element index and only in one direction (up / down)
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Implementation



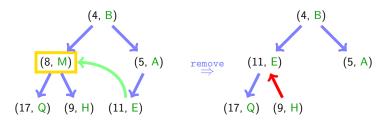
Implementation

Removing an element: remove(item)



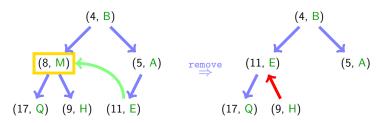
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Implementation



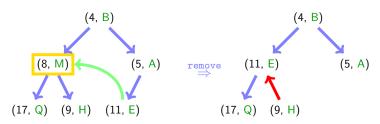
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Implementation



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Implementation



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Implementation - Reparing the Heap

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Repairing after modifying operations:

► The heap condition can be violated after using insert, deleteMin, changeKey, remove, but only at one known position with index i

Implementation - Reparing the Heap

- ► The heap condition can be violated after using insert, deleteMin, changeKey, remove, but only at one known position with index i
- ▶ Heap conditions can be violated in two directions:

Implementation - Reparing the Heap

- ► The heap condition can be violated after using insert, deleteMin, changeKey, remove, but only at one known position with index i
- Heap conditions can be violated in two directions:
 - ▶ Downwards: the key at index i is not ≤ than the value of its children

Implementation - Reparing the Heap

- ► The heap condition can be violated after using insert, deleteMin, changeKey, remove, but only at one known position with index i
- Heap conditions can be violated in two directions:
 - Downwards: the key at index i is not ≤ than the value of its children
 - ▶ Upwards: the key at index i is not ≥ than the value of its parent

Implementation - Reparing the Heap

Repairing after modifying operations:

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- Heap conditions can be violated in two directions:
 - Downwards: the key at index i is not ≤ than the value of its children
 - ▶ Upwards: the key at index i is not ≥ than the value of its parent
- We need two repair methods: repairHeapUp, repairHeapDown

Implementation - Reparing the Heap

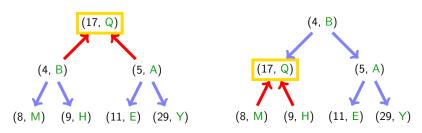


Figure: repairing the heap downwards

Implementation - Reparing the Heap

repairHeapDown:

▶ Sift the element until the heap condition is valid

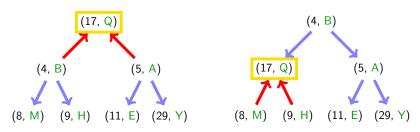


Figure: repairing the heap downwards

Implementation - Reparing the Heap

- Sift the element until the heap condition is valid
 - Change node with child, which has the lower key of both children

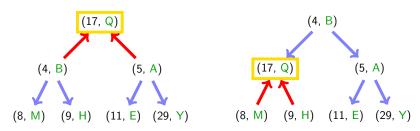


Figure: repairing the heap downwards

Implementation - Reparing the Heap

- Sift the element until the heap condition is valid
 - Change node with child, which has the lower key of both children
 - ▶ If the heap condition is violated repeat for the child node

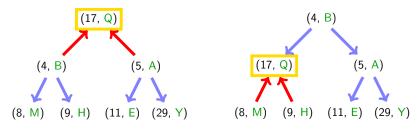


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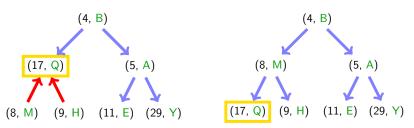


Figure: repairing the heap downwards

Implementation - Reparing the Heap

repairHeapUp:

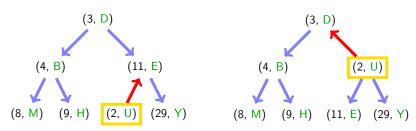


Figure: repairing the heap upwards

Implementation - Reparing the Heap

repairHeapUp:

► Change node with parent

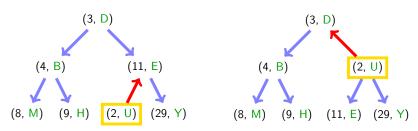


Figure: repairing the heap upwards

Implementation - Reparing the Heap

repairHeapUp:

- Change node with parent
- ▶ If the heap condition is violated repeat for parent node

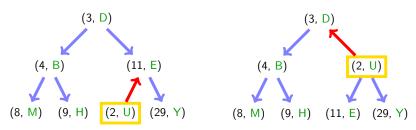


Figure: repairing the heap upwards

Implementation - Reparing the Heap

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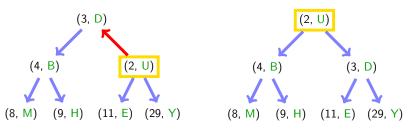


Figure: repairing the heap upwards

Implementation - Priority Queue Item

Index of a priority queue item:

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Index of a priority queue item:

- ► Attention: for changeKey and remove the item has to "know" where it is located in the heap
- Remember for repairHeapUp and repairHeapDown: update the index if moving an heap element

Implementation - Priority Queue Item - Python

```
class PriorityQueueItem:
    """Provides a handle for a queue item.
    This handle can be used to remove or
    update the queue item.
    0.00
    def __init__(self, key, value, index):
        self.key = key
        self.value = value
        self.index = index
```

Priority Queue Complexity

Summary lecture 1:

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- ▶ insert, deleteMin, changeKey, remove: we have to repair the heap: O(log n)
- **petMin**: return the element at index 0: O(1)

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Improvements (Fibonacci heaps):

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- The difference is negligible if the number of elements is relatively small
- Example:
 - For $n = 2^{10} \approx 1,000$, the depth $\log_2 n$ is only 10
 - ► For $n = 2^{20} \approx 1,000,000$, the depth $\log_2 n$ is only 20

Further Literature

Course literature

- [CRL01] Thomas H. Cormen, Ronald L. Rivest, and Charles E. Leiserson. Introduction to Algorithms. MIT Press, Cambridge, Mass, 2001.
- [MS08] Kurt Mehlhorn and Peter Sanders.
 Algorithms and data structures, 2008.
 https://people.mpi-inf.mpg.de/~mehlhorn/
 ftp/Mehlhorn-Sanders-Toolbox.pdf.

Further Literature

Priority Queue - Implementations / API

html#queue.PriorityQueue

```
[Cpp] C++ - priority_queue
    http:
    //www.sgi.com/tech/stl/priority_queue.html

[Jav] Java - PriorityQueue
    https://docs.oracle.com/javase/7/docs/api/
    java/util/PriorityQueue.html

[Pyt] Python - PriorityQueue
```

https://docs.python.org/3/library/queue.