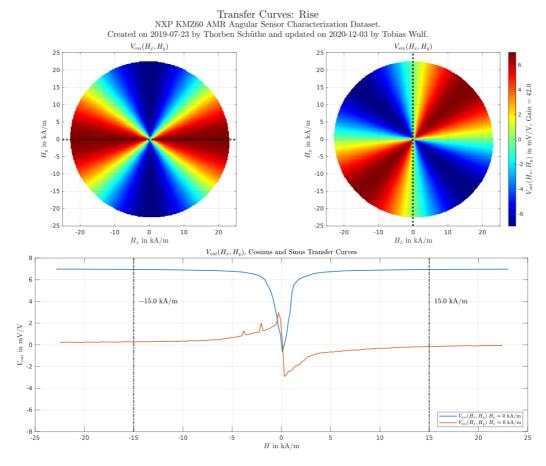
NXP KMZ60 Characterization

NXP KMZ60 characterization as second base of the sensor array simulation was although done before and was manually modified to same structure as TDK dataset. With additional values for bridge gain. TDK dataset is adjusted in the same way now. The raw dataset was aquirred after the method Thorben Schüthe describe in his IEEE paper for two-dimensional characterization of TMR angular sensors. The sensor characterized for both bridges a cosinus and sinus bridge. The bridges have a phisically phase shift of 90° so the sensor as able to reference a superimposed magnetic field flud in x- and y-direction. The field was generated by an cross coil setup.

The resulting AMR characterization field abstracts a full rotation for cosinus and sinus output voltages by representing two maximum and minimun areas in the characterization fields. So circular path on the characterization fields generates two sinoid periods related on current angle position between 0° and 180° or 180° and 360°.



Contents

- See Also
- Magnetic Stimulus
- Cosinuns Bridge Output
- Sinus Bridge Output
- Operating Point
- Dataset Structure

See Also

Magnetic Stimulus

The right stimulus is the keynote for characterization records. It needs to have the abillity record slow enough for quasi static recordings but is not allowed to be real static so the magnetic field is not interrupted during the recording. Therefore slow sinoid carrier functions with even slower amplitude modulation is choosen to provide a quasi static stimulus.

The carrier function for the Hx-field stimulus is related to the cosinus bridge and so:

$$c_1(t) = cos(\phi(t))$$

Due to the physically phase shift the Hy-field stimulus is related to sinus:

$$c_2(t) = sin(\phi(t))$$

Both carrier runs with same carrier frequency:

$$f_c = 3.2Hz$$

so they are executed with the phase vector over time:

$$\phi(t)=2\pi f_c t$$

The carrier functions are triangle modulated to generate rising and falling amplituded. The modulation frequency is set to:

$$f_{m} = 0.01 Hz$$

Which generates a stimulus with 320 periods where 160 periods feeds a rising and falling record each multiplied with maximum fieldstrength amplitude:

$$m(t) = H_{max} \cdot tri(t) = H_{max} \cdot tri(2(t-t_0)f_m)$$

$$t_0 = \frac{1}{2f_m}$$

So the Hx- and Hy-field stimulus is described by:

$$H_x(t) = m(t) \cdot c_1(t)$$

$$H_y(t) = m(t) \cdot c_1(t)$$

The stimulus amplitude depending on the phase in polar coordinates can be displayed for both parts by:

$$H_{x,y}(\phi) = |H_{x,y}(\phi)| \cdot e^{j\phi} = m(t) \cdot e^{j\phi(t)}$$

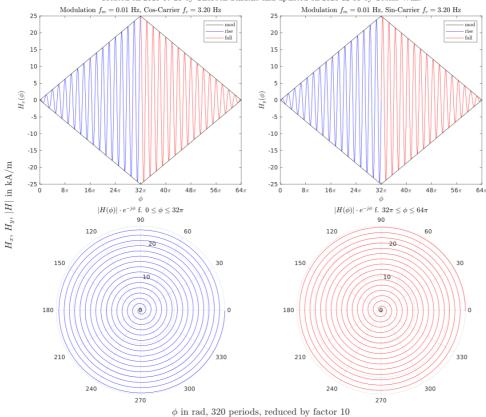
Where a rising spiral runs from center outwards for:

$$0 < t < t_0$$

And a falling spiral of amplitudes from outwards to center for:

$$t_0 < t < rac{1}{f_m}$$

$\begin{array}{c} {\rm Reconstructed} \ H_{x^-}/\ H_y\mbox{-Stimulus in Reduced View} \\ {\rm NXP\ KMZ60\ AMR\ Angular\ Sensor\ Characterization\ Dataset.} \\ {\rm Created\ on\ 2019\text{-}07\text{-}23\ by\ Thorben\ Schüthe\ and\ updated\ on\ 2020\text{-}12\text{-}03\ by\ Tobias\ Wulf.} \end{array}$



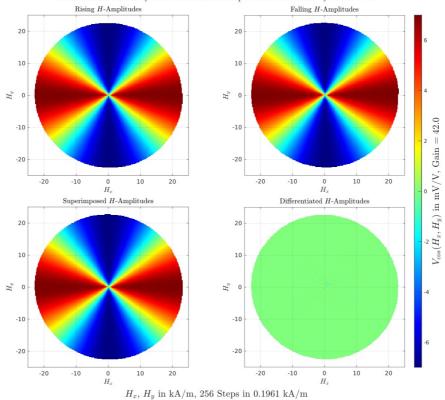
Cosinuns Bridge Output

The record characterization raw data are one dimensional time discrete vecotrs. To fieldstrength images like down below the recorded data must be referenced backwords to driven stimulus of Hx- and Hy-direction. But at first the image size of must be determined. Here fix size is set to 256px for each direction. So it spans a vector for Hx- and Hy-direction from minimum -25kA/m to maximum 25kA/m in 256 steps with a resolution of 0.1961kA/m. So it results into a 256x256 image. Now it runs for each point on the Hx- and Hy-axes and get the record index of the stimulus as backreference to the recorded bridge signal and sets the pixel. That runs for the rising modulation amplitude and falling amplitude until every pixel is hit and ended up into a dimensional function image as:

$$V_{cos}(H_x, H_y) = [mV/V]$$

The information of the image is build up in row. Reference Hx for constant Hy in each row. The method is also comparable to a historgram of Hx matches in the recorded sensor signal for one constant Hy and so on next historgram append on the next row for the next Hy.

$\begin{array}{c} \mbox{Measured Cosinus Bridge Outputs of Corresponding H_x-/$ H_y-Amplitudes} \\ \mbox{NXP KMZ60 AMR Angular Sensor Characterization Dataset.} \\ \mbox{Created on 2019-07-23 by Thorben Schüthe and updated on 2020-12-03 by Tobias Wulf.} \end{array}$

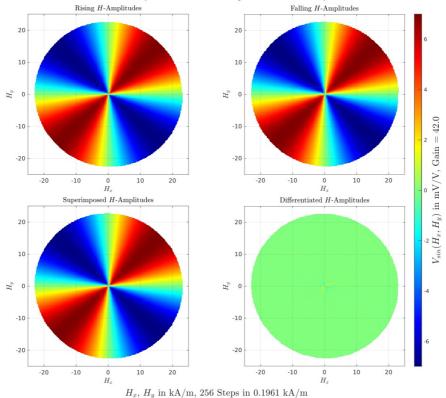


Sinus Bridge Output

The sinus characterization field is build up similar to the cosinus images but the information lays now in the columns so the data is collected in each column for a constant Hx and variable Hy:

$$V_{sin}(H_x,H_y)=[mV/V]$$

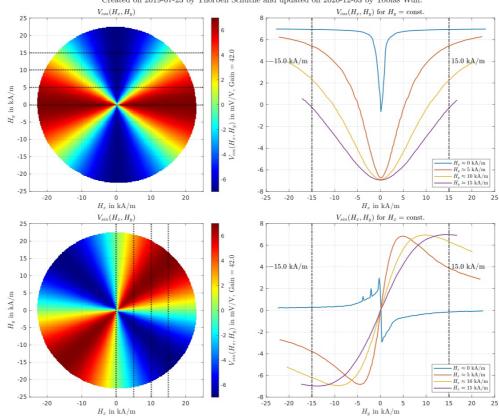
$\begin{array}{c} \mbox{Measured Sinus Bridge Outputs of Corresponding H_x-/$ H_y-Amplitudes} \\ \mbox{NXP KMZ60 AMR Angular Sensor Characterization Dataset.} \\ \mbox{Created on 2019-07-23 by Thorben Schüthe and updated on 2020-12-03 by Tobias Wulf.} \\ \end{array}$

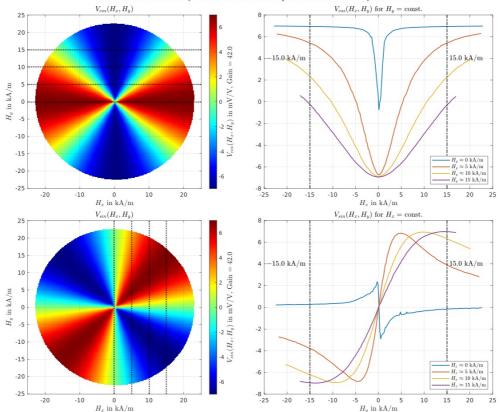


Operating Point

To determine an operating point in sensor array simulation the characterization fields needs some further investigation in static Hy and variable Hx field strength for cosinus bridge and vice versa for sinus bridge references. In compare to the TDK TMR the NXP AMR sensor has clear linear plateu. It has a continous non-linear areas divided in two maximum and minum areas. The best results for bridge outputs is supported by an operating point in saturation of the characterization fields so circular path on the fields should be described at 20 kA/m to 25 kA/m path radius.

Characterization Field: Rise NXP KMZ60 AMR Angular Sensor Characterization Dataset. Created on 2019-07-23 by Thorben Schüthe and updated on 2020-12-03 by Tobias Wulf.





Dataset Structure

Info:

The dataset is parted in two main structs. The first one is filled with meta data. So it represents the file header. The struct is called Info and contains information about how the dataset is aquirred. So the stimulus is reconstructable from that meta data.

- Created string, contains dataset creation date
- Creator string, contains dataset creator
- Edited string, contains last time edited date
- Editor string, contains last time editor
- Senor string, sensor identification name e.g. TAS2141
- SensorType string, kind of sensor e.g. Angular
- \blacksquare SensorTechnology string, bridge technology e.g. AMR, GMR, TMR
- SensorManufacturer string, producer or supplier e.g. NXP, TDK
- MagneticField struct, contains further information about Hx and Hy
- SensorOutput struct, contains information about sensor produced output and gathered image information
- Units struct, contains information about used si units in dataset

■ MagneticField:

■ Modulation - string, contains modulation equivalent Matlab function

- ModulationFrequency double, contains frequeny of modulation in Hz
- CarrierFrequency double, carrier frequency for both Hx and Hy carrier in Hz
- MaxAmplitude double, maximum Hx and Hy field amplitude in kA/m
- MinAmplitude double, minimum Hx and Hy field amplitude in kA/m
- Steps double, Hx- and Hy-field steps to build characterization images
- Resolution double, resolution of one step in kA/m
- CarrierHx string, contains Hx carrier equivalent Matlab function
- CarrierHy string, contains Hy carrier equivalent Matlab function

■ SensorOutput:

- CosinusBridge struct, contains further information about sensor cosinus bridge outpus
- SinusBridge struct, contains further information about sensor sinus bridge outputs
- BridgeGain double, scalar factor of bridge gain for output voltage

■ CosinusBridge/ SinusBridge:

- xDimension double, image size in x-direction
- yDimension double, image size in y-direction
- xDirection string, x-axis label
- yDirection string, y-axis label
- Orientation string, orientation of varying data, row or column
- Determination cell, images in data {"Rise", "Fall", "All", "Diff"}

■ Units:

- MagneticFieldStrength string, kA/m
- Frequency string, Hz
- SensorOutputVoltage string, mV/V

Data:

The second struct contains the preporcessed characteriazation data of the TDK TAS2141 TMR angular Sensor. It is divided into two main structs one for the magnetic field reference points of the characterization images and one for the characteriazation sensor output images.

- MagneticField struct, contain Hx- and Hy-field vectors which are the resolution references to each pixel in the characterization images of the sensors preprocessed bridge outputs
- SensorOutput struct, contains structs for cosinus and sinus bridge outputs preprocessed in images of size of 256x256 pixels where each pixels references a bridge output in mV to a certain Hx- and Hy-fieldstrength amplitude

■ MagneticField:

- hx array, Hx field axis of characteriazation images column vector of 1x256 double values from -25 kA/m to 25 kA/m with a resolution of 0.1961 kA/m
- hy array, Hy field axis of characteriazation images column vector of 1x256 double values from -25 kA/m to 25 kA/m with a resolution of 0.1961 kA/m

■ SensorOutput:

- CosinusBridge struct, contains preprocessed characterization results of the sensors cosinus bridge outputs
- SinusBridge struct, contains preprocessed characterization results of the sensors sinus bridge outputs

■ CosinusBridge:

 Rise - array, double array of size 256x256 which references the cosinus bridge outputs for rising modulated stimulus amplitude to each cross reference of vectors MagneticField.hx and MagneticField.hy

- Fall array, double array of size 256x256 which references the cosinus bridge outputs for falling modulated stimulus amplitude to each cross reference of vectors MagneticField.hx and MagneticField.hy
- All array, double array of size 256x256 superimposed image of Rise and Fall
- Diff array, double array of size 256x256 differentiated image of Rise and Fall

■ SinusBridge:

- Rise array, double array of size 256x256 which references the sinus bridge outputs for rising modulated stimulus amplitude to each cross reference of vectors MagneticField.hx and MagneticField.hy
- Fall array, double array of size 256x256 which references the sinus bridge outputs for falling modulated stimulus amplitude to each cross reference of vectors MagneticField.hx and MagneticField.hy
- All array, double array of size 256x256 superimposed image of Rise and Fall
- Diff array, double array of size 256x256 differentiated image of Rise and Fall

The edited raw dataset provided from Thorben Schüthe is save with Matlabs build-in save function in a certain way to perform partial loads from the dataset.

```
save('data/NXP_KMZ60_Characterization_2020-12-03_16-53-16-721.mat', ...
'Info', 'Data', '-v7.3', '-nocompression')
```

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