# plotSimulationCosSinStats

Search for available trainings or test dataset and plot dataset. Follow user input dialog to choose which dataset to plot and statistics of cos sin. Save created plot to file. Filename same as dataset with attached info.

## **Syntax**

plotSimulationCosSinStats()

#### Description

plotSimulationCosSinStats() plot training or test dataset which are loacated in data/test or data/training. The function lists all datasets and the user must decide during user input dialog which dataset to plot. It loads path from config.mat and scans for file automatically.

### **Examples**

plotSimulationCosSinStats()

### **Input Argurments**

None

### **Output Argurments**

None

### Requirements

- Other m-files required: None
- Subfunctions: None
- MAT-files required: config.mat

#### See Also

- generateSimulationDatasets
- sensorArraySimulation
- generateConfigMat

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```
function plotSimulationCosSinStats()
  try
     disp('Plot simulation dataset ...');
     close all;
      % load path variables
     load('config.mat', 'PathVariables');
      % scan for datasets
     TrainingDatasets = dir(fullfile(PathVariables.trainingDataPath, ...
         'Training_*.mat'));
     TestDatasets = dir(fullfile(PathVariables.testDataPath, 'Test_*.mat'));
     allDatasets = [TrainingDatasets; TestDatasets];
      % check if files available
     if isempty(allDatasets)
         error('No training or test datasets found.');
```

```
catch ME
  rethrow(ME)
% number of datasets
nDatasets = length(allDatasets);
fprintf('Found %d datasets:\n', nDatasets)
for i = 1:nDatasets
  fprintf('%s\t:\t(%d)\n', allDatasets(i).name, i)
% get numeric user input to indicate which dataset to plot
iDataset = input('Type number to choose dataset to plot to: ');
ds = load(fullfile(allDatasets(iDataset).folder, ...
     allDatasets(iDataset).name));
   % check how many angles in dataset and let user decide how many to
   % render in polt
  fprintf('Detect %d angles in dataset ...\n', ...
     ds.Info.UseOptions.nAngles);
  nSubAngles = input('How many angles to you wish to plot: ');
   % nSubAngles = 120;
   % indices for data to plot, get sample distance for even distance
  sampleDistance = length(downsample(ds.Data.angles, nSubAngles));
   % get subset of angles
  subAngles = downsample(ds.Data.angles, sampleDistance);
  nSubAngles = length(subAngles); % just ensure
  \% get indices for subset data
  indices = find(ismember(ds.Data.angles, subAngles));
catch ME
  rethrow(ME)
fPath = fullfile(PathVariables.saveFiguresPath);
fSvgPath = fullfile(PathVariables.saveImagesPath, 'svg');
fEpsPath = fullfile(PathVariables.saveImagesPath, 'eps');
fPdfPath = fullfile(PathVariables.saveImagesPath, 'pdf');
fig = figure('Name', 'Sensor Array', ...
   'NumberTitle' , 'off', ...
   'WindowStyle', 'normal', ...
   'MenuBar', 'none', ...
   'ToolBar', 'none', ...
   'Units', 'centimeters', ..
   'OuterPosition', [0 0 37 29], ...
   'PaperType', 'a4', ...
   'PaperUnits', 'centimeters', ...
   'PaperOrientation', 'landscape', ...
   'PaperPositionMode', 'auto', ...
   'DoubleBuffer', 'on', ...
   'RendererMode', 'manual', ...
   'Renderer', 'painters');
```

```
tdl = tiledlayout(fig, 2, 1, ...
    'Padding', 'compact', ...
    'TileSpacing' , 'compact');
title(tdl, 'Sensor Array Simulation', ...
   'FontWeight', 'normal', ...
    'FontSize', 18, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');
subline1 = "Sensor Array (%s) of $%d\\times%d$ sensors, " + ...
    "an edge length of $%.1f$ mm, a rel. pos. to magnet surface of";
subline2 = " $(%.1f, %.1f, -(%.1f))$ in mm, a magnet tilt" + ...
   " of $%.1f^\\circ$, a sphere radius of $%.1f$ mm, a imprinted";
subline3 = "field strength of $%.1f$ kA/m at $%.1f$ mm from" + ...
   " sphere surface in z-axis, $%d$ rotation angles with a ";
subline4 = "step width of $%.1f^\\circ$ and a resolution of" + ...
    " $%.1f^\\circ$. Visualized is a subset of $%d$ angles in ";
subline5 = "sample distance of $%d$ angles. Based on %s" + ...
   " characterization reference %s.":
sub = [sprintf(subline1, ...
              ds.Info.SensorArrayOptions.geometry, ...
              ds.Info.SensorArrayOptions.dimension, ...
              ds.Info.SensorArrayOptions.dimension, ...
              ds.Info.SensorArrayOptions.edge); ...
      sprintf(subline2, ...
             ds.Info.UseOptions.xPos, ...
              ds.Info.UseOptions.yPos, ...
              ds.Info.UseOptions.zPos, ...
              ds.Info.UseOptions.tilt, ...
             ds.Info.DipoleOptions.sphereRadius); ...
      sprintf(subline3, ...
              ds.Info.DipoleOptions.HOmag, ...
              ds.Info.DipoleOptions.z0, ...
              ds.Info.UseOptions.nAngles); ...
      sprintf(subline4, ...
             ds.Data.angleStep, ...
              ds.Info.UseOptions.angleRes, ...
             nSubAngles)
      sprintf(subline5, ...
             sampleDistance, ...
              ds.Info.CharData, ...
              ds.Info.UseOptions.BridgeReference)];
subtitle(tdl, sub, ...
   'FontWeight', 'normal', ...
    'FontSize', 14, ...
    'FontName', 'Times', ...
   'Interpreter', 'latex');
M = ds.Info.SensorArrayOptions.dimension^2;
% N = ds.Info.UseOptions.nAngles;
res = ds.Info.UseOptions.angleRes;
%angles = ds.Data.angles;
anglesIP = 0:res:360-res;
% load V subset and reshape for easier computing statistics
Vcos = squeeze(reshape(ds.Data.Vcos(:,:,indices), 1, M, nSubAngles));
Vsin = squeeze(reshape(ds.Data.Vsin(:,:,indices), 1, M, nSubAngles));
```

```
% load offset voltage to subtract from cosinus, sinus voltage
Voff = ds.Info.SensorArrayOptions.Voff;
Vcc = ds.Info.SensorArrayOptions.Vcc;
% interpolate with makima makes best results, ensure to kill nans for
% fill otherwise fill strokes, use linstyle none for fill without frame
interpM = 'makima';
VcosMean = mean(Vcos, 1);
VcosMeanIP = interp1(subAngles, VcosMean, anglesIP, interpM);
VcosStd = std(Vcos, 1, 1);
VcosVar = var(Vcos, 1, 1); % std^2
% meanvariation coefficient in percent
VcosMVCP = mean(VcosStd ./ VcosMean) * 100;
VcosUpper1 = VcosMean + VcosStd;
VcosUpper2 = VcosMean + VcosVar;
VcosLower1 = VcosMean - VcosStd;
VcosLower2 = VcosMean - VcosVar;
VcosUpper1IP = interp1(subAngles, VcosUpper1, anglesIP, interpM);
VcosUpper1IP = fillmissing(VcosUpper1IP, 'previous');
VcosLower1IP = interp1(subAngles, VcosLower1, anglesIP, interpM);
VcosLower1IP = fillmissing(VcosLower1IP, 'previous');
VcosUpper2IP = interp1(subAngles, VcosUpper2, anglesIP, interpM);
VcosUpper2IP = fillmissing(VcosUpper2IP, 'previous');
VcosLower2IP = interp1(subAngles, VcosLower2, anglesIP, interpM);
VcosLower2IP = fillmissing(VcosLower2IP, 'previous');
VsinMean = mean(Vsin, 1);
VsinMeanIP = interp1(subAngles, VsinMean, anglesIP, interpM);
VsinStd = std(Vsin, 1, 1);
VsinVar = var(Vsin, 1, 1); % std^2
% meanvariation coefficient in percent
VsinMVCP = mean(VsinStd ./ VsinMean) * 100;
VsinUpper1 = VsinMean + VsinStd;
VsinUpper2 = VsinMean + VsinVar;
VsinLower1 = VsinMean - VsinStd;
VsinLower2 = VsinMean - VsinVar;
VsinUpper1IP = interp1(subAngles, VsinUpper1, anglesIP, interpM);
VsinUpper1IP = fillmissing(VsinUpper1IP, 'previous');
VsinLower1IP = interp1(subAngles, VsinLower1, anglesIP, interpM);
VsinLower1IP = fillmissing(VsinLower1IP, 'previous');
VsinUpper2IP = interp1(subAngles, VsinUpper2, anglesIP, interpM);
VsinUpper2IP = fillmissing(VsinUpper2IP, 'previous');
VsinLower2IP = interp1(subAngles, VsinLower2, anglesIP, interpM);
VsinLower2IP = fillmissing(VsinLower2IP, 'previous');
```

```
% Vcos
nexttile;
hold on;
fillStdX = [anglesIP, fliplr(anglesIP)];
fillStdY = [VcosLower1IP, fliplr(VcosUpper1IP)];
fill(fillStdX, fillStdY, [0.95 0.95 0.95], 'LineStyle', 'none');
fillVarX = [anglesIP, fliplr(anglesIP)];
fillVarY = [VcosLower2IP, fliplr(VcosUpper2IP)];
fill(fillVarX, fillVarY, [0.7 0.7 0.7], 'LineStyle', 'none');
yline(Voff, 'k--');
scatter(subAngles, VcosUpper1, [], 'r*');
plot(anglesIP, VcosUpper1IP, 'r-.');
scatter(subAngles, VcosMean, [], 'm*');
plot(anglesIP, VcosMeanIP, 'm-.');
scatter(subAngles, VcosLower1, [], 'b*');
plot(anglesIP, VcosLower1IP, 'b-.');
hold off;
xlim([-res 360-res]);
%ylim(ylimits);
grid on;
xlabel('$\theta$ in Degree', ...
   'FontWeight', 'normal', ...
   'FontSize', 12, ...
    'FontName', 'Times', ...
   'Interpreter', 'latex');
ylabel('$V{cos}(\theta)$ in V', ...
   'FontWeight', 'normal', ...
    'FontSize', 12, ...
   'FontName', 'Times', ...
   'Interpreter', 'latex');
title(sprintf(...
   "Compare V_{\cos}(\t Array Member \_{cc} = ..."
    "V, $V_{off} = %.2f$ V, $\\bar{\\sigma_\\mu} = %.2f$ perc.", ...
   Vcc, Voff, VcosMVCP), ...
   'FontWeight', 'normal', ...
   'FontSize', 12, ...
   'FontName', 'Times', ...
   'Interpreter', 'latex');
% Vsin
nexttile;
hold on;
fillStdX = [anglesIP, fliplr(anglesIP)];
fillStdY = [VsinLower1IP, fliplr(VsinUpper1IP)];
11 = fill(fillStdX, fillStdY, [0.95 0.95 0.95], 'LineStyle', 'none');
fillVarX = [anglesIP, fliplr(anglesIP)];
fillVarY = [VsinLower2IP, fliplr(VsinUpper2IP)];
12 = fill(fillVarX, fillVarY, [0.7 0.7 0.7], 'LineStyle', 'none');
```

```
13 = yline(Voff, 'k--');
14 = scatter(subAngles, VsinUpper1, [], 'r*');
15 = plot(anglesIP, VsinUpper1IP, 'r-.');
16 = scatter(subAngles, VsinMean, [], 'm*');
17 = plot(anglesIP, VsinMeanIP, 'm-.');
18 = scatter(subAngles, VsinLower1, [], 'b*');
19 = plot(anglesIP, VsinLower1IP, 'b-.');
hold off:
xlim([-res 360-res]);
grid on;
xlabel('$\theta$ in Degree', ...
   'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
   'Interpreter', 'latex');
ylabel('$V{sin}(\theta)$ in V', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
   'FontName', 'Times', ...
    'Interpreter', 'latex');
title(sprintf(...
   "Compare V_{\sin} (\theta)  for each Array Member V_{cc} = ...
    " V, V_{off} = .2f \ V, \lambda = .2f \ perc." ...
   Vcc, Voff, VsinMVCP), ...
    'FontWeight', 'normal', ...
   'FontSize', 12, ...
    'FontName', 'Times', ...
   'Interpreter', 'latex');
1 = [11 12 13 14 15 16 17 18 19];
L = legend(1, {'$2\sigma$', ...
             '$2\sigma^2$', ...
             '$V_{off}$', ...
             '$U_{lim} = \mu + \sigma$', ...
             \texttt{sprintf('\$\%s(U_{\{1im\}})\$', interpM), ...}
             '$\mu(V)$', ...
             sprintf('$%s(\\mu)$', interpM), ...
             '$L_{lim} = \mu - \sigma$', ...
            sprintf('$%s(L_{1im})$', interpM)}, ...
   'FontWeight', 'normal', ...
   'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');
L.Layout.Tile = 'east';
% get file path to save figure with angle index
[~, fName, ~] = fileparts(ds.Info.filePath);
% save to various formats
yesno = input('Save? [y/n]: ', 's');
if strcmp(yesno, 'y')
   fLabel = input('Enter file label: ', 's');
   fName = fName + "_StatsPlot_" + fLabel;
   savefig(fig, fullfile(fPath, fName));
   print(fig, fullfile(fSvgPath, fName), '-dsvg');
```

```
print(fig, fullfile(fEpsPath, fName), '-depsc', '-tiff', '-loose');
    print(fig, fullfile(fPdfPath, fName), '-dpdf', '-loose', '-fillpage');
end
    close(fig);
end
```

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