

plotSimulationDataset

Search for available trainings or test dataset and plot dataset. Follow user input dialog to choose which dataset and decide how many angles to plot. Save dataset content redereed to an avi-file. Filename same as dataset.

Syntax

```
plotSimulationDataset()
```

Description

plotSimulationDataset() plot training or test dataset which are loacated in data/test or data/training. The function lists all datasets and the user must decide during user input dialog which dataset to plot and how many angles to visualize. It loads path from config.mat and scans for file automatically.

Examples

```
plotSimulationDataset()
```

Input Argurments

None

Output Argurments

None

Requirements

- Other m-files required: None
- Subfunctions: None
- MAT-files required: config.mat

See Also

- [generateSimulationDatasets](#)
- [sensorArraySimulation](#)
- [generateConfigMat](#)

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```
function plotSimulationDataset()
    % scan for datasets and load needed configurations %%%%%%%%%%%%%%%
    %%%%%%%%%%%%%%%
    try
        disp('Plot simulation dataset ...');
        close all;
        % load path variables
        load('config.mat', 'PathVariables');
        % scan for datasets
        TrainingDatasets = dir(fullfile(PathVariables.trainingDataPath, ...
            'Training_*.mat'));
        TestDatasets = dir(fullfile(PathVariables.testDataPath, 'Test_*.mat'));
        allDatasets = [TrainingDatasets; TestDatasets];
        % check if files available
        if isempty(allDatasets)
            error('No training or test datasets found.');
```

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catch ME
    rethrow(ME)
end

% display available datasets to user, decide which to plot %%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

% number of datasets
nDatasets = length(allDatasets);
fprintf('Found %d datasets:\n', nDatasets)
for i = 1:nDatasets
    fprintf('%s\t:\t(%d)\n', allDatasets(i).name, i)
end
% get numeric user input to indicate which dataset to plot
iDataset = input('Type number to choose dataset to plot to: ');
% iDataset = 2;

% load dataset and ask user which one and how many angles %%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
try
    ds = load(fullfile(allDatasets(iDataset).folder, ...
        allDatasets(iDataset).name));
    % check how many angles in dataset and let user decide how many to
    % render in plot
    fprintf('Detect %d angles in dataset ...\n',...
        ds.Info.UseOptions.nAngles);
    nSubAngles = input('How many angles to you wish to plot: ');
    % nSubAngles = 120;
    % indices for data to plot, get sample distance for even distance
    sampleDistance = length(downsample(ds.Data.angles, nSubAngles));
    % get subset of angles
    subAngles = downsample(ds.Data.angles, sampleDistance);
    nSubAngles = length(subAngles); % just ensure
    % get indices for subset data
    indices = find(ismember(ds.Data.angles, subAngles));
catch ME
    rethrow(ME)
end

% create dataset figure for a subset or all angle %%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fig = figure('Name', 'Sensor Array', ...
    'NumberTitle', 'off', ...
    'WindowStyle', 'normal', ...
    'MenuBar', 'none', ...
    'ToolBar', 'none', ...
    'Units', 'centimeters', ...
    'OuterPosition', [0 0 30 30], ...
    'PaperType', 'a4', ...
    'PaperUnits', 'centimeters', ...
    'PaperOrientation', 'landscape', ...
    'PaperPositionMode', 'auto', ...
    'DoubleBuffer', 'on', ...
    'RendererMode', 'manual', ...
    'Renderer', 'painters');

tdl = tiledlayout(fig, 2, 2, ...
    'Padding', 'normal', ...
    'TileSpacing', 'compact');

title(tdl, 'Sensor Array Simulation', ...

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'FontWeight', 'normal', ...
'FontSize', 18, ...
'FontName', 'Times', ...
'Interpreter', 'latex');

subline1 = "Sensor Array (%s) of  $\times$  sensors, an edge" + ...
    " length of %.1f mm, a rel. pos. to magnet surface of";
subline2 = "  $(x, y, z)$  in mm, a magnet" + ...
    " tilt of  $^\circ$ , a sphere radius of %.1f mm, a imprinted";
subline3 = "field strength of %.1f kA/m at %.1f mm" + ...
    " from sphere surface in z-axis, rotation angles with a ";
subline4 = "step width of  $^\circ$  and a resolution" + ...
    " of  $^\circ$ . Visualized is a subset of angles in ";
subline5 = "sample distance of angles. Based on %s" + ...
    " characterization reference %s.";
sub = [sprintf(subline1, ...
    ds.Info.SensorArrayOptions.geometry, ...
    ds.Info.SensorArrayOptions.dimension, ...
    ds.Info.SensorArrayOptions.dimension, ...
    ds.Info.SensorArrayOptions.edge); ...
    sprintf(subline2, ...
    ds.Info.UseOptions.xPos, ...
    ds.Info.UseOptions.yPos, ...
    ds.Info.UseOptions.zPos, ...
    ds.Info.UseOptions.tilt, ...
    ds.Info.DipoleOptions.sphereRadius); ...
    sprintf(subline3, ...
    ds.Info.DipoleOptions.H0mag, ...
    ds.Info.DipoleOptions.z0, ...
    ds.Info.UseOptions.nAngles); ...
    sprintf(subline4, ...
    ds.Data.angleStep, ...
    ds.Info.UseOptions.angleRes, ...
    nSubAngles)
    sprintf(subline5, ...
    sampleDistance, ...
    ds.Info.CharData, ...
    ds.Info.UseOptions.BridgeReference)];

subtitle(tdl, sub, ...
    'FontWeight', 'normal', ...
    'FontSize', 14, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

% get subset of needed data to plot, only one load %%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
N = ds.Info.SensorArrayOptions.dimension;
X = ds.Data.X;
Y = ds.Data.Y;
Z = ds.Data.Z;

% calc limits of plot 1
maxX = ds.Info.UseOptions.xPos + ds.Info.SensorArrayOptions.edge;
maxY = ds.Info.UseOptions.yPos + ds.Info.SensorArrayOptions.edge;
minX = ds.Info.UseOptions.xPos - ds.Info.SensorArrayOptions.edge;
minY = ds.Info.UseOptions.yPos - ds.Info.SensorArrayOptions.edge;

% calculate colormap to identify scatter points
c=zeros(N,N,3);
for i = 1:N
    for j = 1:N

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        c(i,j,:) = [(2*N+1-2*i), (2*N+1-2*j), (i+j)]/2/N;
    end
end
c = squeeze(reshape(c, N^2, 1, 3));

% load offset voltage to subtract from cosinus, sinus voltage
Voff = ds.Info.SensorArrayOptions.Voff;

% plot sensor grid in x and y coordinates and constant z layer %%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
ax1 = nexttile(1);
% plot each coordinate in loop to create a special shading constant
% reliable to orientation for all matrice
hold on;
scatter(X(:, Y(:, []), c, 'filled', 'MarkerEdgeColor', 'k', ...
        'LineWidth', 0.8);

% axis shape and ticks
axis square xy;
axis tight;
grid on;
xlim([minX maxX]);
ylim([minY maxY]);

% text and labels
text(minX+0.2, minY+0.2, ...
    sprintf('$Z = %.1f$ mm', Z(1)), ...
    'Color', 'k', ...
    'FontSize', 16, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

xlabel('$X$ in mm', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

ylabel('$Y$ in mm', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

title(sprintf('Sensor Array %d\\times%d$', N, N), ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

hold off;

% plot rotation angles in polar view %%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
nexttile(2);
% plot all angles grayed out
polarscatter(ds.Data.angles/180*pi, ...
    ones(1, ds.Info.UseOptions.nAngles), ...
    [], [0.8 0.8 0.8], 'filled');

% radius ticks and label
rticks(1);

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rticklabels("");
hold on;

% plot subset of angles
% polarscatter(subAngles/180*pi, ones(1, nSubAngles), ...
%   'k', 'LineWidth', 0.8);
ax2 = gca;

% axis shape
axis tight;

% text an labels
% init first rotation step label
tA = text(2/3*pi, 1.5, ...
    '\theta', ...
    'Color', 'b', ...
    'FontSize', 16, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

title('Rotation around Z-Axis in Degree', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

hold off;

% Cosinus bridge outputs for rotation step %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
ax3 = nexttile(3);
hold on;

% set colormap
colormap('gray');

% plot cosinus reference, set NaN values to white color, orient Y to normal
imC = imagesc(ds.Data.HxScale, ds.Data.HyScale, ds.Data.VcosRef);
set(imC, 'AlphaData', ~isnan(ds.Data.VcosRef));
set(gca, 'YDir', 'normal')

% axis shape and ticks
axis square xy;
axis tight;
yticks(xticks);
grid on;

% test and labels
xlabel('$H_x$ in kA/m', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

ylabel('$H_y$ in kA/m', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

title('$V_{\cos}(H_x, H_y)$', ...
    'FontWeight', 'normal', ...

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        'FontSize', 12, ...
        'FontName', 'Times', ...
        'Interpreter', 'latex');

% add colorbar and place it
cb1 = colorbar;
cb1.Label.String = sprintf(...
    '$V_{\cos}(H_x, H_y)$ in V, $V_{cc} = %1.1f$ V, $V_{\off} = %1.2f$ V', ...
    ds.Info.SensorArrayOptions.Vcc, ds.Info.SensorArrayOptions.Voff);
cb1.Label.Interpreter = 'latex';
cb1.Label.FontSize = 12;

hold off;

% Sinus bridge outputs for rotation step %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
ax4 = nexttile(4);
hold on;

% set colormap
colormap('gray');

% plot sinus reference, set NaN values to white color, orient Y to normal
imS = imagesc(ds.Data.HxScale, ds.Data.HyScale, ds.Data.VsinRef);
set(imS, 'AlphaData', ~isnan(ds.Data.VsinRef));
set(gca, 'YDir', 'normal')

% axis shape and ticks
axis square xy;
axis tight;
yticks(xticks);
grid on;

% test and labels
xlabel('$H_x$ in kA/m', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

ylabel('$H_y$ in kA/m', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

title('$V_{\sin}(H_x, H_y)$', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

% add colorbar and place it
cb2 = colorbar;
cb2.Label.String = sprintf(...
    '$V_{\sin}(H_x, H_y)$ in V, $V_{cc} = %1.1f$ V, $V_{\off} = %1.2f$ V', ...
    ds.Info.SensorArrayOptions.Vcc, ds.Info.SensorArrayOptions.Voff);
cb2.Label.Interpreter = 'latex';
cb2.Label.FontSize = 12;

hold off;

```

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% zoom axes for scatter on cosinuns reference images %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
nexttile(3);
ax5 = axes('Position', [0.07 0.02 0.19 0.19], 'XColor', 'r', 'YColor', 'r');
hold on;
axis square xy;
grid on;
hold off;

% draw everything prepared before start renewing frame wise and prepare for
% recording frames to video file %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% draw frame
drawnow;

% get file path and change extension
[~, fName, ~] = fileparts(ds.Info.filePath);
fPath = PathVariables.saveImagesPath;

% string allows simple cat ops
VW = VideoWriter(fullfile(fPath, fName + ".avi"), ...
    "Uncompressed AVI");

% scale frame rate on 10 second movies, ensure at least 1 fps
fr = floor(nSubAngles / 10) + 1;
VW.FrameRate = fr;

% open video file, ready to record frames
open(VW)

% loop through subset angle dataset and renew plots %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
for i = indices
    % H load subset
    Hx = ds.Data.Hx(:, :, i);
    Hy = ds.Data.Hy(:, :, i);
    % get min max
    maxHx = max(Hx, [], 'all');
    maxHy = max(Hy, [], 'all');
    minHx = min(Hx, [], 'all');
    minHy = min(Hy, [], 'all');
    dHx = abs(maxHx - minHx);
    dHy = abs(maxHy - minHy);

    % load V subset
    Vcos = ds.Data.Vcos(:, :, i) - Voff;
    Vsin = ds.Data.Vsin(:, :, i) - Voff;
    angle = ds.Data.angles(i);

    % lock plots
    hold(ax1, 'on');
    hold(ax2, 'on');
    hold(ax3, 'on');
    hold(ax4, 'on');
    hold(ax5, 'on');

    % update plot 1
    qH = quiver(ax1, X, Y, Hx, Hy, 0.5, 'b');
    qV = quiver(ax1, X, Y, Vcos, Vsin, 0.5, 'r');
    legend([qH qV], {'$quiver(H_x,H_y)$', ...
        '$quiver(V_{cos}-V_{off},V_{sin}-V_{off})$'},...)

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        'FontWeight', 'normal', ...
        'FontSize', 9, ...
        'FontName', 'Times', ...
        'Interpreter', 'latex', ...
        'Location', 'NorthEast');

% update plot 2
tA.String = sprintf('$%.1f^\circ$', angle);
pA = polarscatter(ax2, angle/180*pi, 1, 'b', 'filled', ...
    'MarkerEdgeColor', 'k', 'LineWidth', 0.8);

% update plot 3 and 4
sC = scatter(ax3, Hx(:), Hy(:), 5, c, 'filled', ...
    'MarkerEdgeColor', 'k', ...
    'LineWidth', 0.8);
sS = scatter(ax4, Hx(:), Hy(:), 5, c, 'filled', ...
    'MarkerEdgeColor', 'k', ...
    'LineWidth', 0.8);

% calc position of scatter area frame and reframe
pos = [minHx - 0.3 * dHx, minHy - 0.3 * dHy, 1.6 * dHx, 1.6 * dHy];
rtC = rectangle(ax3, 'Position', pos, 'LineWidth', 1, ...
    'EdgeColor', 'r');
rtS = rectangle(ax4, 'Position', pos, 'LineWidth', 1, ...
    'EdgeColor', 'r');

% update plot 5 (zoom)
sZ = scatter(ax5, Hx(:), Hy(:), [], c, 'filled', ...
    'MarkerEdgeColor', 'k', ...
    'LineWidth', 0.8);
xlim(ax5, [pos(1) maxHx + 0.3 * dHx])
ylim(ax5, [pos(2) maxHy + 0.3 * dHy])

% release plots
hold(ax1, 'off');
hold(ax2, 'off');
hold(ax3, 'off');
hold(ax4, 'off');
hold(ax5, 'off');

% draw frame
drawnow;

% record frame to file
frame = getframe(fig);
writeVideo(VW, frame);

% delete part of plots to renew for current angle, delete but last
if i ~= indices(end)
    delete(qH);
    delete(qV);
    delete(pA);
    delete(rtC);
    delete(rtS);
    delete(sC);
    delete(sS);
    delete(sZ);
end
end
% close video file
close(VW)
close(fig)

```


end