# plotSimulationCosSinStats

Search for available trainings or test dataset and plot dataset. Follow user input dialog to choose which dataset to plot and statistics of cos sin. Save created plot to file. Filename same as dataset with attached info.

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#### **Syntax**

plotSimulationCosSinStats()

# **Description**

**plotSimulationCosSinStats()** plot training or test dataset which are loacated in data/test or data/training. The function list all datasets and the user must decide during user input dialog which dataset to plot. It loads path from config.mat and scans for file automatically.

# **Examples**

plotSimulationCosSinStats()

# **Input Argurments**

None

#### **Output Argurments**

#### None

# Requirements

- Other m-files required: None
- Subfunctions: None
- MAT-files required: config.mat

#### See Also

- generateSimulationDatasets
- sensorArraySimulation
- generateConfigMat

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```
TestDatasets = dir(fullfile(PathVariables.testDataPath, 'Test *.mat'));
   allDatasets = [TrainingDatasets; TestDatasets];
   % check if files available
   if isemptv(allDatasets)
      error('No training or test datasets found.');
catch ME
   rethrow(ME)
end
% number of datasets
nDatasets = length(allDatasets);
fprintf('Found %d datasets:\n', nDatasets)
for i = 1:nDatasets
   fprintf('%s\t:\t(%d)\n', allDatasets(i).name, i)
end
% get numeric user input to indicate which dataset to plot
iDataset = input('Type number to choose dataset to plot to: ');
try
   ds = load(fullfile(allDatasets(iDataset).folder, ...
      allDatasets(iDataset).name));
   % check how many angles in dataset and let user decide how many to
   % render in polt
   fprintf('Detect %d angles in dataset ...\n', ds.Info.UseOptions.nAngles);
   nSubAngles = input('How many angles to you wish to plot: ');
   % nSubAngles = 120;
   % indices for data to plot, get sample distance for even distance
   sampleDistance = length(downsample(ds.Data.angles, nSubAngles));
   % get subset of angles
   subAngles = downsample(ds.Data.angles, sampleDistance);
   nSubAngles = length(subAngles); % just ensure
   % get indices for subset data
   indices = find(ismember(ds.Data.angles, subAngles));
catch ME
   rethrow(ME)
fPath = fullfile(PathVariables.saveFiguresPath);
fSvgPath = fullfile(PathVariables.saveImagesPath, 'svg');
fEpsPath = fullfile(PathVariables.saveImagesPath, 'eps');
fPdfPath = fullfile(PathVariables.saveImagesPath, 'pdf');
fig = figure('Name', 'Sensor Array', ...
   'NumberTitle' , 'off', ...
   'WindowStyle', 'normal', ...
   'MenuBar', 'none', ...
'ToolBar', 'none', ...
'Units', 'centimeters'
   'OuterPosition', [0 0 37 29], ...
   'PaperType', 'a4', ...
'PaperUnits', 'centimeters', ...
   'PaperOrientation', 'landscape', ...
   'PaperPositionMode', 'auto', ...
   'DoubleBuffer', 'on', ...
'RendererMode', 'manual', ...
   'Renderer', 'painters');
tdl = tiledlayout(fig, 2, 1, ...
   'Padding', 'compact', .
   'TileSpacing' , 'compact');
```

```
title(tdl, 'Sensor Array Simulation', ...
       'FontWeight', 'normal', ...
       'FontSize', 18, ...
       'FontName', 'Times',
       'Interpreter', 'latex');
   subline1 = "Sensor Array (%s) of $%d\\times sensors, an edge length of $%.1f$ mm,
a rel. pos. to magnet surface of";
   \textbf{subline2} = " \$(\%.1f, \%.1f, -(\%.1f)) \$ \ \text{in mm, a magnet tilt of } \$\%.1f^{\circ} \ \text{a sphere}
radius of $%.1f$ mm, a imprinted";
   subline3 = "field strength of $%.1f$ kA/m at $%.1f$ mm from sphere surface in z-axis,
$%d$ rotation angles with a ";
   subline4 = "step width of $%.1f^\\circ$ and a resolution of $%.1f^\\circ$. Visualized
is a subset of $%d$ angles in ";
   subline5 = "sample distance of $%d$ angles. Based on %s characterization reference %s
   sub = [sprintf(subline1, ...
                 ds.Info.SensorArrayOptions.geometry, ...
                 ds.Info.SensorArrayOptions.dimension, ...
                 ds.Info.SensorArrayOptions.dimension, ...
                 ds.Info.SensorArrayOptions.edge); ...
         sprintf(subline2, ...
                 ds.Info.UseOptions.xPos, ...
                 ds.Info.UseOptions.yPos, ...
                 ds.Info.UseOptions.zPos, ...
                 ds.Info.UseOptions.tilt, ...
                 ds.Info.DipoleOptions.sphereRadius); ...
         sprintf(subline3, ...
                 ds.Info.DipoleOptions.HOmag, ...
                 ds.Info.DipoleOptions.z0, .
                 ds.Info.UseOptions.nAngles); ...
         sprintf(subline4, ...
                 ds.Data.angleStep, ...
                 ds.Info.UseOptions.angleRes, ...
                 nSubAnales)
         sprintf(subline5, ...
                 sampleDistance, ...
                 ds.Info.CharData, ...
                 ds.Info.UseOptions.BridgeReference)];
   subtitle(tdl, sub, ...
    'FontWeight', 'normal', ...
       'FontSize', 14, ...
       'FontName', 'Times', ...
       'Interpreter', 'latex');
   M = ds.Info.SensorArrayOptions.dimension^2;
   % N = ds.Info.UseOptions.nAngles;
   res = ds.Info.UseOptions.angleRes;
   %angles = ds.Data.angles;
   anglesIP = 0:res:360-res;
   % load V subset and reshape for easier computing statistics
   Vcos = squeeze(reshape(ds.Data.Vcos(:,:,indices), 1, M, nSubAngles));
   Vsin = squeeze(reshape(ds.Data.Vsin(:,:,indices), 1, M, nSubAngles));
   % load offset voltage to subtract from cosinus, sinus voltage
   Voff = ds.Info.SensorArrayOptions.Voff;
   Vcc = ds.Info.SensorArrayOptions.Vcc;
   % interpolate with makima makes best results, ensure to kill nans for
   % fill otherwise fill strokes, use linstyle none for fill without frame
   interpM = 'makima';
   VcosMean = mean(Vcos, 1);
   VcosMeanIP = interp1(subAngles, VcosMean, anglesIP, interpM);
```

```
VcosStd = std(Vcos, 1, 1);
VcosVar = var(Vcos, 1, 1); % std^2
% meanvariation coefficient in percent
VcosMVCP = mean(VcosStd ./ VcosMean) * 100;
VcosUpper1 = VcosMean + VcosStd;
VcosUpper2 = VcosMean + VcosVar;
VcosLower1 = VcosMean - VcosStd;
VcosLower2 = VcosMean - VcosVar;
VcosUpper1IP = interp1(subAngles, VcosUpper1, anglesIP, interpM);
VcosUpperlIP = fillmissing(VcosUpperlIP, 'previous');
VcosLower1IP = interp1(subAngles, VcosLower1, anglesIP, interpM);
VcosLower1IP = fillmissing(VcosLower1IP, 'previous');
VcosUpper2IP = interp1(subAngles, VcosUpper2, anglesIP, interpM);
VcosUpper2IP = fillmissing(VcosUpper2IP, 'previous');
VcosLower2IP = interp1(subAngles, VcosLower2, anglesIP, interpM);
VcosLower2IP = fillmissing(VcosLower2IP, 'previous');
VsinMean = mean(Vsin, 1);
VsinMeanIP = interp1(subAngles, VsinMean, anglesIP, interpM);
VsinStd = std(Vsin, 1, 1);
VsinVar = var(Vsin, 1, 1); % std^2
% meanvariation coefficient in percent
VsinMVCP = mean(VsinStd ./ VsinMean) * 100;
VsinUpper1 = VsinMean + VsinStd;
VsinUpper2 = VsinMean + VsinVar;
VsinLower1 = VsinMean - VsinStd;
VsinLower2 = VsinMean - VsinVar;
VsinUpper1IP = interp1(subAngles, VsinUpper1, anglesIP, interpM);
VsinUpper1IP = fillmissing(VsinUpper1IP, 'previous');
VsinLower1IP = interp1(subAngles, VsinLower1, anglesIP, interpM);
VsinLower1IP = fillmissing(VsinLower1IP, 'previous');
VsinUpper2IP = interp1(subAngles, VsinUpper2, anglesIP, interpM);
VsinUpper2IP = fillmissing(VsinUpper2IP, 'previous');
VsinLower2IP = interp1(subAngles, VsinLower2, anglesIP, interpM);
VsinLower2IP = fillmissing(VsinLower2IP, 'previous');
% axes limits
%xlimits = [-10 370];
%ylimits = [min(cat(3, ds.Data.VsinRef, ds.Data.VcosRef), [], 'all') - 0.1*Vcc, ...
   max(cat(3, ds.Data.VsinRef, ds.Data.VcosRef), [], 'all') + 0.1*Vcc];
% Vcos
nexttile;
hold on;
fillStdX = [anglesIP, fliplr(anglesIP)];
fillStdY = [VcosLower1IP, fliplr(VcosUpper1IP)];
fill(fillStdX, fillStdY, [0.95 0.95 0.95], 'LineStyle', 'none');
fillVarX = [anglesIP, fliplr(anglesIP)];
fillVarY = [VcosLower2IP, fliplr(VcosUpper2IP)];
fill(fillVarX, fillVarY, [0.7 0.7 0.7], 'LineStyle', 'none');
yline(Voff, 'k--');
scatter(subAngles, VcosUpper1, [], 'r*');
plot(anglesIP, VcosUpper1IP, 'r-.');
```

```
scatter(subAngles, VcosMean, [], 'm*');
        plot(anglesIP, VcosMeanIP, 'm-.');
        scatter(subAngles, VcosLower1, [], 'b*');
        plot(anglesIP, VcosLower1IP, 'b-.');
        hold off;
       xlim([-res 360-res]);
       %ylim(ylimits);
        grid on;
        xlabel('$\theta$ in Degree', ...
                 'FontWeight', 'normal', ...
'FontSize', 12, ...
                 'FontName', 'Times', ...
                 'Interpreter', 'latex');
       ylabel('$V{cos}(\theta)$ in V', ...
                 'FontWeight', 'normal', ...
                 'FontSize', 12, ...
'FontName', 'Times', ...
                 'Interpreter', 'latex');
        title(sprintf('Compare $V {cos}(\\theta)) for each Array Member $V {cc} = %.1f$ V, $V
_{off} = .2f \ V, \ \frac{\ma_{\mu} = .2f \ perc.', \dots}
                                      Vcc, Voff, VcosMVCP), ...
                 'FontWeight', 'normal', ...
                 'FontSize', 12, ...
                 'FontName', 'Times', ..
                 'Interpreter', 'latex');
        % Vsin
        nexttile;
        hold on;
        fillStdX = [anglesIP, fliplr(anglesIP)];
        fillStdY = [VsinLower1IP, fliplr(VsinUpper1IP)];
        l1 = fill(fillStdX, fillStdY, [0.95 0.95 0.95], 'LineStyle', 'none');
        fillVarX = [anglesIP, fliplr(anglesIP)];
        fillVarY = [VsinLower2IP, fliplr(VsinUpper2IP)];
        l2 = fill(fillVarX, fillVarY, [0.7 0.7 0.7], 'LineStyle', 'none');
        l3 = yline(Voff, 'k--');
        l4 = scatter(subAngles, VsinUpper1, [], 'r*');
       l5 = plot(anglesIP, VsinUpperIIP, 'r-.');
l6 = scatter(subAngles, VsinMean, [], 'm*');
        17 = plot(anglesIP, VsinMeanIP, 'm-.');
        18 = scatter(subAngles, VsinLower1, [], 'b*');
       19 = plot(anglesIP, VsinLower1IP, 'b-.');
       hold off;
       xlim([-res 360-res]);
        grid on;
        xlabel('$\theta$ in Degree', ...
                 'FontWeight', 'normal', ...
                 'FontSize', 12, ...
                 'FontName', 'Times', ...
                 'Interpreter', 'latex');
        ylabel('$V{sin}(\theta)$ in V', ...
                 'FontWeight', 'normal', ...
                 'FontSize', 12, ...
                 'FontName', 'Times', ...
'Interpreter', 'latex');
        \label{title(sprintf('Compare $V_{sin}(\\theta)) for each Array Member $V_{cc} = \$.1f$ V, $V$ is a function of the state of t
_{off} = %.2f$ V, $\\bar{\} = %.2f$ perc.'...
                         , Vcc, Voff, VsinMVCP), ...
                 'FontWeight', 'normal', ...
                 'FontSize', 12, ...
```

```
'FontName', 'Times', ...
       'Interpreter', 'latex');
   l = [11 \ 12 \ 13 \ 14 \ 15 \ 16 \ 17 \ 18 \ 19];
   L = legend(l, {'$2\sigma$', ... '$2\sigma^2$', ...
                 '$V_{off}$', ...
'$U_{lim} = \mu + \sigma$', ...
                 sprintf('$%s(U_{lim})$', interpM), ...
                 '$\mu(V)$', ...
                 sprintf('$%s(\\mu)$', interpM), ...
                 '$L_{lim} = \mu - \sigma$', ...
                sprintf('$%s(L {lim})$', interpM)}, ...
       'FontWeight', 'normal', ...
       'FontSize', 12, ...
'FontName', 'Times', ...
       'Interpreter', 'latex');
   L.Layout.Tile = 'east';
   % get file path to save figure with angle index
   [~, fName, ~] = fileparts(ds.Info.filePath);
   % save to various formats
   yesno = input('Save? [y/n]: ', 's');
   if strcmp(yesno, 'y')
       fLabel = input('Enter file label: ', 's');
       fName = fName + "_StatsPlot_" + fLabel;
       savefig(fig, fullfile(fPath, fName));
      print(fig, fullfile(fSvgPath, fName), '-dsvg');
print(fig, fullfile(fEpsPath, fName), '-depsc', '-tiff', '-loose');
print(fig, fullfile(fPdfPath, fName), '-dpdf', '-loose', '-fillpage');
   end
   close(fig);
end
```

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