

## plotSingleSimulationAngle

Search for available trainings or test dataset and plot dataset. Follow user input dialog to choose which dataset and decide how many angles to plot. Plot single Angle and save figure to file. File name same as dataset with attach angle index.

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### Syntax

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plotSingleSimulationAngle()

### Description

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**plotSingleSimulationAngle()** plot training or test dataset which are located in data/test or data/training. The function list all datasets and the user must decide during user input dialog which dataset to plot and which angle to visualize to. It loads path from config.mat and scans for file automatically.

### Examples

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plotSingleSimulationAngle()

### Input Arguments

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None

### Output Arguments

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None

### Requirements

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- Other m-files required: None
- Subfunctions: None
- MAT-files required: config.mat

### See Also

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- [generateSimulationDatasets](#)
- [sensorArraySimulation](#)
- [generateConfigMat](#)

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```
function plotSingleSimulationAngle()
% scan for datasets and load needed configurations %%%%%%%%%%%
% scan for datasets and load needed configurations %%%%%%%%%%%
try
    disp('Plot single simulation angle ...');
    close all;
    % load path variables
    load('config.mat', 'PathVariables');
    % scan for datasets
    TrainingDatasets = dir(fullfile(PathVariables.trainingDataPath, ...
        'Training_*.mat'));
```

```

TestDatasets = dir(fullfile(PathVariables.testDataPath, 'Test_*.mat'));
allDatasets = [TrainingDatasets; TestDatasets];
% check if files available
if isempty(allDatasets)
    error('No training or test datasets found.');
```

end

```
catch ME
    rethrow(ME)
end

% display available datasets to user, decide which to plot %%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

% number of datasets
nDatasets = length(allDatasets);
fprintf('Found %d datasets:\n', nDatasets)
for i = 1:nDatasets
    fprintf('%s\t:(%d)\n', allDatasets(i).name, i)
end
% get numeric user input to indicate which dataset to plot
iDataset = input('Type number to choose dataset to plot to: ');
% iDataset = 2;

% load dataset and ask user which one and how many angles %%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
try
    ds = load(fullfile(allDatasets(iDataset).folder, ...
        allDatasets(iDataset).name));
    % check how many angles in dataset and let user decide how many to
    % render in plot
    fprintf('Detect %d angles ([1:%d]) in dataset ...\n', ...
        ds.Info.UseOptions.nAngles, ds.Info.UseOptions.nAngles);
    fprintf('Resolution\t:(%d)\n', ds.Info.UseOptions.angleRes);
    fprintf('Step width\t:(%d)\n', ds.Data.angleStep);
    fprintf('Start angle\t:(%d)\n', ds.Data.angles(1))
    idx = input('Which angle do you wish to plot (enter index): ');
    angle = interp1(ds.Data.angles, idx, 'nearest');
catch ME
    rethrow(ME)
end

% figure save path for different formats %%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fPath = fullfile(PathVariables.saveFiguresPath);
fSvgPath = fullfile(PathVariables.saveImagesPath, 'svg');
fEpsPath = fullfile(PathVariables.saveImagesPath, 'eps');
fPdfPath = fullfile(PathVariables.saveImagesPath, 'pdf');

% create dataset figure for a subset or all angle %%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fig = figure('Name', 'Sensor Array', ...
    'NumberTitle', 'off', ...
    'WindowStyle', 'normal', ...
    'MenuBar', 'none', ...
    'ToolBar', 'none', ...
    'Units', 'centimeters', ...
    'OuterPosition', [0 0 30 30], ...
    'PaperType', 'a4', ...
    'PaperUnits', 'centimeters', ...
    'PaperOrientation', 'landscape', ...
    'PaperPositionMode', 'auto', ...
    'DoubleBuffer', 'on', ...
    'RendererMode', 'manual', ...
    'Renderer', 'painters');

tdl = tiledlayout(fig, 2, 2, ...
    'Padding', 'normal', ...
    'TileSpacing', 'compact');

title(tdl, 'Sensor Array Simulation', ...

```

[illegible]

```

% plot each coordinate in loop to create a special shading constant
% reliable to orientation for all matrice
hold on;
scatter(X(:), Y(:), [], c, 'filled', 'MarkerEdgeColor', 'k', ...
        'LineWidth', 0.8);

% axis shape and ticks
axis square xy;
axis tight;
grid on;
xlim([minX maxX]);
ylim([minY maxY]);

% text and labels
text(minX+0.2, minY+0.2, ...
      sprintf('$Z = %.1f$ mm', Z(1)), ...
      'Color', 'k', ...
      'FontSize', 16, ...
      'FontName', 'Times', ...
      'Interpreter', 'latex');

xlabel('$X$ in mm', ...
       'FontWeight', 'normal', ...
       'FontSize', 12, ...
       'FontName', 'Times', ...
       'Interpreter', 'latex');

ylabel('$Y$ in mm', ...
       'FontWeight', 'normal', ...
       'FontSize', 12, ...
       'FontName', 'Times', ...
       'Interpreter', 'latex');

title(sprintf('Sensor Array %d\\times%d$', N, N), ...
       'FontWeight', 'normal', ...
       'FontSize', 12, ...
       'FontName', 'Times', ...
       'Interpreter', 'latex');

hold off;

% plot rotation angles in polar view %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
nexttile(2);
% plot all angles grayed out
polarscatter(ds.Data.angles/180*pi, ones(1, ds.Info.UseOptions.nAngles), ...
            [], [0.8 0.8 0.8], 'filled');

% radius ticks and label
rticks(1);
rticklabels("");
hold on;

% plot subset of angles
% polarscatter(subAngles/180*pi, ones(1, nSubAngles), 'k', 'LineWidth', 0.8);
ax2 = gca;

% axis shape
axis tight;

% text an labels
% init first rotation step label
tA = text(2/3*pi, 1.5, ...
          '$\\theta$', ...
          'Color', 'b', ...
          'FontSize', 16, ...
          'FontName', 'Times', ...
          'Interpreter', 'latex');

title('Rotation around Z-Axis in Degree', ...
      'FontWeight', 'normal', ...

```

```

        'FontSize', 12, ...
        'FontName', 'Times', ...
        'Interpreter', 'latex');

hold off;

% Cosinus bridge outputs for rotation step %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
ax3 = nexttile(3);
hold on;

% set colormap
colormap('gray');

% plot cosinus reference, set NaN values to white color, orient Y to normal
imC = imagesc(ds.Data.HxScale, ds.Data.HyScale, ds.Data.VcosRef);
set(imC, 'AlphaData', ~isnan(ds.Data.VcosRef));
set(gca, 'YDir', 'normal')

% axis shape and ticks
axis square xy;
axis tight;
yticks(xticks);
grid on;

% test and labels
xlabel('$H_x$ in kA/m', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

ylabel('$H_y$ in kA/m', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

title('$V_{\cos}(H_x, H_y)$', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

% add colorbar and place it
cb1 = colorbar;
cb1.Label.String = sprintf(...
    '$V_{\cos}(H_x, H_y)$ in V, $V_{cc} = %1.1f$ V, $V_{off} = %1.2f$ V', ...
    ds.Info.SensorArrayOptions.Vcc, ds.Info.SensorArrayOptions.Voff);
cb1.Label.Interpreter = 'latex';
cb1.Label.FontSize = 12;

hold off;

% Sinus bridge outputs for rotation step %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
ax4 = nexttile(4);
hold on;

% set colormap
colormap('gray');

% plot sinus reference, set NaN values to white color, orient Y to normal
imS = imagesc(ds.Data.HxScale, ds.Data.HyScale, ds.Data.VsinRef);
set(imS, 'AlphaData', ~isnan(ds.Data.VsinRef));
set(gca, 'YDir', 'normal')

% axis shape and ticks
axis square xy;
axis tight;
yticks(xticks);

```

```

grid on;

% test and labels
xlabel('$H_x$ in kA/m', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

ylabel('$H_y$ in kA/m', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

title('$V_{\sin}(H_x, H_y)$', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

% add colorbar and place it
cb2 = colorbar;
cb2.Label.String = sprintf(...
    '$V_{\sin}(H_x, H_y)$ in V, $V_{cc} = %1.1f$ V, $V_{off} = %1.2f$ V', ...
    ds.Info.SensorArrayOptions.Vcc, ds.Info.SensorArrayOptions.Voff);
cb2.Label.Interpreter = 'latex';
cb2.Label.FontSize = 12;

hold off;

% zoom axes for scatter on cosinuns reference images %%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
nexttile(3);
ax5 = axes('Position', [0.07 0.02 0.19 0.19], 'XColor', 'r', 'YColor', 'r');
hold on;
axis square xy;
grid on;
hold off;

% plot angle into plots %%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% H load subset
Hx = ds.Data.Hx(:, :, idx);
Hy = ds.Data.Hy(:, :, idx);
% get min max
maxHx = max(Hx, [], 'all');
maxHy = max(Hy, [], 'all');
minHx = min(Hx, [], 'all');
minHy = min(Hy, [], 'all');
dHx = abs(maxHx - minHx);
dHy = abs(maxHy - minHy);

% load V subset
Vcos = ds.Data.Vcos(:, :, idx) - Voff;
Vsin = ds.Data.Vsin(:, :, idx) - Voff;
angle = ds.Data.angles(idx);

% lock plots
hold(ax1, 'on');
hold(ax2, 'on');
hold(ax3, 'on');
hold(ax4, 'on');
hold(ax5, 'on');

% update plot 1
qH = quiver(ax1, X, Y, Hx, Hy, 0.5, 'b');
qV = quiver(ax1, X, Y, Vcos, Vsin, 0.5, 'r');
legend([qH qV], {'$quiver(H_x, H_y)$', '$quiver(V_{\cos}-V_{off}, V_{\sin}-V_{off})$'}, ...

```

```

        'FontWeight', 'normal', ...
        'FontSize', 9, ...
        'FontName', 'Times', ...
        'Interpreter', 'latex', ...
        'Location', 'NorthEast');

% update plot 2
tA.String = sprintf('$%.1f^\circ$', angle);
polarscatter(ax2, angle/180*pi, 1, 'b', 'filled', ...
    'MarkerEdgeColor', 'k', 'LineWidth', 0.8);

% update plot 3 and 4
scatter(ax3, Hx(:), Hy(:), 5, c, 'filled', 'MarkerEdgeColor', 'k', ...
    'LineWidth', 0.8);
scatter(ax4, Hx(:), Hy(:), 5, c, 'filled', 'MarkerEdgeColor', 'k', ...
    'LineWidth', 0.8);

% calc position of scatter area frame and reframe
pos = [minHx - 0.3 * dHx, minHy - 0.3 * dHy, 1.6 * dHx, 1.6 * dHy];
rectangle(ax3, 'Position', pos, 'LineWidth', 1, 'EdgeColor', 'r');
rectangle(ax4, 'Position', pos, 'LineWidth', 1, 'EdgeColor', 'r');

% update plot 5 (zoom)
scatter(ax5, Hx(:), Hy(:), [], c, 'filled', 'MarkerEdgeColor', 'k', ...
    'LineWidth', 0.8);
xlim(ax5, [pos(1) maxHx + 0.3 * dHx])
ylim(ax5, [pos(2) maxHy + 0.3 * dHy])

% release plots
hold(ax1, 'off');
hold(ax2, 'off');
hold(ax3, 'off');
hold(ax4, 'off');
hold(ax5, 'off');

% save figure to file %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% get file path to save figure with angle index
[~, fName, ~] = fileparts(ds.Info.filePath);

% save to various formats
yesno = input('Save? [y/n]: ', 's');
if strcmp(yesno, 'y')
    fLabel = input('Enter file label: ', 's');
    fName = fName + sprintf("_AnglePlot_%d_", idx) + fLabel;
    savefig(fig, fullfile(fPath, fName));
    print(fig, fullfile(fSvgPath, fName), '-dsvg');
    print(fig, fullfile(fEpsPath, fName), '-depsc', '-tiff', '-loose');
    print(fig, fullfile(fPdfPath, fName), '-dpdf', '-loose', '-fillpage');
end
close(fig);
end

```