plotSimulationDatasetCircle

Search for available trainings or test dataset and plot dataset. Follow user input dialog to choose which dataset to plot. Save created plot to file. Filename same as dataset with attached info.

Syntax

plotSimulationDatasetCircle()

Description

plotSimulationDatasetCircle() plot training or test dataset which are loacated in data/test or data/training. The function lists all datasets and the user must decide during user input dialog which dataset to plot. It loads path from config.mat and scans for file automatically.

Examples

plotSimulationDatasetCircle()

Input Argurments

None

Output Argurments

None

Requirements

- Other m-files required: None
- Subfunctions: None
- MAT-files required: config.mat

See Also

- generateSimulationDatasets
- sensorArraySimulation
- generateConfigMat

Created on December 02. 2020 by Tobias Wulf. Copyright Tobias Wulf 2020.

```
function plotSimulationDatasetCircle()
  try
     disp('Plot simulation dataset ...');
     close all;
      % load path variables
     load('config.mat', 'PathVariables');
      % scan for datasets
     TrainingDatasets = dir(fullfile(PathVariables.trainingDataPath, ...
         'Training_*.mat'));
     TestDatasets = dir(fullfile(PathVariables.testDataPath, 'Test_*.mat'));
     allDatasets = [TrainingDatasets; TestDatasets];
      % check if files available
     if isempty(allDatasets)
         error('No training or test datasets found.');
```

```
catch ME
  rethrow(ME)
% number of datasets
nDatasets = length(allDatasets);
fprintf('Found %d datasets:\n', nDatasets)
for i = 1:nDatasets
  fprintf('%s\t:\t(%d)\n', allDatasets(i).name, i)
% get numeric user input to indicate which dataset to plot
iDataset = input('Type number to choose dataset to plot to: ');
ds = load(fullfile(allDatasets(iDataset).folder, ...
     allDatasets(iDataset).name));
catch ME
  rethrow(ME)
fPath = fullfile(PathVariables.saveFiguresPath);
fSvgPath = fullfile(PathVariables.saveImagesPath, 'svg');
fEpsPath = fullfile(PathVariables.saveImagesPath, 'eps');
fPdfPath = fullfile(PathVariables.saveImagesPath, 'pdf');
fig = figure('Name', 'Sensor Array', ...
   'NumberTitle', 'off', ...
   'WindowStyle', 'normal', ...
   'MenuBar', 'none', ...
  'ToolBar', 'none', ...
   'Units', 'centimeters', ...
   'OuterPosition', [0 0 30 30], ...
   'PaperType', 'a4', ...
   'PaperUnits', 'centimeters', ...
   'PaperOrientation', 'landscape', ...
   'PaperPositionMode', 'auto', ...
  'DoubleBuffer', 'on', ...
   'RendererMode', 'manual', ...
   'Renderer', 'painters');
tdl = tiledlayout(fig, 2, 2, ...
   'Padding', 'compact', ...
   'TileSpacing' , 'compact');
title(tdl, 'Sensor Array Simulation', ...
   'FontWeight', 'normal', ...
   'FontSize', 18, ...
   'FontName', 'Times', ...
   'Interpreter', 'latex');
subline1 = "Sensor Array (%s) of $%d\\times%d$ sensors," + ...
  " an edge length of $%.1f$ mm, a rel. pos. to magnet surface of";
subline2 = " $(%.1f, %.1f, -(%.1f))$ in mm, a magnet tilt" + ...
```

```
" of $%.1f^\\circ$, a sphere radius of $%.1f$ mm, a imprinted";
subline3 = "field strength of $%.1f$ kA/m at $%.1f$ mm from" + ...
   " sphere surface in z-axis, $%d$ rotation angles with a ";
subline4 = "step width of $%.1f^\\circ$ and a resolution of" + ...
    " \$.1f^{\circ}. Visualized are circular path of each array position ";
subline5 = "Based on %s characterization reference %s.";
sub = [sprintf(subline1, ...
              ds.Info.SensorArrayOptions.geometry, ...
              ds.Info.SensorArrayOptions.dimension, ...
              ds.Info.SensorArrayOptions.dimension, ...
              ds.Info.SensorArrayOptions.edge); ...
      sprintf(subline2, ...
              ds.Info.UseOptions.xPos, ...
              ds.Info.UseOptions.yPos, ...
              ds.Info.UseOptions.zPos, ...
              ds.Info.UseOptions.tilt, ...
              ds.Info.DipoleOptions.sphereRadius); ...
      sprintf(subline3, ...
              ds.Info.DipoleOptions.HOmag, ...
              ds.Info.DipoleOptions.z0, ...
              ds.Info.UseOptions.nAngles); ...
       sprintf(subline4, ...
              ds.Data.angleStep, ...
              ds.Info.UseOptions.angleRes)
       sprintf(subline5, ...
              ds.Info.CharData, ...
              ds.Info.UseOptions.BridgeReference)];
subtitle(tdl, sub, ...
   'FontWeight', 'normal', ...
    'FontSize', 14, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');
N = ds.Info.SensorArrayOptions.dimension;
M = ds.Info.UseOptions.nAngles;
Voff = ds.Info.SensorArrayOptions.Voff;
Vcos = ds.Data.Vcos - Voff;
Vsin = ds.Data.Vsin - Voff;
Hx = ds.Data.Hx;
Hy = ds.Data.Hy;
\mbox{\ensuremath{\$}} calulate norm values to align circles around position only for \mbox{\ensuremath{x}},\mbox{\ensuremath{y}}
\mbox{\ensuremath{\mbox{\$}}} directition for each sensor dot over all angles.
Vmag = sqrt(Vcos.^2 + Vsin.^2);
Hmag = sqrt(Hx.^2 + Hy.^2);
%Hmag = ds.Data.Habs;
% related to position, multiply scale factor for circle diameter
diameterFactor = 2 * N / ds.Info.SensorArrayOptions.edge;
MaxVmagPos = max(Vmag, [], 3) * diameterFactor;
MaxHmagPos = max(Hmag, [], 3) * diameterFactor;
% Overall maxima, scalar, multiply scale factor for circle diameter
MaxVmagOA = max(Vmag, [], 'all') * diameterFactor;
MaxHmagOA = max(Hmag, [], 'all') * diameterFactor;
% norm and scale volatages and filed strengths
VcosNorm = Vcos ./ MaxVmagPos;
VcosScaled = Vcos / MaxVmagOA;
```

```
VsinNorm = Vsin ./ MaxVmagPos;
VsinScaled = Vsin / MaxVmagOA;
HxNorm = Hx ./ MaxHmagPos;
HxScaled = Hx / MaxHmagOA;
HyNorm = Hy ./ MaxHmagPos;
HyScaled = Hy / MaxHmagOA;
% sensor array grid
X = ds.Data.X;
Y = ds.Data.Y;
Z = ds.Data.Z;
% calc limits of plot 1
maxX = ds.Info.UseOptions.xPos + 0.7 * ds.Info.SensorArrayOptions.edge;
maxY = ds.Info.UseOptions.yPos + 0.7 * ds.Info.SensorArrayOptions.edge;
minX = ds.Info.UseOptions.xPos - 0.7 * ds.Info.SensorArrayOptions.edge;
minY = ds.Info.UseOptions.yPos - 0.7 * ds.Info.SensorArrayOptions.edge;
% plot each cooredinate in loop to create a special shading constant
% reliable to orientation for all matrice
% calculate colormap to identify scatter points
c=zeros(N,N,3);
for i = 1:N
   for j = 1:N
      c(i,j,:) = [(2*N+1-2*i), (2*N+1-2*j), (i+j)]/2/N;
end
c = squeeze(reshape(c, N^2, 1, 3));
% reshape RGB for picking single sensors
R = reshape(c(:,1), N, N);
G = reshape(c(:,2), N, N);
B = reshape(c(:,3), N, N);
nexttile;
hold on;
for i = 1:N
   for j = 1:N
      plot(squeeze(HxScaled(i, j, :)) + X(i,j), ...
           squeeze(HyScaled(i, j, :)) + Y(i,j), ...
           'Color', [R(i,j) G(i,j) B(i,j)], ...
           'LineWidth' , 1.5)
       line([X(i,j), HxScaled(i,j,1) + X(i,j)], ...
           [Y(i,j), HyScaled(i,j,1) + Y(i,j)], \dots
           'Color','k','LineWidth',1.5)
   end
% scatter magnet x,y position (0,0,z)
scatter(0, 0, 32, 'r', 'filled');
hold off;
% axis shape and ticks
axis square xy;
axis tight;
grid on;
xlim([minX maxX]);
```

```
ylim([minY maxY]);
xlabel('$X$ in mm', ...
   'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');
ylabel('$Y$ in mm', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');
title('$H_x$, $H_y$ Normed to Max overall Positions', ...
   'FontWeight', 'normal', ...
    'FontSize', 12, ...
   'FontName', 'Times', ...
   'Interpreter', 'latex');
nexttile;
hold on;
for i = 1:N
   for j = 1:N
       plot(squeeze(VcosScaled(i, j, :)) + X(i,j), ...
           squeeze(VsinScaled(i, j, :)) + Y(i,j), ...
            'Color', [R(i,j) G(i,j) B(i,j)], ...
            'LineWidth' , 1.5)
       line([X(i,j), VcosScaled(i,j,1) + X(i,j)], ...
           [Y(i,j), VsinScaled(i,j,1) + Y(i,j)], \dots
           'Color','k','LineWidth',1.5)
   end
end
% scatter magnet x,y position (0,0,z)
scatter(0, 0, 32, 'r', 'filled');
hold off:
% axis shape and ticks
axis square xy;
axis tight;
grid on;
xlim([minX maxX]);
ylim([minY maxY]);
xlabel('$X$ in mm', ...
   'FontWeight', 'normal', ...
    'FontSize', 12, ...
   'FontName', 'Times', ...
   'Interpreter', 'latex');
ylabel('$Y$ in mm', ...
   'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');
title('$V_{cos}$, $V_{sin}$ Normed to Max overall Positions', ... 'FontWeight', 'normal', ...
```

```
'FontSize', 12, ...
   'FontName', 'Times', ...
   'Interpreter', 'latex');
nexttile:
hold on;
for i = 1:N
   for j = 1:N
      plot(squeeze(HxNorm(i, j, :)) + X(i,j), ...
          squeeze(HyNorm(i, j, :)) + Y(i,j), ...
           'Color', [R(i,j) G(i,j) B(i,j)], ...
           'LineWidth' , 1.5)
      line([X(i,j), HxNorm(i,j,1) + X(i,j)], ...
           [Y(i,j), HyNorm(i,j,1) + Y(i,j)], \dots
          'Color','k','LineWidth',1.5)
   end
end
% scatter magnet x,y position (0,0,z)
scatter(0, 0, 32, 'r', 'filled');
hold off;
% axis shape and ticks
axis square xy;
axis tight;
grid on;
xlim([minX maxX]);
ylim([minY maxY]);
xlabel('$X$ in mm', ...
   'FontWeight', 'normal', ...
   'FontSize', 12, ...
   'FontName', 'Times', ...
   'Interpreter', 'latex');
ylabel('$Y$ in mm', ...
   'FontWeight', 'normal', ...
   'FontSize', 12, ...
   'FontName', 'Times', ...
   'Interpreter', 'latex');
title('\$H_x$, \$H_y$ Normed to Max at each Position', ...
   'FontWeight', 'normal', ...
   'FontSize', 12, ...
   'FontName', 'Times', ...
   'Interpreter', 'latex');
nexttile;
hold on;
for i = 1:N
   for j = 1:N
      plot(squeeze(VcosNorm(i, j, :)) + X(i,j), ...
           squeeze(VsinNorm(i, j, :)) + Y(i,j), ...
           'Color', [R(i,j) G(i,j) B(i,j)], ...
          'LineWidth' , 1.5)
      line([X(i,j), VcosNorm(i,j,1) + X(i,j)], ...
[Y(i,j), VsinNorm(i,j,1) + Y(i,j)], ...
```

```
'Color','k','LineWidth',1.5)
   end
end
\mbox{\ensuremath{\mbox{\$}}} scatter magnet x,y position (0,0,z)
scatter(0, 0, 32, 'r', 'filled');
hold off;
% axis shape and ticks
axis square xy;
axis tight;
grid on;
xlim([minX maxX]);
ylim([minY maxY]);
xlabel('$X$ in mm', ...
   'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');
ylabel('$Y$ in mm', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');
title('$V_{cos}$, $V_{sin}$ Normed to Max at each Positions', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');
% get file path to save figure with angle index
[~, fName, ~] = fileparts(ds.Info.filePath);
% save to various formats
yesno = input('Save? [y/n]: ', 's');
if strcmp(yesno, 'y')
   fLabel = input('Enter file label: ', 's');
    fName = fName + "_CirclePlot_" + fLabel;
   savefig(fig, fullfile(fPath, fName));
   print(fig, fullfile(fSvgPath, fName), '-dsvg');
   print(fig, fullfile(fEpsPath, fName), '-depsc', '-tiff', '-loose');
print(fig, fullfile(fPdfPath, fName), '-dpdf', '-loose', '-fillpage');
end
close(fig);
```

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