

## initTrainDS

Initiates needed data from training dataset to GPR model struct. Builds GPR target vectors depending on which sensor type was used to process the training dataset.

### Syntax

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```
Mdl = initTrainDS(Mdl, TrainDS)
```

### Description

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**Mdl = initTrainDS(Mdl, TrainDS)** attaches regression relevant data information to model struct and initiates the training data with references and regression targets.

### Input Arguments

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**Mdl** model struct.

**TrainDS** training data struct which includes Info and Data struct.

### Output Arguments

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**Mdl** with attached dataset information, raw training data, reference angles and regression targets for cosine and sine predictions.

### Requirements

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- Other m-files required: None
- Subfunctions: None
- MAT-files required: Train\_\*.mat

### See Also

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- [initGPR](#)
- [Training and Test Datasets](#)

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```
function Mdl = initTrainDS(Mdl, TrainDS)

    % set model parameters from training dataset and training data dependencies
    % N number of angles and references in degree
    Mdl.N = TrainDS.Info.UseOptions.nAngles;
    Mdl.Angles = TrainDS.Data.angles';

    % D sensor array square dimension of DxD sensor array
    Mdl.D = TrainDS.Info.SensorArrayOptions.dimension;

    % P number of predictors in sensor array
    Mdl.P = TrainDS.Info.SensorArrayOptions.SensorCount;

    % get sensor type from dataset
    Mdl.Sensor = TrainDS.Info.UseOptions.BaseReference;

    % choose period factor depending on sensor type
    % how many sinoid periods are abstract on a full rotation by 360°
    switch Mdl.Sensor
        case 'TDK'
            Mdl.PF = 1;
```

```

        case 'KMZ60'
            Mdl.PF = 2;

        otherwise
            error('Unkown Sensor %s.', Mdl.Sensor);
        end

        % get reference angles in degree and transpose to column vector
        % get sinoid target vectors depending period factor,
        % transpose because angles2sinoids works with row vectors
        [Mdl.Ysin, Mdl.Ycos] = angles2sinoids(Mdl.Angles, ...
            false, Mdl.PF);

        % attach training data fro cosine and sine to model
        Mdl.Xcos = TrainDS.Data.Vcos;
        Mdl.Xsin = TrainDS.Data.Vsin;
    end

```