plotSimulationDatasetCircle

Search for available trainings or test dataset and plot dataset. Follow user input dialog to choose which dataset to plot. Save created plot to file. Filename same as dataset with attached info.

Contents

Syntax

```
plotSimulationDatasetCircle()
```

Description

plotSimulationDatasetCircle() plot training or test dataset which are loacated in data/test or data/training. The function list all datasets and the user must decide during user input dialog which dataset to plot. It loads path from config.mat and scans for file automatically.

Examples

```
plotSimulationDatasetCircle()
```

Input Argurments

None

Output Argurments

None

Requirements

- Other m-files required: None
- Subfunctions: None
- MAT-files required: config.mat

See Also

- generateSimulationDatasets
- sensorArraySimulation
- generateConfigMat


```
function plotSimulationDatasetCircle()
```

```
% scan for datasets and load needed configurations %%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
try
    disp('Plot simulation dataset ...');
    close all;
    % load path variables
    load('config.mat', 'PathVariables');
    % scan for datasets
    TrainingDatasets = dir(fullfile(PathVariables.trainingDataPath, ...
        'Training_*.mat'));
    TestDatasets = dir(fullfile(PathVariables.testDataPath, 'Test_*.mat'));
    allDatasets = [TrainingDatasets; TestDatasets];
    % check if files available
    if isempty(allDatasets)
        error('No training or test datasets found.');
    end
catch ME
    rethrow(ME)
end

% display availabe datasets to user, decide which to plot %%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

% number of datasets
nDatasets = length(allDatasets);
fprintf('Found %d datasets:\n', nDatasets)
for i = 1:nDatasets
    fprintf('%s\t:\t(%d)\n', allDatasets(i).name, i)
end
% get numeric user input to indicate which dataset to plot
iDataset = input('Type number to choose dataset to plot to: ');

% load dataset and ask user which one and how many angles %%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
try
    ds = load(fullfile(allDatasets(iDataset).folder, ...
        allDatasets(iDataset).name));
catch ME
    rethrow(ME)
end

% figure save path for different formats %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fPath = fullfile(PathVariables.saveFiguresPath);
fSvgPath = fullfile(PathVariables.saveImagesPath, 'svg');
fEpsPath = fullfile(PathVariables.saveImagesPath, 'eps');
fPdfPath = fullfile(PathVariables.saveImagesPath, 'pdf');

% create dataset figure for a subset or all angle %%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fig = figure('Name', 'Sensor Array', ...
    'NumberTitle' , 'off', ...
    'WindowStyle', 'normal', ...
    'MenuBar', 'none', ...
    'ToolBar', 'none', ...
    'Units', 'centimeters', ...
    'OuterPosition', [0 0 30 30], ...
    'PaperType', 'a4', ...
    'PaperUnits', 'centimeters', ...
    'PaperOrientation', 'landscape', ...
```

```
        'PaperPositionMode', 'auto', ...
        'DoubleBuffer', 'on', ...
        'RendererMode', 'manual', ...
        'Renderer', 'painters');

    tdl = tiledlayout(fig, 2, 2, ...
        'Padding', 'compact', ...
        'TileSpacing' , 'compact');

    title(tdl, 'Sensor Array Simulation', ...
        'FontWeight', 'normal', ...
        'FontSize', 18, ...
        'FontName', 'Times', ...
        'Interpreter', 'latex');

    subline1 = "Sensor Array (%s) of $%d\\times%d$ sensors," + ...
        " an edge length of $%.1f$ mm, a rel. pos. to magnet surface of";
    subline2 = " $(%.1f, %.1f, -(%.1f))$ in mm, a magnet tilt" + ...
        " of $%.1f^\\circ$, a sphere radius of $%.1f$ mm, a imprinted";
    subline3 = "field strength of $%.1f$ kA/m at $%.1f$ mm from" + ...
        " sphere surface in z-axis, $%d$ rotation angles with a ";
    subline4 = "step width of $%.1f^\\circ$ and a resolution of" + ...
        " $%.1f^\\circ$. Visualized are circular path of each array position  ";
    subline5 = "Based on %s characterization reference %s.";
    sub = [sprintf(subline1, ...
                    ds.Info.SensorArrayOptions.geometry, ...
                    ds.Info.SensorArrayOptions.dimension, ...
                    ds.Info.SensorArrayOptions.dimension, ...
                    ds.Info.SensorArrayOptions.edge); ...
           sprintf(subline2, ...
                    ds.Info.UseOptions.xPos, ...
                    ds.Info.UseOptions.yPos, ...
                    ds.Info.UseOptions.zPos, ...
                    ds.Info.UseOptions.tilt, ...
                    ds.Info.DipoleOptions.sphereRadius); ...
           sprintf(subline3, ...
                    ds.Info.DipoleOptions.H0mag, ...
                    ds.Info.DipoleOptions.z0, ...
                    ds.Info.UseOptions.nAngles); ...
           sprintf(subline4, ...
                    ds.Data.angleStep, ...
                    ds.Info.UseOptions.angleRes)
           sprintf(subline5, ...
                    ds.Info.CharData, ...
                    ds.Info.UseOptions.BridgeReference)];

    subtitle(tdl, sub, ...
        'FontWeight', 'normal', ...
        'FontSize', 14, ...
        'FontName', 'Times', ...
        'Interpreter', 'latex');

    % get subset of needed data to plot, only one load %%%%%%%%%%%%%%%%%%%%%%%
    %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
    N = ds.Info.SensorArrayOptions.dimension;
    M = ds.Info.UseOptions.nAngles;
    Voff = ds.Info.SensorArrayOptions.Voff;
    Vcos = ds.Data.Vcos - Voff;
    Vsin = ds.Data.Vsin - Voff;
    Hx = ds.Data.Hx;
```

```
Hy = ds.Data.Hy;

% calulate norm values to align circles around position only for x,y
% directition for each sensor dot over all angles.
Vmag = sqrt(Vcos.^2 + Vsin.^2);
Hmag = sqrt(Hx.^2 + Hy.^2);
%Hmag = ds.Data.Habs;

% related to position, multiply scale factor for circle diameter
diameterFactor = 2 * N / ds.Info.SensorArrayOptions.edge;
MaxVmagPos = max(Vmag, [], 3) * diameterFactor;
MaxHmagPos = max(Hmag, [], 3) * diameterFactor;

% Overall maxima, scalar, multiply scale factor for circle diameter
MaxVmagOA =  max(Vmag, [], 'all') * diameterFactor;
MaxHmagOA =  max(Hmag, [], 'all') * diameterFactor;

% norm and scale volatages and filed strengths
VcosNorm = Vcos ./ MaxVmagPos;
VcosScaled = Vcos / MaxVmagOA;
VsinNorm = Vsin ./ MaxVmagPos;
VsinScaled = Vsin / MaxVmagOA;

HxNorm = Hx ./ MaxHmagPos;
HxScaled = Hx / MaxHmagOA;
HyNorm = Hy ./ MaxHmagPos;
HyScaled = Hy / MaxHmagOA;

% sensor array grid
X = ds.Data.X;
Y = ds.Data.Y;
Z = ds.Data.Z;

% calc limits of plot 1
maxX = ds.Info.UseOptions.xPos + 0.7 * ds.Info.SensorArrayOptions.edge;
maxY = ds.Info.UseOptions.yPos + 0.7 * ds.Info.SensorArrayOptions.edge;
minX = ds.Info.UseOptions.xPos - 0.7 * ds.Info.SensorArrayOptions.edge;
minY = ds.Info.UseOptions.yPos - 0.7 * ds.Info.SensorArrayOptions.edge;

% plot sensor grid in x and y coordinates %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% plot each cooredinate in loop to create a special shading constant
% reliable to orientation for all matrice
 % calculate colormap to identify scatter points
c=zeros(N,N,3);
for i = 1:N
    for j = 1:N
        c(i,j,:) = [(2*N+1-2*i), (2*N+1-2*j), (i+j)]/2/N;
    end
end
c = squeeze(reshape(c, N^2, 1, 3));
% reshape RGB for picking single sensors
R = reshape(c(:,1), N, N);
G = reshape(c(:,2), N, N);
B = reshape(c(:,3), N, N);

% Field strength scaled to overall maxima %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
nexttile;
hold on;
```

```
    for i = 1:N
        for j = 1:N
            plot(squeeze(HxScaled(i, j, :)) + X(i,j), ...
                 squeeze(HyScaled(i, j, :)) + Y(i,j), ...
                 'Color', [R(i,j) G(i,j) B(i,j)], ...
                 'LineWidth' , 1.5)
            line([X(i,j), HxScaled(i,j,1) + X(i,j)], ...
                 [Y(i,j), HyScaled(i,j,1)  + Y(i,j)], ...
                'Color','k','LineWidth',1.5)
        end
    end
    hold off;

    % axis shape and ticks
    axis square xy;
    axis tight;
    grid on;
    xlim([minX maxX]);
    ylim([minY maxY]);

    xlabel('$X$ in mm', ...
        'FontWeight', 'normal', ...
        'FontSize', 12, ...
        'FontName', 'Times', ...
        'Interpreter', 'latex');

    ylabel('$Y$ in mm', ...
        'FontWeight', 'normal', ...
        'FontSize', 12, ...
        'FontName', 'Times', ...
        'Interpreter', 'latex');

    title('$H_x$, $H_y$ Normed to Max overall Positions', ...
        'FontWeight', 'normal', ...
        'FontSize', 12, ...
        'FontName', 'Times', ...
        'Interpreter', 'latex');

    % Cosinus, sinus voltage scaled to overall maxima %%%%%%%%%%%%%%%%%%%%%%%%
    %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
    nexttile;
    hold on;
    for i = 1:N
        for j = 1:N
            plot(squeeze(VcosScaled(i, j, :)) + X(i,j), ...
                 squeeze(VsinScaled(i, j, :)) + Y(i,j), ...
                 'Color', [R(i,j) G(i,j) B(i,j)], ...
                 'LineWidth' , 1.5)
            line([X(i,j), VcosScaled(i,j,1) + X(i,j)], ...
                 [Y(i,j), VsinScaled(i,j,1)  + Y(i,j)], ...
                'Color','k','LineWidth',1.5)
        end
    end
    hold off;

    % axis shape and ticks
    axis square xy;
    axis tight;
    grid on;
    xlim([minX maxX]);
```

```
ylim([minY maxY]);

xlabel('$X$ in mm', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

ylabel('$Y$ in mm', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

title('$V_{cos}$, $V_{sin}$ Normed to Max overall Positions', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

% Field strength normed each maxima at position %%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
nexttile;
hold on;
for i = 1:N
    for j = 1:N
        plot(squeeze(HxNorm(i, j, :)) + X(i,j), ...
             squeeze(HyNorm(i, j, :)) + Y(i,j), ...
             'Color', [R(i,j) G(i,j) B(i,j)], ...
             'LineWidth' , 1.5)
        line([X(i,j), HxNorm(i,j,1) + X(i,j)], ...
             [Y(i,j), HyNorm(i,j,1)  + Y(i,j)], ...
            'Color','k','LineWidth',1.5)
    end
end
hold off;

% axis shape and ticks
axis square xy;
axis tight;
grid on;
xlim([minX maxX]);
ylim([minY maxY]);

xlabel('$X$ in mm', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

ylabel('$Y$ in mm', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

title('$H_x$, $H_y$ Normed to Max at each Position', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
```

```
    'Interpreter', 'latex');

% Cosinus, sinus voltage normed to each maxima at position %%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
nexttile;
hold on;
for i = 1:N
    for j = 1:N
        plot(squeeze(VcosNorm(i, j, :)) + X(i,j), ...
             squeeze(VsinNorm(i, j, :)) + Y(i,j), ...
             'Color', [R(i,j) G(i,j) B(i,j)], ...
             'LineWidth' , 1.5)
        line([X(i,j), VcosNorm(i,j,1) + X(i,j)], ...
             [Y(i,j), VsinNorm(i,j,1)  + Y(i,j)], ...
            'Color','k','LineWidth',1.5)
    end
end
hold off;

% axis shape and ticks
axis square xy;
axis tight;
grid on;
xlim([minX maxX]);
ylim([minY maxY]);

xlabel('$X$ in mm', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

ylabel('$Y$ in mm', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

title('$V_{cos}$, $V_{sin}$ Normed to Max at each Positions', ...
    'FontWeight', 'normal', ...
    'FontSize', 12, ...
    'FontName', 'Times', ...
    'Interpreter', 'latex');

% save figure to file %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% get file path to save figure with angle index
[~, fName, ~] = fileparts(ds.Info.filePath);

% save to various formats
yesno = input('Save? [y/n]: ', 's');
if strcmp(yesno, 'y')
    fLabel = input('Enter file label: ', 's');
    fName = fName + "_CirclePlot_" + fLabel;
    savefig(fig, fullfile(fPath, fName));
    print(fig, fullfile(fSvgPath, fName), '-dsvg');
    print(fig, fullfile(fEpsPath, fName), '-depsc', '-tiff', '-loose');
    print(fig, fullfile(fPdfPath, fName), '-dpdf', '-loose', '-fillpage');
end
close(fig);
```

```
end
```

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