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SAINT: self-attention augmented inception-insideinception network improves protein secondary structure prediction

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Abstract

Motivation: Protein structures provide basic insight into how they can interact with other proteins, their functions and biological roles in an organism. Experimental methods (e.g. X-ray crystallography and nuclear magnetic resonance spectroscopy) for predicting the secondary structure (SS) of proteins are very expensive and time consuming. Therefore, developing efficient computational approaches for predicting the SS of protein is of utmost importance. Advances in developing highly accurate SS prediction methods have mostly been focused on 3-class (Q3) structure prediction. However, 8-class (Q8) resolution of SS contains more useful information and is much more challenging than the Q3 prediction.

Results: We present SAINT, a highly accurate method for Q8 structure prediction, which incorporates self-attention mechanism (a concept from natural language processing) with the Deep Inception-Inside-Inception network in order to effectively capture both the short- and long-range interactions among the amino acid residues. SAINT offers a more interpretable framework than the typical black-box deep neural network methods. Through an extensive evaluation study, we report the performance of SAINT in comparison with the existing best methods on a collection of benchmark datasets, namely, TEST2016, TEST2018, CASP12 and CASP13. Our results suggest that self-attention mechanism improves the prediction accuracy and outperforms the existing best alternate methods. SAINT is the first of its kind and offers the best known Q8 accuracy. Thus, we believe SAINT represents a major step toward the accurate and reliable prediction of SSs of proteins.

Availability and implementation: SAINT is freely available as an open-source project at https://github.com/ SAINTProtein/SAINT.

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1 Introduction

Proteins are bio-molecules made of long chains of amino acid residues connected by peptide bonds. The functions of proteins are usually determined by their tertiary structure and for determining the tertiary structure and related properties, the secondary structure (SS) information is crucial. Protein structure can be experimentally determined by X-ray crystallography and multi-dimensional magnetic resonance in laboratory, but these methods are very costly and time consuming and are yet to be consistent with the proliferation of protein sequence data (Jiang et al., 2017). Thus, the proteins with known primary sequence continue to outnumber the proteins with experimentally determined SSs. The structural properties of a protein depend on its primary sequence (Anfinsen, 1973; Baker and Sali, 2001; Bradley et al., 2005; Dill et al., 2008), yet it remains as a difficult task to accurately determine the secondary and tertiary structures of proteins. Hence, the problem of predicting the structures of a protein — given its primary sequence — is crucially important and remains as one of the greatest challenges in computational biology.

SS — a conformation of the local structure of the polypeptide backbone - prediction dates back to the work of Pauling and Corey in 1951 (Pauling et al., 1951). The SSs of proteins are

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traditionally characterized as three states (Q3): helix (H), strand (E) and coil (C). Afterwards, a more fine-grained characterization of the SSs was proposed (Kabsch and Sander, 1983) for more precise information by extending the Q3 into eight states (Q8): α -helix (H), β -helix (G), π -helix (I), β -strand (E), isolated β -bridge (B), turn (T), bend (S) and Others (C). Q8 prediction is more challenging and can reveal more precise and high resolution on the structural properties of proteins.

Protein SS prediction is an extensively studied field of research. Developing computational approaches (especially using machinelearning techniques) for Q3 SS prediction has a long history, which dates back to the works of Qian and Sejnowski (1988) and Holley and Karplus (1989) who first used neural networks to predict SS. In the 1980s, only statistical model based methods were used on raw sequence data, which could ensure Q3 accuracy merely below 60%. Afterwards, significant improvement was achieved (Jones, 1999; Rost and Sander, 1993; Zvelebil et al., 1987) by leveraging the evolutionary information, such as the position-specific score matrices (PSSM) derived from multiple sequence alignments. Subsequently, many machine-learning methods have been developed for Q3 prediction, which include support vector machines (Guo et al., 2004; Hua and Sun, 2001; Kim and Park, 2003; Ward et al., 2003), probabilistic graphical models (Chu et al., 2004; Schmidler et al., 2000; Van Der Maaten et al., 2011), hidden Markov models (Asai et al., 1993; Aydin et al., 2006), bidirectional recurrent neural networks (RNNs) (Baldi et al., 1999; Chen and Chaudhari, 2007; Heffernan et al., 2017; Magnan and Baldi, 2014; Mirabello and Pollastri, 2013; Pollastri et al., 2002) and other deep learning frameworks (Hou et al., 2019; Spencer et al., 2015).

The performance of Q3 prediction methods has approached the postulated theoretical limit (Yang et al., 2016a). At the same time, there has now been a growing awareness that Q8 prediction can reveal more valuable structural properties. Accurate Q8 SSs predictions can reduce the search space in template-free protein tertiary structure modeling by restricting the variations of backbone dihedral angles within a small range according to the Ramachandran plots (Ramachandran and Sasisekharan, 1968; Yaseen and Li, 2014). Also, differentiation among 3_{10} helix, α -helix and π -helix in SS prediction helps to assign residues and fit protein structure models in cryo-electron microscopy density maps (Topf et al., 2006; Yaseen and Li, 2014). As such, the interest of the research community has recently shifted from Q3 prediction to relatively more challenging Q8 prediction. Quite a few deep-learning methods for Q8 prediction have been proposed over the last few years (Busia and Jaitly, 2017; Fang et al., 2018; Pollastri et al., 2002; Wang et al., 2010; 2016a; Zhou et al., 2018; Zhou and Troyanskaya, 2014). To the best of our knowledge, the first notable success in Q8 prediction methods was SSpro8 (Pollastri et al., 2002), which was published in 2002 and achieved 63.5% Q8 accuracy on the benchmark CB513 dataset (Cuff and Barton, 1999), 64.9% on CASP10 and 65.6% on CASP11 (Wang et al., 2016a). Later in 2011, RaptorX-SS8 (Wang et al., 2010), another Q8 predictor using conditional neural fields, surpassed SSpro8 by demonstrating 64.9% Q8 accuracy on CB513. In 2014, Zhou and Troyanskaya (2014) highlighted the challenges in Q8 prediction and obtained 66.4% Q8 accuracy on CB513 dataset using deep generative stochastic network.

Some of the notable subsequent works include deep conditional random fields (DeepCNF) (Wang et al., 2016a), cascaded convolutional and recurrent neural network (DCRNN) (Li and Yu, 2016), next-step conditioned deep convolutional neural network (NCCNN) (Busia and Jaitly, 2017), multi-scale CNN with highway (CNNH_PSS) (Zhou et al., 2018), DeepACLSTM (Guo et al., 2019) with an asymmetric convolutional neural networks combined with bidirectional long short-term memory, deep inception-inside-inception (Deep3I) network named MUFOLD-SS (Fang et al., 2018), CNN and Bidirectional LSTM based network NetSurfP-2.0 (Klausen et al., 2019) and SPOT-1D (Hanson et al., 2019), which is an ensemble of hybrid models consisting of Residual Convolutional Neural Networks (ResNet) and 2D Bidirectional Residual LSTM Networks (2D-BRLSTM). While most of the methods use sequence data and sequence profiles obtained from PSSM as features, the

more recent methods, such as, MUFOLD-SS, CRRNN, NetSurfP-2.0 and SPOT-1D leveraged HMM profiles and physicochemical properties of residues as well. The most recent and accurate method SPOT-1D (Hanson *et al.*, 2019) also used predicted contact-map information as features and could achieve a significant boost in accuracy. Although these works demonstrate a steady improvement in the published Q8 accuracy over the past few years, the improvements across successive publications are very small. Nevertheless, these small improvements are considered significant given the high complexity of Q8 SS prediction.

Usually the models that focus more on short-range dependencies (local context of the amino acid residues) face difficulties in effectively capturing the long-range dependencies (interactions between amino acid residues that are close in 3D space, but far from each other in the primary sequence) (Hanson et al., 2016; Heffernan et al., 2017; Li and Yu, 2016). Various deep-learning-based models have been leveraged to handle the long-range interactions by using recurrent or highway networks (Busia and Jaitly, 2017; Zhou et al., 2018), deeper networks with convolutional blocks (Fang et al., 2018), long short-term memory (LSTM) cells (Heffernan et al., 2017; Li and Yu, 2016), whereas the short-range interactions have been handled by convolutional blocks of smaller window size (Busia and Jaitly, 2017; Fang et al., 2018; Li and Yu, 2016). These methods circumvent some challenging issues in capturing the non-local interactions, but have limitations of their own. Models, using RNNs to capture long-range dependencies, may suffer from vanishing gradient or exploding gradient problems (Greff et al., 2017; Kanai et al., 2017; Pascanu et al., 2012; Sutskever et al., 2014). Moreover, these methods may fail to effectively capture the dependencies when the sequences are very long (Bengio et al., 1994). Furthermore, as the models grow deeper, the number of parameters also grows, which makes it prone to over-fitting. It is also likely that the short-range relationships captured in the earlier (shallow) layers may disappear as the models grow deeper (Zhou et al., 2018). As a result, developing techniques, which can capture both long- and short-range dependencies simultaneously are of utmost importance. Another limiting factor of the deep-learning methods is that the high accuracy comes at the expense of high abstraction (less interpretability) due to their black-box nature (Chakraborty et al., 2017; Koh and Liang, 2017; Ribeiro et al., 2016; Zhang and Zhu, 2018). Although there has been a flurry of recent works toward designing deeplearning techniques for bio-molecular data, no notable attempt has been made in developing methods with improved interpretability and explainability-models that are able to summarize the reasons of the network behavior, or produce insights about the causes of their decisions and thus gain trust of users.

In this study, we present Self-Attention-Augmented Inception-Inside-Inception NeTwork (SAINT)—a novel method for Q8 SS prediction, which uniquely incorporates the self-attention mechanism (Vaswani et al., 2017) with a state-of-the-art Deep3I network (Fang et al., 2018). We proposed a novel architecture called attentionaugmented inception-inside-inception (2A3I) in order to capture both the local- and long-range interactions. SAINT was compared with a collection of the best alternate methods for Q8 prediction on CASP12 and CASP13 as well as on more recent, challenging and larger test sets (TEST2016 and TEST2018), that were analyzed by a recent and highly accurate method SPOT-1D (Hanson et al., 2019). SAINT obtained superior Q8 accuracy compared to state-of-the-art predictors on the benchmark datasets-77.73% accuracy on TEST2016, 76.09% on TEST2018, 74.78% on CASP13, 74.17% in CASP12 and 72.25% on the CASP Free Modeling (FM) targets. SAINT also obtained high precision, recall and F1-score for individual states. Moreover, SAINT provides interesting insights regarding the interactions and roles of amino acid residues while forming SSs, which help to interpret how the predictions are made. Thus, we have made the following significant contributions: (i) we, for the first time, successfully translated the success of self-attention mechanism from natural language processing to the domain of protein structure prediction, and demonstrated that self-attention improves the accuracy SS prediction, (ii) introduced a method, which can capture both the short- and long-range dependencies, and offers the best

known Q8 accuracy and (iii) improved the interpretability of the black-box deep neural network-based methods, which are often criticized for lack of interpretability.

2 Approach

2.1 Feature representation

takes a protein sequence feature vector $(x_1, x_2, x_3, \dots, x_N)$ as input, where x_i is the vector corresponding to the ith residue, and it returns the protein structure label sequence vector $Y = (y_1, y_2, y_3, \dots, y_N)$ as output, where y_i is the structure label (one of the eight possible states) of the ith residue. Similar to SPOT-1D-base and MUFOLD-SS, our base model contains 57 features from PSSM profiles, HHM profiles and physicochemical properties. To generate PSSM, PSI-BLAST (Altschul et al., 1997) was run against Uniref90 database (UniProt Consortium, 2007) with inclusion threshold 0.001 and three iterations. The HHM profiles were generated using HHblits (Remmert et al., 2012) using default parameters against uniprot20_2013_03 sequence database. HHblits also generates seven transition probabilities and three local alignment diversity values, which we used as features as well. Seven physicochemical properties of each amino acid [e.g. steric parameters (graph-shape index), polarizability, normalized van der Waals volume, hydrophobicity, isoelectric point, helix probability and sheet probability] were obtained from Meiler et al. (2001). So, in our base model, the dimension of x_i is 57 as this is the concatenation of $x_b h m_i \in \mathbb{R}^{d_{bhm}} (d_{hbm} = 30), x_{pss} m_i \in \mathbb{R}^{d_{pssm}} (d_{pssm} = 20)$ and $x_{physical} l_i \in \mathbb{R}^{d_{physical}} (d_{physical} = 7)$. Additional features were generated by windowing the predicted contact information as was done in SPOT-1D. The contact maps were generated using SPOT-Contact (Hanson et al., 2018) and were used as our features by varying window lengths (the number of preceding or succeeding residues whose pairwise contact information were extracted for a target residue). Our ensemble model constitutes of four different models, that we trained with varying input features: one without the contact maps (base model) and three with different window lengths (10, 20 and 50) of the contact-map-based features. The features were normalized to ensure 0 mean and SD of 1 in the training data, similar to SPOT-1D.

2.2 Architecture of SAINT

The architecture of SAINT can be split into three separate discussions: (i) the architecture of our proposed self-attention module, (ii) the architecture of the existing inception module and the proposed attention-augmented inception module and finally (iii) the overall pipeline of SAINT.

2.2.1 Self-attention module

Attention mechanism implies paying attention to specific parts of input data or features while generating output sequence (Bahdanau et al., 2014; Vaswani et al., 2017). It calculates a probability distribution over the elements in the input sequence and then takes the weighted sum of those elements based on this probability distribution while generating outputs.

In self-attention mechanism (Cheng et al., 2016; Parikh et al., 2016; Vaswani et al., 2017), each vector in the input sequence is transformed into three vectors- query, key and value, by three different functions. Each of the output vectors is a weighted sum of the value vectors, where the weights are calculated based on the compatibility of the query vectors with the key vectors by a special function, called compatibility function (discussed later in this section).

The self-attention module, we designed and augmented with the Deep3I network (Fang et al., 2018) is inspired from the self-attention module proposed by Vaswani et al. (2017) and is depicted in Figure 1a. Our self-attention module takes two inputs: (i) the features from the previous inception module or layer, $x \in \mathbb{R}^{d_{protein} \times d_{feature}}$ and (ii) position identifiers, $pos_id \in \mathbb{R}^d_{protein}$, where $d_{protein}$ is the length of the protein sequence and $d_{feature}$ is the length of the feature vector.

2.2.1.1 Positional Encoding Sub-module. The objective of positional encodings is to inject some information about the relative or absolute positions of the residues in a protein sequence. The Positional Encoding PosEnc_p for a position p can be defined as follows (Vaswani et al., 2017).

$$PosEnc_{(p,2i)} = \sin(p/10000^{2i/d_{feature}})$$
 (1)

$$PosEnc_{(p,2i+1)} = cos(p/10000^{2i/d_{feature}}),$$
 (2)

where i is the dimension. We used such function as it may allow the model to easily learn to attend by relative positions since for any fixed offset k, $PosEnc_{p+k}$ can be represented as a linear function of $PosEnc_p$ (Vaswani et al., 2017). For every position p, $PosEnc_p$ has the dimension $d_{protein} \times d_{feature}$. The output of positional encoding is added with the inputs x, resulting in new representations h [see Equation (3)], which contain not only the information extracted by the former layers or modules, but also the information about individual positions.

$$h_{pos} = x_{pos} + PosEnc_{pos}. (3)$$

2.2.1.2 Scaled dot-product attention sub-module. The input features in this sub-module, $h \in \mathbb{R}^{d_{protein} \times d_{feature}}$ are first transformed into three feature spaces Q, K and V, representing *query*, key and value, respectively, in order to compute the scaled dot-product attention, where $Q(h) = W_Q h$, $K(h) = W_K h$, $V(h) = W_V h$. Here, W_Q , W_K , W_V are parameter matrices to be learned. Figure 1b shows a schematic diagram of this module.

Among various compatibility functions [e.g. scaled dot-product attention (Vaswani et al., 2017), additive attention (Bahdanau et al., 2014), similarity-attention (Graves et al., 2014), multiplicative-attention (Luong et al., 2015), biased general attention (Sordoni et al., 2016), etc.], we have chosen the scaled dot-product attention as it showed much promise in case of sequential data. Vaswani et al. (2017) showed that in practice, the dot-product attention is much faster and space-efficient as it can be implemented using highly optimized matrix multiplication code, though theoretically both dot-product and additive attention have similar complexity. Scaled dot-product $s_{i,j}$ of two vectors h_i and h_j is calculated as shown in Equation (4).

$$s_{i,j} = \frac{Q(h_i)K(h_j)^T}{\sqrt{d_K}},\tag{4}$$

where d_K is the dimension of the feature space K. The numerator of the equation, $Q(h_i)K(h_i)^T$ is the dot product between these two vectors, resulting in the similarity between them in a specific vector space. Here, $\sqrt{d_K}$ is the scaling factor, which ensures that the result of the dot product does not get prohibitively large for very long sequences.

The attention weights $e \in \mathbb{R}^{d_{protein} \times d_{feature}}$ are calculated as shown in Equation (5), where $e_{j,i}$ represents how much attention have been given to the vector at position i while synthesizing the vector at position j.

$$e_{j,i} = \frac{\exp(s_{i,j})}{\frac{d_{protein}}{\sum_{n=1}^{n} exp(s_{i,j})}}.$$
 (5)

The attention distribution e is multiplied with the feature vectors V(h) and then in order to reduce the internal covariate shift, this multiplicand is normalized using *batch normalization* (Ioffe and Szegedy, 2015), producing g, the output of the scaled dot-product attention sub-module, following the Equation (6).

$$g_{j} = BatchNorm(\sum_{n=1}^{d_{protein}} e_{j,i}V(h_{i})). \tag{6}$$

Here, BatchNorm(.) is the batch-normalization function and g_j is the j-th vector in the output sequence of this sub-module. Finally,

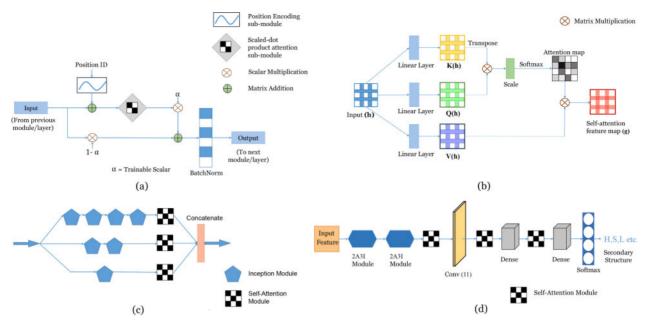


Fig. 1. Schematic diagrams of SAINT and its various components. (a) Architecture of the self-attention module used in SAINT. (b) Architecture of the scaled dot-product attention sub-module. (c) Architecture of our proposed 2A3I module by augmenting self-attention within the 3I network. (d) A schematic diagram of the overall architecture of SAINT, which comprises two 2A3I modules, three self-attention modules, convolutional layers with window size 11 and 2 dense layers

according to the Equation (7), g is multiplied by a scalar parameter α , the original input feature map x is multiplied by $(1 - \alpha)$ and these two multiplicands are summed to synthesize the final output y.

$$y_i = (\alpha)g_i + (1 - \alpha)x_i, \tag{7}$$

where y_i is the ith output and α is a learnable scalar. By introducing weighed sum of g_i and x_i , we give our model the freedom to choose how much weight should be given to each of the features maps, g_i and x_i while generating the output y_i . The optimal value of the parameter α is learnt through back propagation along with the rest of the model.

2.2.2 2A3I module

A novel deep convolutional neural network architecture, Inception, was first introduced by Szegedy et al. (2015), which demonstrated state-of-the-art performance for image classification and detection. An inception module has several branches, each having one or more convolutional layers. Fang et al. used an assembly of inception modules, which they call 3I module, in their proposed method MUFOLD-SS to predict protein SS. They tried to leverage the inception blocks to retrieve both short- and long-range dependencies and achieved the best known accuracy at the time. However, convolutional layers cannot capture enough information about long-range similarities or dependencies among feature vectors of a sequence, synthesized by a certain level of the network (Zhang et al., 2018). In protein SS prediction, this issue leaves more impact on the overall accuracy when the sequence grows in length. Though these types of neural networks that use only convolutional layers need to be deeper to capture the long-range dependency, it is often not feasible to add arbitrarily large numbers of layers. Moreover, the authors of MUFOLD-SS showed that using more than two 3I modules sequentially does not result into significant increase in the overall accuracy, rather increases the computational expense. Earlier works (Chen and Chaudhari, 2007; Guo et al., 2018; Heffernan et al., 2017; Li and Yu, 2016; Pollastri et al., 2002; Sønderby and Winther, 2014) used RNN-based architectures for capturing global features, but incorporating RNN or its derivatives [Gated Recurrent Units (Cho et al., 2014), LSTM (Hochreiter and Schmidhuber, 1997)] inside 3I module would escalate the complexity and computational cost of the model. Therefore, we incorporated the self-attention mechanism to effectively capture both the short- and long-range dependencies

and to bring a better balance between the ability to model long-range dependencies and the computational efficiency. We placed our self-attention modules in each branch of the 3I module as shown in Figure 1c. We call this a 2A3I module.

2.2.3 Overview of SAINT

A schematic diagram of the overall architecture of SAINT is depicted in Figure 1d. SAINT starts with two consecutive 2A3I modules followed by a self-attention module to supplement the nonlocal interactions captured by the initial two 2A3I modules. We also observed that this attention module helps achieve faster learning rate. MUFOLD-SS used one convolutional layer with window size 11 after two 3I modules. The level of long-range interactions being captured varies with varying lengths of the window. However, we observed that using a window size larger than 11 increases the computational cost without significantly increasing the performance. As a result, we used similar convolutional layer as MUFOLD-SS. However, we included another self-attention module after the convolutional layer to help capture the relations among vectors that the convolutional layer failed to retrieve. The last two dense layers in the MUFOLD-SS were also used in SAINT. However, we placed an attention module in between the two dense layers. We did so to understand how the residues align and interact with each other just before generating the output. This paves the way to have an interpretable deep-learning model (as we will discuss in Section 3.4).

3 Results and discussion

We performed an extensive evaluation study, comparing SAINT with the state-of-the-art Q8 prediction methods on a collection of publicly available benchmark datasets.

3.1 Dataset

To make a fair comparison with the most recent state-of-the-art methods, especially with SPOT-1D (the most accurate method to date), we used the same training and validation sets that were used in SPOT-1D. However, apart from comparing our model against the most recent and large test sets TEST2016 and TEST2018 generated and analyzed by Hanson *et al.* (2018, 2019), we evaluated SAINT on CASP12, CASP13 and the template-FM targets of four CASP

datasets (CASP10 \sim CASP13). CB513 (Cuff and Barton, 1999), which is a relatively old, yet widely used benchmark dataset has been excluded from our evaluation as there are many sequences in CB513 with > 25% sequence similarity to the training set.

The training set contains 10 029 proteins from Cull PDB server (Wang and Dunbrack, 2003) with resolution <2.5 Å, *R*-factor <1.0 and a sequence identity cutoff of 25% according to BlastClust (Altschul *et al.*, 1997). The validation set contains 983 proteins from CullPDB (Wang and Dunbrack, 2003) with the same specifications applied to training set [see Hanson *et al.* (2019) and Hanson *et al.* (2018) for more details on these dataset]. We provide brief descriptions of the test sets in subsequent sections.

3.1.1 TEST2016

TEST2016 dataset contains 1213 proteins that were all deposited on PDB (Berman *et al.*, 2000) between June 2015 and February 2017 with similar parameter settings as the training set and do not contain more than 700 residues. It has <25% sequence similarity with the training and validation sets according to BlastClust (Altschul *et al.*, 1997). It was compiled by Hanson *et al.* (2018) and is available at https://servers.sparks-lab.org/downloads/SPOT-1D-dataset.tar.gz.

3.1.2 TEST2018

TEST2018 dataset contains 250 high-quality, non-redundant proteins that were all deposited on PDB between January 2018 and July 2018. The dataset was also filtered to remove redundancy at a 25% sequence identity cutoff and to remove proteins having more than 700 residues. It was generated by Hanson *et al.* (2018) and is available at https://servers.sparks-lab.org/downloads/SPOT-1D-dataset. tar.gz.

3.1.3 CASP

CASP stands for Critical Assessment of protein Structure Prediction. This is an biennial competition for protein structure prediction and a community wide effort to advance the state-of-the-art in modeling protein structure from its amino acid sequences since 1994 (Koehl and Levitt, 1999). Among the CASP datasets, we took into account the most recent ones CASP12 and CASP13. We removed one domain sequence out of 32 in CASP13 (T0951-D1) and 6 domain sequences out of 55 in CASP12 as they had more than 25% sequence similarity to the training set according to CD-HIT (Huang et al., 2010). Apart from these, we prepared a dataset comprising the template-FM targets in CASP datasets to show the performance of SAINT, where the query sequences do not have statistically significant similar protein sequences with known structures. Some of the FM targets had > 25\% sequence similarity with our training set, which were therefore excluded from the test set. Thus, we compiled a test set, which we call CASP-FM comprising 56 domain sequences: 10 FM targets from CASP13, 22 FM targets from CASP12, 16 FM targets (out of 30) from CASP11 and 8 FM targets (out of 12) from CASP10. The CASP proteins were downloaded from its official website http://predictioncenter.org/.

3.2 Method comparison

We compared SAINT with the most recent and accurate Q8 predictors: MUFOLD-SS (Fang et al., 2018), NetSurfP (Klausen et al., 2019) and SPOT-1D (Hanson et al., 2019). These state-of-the-art methods have been shown to outperform other popular Q8 predictors, namely, SSPro8 (Pollastri et al., 2002), RaptorX-SS8 (Wang et al., 2010), DeepGSN (Zhou and Troyanskaya, 2014), DeepCNF (Wang et al., 2016a), DCRNN (Li and Yu, 2016), NCCNN (Busia and Jaitly, 2017), CNNH_PSS (Zhou et al., 2018), CBRNN (Guo et al., 2018), etc.

We evaluated the methods under various evaluation metrics, such as Q8 accuracy, precision, recall and F1-score. We performed Wilcoxon signed-rank test (Wilcoxon et al., 1970) (with $\alpha=0.05$) to measure the statistical significance of the differences between SAINT and each of the compared state-of-the-art methods.

3.3 Results on benchmark dataset

The comparison of SAINT with the state-of-the-art Q8 structure prediction methods on TEST2016, TEST2018, CASP13, CASP12 and CASP-FM is shown in Table 1. To train SAINT and tune necessary hyper-parameters, we have used the same training and validation sets that were used by SPOT-1D. Notably, SPOT-1D is an ensemble of nine models where each single model uses predicted contact map in addition to other features. SAINT, on the other hand, is an ensemble of only four models, three of which take advantage of predicted contact map with different windows sizes. Experimental results show that SAINT outperforms all other methods across all the test sets. It is worth mentioning that SAINT's accuracy on the validation set (78.18%) was also better than that of SPOT-1D (77.60%). SPOT-1D's base model, which does not require contact maps as features is also an ensemble of nine models, whereas SAINT-base model is a single model. Despite being a single model, SAINT-base consistently outperformed SPOT-1D base in TEST2016 and TEST2018. We could not evaluate SPOT-1D base on CASP12, CASP13 and CASP-FM as it is not publicly available. From Table 1, it is also evident that SAINT is substantially better than the other recent methods, namely, NetSurfP-2.0 and MUFOLD-SS. Even the base model of SAINT consistently outperformed both NetSurfP-2.0 and MUFOLD-SS. The remarkably large improvement of SAINT over MUFOLD-SS across all the dataset suggests the advantage of augmenting our proposed self-attention mechanism in the Deep3I network used in MUFOLD-SS. Statistical tests (see Table 2) suggests that these improvements of SAINT over other methods are statistically significant ($P \ll 0.05$).

In addition to the model accuracy, we also investigated the precision, recall and F1-score to obtain better insights on the performances of various methods. Precision, also known as predictivity, denotes the confidence that can be imposed on a prediction. Recall signifies how accurately an algorithm can predict a sample from a particular class. Sometimes an algorithm tends to over-classify which results into high recall but low precision. On the other hand, some algorithms tend to under-classify, preserving the precision at the cost of recall. In order to get an unbiased evaluation of the performance, F1-score is considered to be an appropriate measure and has been being used for over 25 years in various domains (Sasaki et al., 2007; Tjong Kim Sang and De Meulder, 2003). Tables 3-5 show the precision, recall and F1-score on each of the Q8 obtained by SAINT and other methods. These results suggest that SAINT achieves better F1-score than other methods on five states (out of Q8), showing that SAINT produced more balanced and meaningful results than other methods. SAINT substantially outperforms other methods on the non-ordinary states (Wang et al., 2016a), such as I, G, S and T. However, MUFOLD-SS and SPOT-1D achieved slightly better F1-score for the 'B' and 'E' states, respectively. State 'I' (π helix) is extremely rare which comprises 7 or more residues and is present in 15% of all known protein structures (Ludwiczak et al., 2019). They are very difficult to predict, but mostly found at functionally important regions, such as ligand- and ion-binding sites (Ludwiczak et al., 2019). Therefore, specialized predictors, such as PiPred (Ludwiczak et al., 2019), are also available that only predicts

Table 1. A comparison of the Q8 accuracy (%) obtained by SAINT and other state-of-the-art methods on benchmark dataset

Method	TEST2016	TEST2018	CASP13	CASP12	CASP-FM
SAINT ^a	77.73	76.09	74.78	74.17	72.25
SPOT-1D ^a	77.10	75.41	73.91	73.67	71.85
SAINT-base	76.23	74.48	73.5	71.78	70.00
SPOT-1D-base ^{a,b}	76.03	74.26	_	_	_
NetSurfP-2.0	75.68	73.04	72.85	71.43	70.16
MUFOLD-SS	75.56	73.66	73.44	71.44	70.21

Note: Best results for each benchmark dataset are shown in bold. ^aIndicates ensemble model.

^bNot publicly available. Results reported by SPOT-1D (Hanson *et al.*, 2019).

Table 2. Statistical significance of the Q8 accuracy between SAINT and other state-of-the-art methods

Method		TEST2018 (250)		CASP12 (49)	CASP-FM (56)
SPOT-1D NetSurfP-2.0 MUFOLD-SS	2.607 <i>e</i> -57		0.179	1.55e-6	0.0001

Note: The numbers of protein chains or domains in these datasets are shown in parentheses. We show the P-values using a Wilcoxon signed-rank test

Table 3. Predictive precision on each of the Q8 obtained by SAINT and other state-of-the-art methods on TEST2016 dataset

Q8 label	SAINT	SPOT-1D	NetSurfP-2.0	MUFOLD-SS
Н	0.879	0.884	0.885	0.868
В	0.76	0.671	0.65	0.609
E	0.843	0.852	0.822	0.85
G	0.581	0.547	0.536	0.519
I	1	1	0.044	0.857
T	0.663	0.641	0.615	0.631
S	0.639	0.624	0.579	0.589
C	0.648	0.631	0.613	0.607

Note: Best results are shown in bold.

Table 4. Recall on each of the Q8 obtained by SAINT and other state-of-the-art methods on TEST2016 dataset

Q8 label	SAINT	SPOT-1D	NetSurfP-2.0	MUFOLD-SS
Н	0.948	0.941	0.933	0.943
В	0.104	0.097	0.07	0.115
E	0.887	0.878	0.903	0.842
G	0.39	0.375	0.334	0.348
I	0.447	0.128	0.426	0.383
T	0.618	0.612	0.585	0.586
S	0.367	0.337	0.278	0.313
С	0.731	0.741	0.704	0.727

Note: Best results are shown in bold.

the π -helix structures. SAINT significantly outperforms SPOT-1D, NetSurfP-2.0 and MUFOLD-SS in predicting π -helix in TEST2016 dataset by correctly predicting 21 out of 47 °T states and thus achieving a recall of 0.45 for this structure. SAINT's precision for π -helix, on the other hand, is 1. This is remarkable considering the fact that the π -helix specific predictor, PiPred, reports precision and recall of 0.48 and 0.46, respectively, on a different dataset which they analyzed in Ludwiczak *et al.* (2019). However, this comparison should be taken with a grain of salt since the reported values are on different test sets.

We analyzed the CASP-FM dataset comprising the FM targets in the CASP dataset to demonstrate the performance of models on proteins with previously unseen folds. SAINT achieved the best accuracy on CASP-FM, suggesting SAINT's superiority in predicting structures of proteins having unseen folds.

While the advantage of utilizing our proposed self-attention mechanism in the Deep3I framework of MUFOLD-SS is evident from the significant improvement of SAINT over MUFOLD-SS across all the dataset analyzed in this study, we further investigated the efficacy of our proposed attention mechanism in capturing the long-range interactions. We computed the number of non-local

Table 5. F1-score on each of the Q8 obtained by SAINT and other state-of-the-art methods on TEST2016 dataset

Q8 label	Frequency	SAINT	SPOT-1D	NetSurfP-2.0	MUFOLD-SS
Н	98 139	0.912	0.911	0.908	0.904
В	3018	0.183	0.169	0.126	0.193
E	62 657	0.864	0.865	0.861	0.846
G	10 770	0.467	0.445	0.412	0.417
I	47	0.618	0.227	0.079	0.529
T	32 297	0.639	0.626	0.599	0.608
S	23 466	0.466	0.438	0.376	0.409
C	57 483	0.687	0.682	0.655	0.662

Note: Best results are shown in bold.

Table 6. Accuracy of SAINT(base) and MUFOLD-SS under various levels of non-local interactions

Non-local contacts per residue	•	Accuracy (%) MUFOLD-SS		P-value
0-0.61	83.01	83.05	-0.04	0.721
0.61-0.99	78.77	78.46	0.31	0.0103
0.99-1.24	75.80	75.37	0.43	0.004
1.24-1.45	75.79	75.14	0.65	0.0003
1.45-1.64	75.46	74.60	0.86	0.0001
1.64-2.70	73.79	72.63	1.16	1.36e-6

Note: A total of 1213 proteins in TEST2016 were divided into 6 disjoint bins each having 202 proteins except the last one, which had 203 proteins. The binning was based on the number of non-local contacts per residue in the proteins.

interactions per residue for each of the 1213 proteins in TEST2016, and sorted them in an ascending order. Two residues at sequence position i and j are considered to have non-local interaction if they are at least 20 residues apart ($|i-j| \ge 20$), but <8 Å away in terms of their atomic distances between Cα atoms (Heffernan et al., 2017). Next, we put them in six equal sized bins b_1, b_2, \dots, b_6 (each containing 202 proteins except for b_6 , which contains 203 proteins), where b_1 contains the proteins with the lowest level of non-local interactions and b_6 represents the model condition with the highest level of non-local interactions. We show the Q8 accuracy of SAINTbase and MUFOLD-SS on these model conditions in Table 6 and Figure 2. Note that, instead of our ensemble model, which is more accurate than our base model, we deliberately show the results for our single base model, which uses the same feature set as MUFOLD-SS, and the only difference between them is the self-attention modules introduced in our architecture.

These results show that the difference in predictive performance between SAINT-base and MUFOLD-SS significantly increases with increasing levels of non-local interactions. There is no statistically significant difference between them on b_1 , but as we increase the level of non-local interactions, SAINT becomes significantly more accurate than MUFOLD-SS and attains the highest level of improvement on b_6 . This clearly indicates that capturing non-local interactions by self-attention is the key factor in the improvement. We also performed the same analyses on other methods (see Fig. 3). The results in Figure 3 show that the differences among of these methods are not that substantial on the model conditions with low levels of long-range interactions, but the differences become notable as we increase the non-local interactions. SAINT not only achieved the best accuracy, its improvement over other methods increases with increasing amount of long-range interactions as well-suggesting the superiority of our proposed self-attention mechanism compared CNN+LSTM (used in NetSurfP-2.0) and

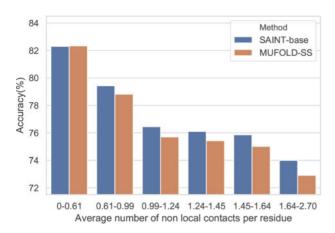


Fig. 2. Accuracy of SAINT-base and MUFOLD-SS under various levels of non-local interactions. We show the results on the TEST2016 test set using six bins of proteins as shown in Table 6

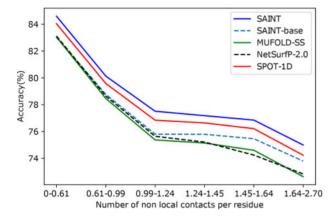


Fig. 3. Accuracy of SAINT, SPOT-1D, NetSurfP-2.0 and MUFOLD-SS as a function of the average number of non-local interactions per residue. We show the results on the six bins as shown in Table 6

(ResNet)+BRLSTM (used in SPOT-1D) in terms of capturing the non-local interactions. In order to demonstrate the efficacy of SAINT and other methods in capturing the continuous structure of a protein, we show the 1D map of the annotated and predicted SS of a representative protein 5M2PA in TEST2016 (see Fig. 4).

3.4 Interpretability

One notable feature of SAINT is that, unlike most of the existing deep-learning techniques, it can provide insights on how the architecture is making decisions, especially regarding the long-range interactions. Self-attention alignment matrix has already been used to interpret how different parts of input are dependent on each other while generating the output (Alkhouli and Ney, 2017; Ghaeini *et al.*, 2018; Lee *et al.*, 2017; Vaswani *et al.*, 2017; Xu *et al.*, 2015), and hence it was used to develop interpretable models (Chen *et al.*, 2019; Choi *et al.*, 2016; Karimi *et al.*, 2019; Kim and Canny, 2017). Thus, we made an attempt at using attention matrix to capture and provide insight into the long-range interactions. Long-range interactions are crucial for predicting the SS of proteins. For example, a SS state β -strand is stabilized by hydrogen bonds formed with other β -strands that can be far apart from each other in the protein sequence (Zhou and Troyanskaya, 2014).

As mentioned earlier, we placed an attention module just before the last dense layer in the architecture of SAINT. In addition to improving the prediction performance, a motivation behind this attention module has been to introduce some form of interpretability to the deep-learning model. Indeed, we are able to relate the selfattention alignment score matrix of this attention module to the spatial proximity of a residue with other residues far apart in the primary sequence. In Figure 5, we show the relation between the spatial proximity and attention scores for a sample protein 5epmD in TEST2016. We selected a short sequence 5epmD (only 33 residues) to easily demonstrate with visualizations how the selfattention alignment matrix provides insight about the long-range interactions. We show the distances of the first five residues ('D', 'C', 'L', 'G', 'M') to all other subsequent residues as line graphs and superimpose them on the attention matrix obtained by a single model of SAINT. We choose only the first five residues for the sake of readability and clarity of this figure. For an attention matrix A, an attention score A(i,j) represents the amount of attention given to the residue *j* while encoding the information of residue *i*. Attention scores are represented by the darkness of the hues in the matrix

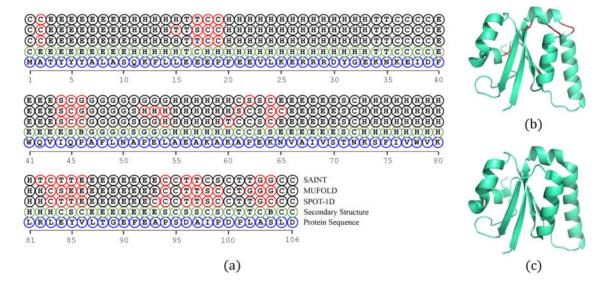


Fig. 4. Structure prediction on 5M2PA protein chain by various methods. (a) 1D map of the native structure of 5M2PA and the predicted structures by various methods. (b) Native structure of 5M2PA, rendered by Pymol (DeLano et al., 2002), reflecting the SSs predicted by SAINT. The areas where the predicted states do not match with the annotated states (obtained from PDB) are shown in red. Since Pymol does not differentiate between all the eight distinct states, we translated the eight-state structure to three-state structure according to the Rost and Sander scheme (Rost and Sander, 1993). (c) Native structure of 5M2PA using the SS obtained from PDB

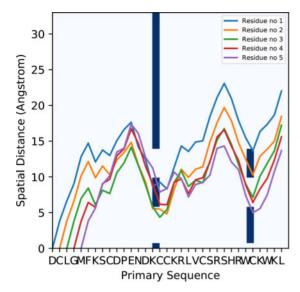


Fig. 5. Demonstration of the interpretability of SAINT using the attention map. Spatial distances of the first five residues ('D', 'C', 'L', 'G', 'M') in 5epmD to all other subsequent residues are shown by line graphs and they are superimposed on the attention matrix. Deeper hue on the 15th residue 'K' and the 28th residue 'W' indicates that higher levels of attention have been given to these two residues

shown in Figure 5, i.e. deeper hues indicate higher levels of attention. If we take the summation of attention scores given to various residues, relatively higher attentions can be observed for the 15th residue 'K' and 28th residue 'W' in 5epmD. Interestingly, these two residues are where the spatial distance lines reach their local minima, indicating a possible turn, bend or contact pair. Being inspired by this, we systematically analyzed the attention matrices and spatial distance graphs of all the 1213 proteins in TEST2016. We define a 'downslope' region in a spatial proximity line graph to be a segment where the slope of the line is negative for three or more successive residues. A downslope region thus indicates that the spatial distance is decreasing while the distance in primary sequence is increasing. Segments with negative slope spanning <3 residues (i.e. very small decreasing regions) are not considered. We have observed that, in 93.33% of these proteins, the residues with most attention on them are within a downslope region of another residue's spatial distance line curve. This indicates that the residues with relatively higher attention scores are likely to be spatially closer to some other distant residues in the primary sequence. Further analysis shows that the average (over the 1213 proteins in TEST2016) number of contact pairs associated to the residues with the highest attention is 1.85, which is much higher than the average number of contact pairs per residue equaling 1.15. While these results are promising, especially considering the black-box nature of other deep learning based methods, they should be interpreted with care. The long-range interactions suggested by the attention matrix may contain false positives and false negatives. Higher attention scores do not necessarily guarantee a contact pair, nor is it certain that all the contact pairs will have relatively higher attention scores. More work is required to design an attention mechanism so that the attention matrix is more closely related to the contact map. This is an interesting research avenue, which we left as a future work. We believe that this matrix with appropriate modifications will be useful to understand the complex relationship between the primary sequence and various structural and functional properties of proteins.

3.5 Running time

SAINT is much faster than the best alternate method SPOT-1D. For generating the structures of 1213 protein chains in TEST2016, given the necessary input files, SAINT took \sim 360 \pm 5 s whereas SPOT-1D took \sim 2485 \pm 5 s on our local machine [Intel core i7-7700 CPU (4 cores), 16 GB RAM, NVIDIA GeForce GTX 1070 GPU]. Under the

same settings, SAINT took \sim 197 ± 5 s to generate SSs for the 250 proteins in TEST2018, whereas SPOT-1D took \sim 668 ± 5 s. Since both these methods use the same input files for feature generation, this substantial difference in running time can be attributed to the efficiency of our attention based method over the LSTM network-based model used in SPOT-1D.

4 Conclusions

We have presented SAINT, a highly accurate, fast and interpretable method for O8 SS prediction. We demonstrate for the first time that the self-attention mechanism proposed by Vaswani et al. (2017) is a valuable tool to apply in the structural analyses of proteins. Another earlier type of attention mechanism proposed by Bahdanau et al. (2014) coupled with RNN based encoder-decoder architectures achieved state-of-the-art performance on various natural language processing tasks [e.g. neural machine translation (Firat et al., 2016; Luong et al., 2015), question answering task (Lu et al., 2016; Xiong et al., 2016), text summarization (Rush et al., 2015; See et al., 2017), document classification (Pappas and Popescu-Belis, 2017; Yang et al., 2016b), sentiment classification (Tang et al., 2016; Wang et al., 2016b), etc.]. As proteins are also sequences similar to sentences in a language, this type of architecture is expected do well in protein SS prediction as well. However, previous attempts (Drori et al., 2018) on using attention with LSTM based encoder-decoder only achieved 68.4% accuracy on CB513 dataset, which is significantly worse than the performance of MUFOLD-SS (70.63% on CB513) (Fang et al., 2018). In this study, we have used the selfattention mechanism in a unique way and proposed a novel 2A3I module and achieved notable success. We have used the selfattention mechanism to retrieve the relation between vectors that lay far from each other in a sequence. As self-attention mechanism looks at a single vector and measures its similarity or relationship with all other vectors in the same sequence, it does not need to encode all the information in a sequence into a single vector like RNNs. This reduces the loss of contextual information for long sequences.

SAINT contributes toward simultaneously capturing the local and non-local dependencies among the amino acid residues. Unlike some of the existing deep-learning methods, SAINT can capture the long-range dependencies without using computationally expensive recurrent networks or convolution networks with large window sizes. SAINT was assessed for its performance against the state-ofthe-art Q8 SS prediction methods on a collection of widely used benchmark dataset. Experimental results suggest that SAINT consistently improved upon the best existing methods across various widely used benchmark dataset. One of the most significant conclusions from the demonstrated experimental results is that appropriate use of self-attention mechanism can significantly boost the performance of deep neural networks and is capable of producing results, which rank SAINT at the very top of the current SS prediction methods. Thus, the idea of applying self-attention mechanism can be applied to predict various other protein attributes [e.g. torsion angles, turns, etc. (Fang et al., 2019)] as well. Therefore, we believe SAINT advances the state-of-the-art in this domain, and will be considered as a useful tool for predicting the SSs of proteins.

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Conflict of Interest: none declared.

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