

Experimental Validation and Adjustment of a Theoretical Model for Mid-Air Collision of Projectiles

Aaradhay Anand, Tolly Zhang

October 24, 2024

1 Abstract

This experiment explored the collision dynamics of two projectiles launched simultaneously from distinct starting points to apply principles of projectile motion in predicting precise collision coordinates. Positioned two meters apart, the launch apparatuses propelled projectiles in parallel, necessitating accurate calculation of initial velocities and launch angles. Measured velocities obtained from speed traps and calculated launch angles were used to establish initial conditions for predicting and observing the collision of both projectiles. A comparison of theoretical predictions with observed results demonstrated the reliability of projectile motion equations and highlighted their relevance to practical applications, reinforcing our understanding of kinematic principles in physics.

2 Introduction

2.1 Theory

A projectile is defined as a body under motion subject only to the force of gravity. On the earth's surface, a freely falling body will experience an acceleration of $g = 9.81 \text{ m/s}$. The following pair of parametric equations can model the motion of a projectile based on its initial setup:

$$\begin{aligned}x(t) &= v_0 \cos(\theta) \cdot t \\ y(t) &= v_0 \sin(\theta) \cdot t - \frac{1}{2}gt^2\end{aligned}$$

where:

1. $x(t)$ is the **horizontal displacement** from the launch point at time t ,
2. $y(t)$ is the **vertical displacement** from the launch point at time t .
3. v_0 is the **initial velocity**,
4. θ is the **launch angle**, and
5. g is the **acceleration due to gravity**.

2.2 Setup

Our setup consisted of two projectile launchers positioned at the same vertical height and angled so their projectile paths would be co-planar. Let them be launchers A and B . The following variables were defined:

- Define a coordinate plane that is co-planar to the paths of both projectiles. The unit vectors, \hat{i} and \hat{j} , are equal to 1mm, respectively.
- Let t be time, where $t = 0$ at the instant both projectiles are launched.
- Let $x^A(t)$, $y^A(t)$, $x^B(t)$, and $y^B(t)$ be the positions of x and y for launchers A and B , respectively, as a function of t .
 - The displacement vectors of both launchers can be represented using $\vec{s}^A(t)$ and $\vec{s}^B(t)$, where:

$$\vec{s}^A(t) = \begin{bmatrix} x^A(t) - x^A(0) \\ y^A(t) - y^A(0) \end{bmatrix}$$

$$\vec{s}^B(t) = \begin{bmatrix} x^B(t) - x^B(0) \\ y^B(t) - y^B(0) \end{bmatrix}$$

- Let $v_x^A(t)$, $v_y^A(t)$, $v_x^B(t)$, and $v_y^B(t)$ be the horizontal and vertical velocities of launchers A and B , respectively, as a function of t .
 - Here, the functions are equal to the first-order derivatives of their position counterparts. For example:

$$v_x^A(t) = \frac{dx^A(t)}{dt}$$

The same applies to the other 3 functions.

- Likewise, the combined velocities of both launchers can be represented using $\vec{v}^A(t)$ and $\vec{v}^B(t)$, where:

$$\vec{v}^A(t) = \begin{bmatrix} v_x^A(t) \\ v_y^A(t) \end{bmatrix}$$

$$\vec{v}^B(t) = \begin{bmatrix} v_x^B(t) \\ v_y^B(t) \end{bmatrix}$$

- Let the displacement vector from the position of launcher A to launcher B be denoted as \vec{D} . Assuming the starting position of launcher A is at the origin, the starting positions of both launchers can be written as:

$$\vec{s}^A(0) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\vec{s}^B(0) = \vec{s}^A(0) + \vec{D}$$

2.3 Collision Conditions

Let the collision time be denoted as t_c such that $\vec{s}^A(t_c) = \vec{s}^B(t_c)$.

2.4 Predicted Calculations

Calculations:

1. Equating Vertical Positions:

Set $y_A(t_c) = y_B(t_c)$:

$$v_A \sin(\theta_A)t_c - \frac{1}{2}gt_c^2 = v_B \sin(\theta_B)t_c - \frac{1}{2}gt_c^2$$

Simplify:

$$v_A \sin(\theta_A)t_c = v_B \sin(\theta_B)t_c$$

Since t_c is common on both sides of the equation, it would cancel out.

Equation (1):

$$v_A \sin(\theta_A) = v_B \sin(\theta_B)$$

2. Equate Horizontal Positions:

Set $x_A(t_c) = x_B(t_c)$:

$$v_A \cos(\theta_A)t_c = D + v_B \cos(\theta_B)t_c$$

Taking all terms that have t_c to one side:

$$(v_A \cos(\theta_A) - v_B \cos(\theta_B))t_c = D$$

Equation (2):

$$t_c = \frac{D}{v_A \cos(\theta_A) - v_B \cos(\theta_B)}$$

Solve for θ_A and θ_B : We have two equations with three unknowns (θ_A , θ_B , t_c). To solve this, we would choose a value for one of the angles and solve for the others.

For this, we would take the angle of our launcher B, i.e. $\theta_B = 74^\circ$.

Calculate $\sin(\theta_B)$ and $\cos(\theta_B)$:

- $\sin(74^\circ) = 0.9613$

- $\cos(74^\circ) = 0.2756$

Using Equation (1) that we found above to solve for θ_A :

$$v_A \sin(\theta_A) = v_B \sin(\theta_B)$$

$$6.45 \sin(\theta_A) = 4.735 \times 0.9613$$

$$6.45 \sin(\theta_A) = 4.552 \text{ m/s}$$

Solving for $\sin(\theta_A)$:

$$\sin(\theta_A) = \frac{4.552}{6.45} \Rightarrow 0.7066$$

Calculate θ_A :

$$\theta_A = \arcsin(0.7066) = 44.9^\circ$$

Therefore, our predicted value for our large launcher is 44.9 degrees, making $\theta_A = 44.9^\circ$.

Calculating Collision Time (t_c) Calculate $\cos(\theta_A)$:

$$\cos(44.9) = \sqrt{1 - \sin^2(44.9)} = \sqrt{1 - (0.7066)^2} = 0.7076$$

Calculate $v_A \cos(\theta_A)$ and $v_B \cos(\theta_B)$:

$$v_A \cos(\theta_A) = 6.45 \times 0.7076 = 4.563 \text{ m/s}$$

$$v_B \cos(\theta_B) = 4.735 \times 0.2756 = 1.304 \text{ m/s}$$

From here, we use Equation (2) to calculate the time (t_c):

$$t_c = \frac{D}{v_A \cos(\theta_A) - v_B \cos(\theta_B)}$$

$$t_c = \frac{2.0}{4.563 - 1.304} \Rightarrow \frac{2.0}{3.259} = 0.6136 \text{ s}$$

Calculate Collision Point Horizontal position at t_c

- **Projectile A:**

$$x_A(t_c) = v_A \cos(\theta_A)t_c = 4.563 \times 0.6136 = 2.798 \text{ m}$$

- **Projectile B:**

$$x_B(t) = D + v_B \cos(\theta_B)t$$
$$x_B(t) = 2.0 + 1.304 \times 0.6136 = 2.0 + 0.8 = 2.798 \text{ m}$$

These calculations show that our horizontal values are equal, which means that our projectile would be at the same position on the x-axis.

Vertical position at t_c

- **Projectile A:**

$$y_A(t_c) = v_A \sin(\theta_A)t - \frac{1}{2}gt^2$$
$$y_A(t_c) = 4.552 \times 0.6136 - 4.905 \times (0.6136)^2$$
$$y_A(t_c) = 2.793 - 1.847 = 0.946 \text{ m}$$

- **Projectile B:**

$$y_B(t_c) = v_B \sin(\theta_B)t - \frac{1}{2}gt^2$$
$$y_B(t_c) = 4.552 \times 0.6136 - 4.905 \times (0.6136)^2$$
$$y_B(t_c) = 2.793 - 1.847 = 0.946 \text{ m}$$

Since vertical and horizontal velocities are equal, we can predict that the projectiles would collide at these coordinates, given these values.

3 Materials and Methods

3.1 Materials

- **Launcher A (Big Launcher):**

- Plastic ball (25.3 mm in diameter, 9.73 g mass)
- Positioned at $x = 0 \text{ m}$

- Velocity is measured using a speed trap
- **Launcher B (Small Launcher):**
 - Metal ball (15.7 mm diameter, 16.36 g mass)
 - Positioned at $x = D = 2$ m
 - Velocity is measured using a speed trap
- Sparkview Speed Trap
- Measuring Tape to measure the distance between launchers

3.2 Methods

1. Position Launcher A (big launcher) at $x = 0$ m and Launcher B (small launcher) at $x = 2$ m, both set to the same vertical height.
2. Record the exit velocities of both projectiles by conducting several trials.
3. Calculate the average velocity for both projectiles.
4. Use kinematic equations to predict the required launch angles for both projectiles to collide in mid-air, considering that Launcher A is two meters behind Launcher B.
5. Launch both projectiles simultaneously and record the actual launch angles and collision points.
6. Compare the calculated values with the actual results and analyze any differences.

4 Results

4.1 Launcher A (Big Launcher)

	Slowest mode	Medium mode	High Speed
Trial 1	3.22 m/s	4.74 m/s	6.64 m/s
Trial 2	3.17 m/s	4.84 m/s	6.27 m/s
Trial 3	3.18 m/s	4.80 m/s	6.44 m/s
Average	3.19 m/s	4.79 m/s	6.45 m/s

Table 1: Velocity data for Launcher A (Big Launcher)

4.2 Launcher B (Small Launcher)

	Slowest mode	Medium mode	High Speed
Trial 1	2.49 m/s	3.55 m/s	4.69 m/s
Trial 2	2.55 m/s	3.55 m/s	4.73 m/s
Trial 3	2.55 m/s	3.55 m/s	4.75 m/s
Average	2.53 m/s	3.55 m/s	4.72 m/s

Table 2: Velocity data for Launcher B (Small Launcher)

4.3 Additional Information

- Distance between launchers: $D = 2.0$ m
- Gravity: $g = 9.81$ m/s²

5 Discussion

5.1 Summary of Experimental Results

In this experiment, we aimed to determine the required launch angles and timing for two projectiles, launched in the same direction from different starting points, to collide mid-air. After conducting the experiment and analyzing the slow-motion footage, we obtained the following values:

- **Launcher A (Large Projectile):** Experimental launch angle of 40° .
- **Launcher B (Small Projectile):** Experimental launch angle of 74° .
- **Collision Time:** 0.62 seconds, calculated by multiplying the time measured in slow motion by the frames per second (FPS) of the recording.

These values closely align with the pre-lab calculations, which predicted angles close to 44.9° for Launcher A and exactly 74° for Launcher B, as well as a collision time of approximately 0.6136 seconds.

5.2 Comparison with Pre-Lab Calculations

The experimentally obtained angle for Launcher A is 40° , while the pre-lab calculation predicted an angle of 44.9° . This corresponds to a difference of approximately 4.9° , or

a 12.25% discrepancy from the predicted angle. For Launcher B, the experimental and calculated angles match exactly at 74° . The collision time calculated from the experiment (0.62 seconds) is also remarkably close to the predicted time of 0.6136 seconds, differing by less than 1%.

These results suggest that the pre-lab calculations provided the predicted values necessary for a collision. The slight discrepancy in Launcher A's angle could be due to minor errors in angle measurement, subtle inconsistencies in initial velocity, or the effects of air resistance, which were neglected in the theoretical model.

5.3 Evaluation of Measurement Techniques

The collision time was determined using a slow-motion recording. To obtain the time, I multiplied the recorded slow-motion time by the video's FPS. This technique allowed for accurate time measurement, minimizing human error in timing but introducing potential error due to slight frame rate variations or imprecisions in playback speed.

5.4 Potential Sources of Error

1. **Angle Measurement:** Small errors in measuring the launch angles could contribute to the observed discrepancies. Even a minor deviation in the launcher setup could slightly alter the launch angle.
2. **Initial Velocity Variations:** The experimental setup may not perfectly reproduce the exact initial velocities used in calculations. Variations in launcher tension or minor friction effects could impact the speed. The reason for this is spring overuse; as we keep loading and releasing a spring, its base length tends to grow shorter because of how often it is compressed, which can lead to the spring being more compressed and releasing less force on the ball.
3. **Air Resistance:** Although the theoretical calculations assumed no air resistance, real-world conditions introduce a slight drag on each projectile, which could affect both angle and collision timing.
4. **Data Collection:** While collecting our initial velocities, we had the launchers shoot the projectile horizontally and vertically to find the velocity of the ball now because we couldn't predict at what angle our ball would be launching just to get our velocity values, we shot the ball horizontally along the table. Although this method did work, there are chances that the ball might have rubbed against the barrel of the turret, which could've slowed down its initial release trajectory.
5. **Laser Discrepancies:**

6 Conclusion

The experiment successfully validated the pre-lab calculations, demonstrating that the theoretical model for projectile motion can accurately predict collision conditions within an acceptable margin of error. The small discrepancies observed emphasize the impact of real-world factors like measurement precision and air resistance, which should be accounted for in further studies. This experiment underscores the reliability of kinematic equations for predicting projectile motion, even in complex scenarios with multiple variables.