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In [1]: from __future__ import print_function

import tensorflow as tf
import os

In [2]: # Dataset Parameters - CHANGE HERE
MODE = 'folder' # or 'file', if you choose a plain text file (see above).
DATASET_PATH = 'C:/Users/tom13/jupyter/FYP/food-101/train' # the dataset file or root folder

# Image Parameters
N_CLASSES = 101 # CHANGE HERE, total number of classes
IMG_HEIGHT = 128 # CHANGE HERE, the image height to be resized to
IMG_WIDTH = 128 # CHANGE HERE, the image width to be resized to
CHANNELS = 3 # The 3 color channels, change to 1 if grayscale

In [3]: # Reading the dataset
# 2 modes: 'file' or 'folder'
def read_images(dataset_path, mode, batch_size):
    imagepaths, labels = list(), list()
    if mode == 'file':
        # Read dataset file
        data = open(dataset_path, 'r').read().splitlines()
        for d in data:
            imagepaths.append(d.split(' ')[0])
            labels.append(int(d.split(' ')[1]))
    elif mode == 'folder':
        # An ID will be affected to each sub-folders by alphabetical order
        label = 0
        # List the directory
        try: # Python 2
            classes = sorted(os.walk(dataset_path).next()[1])
        except Exception: # Python 3
            classes = sorted(os.walk(dataset_path).__next__()[1])
        # List each sub-directory (the classes)
        for c in classes:
            c_dir = os.path.join(dataset_path, c)
            try: # Python 2
                walk = os.walk(c_dir).next()
            except Exception: # Python 3
                walk = os.walk(c_dir).__next__()
            # Add each image to the training set

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        for sample in walk[2]:
            # Only keeps jpeg images
            if sample.endswith('.jpg') or sample.endswith('.jpeg'):
                imagepaths.append(os.path.join(c_dir, sample))
                labels.append(label)
            label += 1
    else:
        raise Exception("Unknown mode.")

    # Convert to Tensor
    imagepaths = tf.convert_to_tensor(imagepaths, dtype=tf.string)
    labels = tf.convert_to_tensor(labels, dtype=tf.int32)
    # Build a TF Queue, shuffle data
    image, label = tf.train.slice_input_producer([imagepaths, labels],
                                                shuffle=True)

    # Read images from disk
    image = tf.read_file(image)
    image = tf.image.decode_jpeg(image, channels=CHANNELS)

    # Resize images to a common size
    image = tf.image.resize_images(image, [IMG_HEIGHT, IMG_WIDTH])

    # Normalize
    image = image * 1.0/127.5 - 1.0

    # Create batches
    X, Y = tf.train.batch([image, label], batch_size=batch_size,
                          capacity=batch_size * 8,
                          num_threads=4)

    return X, Y

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In [4]: # Parameters
        learning_rate = 0.001
        num_steps = 5000
        batch_size = 32
        display_step = 500

        # Network Parameters
        dropout = 0.75 # Dropout, probability to keep units

        # Build the data input
        X, Y = read_images(DATASET_PATH, MODE, batch_size)

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In [5]: # Create model
        def conv_net(x, n_classes, dropout, reuse, is_training):
            # Define a scope for reusing the variables

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with tf.variable_scope('ConvNet', reuse=reuse):

    # Convolution Layer with 32 filters and a kernel size of 5
    conv1 = tf.layers.conv2d(x, 32, 5, activation=tf.nn.relu)
    # Max Pooling (down-sampling) with strides of 2 and kernel size of 2
    conv1 = tf.layers.max_pooling2d(conv1, 2, 2)

    # Convolution Layer with 32 filters and a kernel size of 5
    conv2 = tf.layers.conv2d(conv1, 64, 3, activation=tf.nn.relu)
    # Max Pooling (down-sampling) with strides of 2 and kernel size of 2
    conv2 = tf.layers.max_pooling2d(conv2, 2, 2)

    # Convolution Layer with 32 filters and a kernel size of 5
    conv3 = tf.layers.conv2d(conv2, 64, 3, activation=tf.nn.relu)
    # Max Pooling (down-sampling) with strides of 2 and kernel size of 2
    conv3 = tf.layers.max_pooling2d(conv3, 2, 2)

    # Flatten the data to a 1-D vector for the fully connected layer
    fc1 = tf.contrib.layers.flatten(conv3)

    # Fully connected layer (in contrib folder for now)
    fc1 = tf.layers.dense(fc1, 1024)
    # Apply Dropout (if is_training is False, dropout is not applied)
    fc1 = tf.layers.dropout(fc1, rate=dropout, training=is_training)

    # Output layer, class prediction
    out = tf.layers.dense(fc1, n_classes)
    # Because 'softmax_cross_entropy_with_logits' already apply softmax,
    # we only apply softmax to testing network
    out = tf.nn.softmax(out) if not is_training else out

    return out

In [6]: # Create a graph for training
logits_train = conv_net(X, N_CLASSES, dropout, reuse=False, is_training=True)
# Create another graph for testing that reuse the same weights
logits_test = conv_net(X, N_CLASSES, dropout, reuse=True, is_training=False)

In [7]: # Define loss and optimizer (with train logits, for dropout to take effect)
loss_op = tf.reduce_mean(tf.nn.sparse_softmax_cross_entropy_with_logits(
    logits=logits_train, labels=Y))
optimizer = tf.train.AdamOptimizer(learning_rate=learning_rate)
train_op = optimizer.minimize(loss_op)

In [8]: # Evaluate model (with test logits, for dropout to be disabled)
correct_pred = tf.equal(tf.argmax(logits_test, 1), tf.cast(Y, tf.int64))
accuracy = tf.reduce_mean(tf.cast(correct_pred, tf.float32))

In [9]: # Initialize the variables (i.e. assign their default value)
init = tf.global_variables_initializer()

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In [10]: # Saver object
saver = tf.train.Saver()

In [11]: # Start training
with tf.Session() as sess:

    # Run the initializer
    sess.run(init)

    # Start the data queue
    tf.train.start_queue_runners()

    # Training cycle
    for step in range(1, num_steps+1):

        if step % display_step == 0:
            # Run optimization and calculate batch loss and accuracy
            _, loss, acc = sess.run([train_op, loss_op, accuracy])
            print('Step')
            print("Step " + str(step) + ", Minibatch Loss= " + \
                  "{:.4f}".format(loss) + ", Training Accuracy= " + \
                  "{:.3f}".format(acc))
        else:
            # Only run the optimization op (backprop)
            sess.run(train_op)

    print("Optimization Finished!")

    # Save your model
    saver.save(sess, 'my_tf_model')

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Step
Step 500, Minibatch Loss= 4.6192, Training Accuracy= 0.031
Step
Step 1000, Minibatch Loss= 4.6240, Training Accuracy= 0.031
Step
Step 1500, Minibatch Loss= 4.5927, Training Accuracy= 0.031
Step
Step 2000, Minibatch Loss= 4.5935, Training Accuracy= 0.000
Step
Step 2500, Minibatch Loss= 4.6218, Training Accuracy= 0.000
Step
Step 3000, Minibatch Loss= 4.6296, Training Accuracy= 0.000
Step
Step 3500, Minibatch Loss= 4.4787, Training Accuracy= 0.031
Step
Step 4000, Minibatch Loss= 4.3978, Training Accuracy= 0.000
Step

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Step 4500, Minibatch Loss= 4.3245, Training Accuracy= 0.062

Step

Step 5000, Minibatch Loss= 3.8302, Training Accuracy= 0.188

Optimization Finished!

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Traceback (most recent call last):

File "c:\users\tom13\appdata\local\conda\conda\envs\tensorflow-gpu\lib\threading.py", line 914

self.run()

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