

Food101

January 21, 2018

```
In [1]: from __future__ import print_function
```

```
import tensorflow as tf
import os
```

```
In [2]: # Dataset Parameters - CHANGE HERE
```

```
MODE = 'folder' # or 'file', if you choose a plain text file (see above).
```

```
DATASET_PATH = 'C:/Users/tom13/jupyter/FYP/food-101/train' # the dataset file or root folder
```

```
# Image Parameters
```

```
N_CLASSES = 101 # CHANGE HERE, total number of classes
```

```
IMG_HEIGHT = 128 # CHANGE HERE, the image height to be resized to
```

```
IMG_WIDTH = 128 # CHANGE HERE, the image width to be resized to
```

```
CHANNELS = 3 # The 3 color channels, change to 1 if grayscale
```

```
In [3]: # Reading the dataset
```

```
# 2 modes: 'file' or 'folder'
```

```
def read_images(dataset_path, mode, batch_size):
```

```
    imagepaths, labels = list(), list()
```

```
    if mode == 'file':
```

```
        # Read dataset file
```

```
        data = open(dataset_path, 'r').read().splitlines()
```

```
        for d in data:
```

```
            imagepaths.append(d.split(' ')[0])
```

```
            labels.append(int(d.split(' ')[1]))
```

```
    elif mode == 'folder':
```

```
        # An ID will be affected to each sub-folders by alphabetical order
```

```
        label = 0
```

```
        # List the directory
```

```
        try: # Python 2
```

```
            classes = sorted(os.walk(dataset_path).next()[1])
```

```
        except Exception: # Python 3
```

```
            classes = sorted(os.walk(dataset_path).__next__()[1])
```

```
        # List each sub-directory (the classes)
```

```
        for c in classes:
```

```
            c_dir = os.path.join(dataset_path, c)
```

```
            try: # Python 2
```

```
                walk = os.walk(c_dir).next()
```

```

except Exception: # Python 3
    walk = os.walk(c_dir).__next__()
    # Add each image to the training set
    for sample in walk[2]:
        # Only keeps jpeg images
        if sample.endswith('.jpg') or sample.endswith('.jpeg'):
            imagepaths.append(os.path.join(c_dir, sample))
            labels.append(label)
        label += 1
    else:
        raise Exception("Unknown mode.")

# Convert to Tensor
imagepaths = tf.convert_to_tensor(imagepaths, dtype=tf.string)
labels = tf.convert_to_tensor(labels, dtype=tf.int32)
# Build a TF Queue, shuffle data
image, label = tf.train.slice_input_producer([imagepaths, labels],
                                             shuffle=True)

# Read images from disk
image = tf.read_file(image)
image = tf.image.decode_jpeg(image, channels=CHANNELS)

# Resize images to a common size
image = tf.image.resize_images(image, [IMG_HEIGHT, IMG_WIDTH])

# Normalize
image = image * 1.0/127.5 - 1.0

# Create batches
X, Y = tf.train.batch([image, label], batch_size=batch_size,
                      capacity=batch_size * 8,
                      num_threads=4)

return X, Y

```

```

In [4]: # Parameters
        learning_rate = 0.001
        num_steps = 5000
        batch_size = 32
        display_step = 500

        # Network Parameters
        dropout = 0.75 # Dropout, probability to keep units

        # Build the data input
        X, Y = read_images(DATASET_PATH, MODE, batch_size)

```

```

In [5]: # Create model

```

```

def conv_net(x, n_classes, dropout, reuse, is_training):
    # Define a scope for reusing the variables
    with tf.variable_scope('ConvNet', reuse=reuse):

        # Convolution Layer with 32 filters and a kernel size of 5
        conv1 = tf.layers.conv2d(x, 32, 5, activation=tf.nn.relu)
        # Max Pooling (down-sampling) with strides of 2 and kernel size of 2
        conv1 = tf.layers.max_pooling2d(conv1, 2, 2)

        # Convolution Layer with 32 filters and a kernel size of 5
        conv2 = tf.layers.conv2d(conv1, 64, 3, activation=tf.nn.relu)
        # Max Pooling (down-sampling) with strides of 2 and kernel size of 2
        conv2 = tf.layers.max_pooling2d(conv2, 2, 2)

        # Convolution Layer with 32 filters and a kernel size of 5
        conv3 = tf.layers.conv2d(conv2, 64, 3, activation=tf.nn.relu)
        # Max Pooling (down-sampling) with strides of 2 and kernel size of 2
        conv3 = tf.layers.max_pooling2d(conv3, 2, 2)

        # Flatten the data to a 1-D vector for the fully connected layer
        fc1 = tf.contrib.layers.flatten(conv3)

        # Fully connected layer (in contrib folder for now)
        fc1 = tf.layers.dense(fc1, 1024)
        # Apply Dropout (if is_training is False, dropout is not applied)
        fc1 = tf.layers.dropout(fc1, rate=dropout, training=is_training)

        # Output layer, class prediction
        out = tf.layers.dense(fc1, n_classes)
        # Because 'softmax_cross_entropy_with_logits' already apply softmax,
        # we only apply softmax to testing network
        out = tf.nn.softmax(out) if not is_training else out

    return out

```

```

In [6]: # Create a graph for training
        logits_train = conv_net(X, N_CLASSES, dropout, reuse=False, is_training=True)
        # Create another graph for testing that reuse the same weights
        logits_test = conv_net(X, N_CLASSES, dropout, reuse=True, is_training=False)

In [7]: # Define loss and optimizer (with train logits, for dropout to take effect)
        loss_op = tf.reduce_mean(tf.nn.sparse_softmax_cross_entropy_with_logits(
            logits=logits_train, labels=Y))
        optimizer = tf.train.AdamOptimizer(learning_rate=learning_rate)
        train_op = optimizer.minimize(loss_op)

In [8]: # Evaluate model (with test logits, for dropout to be disabled)
        correct_pred = tf.equal(tf.argmax(logits_test, 1), tf.cast(Y, tf.int64))
        accuracy = tf.reduce_mean(tf.cast(correct_pred, tf.float32))

```

```

In [9]: # Initialize the variables (i.e. assign their default value)
        init = tf.global_variables_initializer()

In [10]: # Saver object
        saver = tf.train.Saver()

In [11]: # Start training
        with tf.Session() as sess:

            # Run the initializer
            sess.run(init)

            # Start the data queue
            tf.train.start_queue_runners()

            # Training cycle
            for step in range(1, num_steps+1):

                if step % display_step == 0:
                    # Run optimization and calculate batch loss and accuracy
                    _, loss, acc = sess.run([train_op, loss_op, accuracy])
                    print('Step')
                    print("Step " + str(step) + ", Minibatch Loss= " + \
                          "{:.4f}".format(loss) + ", Training Accuracy= " + \
                          "{:.3f}".format(acc))
                else:
                    # Only run the optimization op (backprop)
                    sess.run(train_op)

            print("Optimization Finished!")

            # Save your model
            saver.save(sess, 'my_tf_model')

```

```

Step
Step 500, Minibatch Loss= 4.6192, Training Accuracy= 0.031
Step
Step 1000, Minibatch Loss= 4.6240, Training Accuracy= 0.031
Step
Step 1500, Minibatch Loss= 4.5927, Training Accuracy= 0.031
Step
Step 2000, Minibatch Loss= 4.5935, Training Accuracy= 0.000
Step
Step 2500, Minibatch Loss= 4.6218, Training Accuracy= 0.000
Step
Step 3000, Minibatch Loss= 4.6296, Training Accuracy= 0.000
Step
Step 3500, Minibatch Loss= 4.4787, Training Accuracy= 0.031

```

Step

Step 4000, Minibatch Loss= 4.3978, Training Accuracy= 0.000

Step

Step 4500, Minibatch Loss= 4.3245, Training Accuracy= 0.062

Step

Step 5000, Minibatch Loss= 3.8302, Training Accuracy= 0.188

Optimization Finished!

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Traceback (most recent call last):

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self.run()

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