

$$- \vec{L} = \vec{r} \times \vec{p} \Rightarrow \vec{L} = I \vec{\omega}$$

$$2) \vec{L} = \left(\frac{d}{2} M v + \frac{d}{2} M v \right) \hat{z} = M v d \hat{z}$$

$$3) K = \frac{M v^2}{2} + \frac{M v^2}{2} = M v^2$$

$$4) \vec{L}_i = \vec{L}_f \Rightarrow \vec{L}_f = M v d \hat{z}$$

$$5) 2M \frac{d}{4} \cdot v_f = M d v$$

$$v_f = 2v$$

$$6) K_f = \frac{M}{2} (2v)^2 + \frac{M}{2} (2v)^2 = 2M v^2 + 2M v^2 = 4M v^2$$

$$7) \Delta K = W \Rightarrow W = 4M v^2 - M v^2 = 3M v^2$$

$$8) a) L_i = L_f$$

$$L_i = m v_i \frac{d}{2} = L_f = I_B \omega + m \left(\frac{d}{2} \right)^2 \omega$$

$$I_B = \int_{-\frac{d}{2}}^{\frac{d}{2}} x^2 \lambda dx = \lambda \left. \frac{x^3}{3} \right|_{-\frac{d}{2}}^{\frac{d}{2}} = \frac{\lambda}{3} \left(\frac{d^3}{8} + \frac{d^3}{8} \right) = \frac{\lambda d^3}{12} = \frac{M d^2}{12}$$

$$\Rightarrow \frac{M d^2}{12} \omega + m \frac{d^2}{4} \omega = m v_i \frac{d}{2}$$

$$\frac{M d}{6} \omega + m \frac{d}{2} \omega = m v_i$$

$$\omega = \frac{2 m v_i}{d (m + M/3)} = \frac{2 v_i}{d} \left(1 + \frac{M}{3m} \right)^{-1}$$

$$c) K = \frac{I_B \omega^2}{2} + \frac{m d^2}{2} \omega^2 = \frac{1}{2} \left(\frac{M d^2}{12} + \frac{m d^2}{4} \right) \frac{4 m^2 v_i^2}{d^2 (m + M/3)^2}$$

$$= \frac{1}{2} \frac{m^2 v_i^2}{m + M/3} = \frac{m v_i^2}{2} \left(1 + \frac{M}{3m} \right)^{-1}$$

$$i- mgh = \frac{m v^2}{2}$$

$$v^2 = 2gh$$

$$v = \sqrt{2gh}$$

$$x) L = D p = m D \sqrt{2gh}$$

$$y) I_B = \int_0^D x^2 \lambda dx = \lambda \frac{x^3}{3} \Big|_0^D = \lambda \frac{D^3}{3} = \frac{M D^2}{3}$$

$$L_i = L_f$$

$$I_B \omega + m D^2 \omega = m D \sqrt{2gh}$$

$$\frac{M D^2}{3} \omega + m D^2 \omega = m D \sqrt{2gh}$$

$$\omega = \frac{m \sqrt{2gh}}{D (m + M/3)} = \frac{\sqrt{2gh}}{D} \left(1 + \frac{M}{3m} \right)^{-1}$$

$$z) mg \left[D - \frac{D}{2} \cos \theta - \frac{D}{2} \right] + mg \left[D - D \cos \theta \right] = (I_B + m D^2) \frac{\omega^2}{2}$$

$$mg \frac{D}{2} (1 - \cos \theta) + mg D (1 - \cos \theta) = \left(\frac{M}{3} D^2 + m D^2 \right) \frac{\omega^2}{2}$$

$$1 - \cos \theta = \left(\frac{M}{3} D + m D \right) \frac{\omega^2}{2g \left(\frac{M}{2} + m \right)} =$$

$$- \cos \theta = \frac{M/3 + m}{M/2 + m} \frac{D}{2g} \frac{m^2}{D^2(m + M/3)^2} 2gh$$

$$= \frac{m^2}{(M/2 + m)(M/3 + m)} \frac{h}{D} = \frac{h}{D} \left(1 + \frac{M}{2m}\right)^{-1} \left(1 + \frac{M}{3m}\right)^{-1}$$

1) Não. O pivô em torno do qual a barra gira exerce uma força externa.