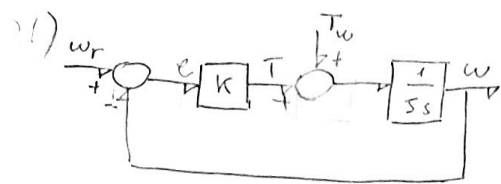


721 - Tarefa 03)



$$1) \quad U_{T_w=0} = \frac{1}{s} K (U_R - U) \rightarrow \frac{U}{U_R} = \frac{K}{s + K}$$

$$U_{U_R=0} = \frac{1}{s} (T_w - K U) \rightarrow \frac{U}{T_w} = \frac{1}{s + K}$$

$$\hookrightarrow U(s) = U_R(s) \frac{K}{s + K} + T_w \frac{1}{s + K}$$

$$\rightarrow \text{pólo} = \left\{ -\frac{K}{s} \right\}$$

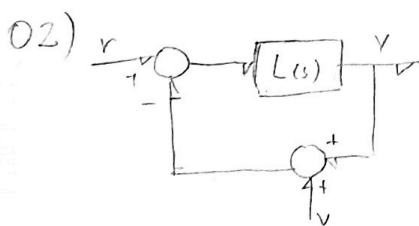
\hookrightarrow para todo $K > 0$, o sistema é estável.

$$b) \quad E = -\frac{1}{s} (T_w + EK) \rightarrow \frac{E(s)}{T_w(s)} = \frac{-1}{s + K}$$

$$c) \quad T_w(s) = W_0 \frac{\omega_0}{s^2 + \omega_0^2}$$

$$\hookrightarrow E(s) = W_0 \frac{-\omega_0}{(s^2 + \omega_0^2)(s + K)}$$

$$\hookrightarrow \lim_{t \rightarrow \infty} e(t) = \lim_{s \rightarrow 0} s E(s) = W_0 \frac{-\omega_0 s}{(s^2 + \omega_0^2)(s + K)} = W_0 \frac{0}{K \omega_0^2} = 0$$



$$a) \quad Y = -L(V + Y) \rightarrow \frac{Y(s)}{V(s)} = \frac{-L(s)}{1 + L(s)}$$

$$b) \quad T_{vr} = \frac{1}{s} \frac{Y(s)}{V(s)} = \frac{1}{s} \frac{-L(s)}{1 + L(s)}$$

$$\hookrightarrow \lim_{s \rightarrow 0} s \frac{Y(s)}{V(s)} = \left| \frac{-L(s)}{1 + L(s)} \right| \rightarrow \text{se } L(0) = 0 \text{ então o distúrbio não afetará o valor final}$$

$$c) \quad E = R - EL \rightarrow \frac{E(s)}{R(s)} = \frac{1}{1 + L(s)}$$

$$\hookrightarrow \lim_{s \rightarrow 0} s \frac{E(s)}{R(s)} = \frac{1}{1 + L(0)} \rightarrow \text{não, pois é preciso que } L(0) \rightarrow \infty \text{ para isso.}$$