CS 425 Homework 1

Mukai Yu

February 8, 2022

1. (a) In worst case, In worst case, assuming process a crashes immediately after it sends out the last heartbeat (died right after SOS):

$$e_{a\to b} = \max\{a \to b\} + \Delta_{a\to b} = 2\max\{a \to b\} - \min\{a \to b\}$$

$$T_b = T + e_{a\to b} = 50 + 10 = 60(s)$$

$$T_c = T + e_{a\to c} = 50 + 26 = 76(s)$$

$$T_d = T + e_{a\to d} = 50 + 19 = 69(s)$$

(b) Need to check all the path from **a** to other processes

$$\begin{split} T_b' = & T + \min_{path} \{e_{a \to b}, \\ & e_{a \to c} + \max\{d \to b\}, \\ & e_{a \to d} + \max\{d \to b\}, \\ & e_{a \to c} + \max\{c \to d\} + \max\{d \to b\}, \\ & e_{a \to d} + \max\{d \to c\} + \max\{c \to b\}\} \\ & = & 50 + \min\{10, 26 + 18, 19 + 13, 26 + 4 + 13, 19 + 4 + 18\} \\ & = & 50 + 10 \\ & = & 60(s) \end{split}$$

$$T_c' = & T + \min_{path} \{e_{a \to c}, \\ & e_{a \to b} + \max\{c \to c\}, \\ & e_{a \to d} + \max\{d \to c\}, \\ & e_{a \to d} + \max\{d \to c\}, \\ & e_{a \to d} + \max\{d \to b\} + \max\{d \to c\}, \\ & e_{a \to d} + \max\{d \to b\} + \max\{b \to c\}\} \\ & = & 50 + \min\{26, 10 + 18, 19 + 4, 10 + 13 + 4, 19 + 13 + 18\} \\ & = & 50 + 23 \\ & = & 73(s) \end{split}$$

$$\begin{split} T_d' = & T + \min_{path} \{e_{a \to d}, \\ & e_{a \to b} + \max\{b \to d\}, \\ & e_{a \to c} + \max\{c \to d\}, \\ & e_{a \to b} + \max\{b \to c\} + \max\{c \to d\}, \\ & e_{a \to c} + \max\{c \to b\} + \max\{b \to d\}\} \\ & = & 50 + \min\{19, 10 + 13, 26 + 4, 10 + 18 + 4, 26 + 18 + 13\} \\ & = & 50 + 19 \\ & = & 69(s) \end{split}$$

- (c) Protocol: each process sends heartbeat to 2 other nearest processes, where nearest process means a process that has the least worst case failure detection time of the current process.
- (d) the minimal set of processes **a** must send heartbeats to $= \{b, d\}$

2. (a) i. The client should choose S_2 to achieve the lowest accuracy at:

$$skew(client, S_2) \leqslant \frac{RTT(S_2)}{2} + \min < \frac{RTT(S_2)}{2} = 12(ms)$$

- ii. The longest time-period = $\frac{(90-12)\times10^{-3}}{3\times10^{-6}}$ = 26,000(s)
- (b) i. The lowest synchronization bound is:

$$\frac{(39-12)+(52-71)}{2}=4$$

The corresponding estimated offset value of ${\bf B}$ relative to ${\bf A}$ is:

$$\frac{(39-12)-(52-71)}{2}=23$$

So the estimated offset value of A relative to B is -23

ii. The tightest synchronization bound is:

$$\frac{75 - 60}{2} = 7.5$$

3. (a)

(b)

b)		
)	Α	$1\ 0\ 0\ 0$
	В	$2\ 0\ 1\ 0$
	С	3 3 1 3
	D	$4\ 3\ 1\ 3$
	E	0110
	F	$1\ 2\ 1\ 3$
	G	1 3 1 3
	Н	$1\ 4\ 1\ 3$
	I	0010
	J	$1\ 0\ 2\ 0$
	K	1033
	L	$1\ 3\ 4\ 3$
	M	0011
	N	$1\ 0\ 1\ 2$
	О	1013
	Р	1 3 1 4

- (c) i. A $|| e \in \{E, I, M\}$
 - ii. F || $e \in \{B, J, K\}$
 - iii. K $||~e \in \{B,C,D,E,F,G,H,P\}$
 - iv. N || $e \in \{B, E, J\}$

4. (a) $E || e \in \{A, B, J, K, M, N, O\}$

So removing the events happened too early (events that happened before the last event right before real time 8, we have the following possible frontier events combination of cuts:

$$\{A, E, J, O\}$$

$$\{A, E, K, O\}$$

$$\{B, E, J, O\}$$

$$\{B, E, K, O\}$$

(b)

Frontier Cuts	Incoming channel of P_1	Incomming Channel of P_3
A, E, J, O	IB, OD	OK
A, E, K, O	IB, OD	
B, E, J, O	OD	OK
B, E, K, O	OD	