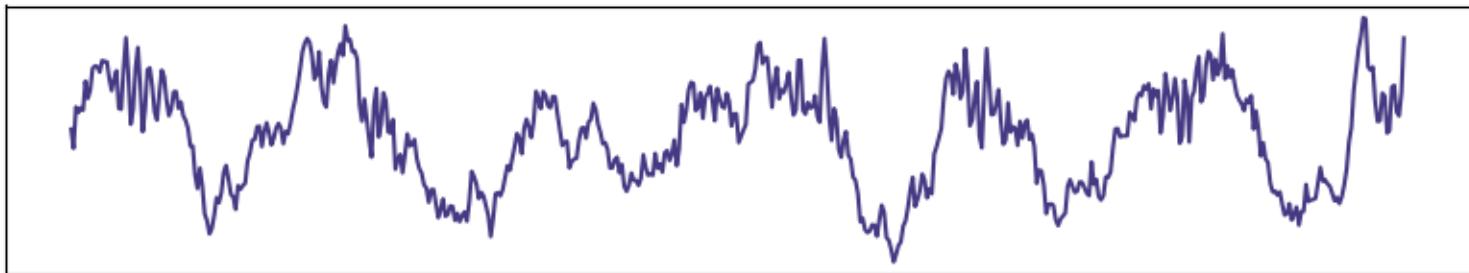


# NON-LINEAR MODELS FOR NEUROPHYSIOLOGICAL TIME SERIES

Tom Dupré la Tour

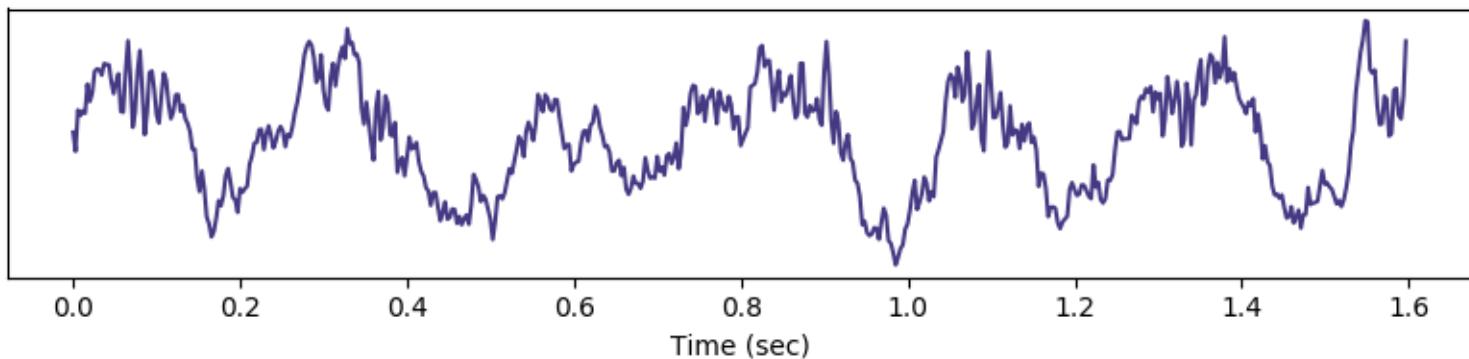
PhD Defense – 26 Nov 2018



# NON-LINEAR MODELS FOR NEUROPHYSIOLOGICAL TIME SERIES

Tom Dupré la Tour

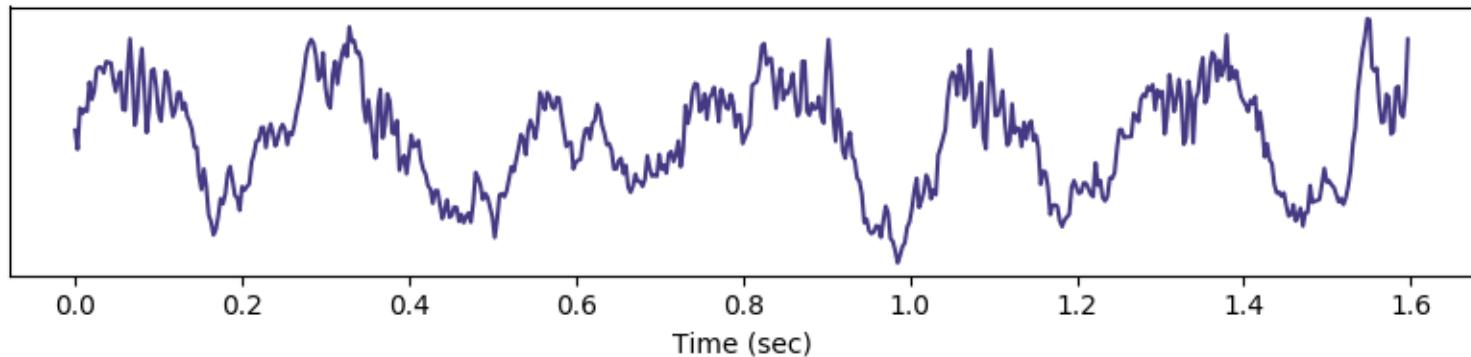
PhD Defense – 26 Nov 2018



# Neurophysiological time series

Local field potential (LFP)

Example: LFP in rodent striatum

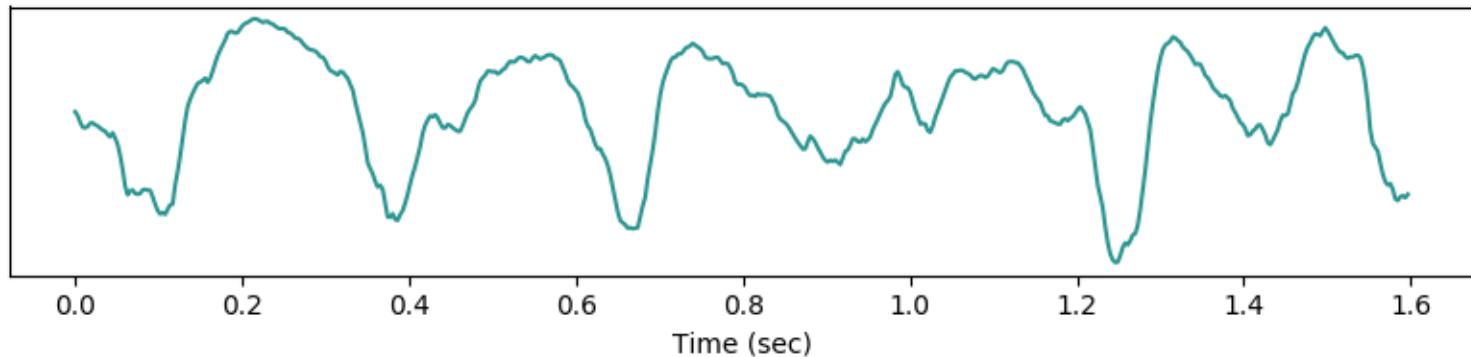


# Neurophysiological time series

Local field potential (LFP)

Electro-corticogram (ECoG)

Example: ECoG in human auditory cortex



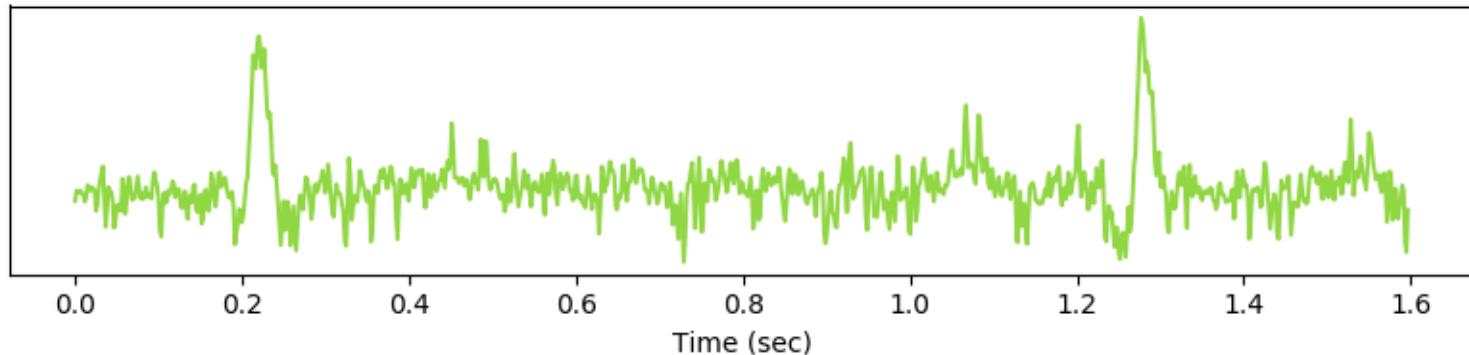
# Neurophysiological time series

Local field potential (LFP)

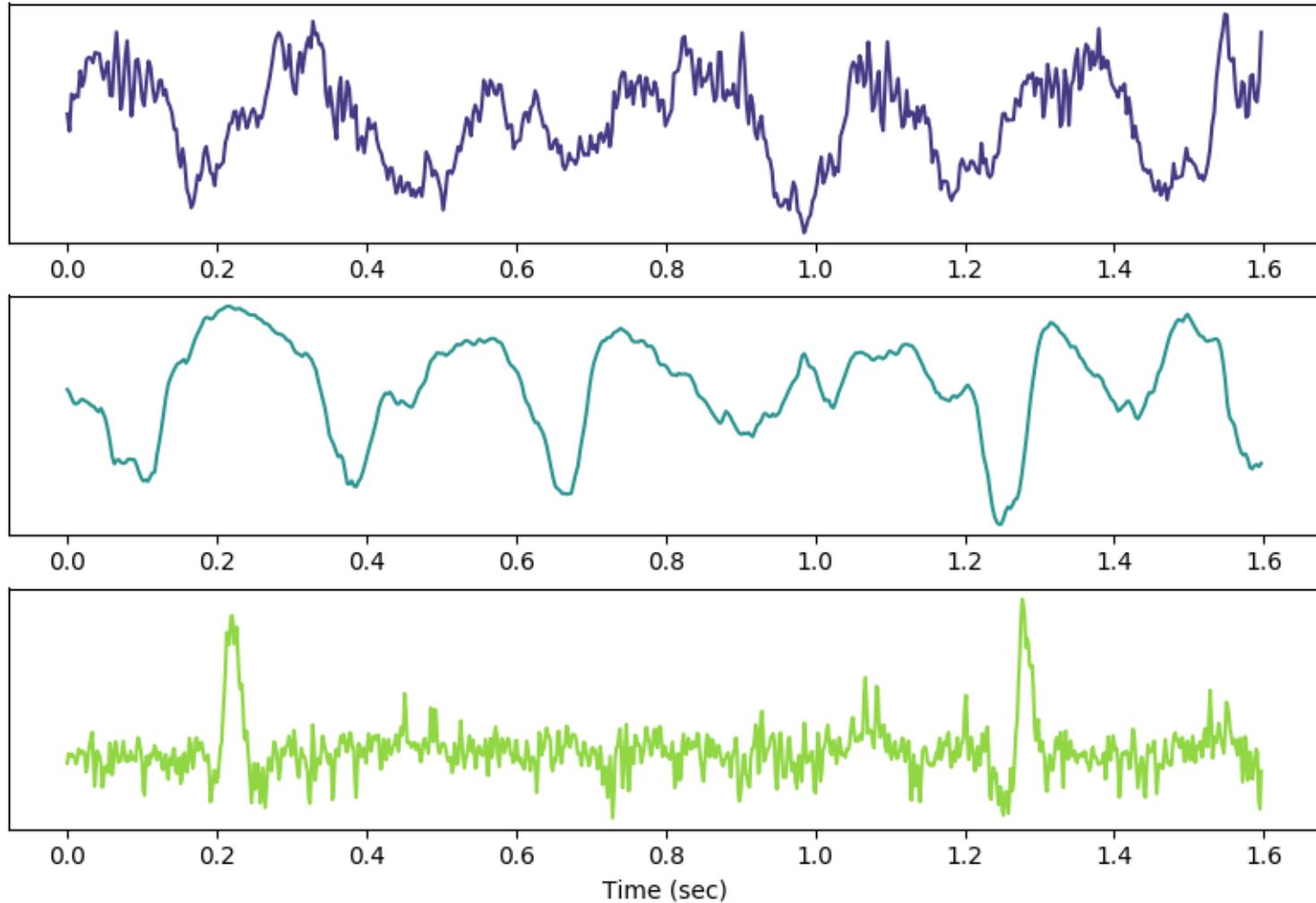
Electro-corticogram (ECoG)

Electro/Magneto-encephalogram (EEG/MEG)

Example: MEG in human

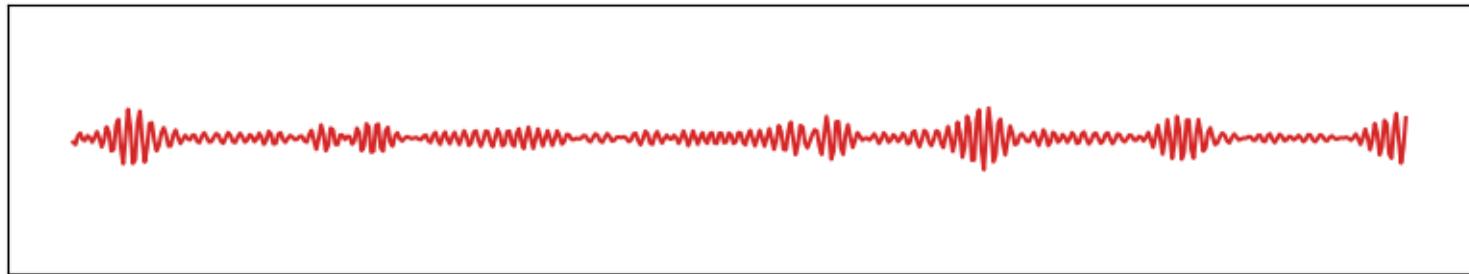
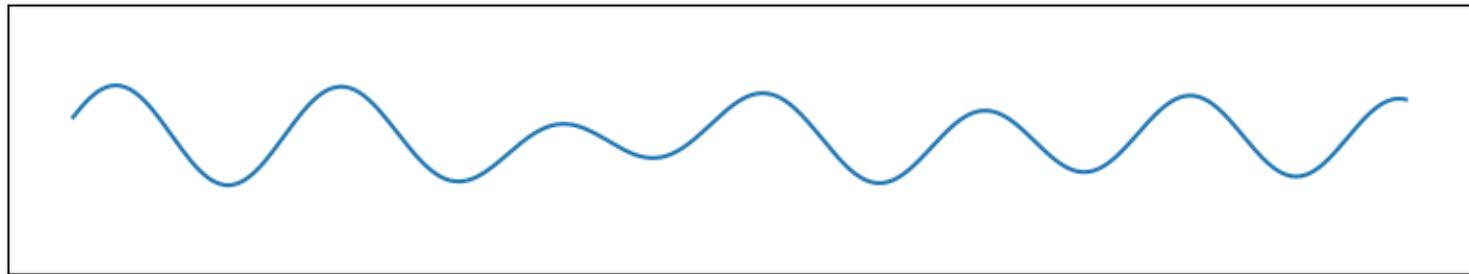
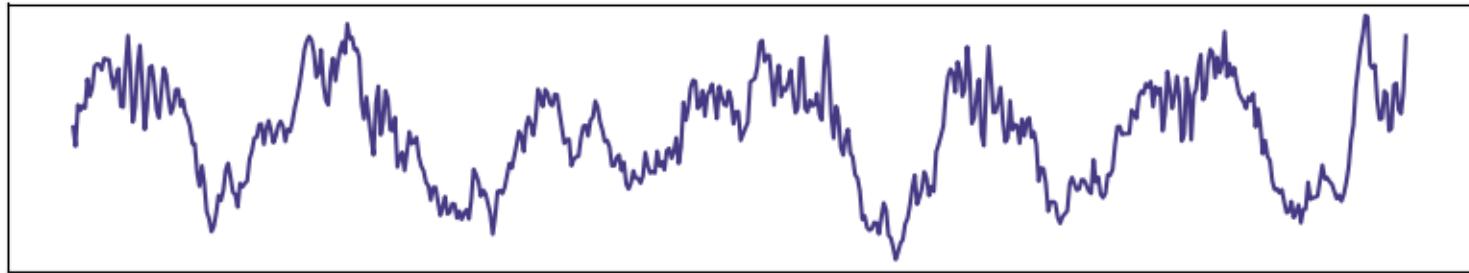


# Neurophysiological time series



# Narrow-band representation

LFP



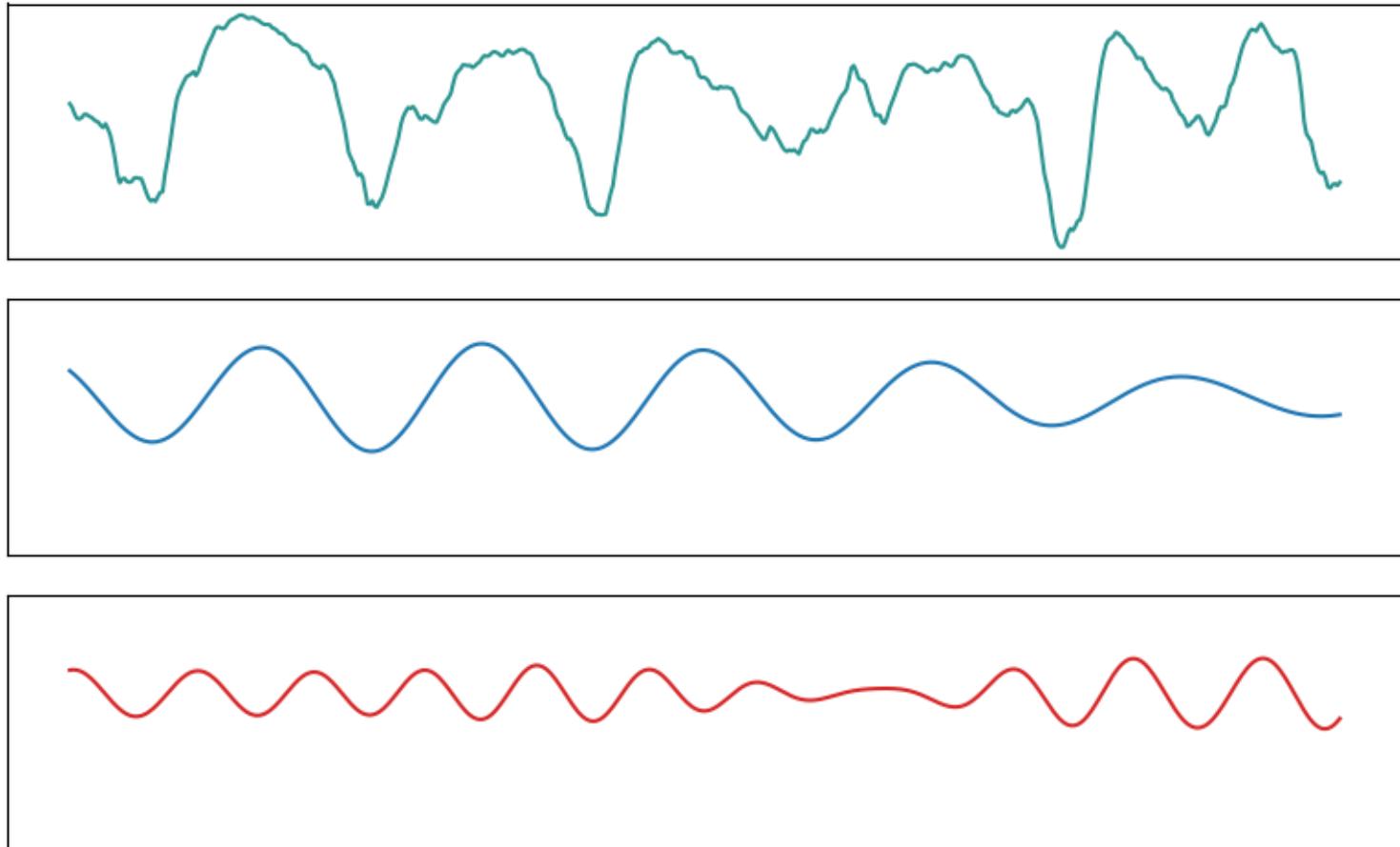
# Fourier fallacy

«Even though it may be possible to analyze the complex forms of brain waves into **a number of different sine-wave** frequencies, this may lead only to what might be termed a “**Fourier fallacy**”, if one assumes ***ad hoc*** that all of the necessary frequencies actually occur as periodic phenomena in **cell groups** within the brain. »

Jasper, 1948

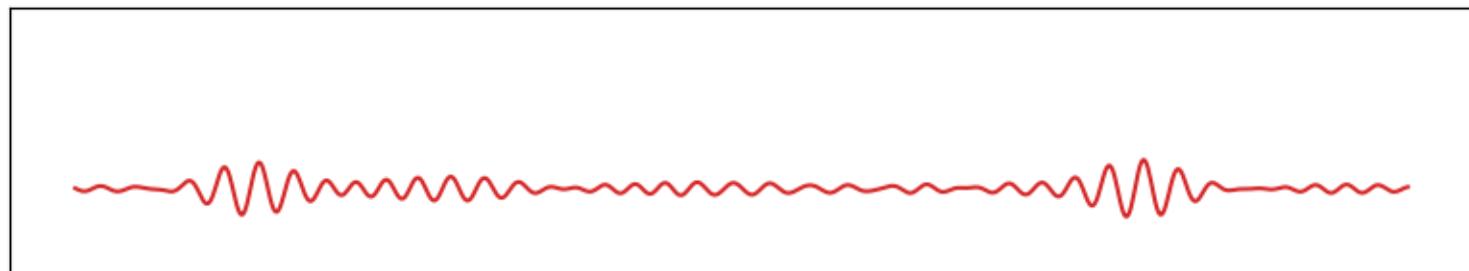
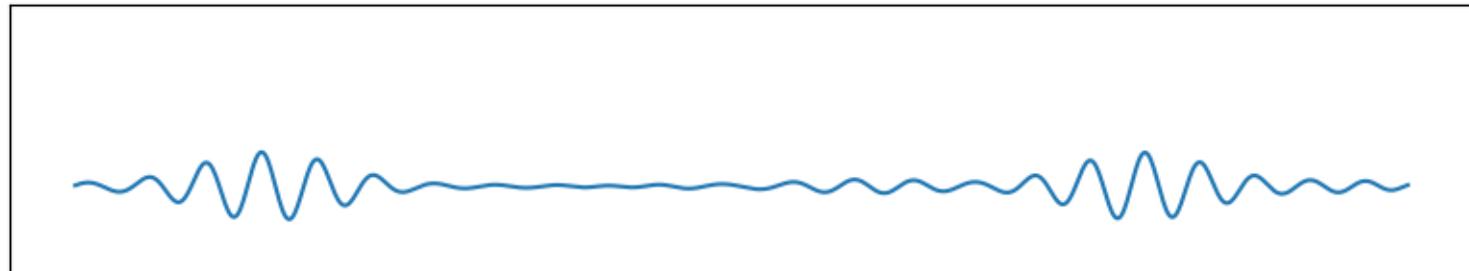
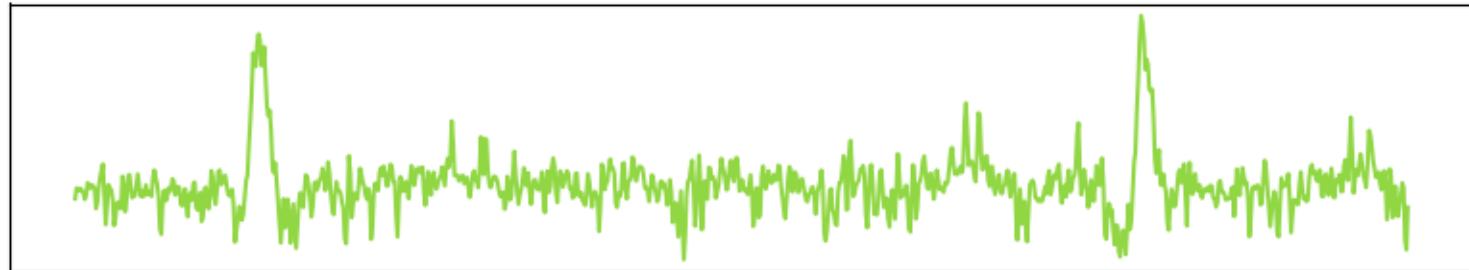
# Narrow-band representation

ECoG



# Narrow-band representation

MEG



# Need to go beyond Fourier

- Fourier fallacy

(Jasper, 1948)

- Narrow-band linear filtering is too reductive

(Mazaheri and Jensen, 2008)

- Wide-band waveforms as key features

(Jones, 2016, Cole and Voytek, 2017)

In this work, we developed non-linear signal models, to go beyond narrow-band linear filtering.

# Outline

1. Cross-frequency coupling analysis  
*with driven autoregressive models*

2. Temporal waveform analysis  
*with convolutional sparse coding models*

# Part 1

## 1. Cross-frequency coupling analysis with driven autoregressive models

Non-linear autoregressive models for cross-frequency coupling in neural time series

T. Dupré la Tour, L. Tallot, L. Grabot, V. Doyère, V. van Wassenhove, Y. Grenier, A. Gramfort, *PLOS Computational Biology* 2017

Parametric estimation of spectrum driven by an exogenous signal

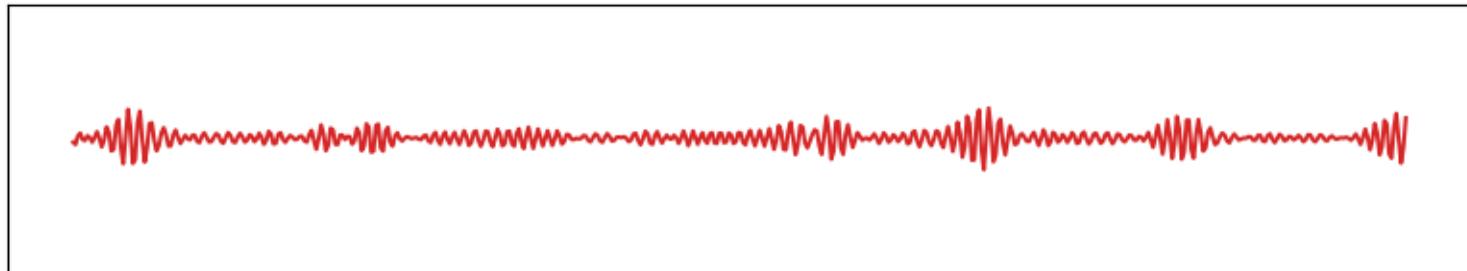
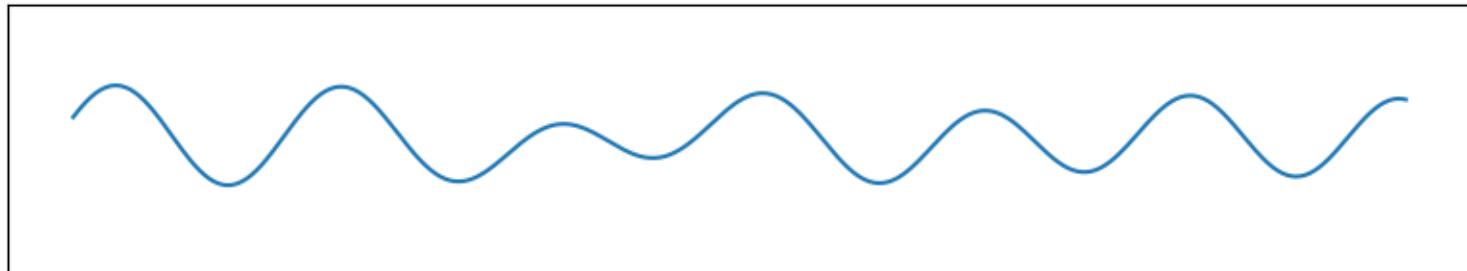
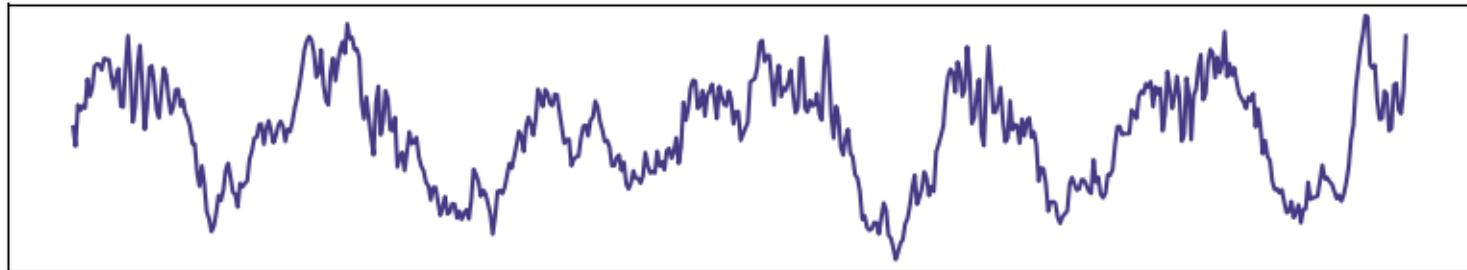
T. Dupré la Tour, Y. Grenier, A. Gramfort, *ICASSP* 2017

Driver estimation in non-linear autoregressive models

T. Dupré la Tour, Y. Grenier, A. Gramfort, *ICASSP* 2018

# Cross-frequency coupling

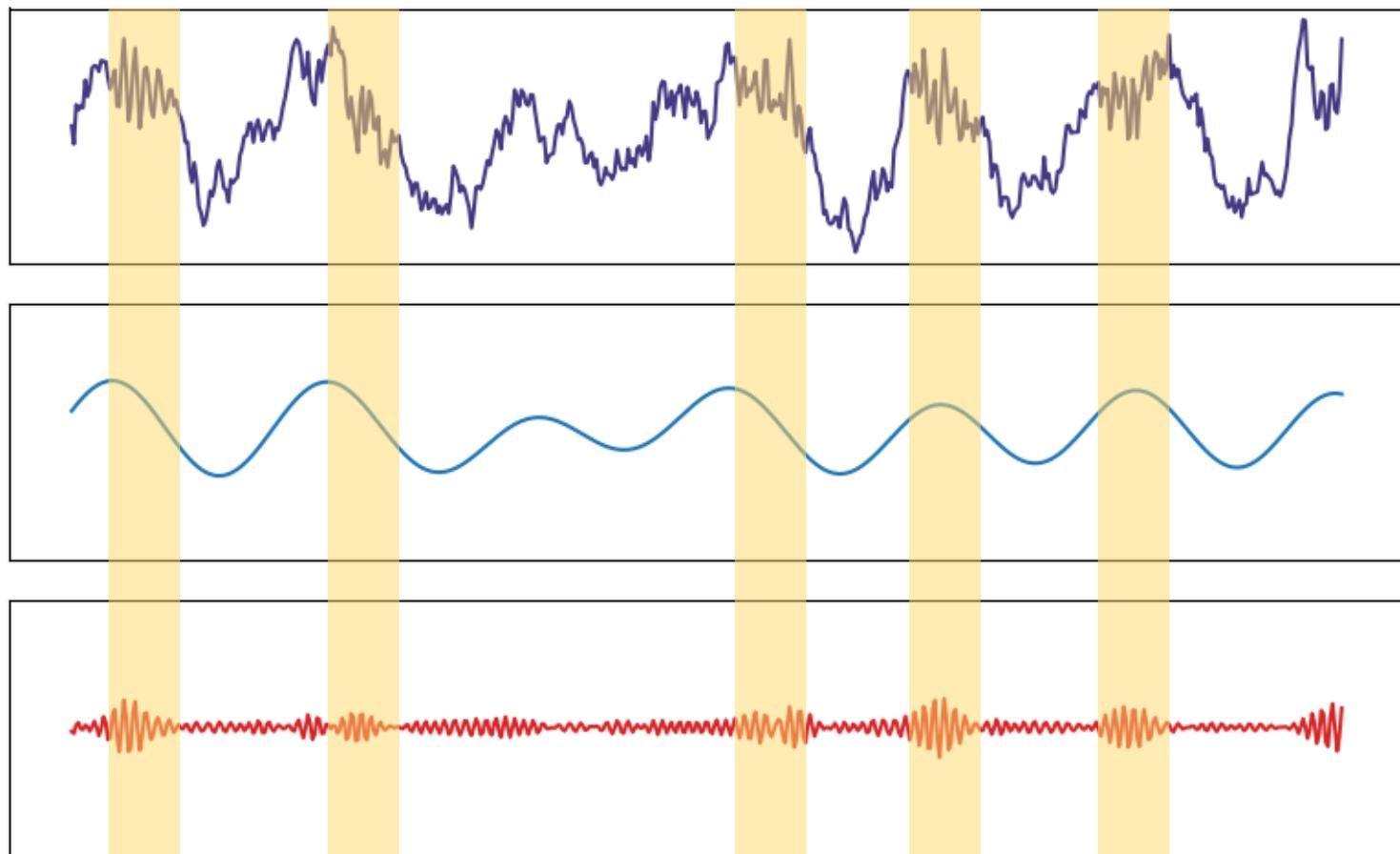
LFP



# Cross-frequency coupling

Low-frequency phase and high-frequency amplitude

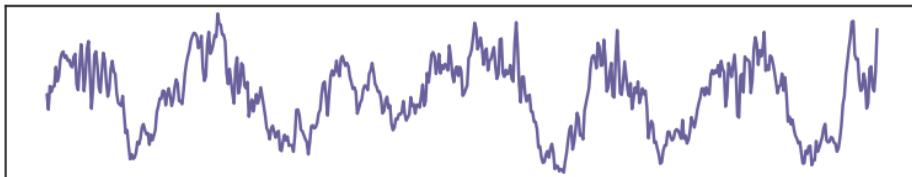
(Bragin et al 1995, Canolty et al, 2006)



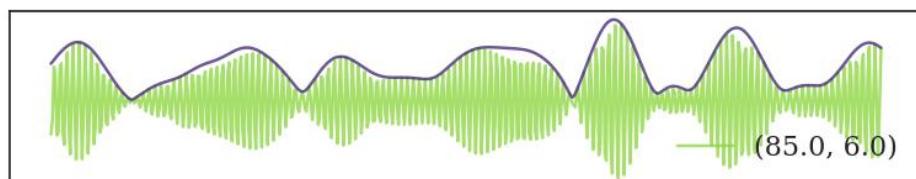
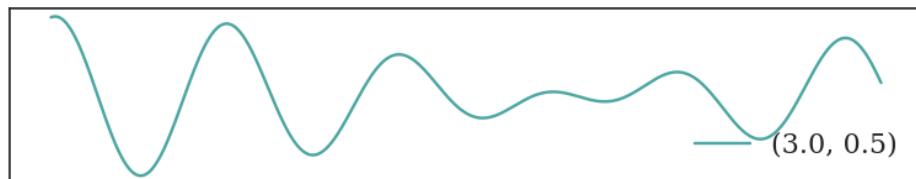
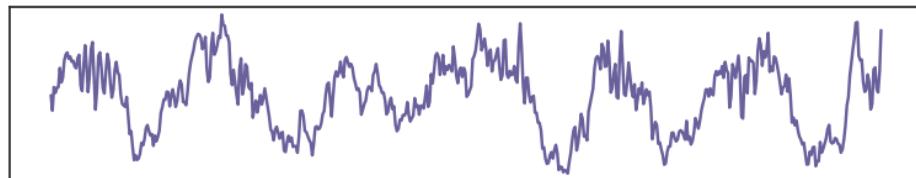
# What is the role of CFC?

- Multi-item/sequence representation  
(Penttonen et al, 1998, Gupta et al, 2012)
- Long-term and working memory  
(Lisman and Idiart, 1995, Jensen, 2006, Tort et al, 2009)
- Long distance synchronization  
(Canolty et al, 2006, Bonnefond et al, 2017)
- A canonical neural syntax  
(Buzsaki, 2010, Lisman and Jensen 2013, Hyafil et al, 2015)

# Common approach to measure CFC...



# Common approach to measure CFC...

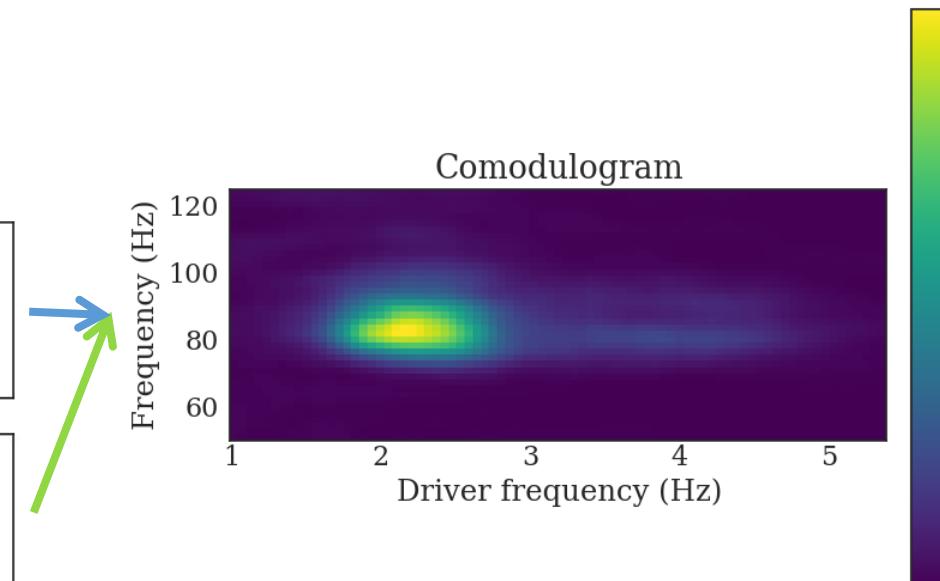
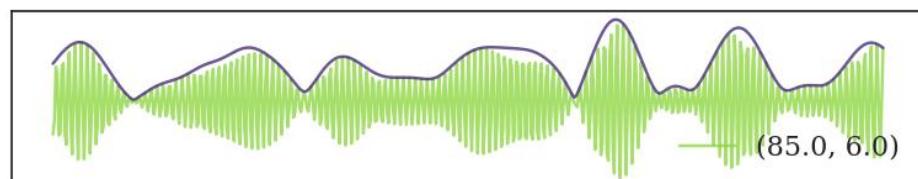
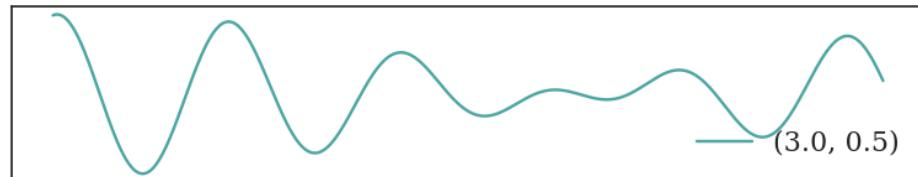
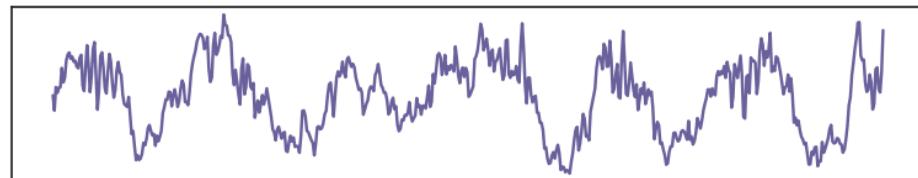


Correlation bewteen:

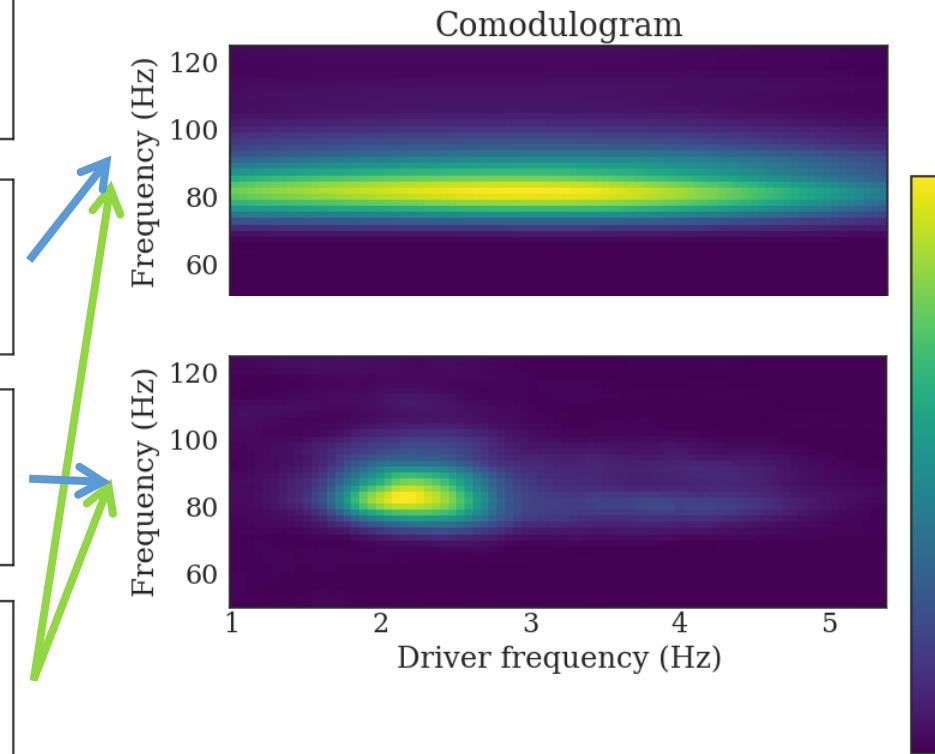
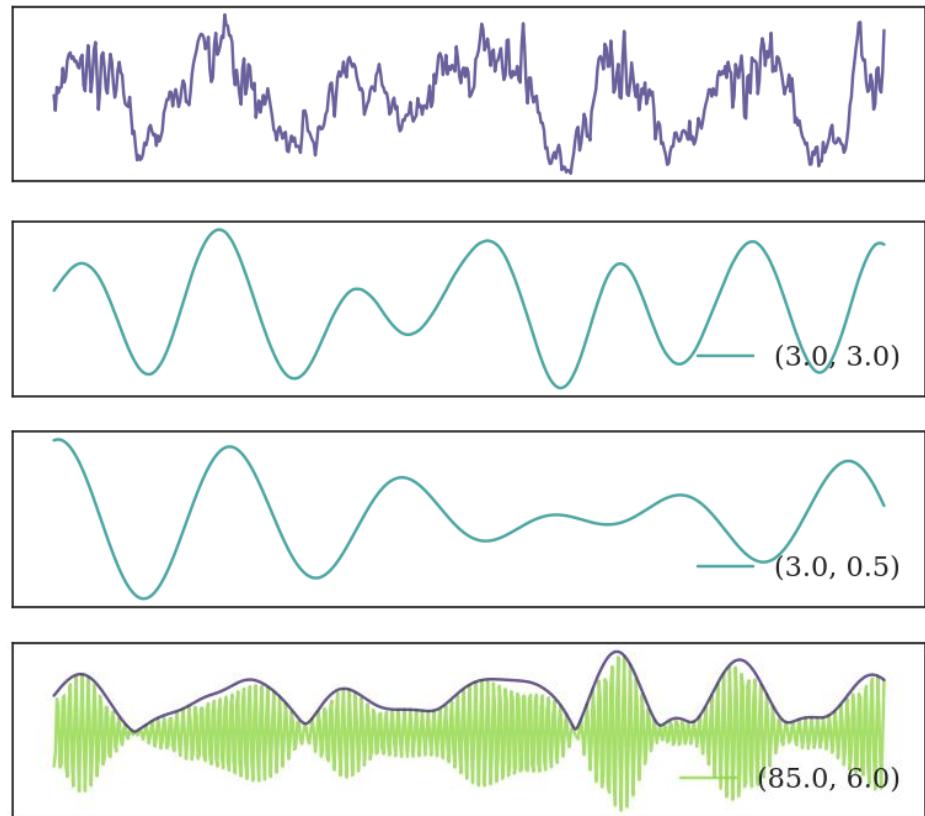
→ the low-frequency signal

→ the high-frequency envelope

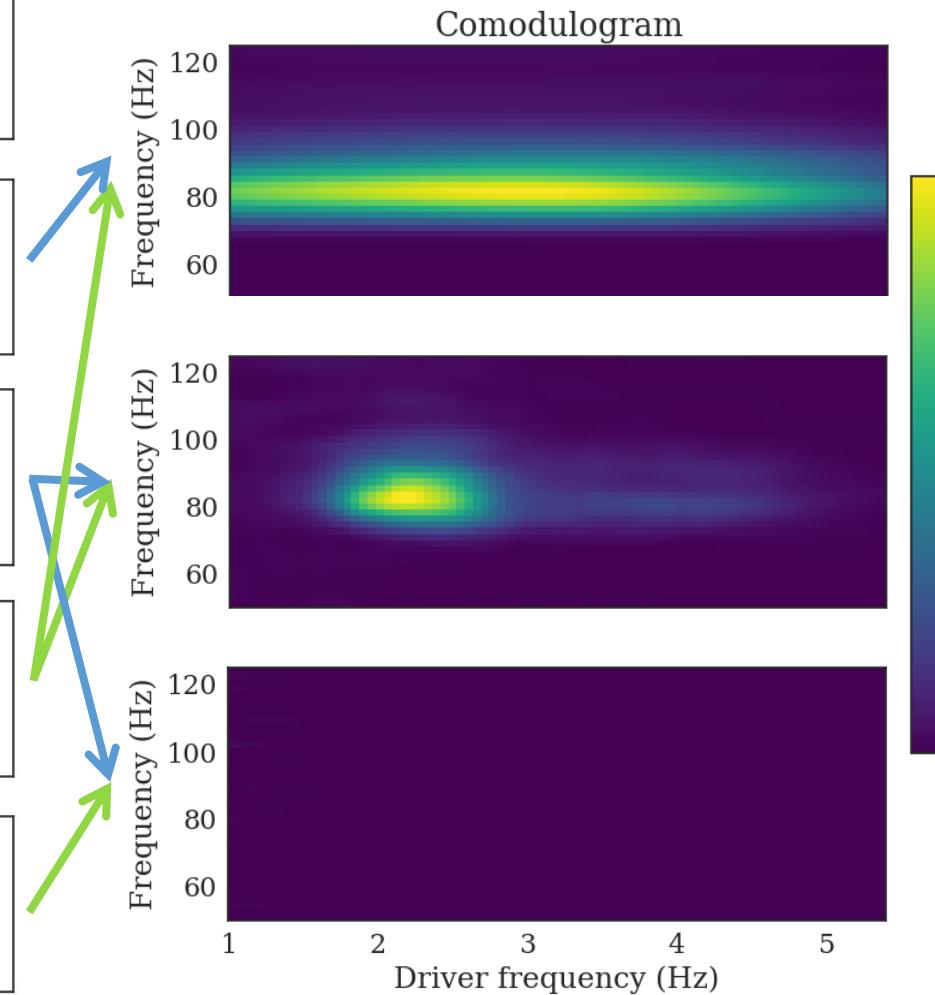
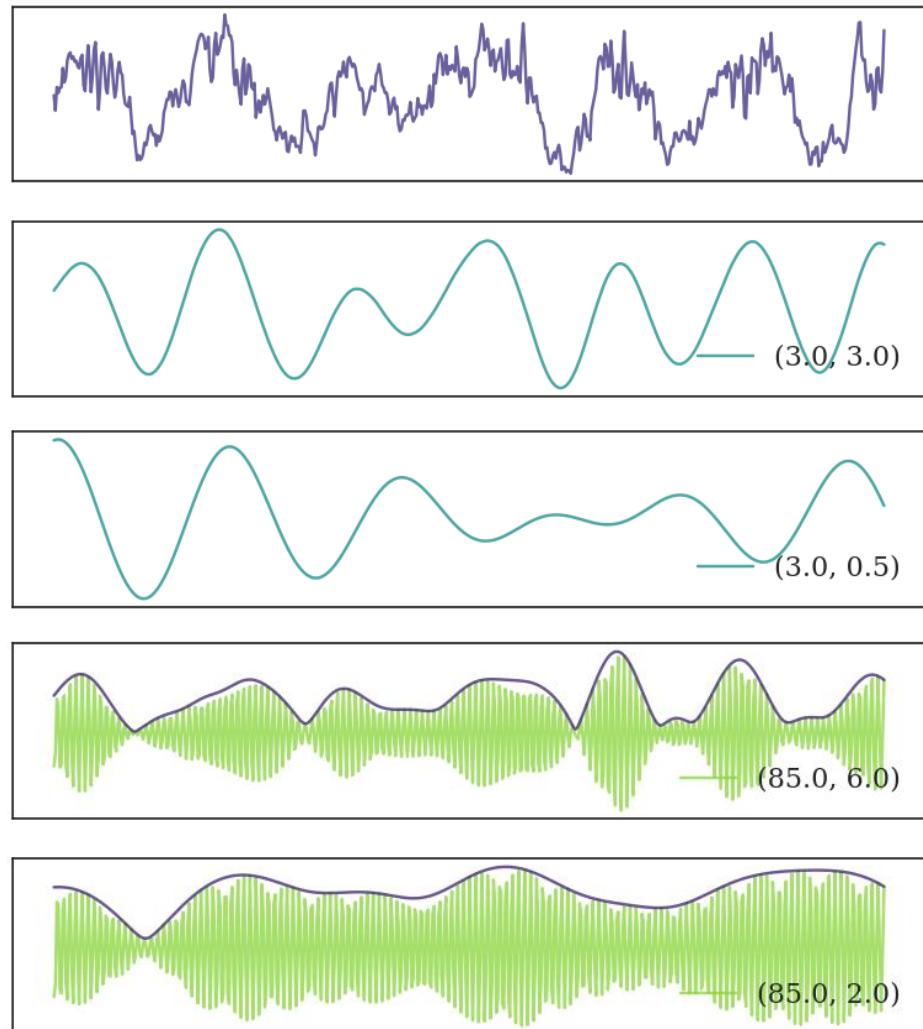
# Common approach to measure CFC...



# ... but choosing filtering parameters is hard



# ... but choosing filtering parameters is hard



# Autoregressive model

Autoregressive (AR) model

(Makhoul 1975)

$$y(t) + \sum_{i=1}^p a_i y(t-i) = \varepsilon(t) \quad \varepsilon(t) \sim \mathcal{N}(0, \sigma^2)$$

# Spectral estimation

Autoregressive (AR) model

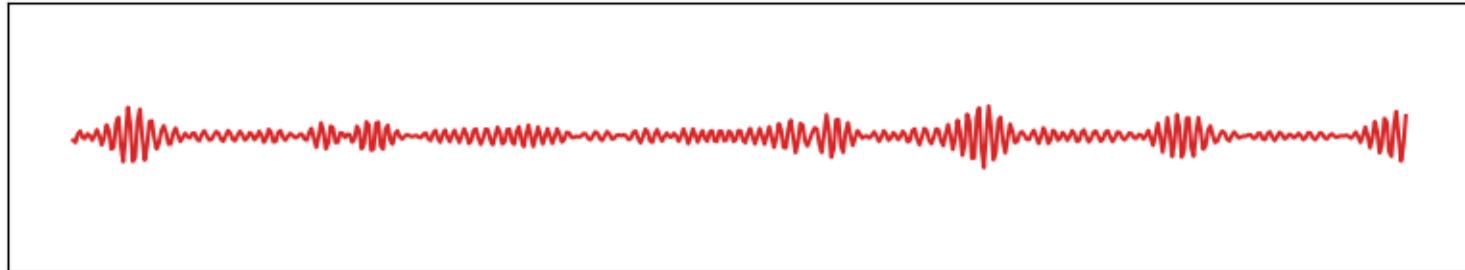
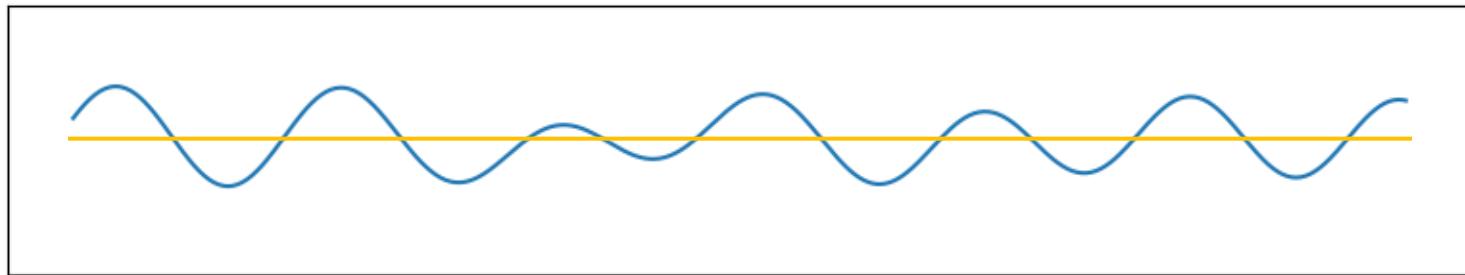
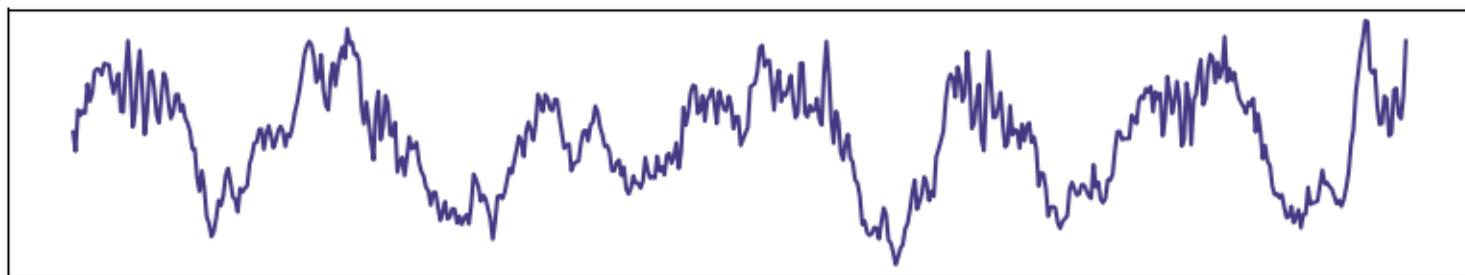
(Makhoul 1975)

$$y(t) + \sum_{i=1}^p a_i y(t-i) = \varepsilon(t) \quad \varepsilon(t) \sim \mathcal{N}(0, \sigma^2)$$

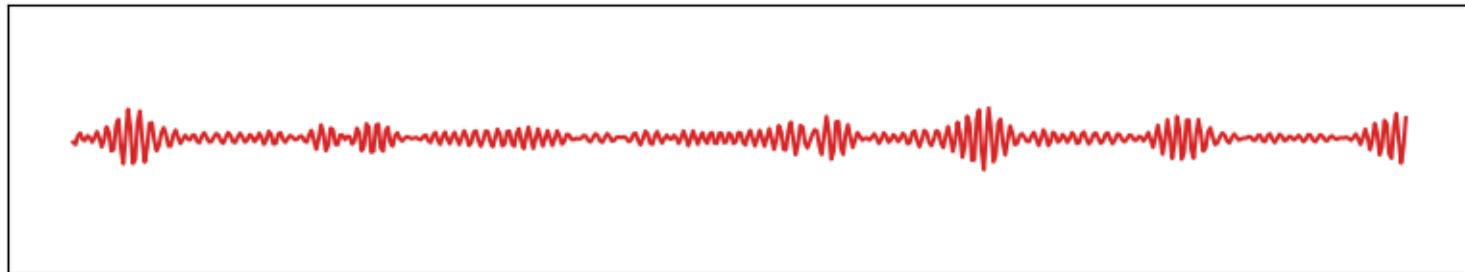
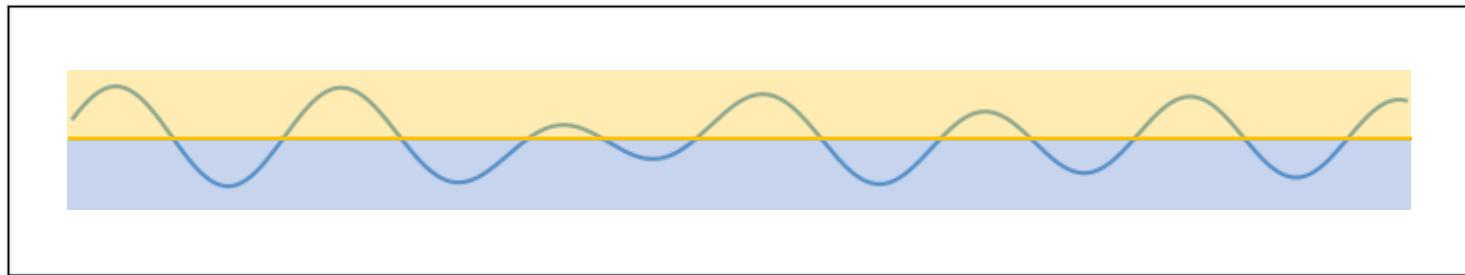
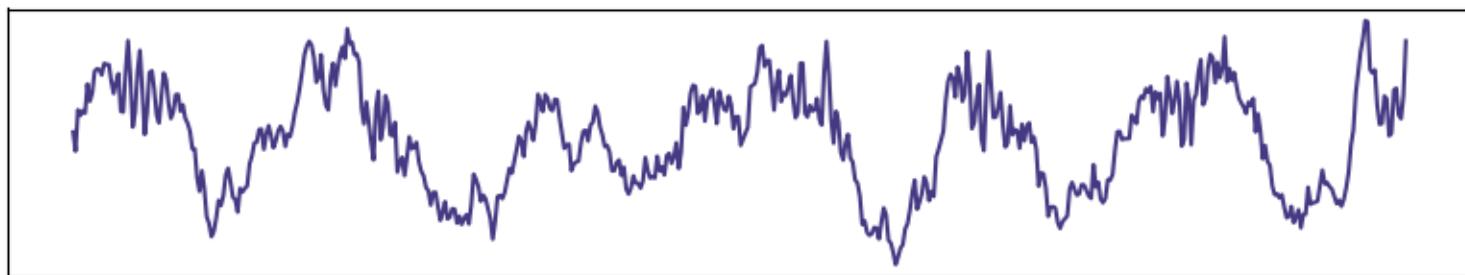
Power spectral density (PSD)

$$\text{PSD}_y(f) = \sigma^2 \left| \sum_{i=0}^p a_i e^{-j2\pi f i} \right|^{-2}$$

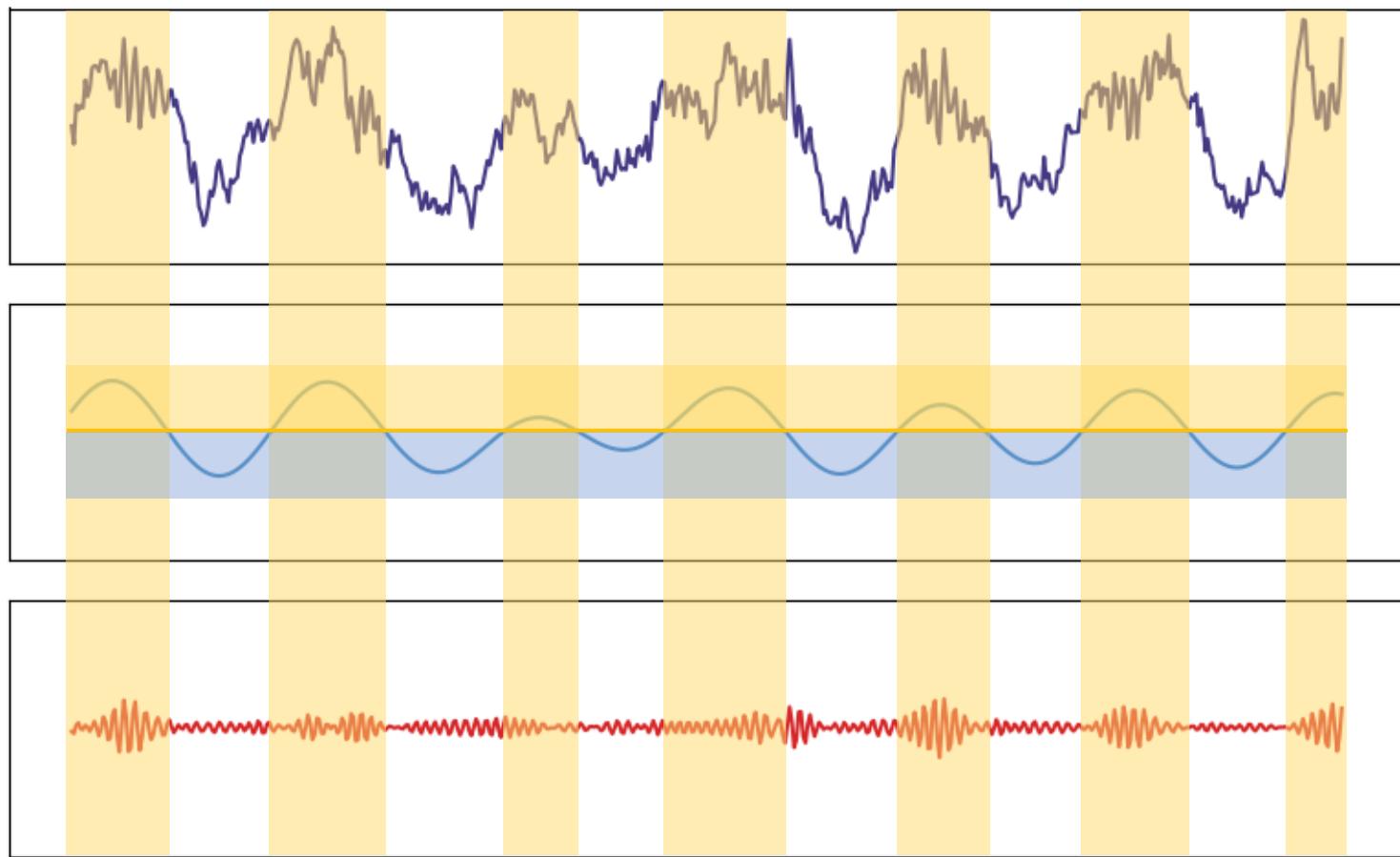
# Cross-frequency coupling



# Cross-frequency coupling

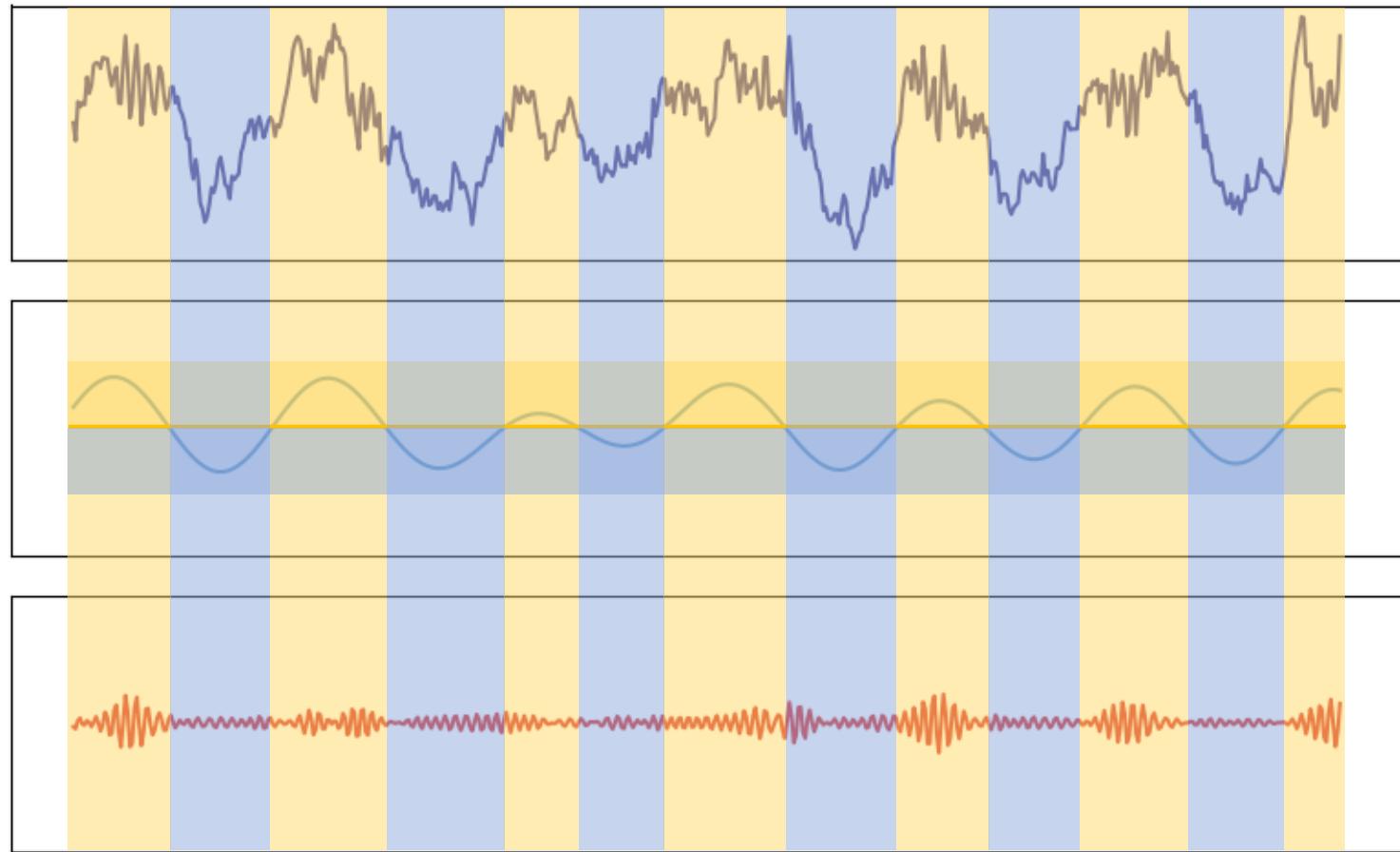


# Cross-frequency coupling



# Cross-frequency coupling

(Tong and Lim, 1980, Chan and Tong, 1986, Dijk et al, 2002)



# Driven autoregressive (DAR) model

Autoregressive (AR) model

(Makhoul, 1975)

$$y(t) + \sum_{i=1}^p a_i y(t-i) = \varepsilon(t) \quad \varepsilon(t) \sim \mathcal{N}(0, \sigma^2)$$

Driven AR (DAR) model

(Grenier, 1983, 2013)

$$a_i(t) = \sum_{j=0}^m a_{ij} x(t)^j \quad \log(\sigma(t)) = \sum_{j=0}^m b_j x(t)^j$$

# Driven autoregressive (DAR) model

Autoregressive (AR) model

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$$y(t) + \sum_{i=1}^p a_i y(t-i) = \varepsilon(t) \quad \varepsilon(t) \sim \mathcal{N}(0, \sigma^2)$$

Driven AR (DAR) model

(Grenier, 1983, 2013)

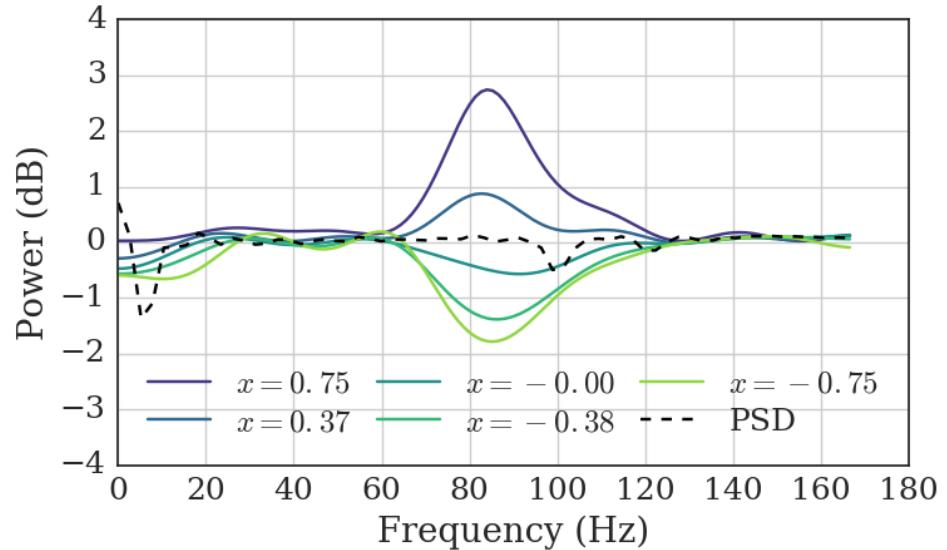
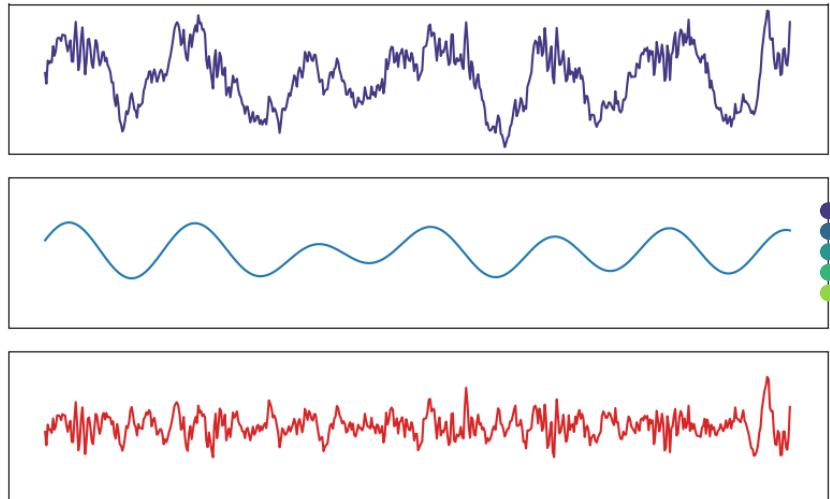
$$a_i(t) = \sum_{j=0}^m a_{ij} x(t)^j \quad \log(\sigma(t)) = \sum_{j=0}^m b_j x(t)^j$$

A different parametrization ensuring DAR model stability :

Parametric estimation of spectrum driven by an exogenous signal

T. Dupré la Tour, Y. Grenier, A. Gramfort, ICASSP 2017

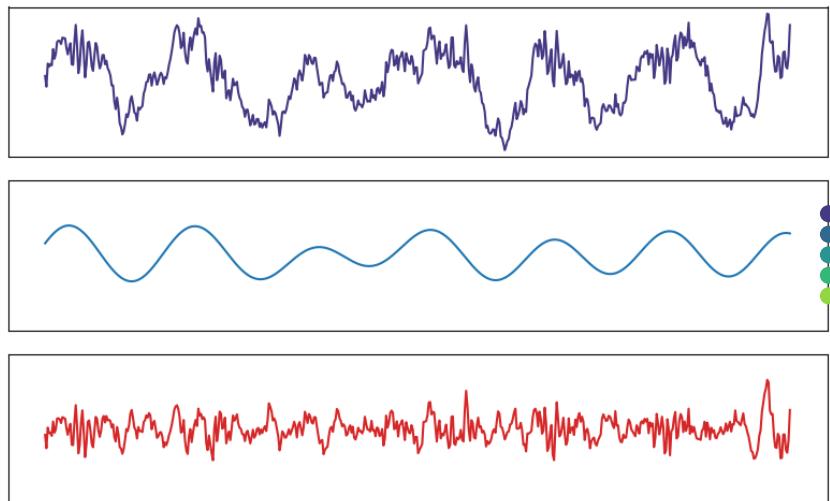
# Conditional PSD



LFP

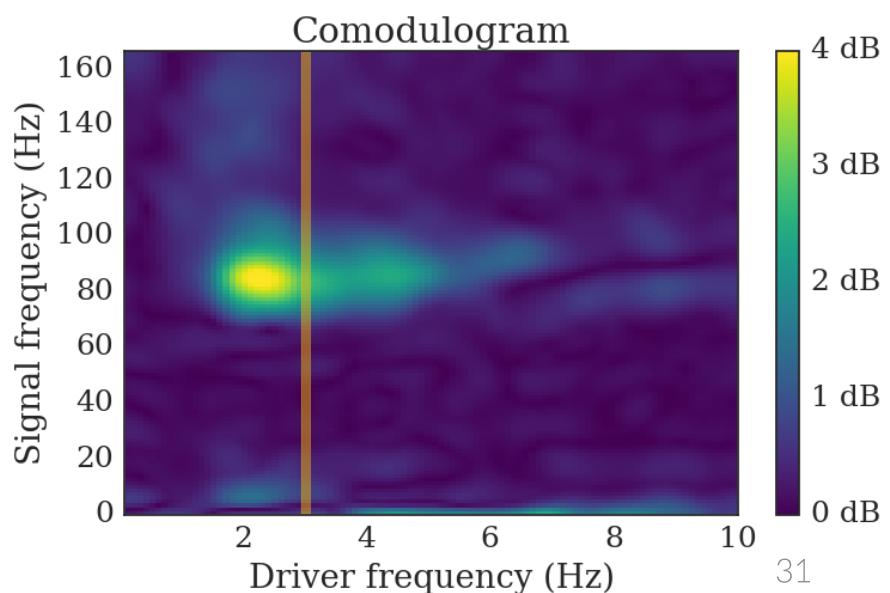
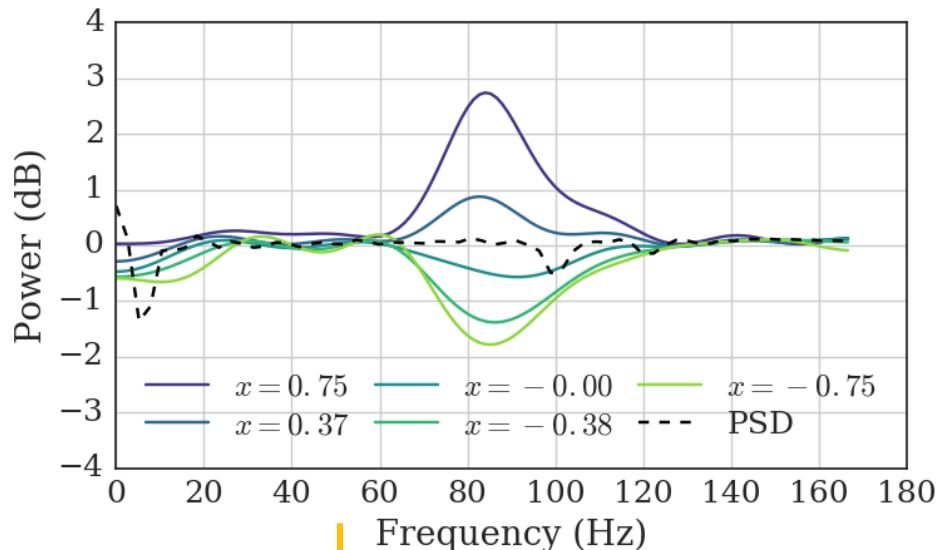
$$\text{PSD}_y(x_0)(f) = \sigma(x_0)^2 \left| \sum_{i=0}^p a_i(x_0) e^{-j2\pi f i} \right|^{-2}$$

# Conditional PSD



LFP

$$\text{PSD}_y(x_0)(f) = \sigma(x_0)^2 \left| \sum_{i=0}^p a_i(x_0) e^{-j2\pi f i} \right|^2$$



# Comodulogram on two empirical signals

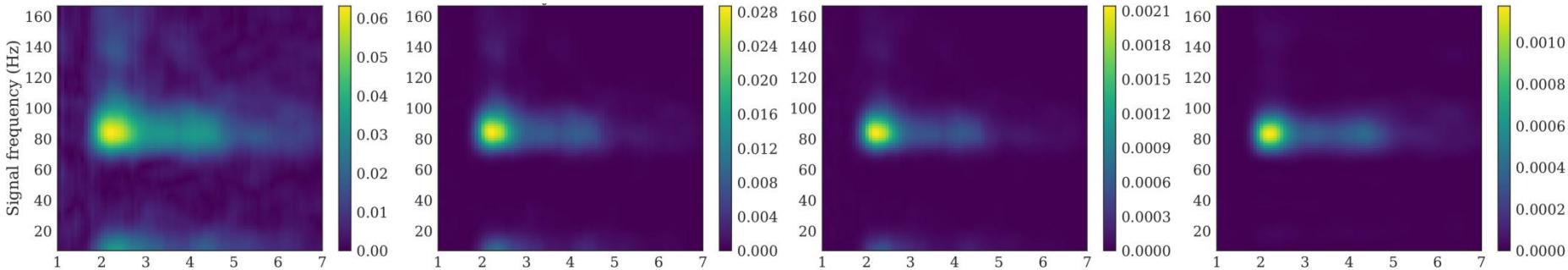
LFP

(Ozkurt et al, 2011)

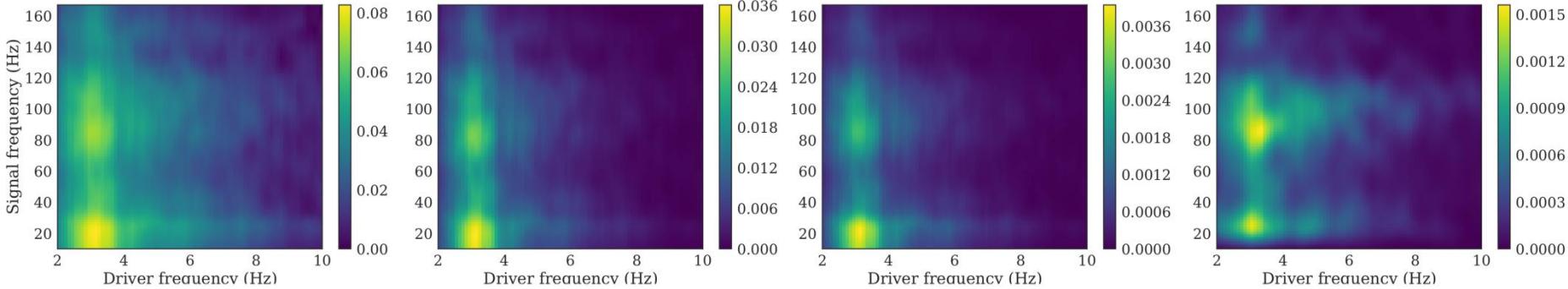
(Penny et al, 2008)

(Tort et al, 2009)

(Dupré la Tour et al, 2017)



ECoG



# Model and parameter selection

$$L = \prod_{t=p+1}^T \frac{1}{\sqrt{2\pi\sigma(t)^2}} \exp\left(-\frac{\varepsilon(t)^2}{2\sigma(t)^2}\right)$$

$$-2 \log(L) = T \log(2\pi) + \sum_{t=p+1}^T \frac{\varepsilon(t)^2}{\sigma(t)^2} + 2 \sum_{t=p+1}^T \log(\sigma(t))$$

**Main gain:** A likelihood function → parameter selection

# Model and parameter selection

$$L = \prod_{t=p+1}^T \frac{1}{\sqrt{2\pi\sigma(t)^2}} \exp\left(-\frac{\varepsilon(t)^2}{2\sigma(t)^2}\right)$$

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**Main gain:** A likelihood function → parameter selection

Example: Selection of AR order ( $p$ ) and DAR polynomial order ( $m$ ):

# Model and parameter selection

$$L = \prod_{t=p+1}^T \frac{1}{\sqrt{2\pi\sigma(t)^2}} \exp\left(-\frac{\varepsilon(t)^2}{2\sigma(t)^2}\right)$$

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**Main gain:** A likelihood function → parameter selection

Example: Selection of AR order ( $p$ ) and DAR polynomial order ( $m$ ):

- Akaike information criterion (AIC), Bayesian information criterion (BIC), ...

(Akaike, 1974)

(Schwartz, 1978)

# Model and parameter selection

$$L = \prod_{t=p+1}^T \frac{1}{\sqrt{2\pi\sigma(t)^2}} \exp\left(-\frac{\varepsilon(t)^2}{2\sigma(t)^2}\right)$$

$$-2 \log(L) = T \log(2\pi) + \sum_{t=p+1}^T \frac{\varepsilon(t)^2}{\sigma(t)^2} + 2 \sum_{t=p+1}^T \log(\sigma(t))$$

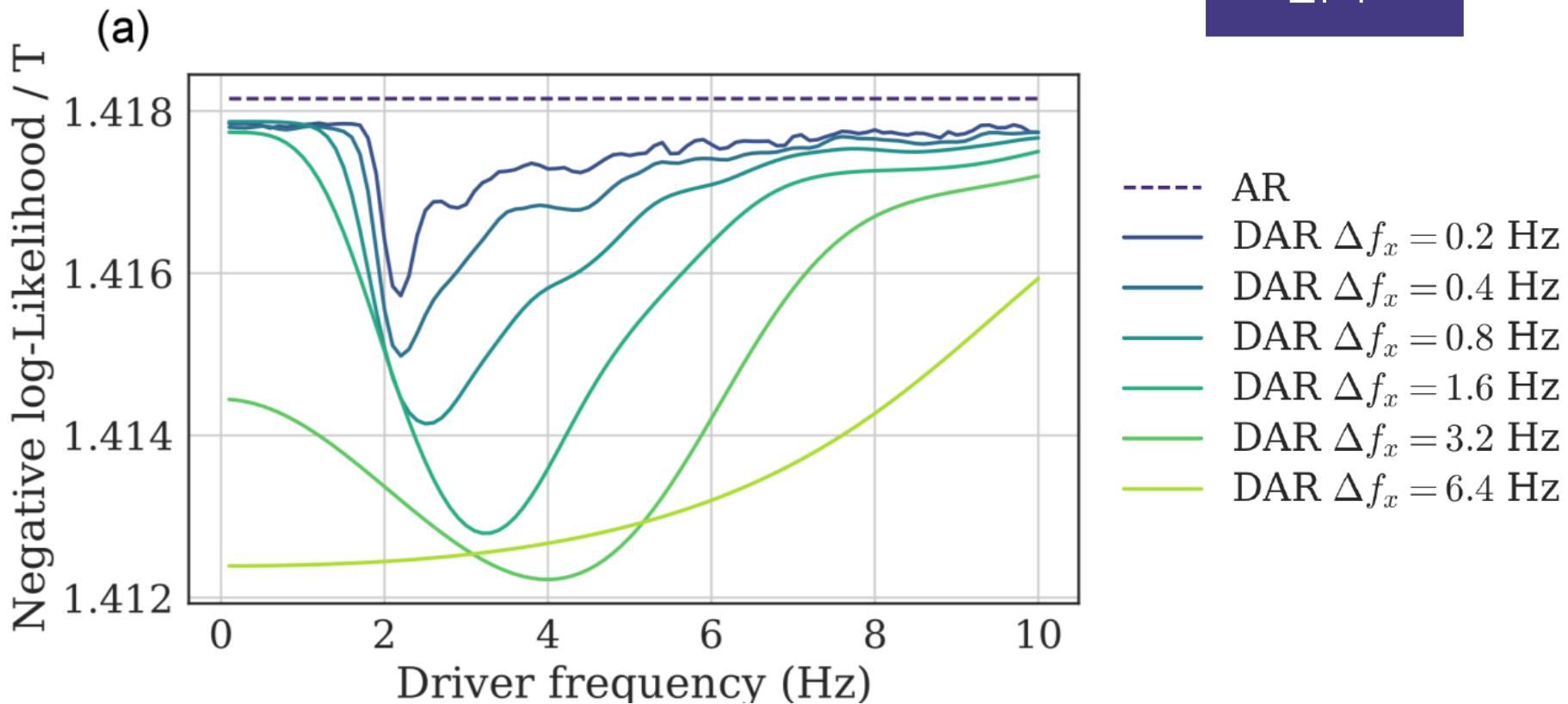
**Main gain:** A likelihood function → parameter selection

Example: Selection of AR order ( $p$ ) and DAR polynomial order ( $m$ ):

- Akaike information criterion (AIC), Bayesian information criterion (BIC), ...
- Evaluation on left-out data, cross-validation (Akaike, 1974)
- Evaluation on left-out data, cross-validation (Schwartz, 1978)

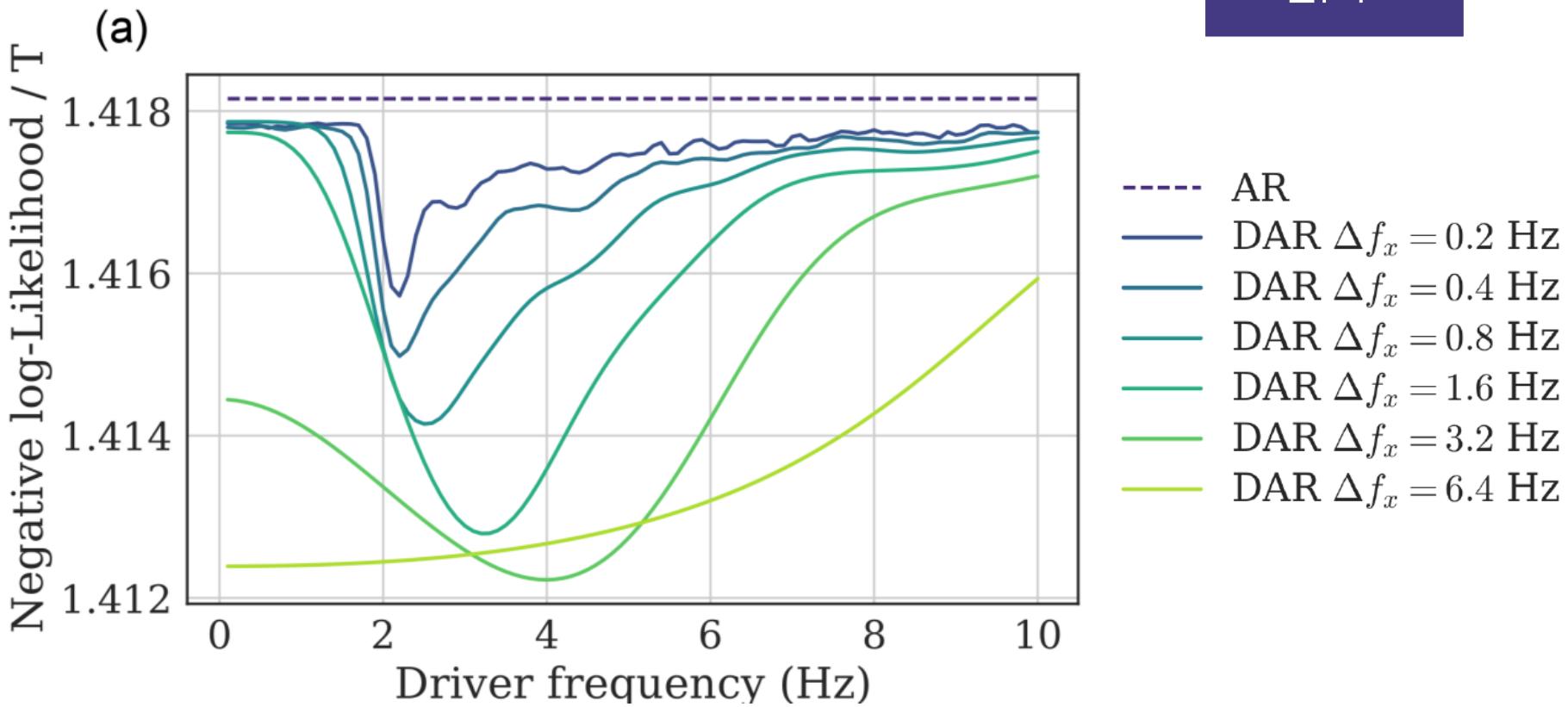
# Driver selection

LFP



# Driver selection

LFP



Further optimizing the driver filter with gradient descent:

Driver estimation in non-linear autoregressive models

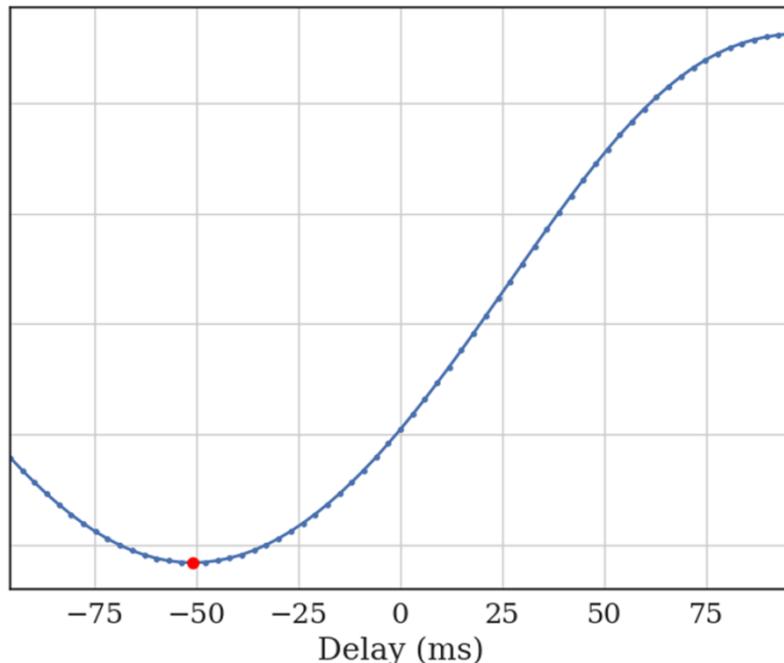
T. Dupré la Tour, Y. Grenier, A. Gramfort, ICASSP 2018

# Delay estimation

- DAR model between  $y(t)$  and  $x_\tau(t) = x(t - \tau)$
- Minimize the negative log-likelihood

# Delay estimation

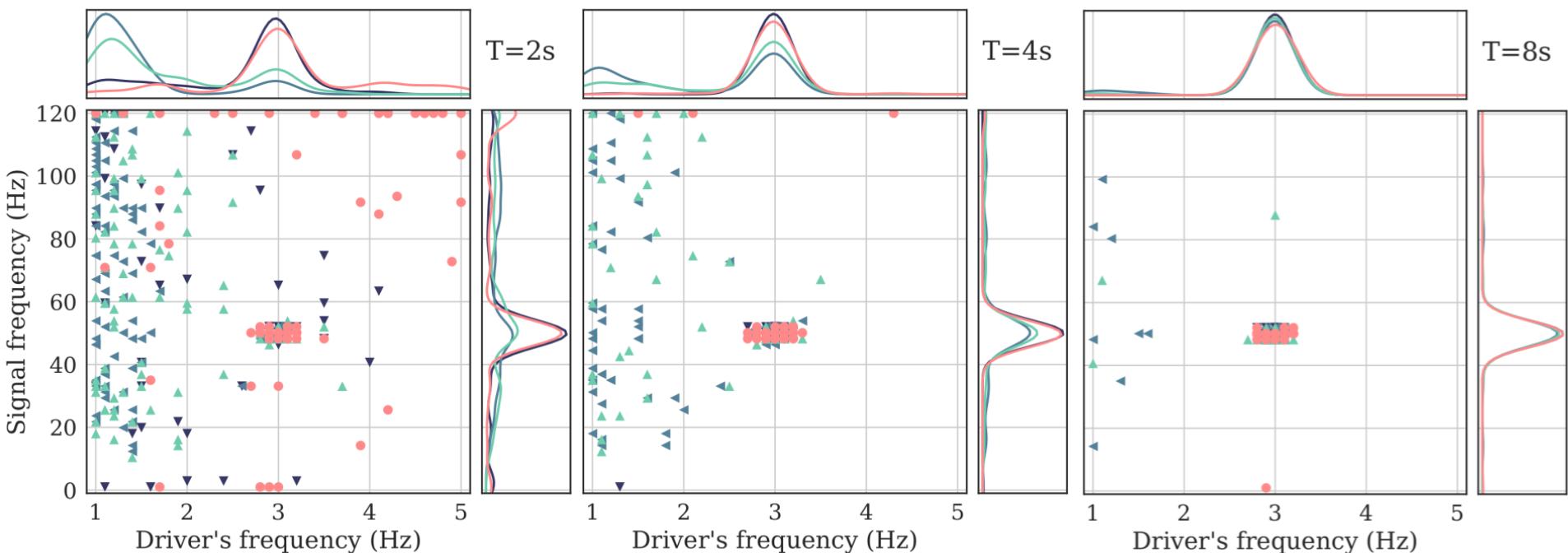
- DAR model between  $y(t)$  and  $x_\tau(t) = x(t - \tau)$
- Minimize the negative log-likelihood



(Besserve et al , 2010)  
(Jiang et al , 2015)



# Robustness to short signals



- ▼ (Penny et al, 2008)
- △ (Tort et al, 2009)
- ▲ (Ozkurt et al, 2011)
- (Dupré la Tour et al, 2017)

# 1. Cross-frequency coupling analysis with driven autoregressive models

- Estimation of spectral modulation → capture CFC
- Generative model → easy comparison of parameters
- Delay estimation → directionality of the coupling
- Parametric model → robust to short signals

Non-linear autoregressive models for cross-frequency coupling in neural time series

T. Dupré la Tour, L. Tallot, L. Grabot, V. Doyère, V. van Wassenhove, Y. Grenier, A. Gramfort, *PLOS Computational Biology* 2017

**Parametric estimation of spectrum driven by an exogenous signal**

T. Dupré la Tour, Y. Grenier, A. Gramfort, *ICASSP* 2017

**Driver estimation in non-linear autoregressive models**

T. Dupré la Tour, Y. Grenier, A. Gramfort, *ICASSP* 2018

# Outline

1. Cross-frequency coupling analysis  
*with driven autoregressive models*

2. Temporal waveform analysis  
*with convolutional sparse coding models*

# Part 2

## 2. Temporal waveform analysis with convolutional sparse coding models

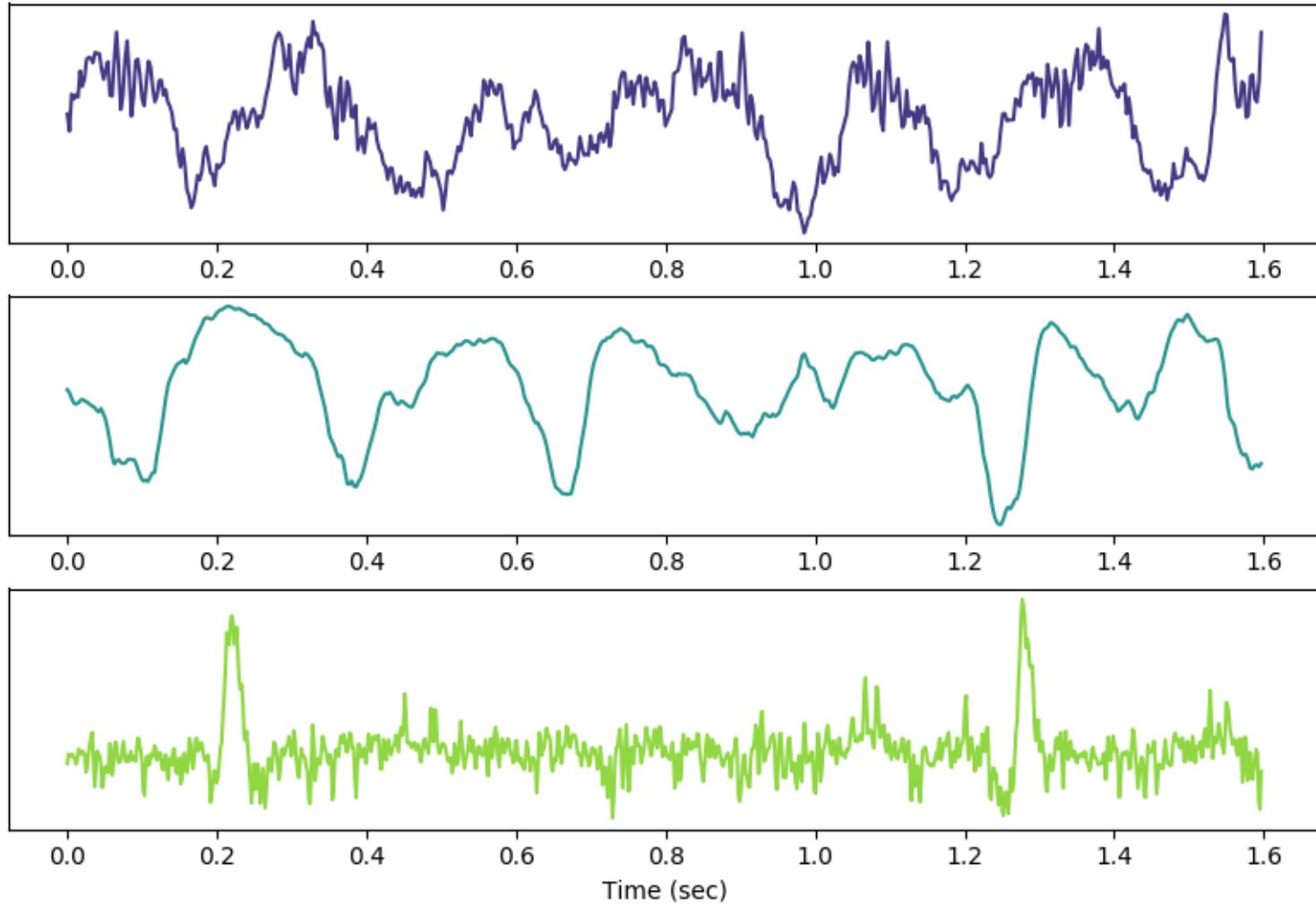
Learning the morphology of brain signals using alpha-stable convolutional sparse coding

M. Jas, T. Dupré la Tour, U. Şimşekli, A. Gramfort, NeurIPS 2017

Multivariate Convolutional Sparse Coding for Electromagnetic Brain Signals

T. Dupré la Tour\*, T. Moreau\*, M. Jas, A. Gramfort, NeurIPS 2018

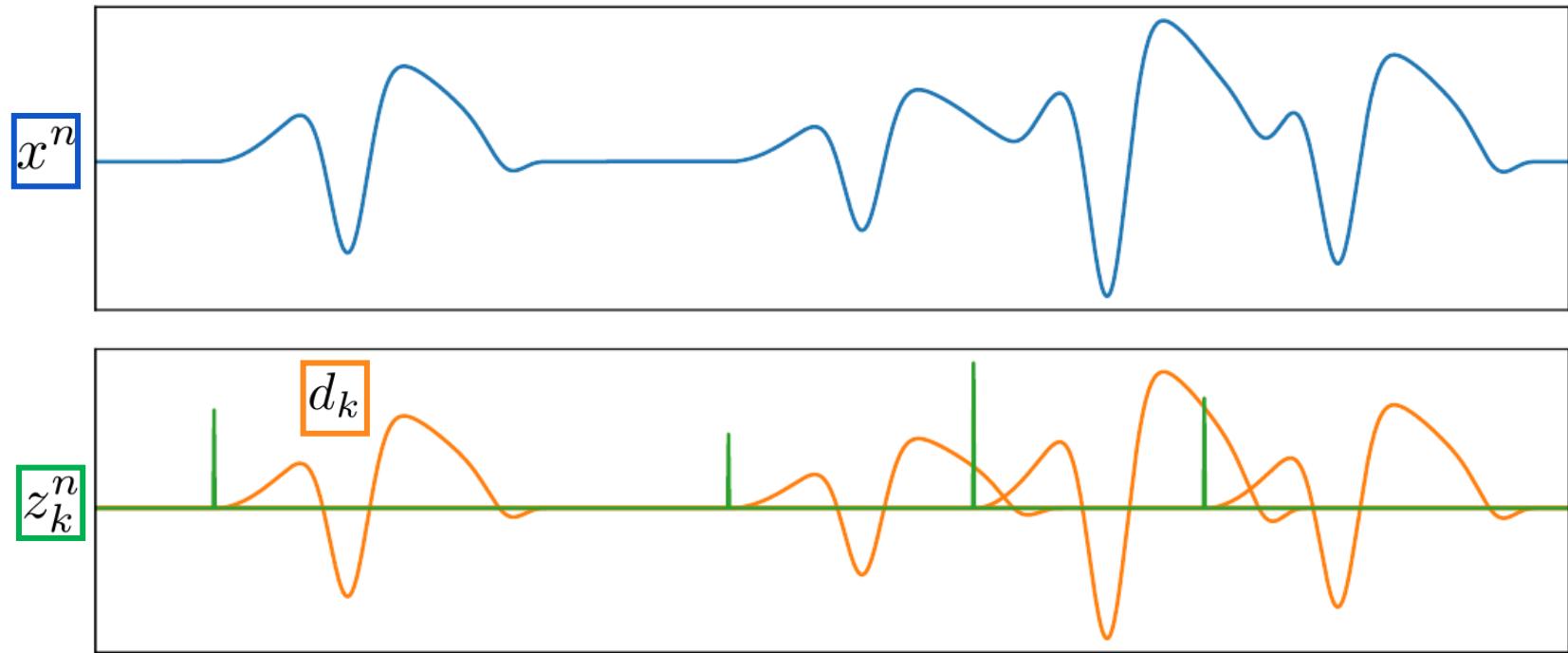
# Neurophysiological time series



# Temporal waveform analysis

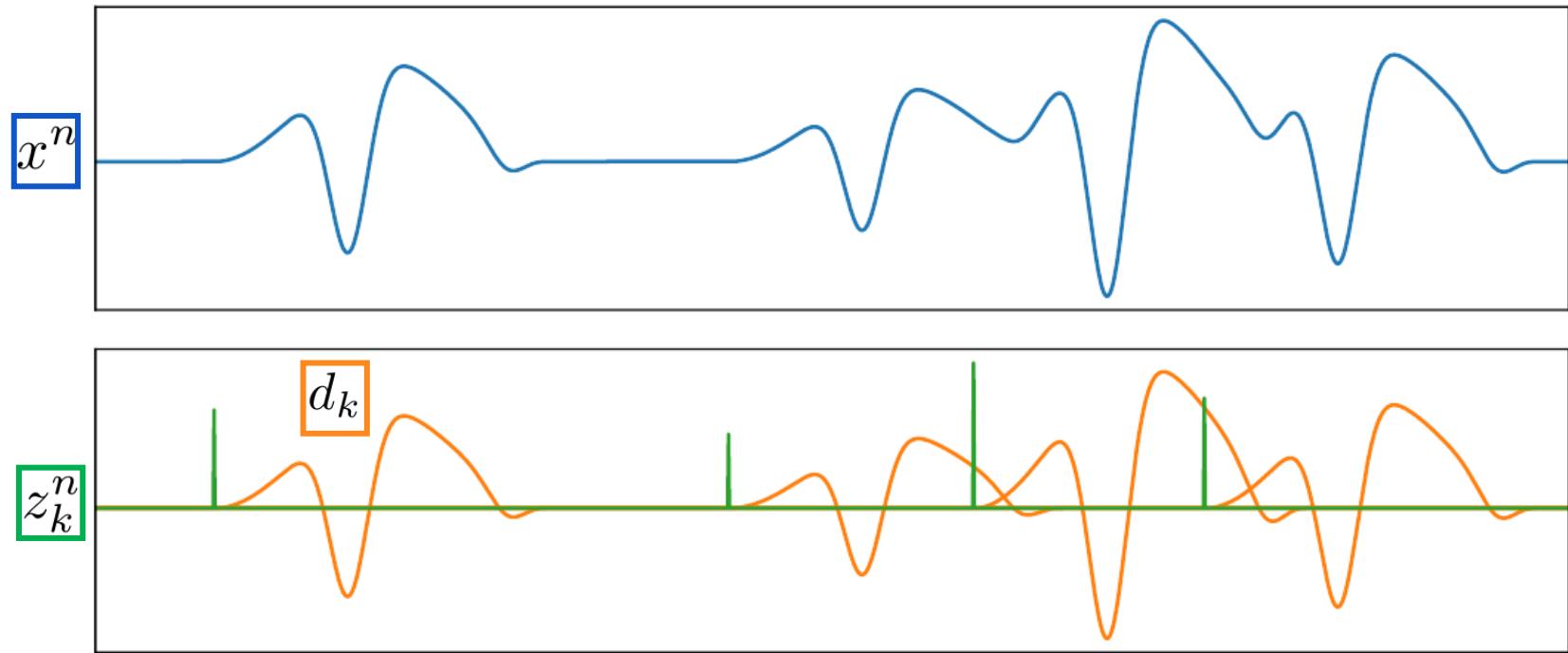
- Sparse representations: wavelet basis  
(Mallat and Zhang, 1993, Candès et al, 2006)
- Sparse coding / dictionary learning  
(Olshausen and Field, 1996, Elad and Aharon, 2006)
- Shift-invariant representations  
(Lewicki and Sejnowski, 1999, Grosse et al, 2007)
- In neurophysiology:
  - Matching of time-invariant filters (Jost et al, 2006)
  - Multivariate orthogonal matching pursuit (Barthélemy et al, 2012)
  - Matching pursuit and heuristics (Brokmeier and Principe, 2016)
  - Sliding window machine (Gips et al, 2017)
  - Adaptive waveform learning (Hitziger et al, 2017)

# Convolutional sparse coding



(Grosse et al, 2007)

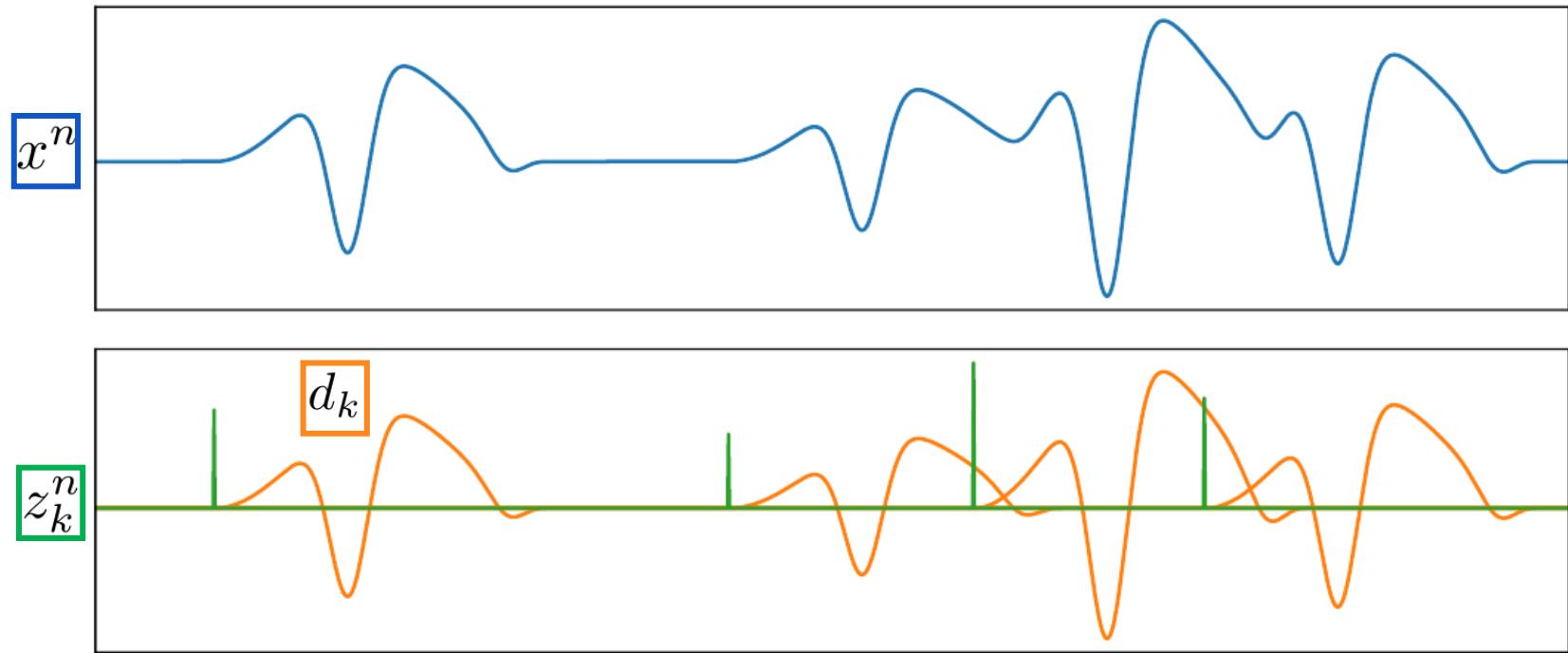
# Convolutional sparse coding



$$x^n[t] = \sum_{k=1}^K (z_k^n * d_k)[t] + \varepsilon[t]$$

(Grosse et al, 2007)

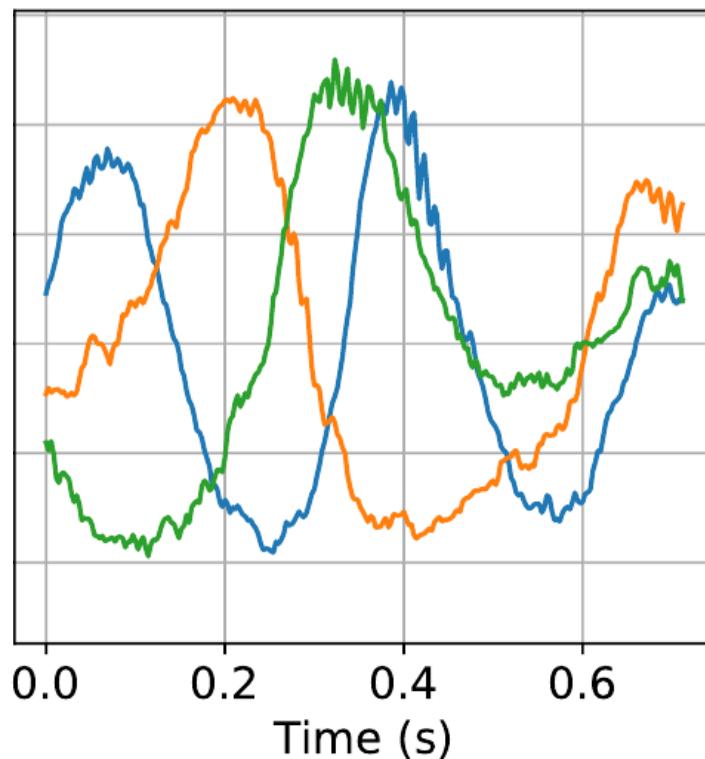
# Convolutional sparse coding



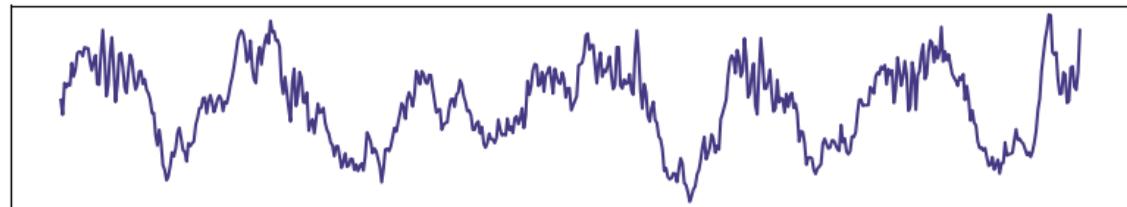
$$\min_{d,z} \sum_{n=1}^N \frac{1}{2} \left\| \boxed{x^n} - \sum_{k=1}^K \boxed{z_k^n} * \boxed{d_k} \right\|_2^2 + \lambda \sum_{k=1}^K \|\boxed{z_k^n}\|_1,$$

s.t.     $\|\boxed{d_k}\|_2^2 \leq 1$  and  $\boxed{z_k^n} \geq 0$ .              (Grosse et al, 2007)

# Learned atoms



LFP



# First challenge: optimization speed

$$\begin{aligned} \min_{d,z} \sum_{n=1}^N \frac{1}{2} \left\| x^n - \sum_{k=1}^K z_k^n * d_k \right\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1, \\ \text{s.t. } \|d_k\|_2^2 \leq 1 \text{ and } z_k^n \geq 0. \end{aligned}$$

Block-coordinate descent

- Z-step
- D-step

# First challenge: optimization speed

$$\begin{aligned} \min_{d,z} \sum_{n=1}^N \frac{1}{2} \left\| x^n - \sum_{k=1}^K z_k^n * d_k \right\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1, \\ \text{s.t. } \|d_k\|_2^2 \leq 1 \text{ and } z_k^n \geq 0. \end{aligned}$$

Block-coordinate descent

- Z-step
  - GCD (Kavukcuoglu et al, 2010)
  - FISTA (Chalasani et al, 2013)
  - ADMM (Bristow et al, 2013)
  - ADMM + FFT (Wohlberg, 2016)
  - L-BFGS (Jas et al, 2017)
  - LGCD (Dupré la Tour et al, 2018)
- D-step

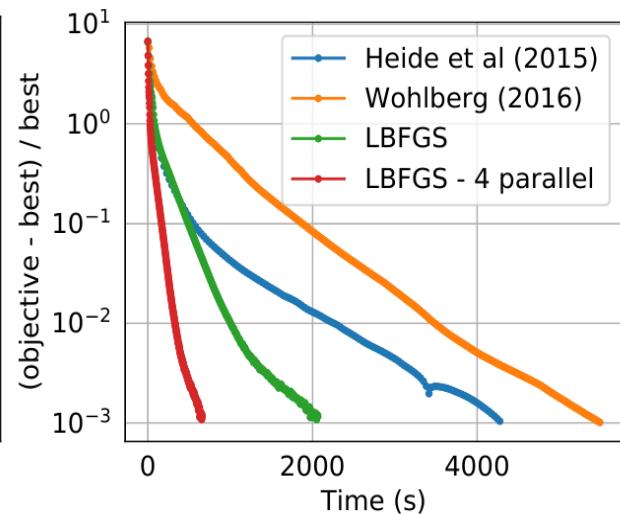
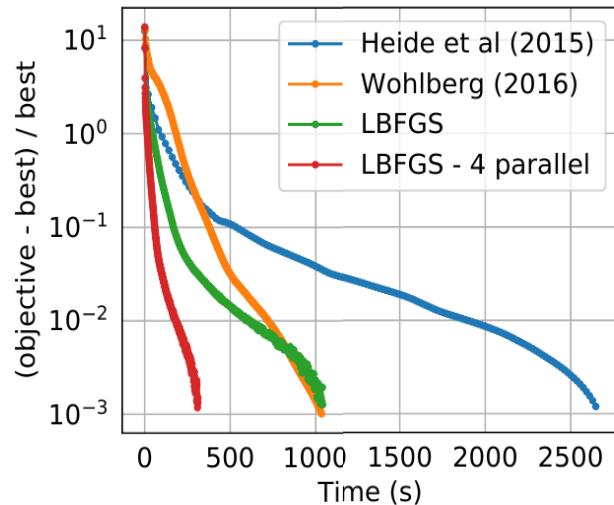
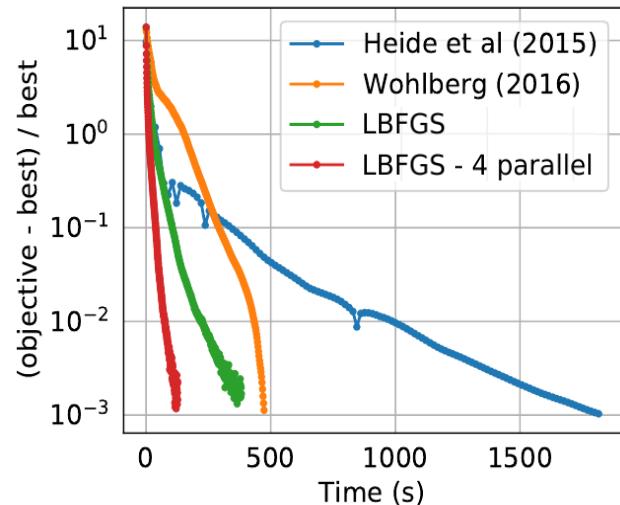
# First challenge: optimization speed

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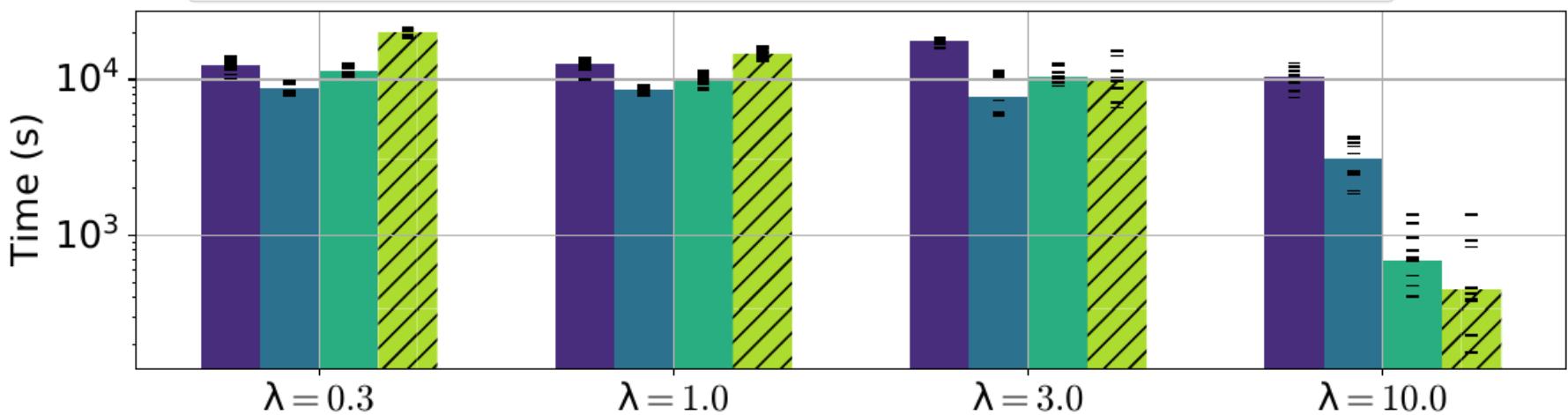
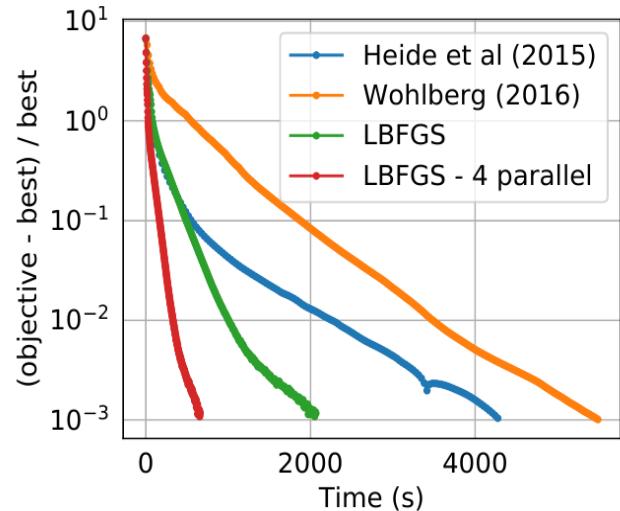
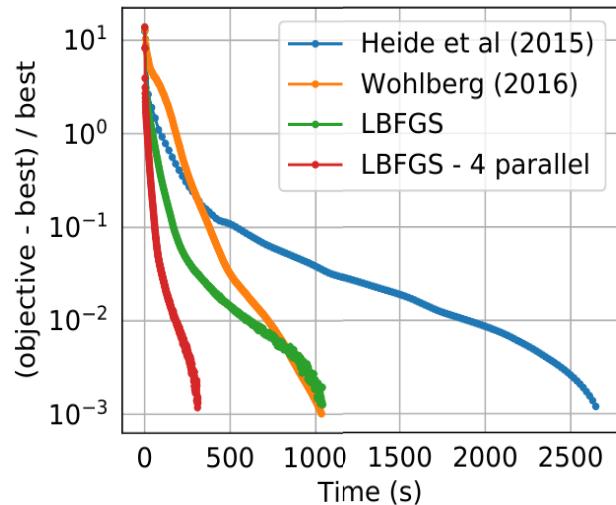
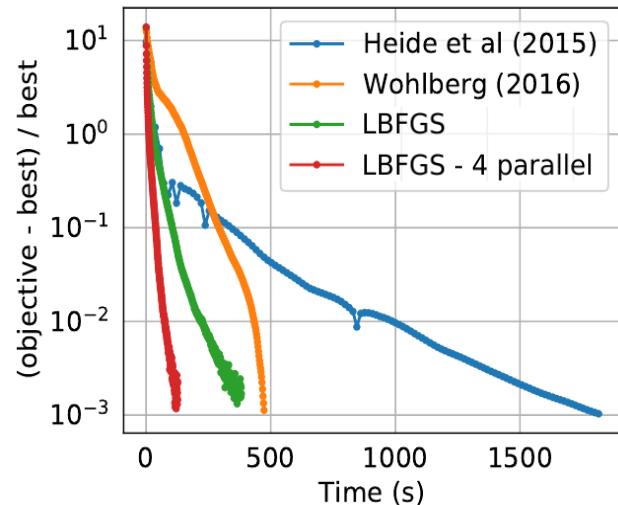
## Block-coordinate descent

- Z-step
  - GCD (Kavukcuoglu et al, 2010)
  - FISTA (Chalasani et al, 2013)
  - ADMM (Bristow et al, 2013)
  - ADMM + FFT (Wohlberg, 2016)
  - L-BFGS (Jas et al, 2017) (Jas et al, 2017)
  - LGCD (Dupré la Tour et al, 2018)
- D-step
  - FFT (Grosse et al, 2007)
  - ADMM + FFT (Heide et al, 2015)
  - ADMM + FFT (Wohlberg, 2016)
  - L-BFGS (dual) (Jas et al, 2017) (Jas et al, 2017)
  - PGD (Dupré la Tour et al, 2018)

# Speed benchmarks



# Speed benchmarks



## Second challenge: strong artifacts

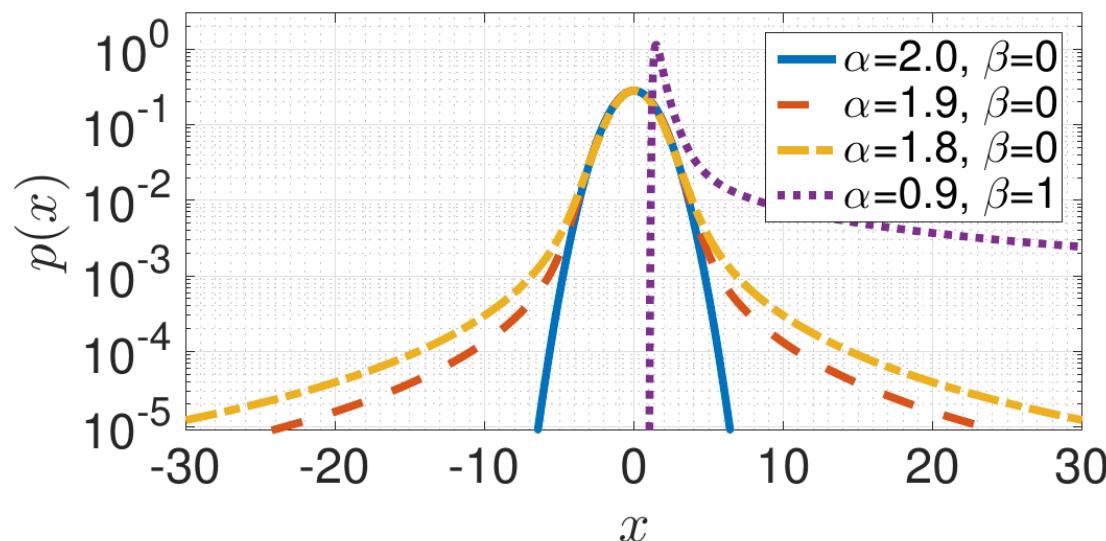
Gaussian CSC model

$$\hat{x}^n \triangleq \sum_{k=1}^K z_k^n * d_k$$

$$z_k^n[t] \sim \mathcal{E}(\lambda), \quad x^n[t]|z, d \sim \mathcal{N}(\hat{x}^n[t], 1),$$

Alpha-stable CSC model

$$z_k^n[t] \sim \mathcal{E}(\lambda), \quad x^n[t]|z, d \sim \mathcal{S}(\alpha, 0, 1/\sqrt{2}, \hat{x}^n[t])$$



## Second challenge: strong artifacts

Gaussian CSC model

$$\hat{x}^n \triangleq \sum_{k=1}^K z_k^n * d_k$$

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Alpha-stable CSC model

$$z_k^n[t] \sim \mathcal{E}(\lambda), \quad x^n[t]|z, d \sim \mathcal{S}(\alpha, 0, 1/\sqrt{2}, \hat{x}^n[t])$$

Conditional formulation (Samorodnitsky and Taqqu, 1994)

$$z_k^n[t] \sim \mathcal{E}(\lambda), \quad \phi^n[t] \sim \mathcal{S}\left(\frac{\alpha}{2}, 1, 2\left(\cos \frac{\pi \alpha}{4}\right)^{2/\alpha}, 0\right)$$

$$x^n[t]|z, d, \phi \sim \mathcal{N}\left(\hat{x}^n[t], \frac{1}{2}\phi^n[t]\right)$$

# Alpha CSC estimation

Monte Carlo Expectation-Maximization algorithm

- E-step: MCMC estimation (Chib and Greenberg, 1995)

$$w^n[t]^{(i)} \triangleq \mathbb{E} \left[ 1/\phi^n[t] \right]_{p(\phi|x, z^{(i)}, d^{(i)})}$$

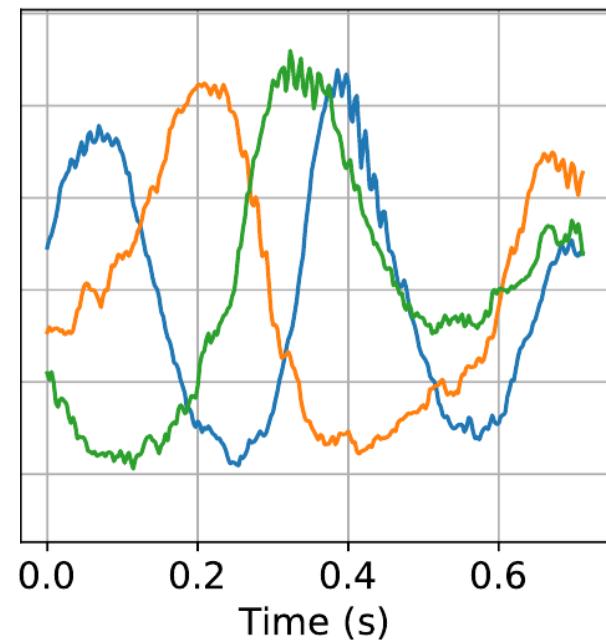
- M-step: weighted CSC

$$\min_{d, z} \sum_{n=1}^N \frac{1}{2} \left\| \sqrt{w^n} \odot \left( x^n - \sum_{k=1}^K z_k^n * d_k \right) \right\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1$$

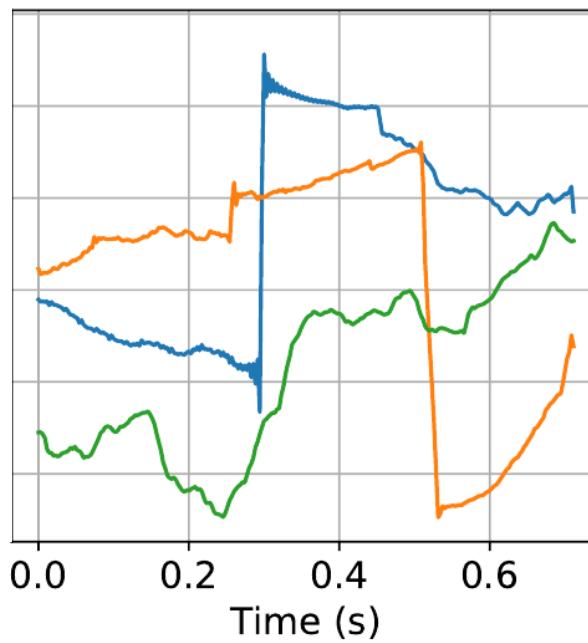
$$\text{s.t. } \|d_k\|_2^2 \leq 1, \text{ and } z_k^n \geq 0, \quad \forall k, n.$$

# Learned atoms

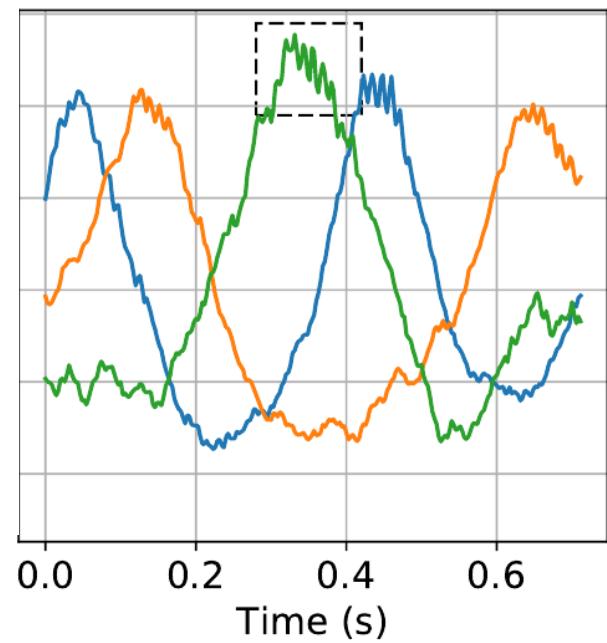
CSC (without artifacts)



CSC (with artifacts)



Alpha CSC (with artifacts)



Learning the morphology of brain signals using alpha-stable convolutional sparse coding

M. Jas, T. Dupré la Tour, U. Şimşekli, A. Gramfort, NeurIPS 2017

# Third challenge: multivariate models

MEG



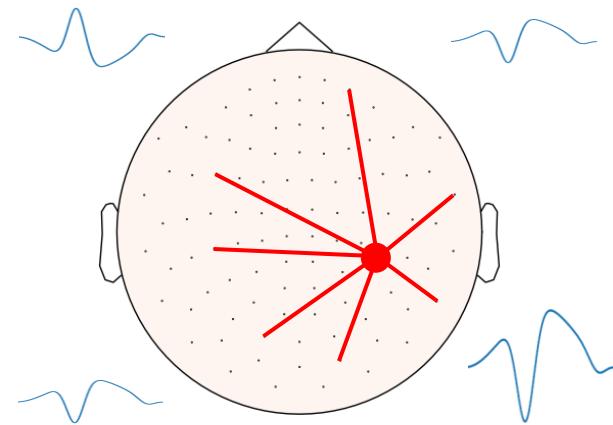
# Third challenge: multivariate models

$$\begin{aligned} \min_{D, z} & \sum_{n=1}^N \frac{1}{2} \left\| X^n - \sum_{k=1}^K z_k^n * D_k \right\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1, \\ \text{s.t. } & \|D_k\|_2^2 \leq 1 \text{ and } z_k^n \geq 0. \end{aligned}$$

# Third challenge: multivariate models

$$\min_{D,z} \sum_{n=1}^N \frac{1}{2} \left\| X^n - \sum_{k=1}^K z_k^n * D_k \right\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1,$$

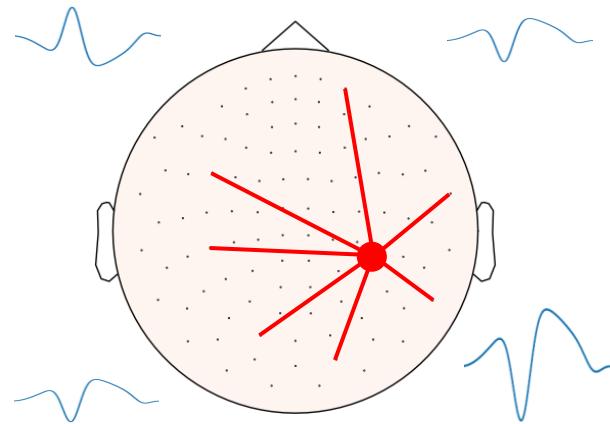
s.t.     $\|D_k\|_2^2 \leq 1$  and  $z_k^n \geq 0$ .



# Third challenge: multivariate models

$$\min_{u,v,z} \sum_{n=1}^N \frac{1}{2} \left\| X^n - \sum_{k=1}^K z_k^n * (u_k v_k^\top) \right\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1,$$

s.t.     $\|u_k\|_2^2 \leq 1$  ,  $\|v_k\|_2^2 \leq 1$  and  $z_k^n \geq 0$ .



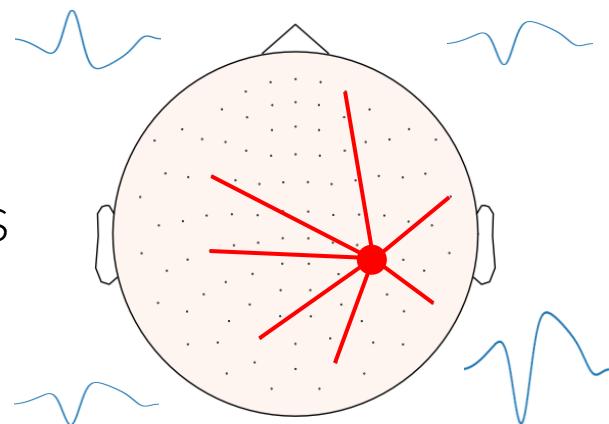
# Third challenge: multivariate models

$$\min_{u,v,z} \sum_{n=1}^N \frac{1}{2} \left\| X^n - \sum_{k=1}^K z_k^n * (u_k v_k^\top) \right\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1,$$

s.t.     $\|u_k\|_2^2 \leq 1$  ,  $\|v_k\|_2^2 \leq 1$  and  $z_k^n \geq 0$ .

Rank-1 constraint

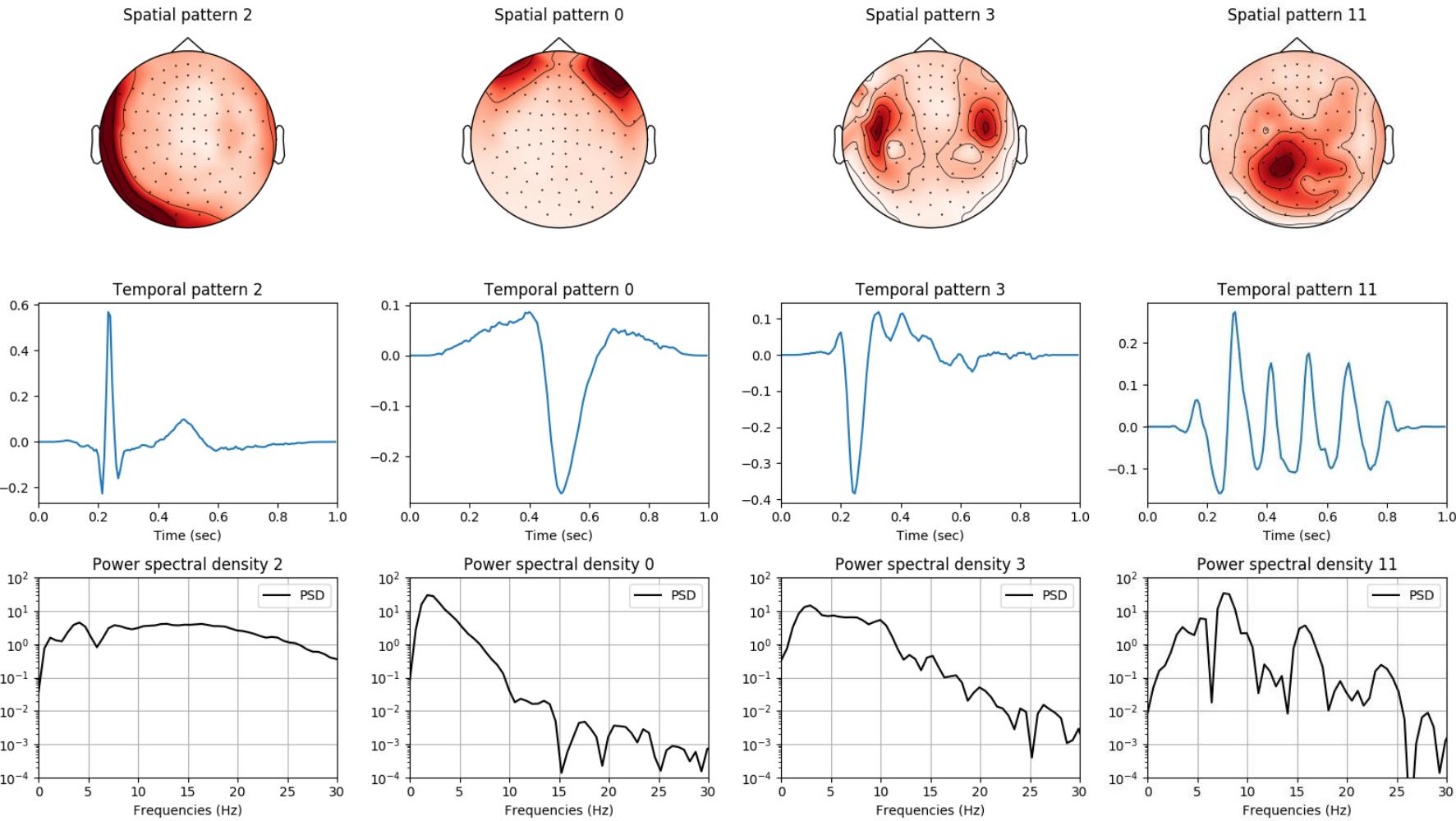
- Consistent with Physics of EM waves
- Scales in (L+P) instead of (LP)



Multivariate Convolutional Sparse Coding for Electromagnetic Brain Signals

T. Dupré la Tour\*, T. Moreau\*, M. Jas, A. Gramfort, NeurIPS 2018

# Multivariate atoms



## 2. Temporal waveform analysis *with convolutional sparse coding models*

- CSC well-posed optimization problem
- State-of-the-art optimization speed
- Alpha CSC model for robustness to strong artifacts
- Multivariate CSC model, rank-1 constraint

Learning the morphology of brain signals using alpha-stable convolutional sparse coding

M. Jas, T. Dupré la Tour, U. Şimşekli, A. Gramfort, NeurIPS 2017

Multivariate Convolutional Sparse Coding for Electromagnetic Brain Signals

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# Conclusion

1. Cross-frequency coupling analysis  
with driven autoregressive models

2. Temporal waveform analysis  
with convolutional sparse coding models

# Dissemination of our work

We published our code online, with:

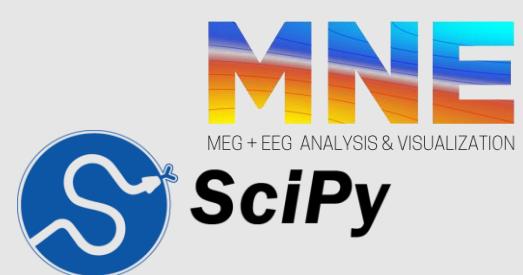
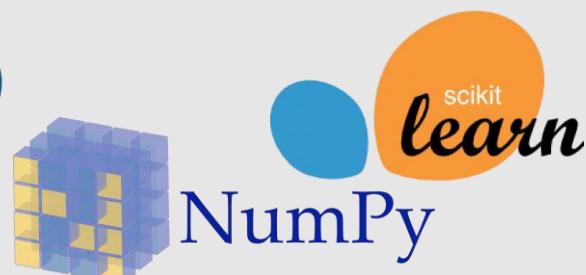
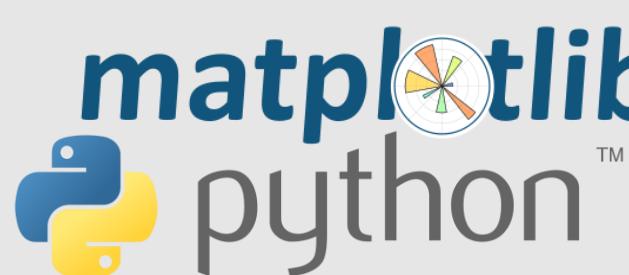
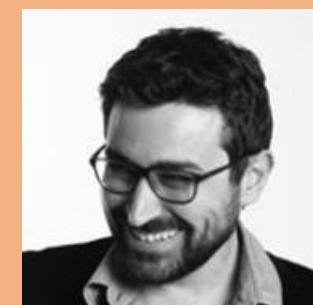
- Tests, and continuous integration
- Extensive documentation
- Gallery of examples

1. PAC metrics, DAR models

<https://pactools.github.io>

2. CSC, alpha-stable CSC, multivariate CSC, rank-1 constraint

<https://alphacsc.github.io>



# Thank you for your attention

**Non-linear autoregressive models for cross-frequency coupling in neural time series**

T. Dupré la Tour, L. Tallot, L. Grabot, V. Doyère, V. van Wassenhove, Y. Grenier, A. Gramfort, *PLOS Computational Biology* 2017

**Parametric estimation of spectrum driven by an exogenous signal**

T. Dupré la Tour, Y. Grenier, A. Gramfort, *ICASSP* 2017

**Driver estimation in non-linear autoregressive models**

T. Dupré la Tour, Y. Grenier, A. Gramfort, *ICASSP* 2018

<https://pactools.github.io>

**Learning the morphology of brain signals using alpha-stable convolutional sparse coding**

M. Jas, T. Dupré la Tour, U. Şimşekli, A. Gramfort, *NeurIPS* 2017

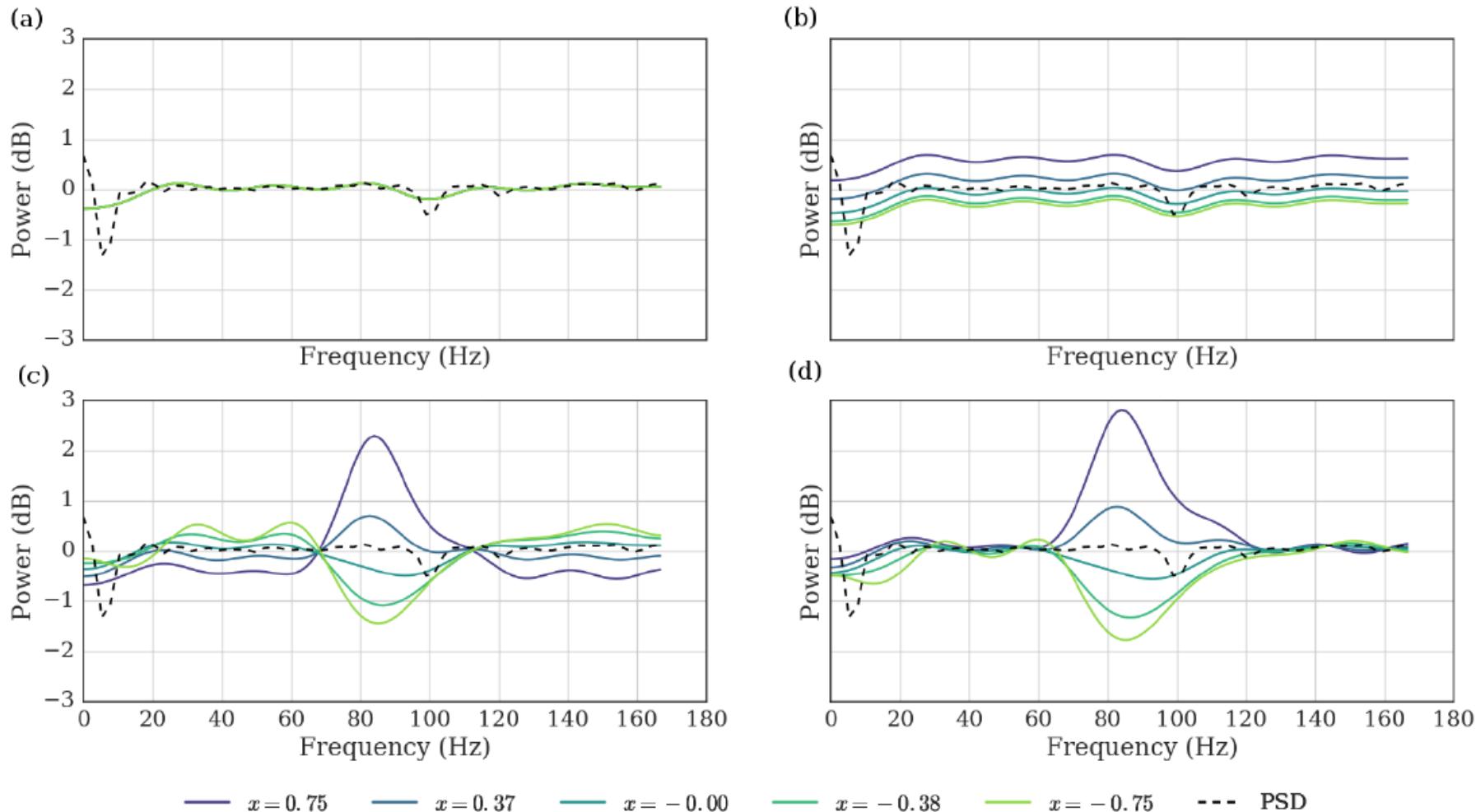
**Multivariate Convolutional Sparse Coding for Electromagnetic Brain Signals**

T. Dupré la Tour\*, T. Moreau\*, M. Jas, A. Gramfort, *NeurIPS* 2018

<https://alphacsc.github.io>



# DAR models conditional PSD



# Guarantee local stability

- AR model

$$y(t) + \sum_{i=1}^p a_i y(t-i) = \varepsilon(t)$$

- Non-stationary AR model

$$a_i(t) = \sum_{j=0}^m a_{ij} x(t)^j$$

- Lattice parameterization

$$a_p^{(p)} = k_p; \quad \forall i \in [1, p-1], \quad a_i^{(p)} = a_i^{(p-1)} + k_p a_{p-i}^{(p-1)}$$

- Local stability criterion

$$-1 < k_i < 1$$

- Log Area Ratio

$$\gamma_i = \log \left( \frac{1+k_i}{1-k_i} \right) \iff k_i = \frac{e^{\gamma_i} - 1}{e^{\gamma_i} + 1}$$

- Driven AR model

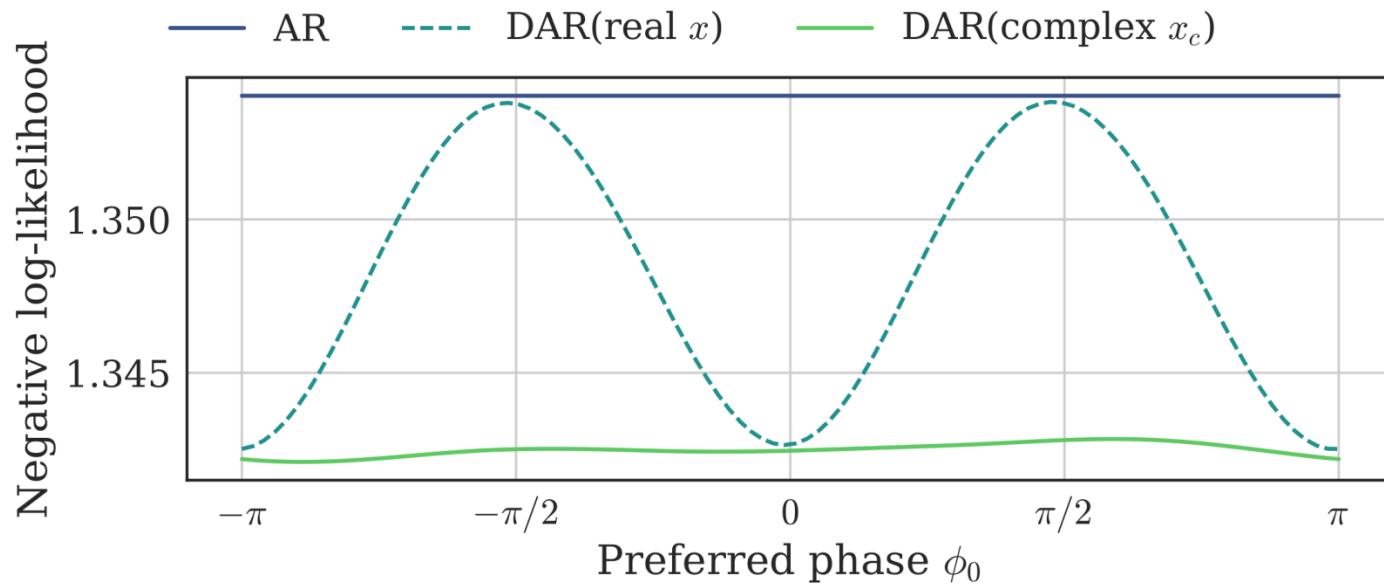
$$\gamma_i(t) = \sum_{j=0}^m \gamma_{ij} x(t)^j :$$

# Using a complex driver

- With a real driver
- With a complex driver

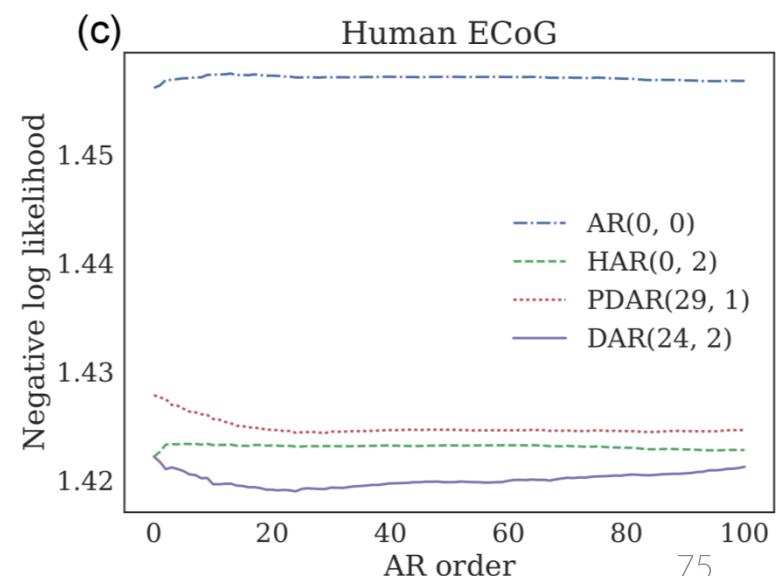
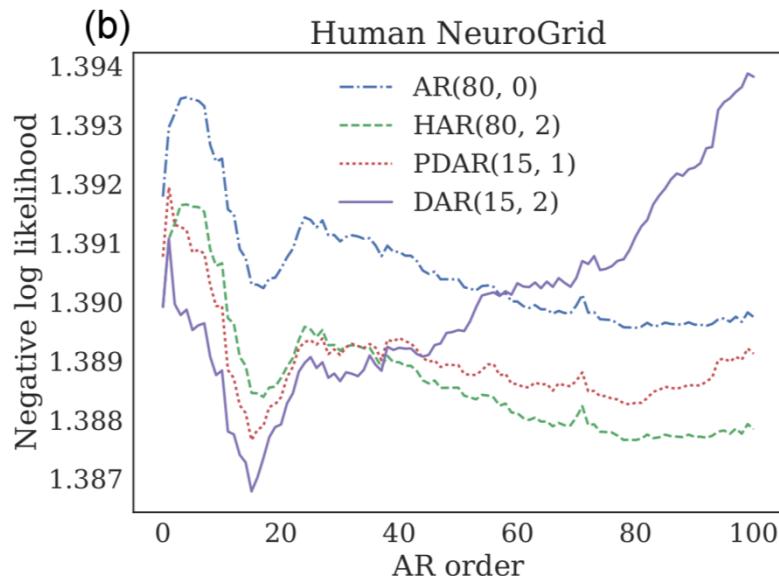
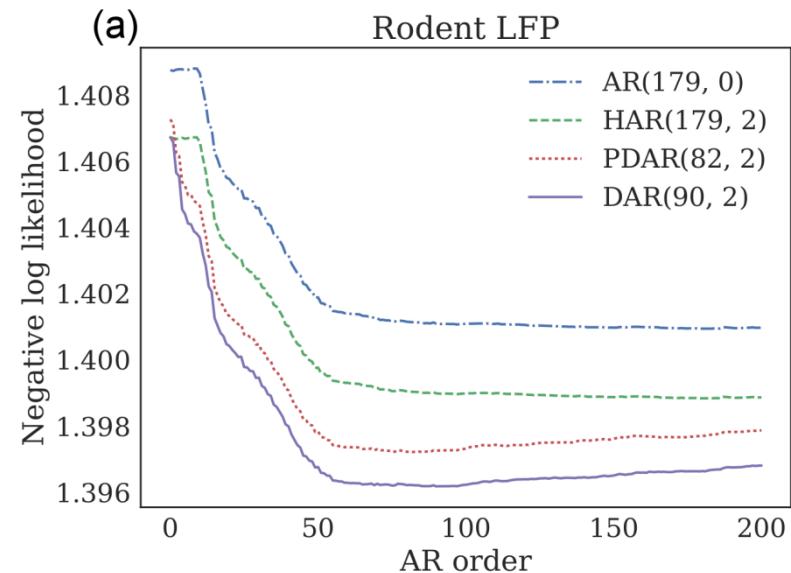
$$a_i(t) = \sum_{k=0}^m a_{ik} x(t)^k$$

$$a_i(t) = \sum_{0 \leq k+l \leq m} a_{ikl} x(t)^k \bar{x}(t)^l$$

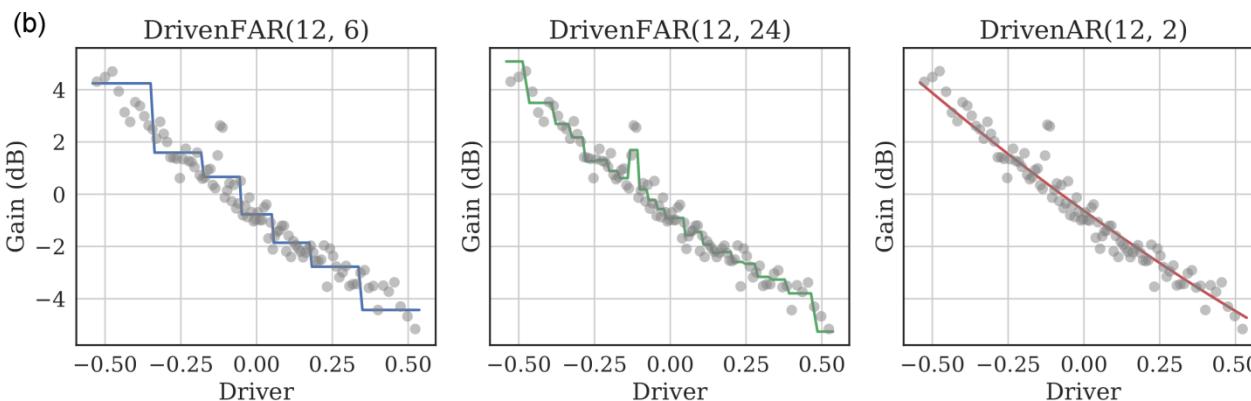
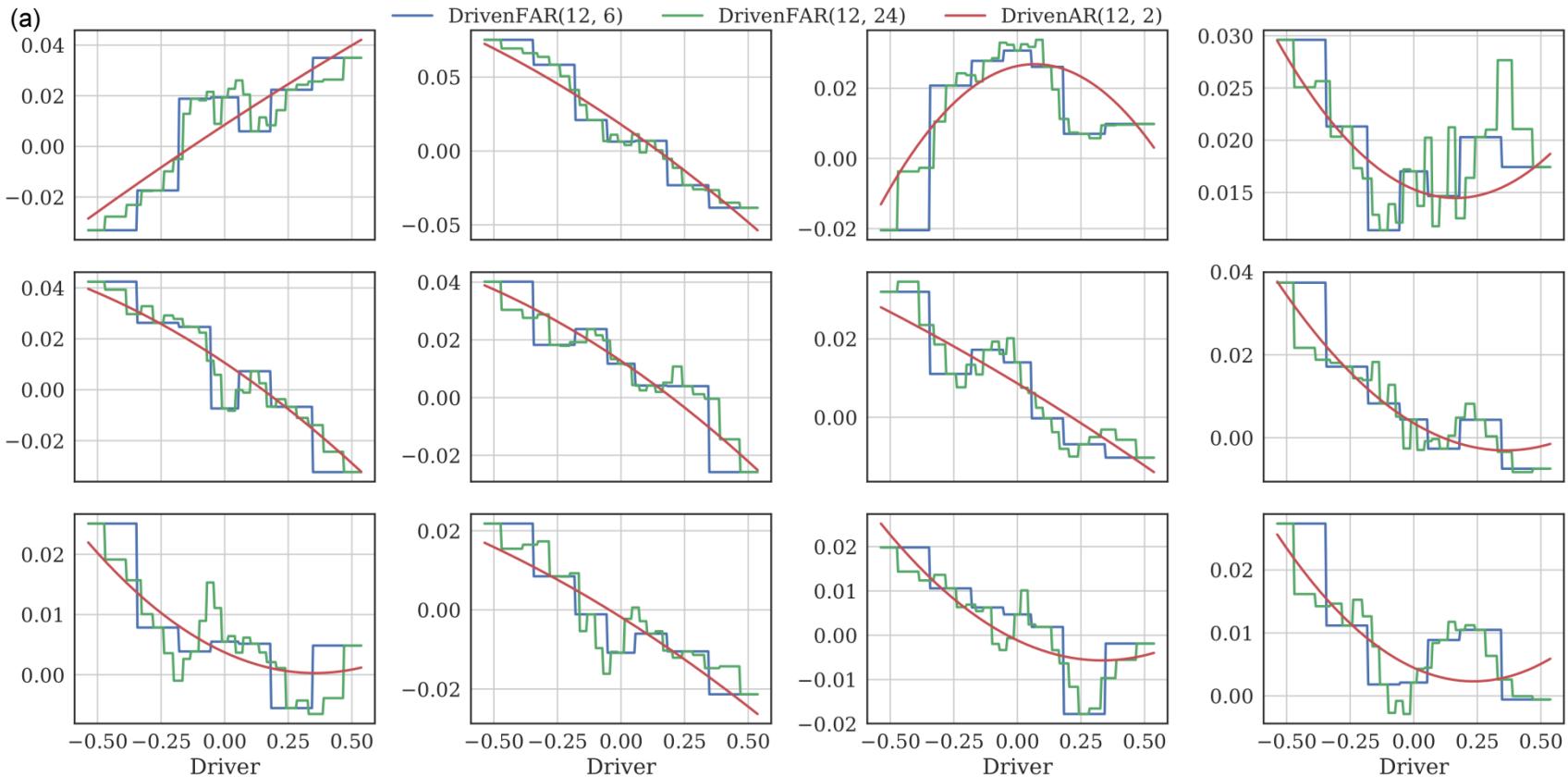


# Model variants and cross-validation

- AR: linear AR model
- HAR: linear AR model + driven innovation variance
- PDAR: driven AR model with constant amplitude driver
- DAR: driven AR model



# The polynomial basis is good enough



# Model and parameter selection

- Likelihood function

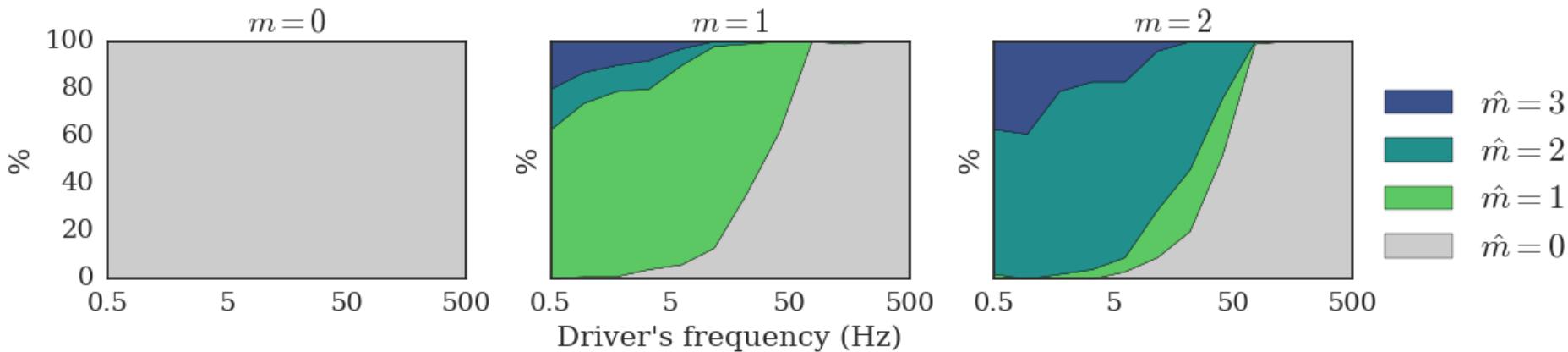
$$L = \prod_{t=p}^T \frac{1}{\sqrt{2\pi\sigma(t)^2}} \exp\left(-\frac{\varepsilon(t)^2}{2\sigma(t)^2}\right)$$

- BIC selection

$$BIC = -2 \log(L) + d \log(T)$$

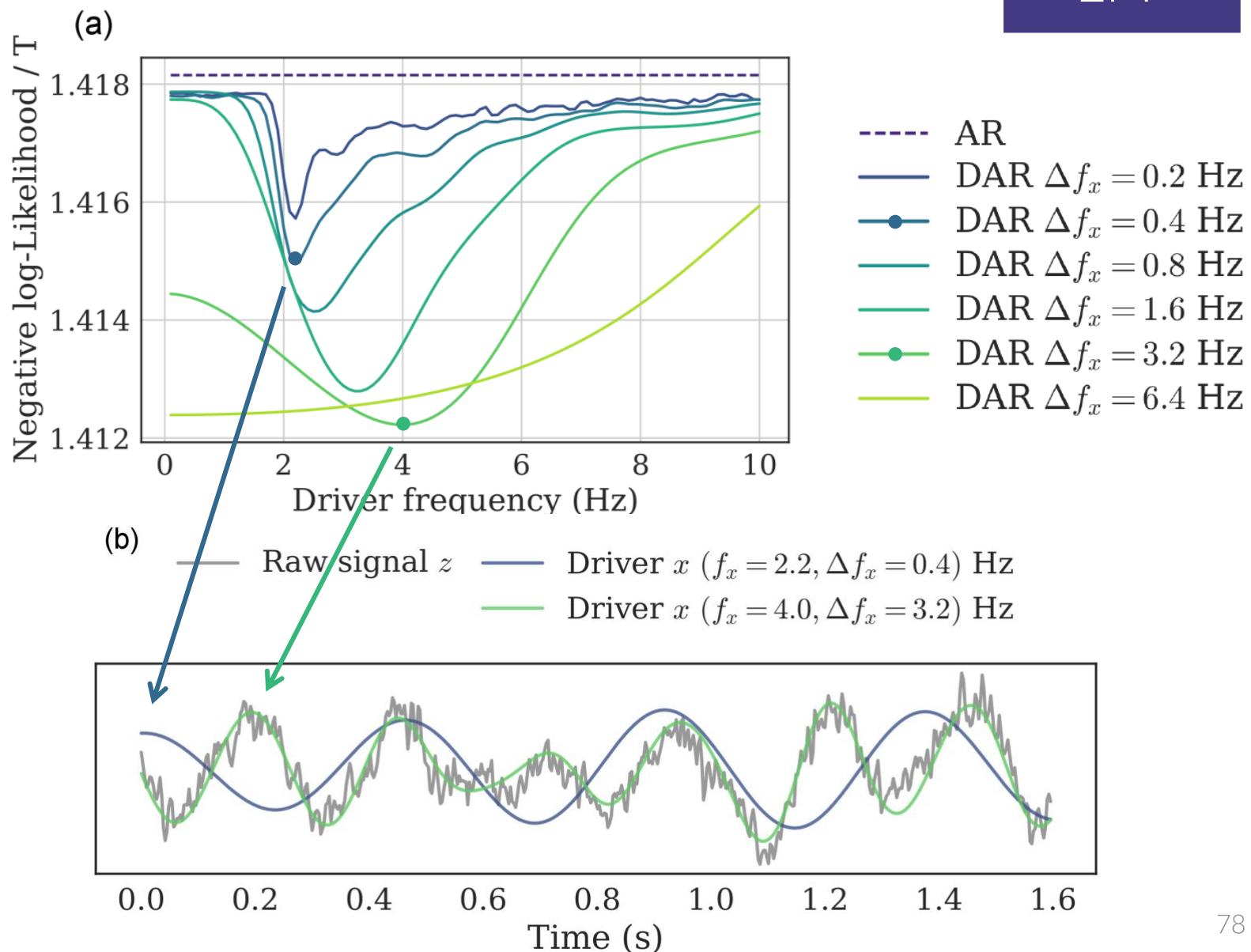
$$d = (p+1)(m+1)$$

- Testing the limits

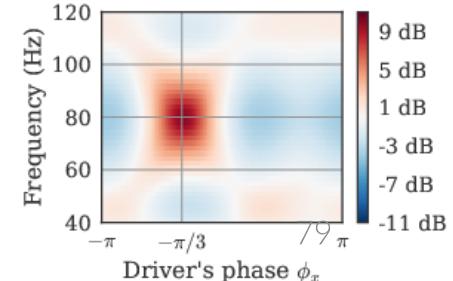
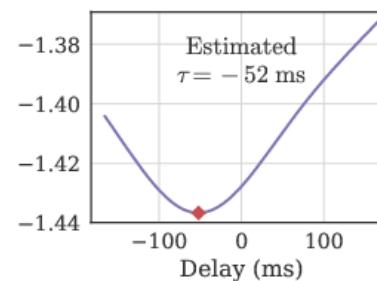
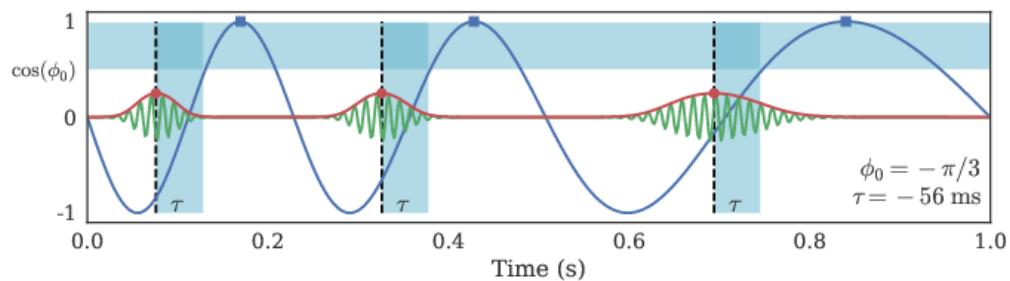
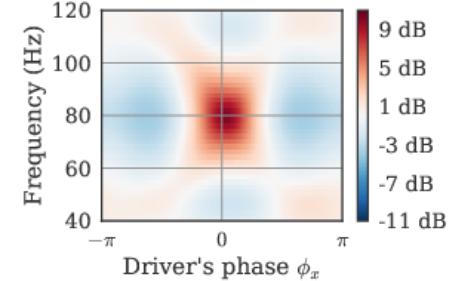
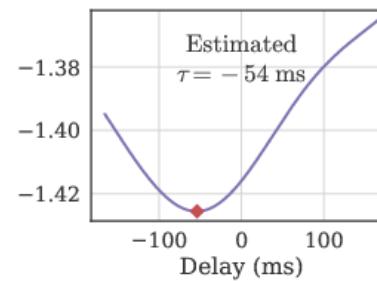
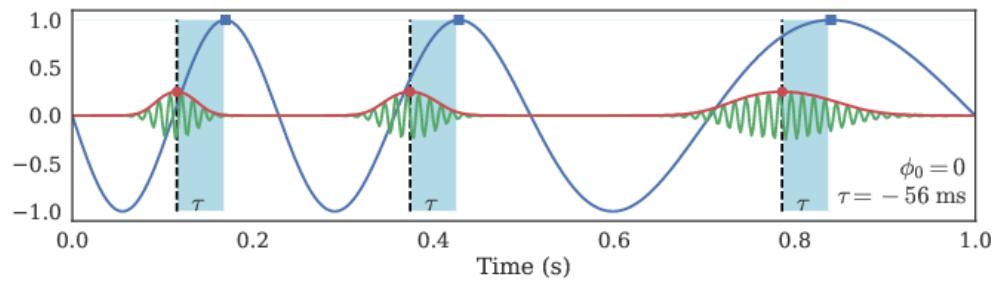
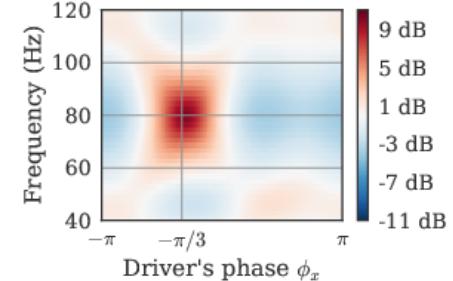
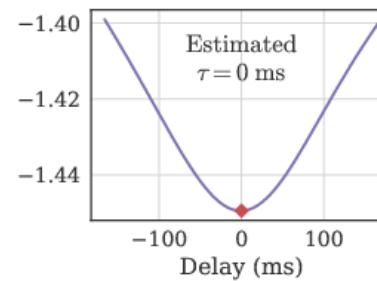
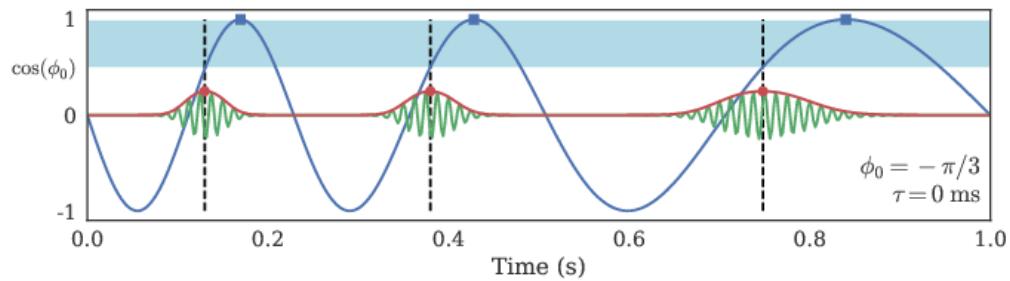
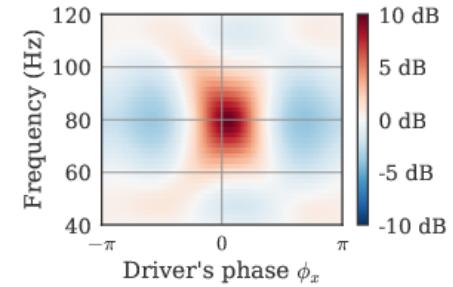
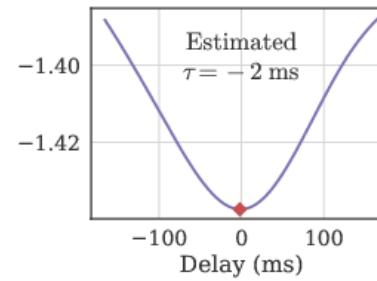
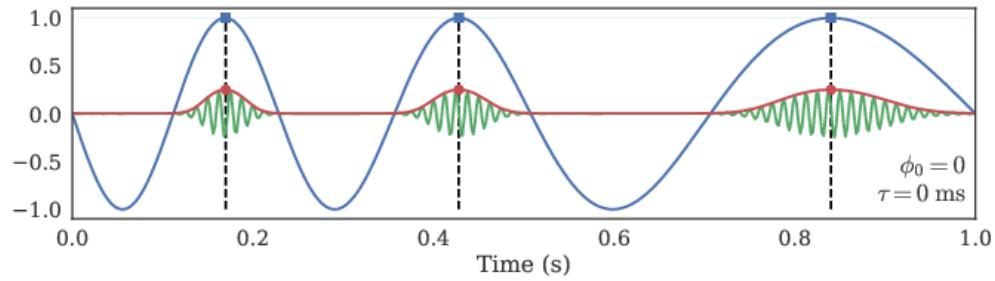


# Driver selection

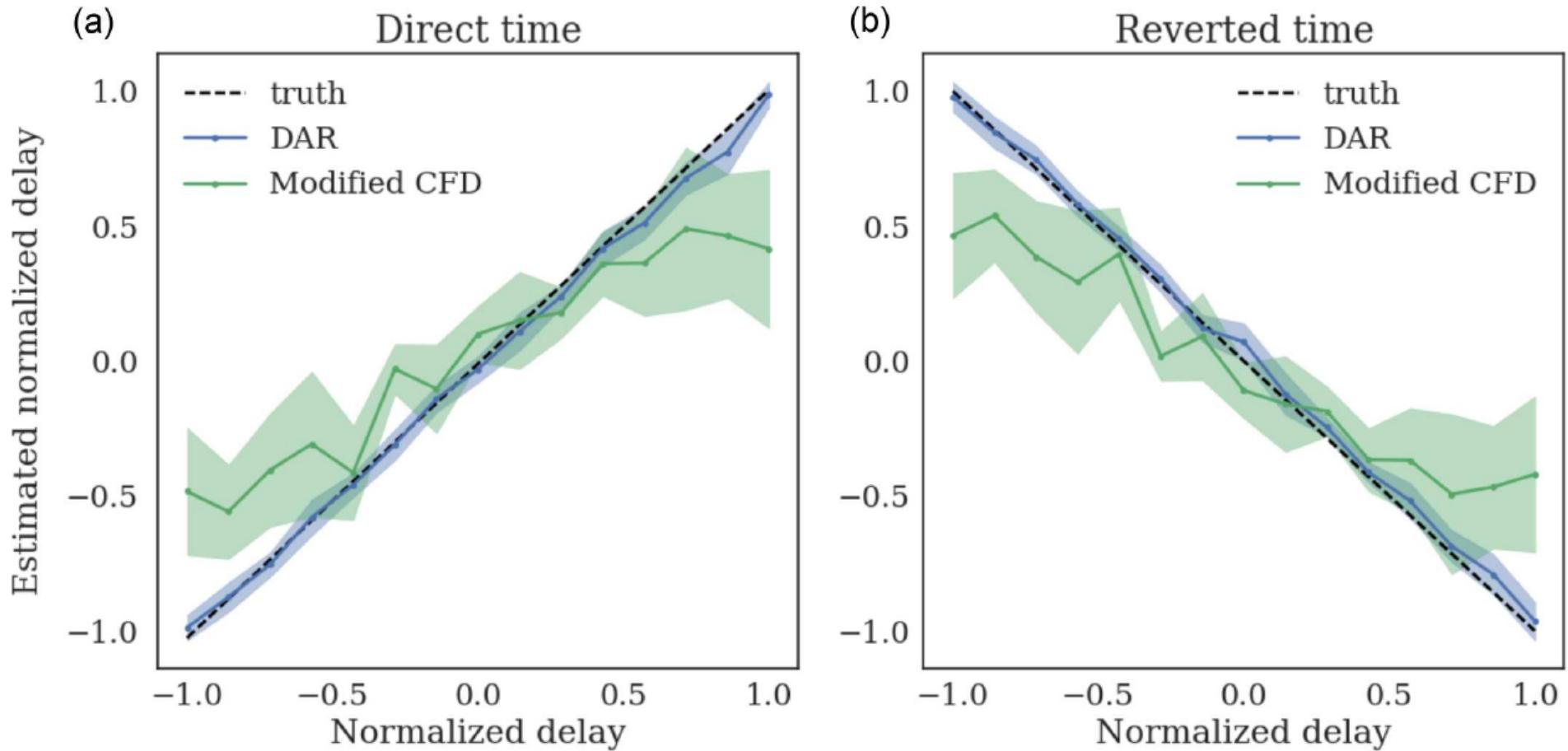
LFP



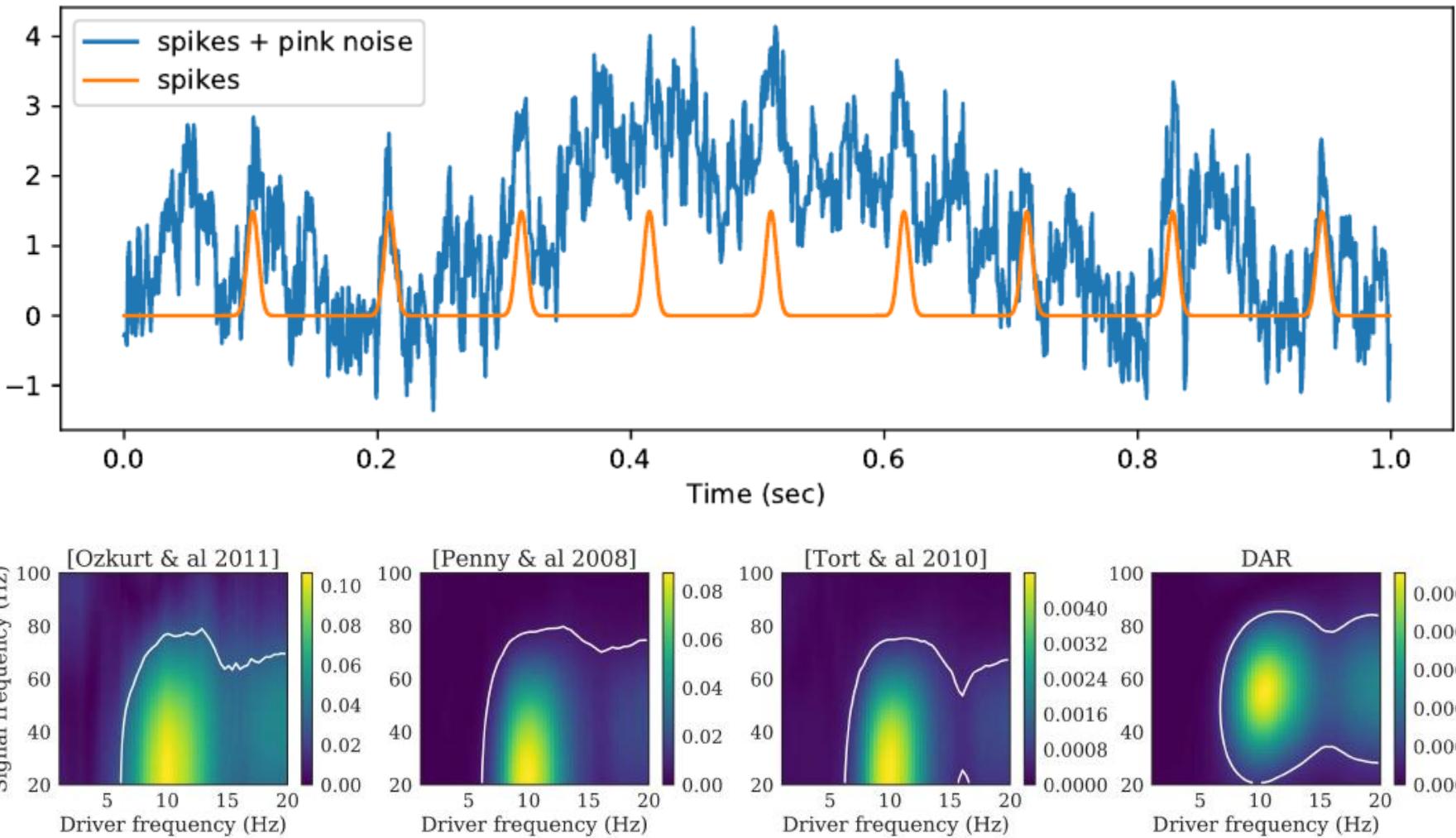
# Time delay and preferred phase



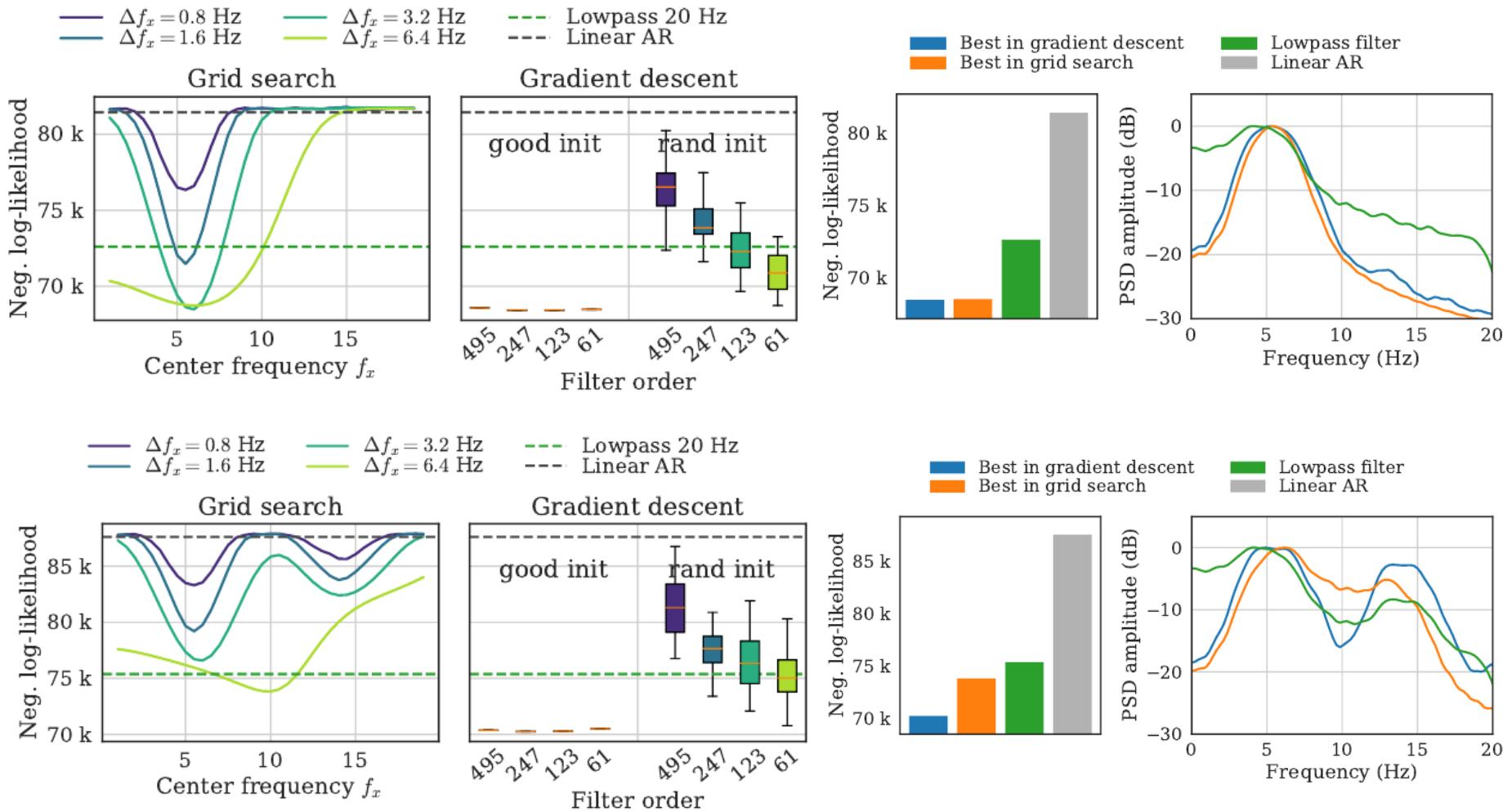
# Delay estimation on simulations



# Spurious CFC simulation

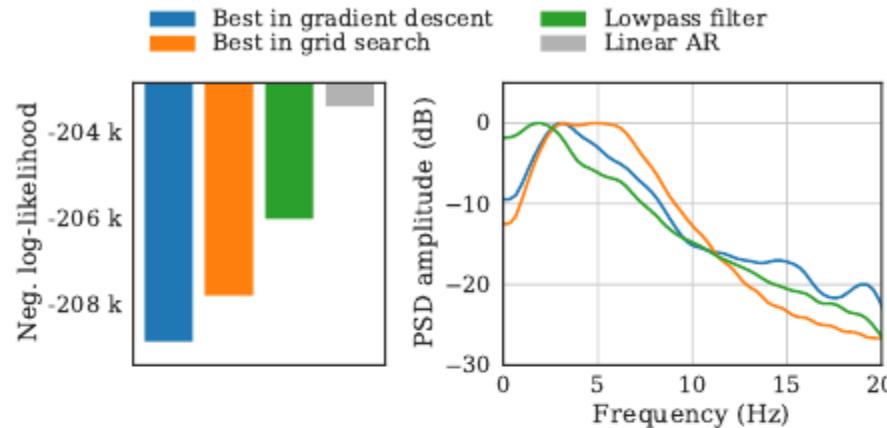


# Driver filter estimation

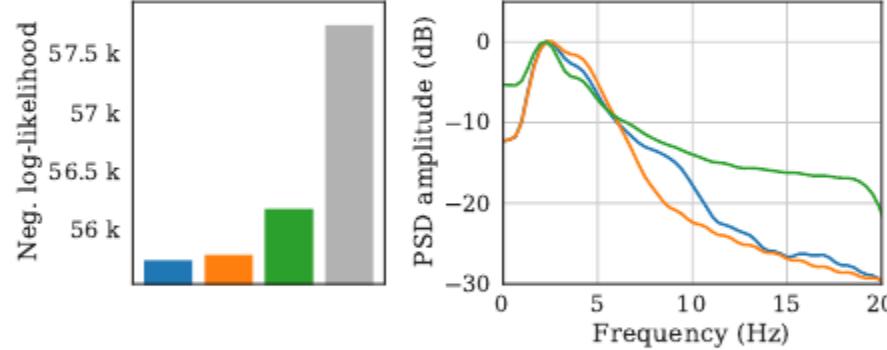


# Driver filter estimation

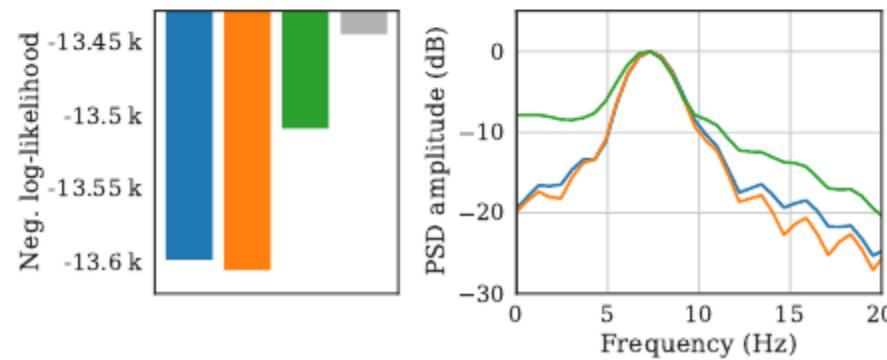
ECoG



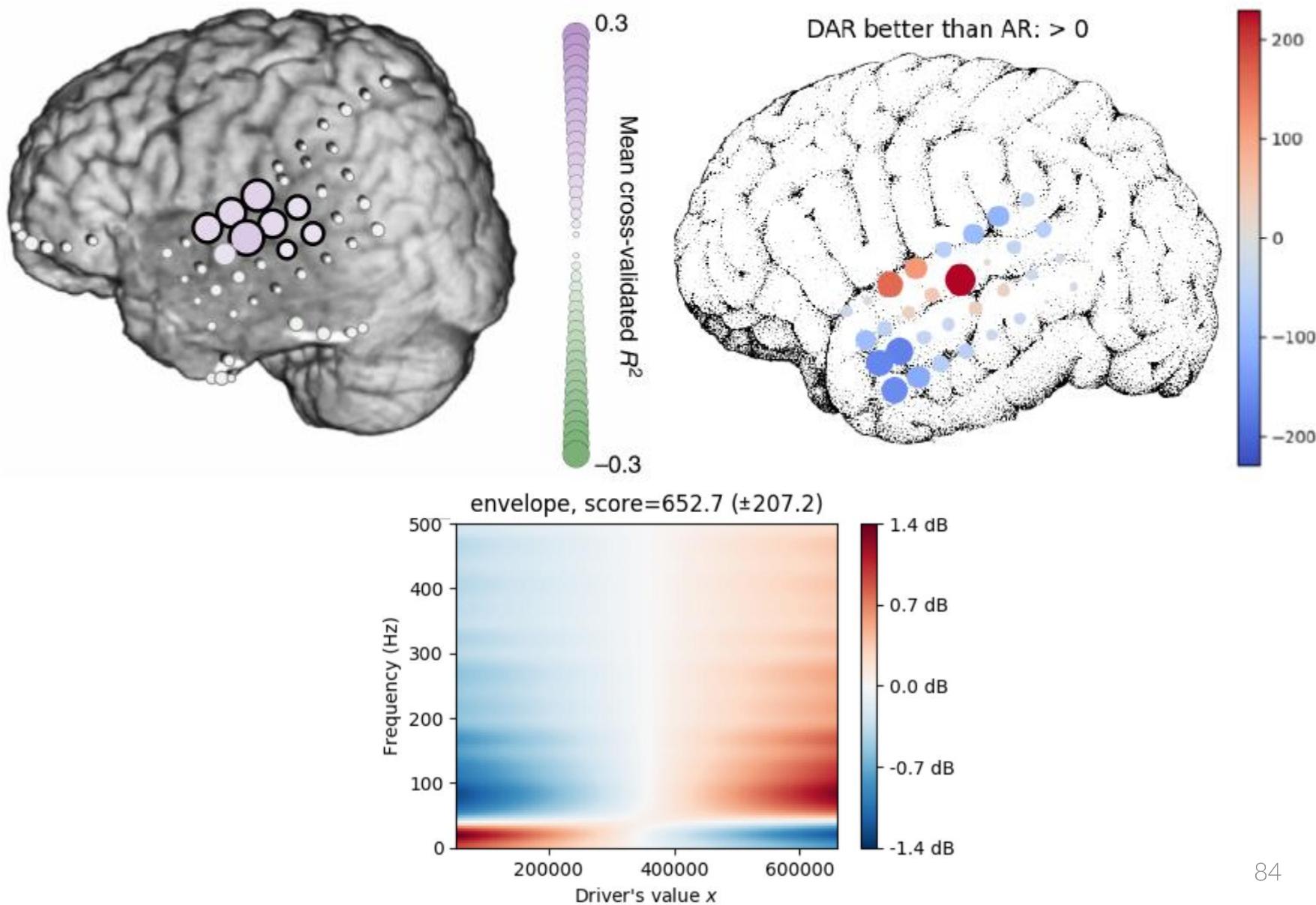
LFP



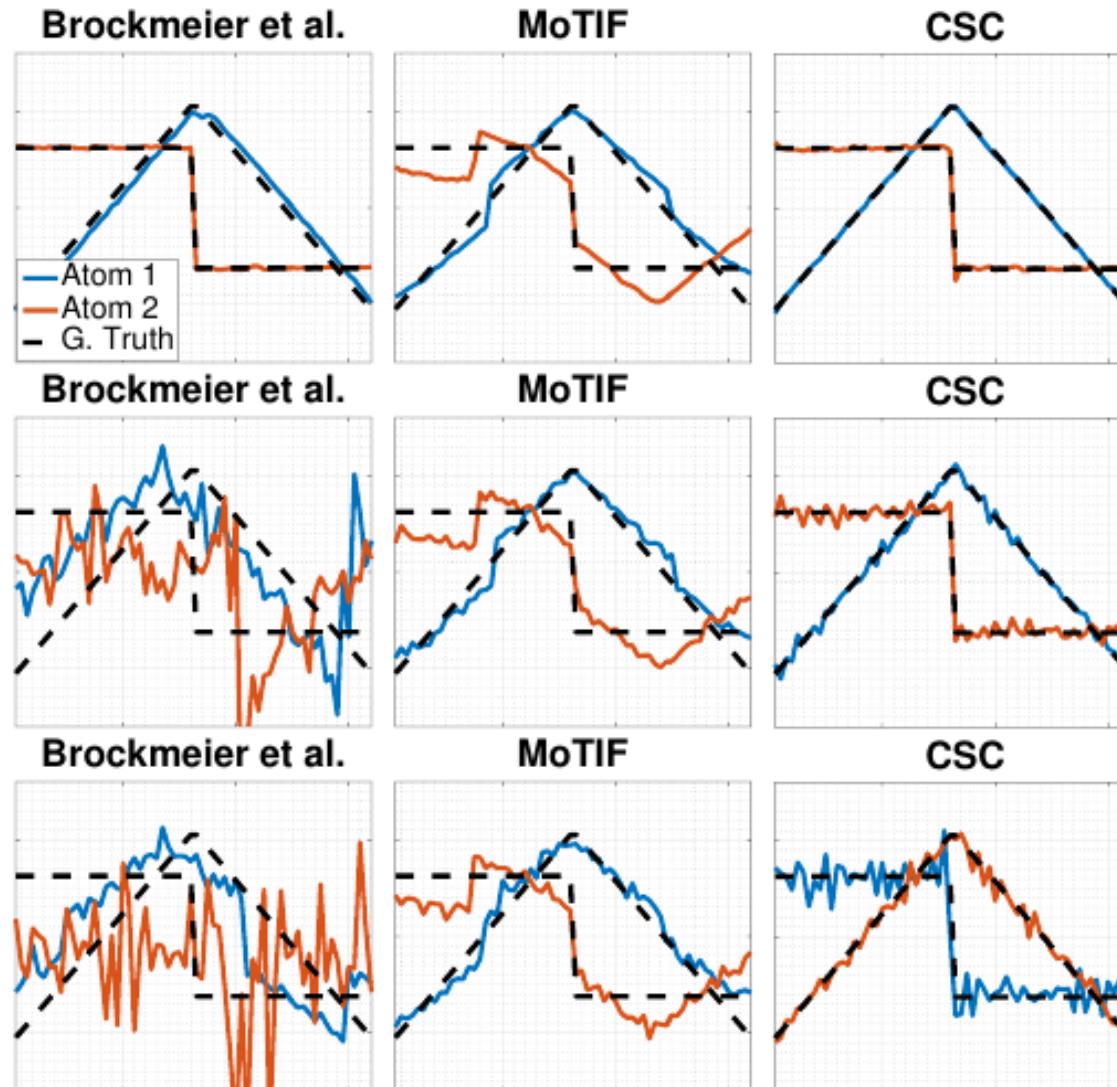
LFP



# Encoding DAR model



# Shift-invariant sparse coding comparison

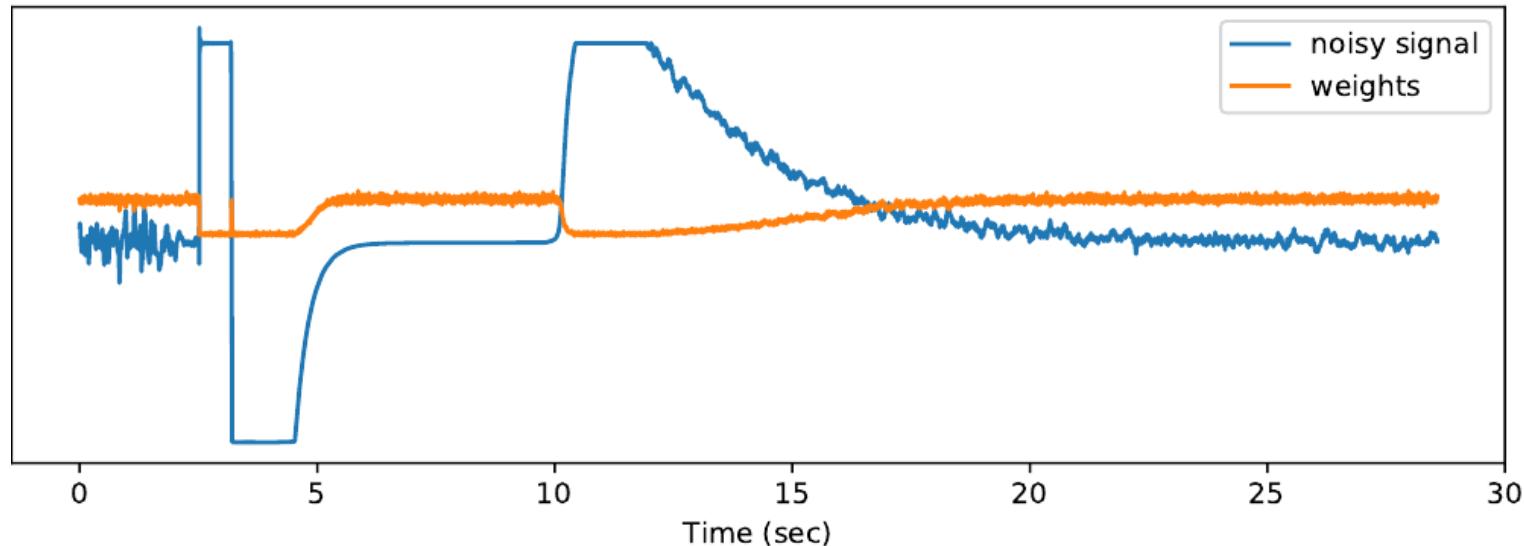


# Weights in alpha CSC

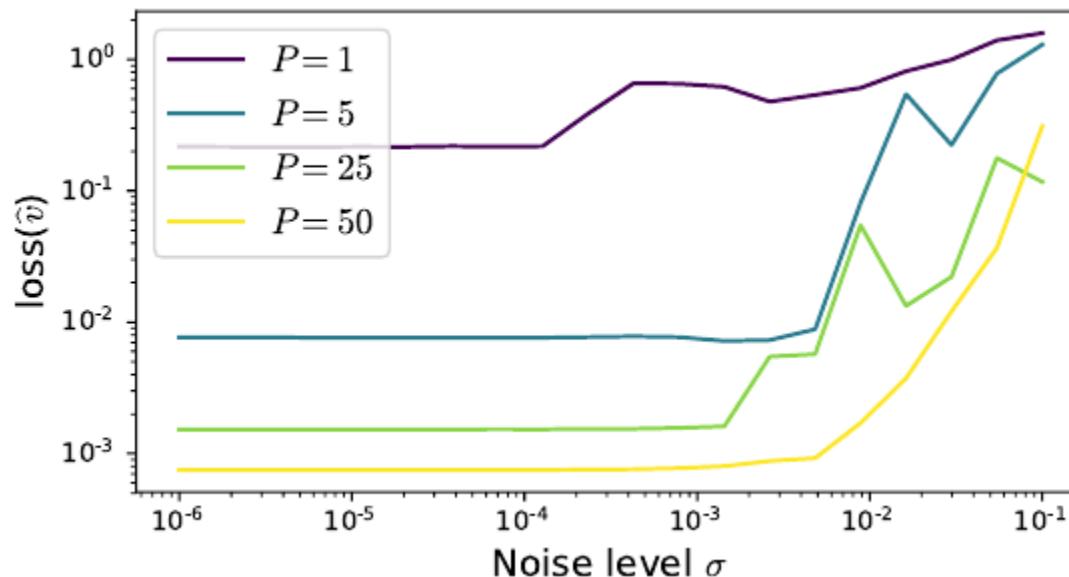
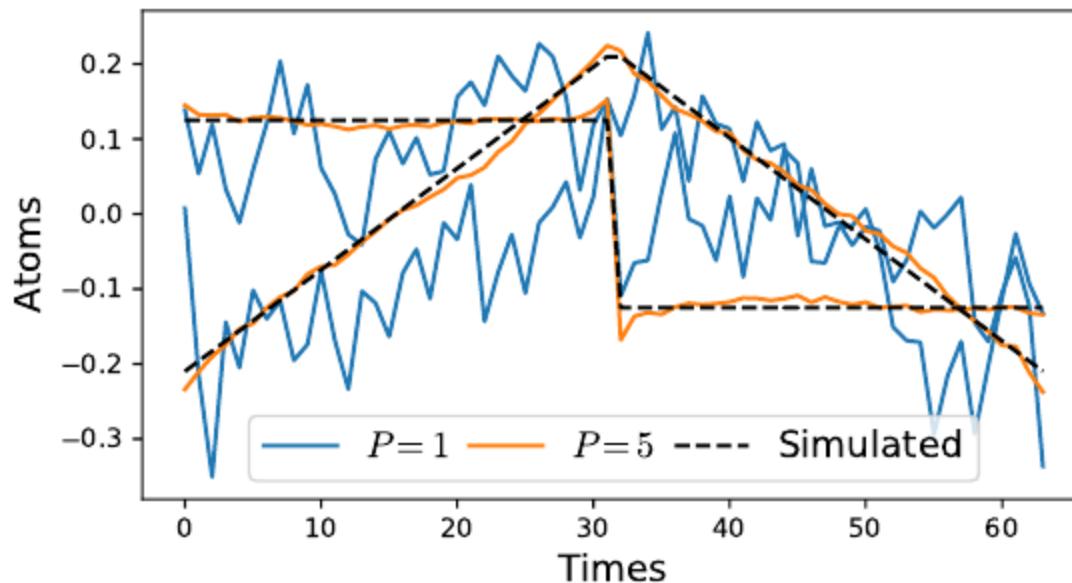
Expectation-Maximization algorithm

E-step

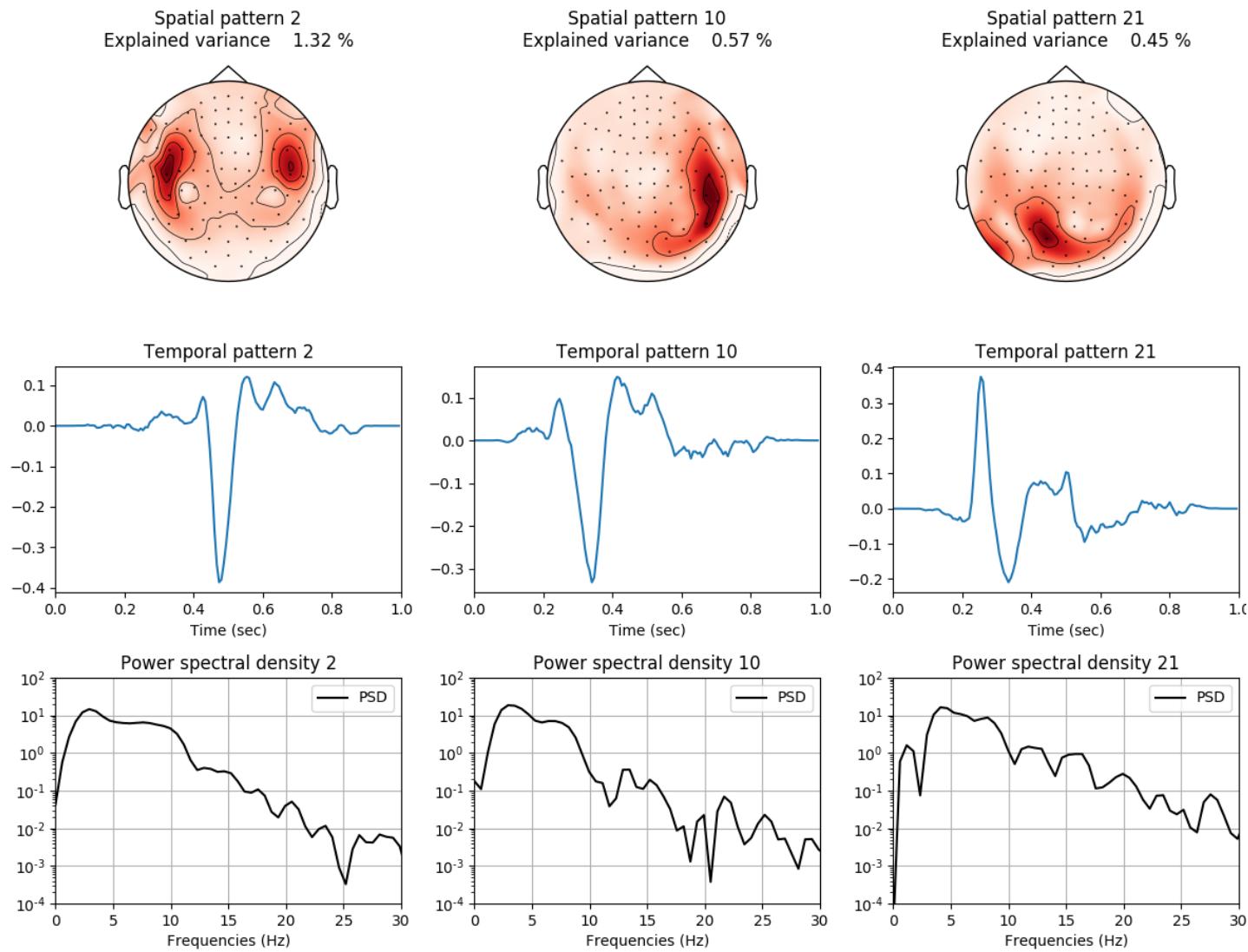
$$w^n[t]^{(i)} \triangleq \mathbb{E} \left[ 1/\phi^n[t] \right]_{p(\phi|x, z^{(i)}, d^{(i)})}$$

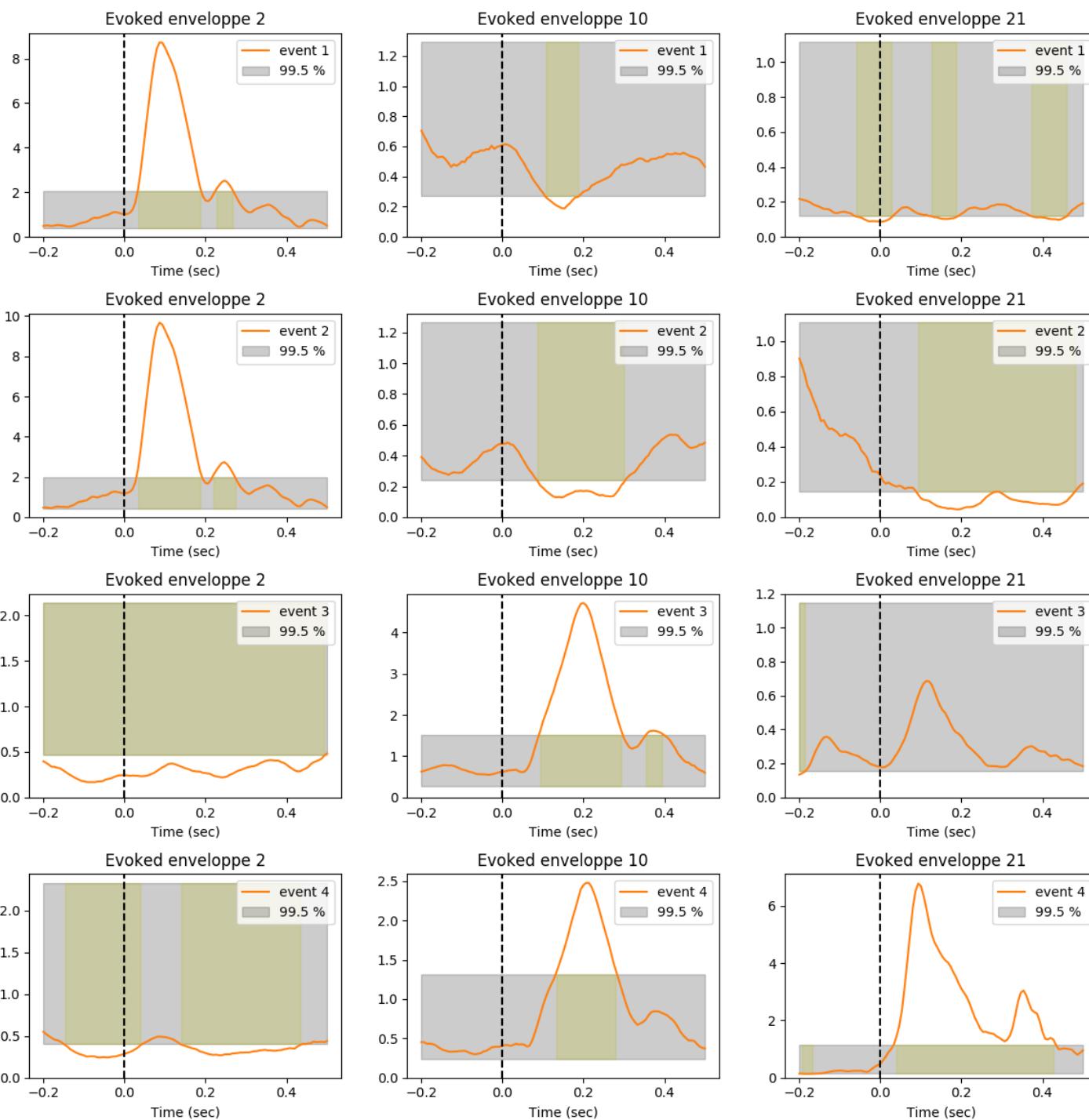


# Simulations on multivariate CSC

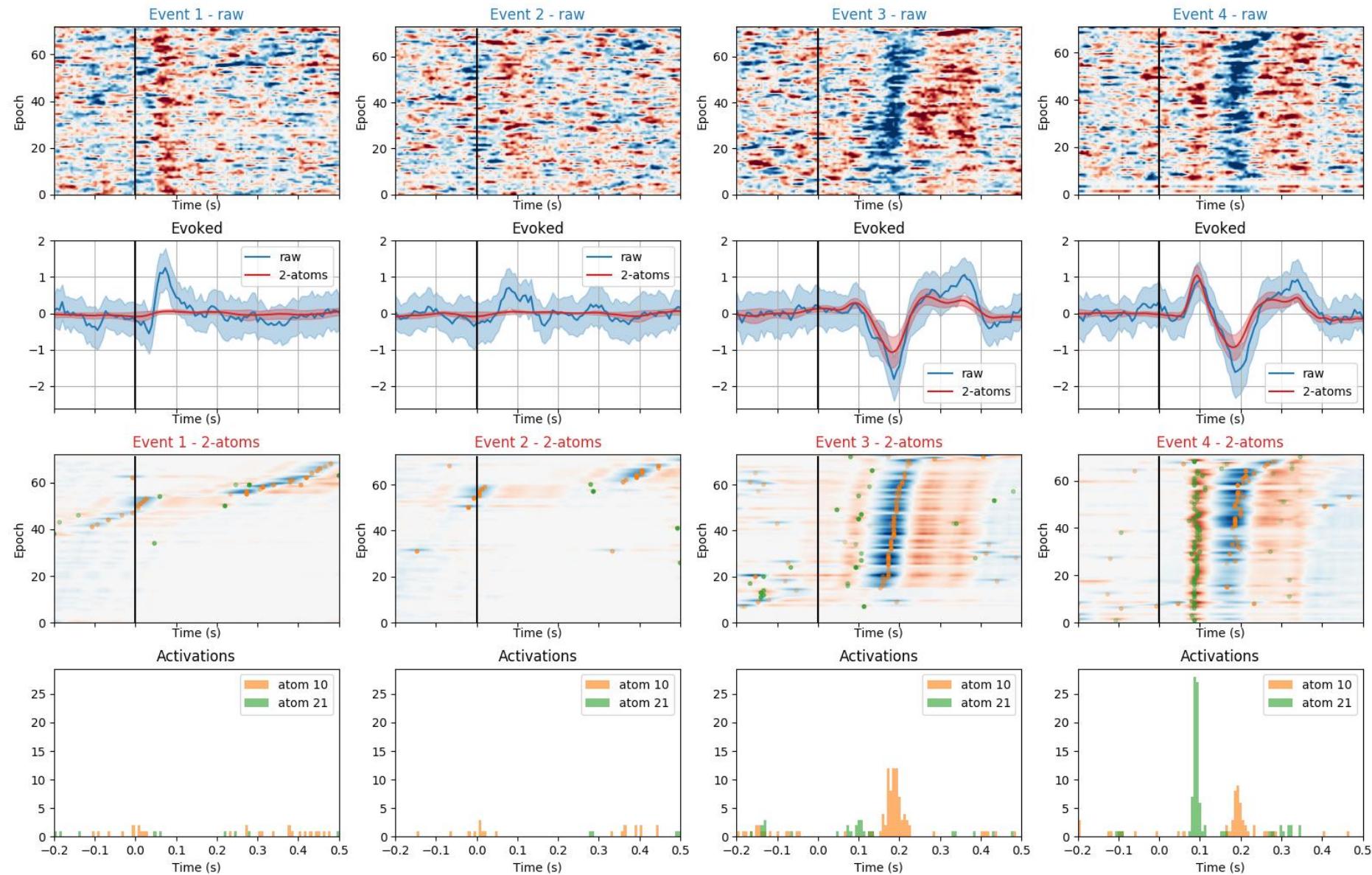


# Event-related atoms

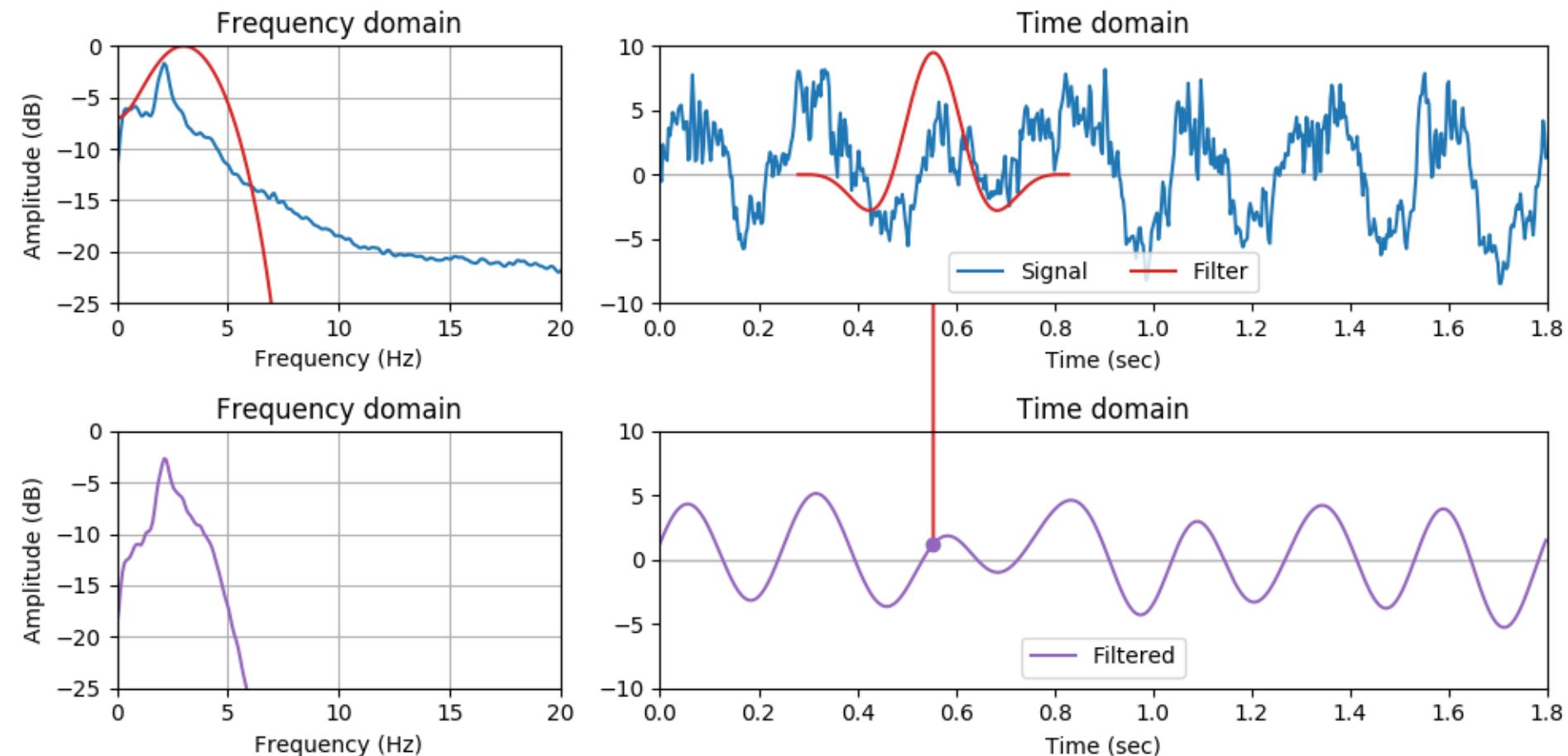




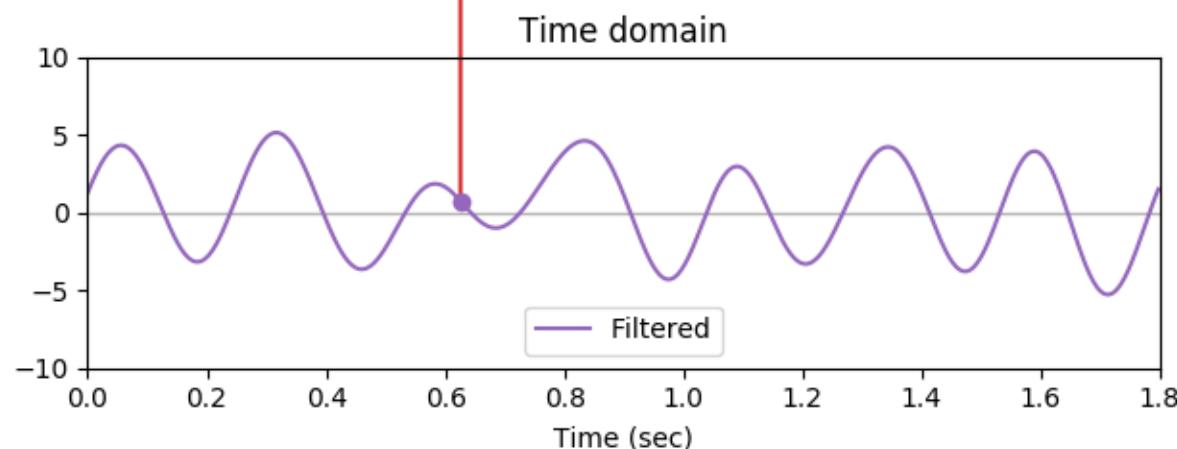
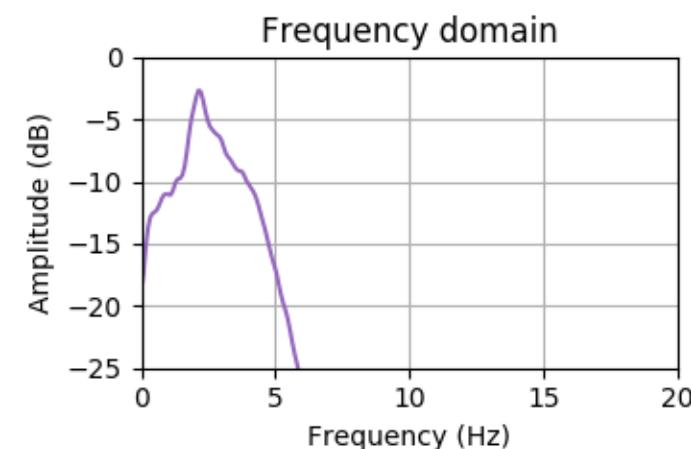
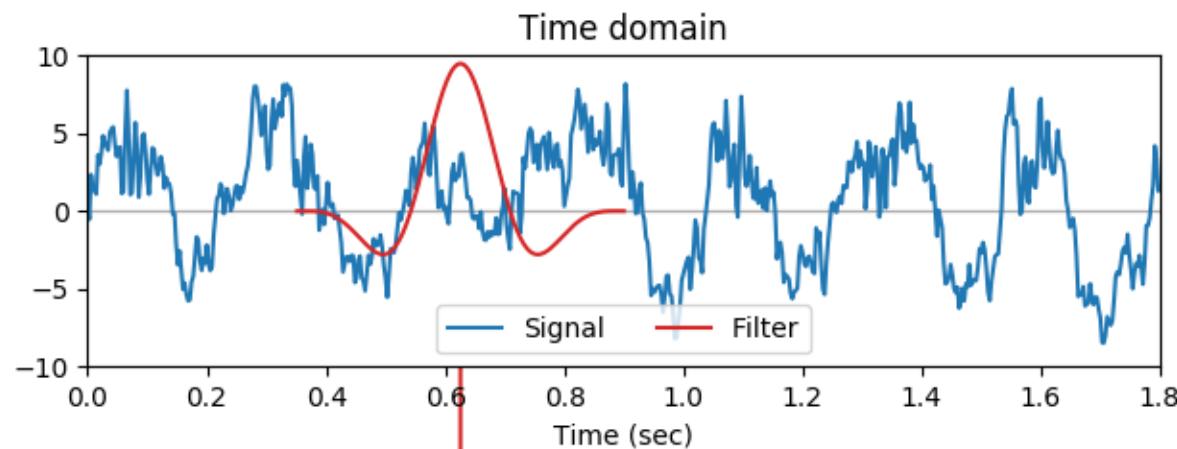
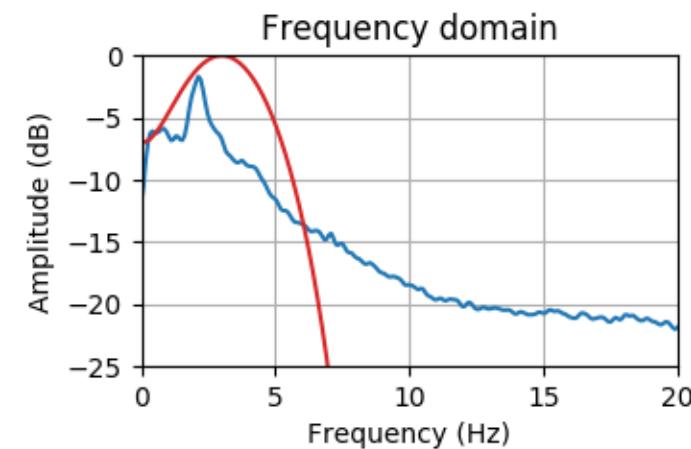
# Event-related activations



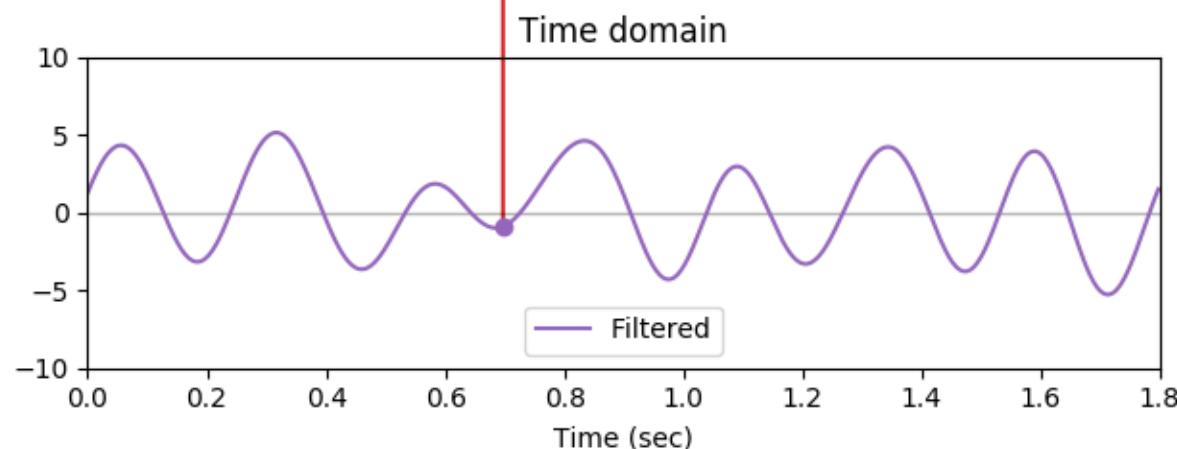
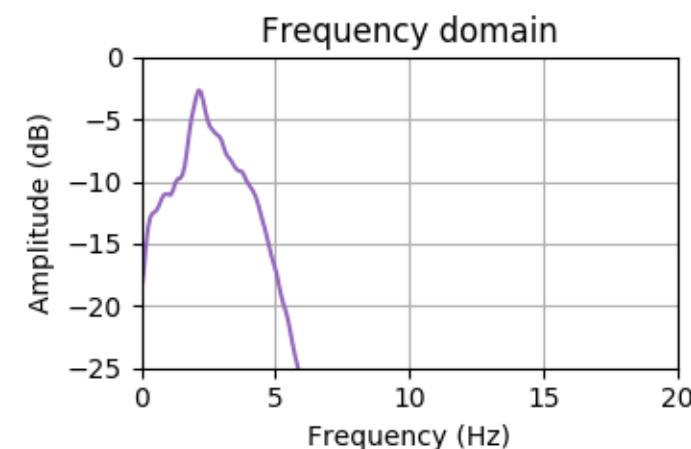
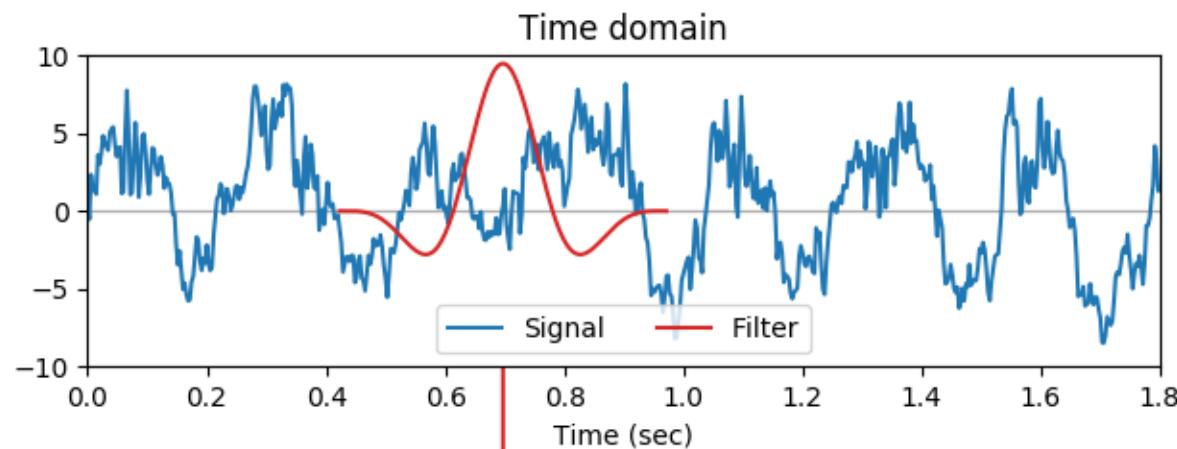
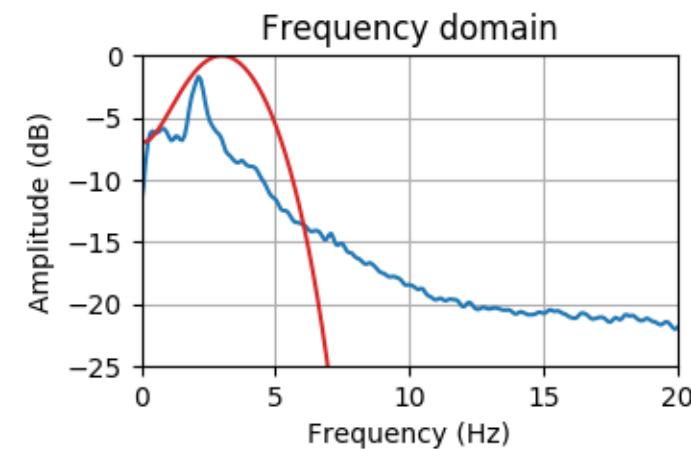
# Narrow-band linear filtering



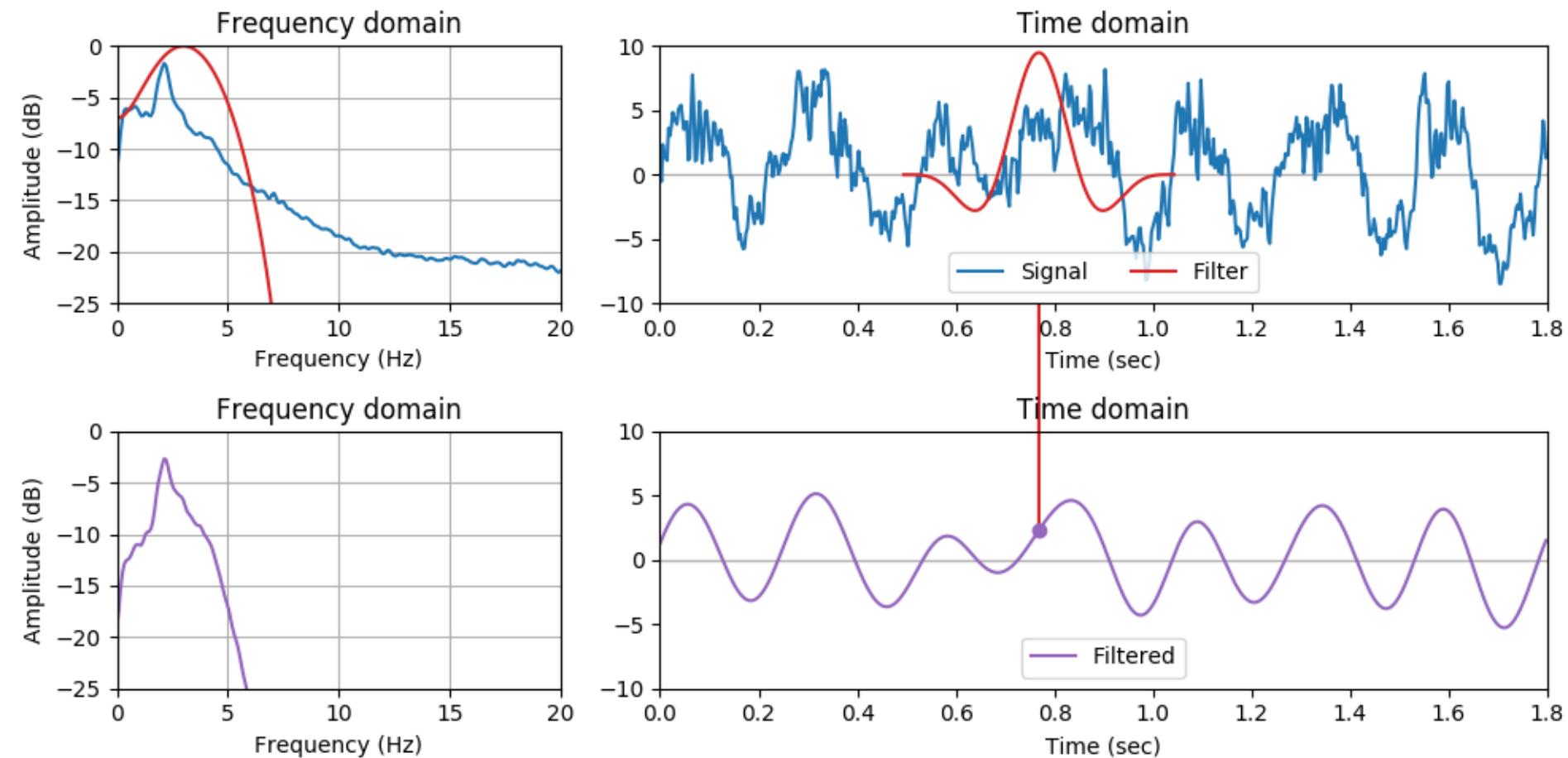
# Narrow-band linear filtering



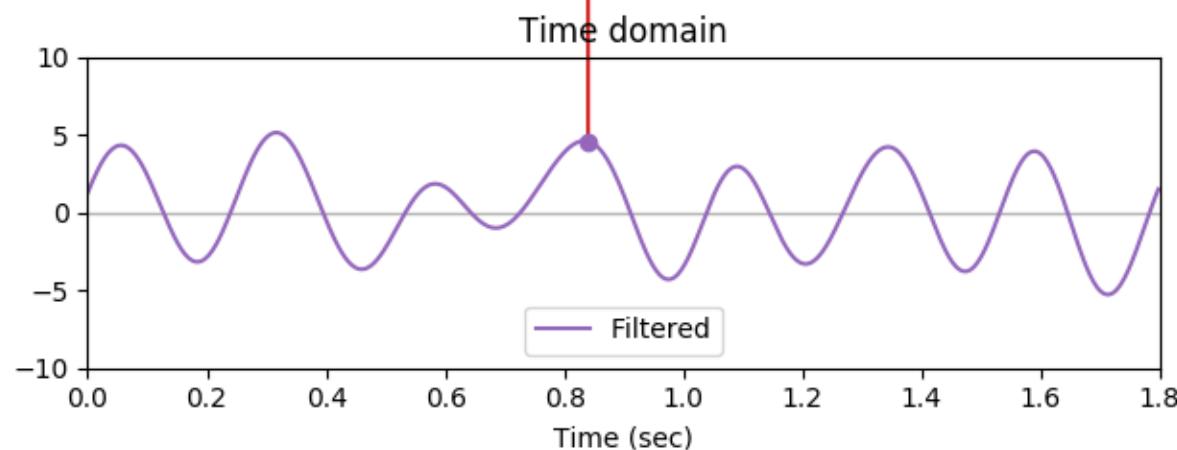
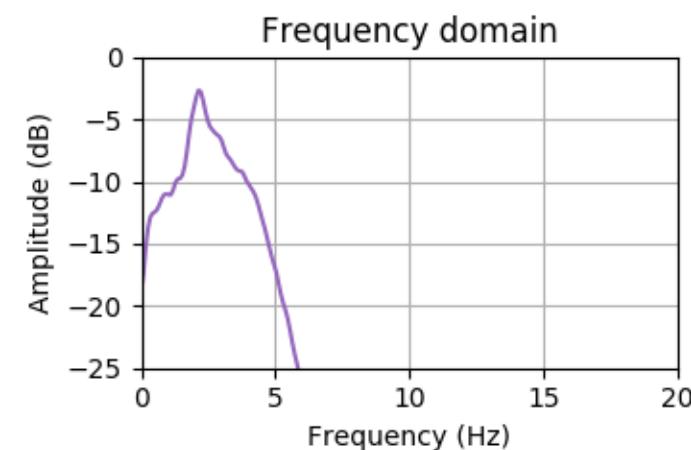
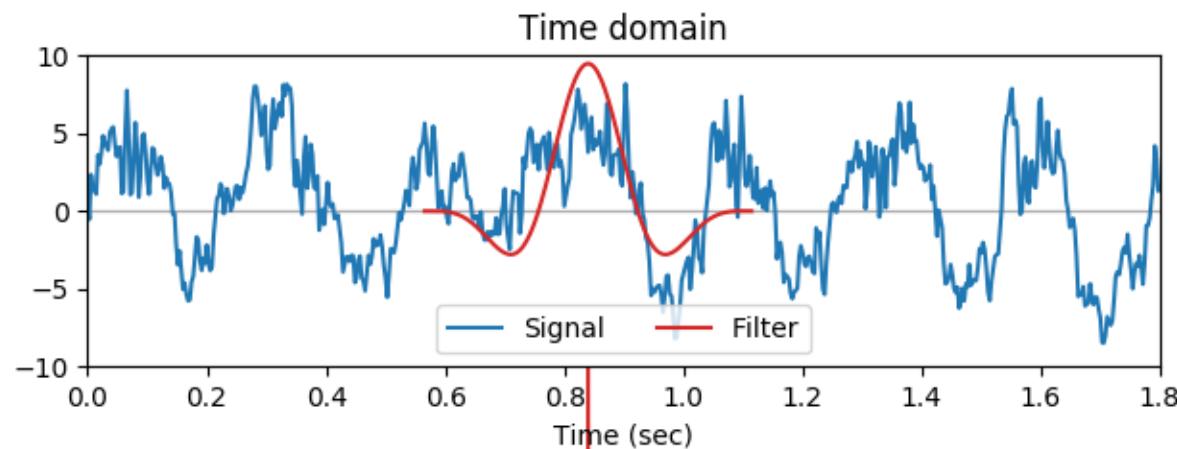
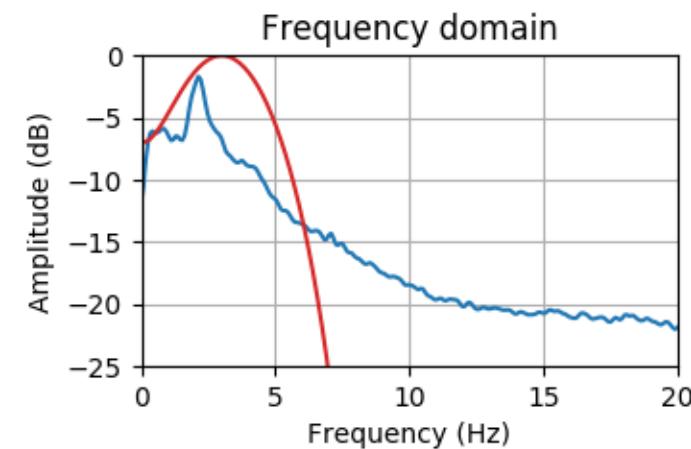
# Narrow-band linear filtering



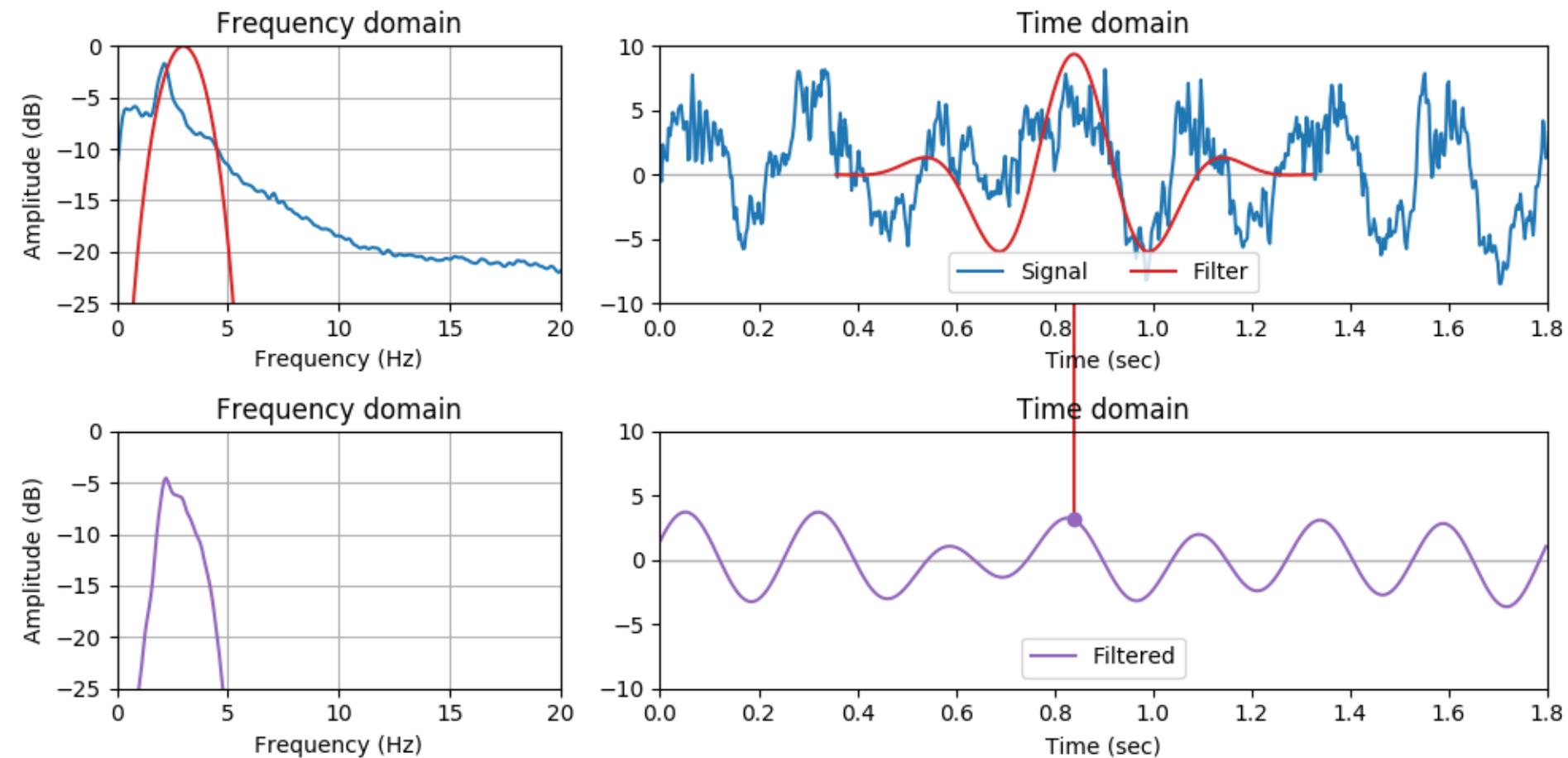
# Narrow-band linear filtering



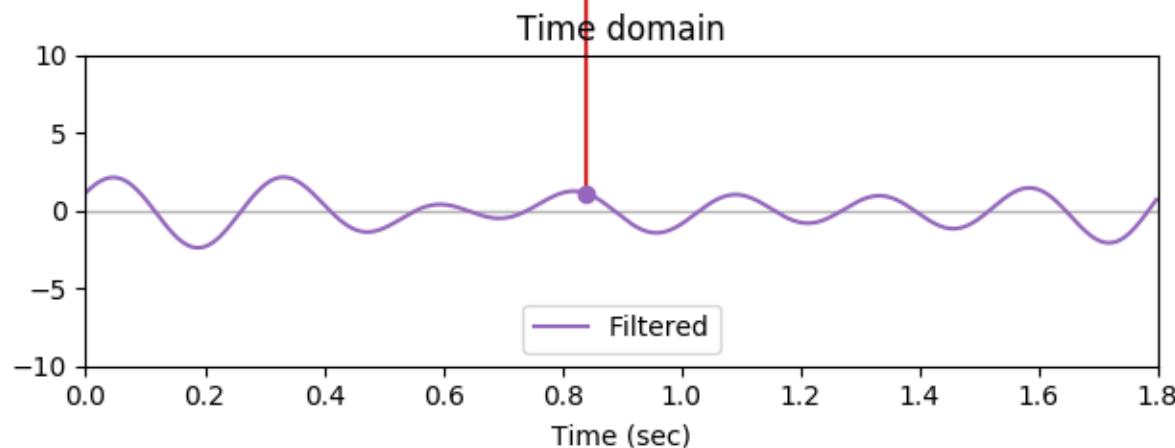
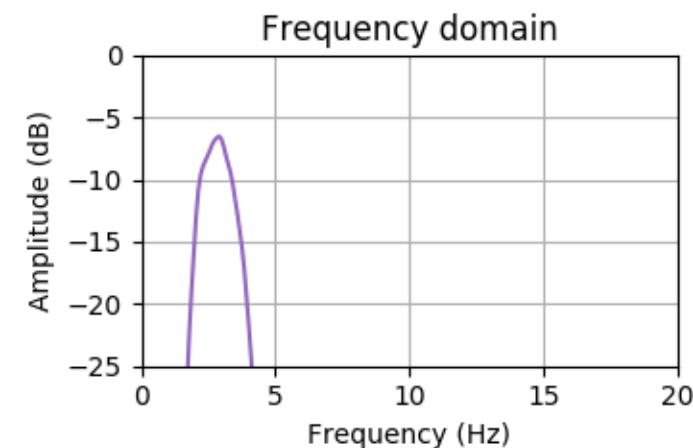
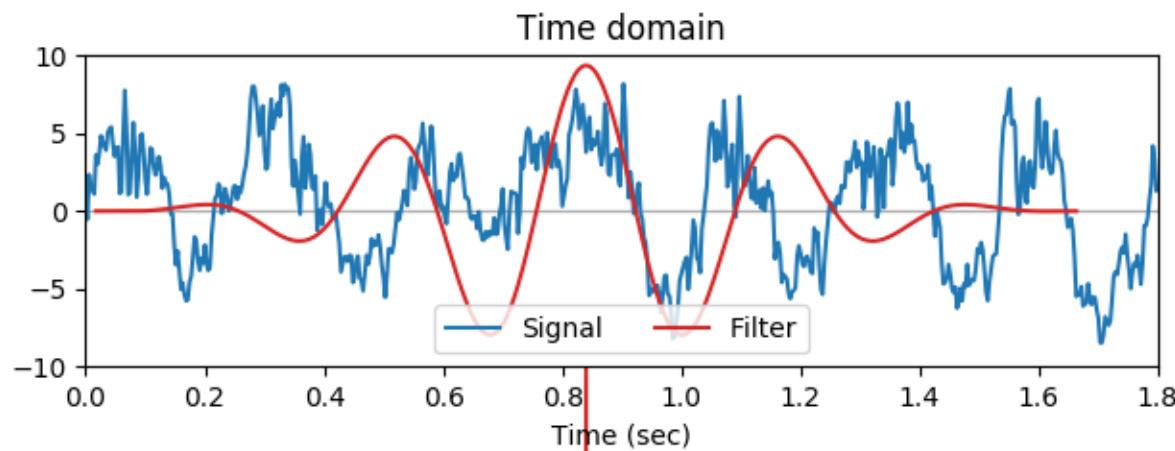
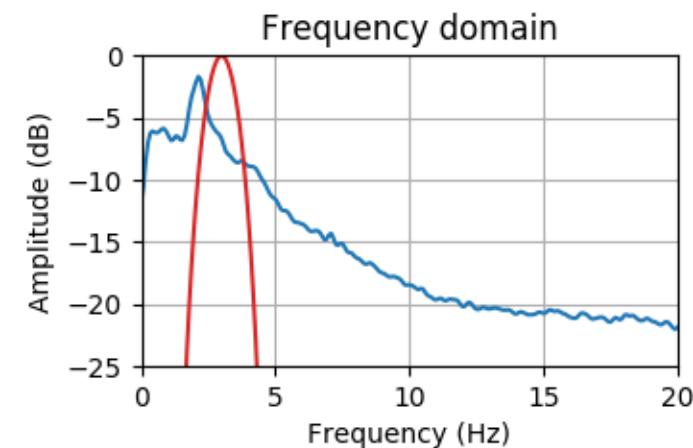
# Narrow-band linear filtering



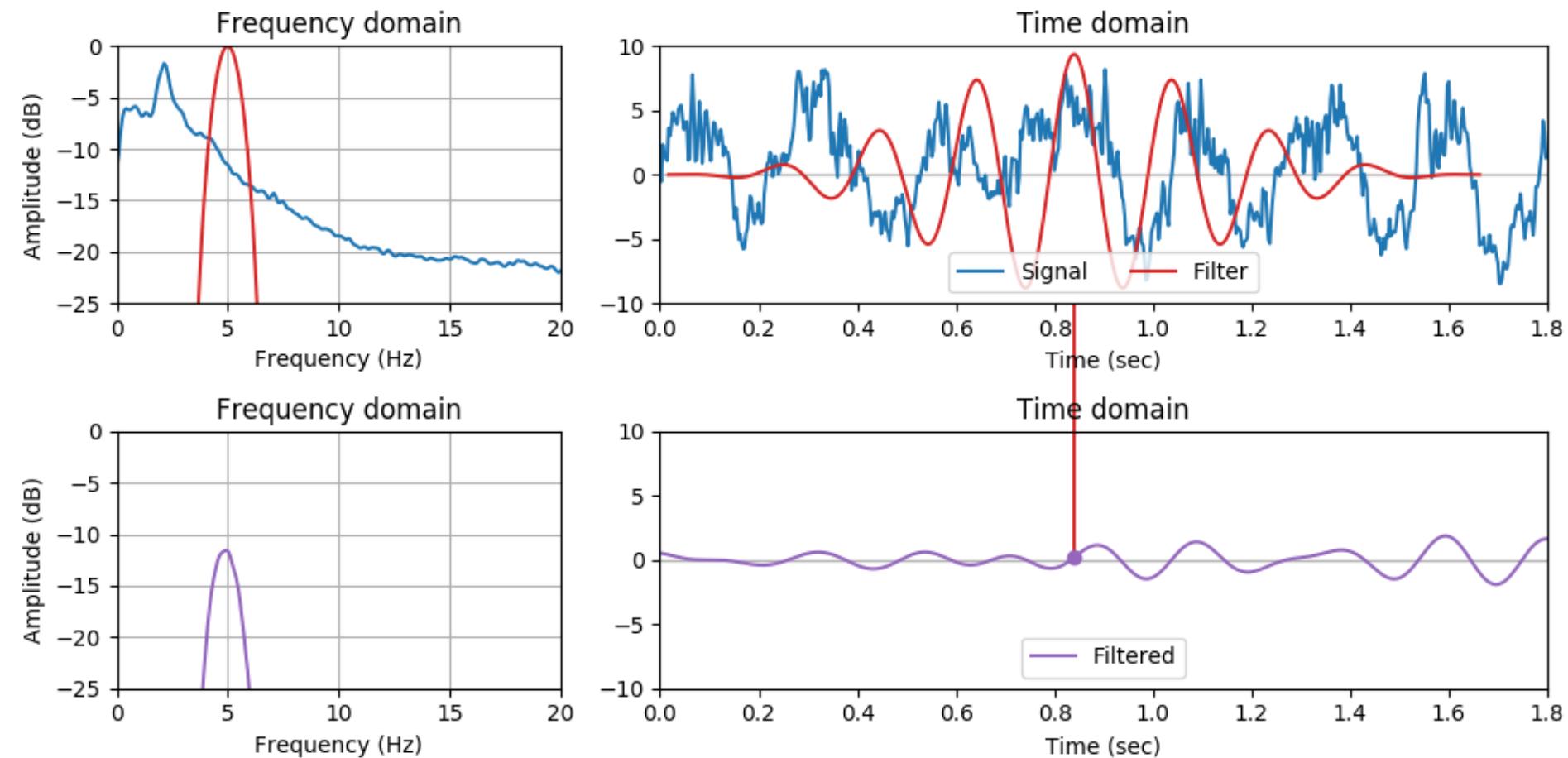
# Narrow-band linear filtering



# Narrow-band linear filtering



# Narrow-band linear filtering



# Narrow-band linear filtering

