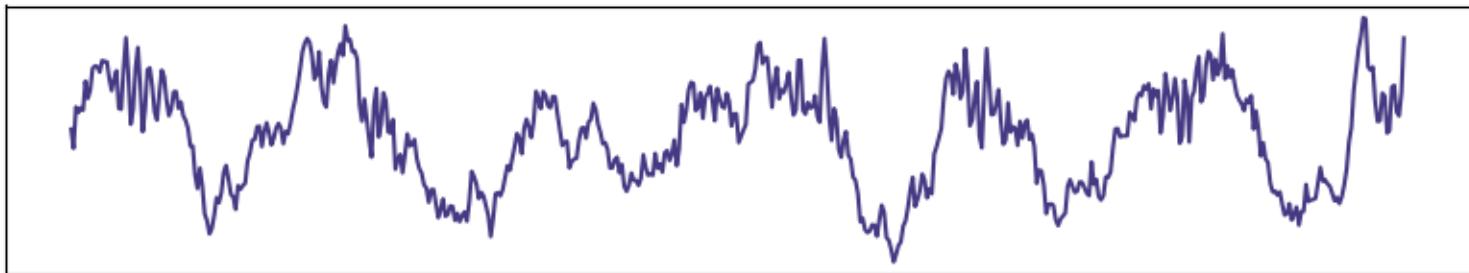


NON-LINEAR MODELS FOR NEUROPHYSIOLOGICAL TIME SERIES

Tom Dupré la Tour

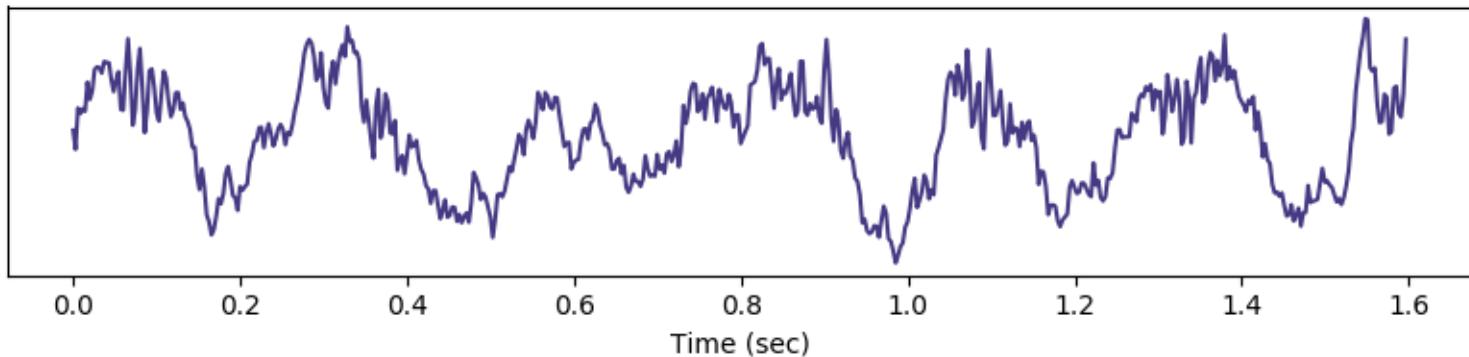
PhD Defense – 26 Nov 2018



NON-LINEAR MODELS FOR NEUROPHYSIOLOGICAL TIME SERIES

Tom Dupré la Tour

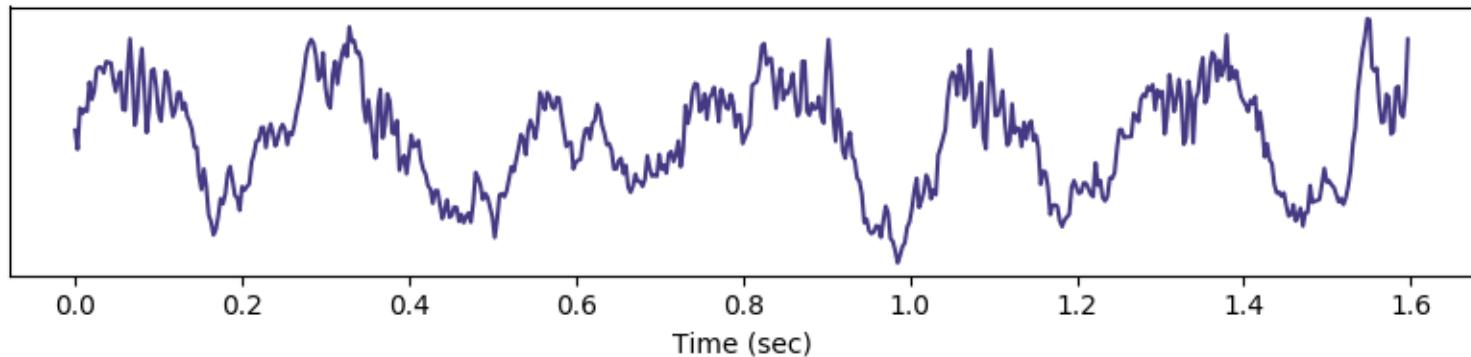
PhD Defense – 26 Nov 2018



Neurophysiological time series

Local field potential (LFP)

Example: LFP in rodent striatum

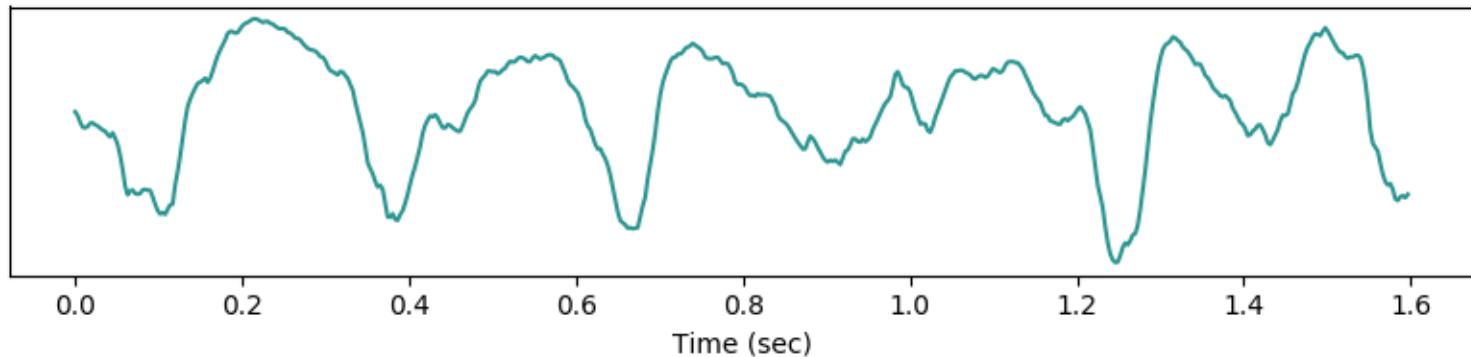


Neurophysiological time series

Local field potential (LFP)

Electro-corticogram (ECoG)

Example: ECoG in human auditory cortex



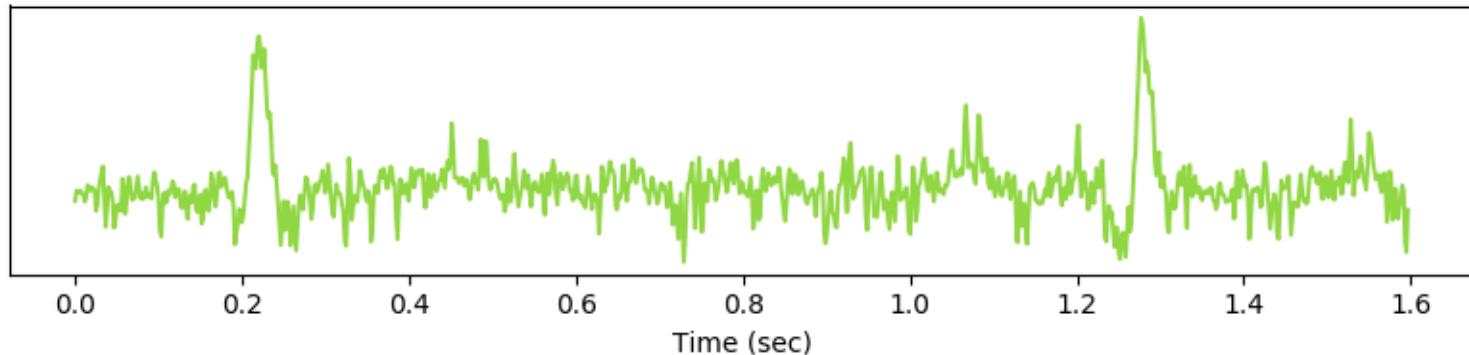
Neurophysiological time series

Local field potential (LFP)

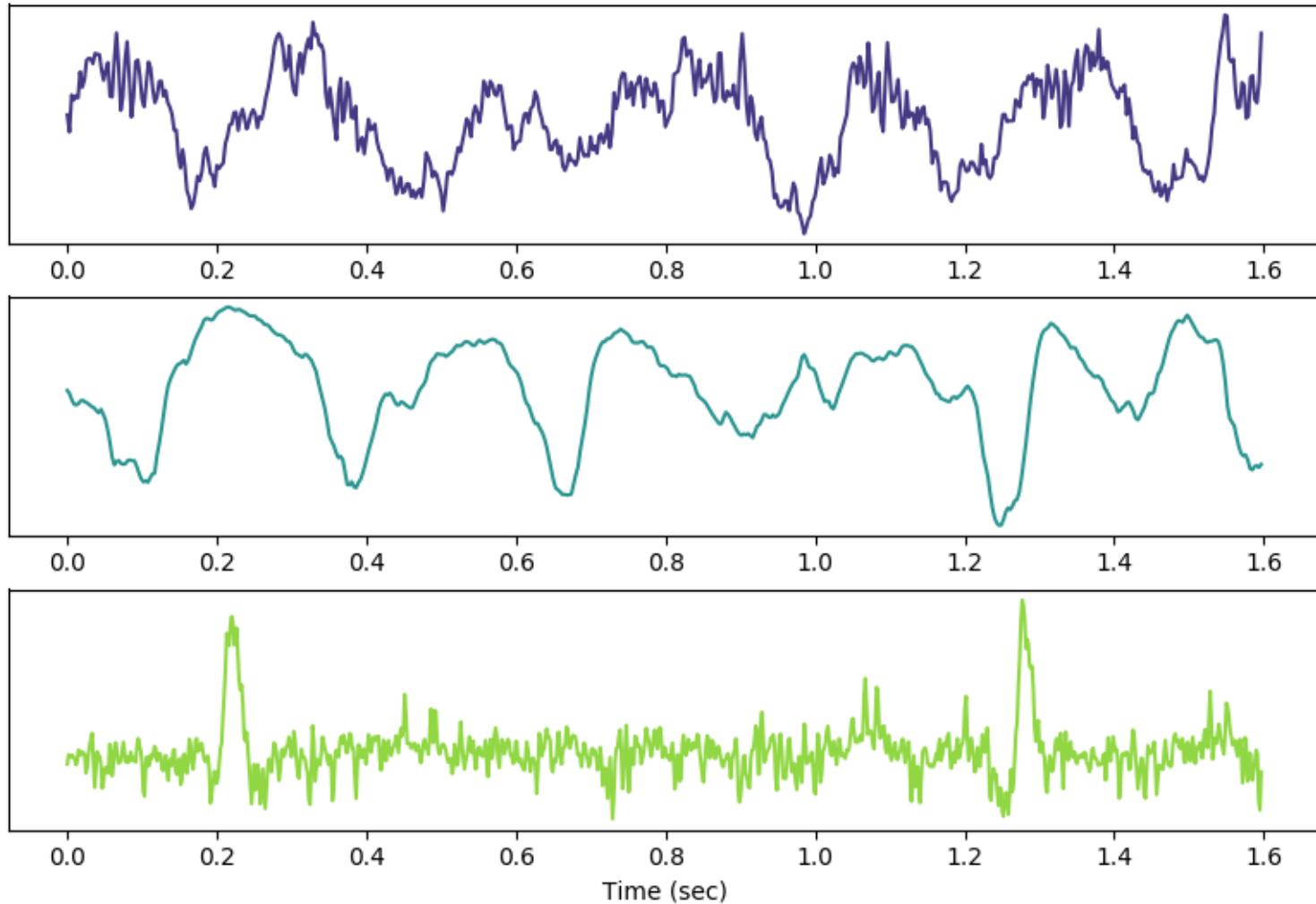
Electro-corticogram (ECoG)

Electro/Magneto-encephalogram (EEG/MEG)

Example: MEG in human

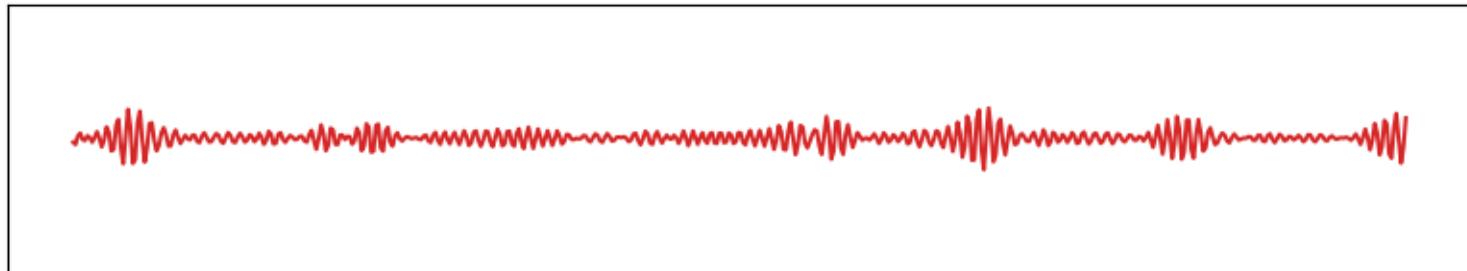
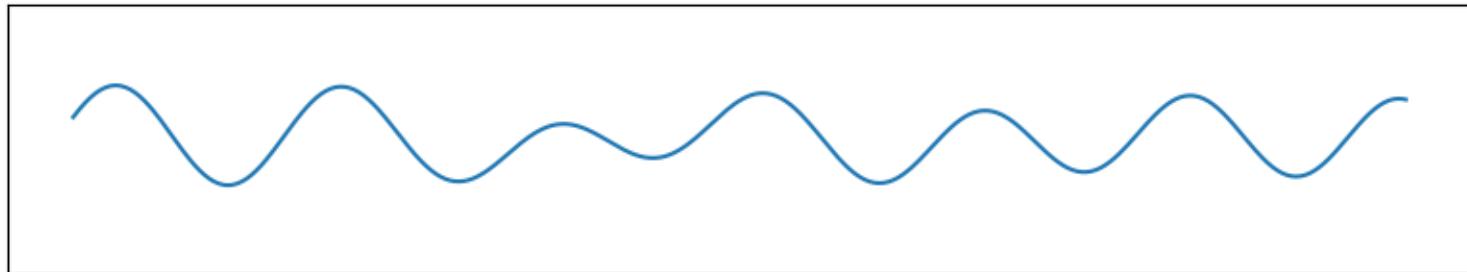
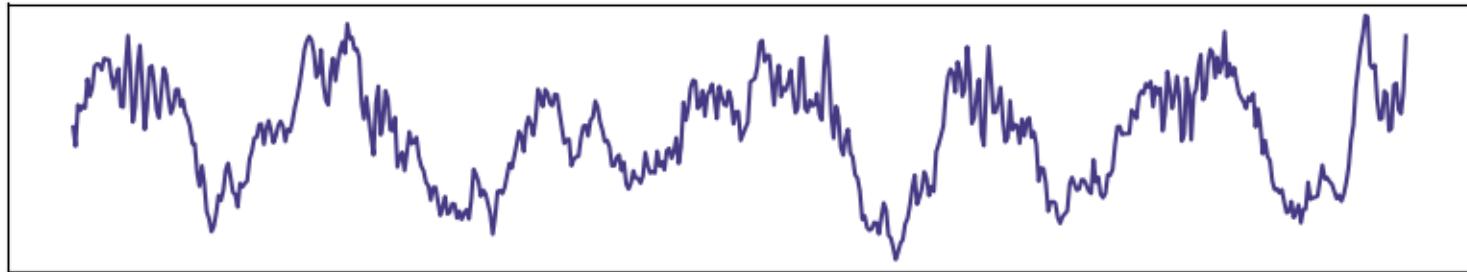


Neurophysiological time series



Narrow-band representation

LFP



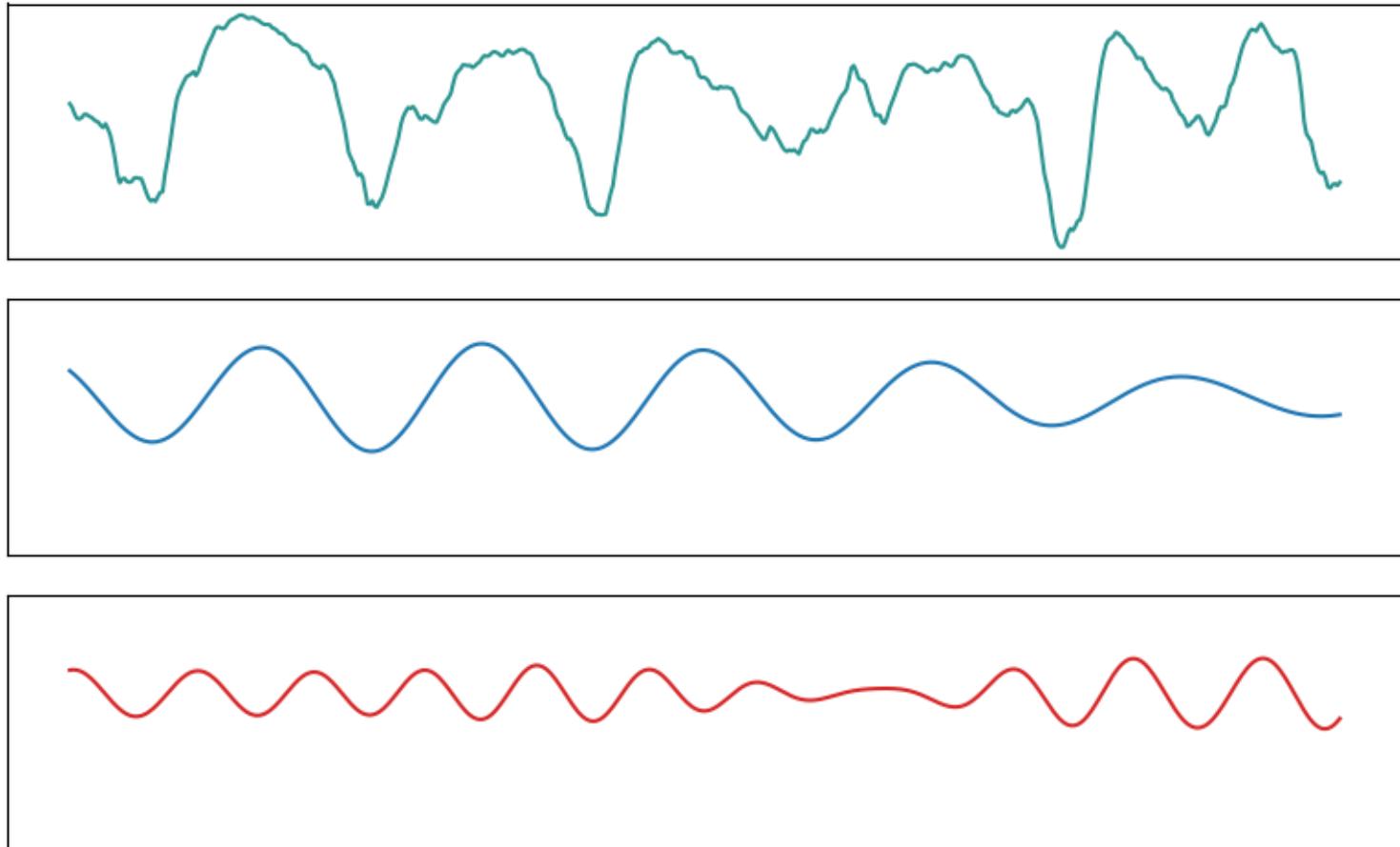
Fourier fallacy

«Even though it may be possible to analyze the complex forms of brain waves into **a number of different sine-wave** frequencies, this may lead only to what might be termed a “**Fourier fallacy**”, if one assumes *ad hoc* that all of the necessary frequencies actually occur as periodic phenomena in **cell groups** within the brain. »

Jasper, 1948

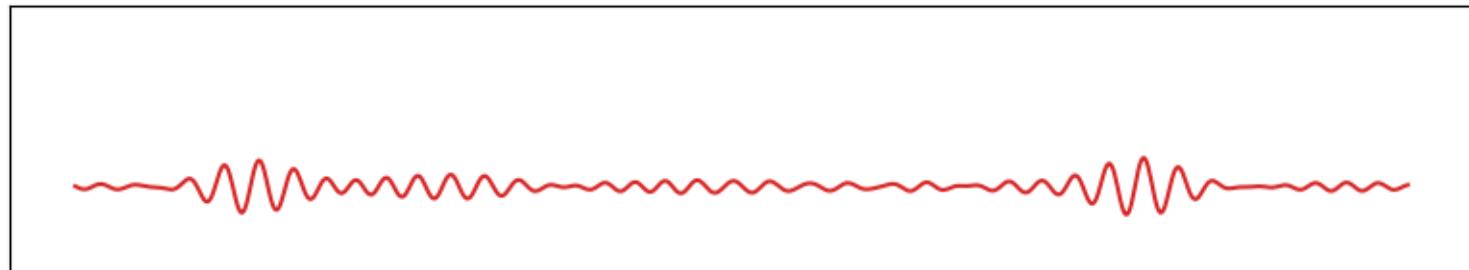
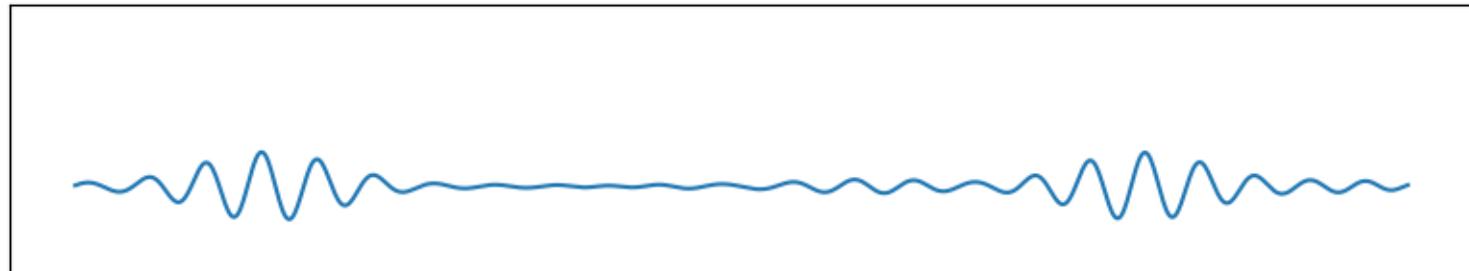
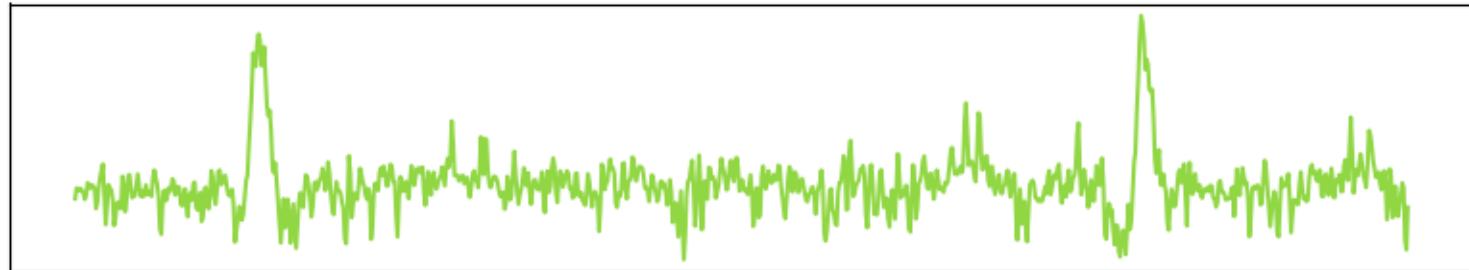
Narrow-band representation

ECoG



Narrow-band representation

MEG



Need to go beyond Fourier

- Fourier fallacy

(Jasper, 1948)

- Narrow-band linear filtering is too reductive

(Mazaheri and Jensen, 2008)

- Wide-band waveforms as key features

(Jones, 2016, Cole and Voytek, 2017)

In this work, we developed non-linear signal models, to go beyond narrow-band linear filtering.

Outline

1. Cross-frequency coupling analysis
with driven autoregressive models

2. Temporal waveform analysis
with convolutional sparse coding models

Part 1

1. Cross-frequency coupling analysis with driven autoregressive models

Non-linear autoregressive models for cross-frequency coupling in neural time series

T. Dupré la Tour, L. Tallot, L. Grabot, V. Doyère, V. van Wassenhove, Y. Grenier, A. Gramfort, *PLOS Computational Biology* 2017

Parametric estimation of spectrum driven by an exogenous signal

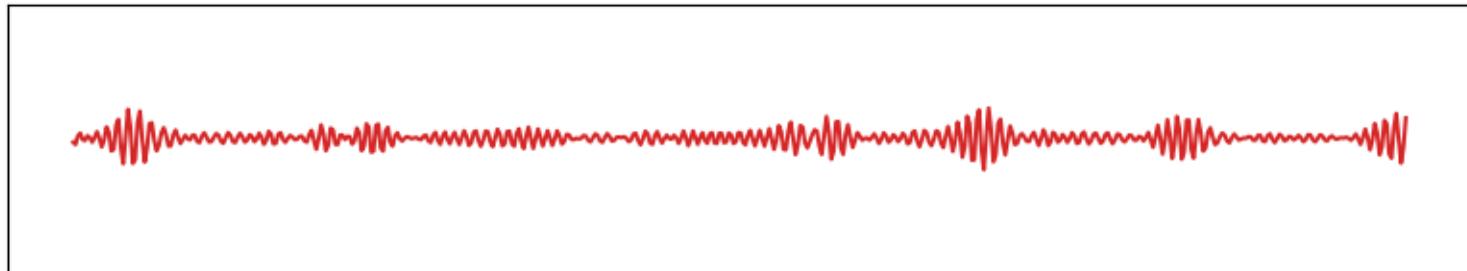
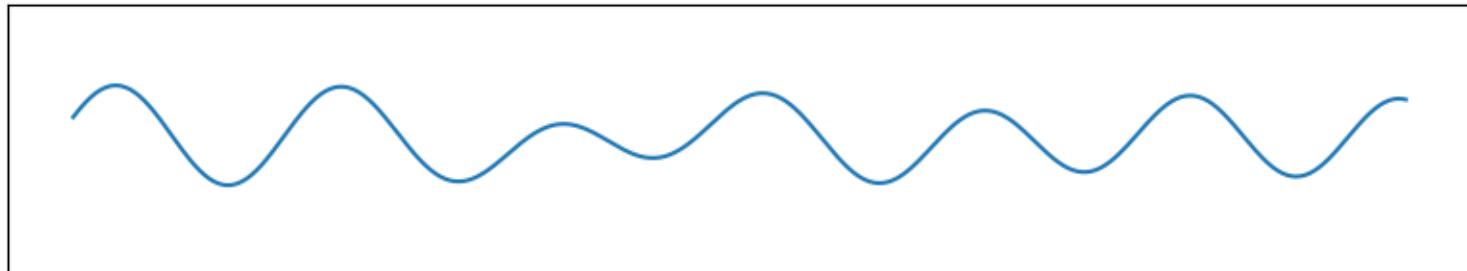
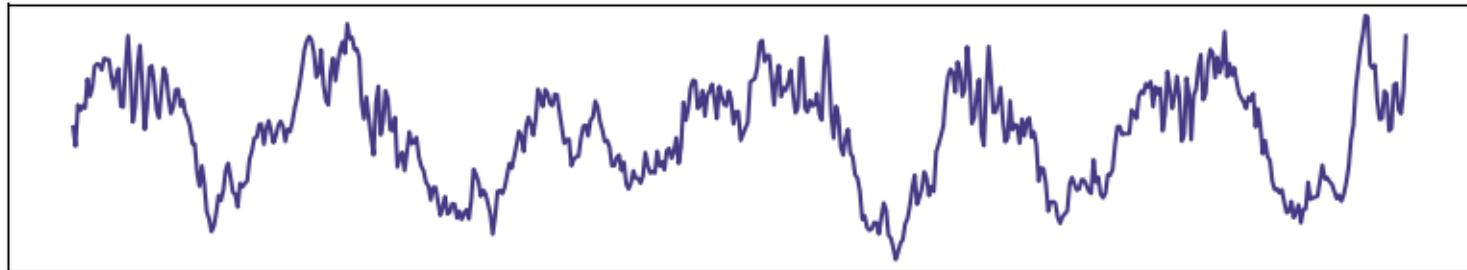
T. Dupré la Tour, Y. Grenier, A. Gramfort, *ICASSP* 2017

Driver estimation in non-linear autoregressive models

T. Dupré la Tour, Y. Grenier, A. Gramfort, *ICASSP* 2018

Cross-frequency coupling

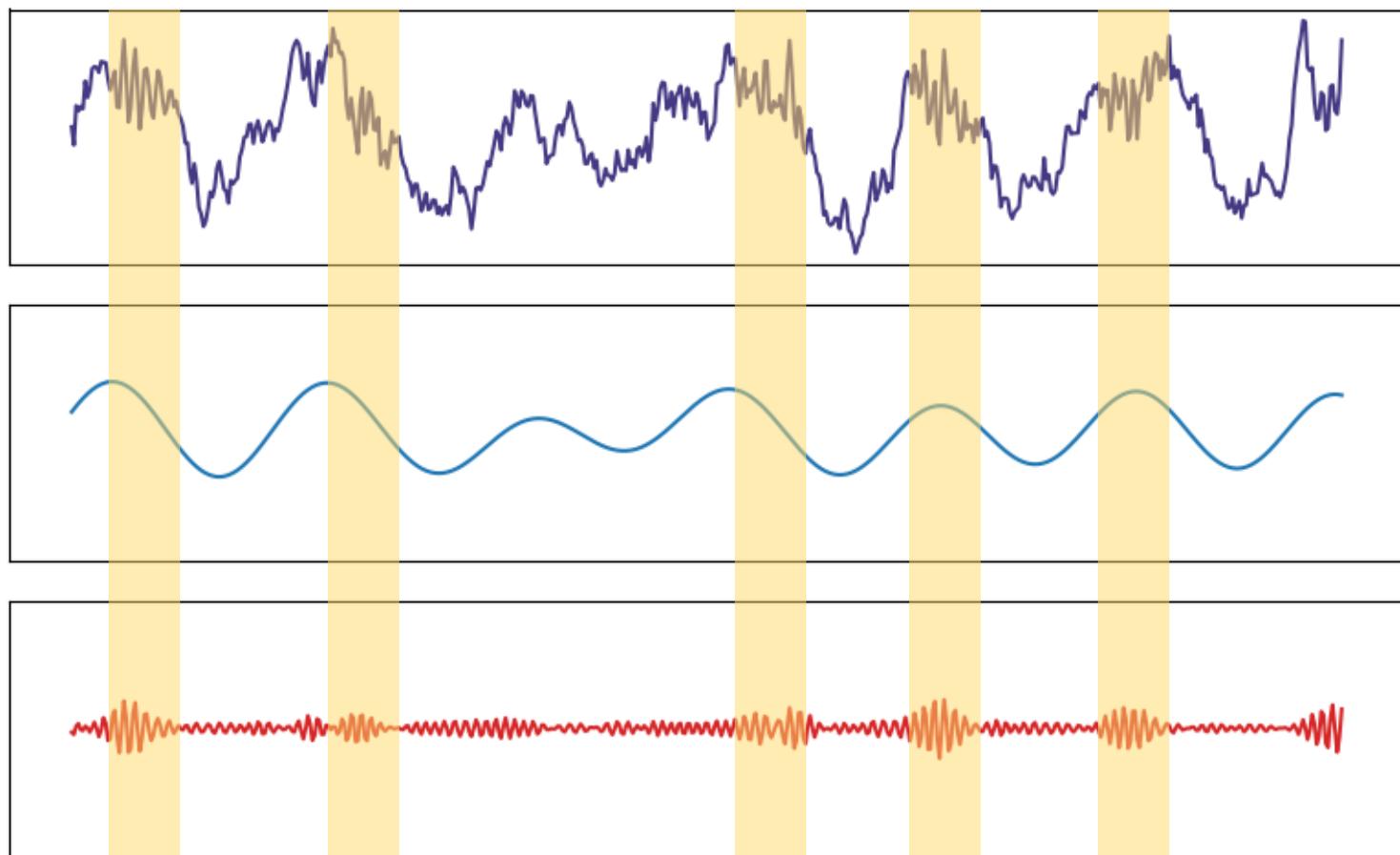
LFP



Cross-frequency coupling

Low-frequency phase and high-frequency amplitude

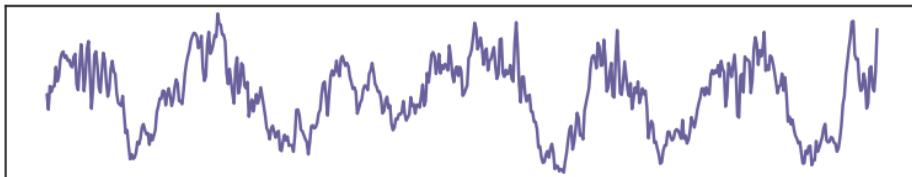
(Bragin et al 1995, Canolty et al, 2006)



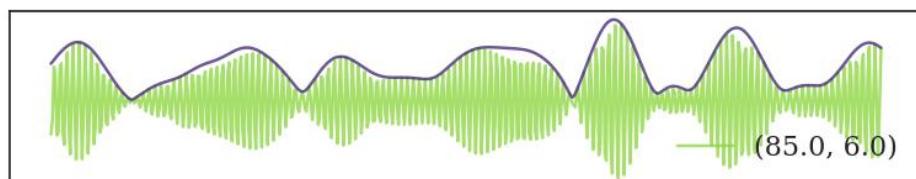
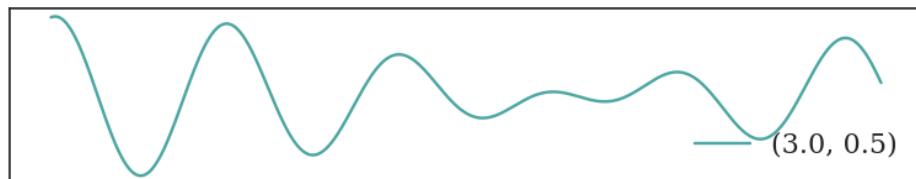
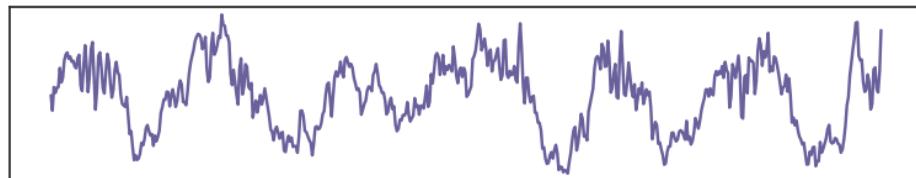
What is the role of CFC?

- Multi-item/sequence representation
(Penttonen et al, 1998, Gupta et al, 2012)
- Long-term and working memory
(Lisman and Idiart, 1995, Jensen, 2006, Tort et al, 2009)
- Long distance synchronization
(Canolty et al, 2006, Bonnefond et al, 2017)
- A canonical neural syntax
(Buzsaki, 2010, Lisman and Jensen 2013, Hyafil et al, 2015)

Common approach to measure CFC...



Common approach to measure CFC...

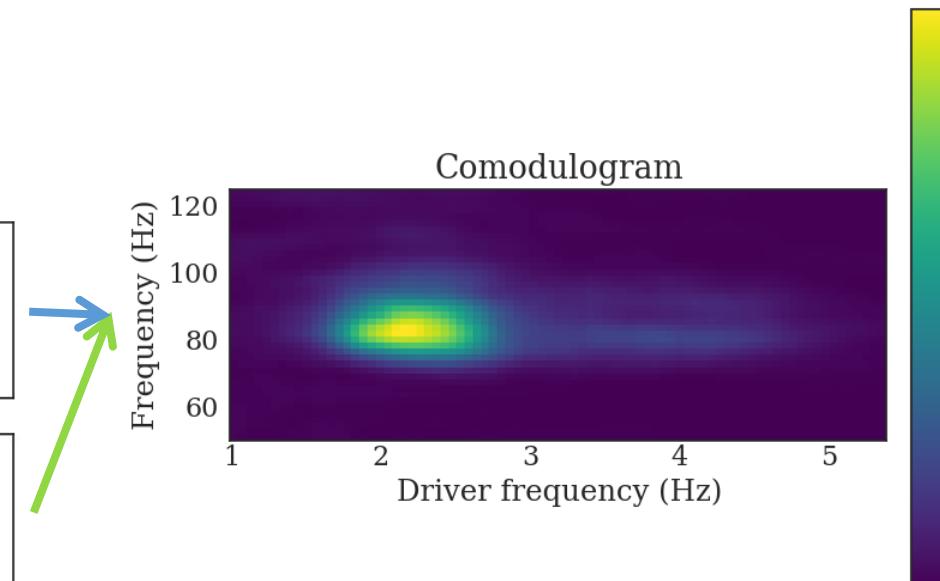
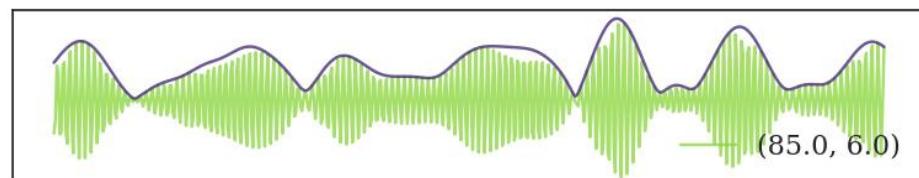
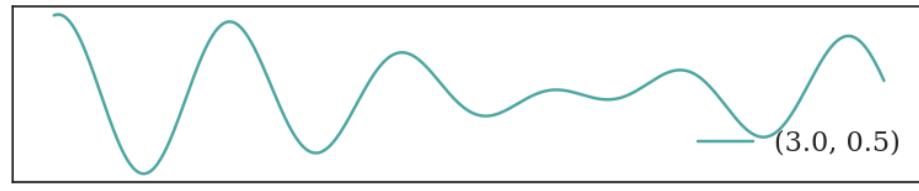
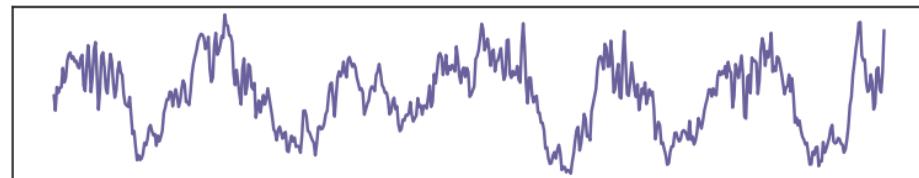


Correlation bewteen:

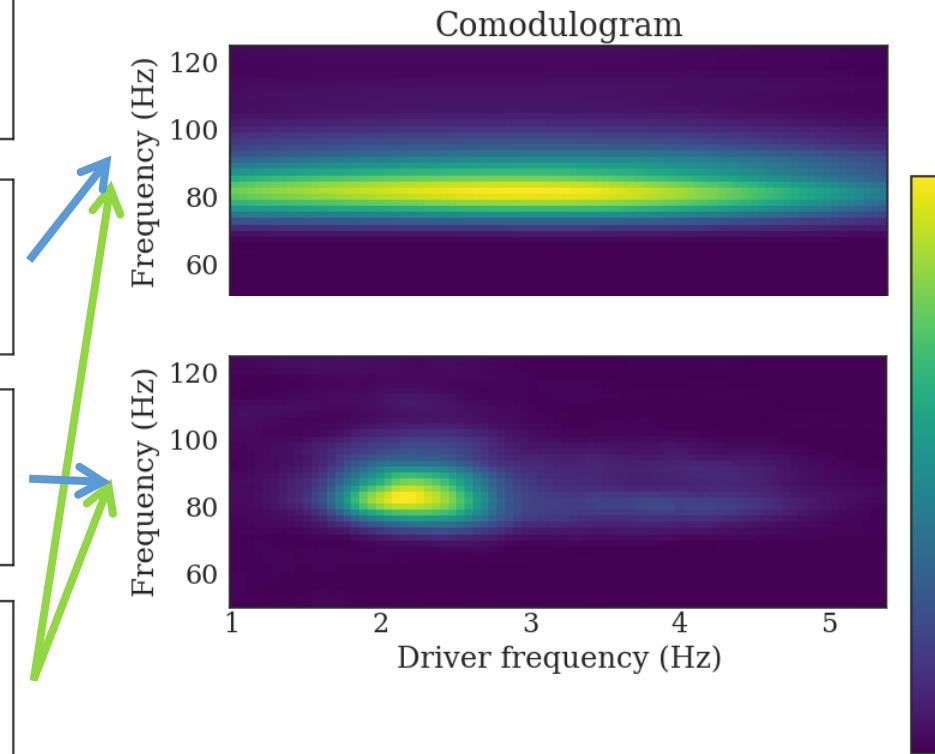
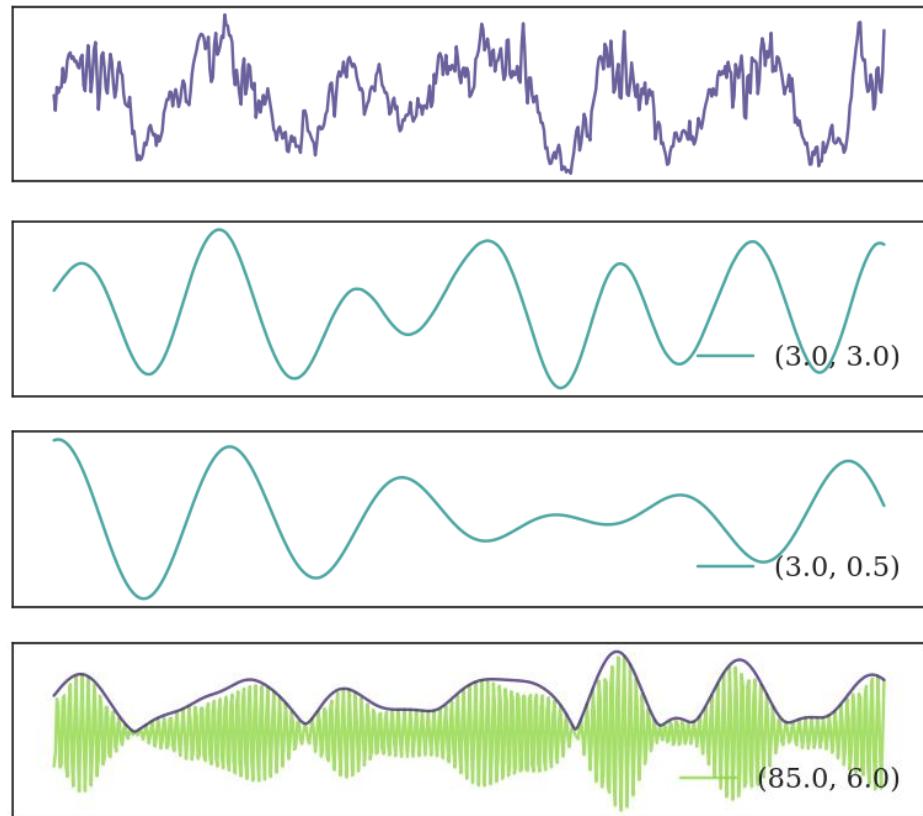
→ the low-frequency signal

→ the high-frequency envelope

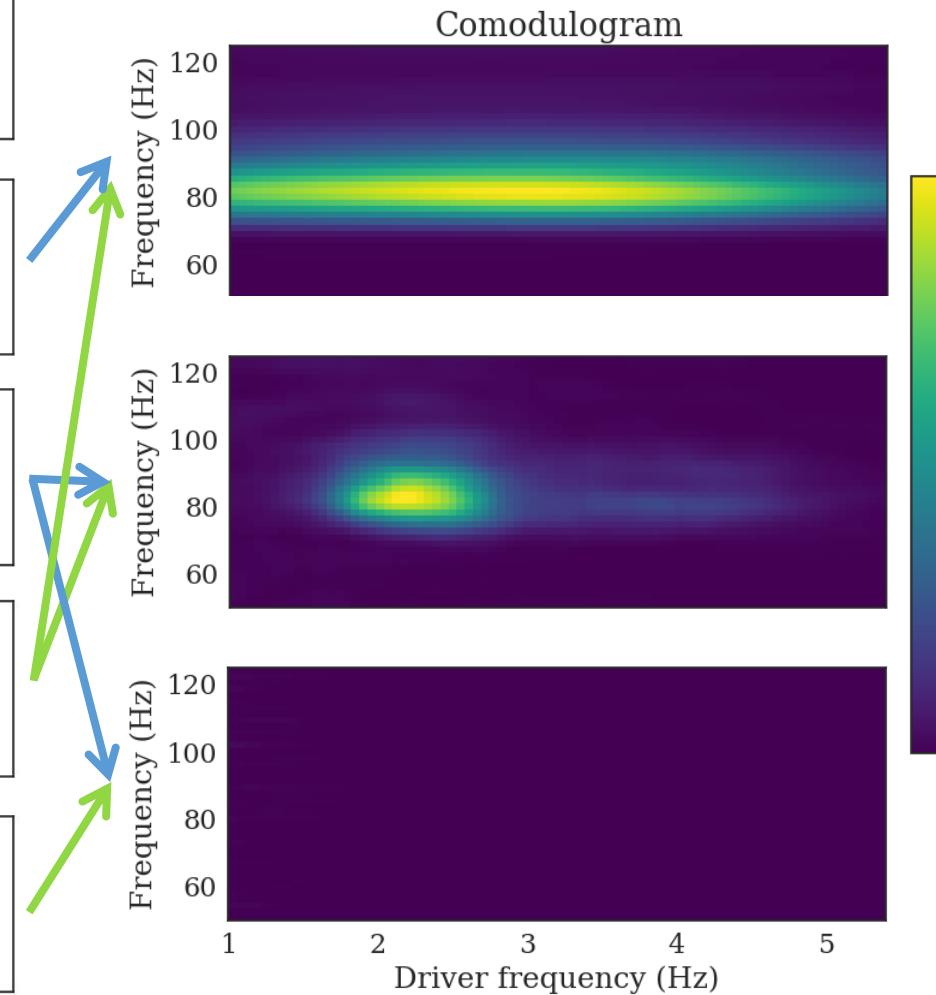
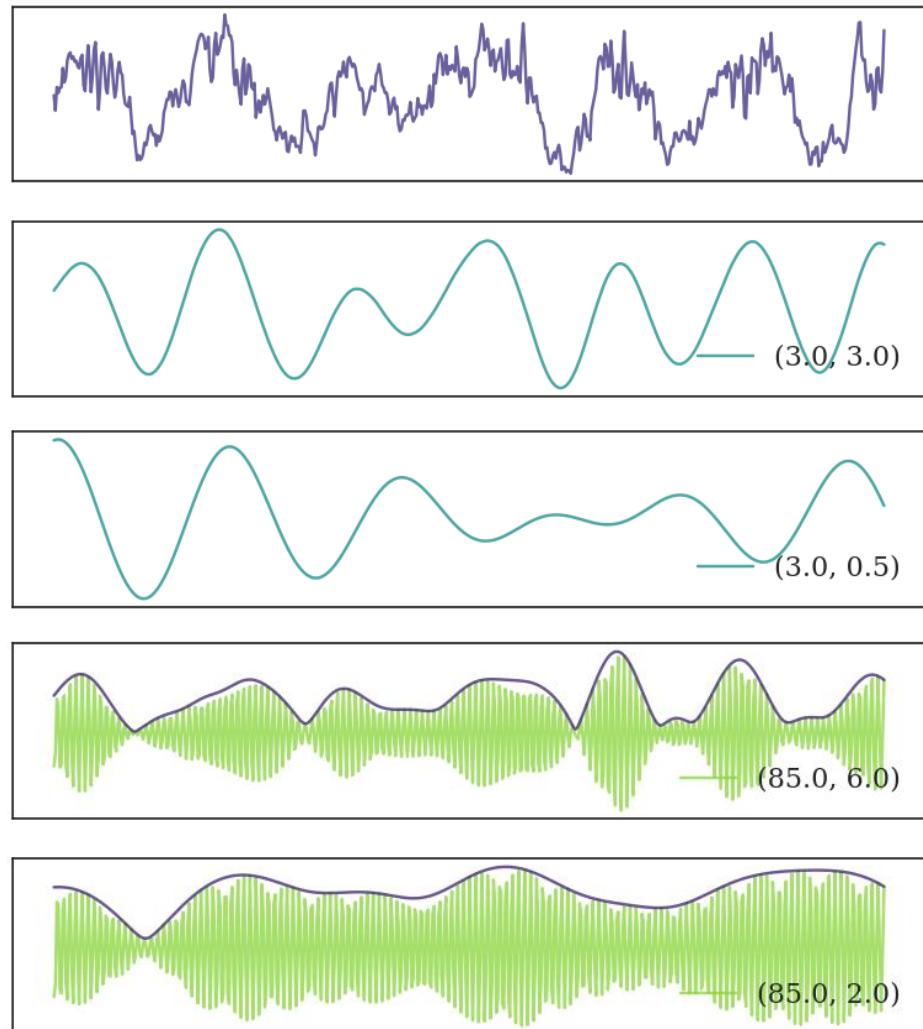
Common approach to measure CFC...



... but choosing filtering parameters is hard



... but choosing filtering parameters is hard



Autoregressive model

Autoregressive (AR) model

(Makhoul 1975)

$$y(t) + \sum_{i=1}^p a_i y(t-i) = \varepsilon(t) \quad \varepsilon(t) \sim \mathcal{N}(0, \sigma^2)$$

Spectral estimation

Autoregressive (AR) model

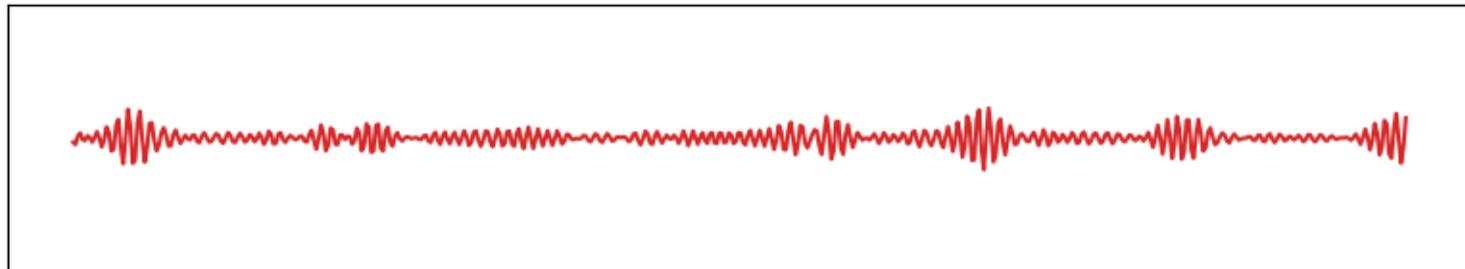
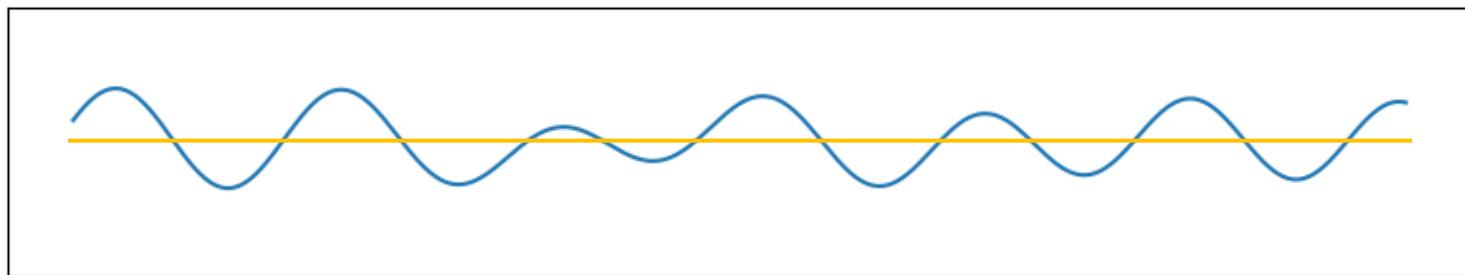
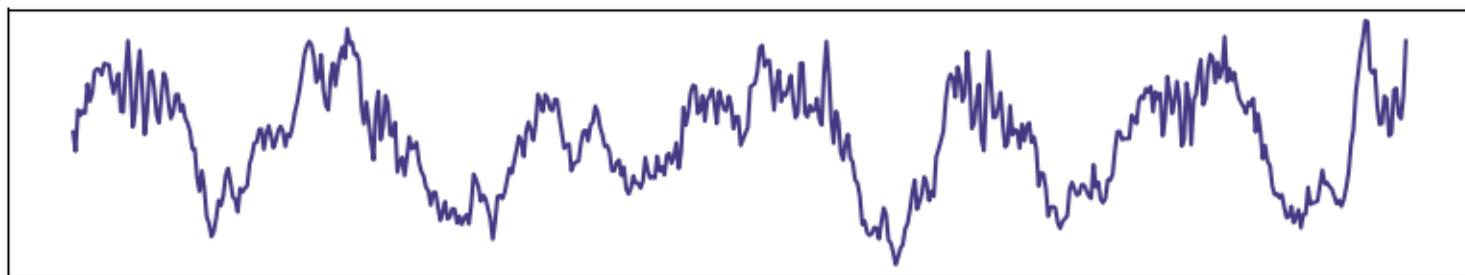
(Makhoul 1975)

$$y(t) + \sum_{i=1}^p a_i y(t-i) = \varepsilon(t) \quad \varepsilon(t) \sim \mathcal{N}(0, \sigma^2)$$

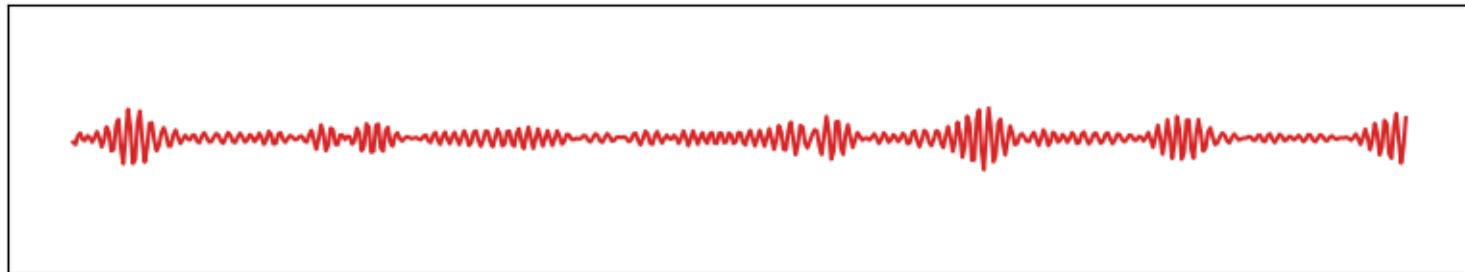
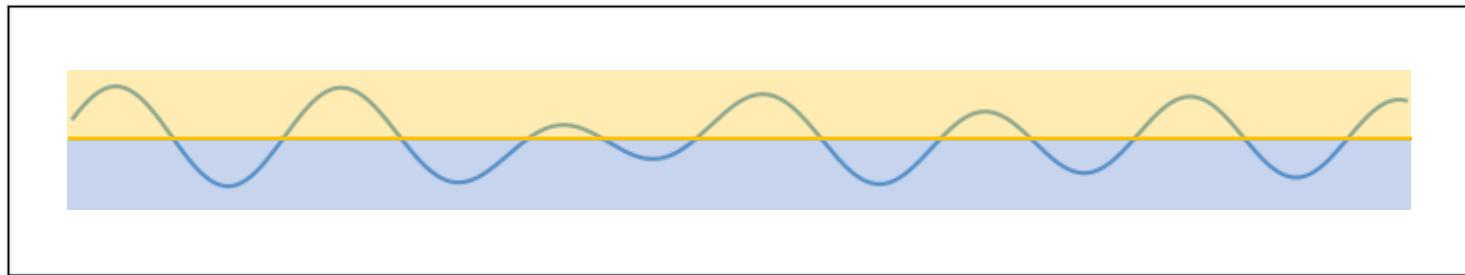
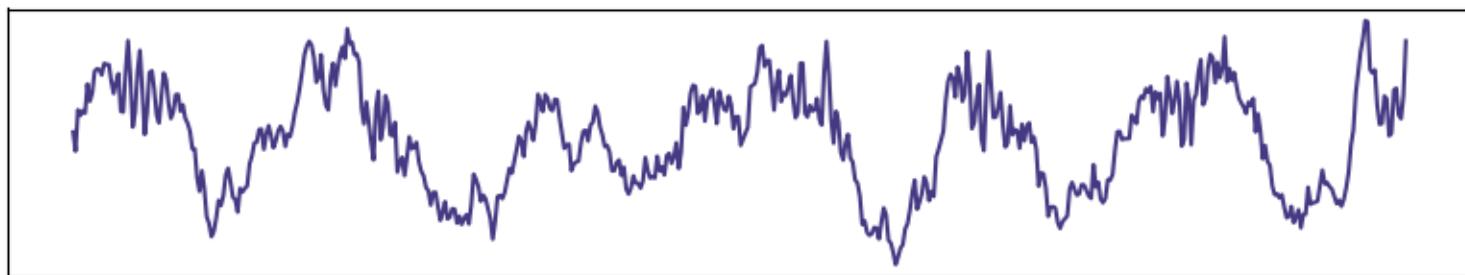
Power spectral density (PSD)

$$\text{PSD}_y(f) = \sigma^2 \left| \sum_{i=0}^p a_i e^{-j2\pi f i} \right|^{-2}$$

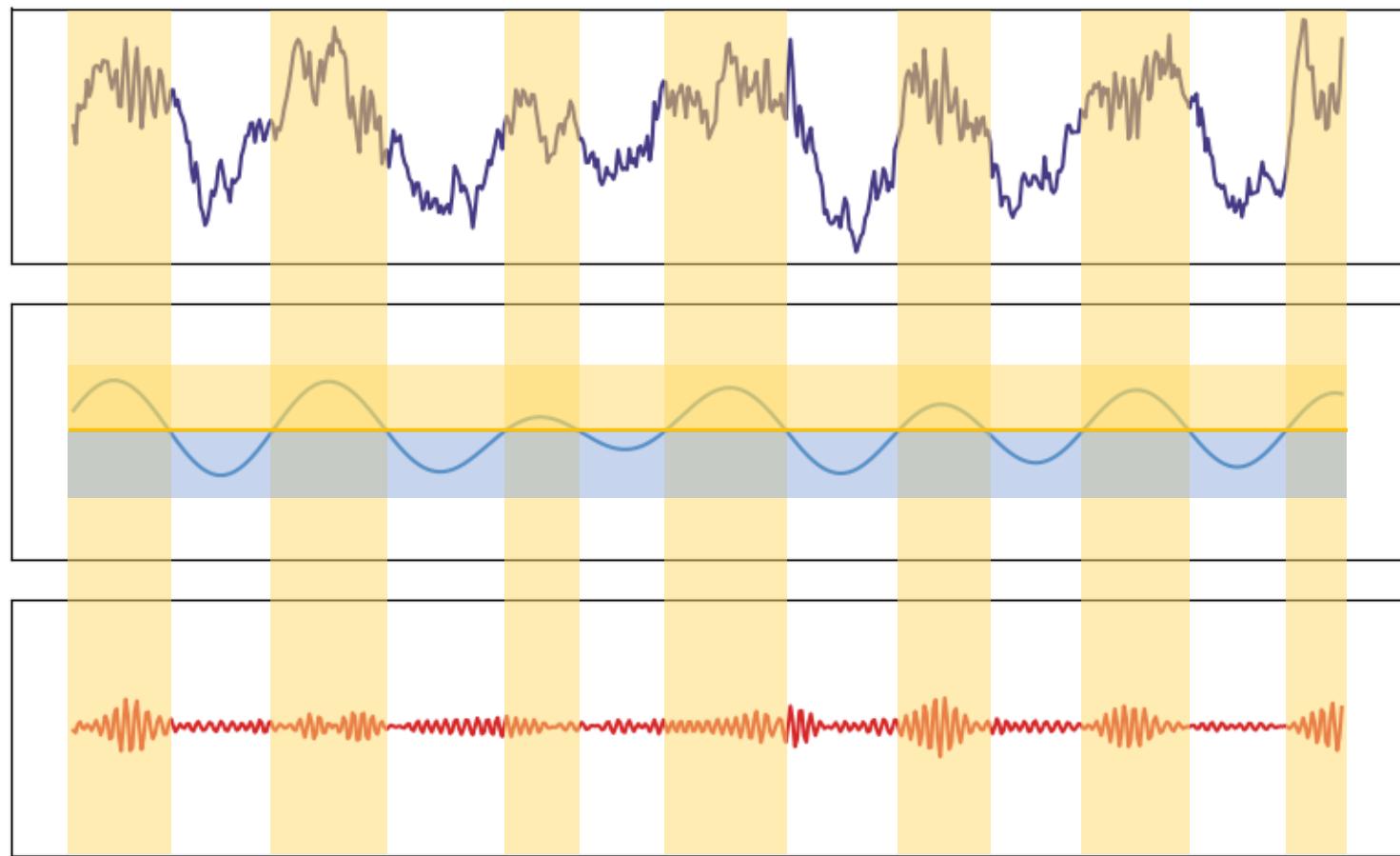
Cross-frequency coupling



Cross-frequency coupling

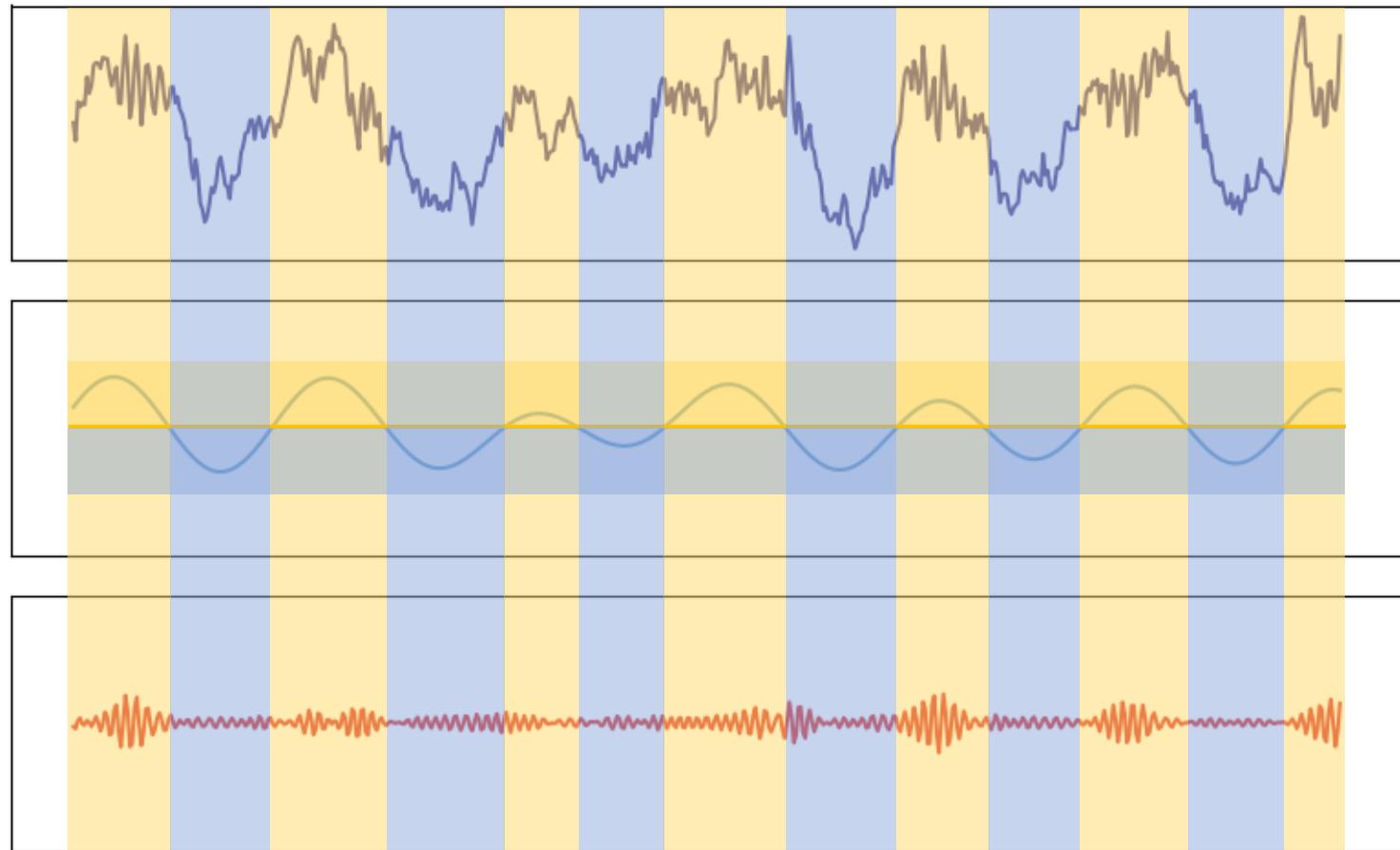


Cross-frequency coupling



Cross-frequency coupling

(Tong and Lim, 1980, Chan and Tong, 1986, Dijk et al, 2002)



Driven autoregressive (DAR) model

Autoregressive (AR) model

(Makhoul, 1975)

$$y(t) + \sum_{i=1}^p a_i y(t-i) = \varepsilon(t) \quad \varepsilon(t) \sim \mathcal{N}(0, \sigma^2)$$

Driven AR (DAR) model

(Grenier, 1983, 2013)

$$a_i(t) = \sum_{j=0}^m a_{ij} x(t)^j \quad \log(\sigma(t)) = \sum_{j=0}^m b_j x(t)^j$$

Driven autoregressive (DAR) model

Autoregressive (AR) model

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$$y(t) + \sum_{i=1}^p a_i y(t-i) = \varepsilon(t) \quad \varepsilon(t) \sim \mathcal{N}(0, \sigma^2)$$

Driven AR (DAR) model

(Grenier, 1983, 2013)

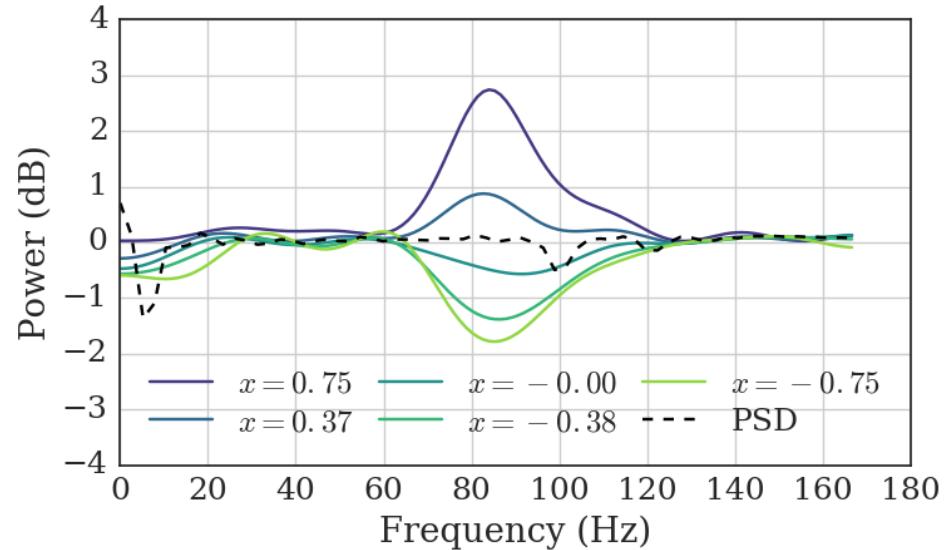
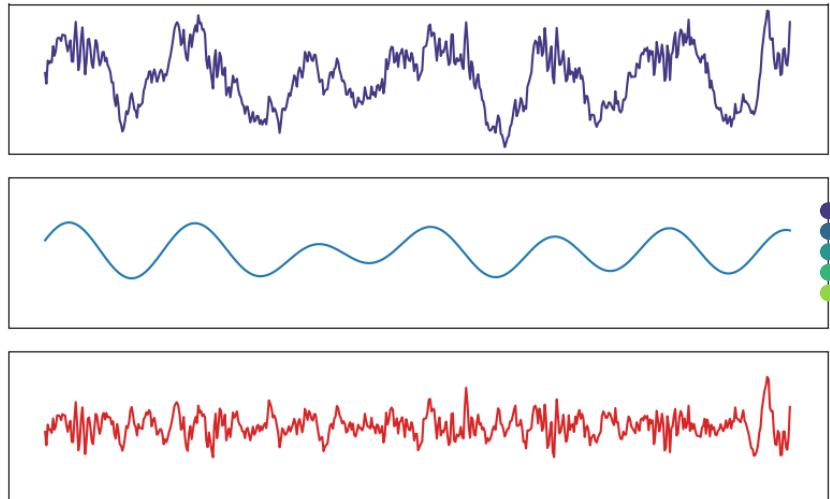
$$a_i(t) = \sum_{j=0}^m a_{ij} x(t)^j \quad \log(\sigma(t)) = \sum_{j=0}^m b_j x(t)^j$$

A different parametrization ensuring DAR model stability :

Parametric estimation of spectrum driven by an exogenous signal

T. Dupré la Tour, Y. Grenier, A. Gramfort, ICASSP 2017

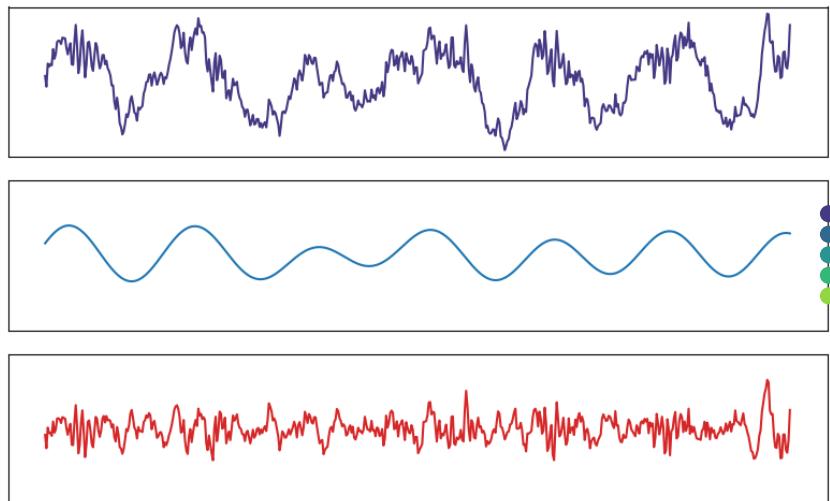
Conditional PSD



LFP

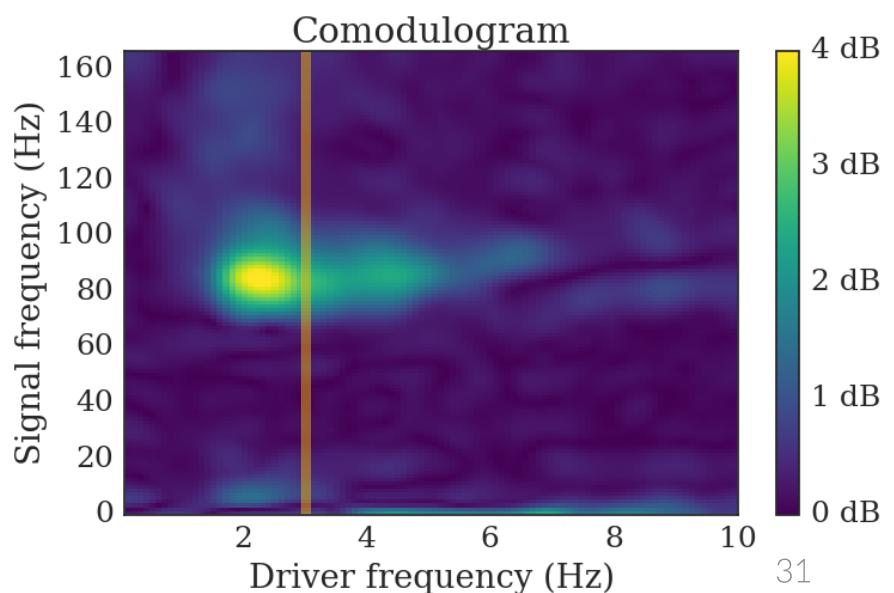
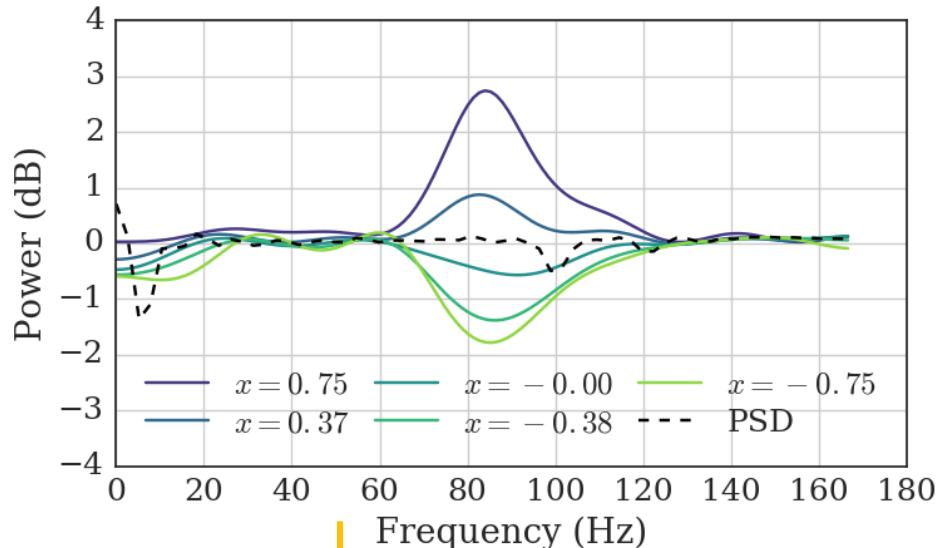
$$\text{PSD}_y(x_0)(f) = \sigma(x_0)^2 \left| \sum_{i=0}^p a_i(x_0) e^{-j2\pi f i} \right|^{-2}$$

Conditional PSD



LFP

$$\text{PSD}_y(x_0)(f) = \sigma(x_0)^2 \left| \sum_{i=0}^p a_i(x_0) e^{-j2\pi f i} \right|^2$$



Comodulogram on two empirical signals

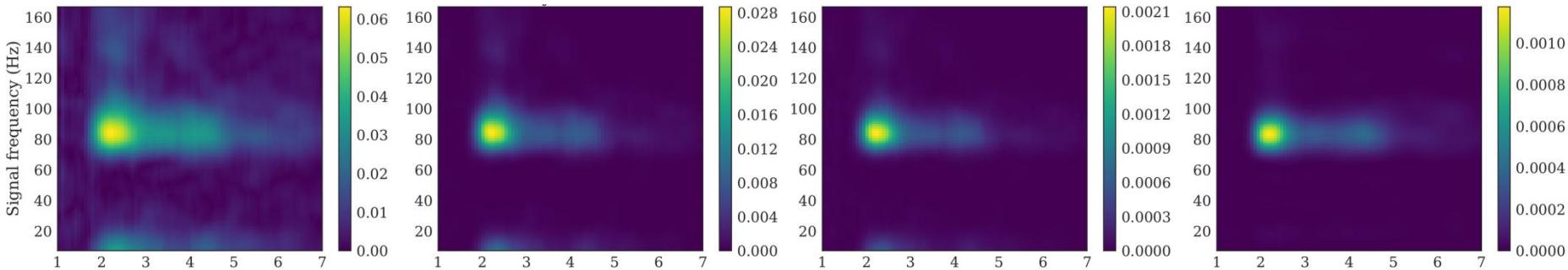
LFP

(Ozkurt et al, 2011)

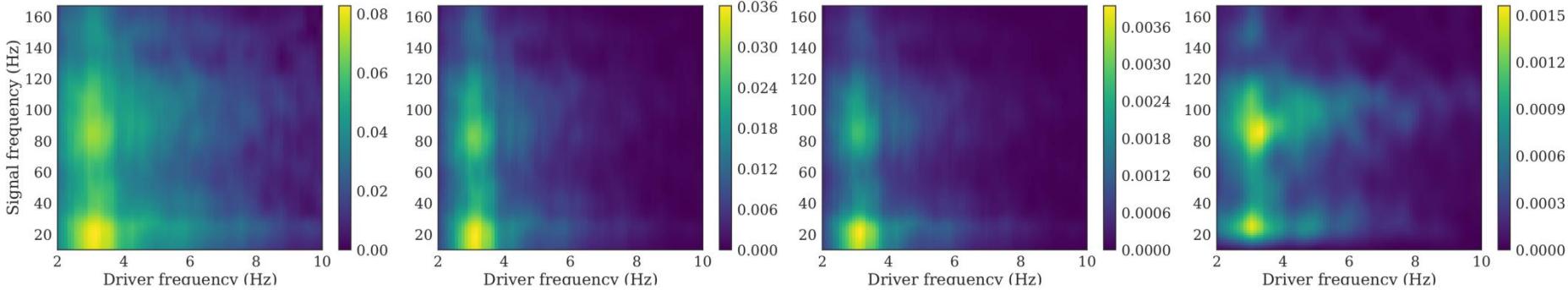
(Penny et al, 2008)

(Tort et al, 2009)

(Dupré la Tour et al, 2017)



ECoG



Model and parameter selection

$$L = \prod_{t=p+1}^T \frac{1}{\sqrt{2\pi\sigma(t)^2}} \exp\left(-\frac{\varepsilon(t)^2}{2\sigma(t)^2}\right)$$

$$-2 \log(L) = T \log(2\pi) + \sum_{t=p+1}^T \frac{\varepsilon(t)^2}{\sigma(t)^2} + 2 \sum_{t=p+1}^T \log(\sigma(t))$$

Main gain: A likelihood function → parameter selection

Model and parameter selection

$$L = \prod_{t=p+1}^T \frac{1}{\sqrt{2\pi\sigma(t)^2}} \exp\left(-\frac{\varepsilon(t)^2}{2\sigma(t)^2}\right)$$

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Main gain: A likelihood function → parameter selection

Example: Selection of AR order (p) and DAR polynomial order (m):

Model and parameter selection

$$L = \prod_{t=p+1}^T \frac{1}{\sqrt{2\pi\sigma(t)^2}} \exp\left(-\frac{\varepsilon(t)^2}{2\sigma(t)^2}\right)$$

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Main gain: A likelihood function → parameter selection

Example: Selection of AR order (p) and DAR polynomial order (m):

- Akaike information criterion (AIC), Bayesian information criterion (BIC), ...

(Akaike, 1974)

(Schwartz, 1978)

Model and parameter selection

$$L = \prod_{t=p+1}^T \frac{1}{\sqrt{2\pi\sigma(t)^2}} \exp\left(-\frac{\varepsilon(t)^2}{2\sigma(t)^2}\right)$$

$$-2 \log(L) = T \log(2\pi) + \sum_{t=p+1}^T \frac{\varepsilon(t)^2}{\sigma(t)^2} + 2 \sum_{t=p+1}^T \log(\sigma(t))$$

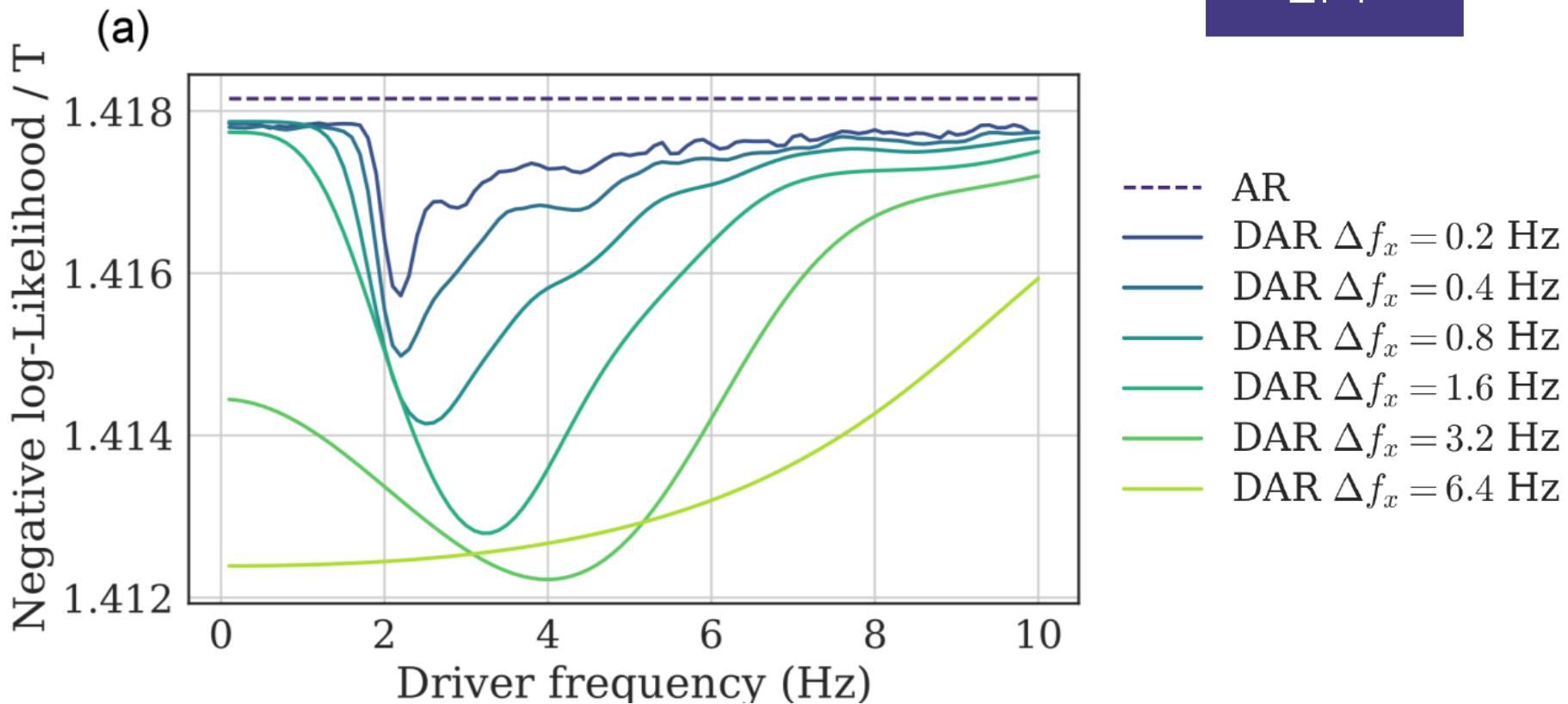
Main gain: A likelihood function → parameter selection

Example: Selection of AR order (p) and DAR polynomial order (m):

- Akaike information criterion (AIC), Bayesian information criterion (BIC), ...
- Evaluation on left-out data, cross-validation (Akaike, 1974)
(Schwartz, 1978)

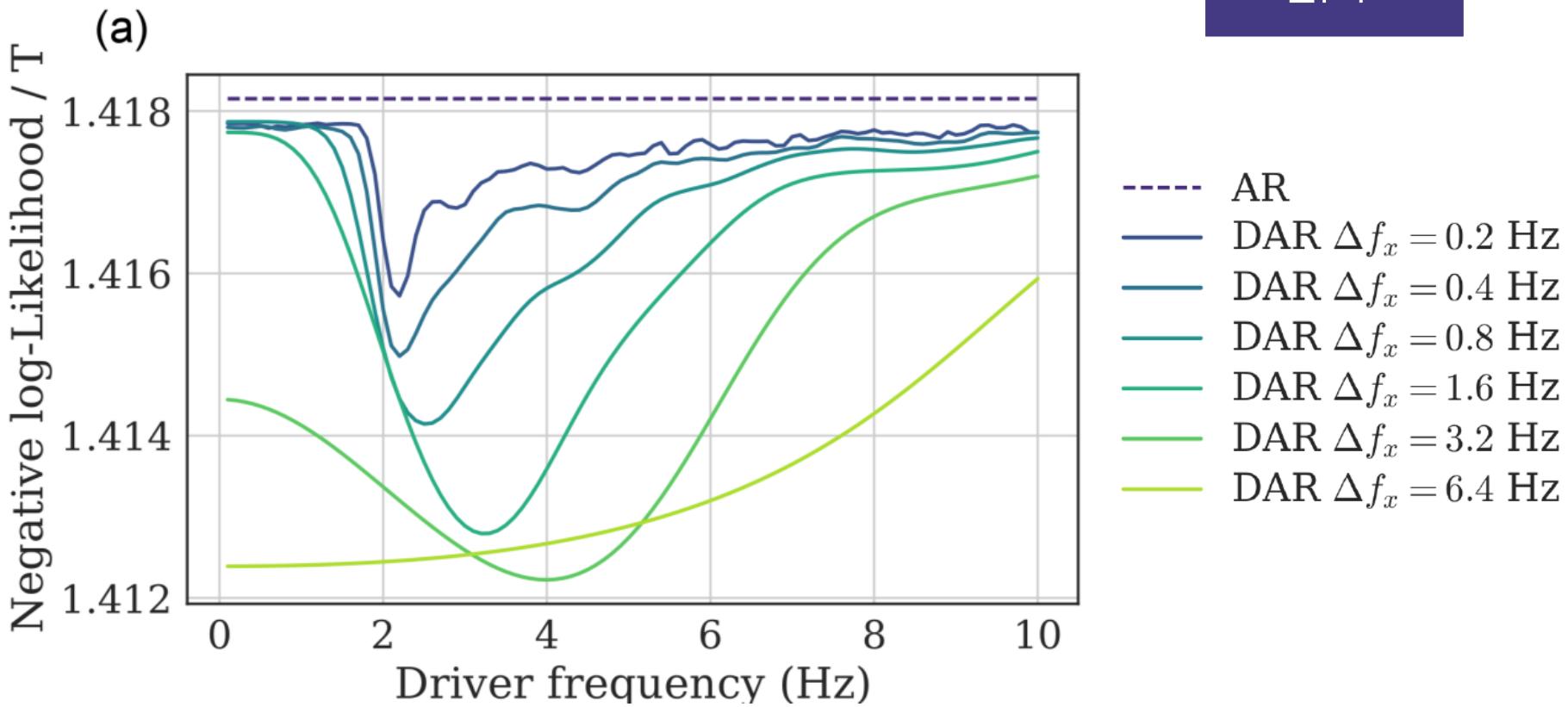
Driver selection

LFP



Driver selection

LFP



Further optimizing the driver filter with gradient descent:

Driver estimation in non-linear autoregressive models

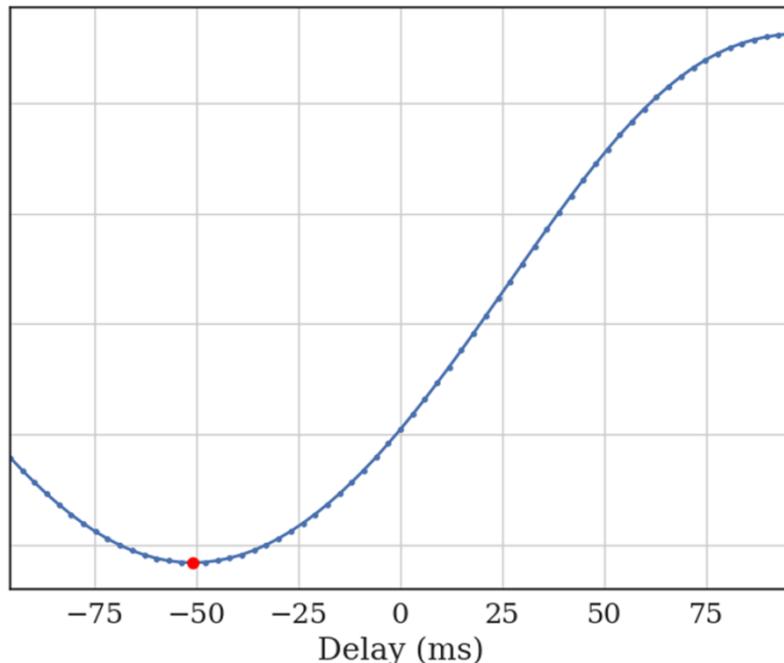
T. Dupré la Tour, Y. Grenier, A. Gramfort, ICASSP 2018

Delay estimation

- DAR model between $y(t)$ and $x_\tau(t) = x(t - \tau)$
- Minimize the negative log-likelihood

Delay estimation

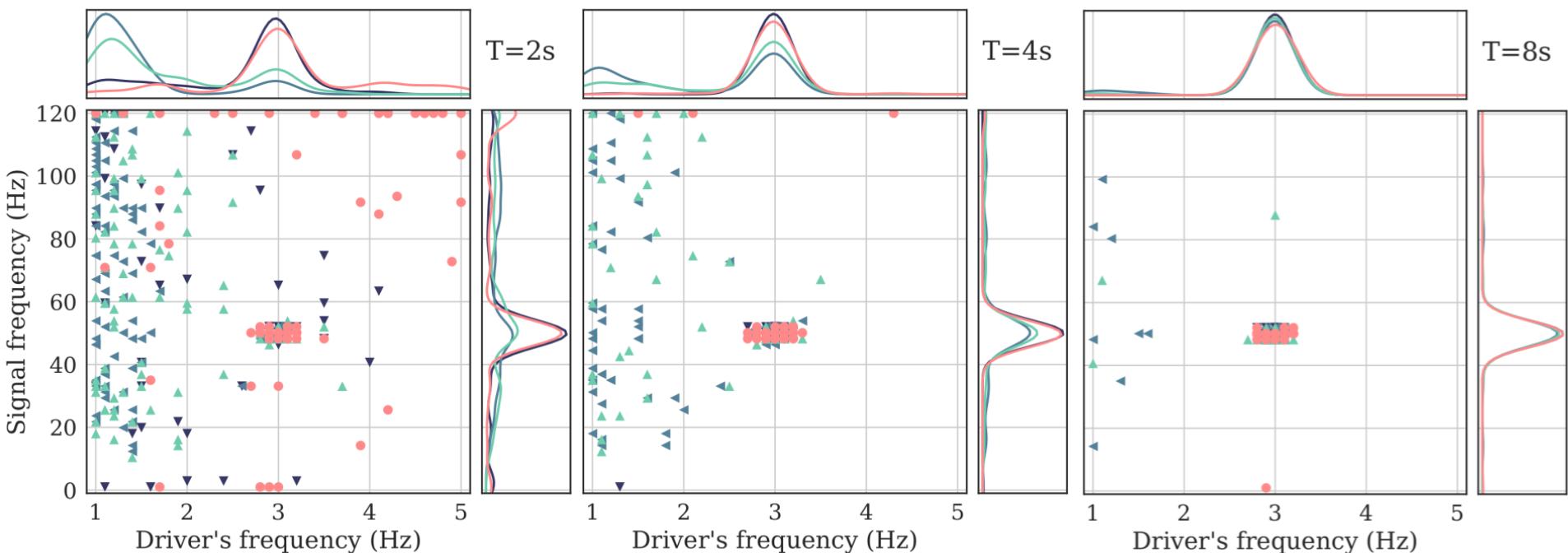
- DAR model between $y(t)$ and $x_\tau(t) = x(t - \tau)$
- Minimize the negative log-likelihood



(Besserve et al , 2010)
(Jiang et al , 2015)



Robustness to short signals



- ▼ (Penny et al, 2008)
- △ (Tort et al, 2009)
- ▲ (Ozkurt et al, 2011)
- (Dupré la Tour et al, 2017)

1. Cross-frequency coupling analysis with driven autoregressive models

- Estimation of spectral modulation → capture CFC
- Generative model → easy comparison of parameters
- Delay estimation → directionality of the coupling
- Parametric model → robust to short signals

Non-linear autoregressive models for cross-frequency coupling in neural time series

T. Dupré la Tour, L. Tallot, L. Grabot, V. Doyère, V. van Wassenhove, Y. Grenier, A. Gramfort, *PLOS Computational Biology* 2017

Parametric estimation of spectrum driven by an exogenous signal

T. Dupré la Tour, Y. Grenier, A. Gramfort, *ICASSP* 2017

Driver estimation in non-linear autoregressive models

T. Dupré la Tour, Y. Grenier, A. Gramfort, *ICASSP* 2018

Outline

1. Cross-frequency coupling analysis
with driven autoregressive models

2. Temporal waveform analysis
with convolutional sparse coding models

Part 2

2. Temporal waveform analysis with convolutional sparse coding models

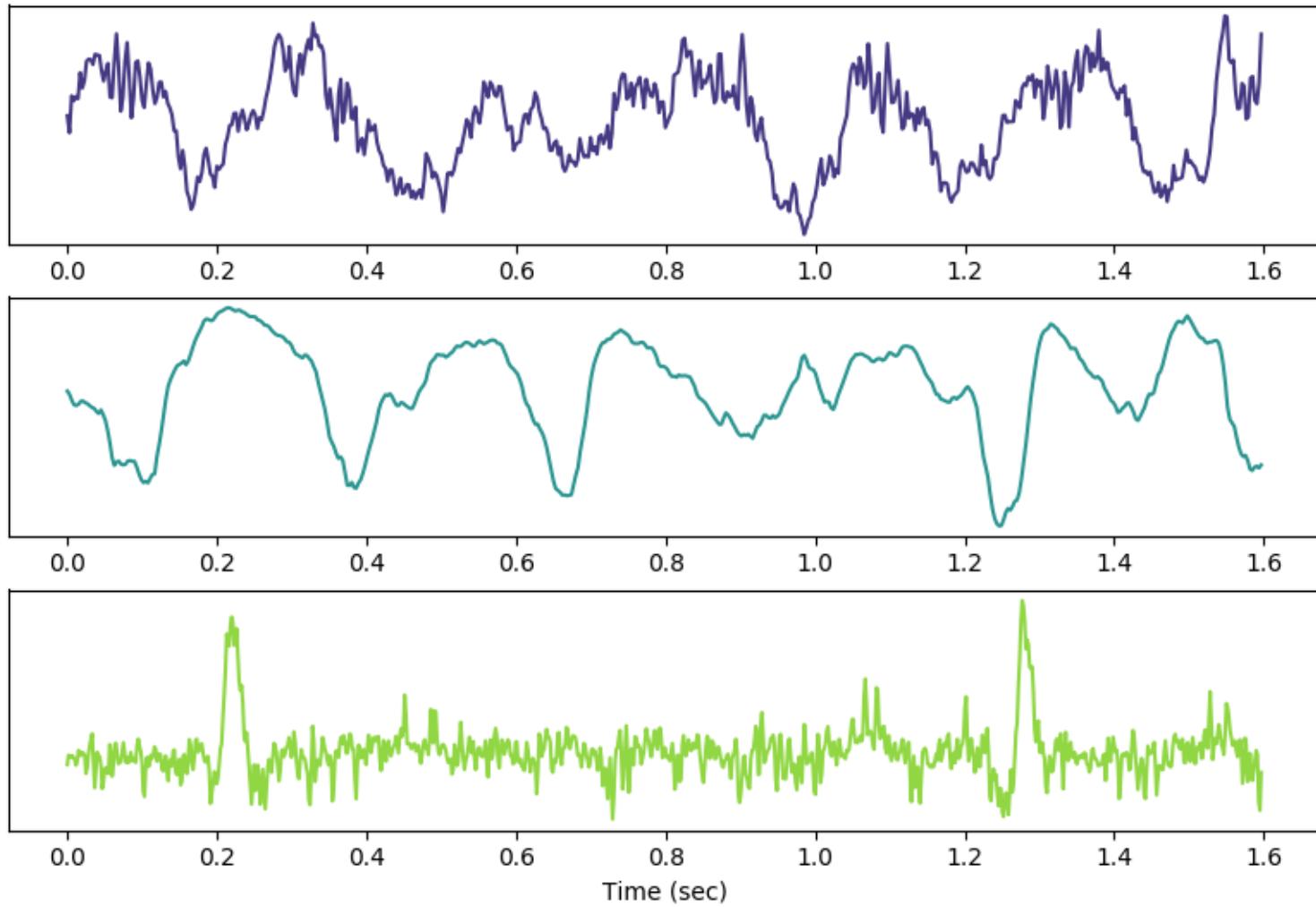
Learning the morphology of brain signals using alpha-stable convolutional sparse coding

M. Jas, T. Dupré la Tour, U. Şimşekli, A. Gramfort, NeurIPS 2017

Multivariate Convolutional Sparse Coding for Electromagnetic Brain Signals

T. Dupré la Tour*, T. Moreau*, M. Jas, A. Gramfort, NeurIPS 2018

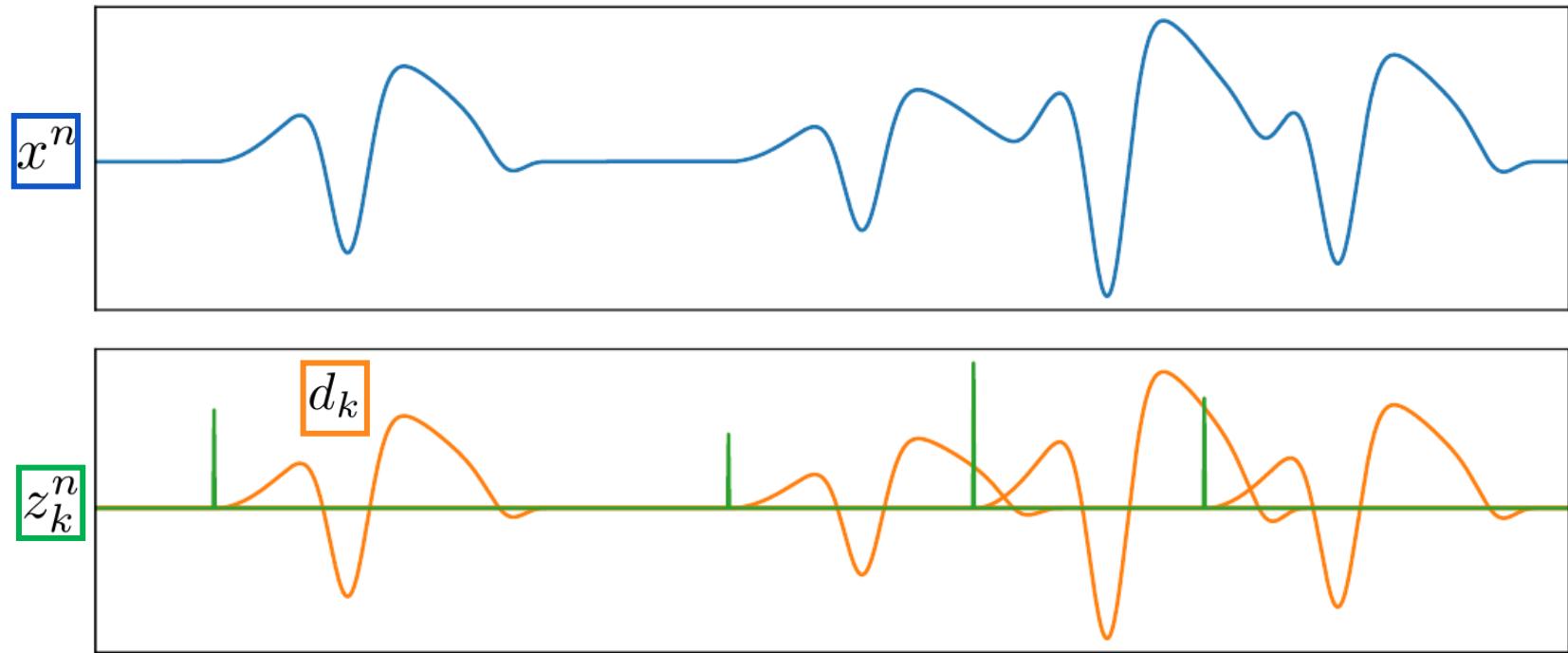
Neurophysiological time series



Temporal waveform analysis

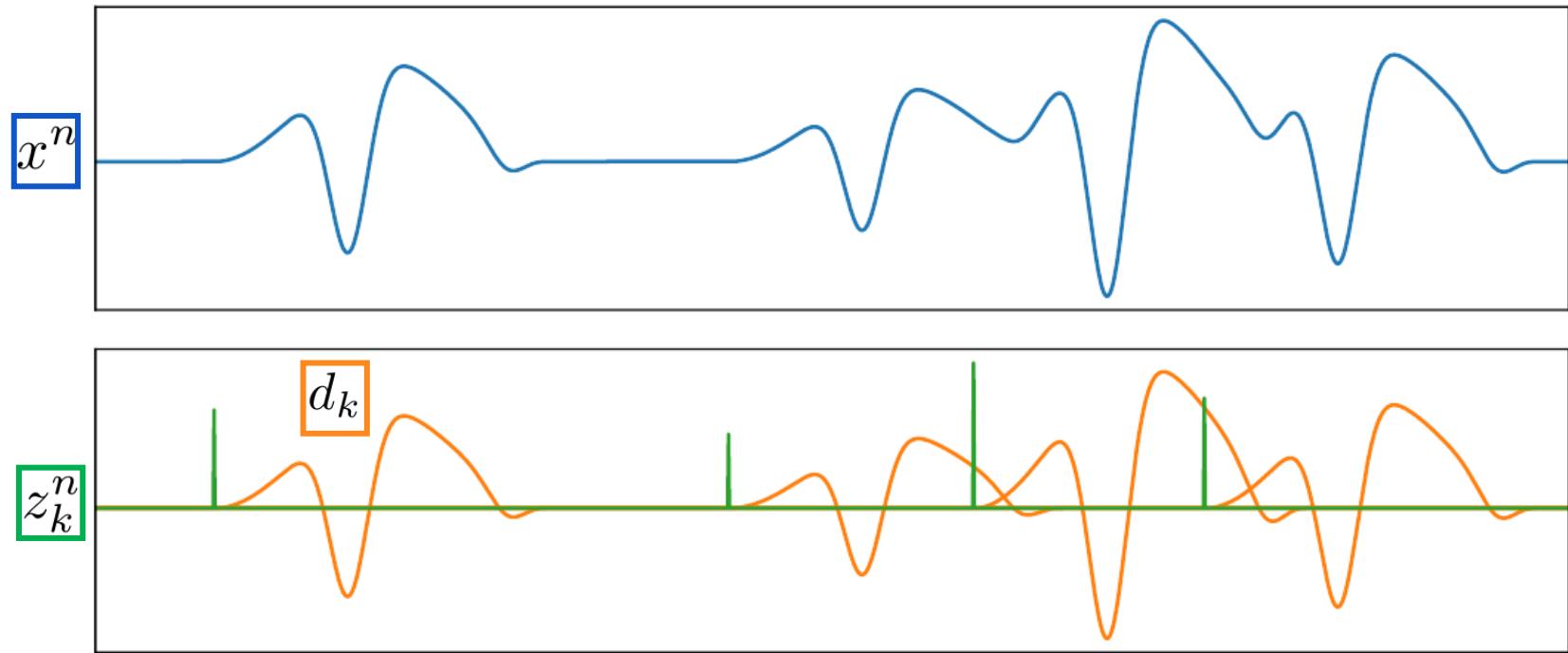
- Sparse representations: wavelet basis
(Mallat and Zhang, 1993, Candès et al, 2006)
- Sparse coding / dictionary learning
(Olshausen and Field, 1996, Elad and Aharon, 2006)
- Shift-invariant representations
(Lewicki and Sejnowski, 1999, Grosse et al, 2007)
- In neurophysiology:
 - Matching of time-invariant filters (Jost et al, 2006)
 - Multivariate orthogonal matching pursuit (Barthélemy et al, 2012)
 - Matching pursuit and heuristics (Brokmeier and Principe, 2016)
 - Sliding window machine (Gips et al, 2017)
 - Adaptive waveform learning (Hitziger et al, 2017)

Convolutional sparse coding



(Grosse et al, 2007)

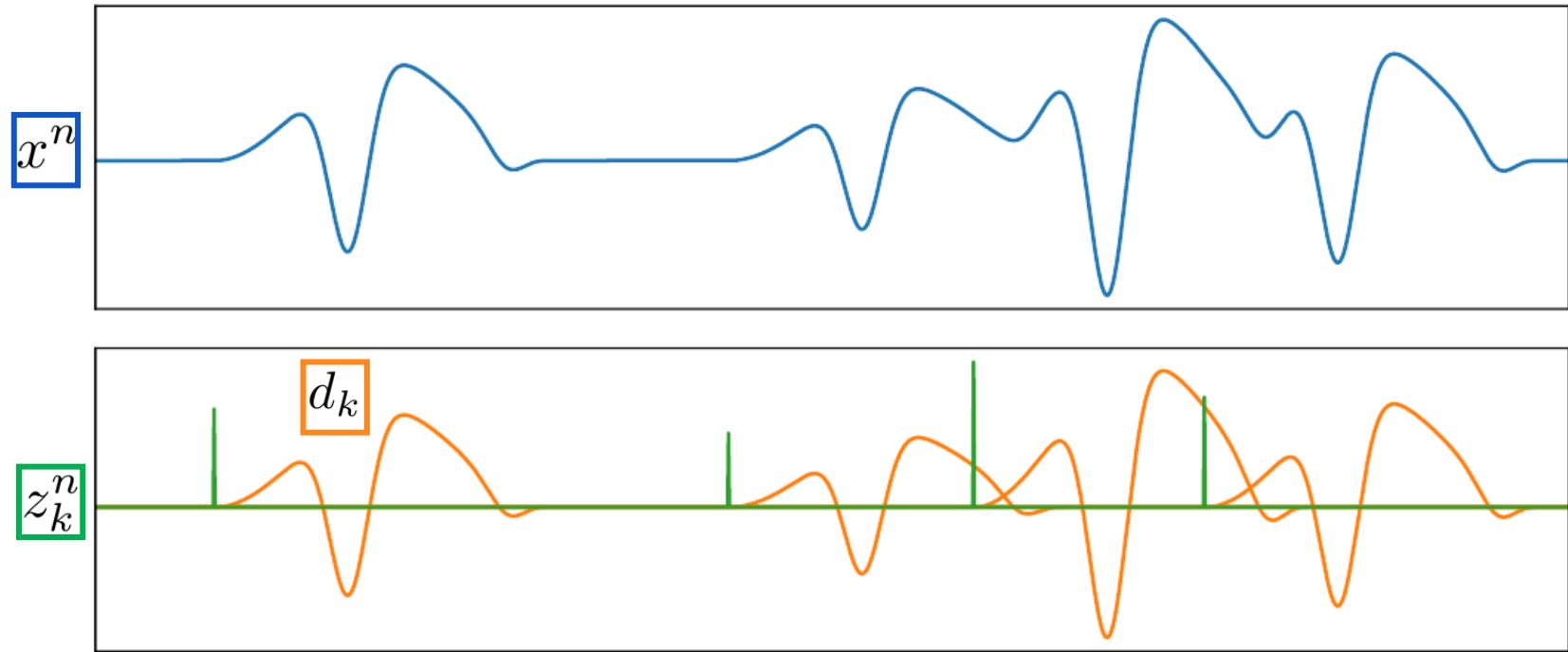
Convolutional sparse coding



$$x^n[t] = \sum_{k=1}^K (z_k^n * d_k)[t] + \varepsilon[t]$$

(Grosse et al, 2007)

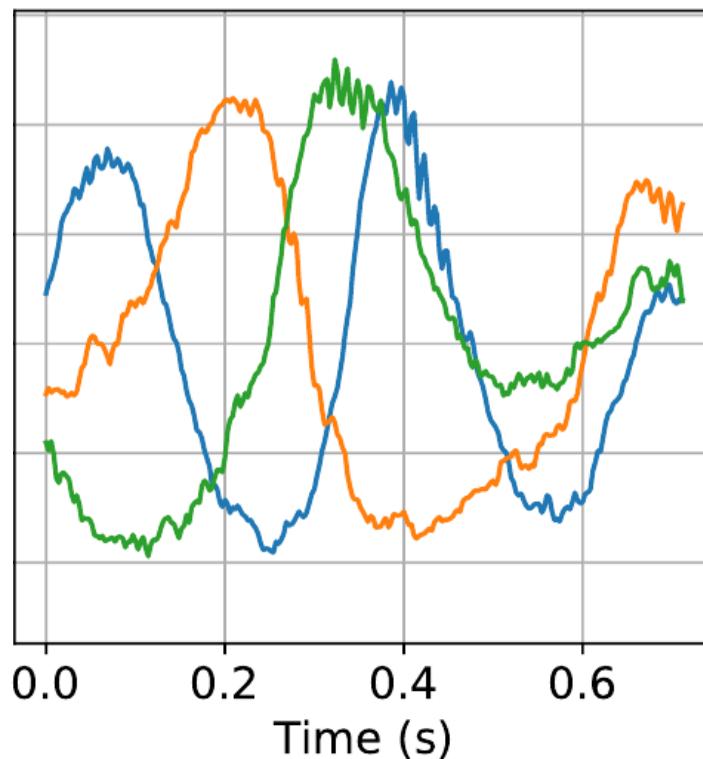
Convolutional sparse coding



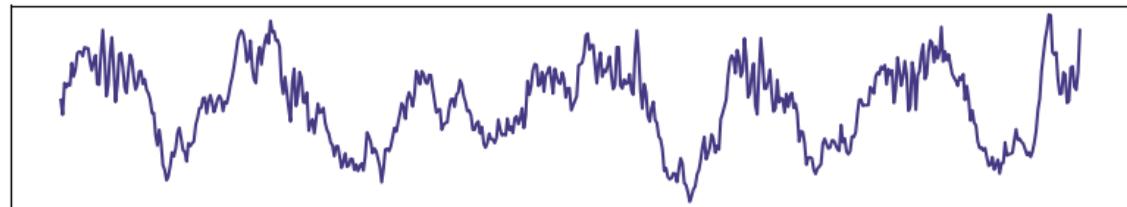
$$\min_{d,z} \sum_{n=1}^N \frac{1}{2} \left\| \boxed{x^n} - \sum_{k=1}^K \boxed{z_k^n} * \boxed{d_k} \right\|_2^2 + \lambda \sum_{k=1}^K \|\boxed{z_k^n}\|_1,$$

s.t. $\|\boxed{d_k}\|_2^2 \leq 1$ and $\boxed{z_k^n} \geq 0$. (Grosse et al, 2007)

Learned atoms



LFP



First challenge: optimization speed

$$\begin{aligned} \min_{d,z} \sum_{n=1}^N \frac{1}{2} \left\| x^n - \sum_{k=1}^K z_k^n * d_k \right\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1, \\ \text{s.t. } \|d_k\|_2^2 \leq 1 \text{ and } z_k^n \geq 0. \end{aligned}$$

Block-coordinate descent

- Z-step
- D-step

First challenge: optimization speed

$$\begin{aligned} \min_{d,z} \sum_{n=1}^N \frac{1}{2} \left\| x^n - \sum_{k=1}^K z_k^n * d_k \right\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1, \\ \text{s.t. } \|d_k\|_2^2 \leq 1 \text{ and } z_k^n \geq 0. \end{aligned}$$

Block-coordinate descent

- Z-step
 - GCD (Kavukcuoglu et al, 2010)
 - FISTA (Chalasani et al, 2013)
 - ADMM (Bristow et al, 2013)
 - ADMM + FFT (Wohlberg, 2016)
 - L-BFGS (Jas et al, 2017)
 - LGCD (Dupré la Tour et al, 2018)
- D-step

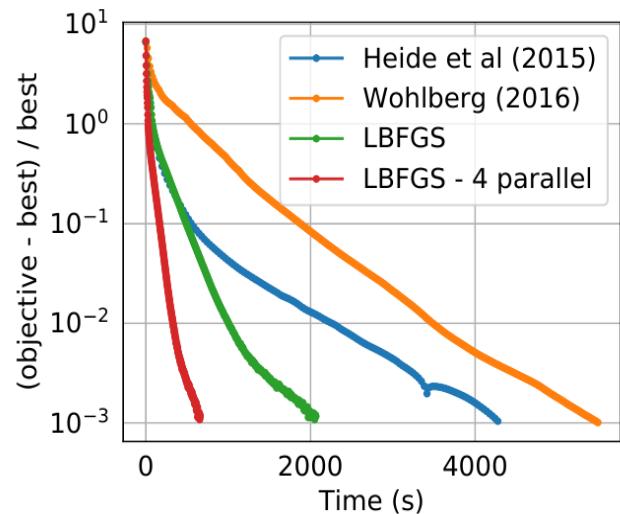
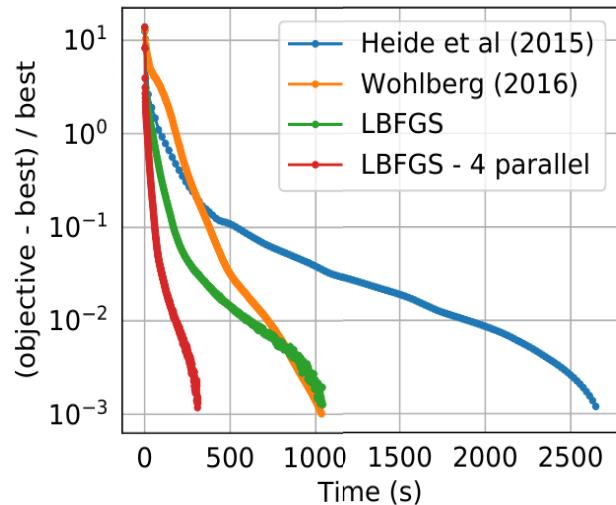
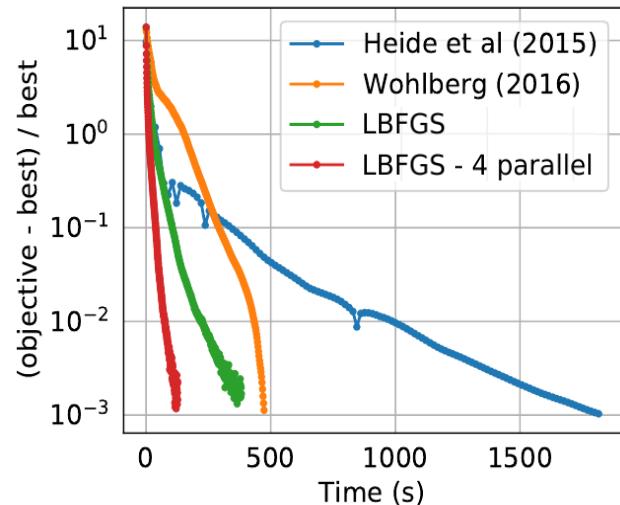
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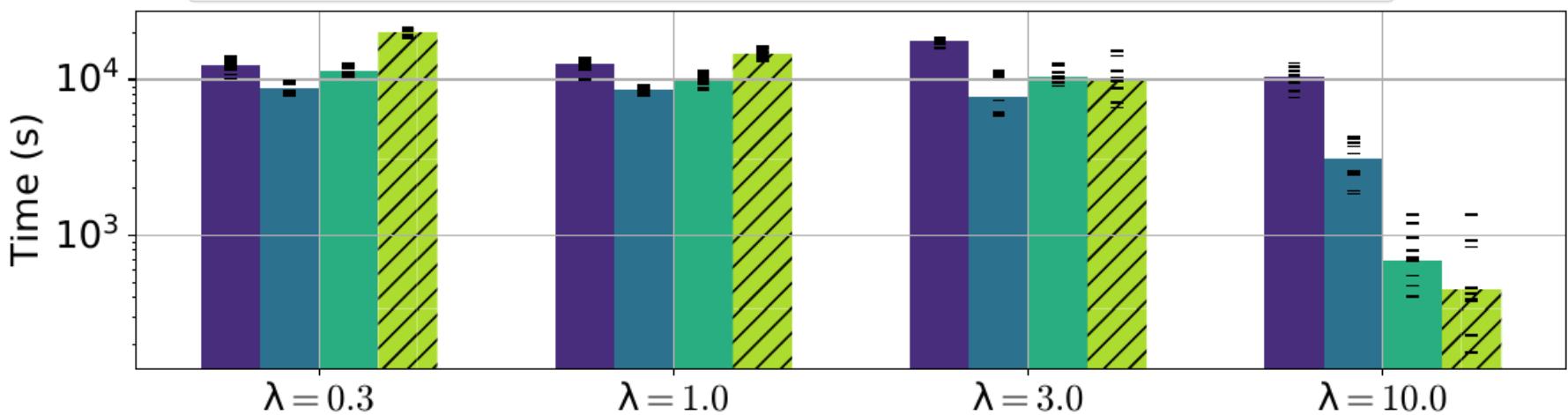
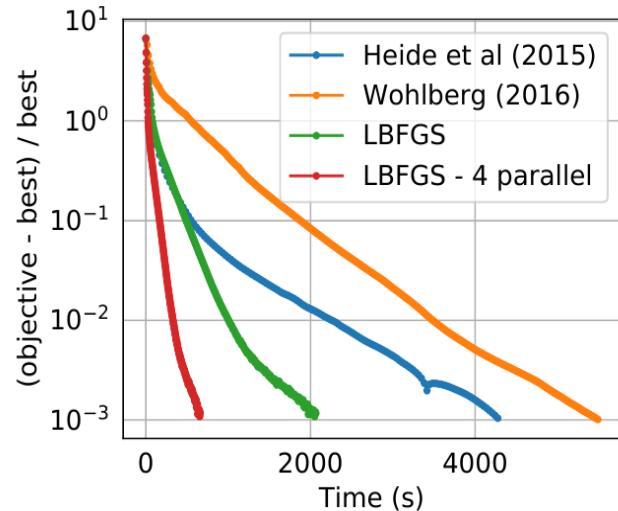
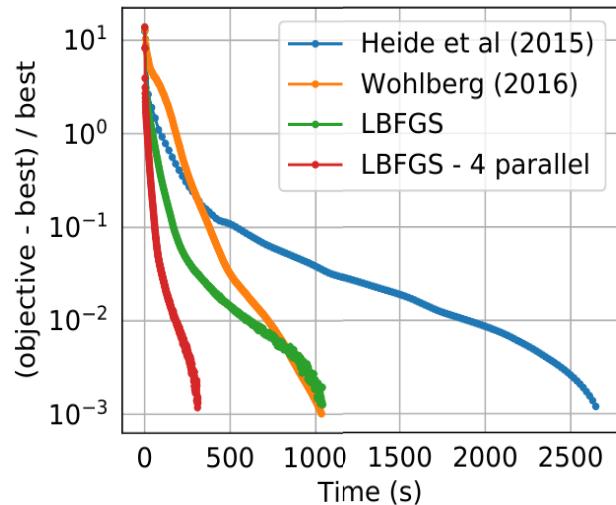
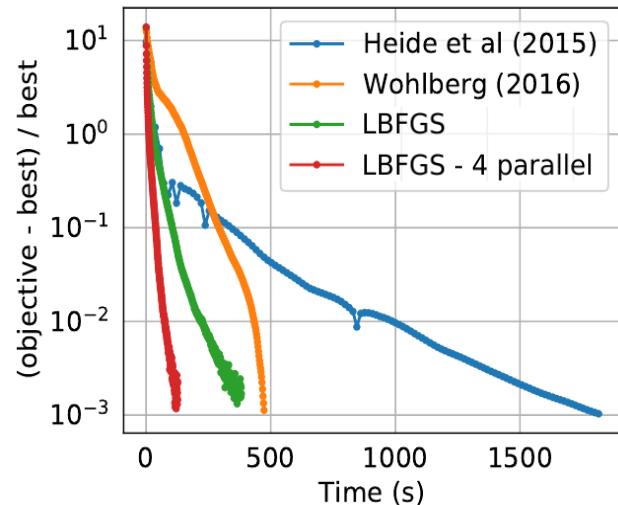
Block-coordinate descent

- Z-step
 - GCD (Kavukcuoglu et al, 2010)
 - FISTA (Chalasani et al, 2013)
 - ADMM (Bristow et al, 2013)
 - ADMM + FFT (Wohlberg, 2016)
 - L-BFGS (Jas et al, 2017) (Jas et al, 2017)
 - LGCD (Dupré la Tour et al, 2018)
- D-step
 - FFT (Grosse et al, 2007)
 - ADMM + FFT (Heide et al, 2015)
 - ADMM + FFT (Wohlberg, 2016)
 - L-BFGS (dual) (Jas et al, 2017) (Jas et al, 2017)
 - PGD (Dupré la Tour et al, 2018)

Speed benchmarks



Speed benchmarks



Second challenge: strong artifacts

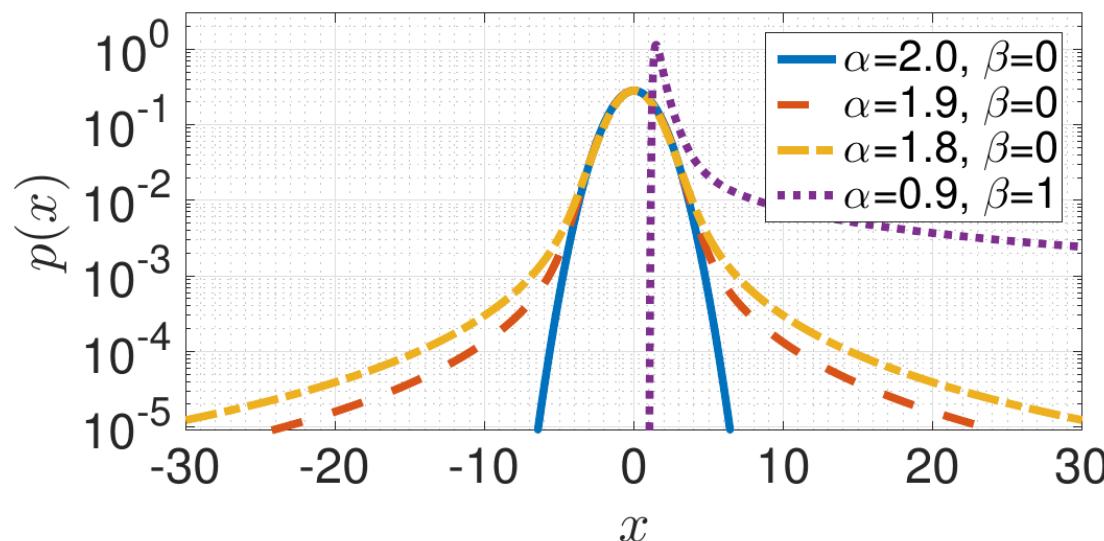
Gaussian CSC model

$$\hat{x}^n \triangleq \sum_{k=1}^K z_k^n * d_k$$

$$z_k^n[t] \sim \mathcal{E}(\lambda), \quad x^n[t]|z, d \sim \mathcal{N}(\hat{x}^n[t], 1),$$

Alpha-stable CSC model

$$z_k^n[t] \sim \mathcal{E}(\lambda), \quad x^n[t]|z, d \sim \mathcal{S}(\alpha, 0, 1/\sqrt{2}, \hat{x}^n[t])$$



Second challenge: strong artifacts

Gaussian CSC model

$$\hat{x}^n \triangleq \sum_{k=1}^K z_k^n * d_k$$

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Alpha-stable CSC model

$$z_k^n[t] \sim \mathcal{E}(\lambda), \quad x^n[t]|z, d \sim \mathcal{S}(\alpha, 0, 1/\sqrt{2}, \hat{x}^n[t])$$

Conditional formulation (Samorodnitsky and Taqqu, 1994)

$$z_k^n[t] \sim \mathcal{E}(\lambda), \quad \phi^n[t] \sim \mathcal{S}\left(\frac{\alpha}{2}, 1, 2\left(\cos \frac{\pi \alpha}{4}\right)^{2/\alpha}, 0\right)$$

$$x^n[t]|z, d, \phi \sim \mathcal{N}\left(\hat{x}^n[t], \frac{1}{2}\phi^n[t]\right)$$

Alpha CSC estimation

Monte Carlo Expectation-Maximization algorithm

- E-step: MCMC estimation (Chib and Greenberg, 1995)

$$w^n[t]^{(i)} \triangleq \mathbb{E} \left[1/\phi^n[t] \right]_{p(\phi|x, z^{(i)}, d^{(i)})}$$

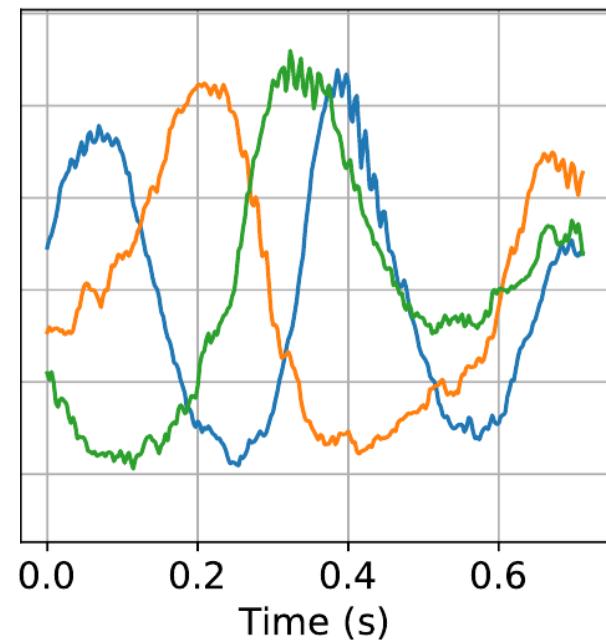
- M-step: weighted CSC

$$\min_{d, z} \sum_{n=1}^N \frac{1}{2} \left\| \sqrt{w^n} \odot \left(x^n - \sum_{k=1}^K z_k^n * d_k \right) \right\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1$$

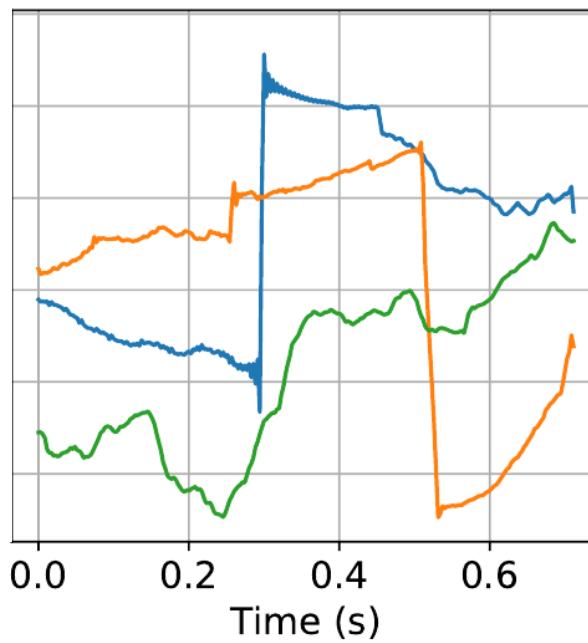
$$\text{s.t. } \|d_k\|_2^2 \leq 1, \text{ and } z_k^n \geq 0, \quad \forall k, n.$$

Learned atoms

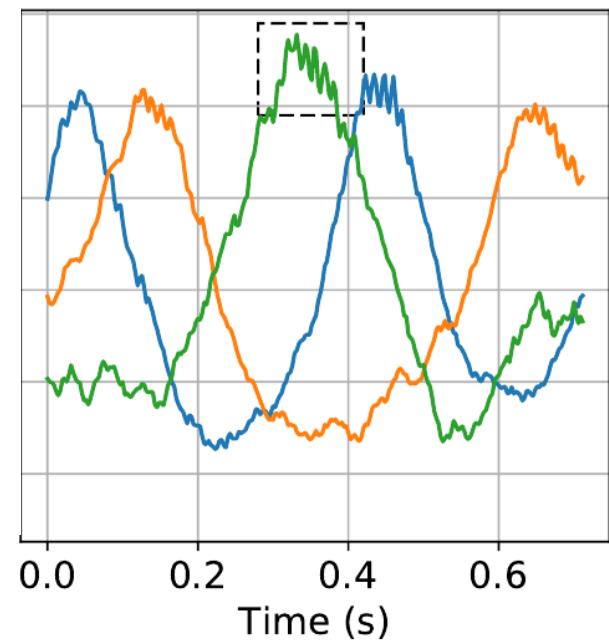
CSC (without artifacts)



CSC (with artifacts)



Alpha CSC (with artifacts)



Learning the morphology of brain signals using alpha-stable convolutional sparse coding

M. Jas, T. Dupré la Tour, U. Şimşekli, A. Gramfort, NeurIPS 2017

Third challenge: multivariate models

MEG



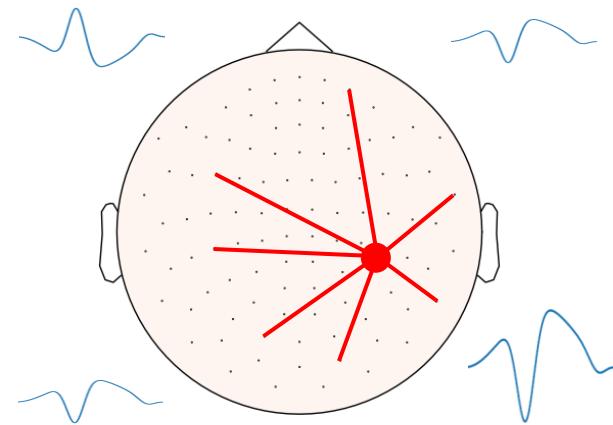
Third challenge: multivariate models

$$\begin{aligned} \min_{D, z} \sum_{n=1}^N \frac{1}{2} \left\| X^n - \sum_{k=1}^K z_k^n * D_k \right\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1, \\ \text{s.t. } \|D_k\|_2^2 \leq 1 \text{ and } z_k^n \geq 0. \end{aligned}$$

Third challenge: multivariate models

$$\min_{D,z} \sum_{n=1}^N \frac{1}{2} \left\| X^n - \sum_{k=1}^K z_k^n * D_k \right\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1,$$

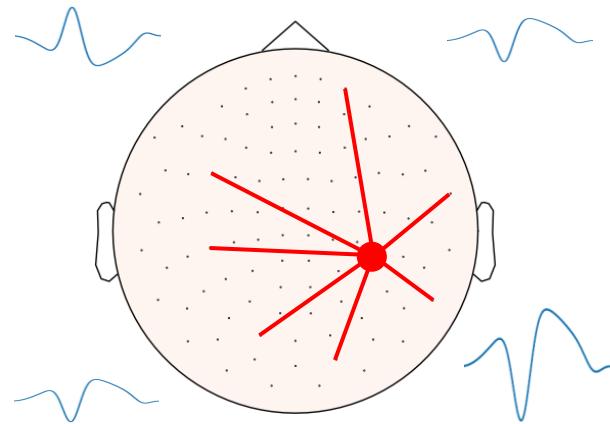
s.t. $\|D_k\|_2^2 \leq 1$ and $z_k^n \geq 0$.



Third challenge: multivariate models

$$\min_{u,v,z} \sum_{n=1}^N \frac{1}{2} \left\| X^n - \sum_{k=1}^K z_k^n * (u_k v_k^\top) \right\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1,$$

s.t. $\|u_k\|_2^2 \leq 1$, $\|v_k\|_2^2 \leq 1$ and $z_k^n \geq 0$.



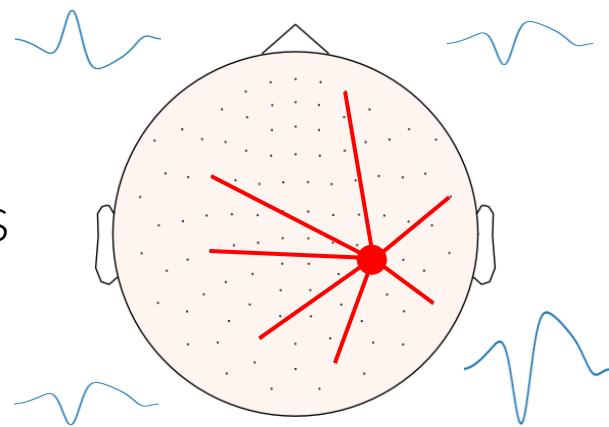
Third challenge: multivariate models

$$\min_{u,v,z} \sum_{n=1}^N \frac{1}{2} \left\| X^n - \sum_{k=1}^K z_k^n * (u_k v_k^\top) \right\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1,$$

s.t. $\|u_k\|_2^2 \leq 1$, $\|v_k\|_2^2 \leq 1$ and $z_k^n \geq 0$.

Rank-1 constraint

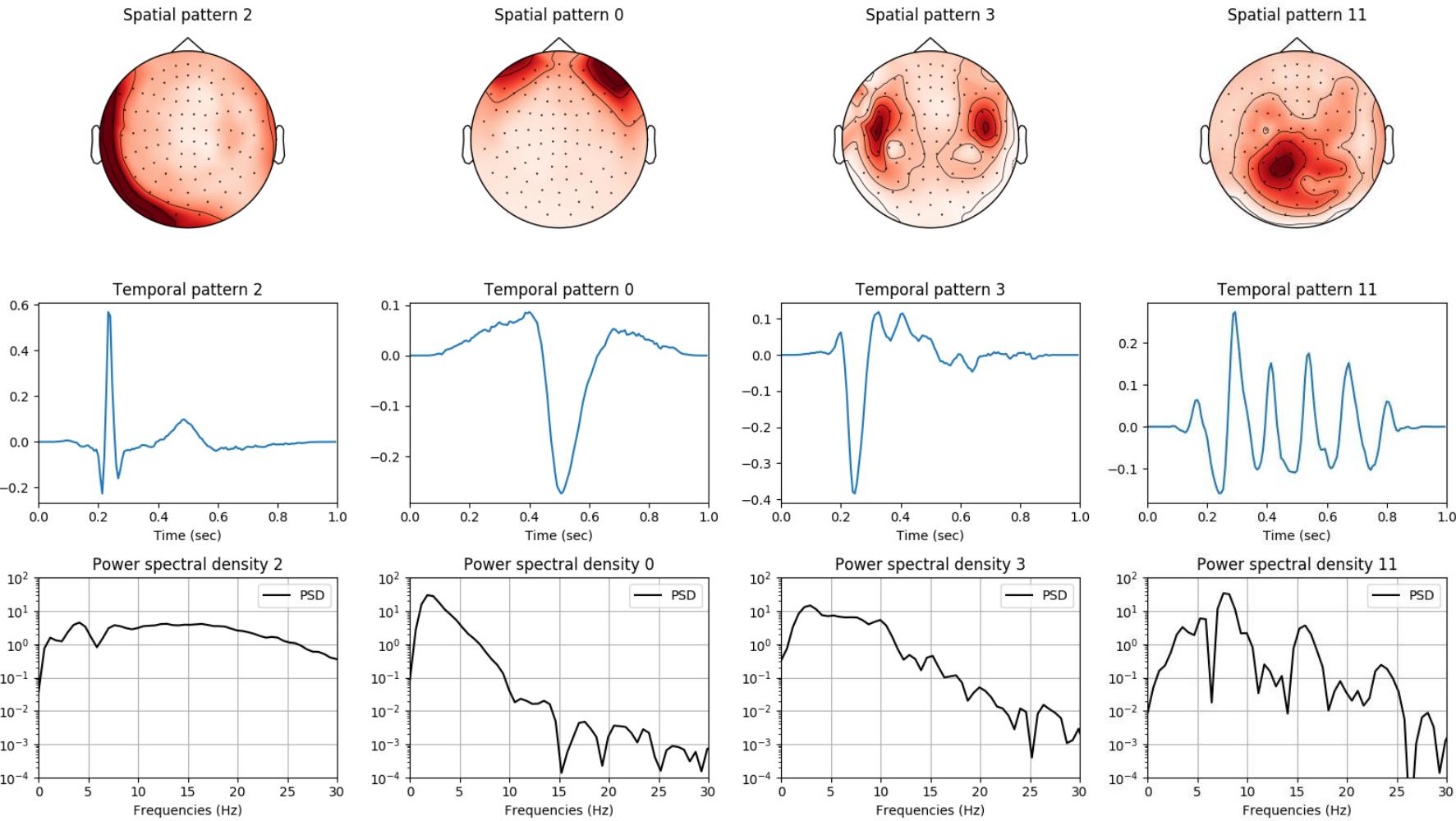
- Consistent with Physics of EM waves
- Scales in (L+P) instead of (LP)



Multivariate Convolutional Sparse Coding for Electromagnetic Brain Signals

T. Dupré la Tour*, T. Moreau*, M. Jas, A. Gramfort, NeurIPS 2018

Multivariate atoms



2. Temporal waveform analysis *with convolutional sparse coding models*

- CSC well-posed optimization problem
- State-of-the-art optimization speed
- Alpha CSC model for robustness to strong artifacts
- Multivariate CSC model, rank-1 constraint

Learning the morphology of brain signals using alpha-stable convolutional sparse coding

M. Jas, T. Dupré la Tour, U. Şimşekli, A. Gramfort, NeurIPS 2017

Multivariate Convolutional Sparse Coding for Electromagnetic Brain Signals

T. Dupré la Tour*, T. Moreau*, M. Jas, A. Gramfort, NeurIPS 2018

Conclusion

1. Cross-frequency coupling analysis
with driven autoregressive models

2. Temporal waveform analysis
with convolutional sparse coding models

Dissemination of our work

We published our code online, with:

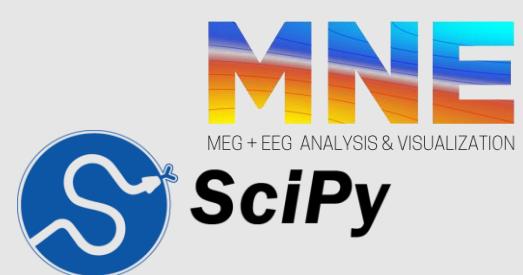
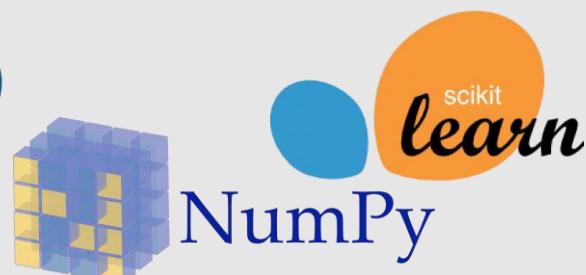
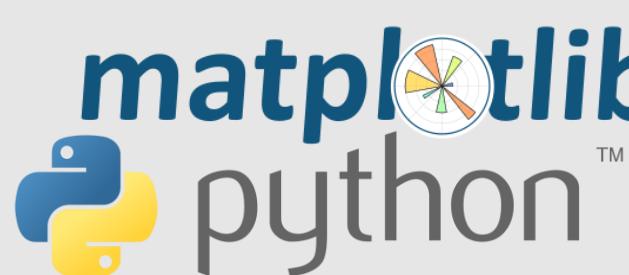
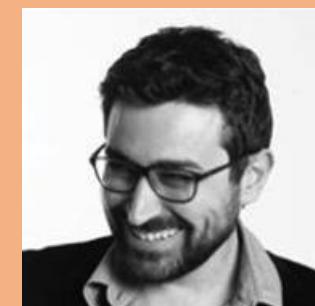
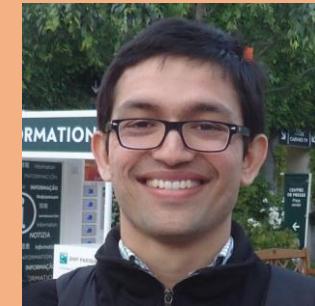
- Tests, and continuous integration
- Extensive documentation
- Gallery of examples

1. PAC metrics, DAR models

<https://pactools.github.io>

2. CSC, alpha-stable CSC, multivariate CSC, rank-1 constraint

<https://alphacsc.github.io>



Thank you for your attention

Non-linear autoregressive models for cross-frequency coupling in neural time series

T. Dupré la Tour, L. Tallot, L. Grabot, V. Doyère, V. van Wassenhove, Y. Grenier, A. Gramfort, *PLOS Computational Biology* 2017

Parametric estimation of spectrum driven by an exogenous signal

T. Dupré la Tour, Y. Grenier, A. Gramfort, *ICASSP* 2017

Driver estimation in non-linear autoregressive models

T. Dupré la Tour, Y. Grenier, A. Gramfort, *ICASSP* 2018

<https://pactools.github.io>

Learning the morphology of brain signals using alpha-stable convolutional sparse coding

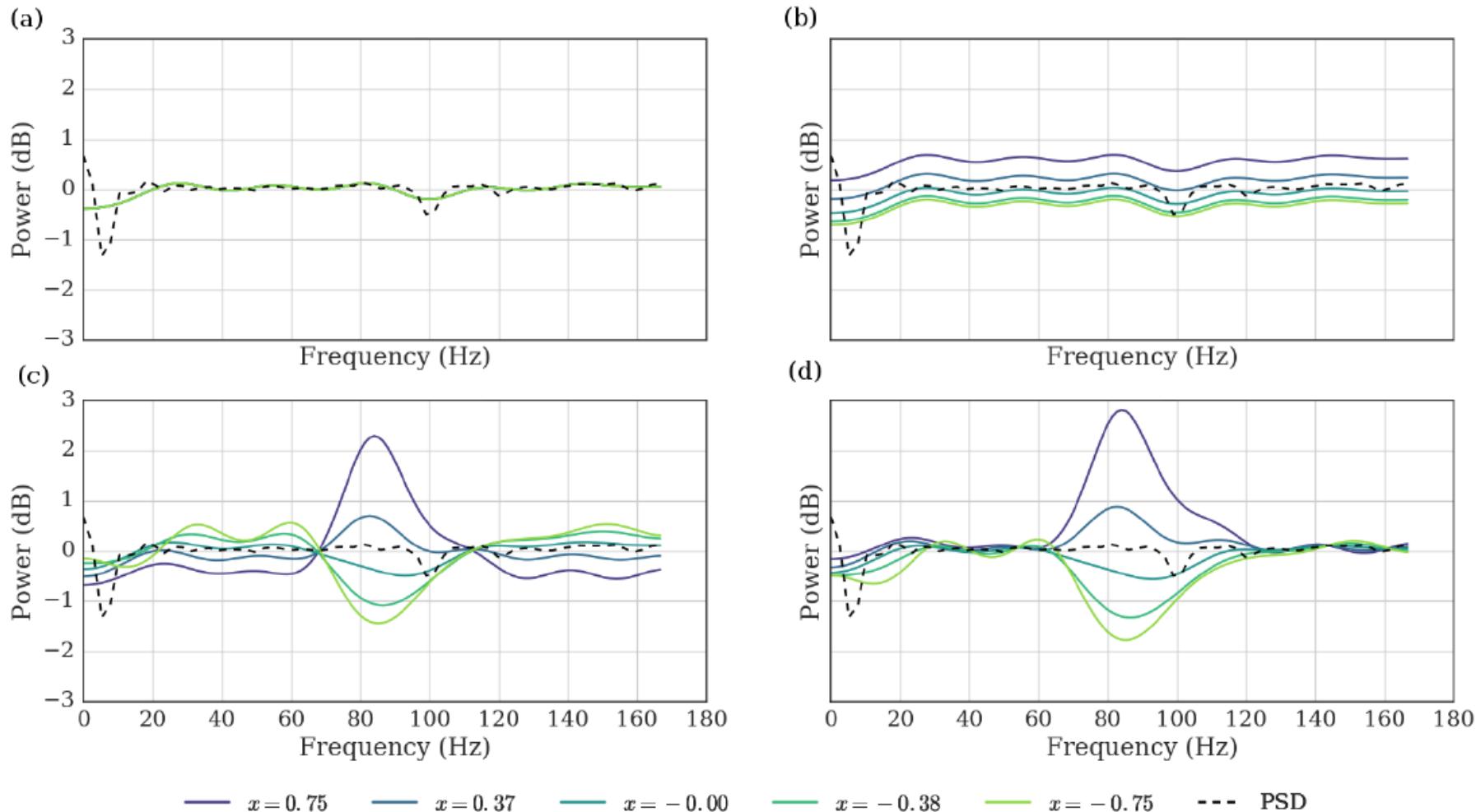
M. Jas, T. Dupré la Tour, U. Şimşekli, A. Gramfort, *NeurIPS* 2017

Multivariate Convolutional Sparse Coding for Electromagnetic Brain Signals

T. Dupré la Tour*, T. Moreau*, M. Jas, A. Gramfort, *NeurIPS* 2018

<https://alphacsc.github.io>

DAR models conditional PSD



Guarantee local stability

- AR model

$$y(t) + \sum_{i=1}^p a_i y(t-i) = \varepsilon(t)$$

- Non-stationary AR model

$$a_i(t) = \sum_{j=0}^m a_{ij} x(t)^j$$

- Lattice parameterization

$$a_p^{(p)} = k_p; \quad \forall i \in [1, p-1], \quad a_i^{(p)} = a_i^{(p-1)} + k_p a_{p-i}^{(p-1)}$$

- Local stability criterion

$$-1 < k_i < 1$$

- Log Area Ratio

$$\gamma_i = \log \left(\frac{1+k_i}{1-k_i} \right) \iff k_i = \frac{e^{\gamma_i} - 1}{e^{\gamma_i} + 1}$$

- Driven AR model

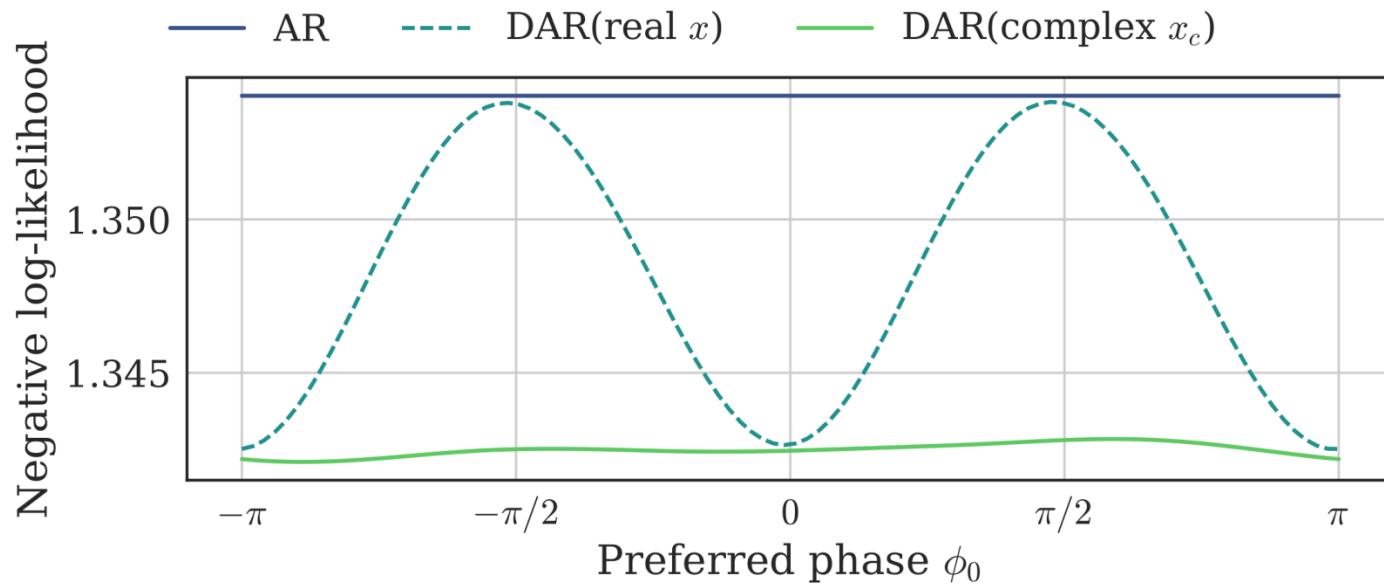
$$\gamma_i(t) = \sum_{j=0}^m \gamma_{ij} x(t)^j :$$

Using a complex driver

- With a real driver
- With a complex driver

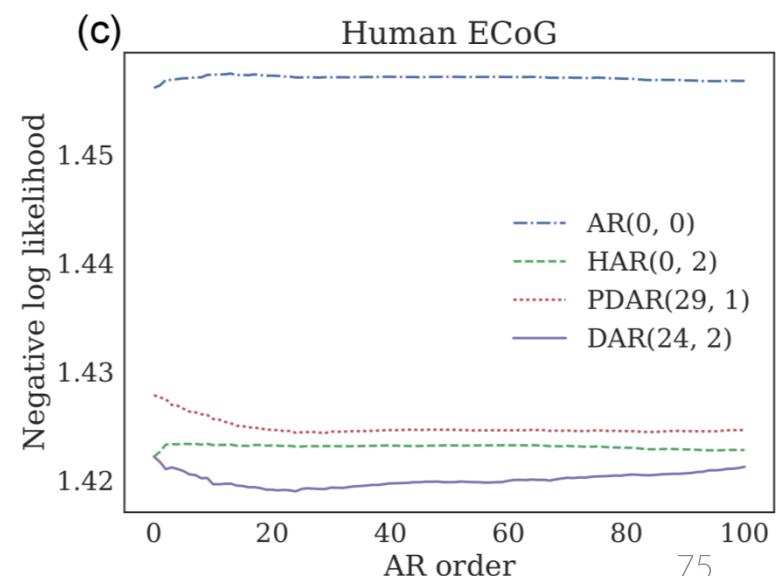
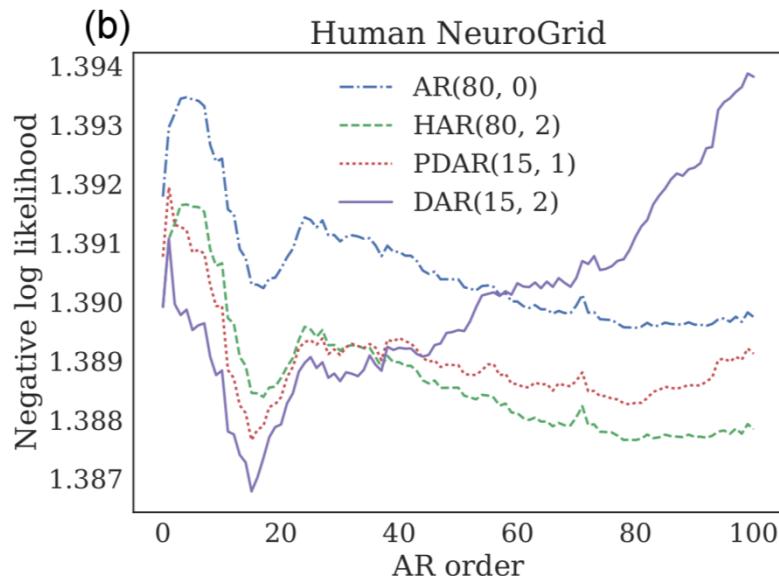
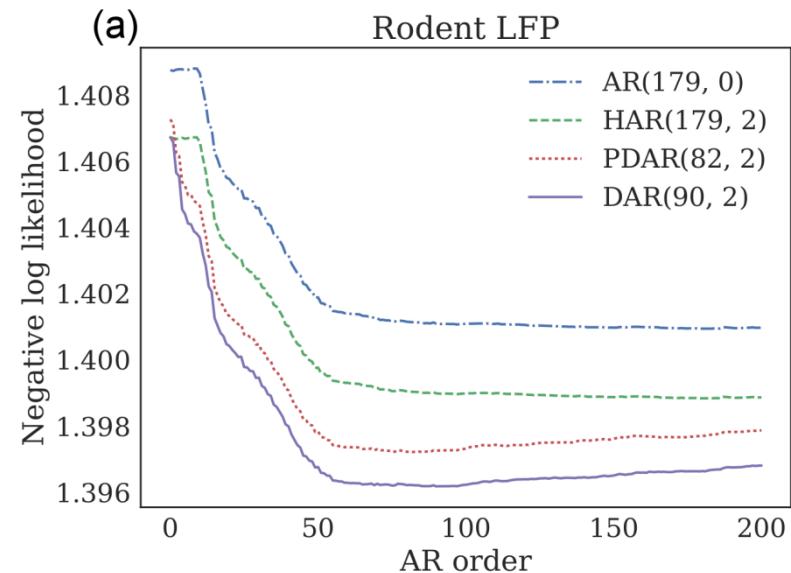
$$a_i(t) = \sum_{k=0}^m a_{ik} x(t)^k$$

$$a_i(t) = \sum_{0 \leq k+l \leq m} a_{ikl} x(t)^k \bar{x}(t)^l$$

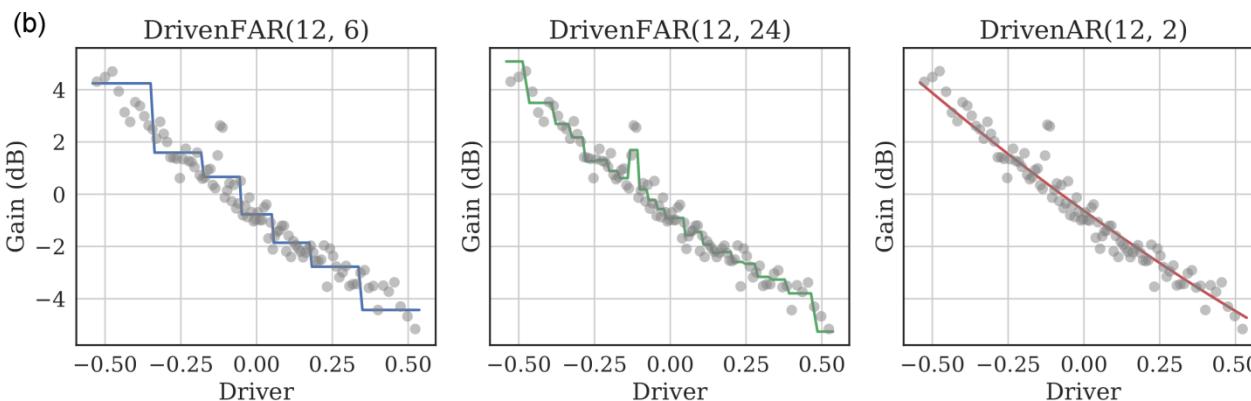
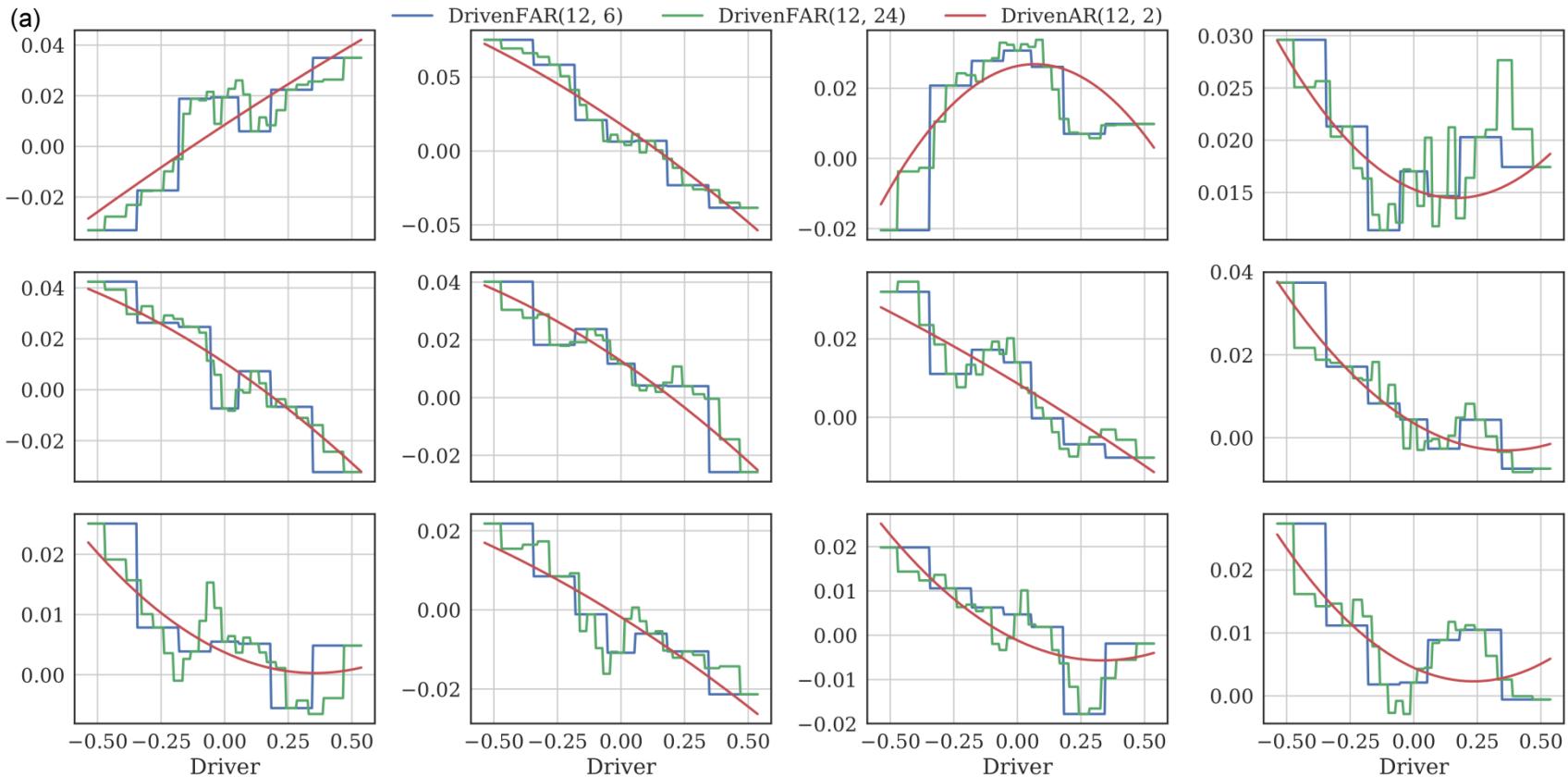


Model variants and cross-validation

- AR: linear AR model
- HAR: linear AR model + driven innovation variance
- PDAR: driven AR model with constant amplitude driver
- DAR: driven AR model



The polynomial basis is good enough



Model and parameter selection

- Likelihood function

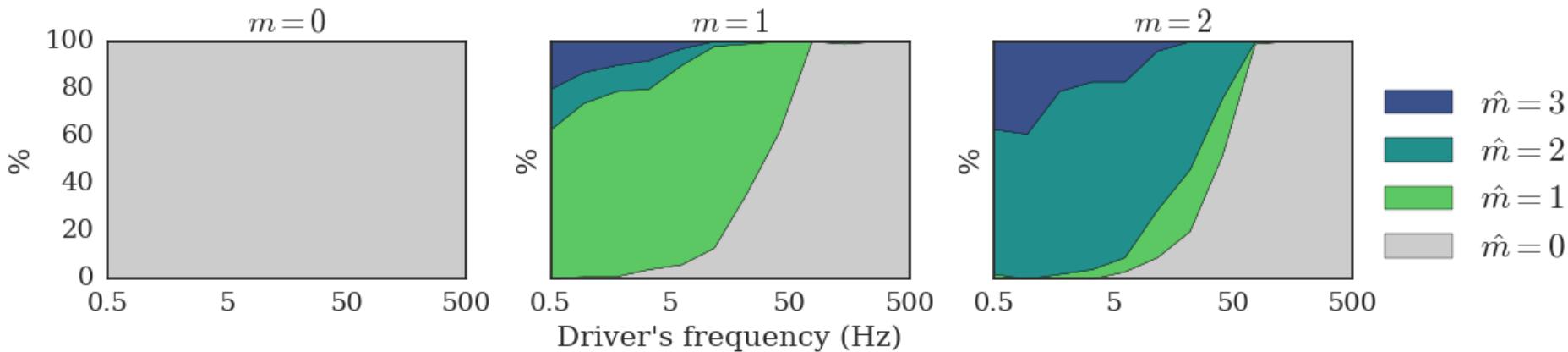
$$L = \prod_{t=p}^T \frac{1}{\sqrt{2\pi\sigma(t)^2}} \exp\left(-\frac{\varepsilon(t)^2}{2\sigma(t)^2}\right)$$

- BIC selection

$$BIC = -2 \log(L) + d \log(T)$$

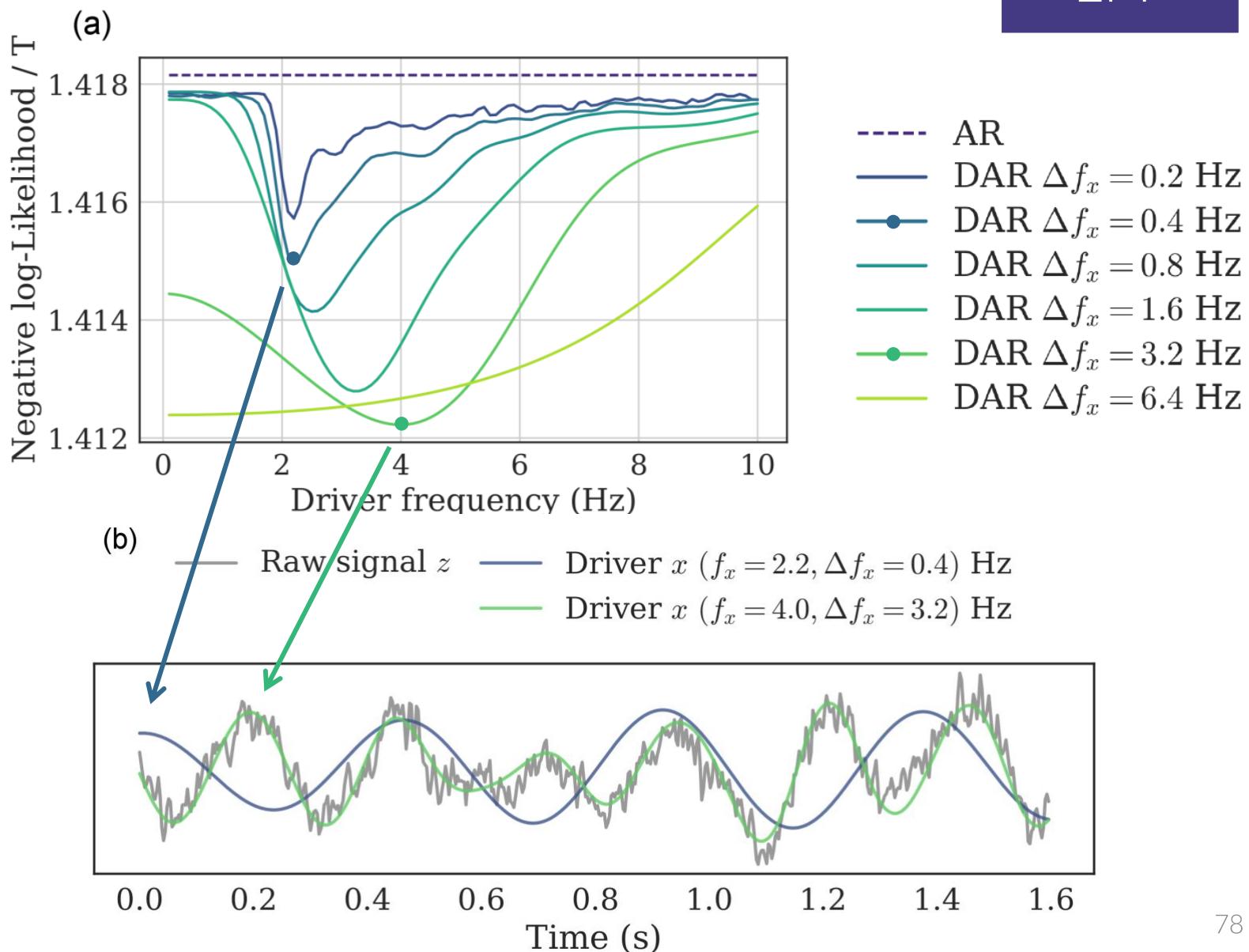
$$d = (p+1)(m+1)$$

- Testing the limits

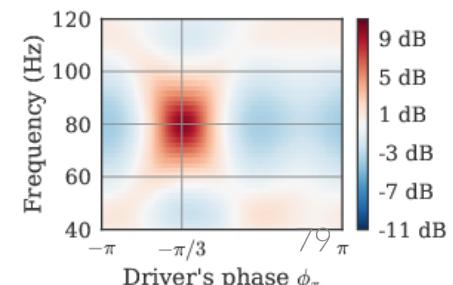
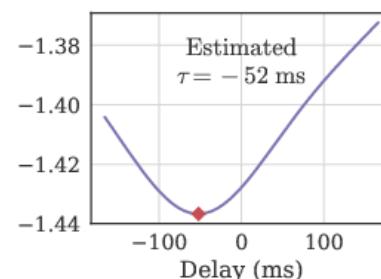
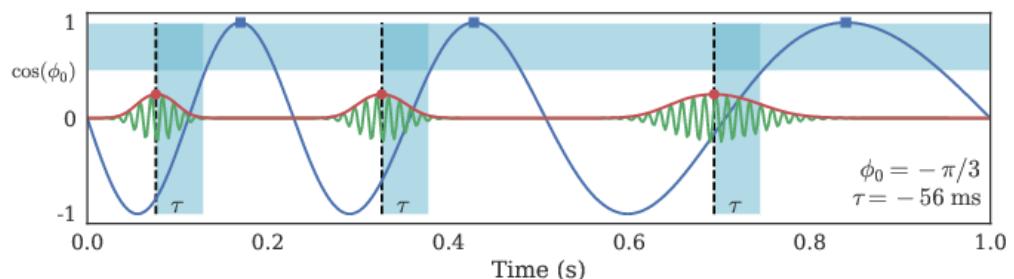
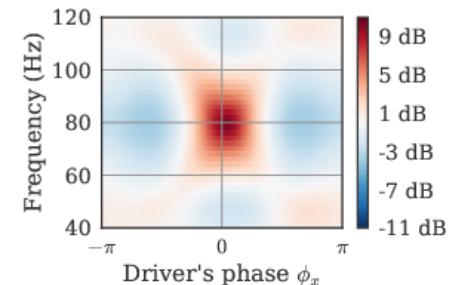
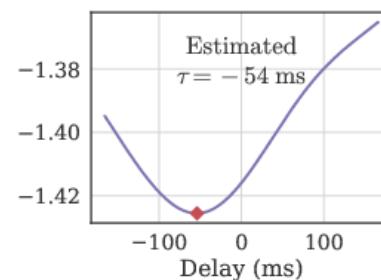
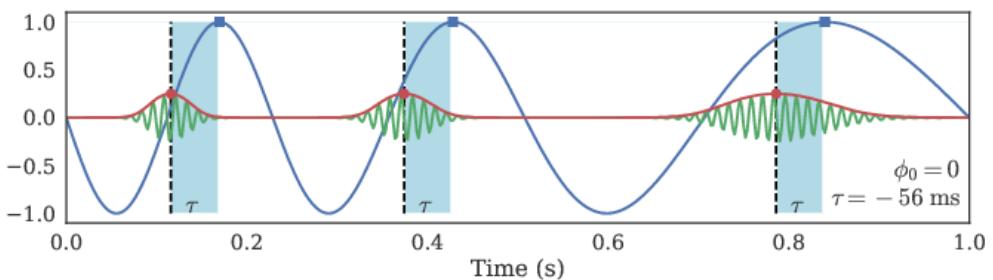
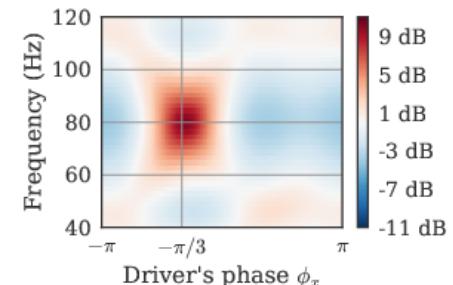
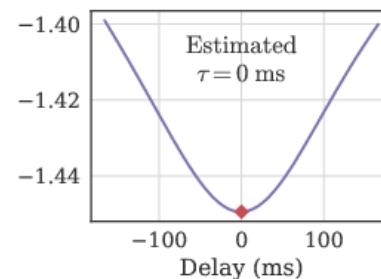
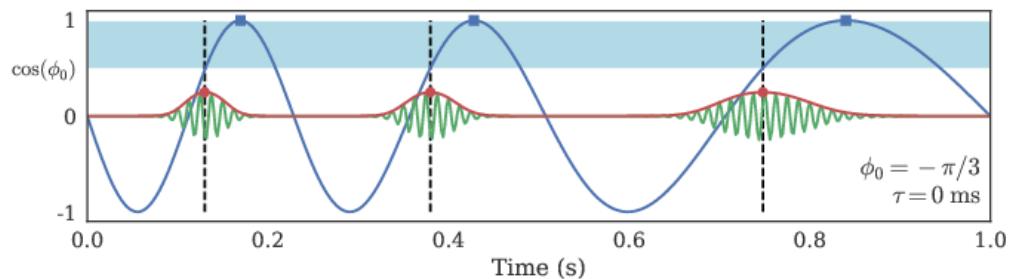
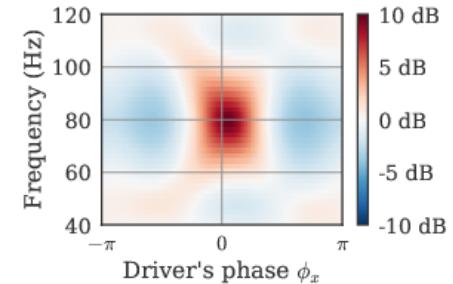
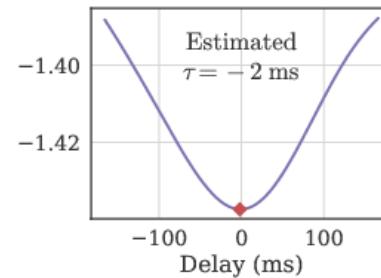
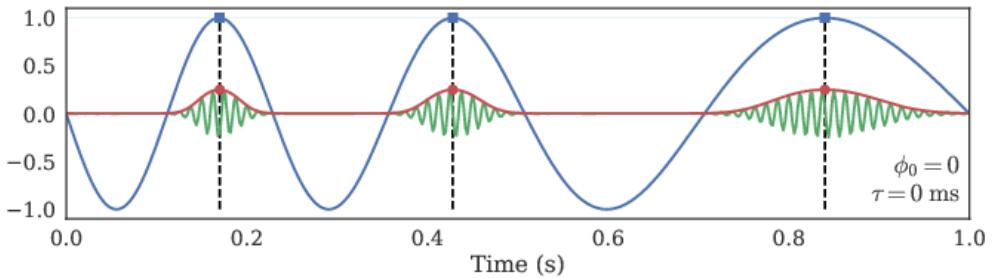


Driver selection

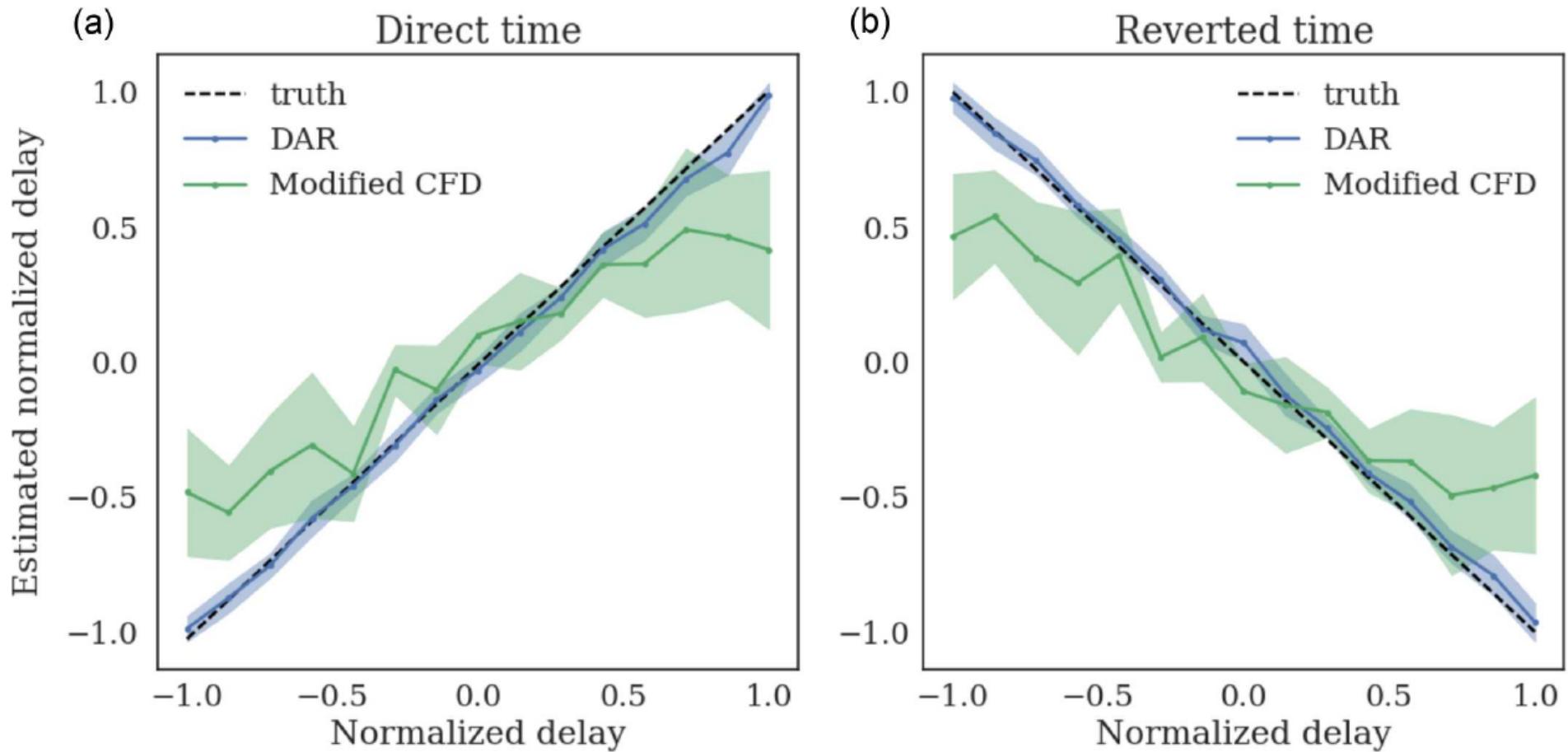
LFP



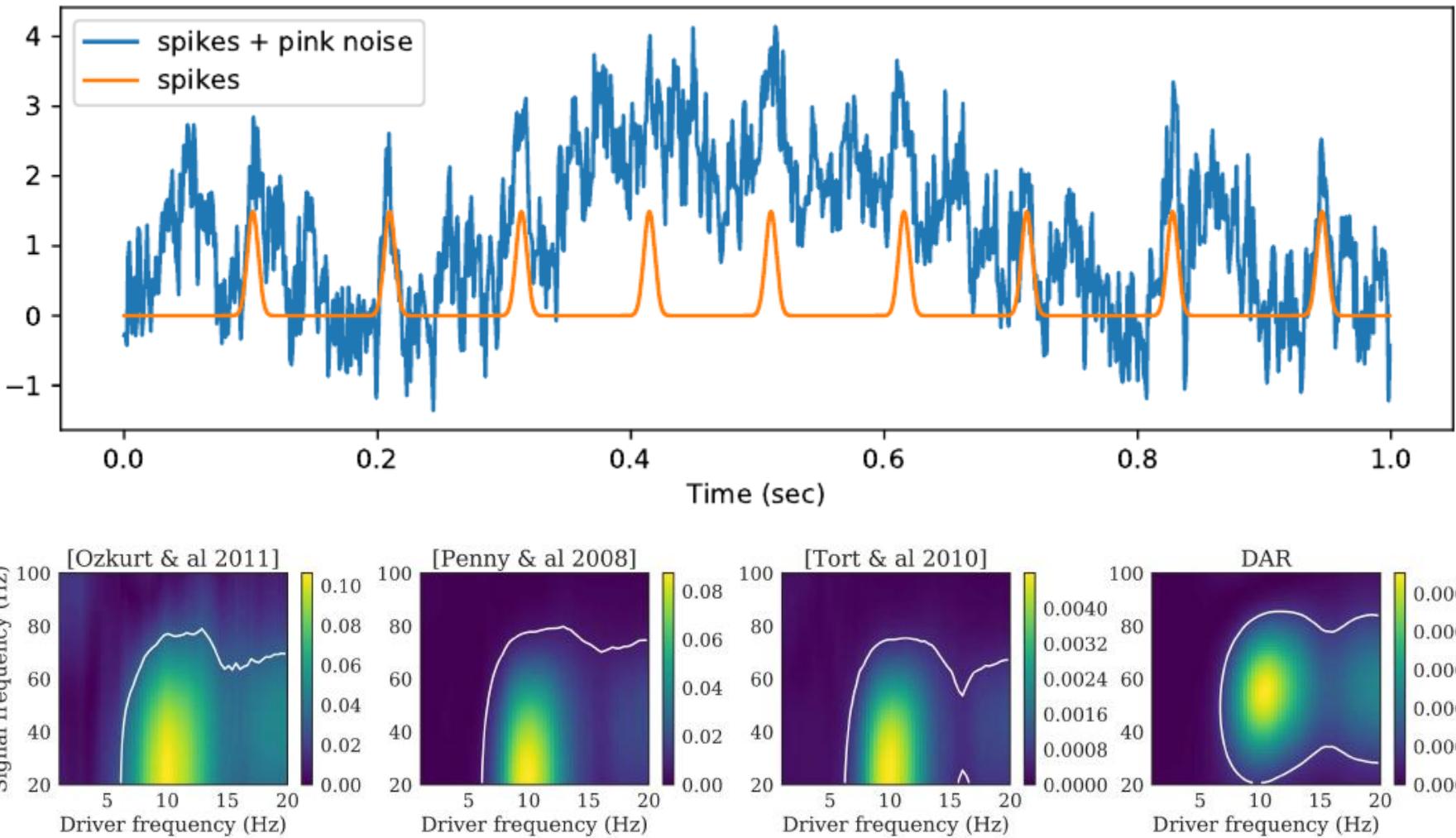
Time delay and preferred phase



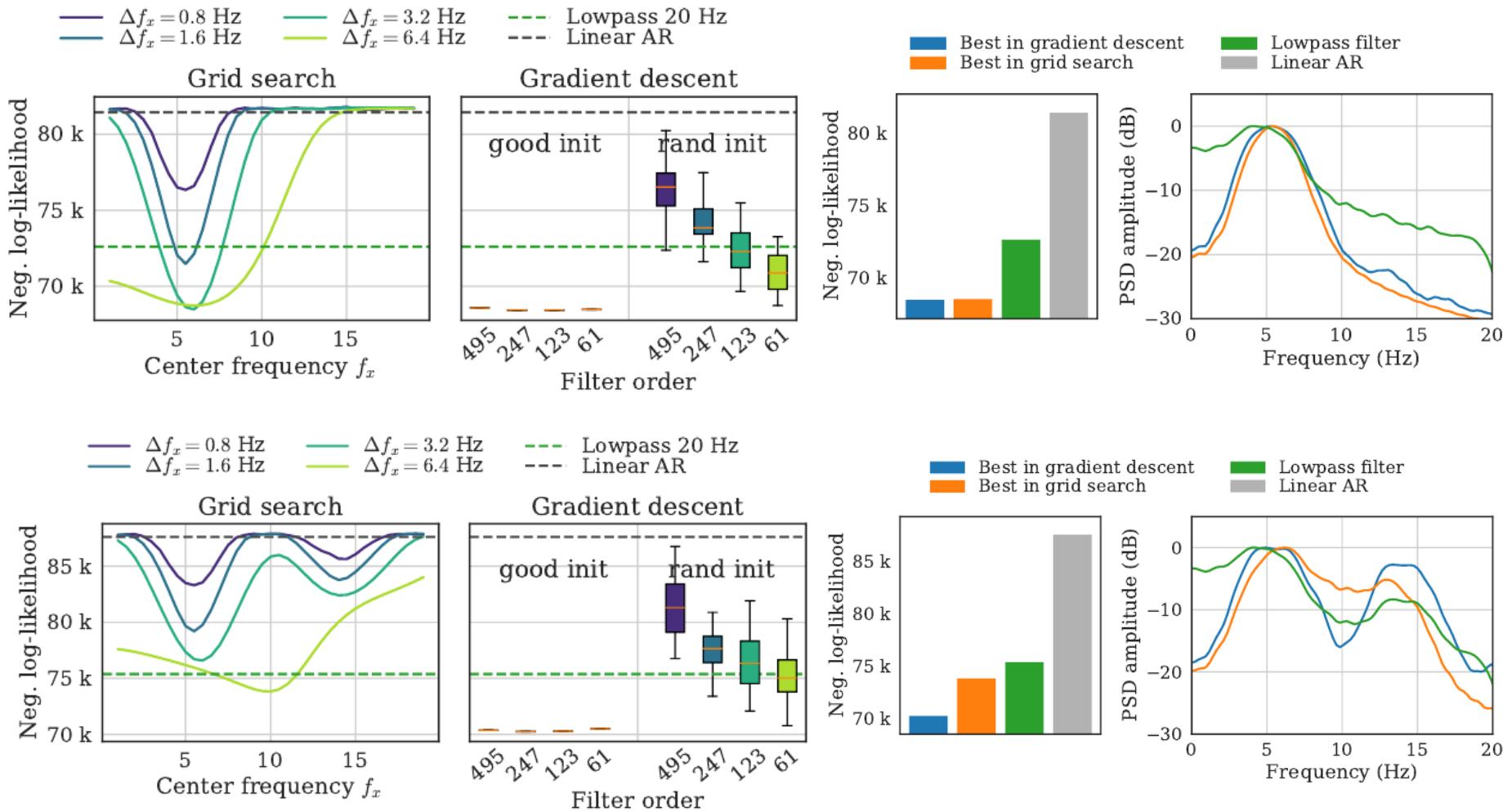
Delay estimation on simulations



Spurious CFC simulation

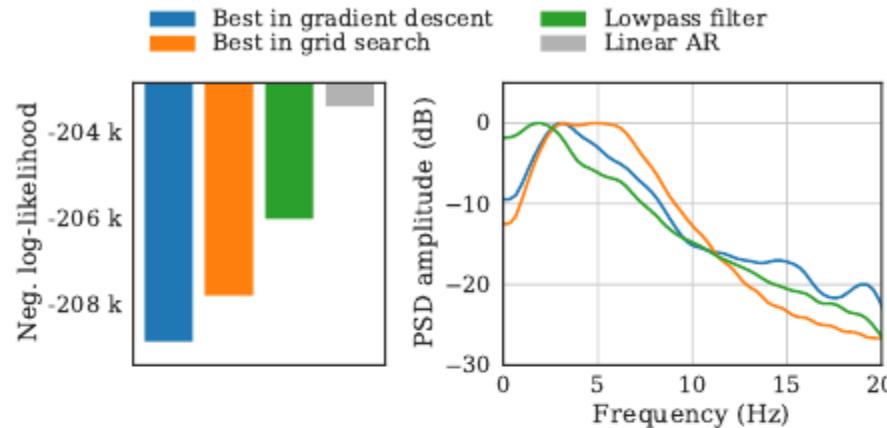


Driver filter estimation

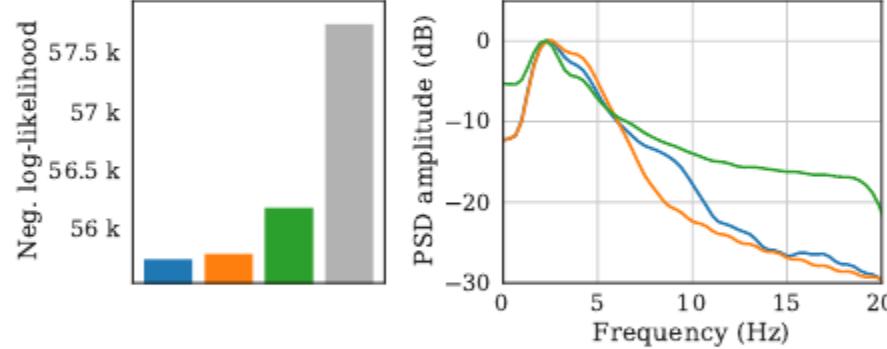


Driver filter estimation

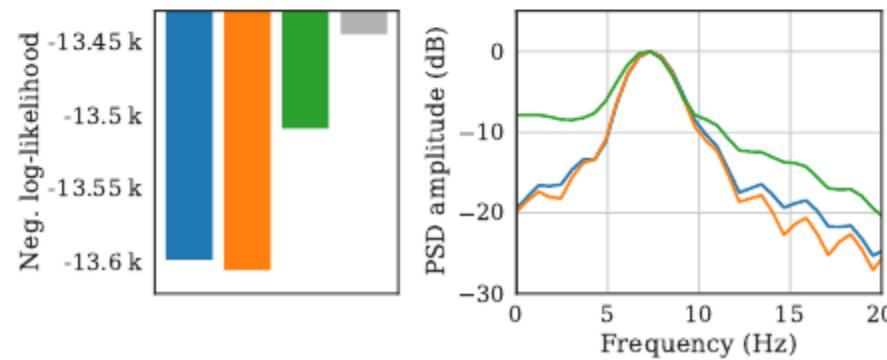
ECoG



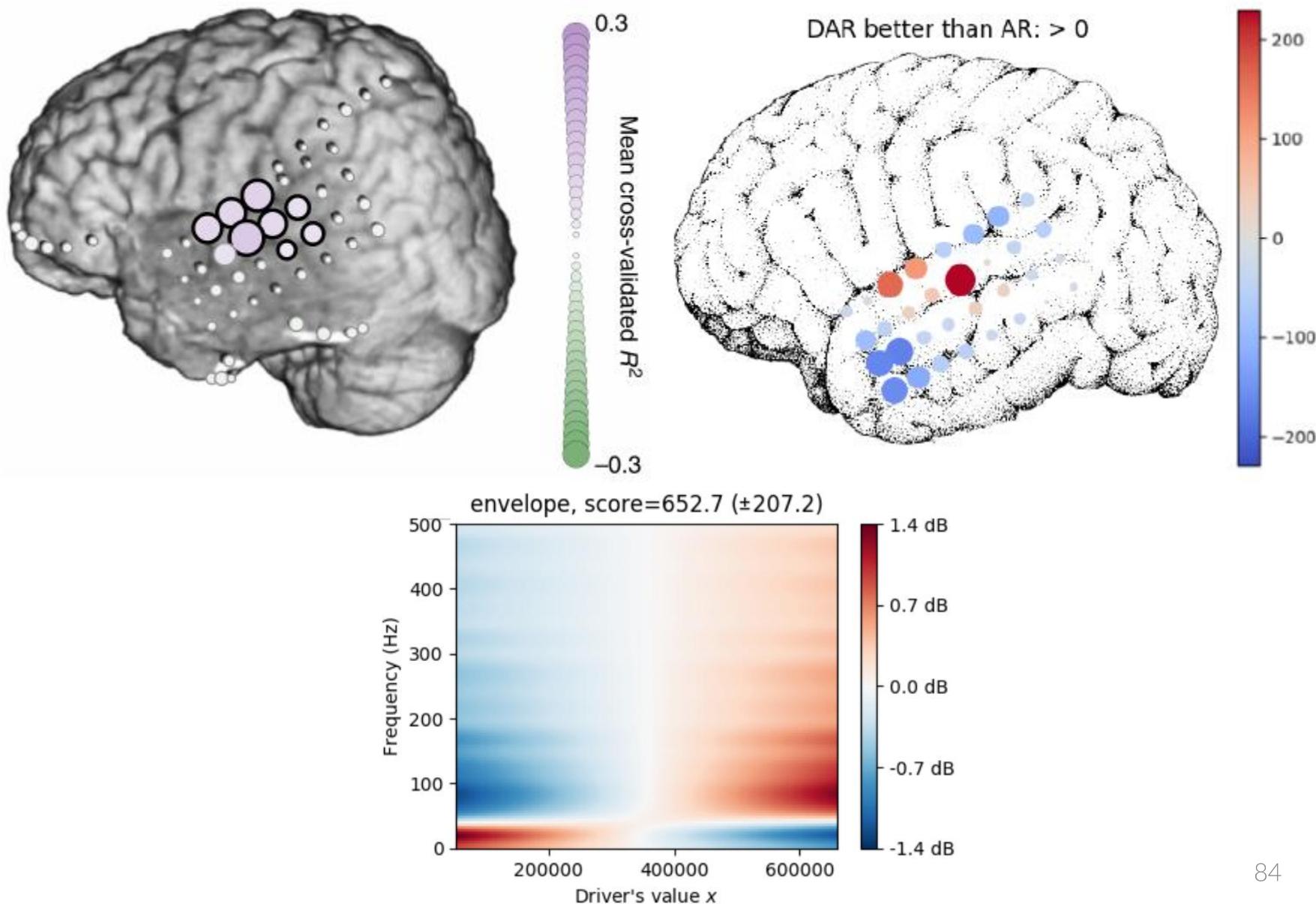
LFP



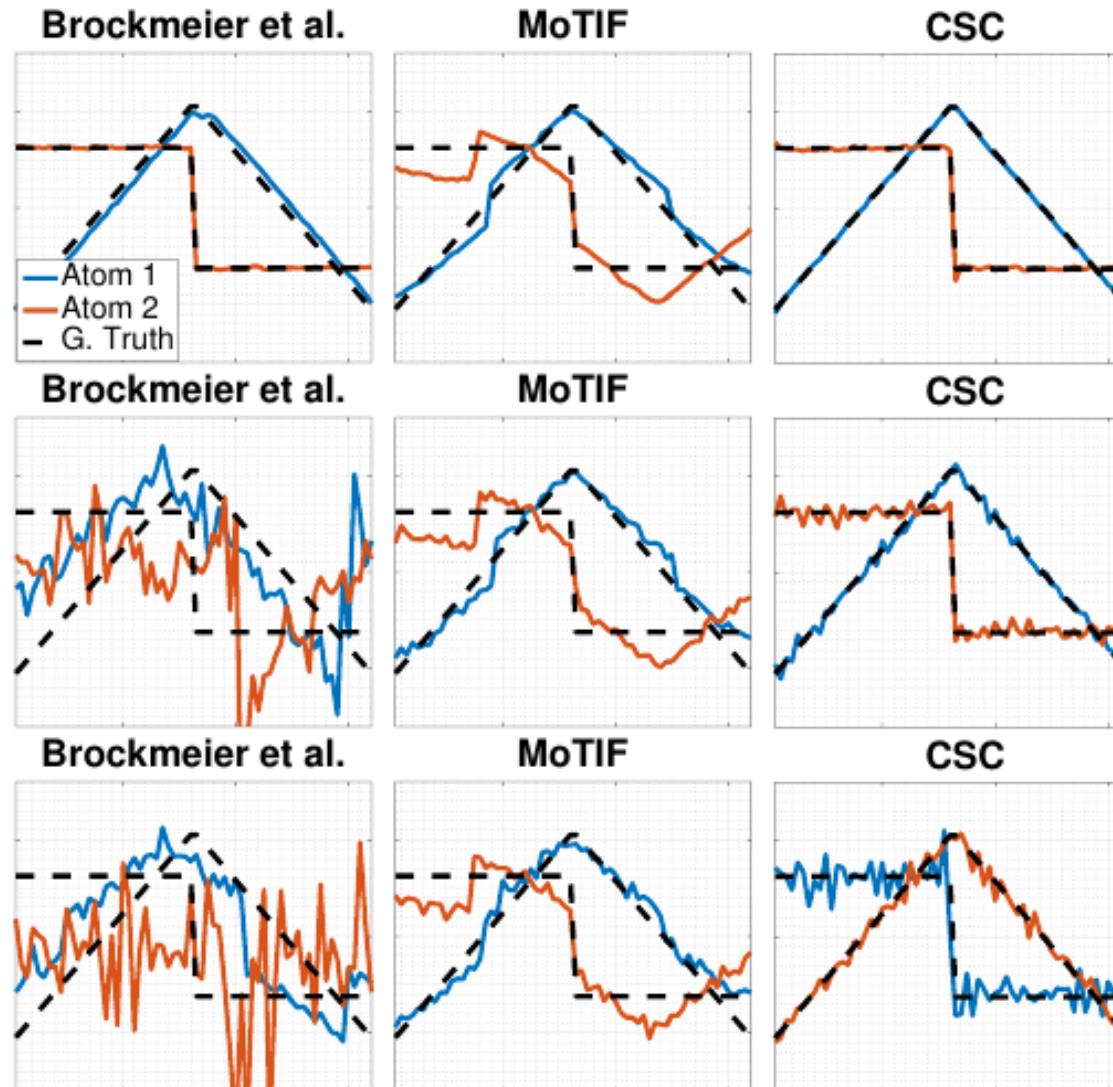
LFP



Encoding DAR model



Shift-invariant sparse coding comparison

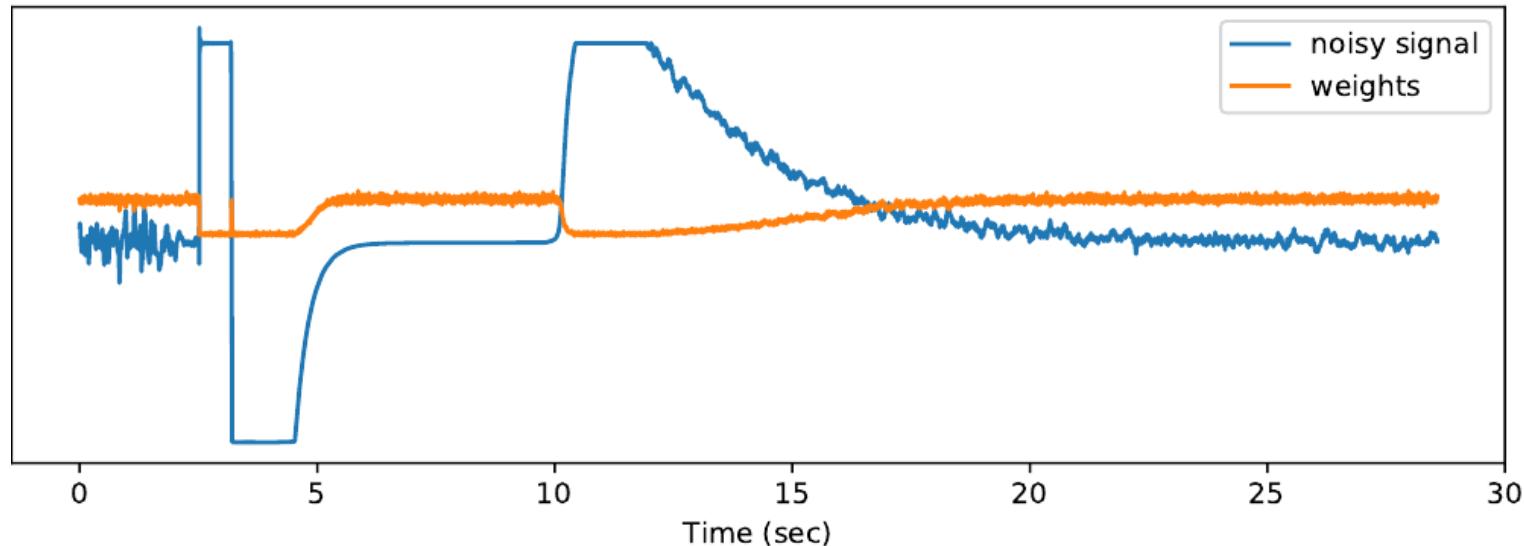


Weights in alpha CSC

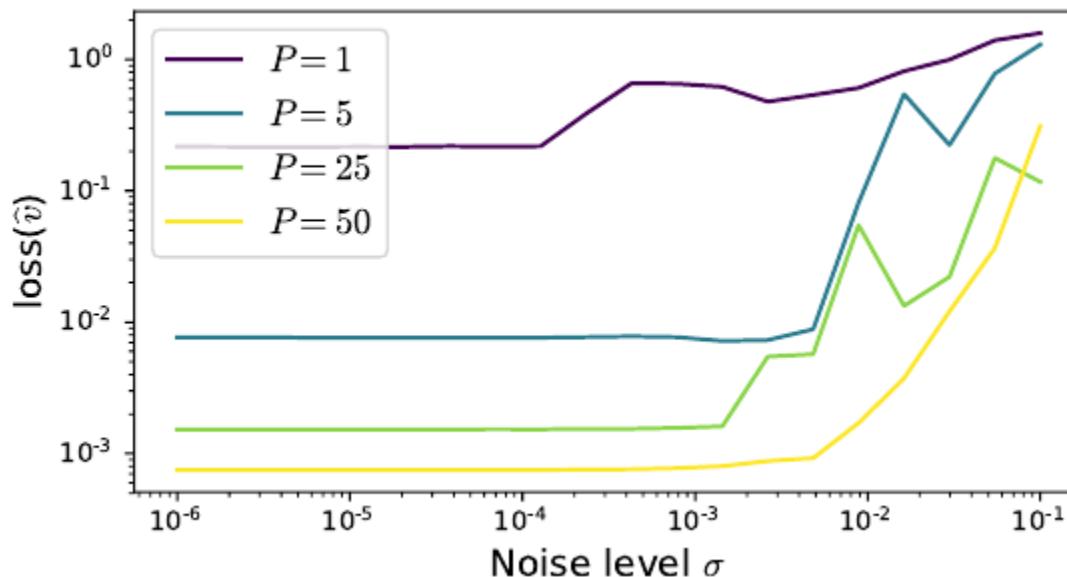
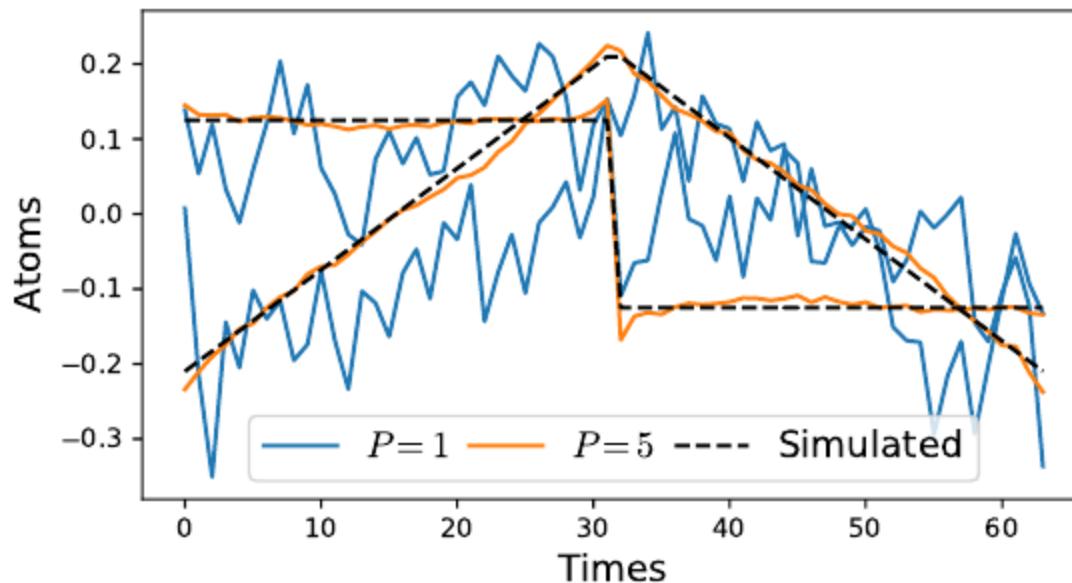
Expectation-Maximization algorithm

E-step

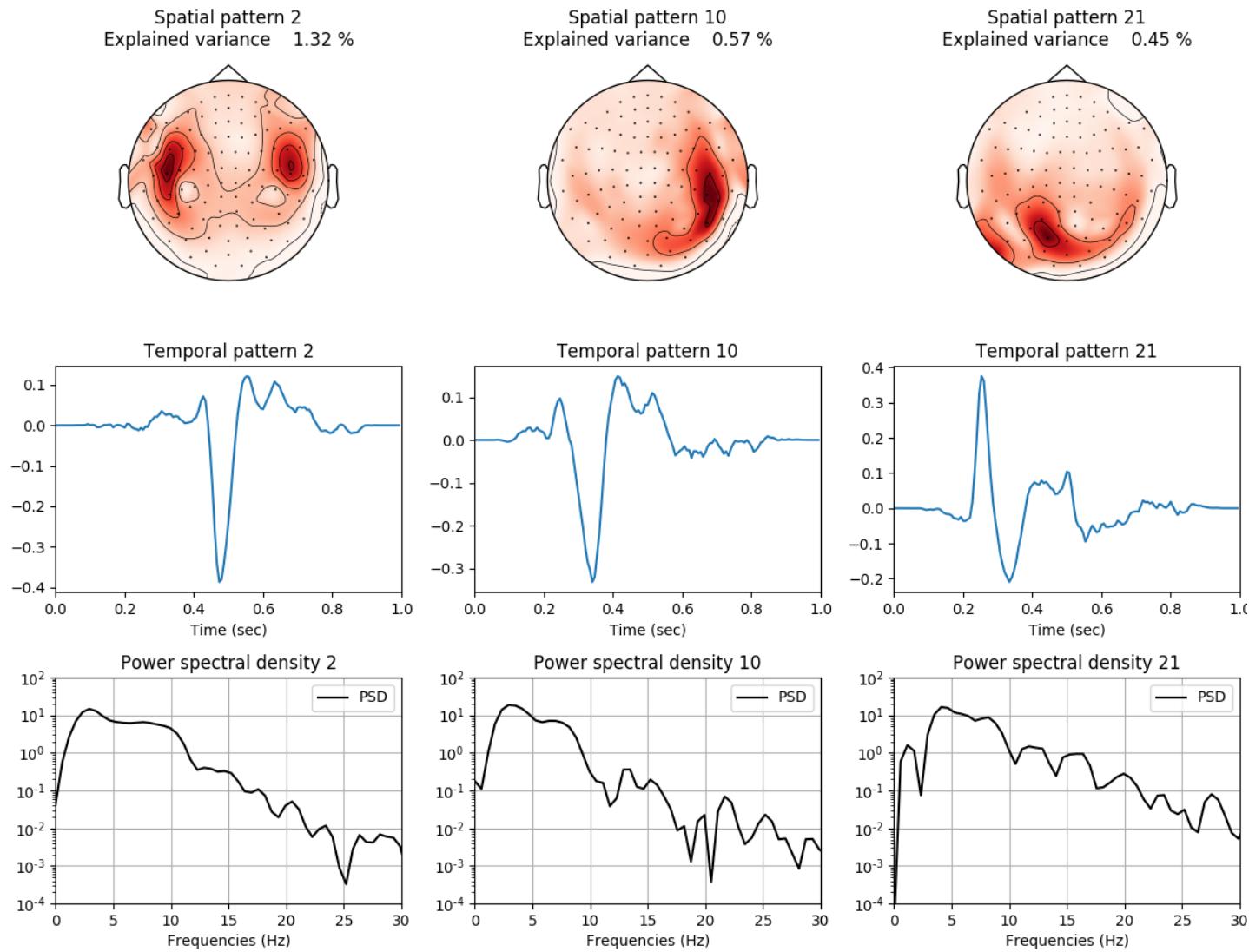
$$w^n[t]^{(i)} \triangleq \mathbb{E} \left[1/\phi^n[t] \right]_{p(\phi|x, z^{(i)}, d^{(i)})}$$

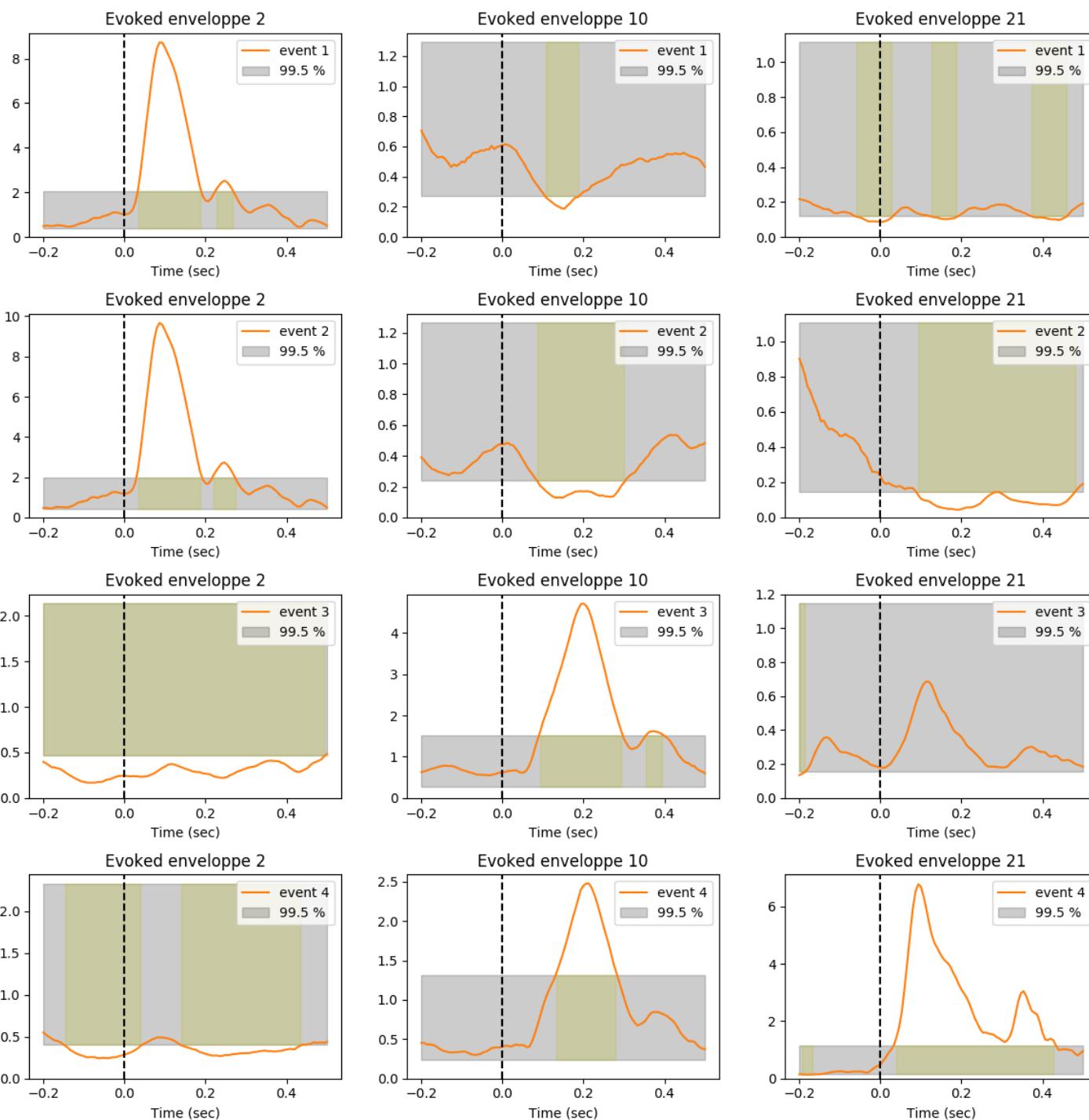


Simulations on multivariate CSC

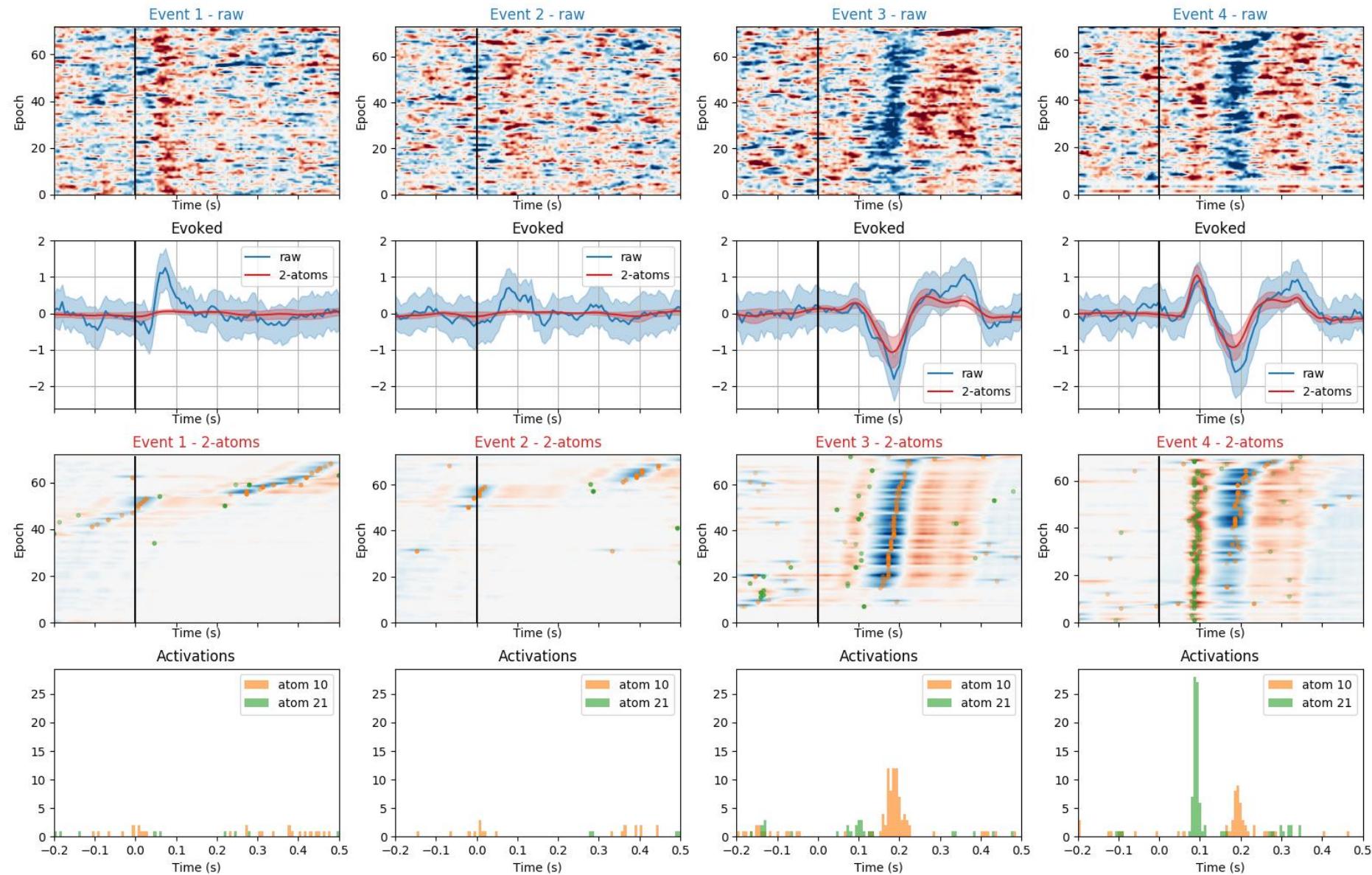


Event-related atoms

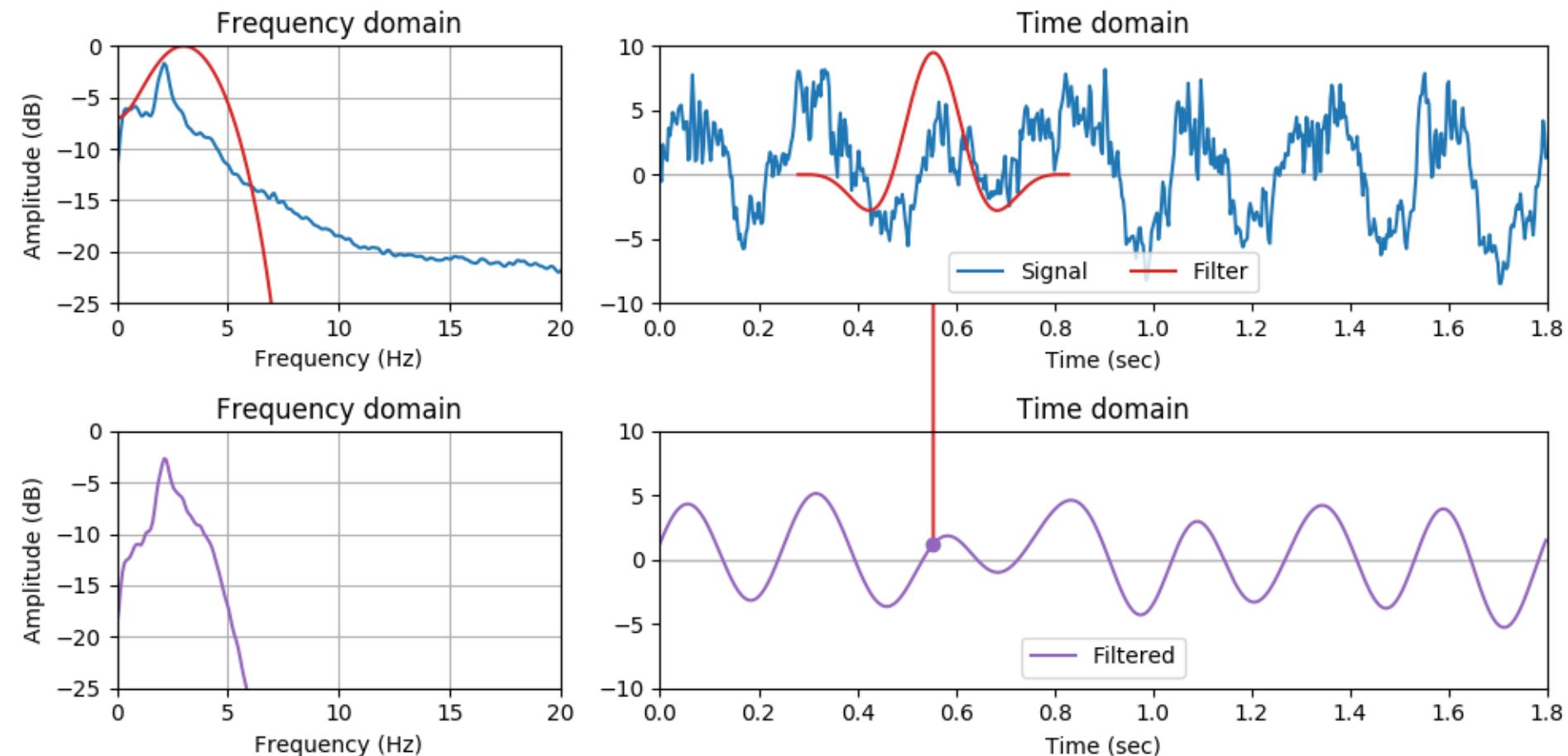




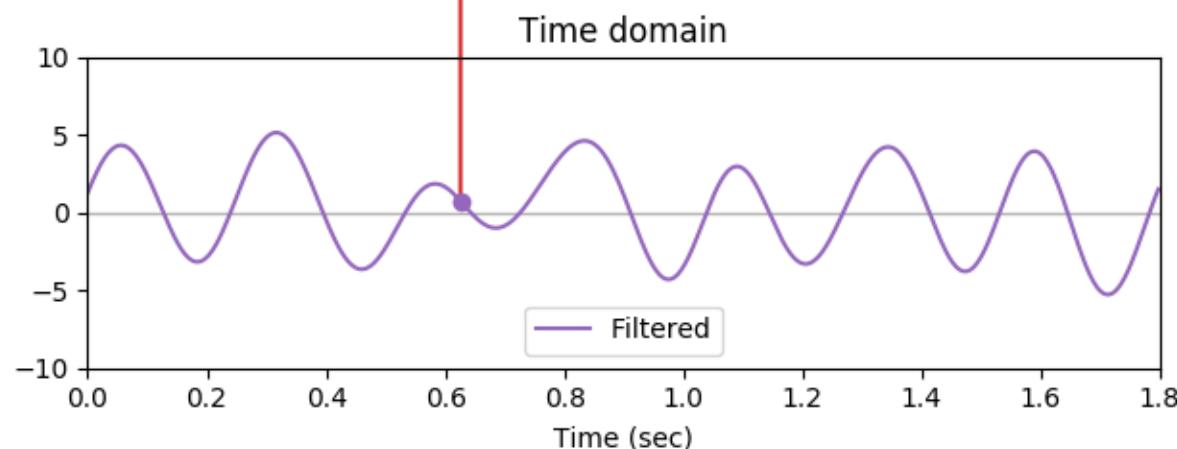
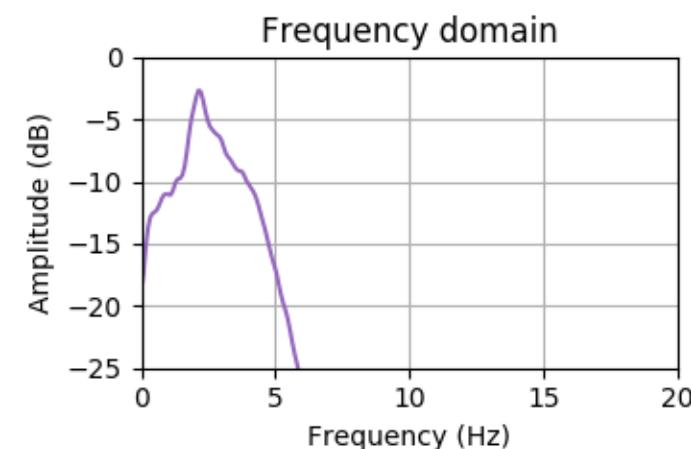
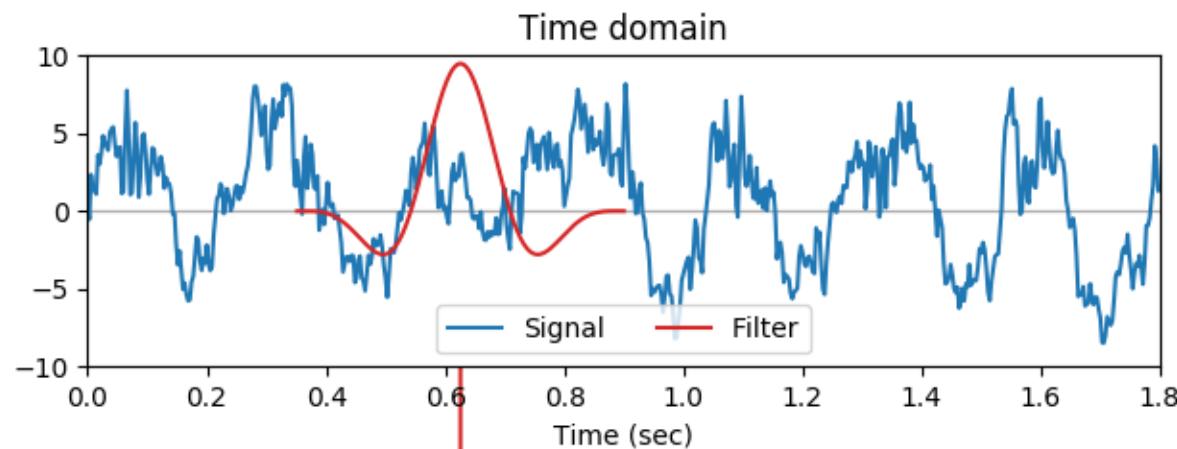
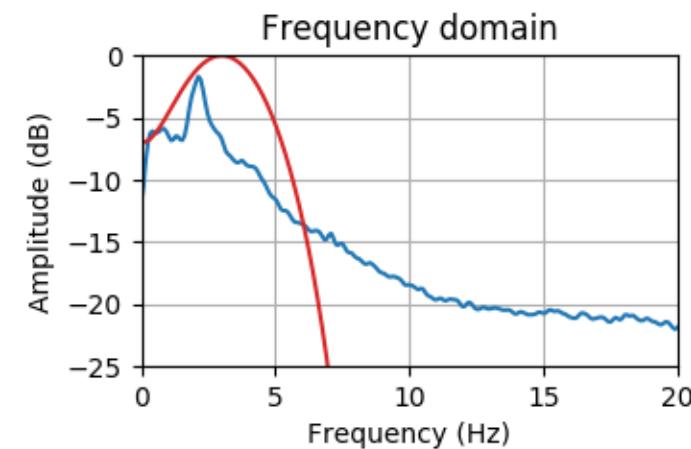
Event-related activations



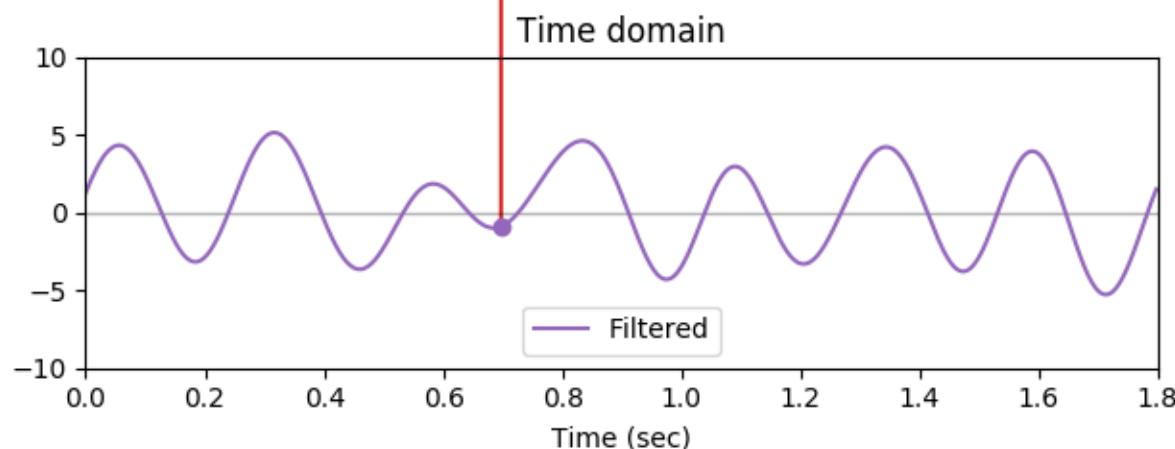
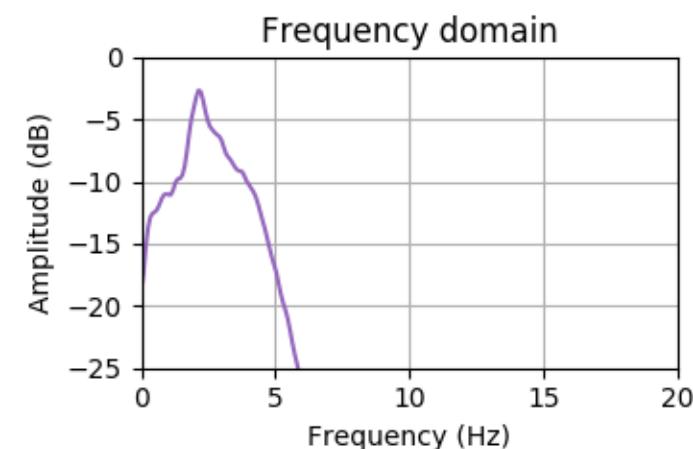
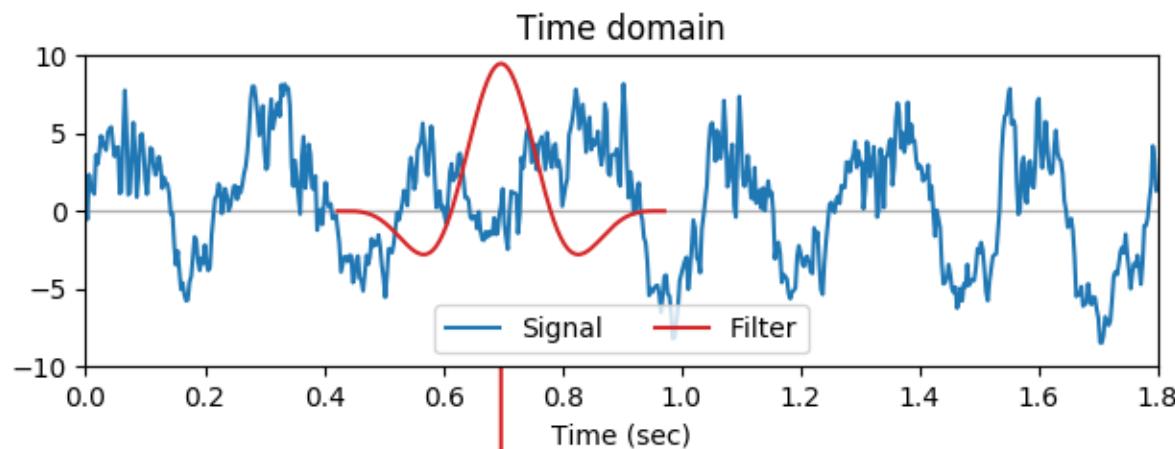
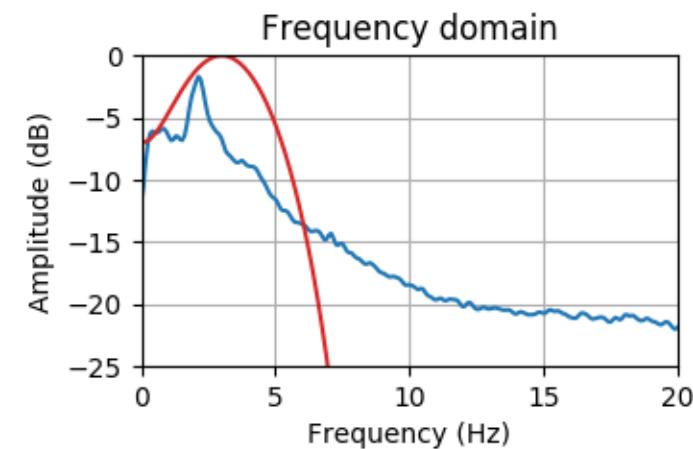
Narrow-band linear filtering



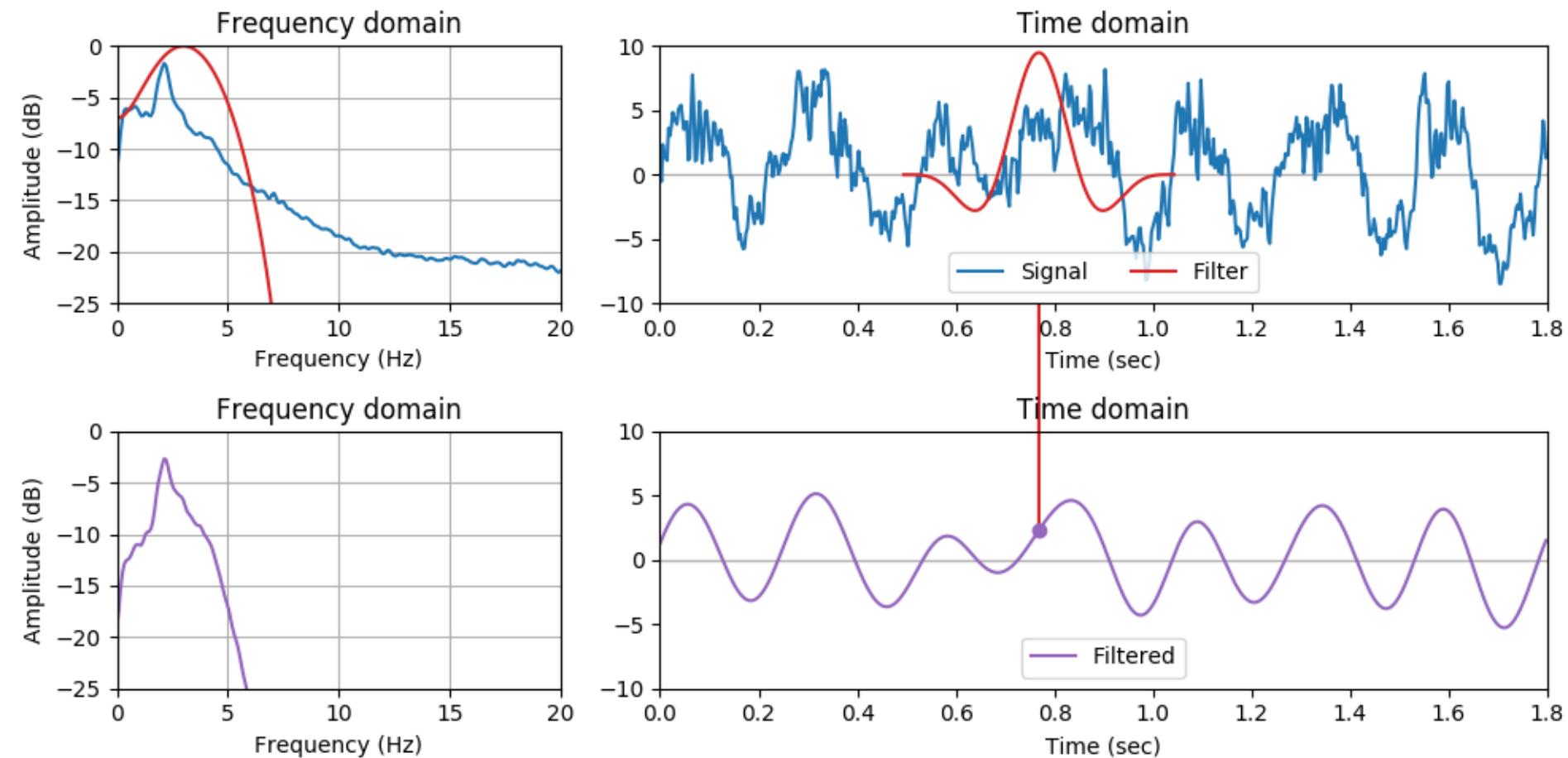
Narrow-band linear filtering



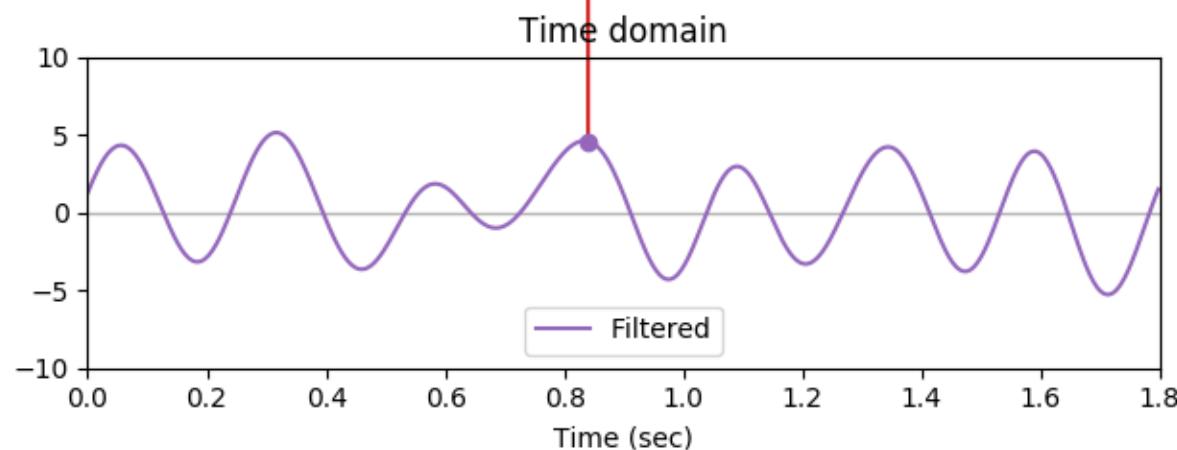
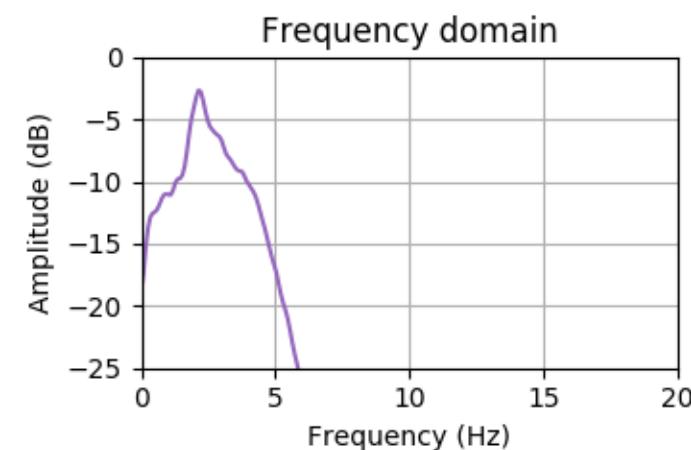
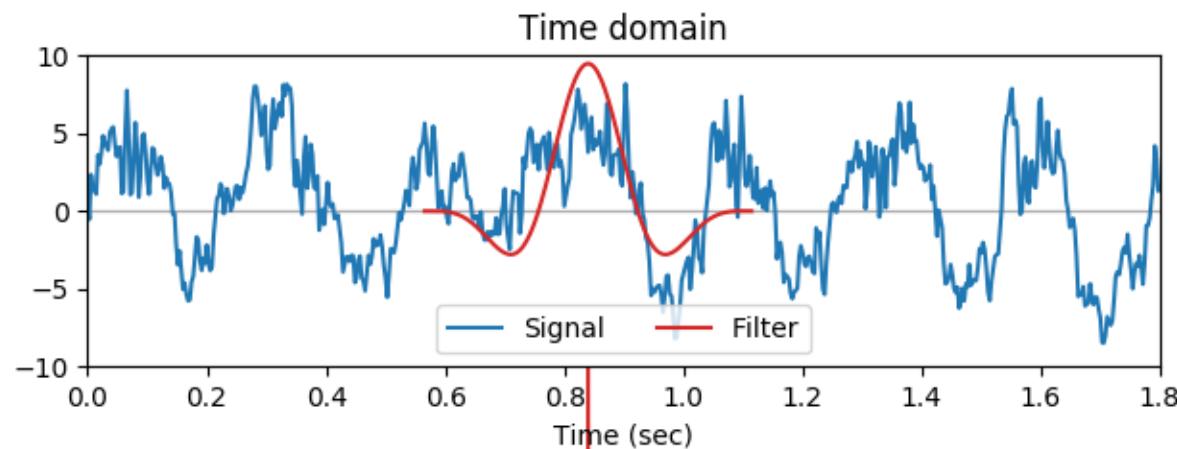
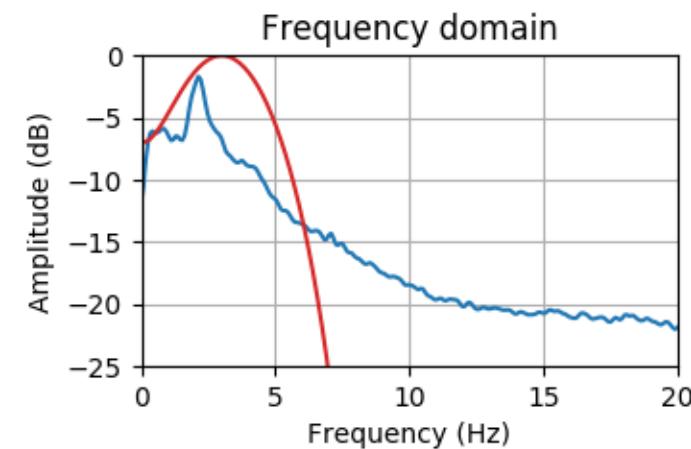
Narrow-band linear filtering



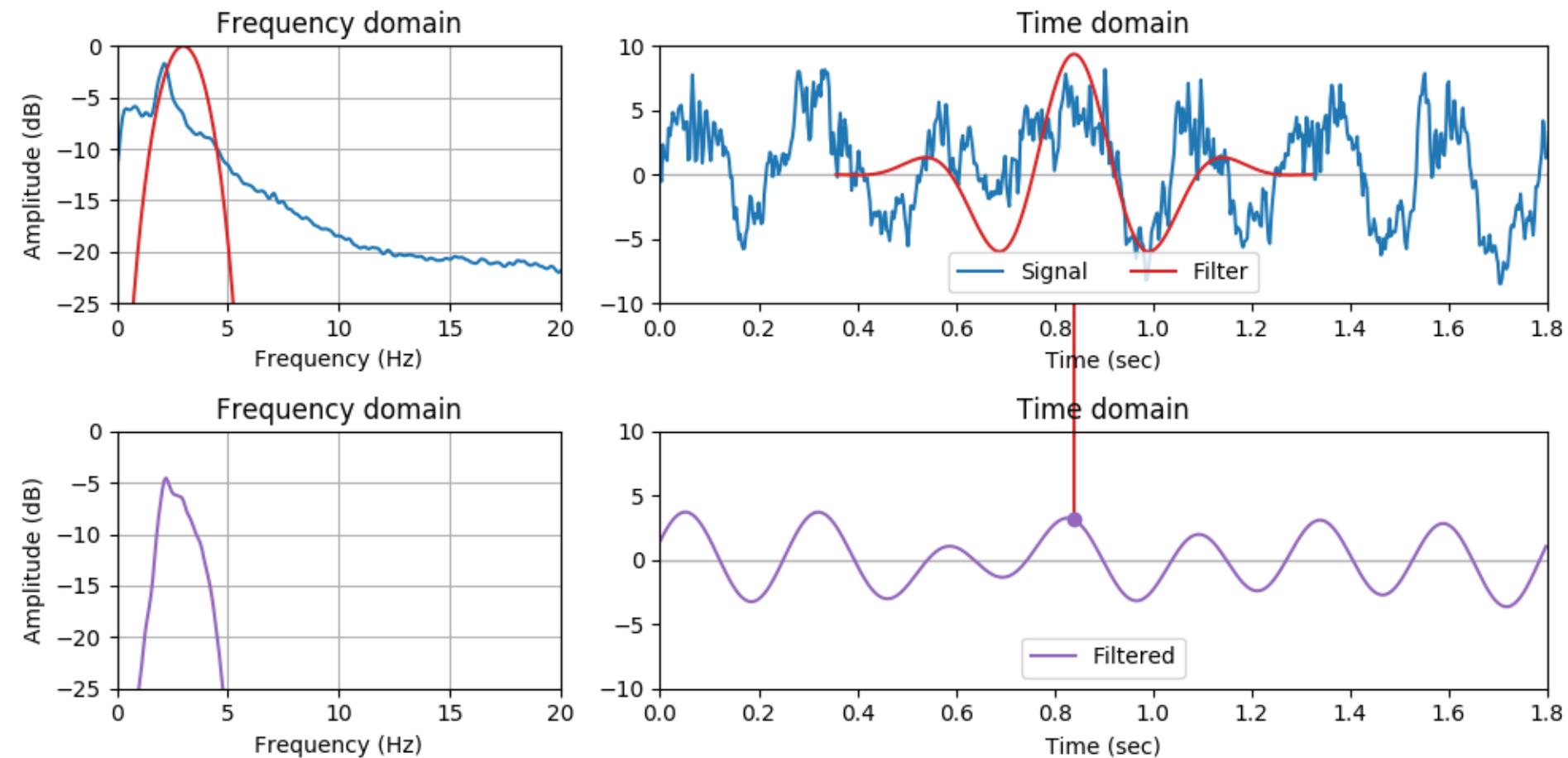
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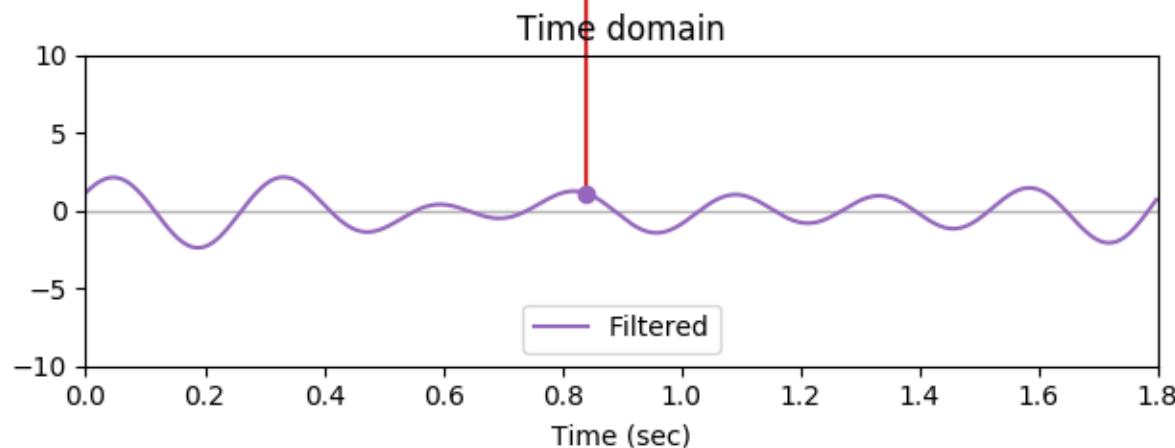
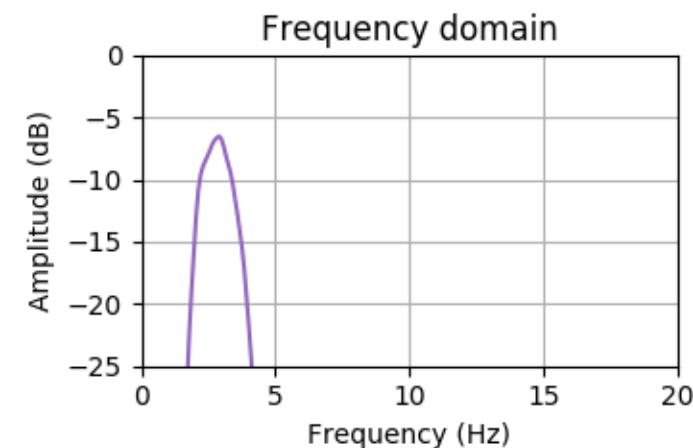
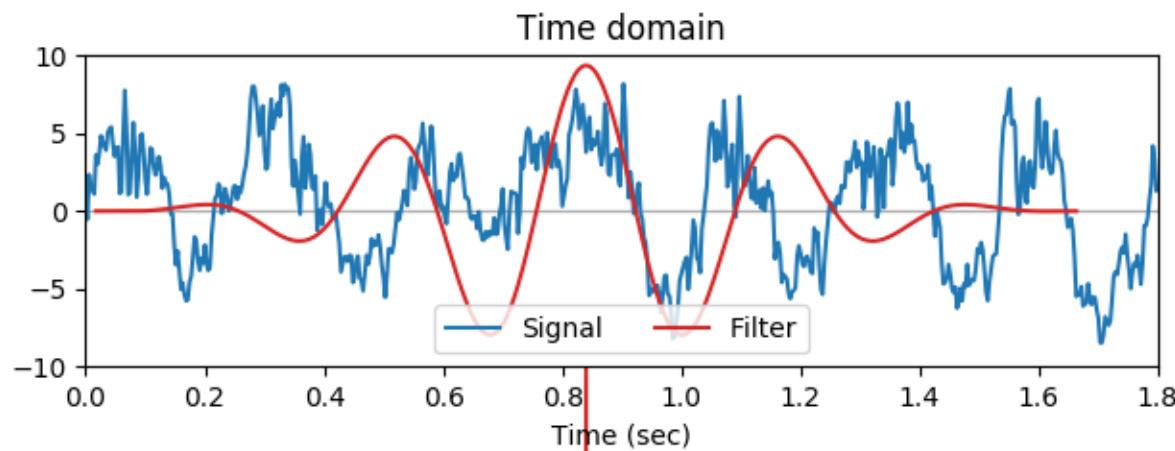
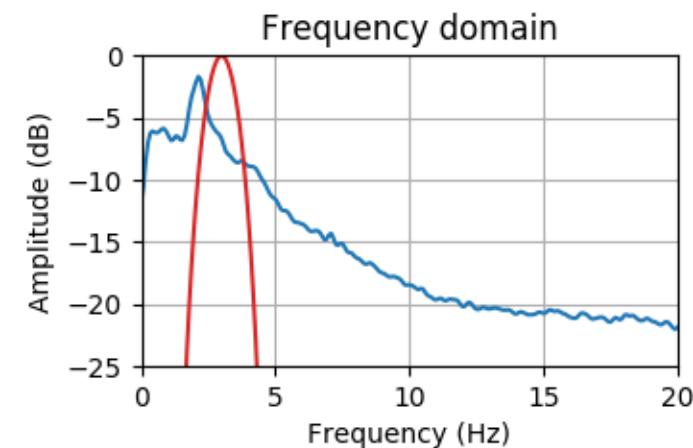
Narrow-band linear filtering



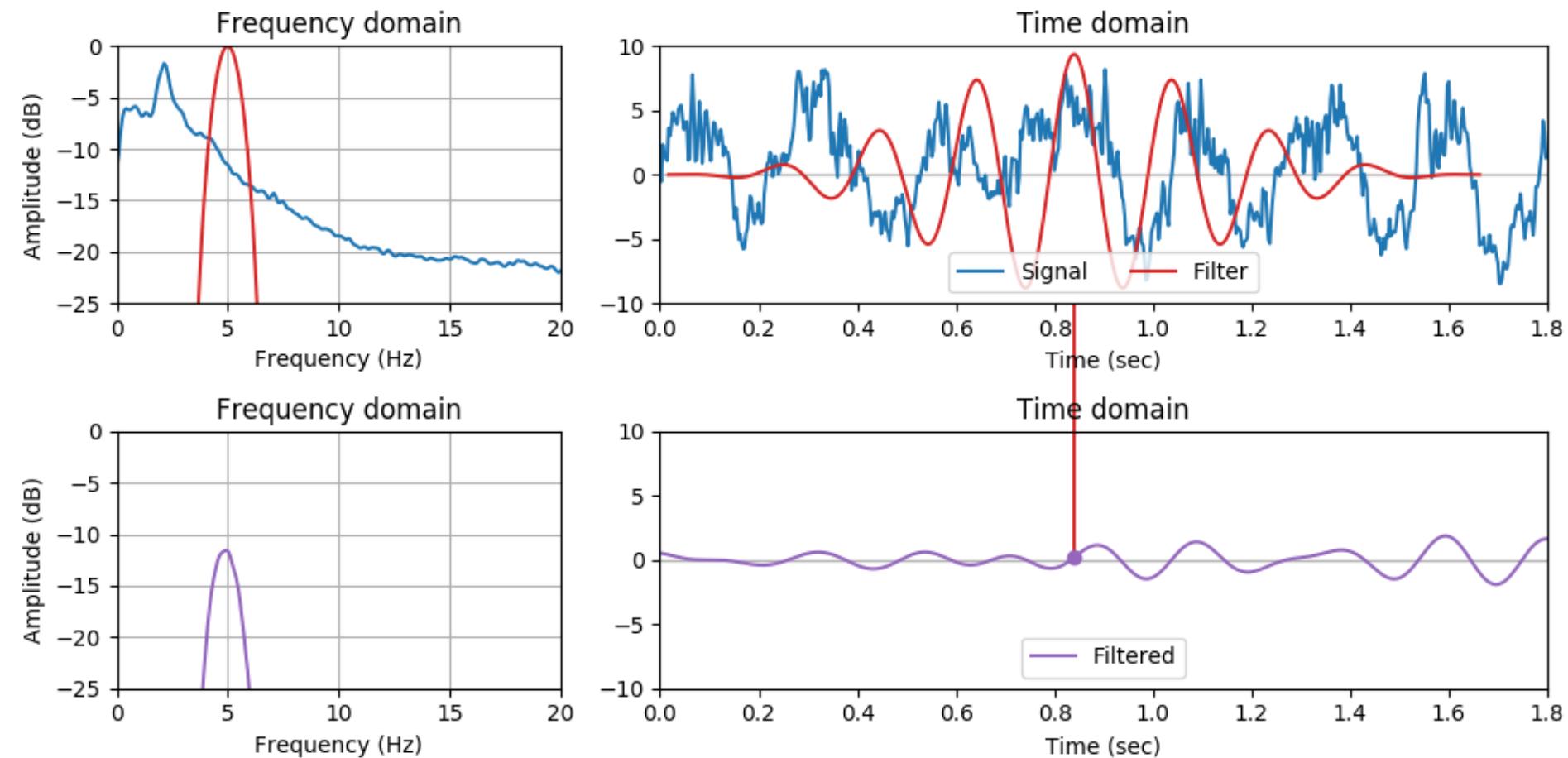
Narrow-band linear filtering



Narrow-band linear filtering



Narrow-band linear filtering



Narrow-band linear filtering

