



Universität  
Bremen

Center for Industrial  
Mathematics (ZeTeM)

Faculty 03

Mathematics / Computer science

# Introduction to TorchPhysics

Working with DeepONets

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But first...

## Setting up Google Colab

# DeepONet Example in TORCHPHYSICS

**Goal:** Learn for many  $f : I_x \rightarrow \mathbb{R}$

Wave equation:

$$\begin{aligned}\partial_t^2 u &= c^2 \partial_x^2 u && \text{on } I_x \times I_t \subset \mathbb{R}^2, \\ u &= 0 && \text{on } \partial I_x \times I_t, \\ \partial_t u(\cdot, 0) &= 0 && \text{on } I_x, \\ u(x, 0) &= f(x) && \text{for } x \in I_x.\end{aligned}$$

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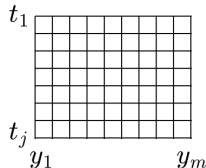
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$$f_2(x, k_1, k_2, k_3) = \frac{1}{3} \sum_{n=1}^3 k_n \sin(nx)$$

- Paired with analytical solutions  $u_f$
- **Dataset:**  $f$  sampled at points  $y_1, \dots, y_m \in I_x$   
 $u$  sampled on grid

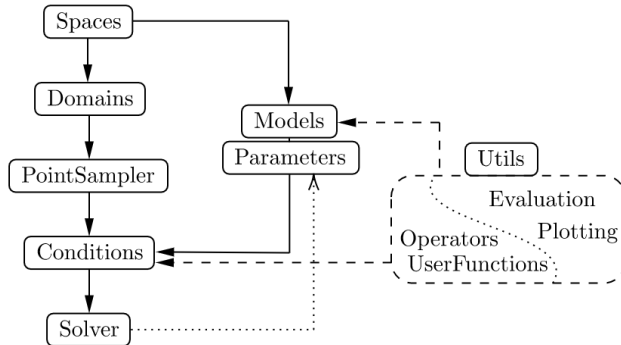
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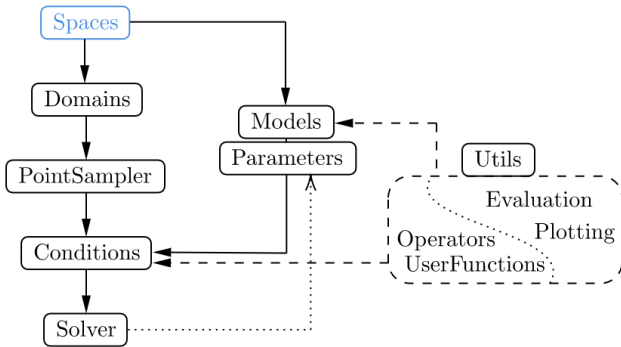
# TORCHPHYSICS

## Structure



# TORCHPHYSICS

## Spaces



**As before:** Spaces for

- Variables  $x, t$
- Output  $u$

**New:** Space for  $f$

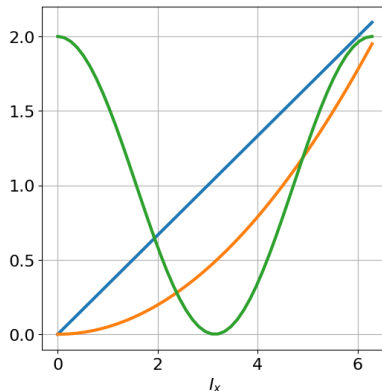


# Function Spaces

- Equivalent to the mathematical definition

$$\{f \mid f : I_x \rightarrow \mathbb{R}\}$$

- Function space for  $f : I_x \rightarrow \mathbb{R}$  determined by
  - Domain  $I_x$
  - Output space  $\mathbb{R}$



# Function Spaces

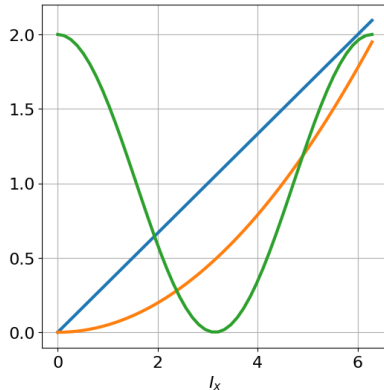
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```

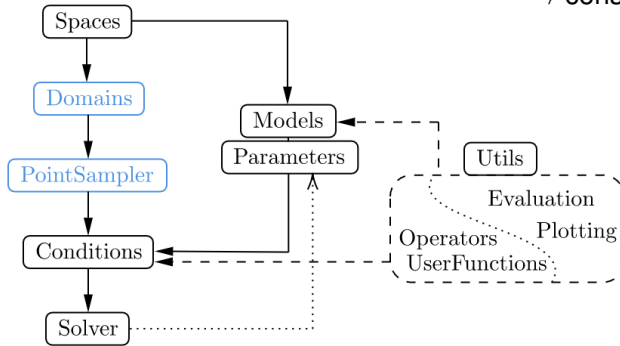
1 F      = tp.spaces.R1('f')
2
3 I_x     = tp.domains.Interval(X, x_min, x_max)
4
5 Fn_space = tp.spaces.FunctionSpace(I_x, F)
    
```



# TORCHPHYSICS

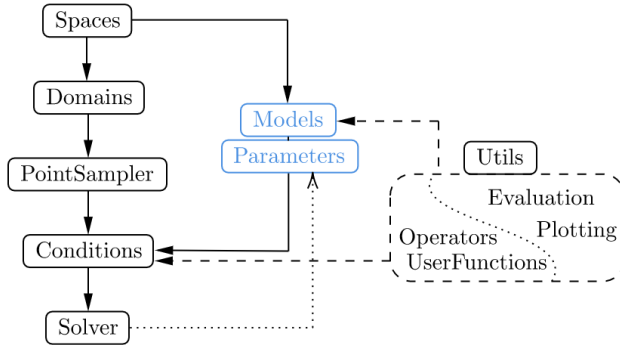
## Domains

- Functionality only needed for PI-DeepONet  
→ considered later



# TORCHPHYSICS

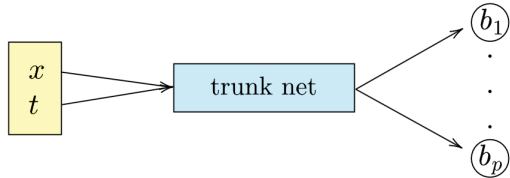
## Neural Networks



# Construct DeepONet

## Trunk net:

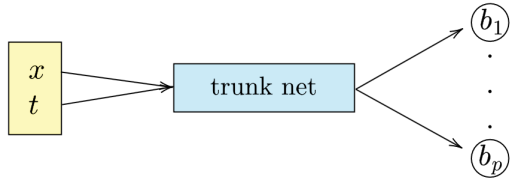
- Inputs similar to previous examples
- Arbitrary NN architecture



# Construct DeepONet

## Trunk net:

- Inputs similar to previous examples
- Arbitrary NN architecture

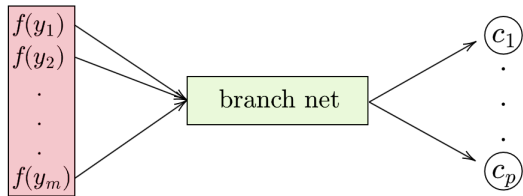


```
1 trunk_net = tp.models.FCTrunkNet(input_space=T*X,
2                                 hidden=(20, 30, 30, 30, 30, 40))
```

# Construct DeepONet

## Branch Net:

- Arbitrary NN architectures
- Branch inputs:
  - Discrete  $(f(y_1), \dots, f(y_m))$
  - Continuous  $f : I_X \rightarrow \mathbb{R}$
- 💡 Discretization sampler

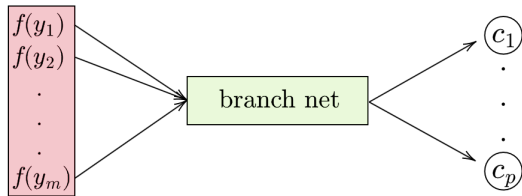


# Construct DeepONet

## Branch Net:

- Arbitrary NN architectures
- Branch inputs:
  - Discrete  $(f(y_1), \dots, f(y_m))$
  - Continuous  $f : I_x \rightarrow \mathbb{R}$

💡 Discretization sampler



```

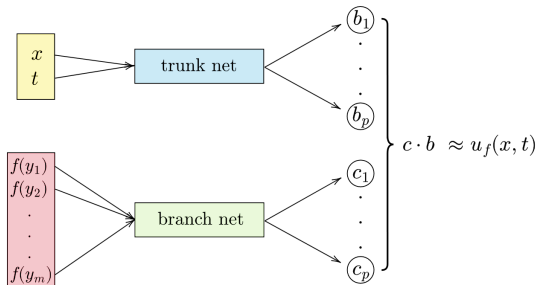
3 branch_net = tp.models.FCBranchNet(function_space=Fn_space,
4                                     discretization_sampler=discretization_sampler,
5                                     hidden=(50, 20, 20, 20, 50))
    
```



# Construct DeepONet

## DeepONet:

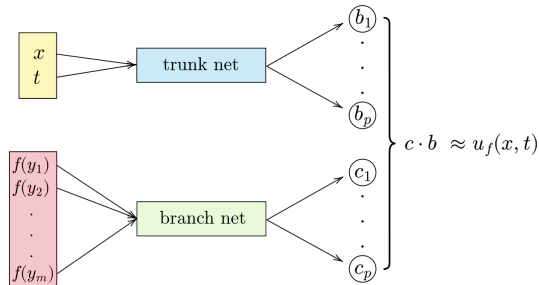
- Combines Trunk and Branch
- Set number of brunch/trunk outputs



# Construct DeepONet

## DeepONet:

- Combines Trunk and Branch
- Set number of brunch/trunk outputs



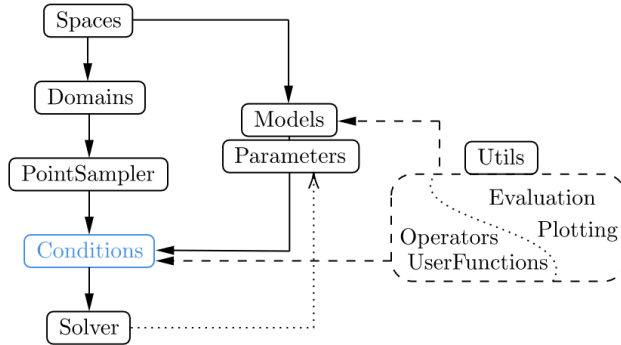
```

6 deep_O_net = tp.models.DeepONet(trunk_net, branch_net,
7                                   output_space=U,
8                                   output_neurons=100)

```

# TORCHPHYSICS

## Conditions



# Conditions

- Different types, e.g `DeepONetDataCondition` or `PIDeepONetCondition`
- Still represents one mathematical equation, here

$$u_\theta \left( x_i, t_i, \begin{pmatrix} f(y_1) \\ \vdots \\ f(y_m) \end{pmatrix} \right) = u_f(x_i, t_i), \quad u_\theta \text{ DeepONet}$$

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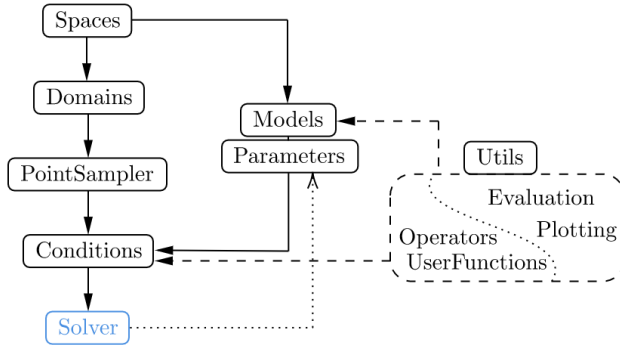
$$u_{\theta} \left( x_i, t_i, \begin{pmatrix} f(y_1) \\ \vdots \\ f(y_m) \end{pmatrix} \right) = u_f(x_i, t_i), \quad u_{\theta} \text{ DeepONet}$$

- `DeepONetDataCondition` implements the above condition given a corresponding dataloader

```
1 data_condition = tp.conditions.DeepONetDataCondition(module=deep_O_net,
2                                                       dataloader=dataloader,
3                                                       norm=2, root=2)
```

# TORCHPHYSICS

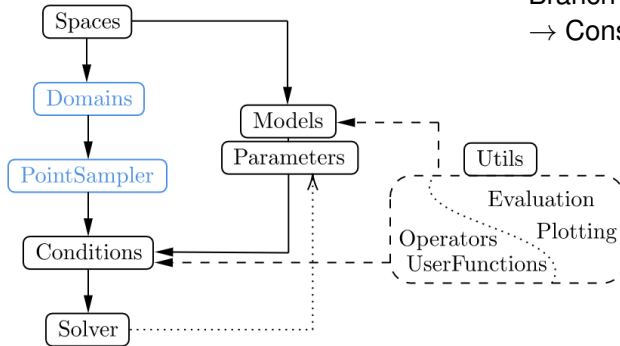
## Solver



# PI-DeepONet

# TORCHPHYSICS

## Function Sets



- Branch input not necessarily discrete data  
→ Construct numerous different inputs



# Function Sets

- Set of functions used as the Branch input
- Belongs to a given function space

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$$f_1(x; k) = kx$$

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1 def f1(k, x):  
2     return k*x
```

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$$f_1(x; k) = kx$$

```
1 def f1(k, x):  
2     return k*x  
3  
4 K_int      = tp.domains.Interval(K, 0, 6)  
5 param_sampler = tp.samplers.RandomUniformSampler(K_int, n_points=80)  
6 Fn_set_1    = tp.domains.CustomFunctionSet(Fn_space, param_sampler, f1)
```

# Function Sets

- Set of functions used as the Branch input
- Belongs to a given function space

$$f_2(x; k) = k \cos(kx)$$

```
7 def f2(k, x):  
8     return k*cos(kx)  
9  
10 K_int      = tp.domains.Interval(K, 0, 6)  
11 param_sampler = tp.samplers.RandomUniformSampler(K_int, n_points=80)  
12 Fn_set_2     = tp.domains.CustomFunctionSet(Fn_space, param_sampler, f2)
```

# Function Sets

- Set of functions used as the Branch input
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$$f_2(x; k) = k \cos(kx)$$

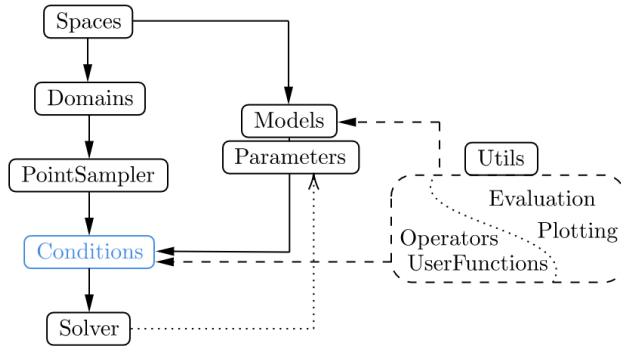
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7 def f2(k, x):  
8     return k*cos(kx)  
9  
10 K_int      = tp.domains.Interval(K, 0, 6)  
11 param_sampler = tp.samplers.RandomUniformSampler(K_int, n_points=80)  
12 Fn_set_2     = tp.domains.CustomFunctionSet(Fn_space, param_sampler, f2)
```

- Multiple function sets can be combined (set union)

```
13 Fn_set = Fn_set_1 + Fn_set_2
```

# TORCHPHYSICS

## Conditions



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- Separate `PIDeepONetCondition` for mathematical equations, e.g

$$\partial_t^2 u = c^2 \partial_x^2 u \quad \text{or} \quad u(x, 0) = f(x).$$

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$$\partial_t^2 u = c^2 \partial_x^2 u \quad \text{or} \quad u(x, 0) = f(x).$$

```
1 def initial_residual(u, f):  
2     return u - f  
3  
4 initial_cond = tp.conditions.PIDeepONetCondition(deeponet_model = model,  
5                                                    function_set    = Fn_set,  
6                                                    input_sampler    = initial_sampler,  
7                                                    residual_fn      = initial_residual)
```

- In residual:  $f$  has already been evaluated at  $x$



# Exercises

## Data driven (Example\_8.ipynb)

- Add noise to dataset
- Study the influence of the dataset size on the generalization
- Implement different initial conditions

## Physics informed (Example\_9.ipynb)

- Implement a simple ODE problem
- Add different right hand sides to the training