

Introduction to TorchPhysics

Getting started with a simple example

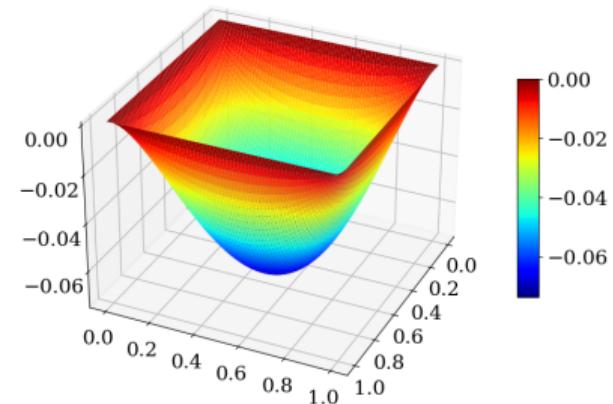


Tom Freudenberg, Nick Heilenkötter, Janek
Gödeke
Renningen, 20.11.2025

Starting with TORCHPHYSICS

- We introduce the library with the Laplace equation:

$$\begin{aligned}\Delta u &= 1 && \text{in } \Omega = (0, 1) \times (0, 1) \\ u &= 0 && \text{on } \partial\Omega\end{aligned}$$

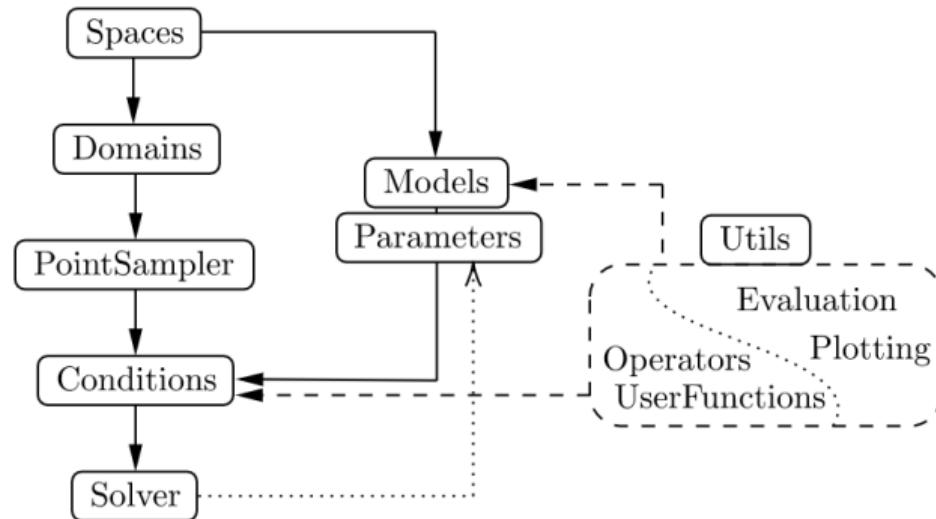


But first...

Setting up the coding environment

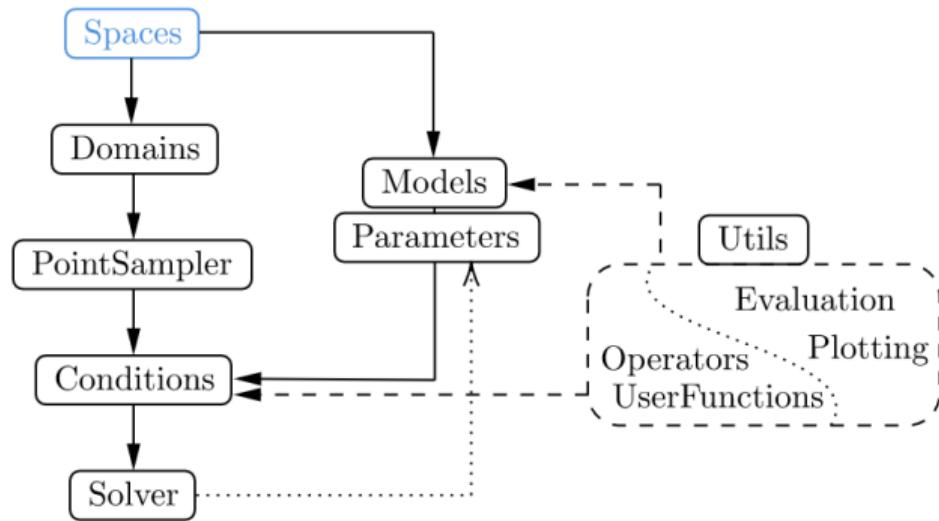
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Structure



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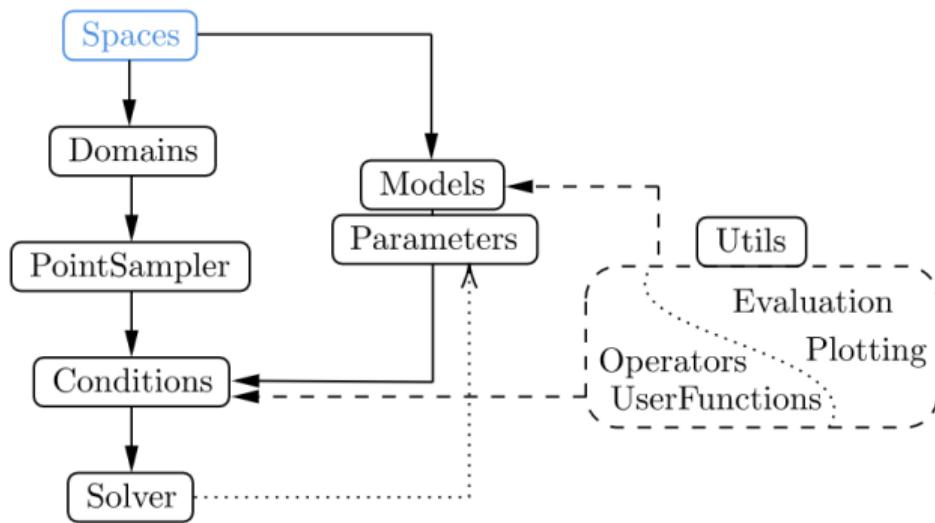
Spaces



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Spaces

Example: $\Omega = (0, 1) \times (0, 1)$

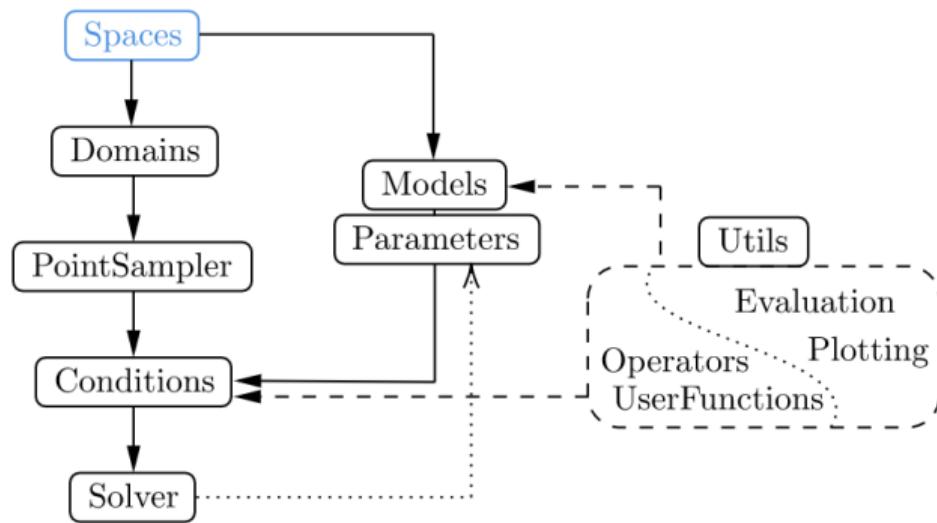


$\Delta u(x) = 1, \quad \text{for } x \in \Omega,$
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Spaces

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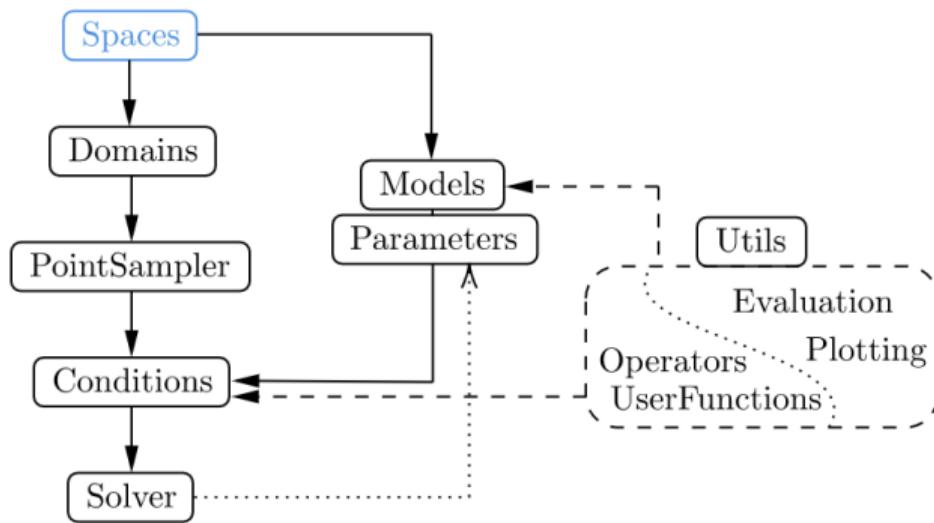


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Spaces

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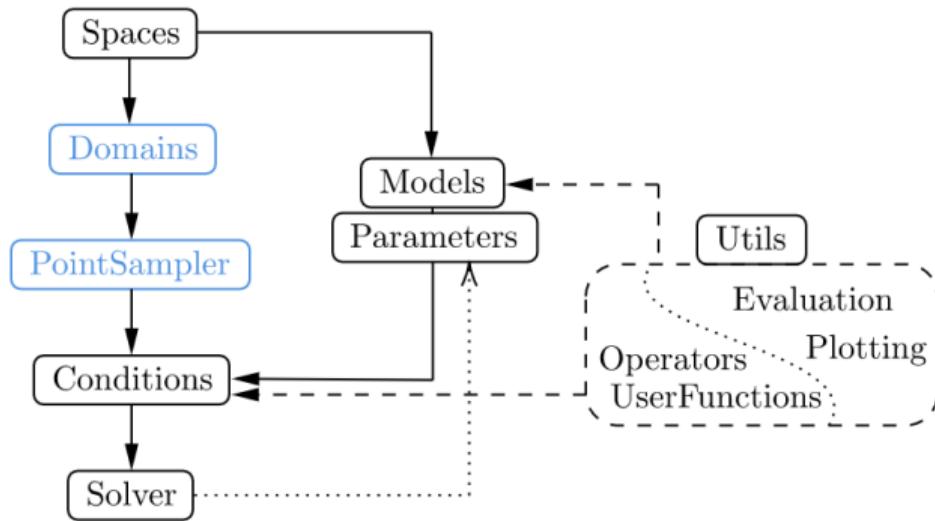


$$\Delta u(x) = 1, \quad \text{for } x \in \Omega,$$
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```
1 import torchphysics as tp
2 X = tp.spaces.R2('x')
3 U = tp.spaces.R1('u')
```

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Domains



Domains

- Basic geometries implemented:
 - Point, Interval, Parallelogram, Circle, ...

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```
4 omega = tp.domains.Parallelogram(X, [0,0], [1,0], [0,1])
```

PointSampler

- Creation of training/validation points inside of the domains
- Different types of sampling:
 - `RandomUniformSampler`, `GridSampler`, `GaussianSampler`,
`AdaptiveRejectionSampler`, ...

PointSampler

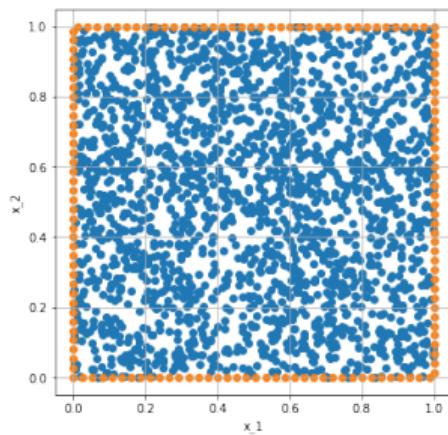
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4 omega = tp.domains.Parallelogram(X, [0,0], [1,0], [0,1])
5
6 inner_sampler = tp.samplers.RandomUniformSampler(omega,
7                                     n_points=15000)
8
9 boundary_sampler = tp.samplers.GridSampler(omega.boundary,
10                                         n_points=5000)
```

PointSampler

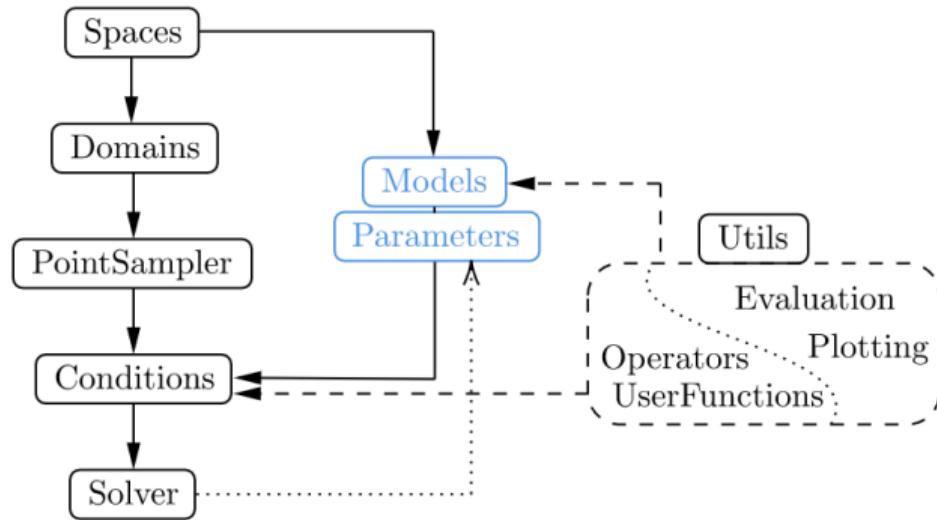
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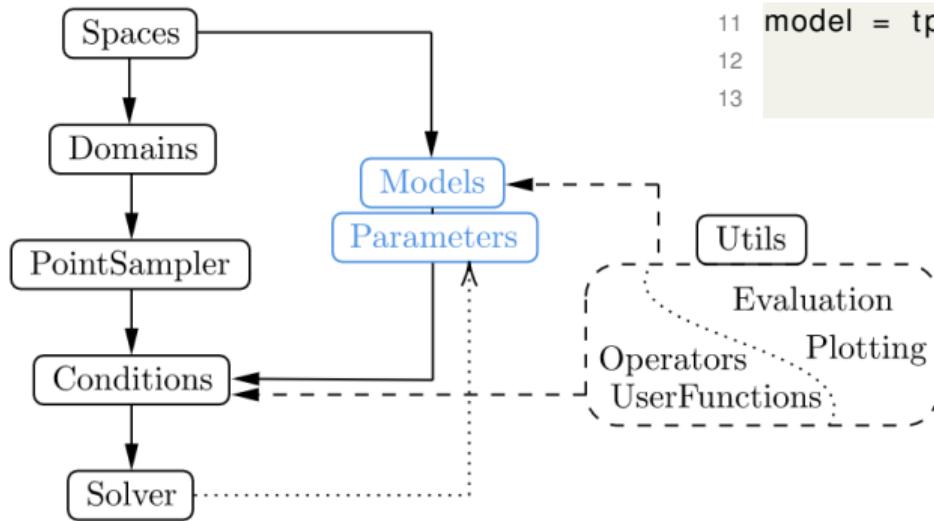
Neural Networks



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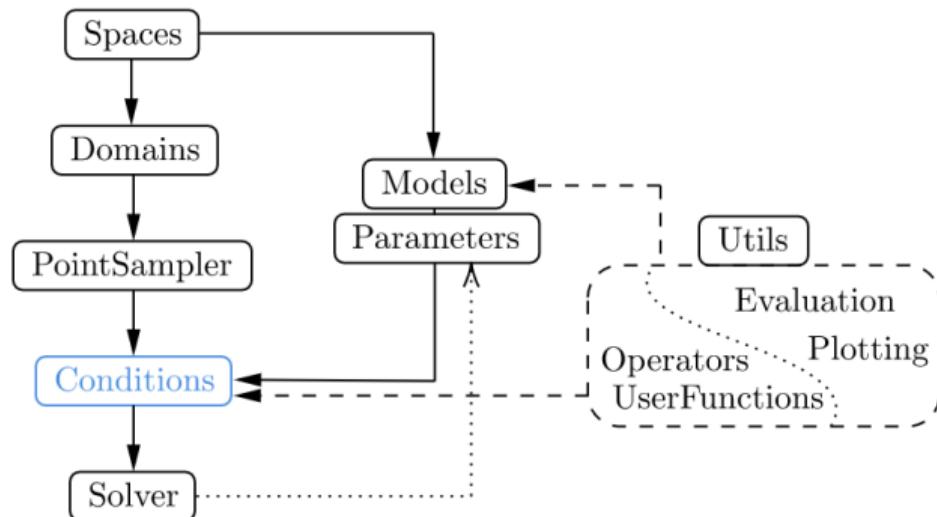
Neural Networks

$$\Delta u(x) = 1$$



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Conditions



Conditions

- Different types, e.g., PINNCondition
- Represents one mathematical condition, e.g.

$$\Delta u = 1 \text{ in } \Omega \quad \text{or} \quad u = 0 \text{ at } \partial\Omega$$

- DifferentialOperators allow natural definition:

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- DifferentialOperators allow natural definition:

```
14 def pde_residual(u, x):  
15     return tp.utils.laplacian(u, x) - 1.0  
16  
17 pde_cond = PINNCondition(model,  
18                             inner_sampler,  
19                             pde_residual)
```

Conditions

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- Represents one mathematical condition, e.g.

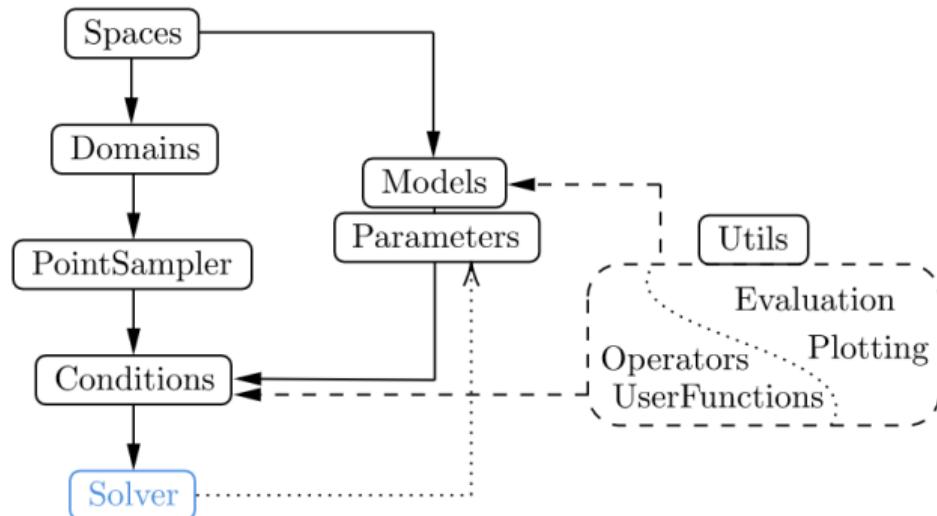
$$\Delta u = 1 \text{ in } \Omega \quad \text{or} \quad u = 0 \text{ at } \partial\Omega$$

- DifferentialOperators allow natural definition:

```
14 def pde_residual(u, x):          20 def boundary_residual(u):  
15     return tp.utils.laplacian(u, x) - 1.0 21     return u - 0.0  
16  
17 pde_cond = PINNCondition(model,  
18                           inner_sampler,  
19                           pde_residual)  
20  
21 boundary_cond = PINNCondition(model,  
22                                   boundary_sampler,  
23                                   boundary_residual)  
24  
25
```

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Solver



Solver

- Collects all conditions → overall loss computation
- Flexible choice optimization algorithm

```
21 optim = tp.OptimizerSetting(torch.optim.Adam, lr=0.001)
22 solver = tp.solver.Solver([boundary_cond, pde_cond],
23                           optimizer_setting=optim))
```

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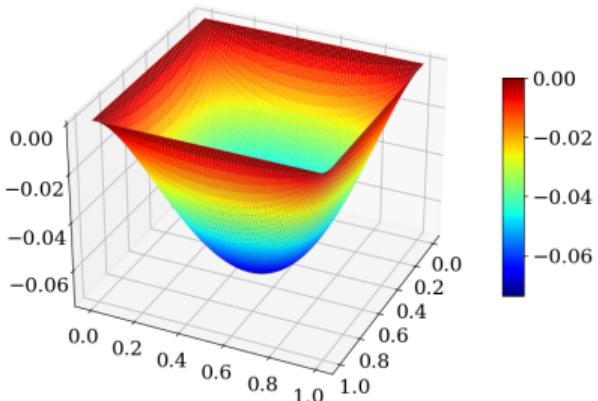
- Based upon  PyTorch LIGHTNING

```
24 import pytorch_lightning as pl
25 trainer = pl.Trainer(devices=1, accelerator="gpu", # use one GPU
26                       max_steps=3000) # iteration number
27 trainer.fit(solver)
```

Utils - Plot Results

$$\Delta u(x) = 1.0 \quad \text{for } x \in \Omega$$

$$u(x) = 0.0 \quad \text{for } x \in \partial\Omega$$



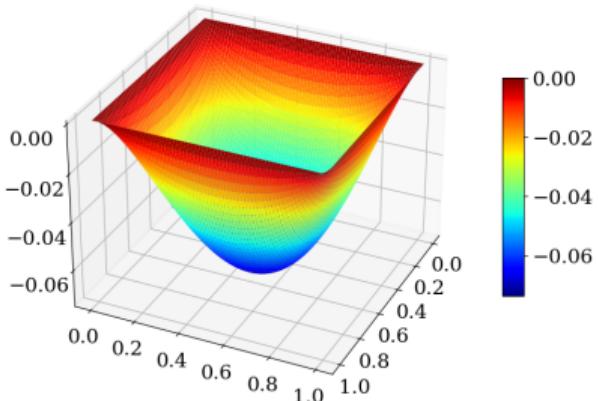
Learned solution of the PDE

```
28 plot_sampler = tp.samplers.PlotSampler(plot_domain=omega,  
29 n_points=2000)  
30 fig = tp.utils.plot(model, lambda u : u, plot_sampler)
```

Utils - Plot Results

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```

Does your solution look like the
one at the left?

First extension of the example

- Learning the time dependent Laplace equation (**heat equation**):

$$\partial_t u - 0.1 \Delta u = 1 \quad \text{in } \Omega \times (0, 2)$$

$$u = 0 \quad \text{on } \partial\Omega \times (0, 2)$$

$$u(\cdot, 0) = 0 \quad \text{in } \Omega$$

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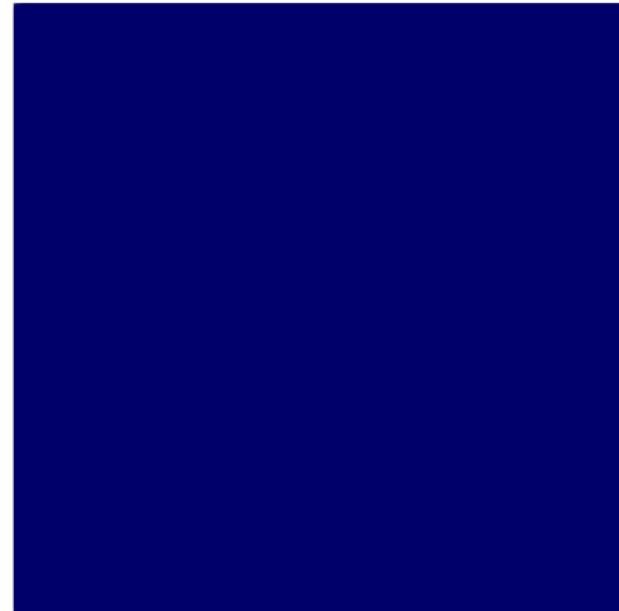
$$u(\cdot, 0) = 0 \quad \text{in } \Omega$$

- Aspects to adjust:
 - Adding a time variable t , time interval and sample time points
 - One more input to the neural network
 - Adapt PDE-condition and implement initial condition
- Template: Exercise_2.ipynb

Choose your Track!

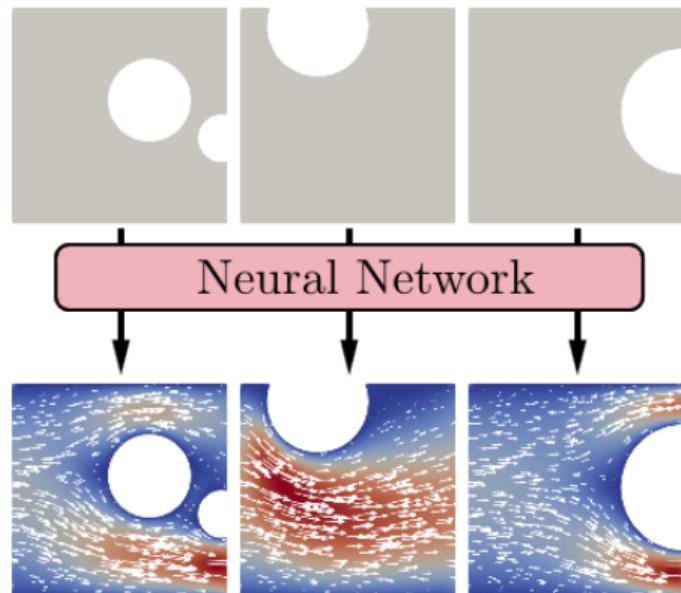
Track 1: Function Learning

- In-depth application of PINNs
- **Requires:**
 - The underlying PDE
 - **No** dataset
- **Goal:** compute unknown solution
(once)
- Workshop examples:
 - Time-dependent domain
 - Inverse wave equation
 - Stokes equations



Track 2: Operator Learning

- Learn about PCA-Nets and FNOs
- **Requires:**
 - Underlying PDE is optional
 - A dataset
- **Goal:** learn parameter-function to solution mapping (*parameter studies*)
- Workshop examples:
 - Allen-Cahn equation
 - Stokes equations
 - Inverse Allen-Cahn equation



Track 1: Function Learning

3 p.m. at 6th floor, room **Leibniz**

- In-depth application of PINNs
- **Requires:**
 - The underlying PDE
 - **No** dataset
- **Goal:** compute single solution
- Workshop examples:
 - Time-dependent domain
 - Inverse wave equation
 - Stokes equations

Track 2: Operator Learning

3 p.m. at 1st floor, room **C.112**

- Learn about PCA-Nets and FNOs
- **Requires:**
 - Underlying PDE is optional
 - A dataset
- **Goal:** learn parameter-function to solution mapping (*parameter studies*)
- Workshop examples:
 - Allen-Cahn equation
 - Stokes equations