## **MiniMetroBot**

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## **Description**

MiniMetroBot is an object detection bot for the game MiniMetro. It uses YOLOv8 for object detection and OpenCV for image processing.

The recent status of the Bot is that it is capable to detect the main game object of the game Minimetro and it executes before the detection starts

a basic automated mouse click and move.

## **Project Scope and Targets**

Main scope of the project is to detect game object which includes the position of the relevant objects and to add the capability to automatically perform user inputs.

Out of scope are further steps to further train another model which actually can play the game.

## **In Scope Targets**

- -[x] Game object detection
- -[x] Basic user input
- -[x] Runs on a resolution which is available on a Macbook Pro M1 Max 2021

## Out of Scope Targets (to be handled in a subsequent project)

-[] Fully automated gaming performed by the final bot

# **Project Structure**

MiniMetroBot/	# Root directory
minimetrobot/	# Source code
	# Core modules containing the main bot
functionality	
ScreenDetector.py	# Class for detecting objects and to mock input
actions (docstring available)	
- evidences/	# Folder contains an evidence which shows that the
bot works as discussed	
mock_activity_start.mov	# Screenvideo activity mock -> startup Minimetro
game	
detection_evidence.mov	# Screenvideo from bot usage -> object detection
while gaming	
— models/	# Model files
best.pt	# Best model from training exercise
labels.yaml	# List of object labels which can be detected by
the model	
	# Main folder which holds objects for model
training (not part of whl installation)	
images_annotated/	# Annotated training data for YOLOv8 training
images_pre_selected/	# Updated version of the raw data images
	# Raw images
model_source/	
	# Base YOLOv8 model which is tuned based on the
training data	
model_tuned	
yolo_model_tuning.py	# Script for model tuning (docstring available)
—initpy	
mainpy	# Main program used for active object detection in
live game (docstring available)	
— docs/	# Documentation
README.md	# Project description as markdown
README.pdf	# Markdown converted to pdf

# **Dependencies**

The project has the following dependencies:

• python: 3.10.9

• comet-ml: 3.33.6

• ipython: 8.14.0

• numpy: 1.24.2

• opency-contrib-python: 4.7.0.72

• opency-python: 4.7.0.72

• pillow: 10.0.0

• pyyaml: 6.0.1

screeninfo: 0.8.1

• torch: 2.0.0

• torchvision: 0.15.1

• ultralytics: 8.0.162

• pyautogui: 0.9.54

To install the system and its dependencies follow the installation instructions below.

#### Installation of the Final Bot

### **Option 1: Using Git and Poetry**

1. Clone the repository:

```
git clone https://github.com/TomGFFM/PraxisProjektSemester4_30313.git
```

2. Navigate to the project directory:

```
cd PraxisProjektSemester4_30313/MiniMetroBot
```

3. Install dependencies using **Poetry**:

```
poetry install
```

#### **Option 2: Using Wheel File**

- 1. Download the latest wheel file, minimetrobot-0.1.6-py3-none-any.whl, from the repository.
- 2. Install the package using pip:

```
pip install path/to/minimetrobot-0.1.6-py3-none-any.whl
```

### **Usage**

#### **Option 1: Using the Poetry Entry Point**

(notice different naming convention here. Just: "metrobot")

If poetry is installed you can use the following command to run the MiniMetroBot from the environment where the package is installed:

poetry run metrobot

### **Option 2: Running the Python Script Manually**

Activate the virtual environment and execute the following command:

 $\verb"python -m" minimetrobot"$ 

Either of these options will start the MiniMetroBot.

## **YOLOv8 Model Training information**

#### **Model Information**

The project folder "yolo\_tuning" contains a subfolder "model\_tuned". Here are a number of model folders available which contain trained YOLOv8 object detection models.

The final model which was chosen and integrated into the recent version of the Bot is in the folder: "round\_optimized\_with\_Adamax\_True\_bs\_16\_20230826\_1342"

### **Training Metrics**

The relevant training metrics can be reviewed in the public CometML report for this project. Click here to visit the report page: MiniMetroBot CometML Metrics Report.

#### **Model Training**

The YOLOv8 model training can be performed via the script yolo\_model\_tuning.py. The underlying base model is available in the folder "model\_source".

This contains the basic YOLOv8 which is used as a foundation for the detection model training. Review contained docstring for further usage and information.

# **Contributing**

Contributions, issues, and feature requests are welcome! Feel free to check <u>issues page</u>.

## License

This project is <u>BSD</u> licensed.

## **Show your support**

Give a 🚖 if this project helped you!