Machine Learning Worksheet 5

Tomas Ladek, Michael Kratzer 3602673, 3612903

tom.ladek@tum.de, mkratzer@mytum.de

Problem 1

$$E_{\mathcal{D}}(w) = \frac{1}{2} \sum_{n=1}^{N} T_n [\mathbf{W}^T \phi(x_n) - Z_n]^2$$
$$= \frac{1}{2} [T(\Phi W - Z)^T] [T(\Phi W - Z)]$$

with

$$T = \begin{pmatrix} \sqrt{T_1} & 0 \\ & \ddots & \\ 0 & \sqrt{T_n} \end{pmatrix}$$

Now, finding the optimal W so that this error function is minimal (using the knowledge about the derivative from the slides and the Matrix Cookbook):

$$\nabla_W E_{\mathcal{D}}(W) = \frac{\partial}{\partial W} \frac{1}{2} [T(\Phi W - Z)^T] [T(\Phi W - Z)]$$
$$= -T^2 \Phi^T (\Phi W - Z)$$

Further, setting this to 0 and solving for W:

$$-T^{2}\Phi^{T}(\Phi W - Z) = 0$$

$$-T^{2}\Phi^{T}\Phi W + T^{2}\Phi^{T}Z = 0$$

$$T^{2}\Phi^{T}\Phi W = T^{2}\Phi^{T}Z$$

$$(T^{2}\Phi^{T}\Phi)^{-1}(T^{2}\Phi^{T}\Phi W) = (T^{2}\Phi^{T}\Phi)^{-1}T^{2}\Phi^{T}Z$$

$$W = T^{-2}T^{2}(\Phi^{T}\Phi)^{-1}\Phi^{T}Z$$

$$W = (\Phi^{T}\Phi)^{-1}\Phi^{T}Z$$

By carefully choosing values of T_n , the error function can be made less sensitive against outliers (that can have a significant impact on the variance of the data noise). Also duplicate data points can be weighted accordingly (e.g. small value of T_i for the data point copies: the error is also made smaller).

Problem 2

The following calculation assumes, that p is equal the the number of rows in the matrix Φ . The normal least squares algorithm is defined as:

$$E_D(w) = \frac{1}{2} \sum_{n=1}^{N} [W^T \Phi(x_n) - z_n]^2 = \frac{1}{2} (\Phi W - Z)^T (\Phi W - Z)$$
 (1)

Augmenting the matrix and the vector by the given values leeds to:

$$\frac{1}{2}\begin{pmatrix} \phi_0(X_1) & \dots & \phi_{m-1}(X_1) \\ \vdots & \ddots & \vdots \\ \phi_0(X_N) & \dots & \phi_{m-1}(X_N) \\ \sqrt{\lambda} & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \sqrt{\lambda} \end{pmatrix} \begin{pmatrix} w_0 \\ \vdots \\ w_{m-1} \end{pmatrix} - \begin{pmatrix} z_0 \\ \vdots \\ z_{m-1} \\ 0 \\ \vdots \\ 0 \end{pmatrix})^T \begin{pmatrix} \phi_0(X_1) & \dots & \phi_{m-1}(X_1) \\ \vdots & \ddots & \vdots \\ \phi_0(X_N) & \dots & \phi_{m-1}(X_N) \\ \sqrt{\lambda} & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \sqrt{\lambda} \end{pmatrix} \begin{pmatrix} w_0 \\ \vdots \\ z_{m-1} \\ 0 \\ \vdots \\ 0 \end{pmatrix})$$

$$(2)$$

$$=\frac{1}{2}\begin{pmatrix} w_{0}\phi_{0}(X_{1})-z_{0}+\cdots+w_{m-1}\phi_{m-1}(X_{1})-z_{m-1}\\ \vdots\\ w_{0}\phi_{0}X_{N}-z_{0}+\cdots+w_{m-1}\phi_{m-1}(X_{N})-z_{m-1}\\ \sqrt{\lambda}w_{0}\\ \vdots\\ \sqrt{\lambda}w_{m-1} \end{pmatrix}^{T}\begin{pmatrix} w_{0}\phi_{0}(X_{1})-z_{0}+\cdots+w_{m-1}\phi_{m-1}(X_{1})-z_{m-1}\\ \vdots\\ w_{0}\phi_{0}X_{N}-z_{0}+\cdots+w_{m-1}\phi_{m-1}(X_{N})-z_{m-1}\\ \sqrt{\lambda}w_{0}\\ \vdots\\ \sqrt{\lambda}w_{m-1} \end{pmatrix}$$

$$= \frac{1}{2} \left(\sum_{n=0}^{N} [W^{T} \Phi(x_{n})]^{2} + \lambda w_{0}^{2} + \dots + \lambda w_{m-1}^{2} \right) = \frac{1}{2} \left(\sum_{n=0}^{N} [W^{T} \Phi(x_{n})]^{2} + \lambda ||w|| \right) = \frac{1}{2} \sum_{n=0}^{N} [W^{T} \Phi(x_{n})]^{2} + \frac{\lambda}{2} ||w|| = \widetilde{E}_{D}(w)$$
(4)

Problem 3

$$p(W, \beta|Z, X) \propto p(Z|X, W, \beta)p(W|\beta)p(\beta) \tag{5}$$

$$= p(Z|X, W, \beta)p(W, \beta) \tag{6}$$

$$= \prod_{n=1}^{N} \mathcal{N}(Z_n | W^T \phi(X_n), \beta^{-1}) \mathcal{N}(W | M_0, \beta^{-1} S_0) Gam(\beta | a_0, b_0)$$
 (7)

Problem 4

With $y \sim \mathcal{N}(10,4)$, then p(y > 10) = 0.5. 10 is exactly the expected value of the normal distribution. To show this easily we can transform the random variable to a standard gaussian distribution.

$$Z = \frac{y - \mu}{\sigma} = \frac{y - 10}{2} \tag{8}$$

To get the probability for y > 10 we just have to plug in 10 into the formular for Z and look ap the corresponding value in the cumulative table. This results in p(y > 10) = 0.5

Problem 5

Given $y \sim \mathcal{N}(5x + 10, 4)$ and x = 1, then $y \sim \mathcal{N}(15, 4)$. Then the expected value of y is just 15.

Problem 6

We just square the norm, which is ok because we are only interested in distances.

$$||x_1 - x_2||_2^2 = \langle x_1 - x_2, x_1 - x_2 \rangle \tag{9}$$

$$= (x_1 - x_2)^T (x_1 - x_2) (10)$$

$$= (x_1^T - x_2^T)(x_1 - x_2) (11)$$

$$= x_1^T x_1 - x_1^T x_2 - x_2^T x_1 + x_2^T x_2 (12)$$

$$= x_1^T x_1 + x_2^T x_2 - 2x_1^T x_2 (13)$$

Using the kernel: $k(x_1, x_1) + k(x_2, x_2) - 2k(x_1, x_2)$

Problem 7

$$k(x_1, x_2) = exp\{-\frac{1}{2}||x_1 - x_2||^2\}$$
(14)

$$= exp\{-\frac{1}{2}(x_1^T x_1 + x_2^T x_2 - 2x_1^T x_2)\}$$
(15)

$$= exp\{-\frac{1}{2}x_1^Tx_1\}exp\{-\frac{1}{2}x_2^Tx_2\}exp\{x_1^Tx_2\}$$
 (16)

$$= f(x_1)k(x_1, x_2)f(x_2) \tag{17}$$

with $f(x) = exp\{-\frac{1}{2}x^Tx\}$ and $k(x_1, x_2) = exp\{x_1^Tx_2\}$. f(x) is only a scalar and a kernel times a scalar is also a kernel. $x_1^Tx_2$ is the linear kernel. Also $exp\{k(x_1, x_2)\}$ is also a kernel.