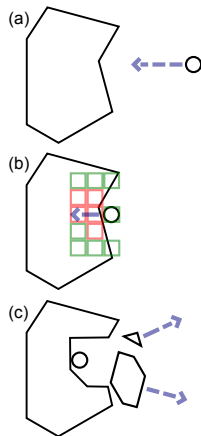


# Mesh to Voxel Transformations for Optimised Physics-Based Interactions

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Project Presentation, 2015

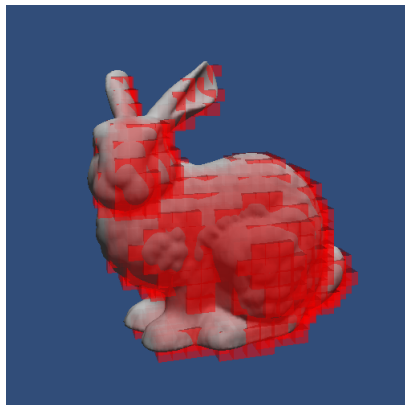
# Motivation



**Figure:** A simple collision and its volumetric resolution.

- ▶ Meshes only store surface information
- ▶ Reasoning on interior difficult
- ▶ Most destruction algorithms limited
  - ▶ Only work on convex shapes
  - ▶ Or have to split concave shapes first
- ▶ By precomputing volume data we have an  $O(1)$  check for inside/outside a shape

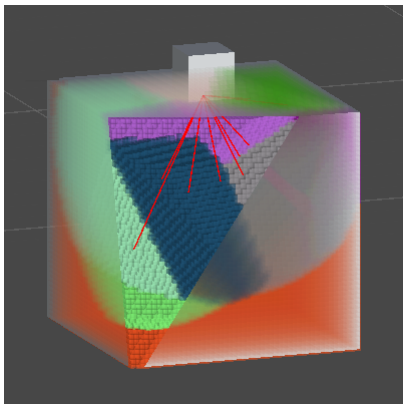
# Voxelisation



**Figure:** Voxelisation of the 'Stanford Bunny' model, composed of 69,666 triangles.

- ▶ HLSL GPU algorithm
- ▶ Based on GPU Pro 3 implementation of Schwarz and Seidel's method
- ▶ Achieves solid voxelisation of convex and concave bodies

# Destruction



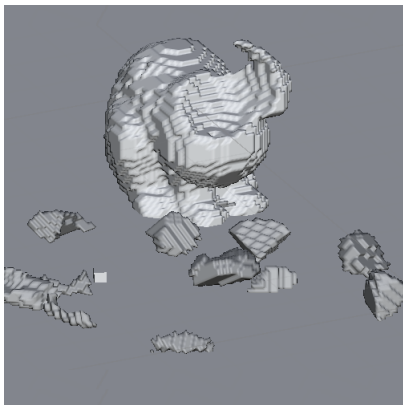
**Figure:** Labelling of voxels to their correct fragments.

- ▶ Process collision information
  - ▶ Find collision point
  - ▶ Calculate force
  - ▶ Generate fragment points
- ▶ Construct 3D voronoi diagram
  - ▶ Label each voxel by nearest point
  - ▶ Within radius
- ▶ Find islands
  - ▶ Flood fill

# Rebuilding the Mesh

## Different Approaches

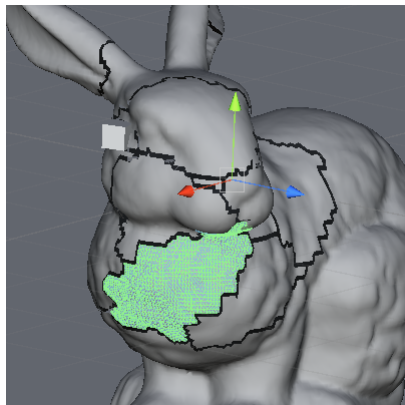
- ▶ Marching Tetrahedra
  - ▶ Original mesh not preserved
  - ▶ Detail loss



**Figure:** Fractured Stanford Bunny remeshed using the Marching Tetrahedrons algorithm.

# Rebuilding the Mesh

## Different Approaches

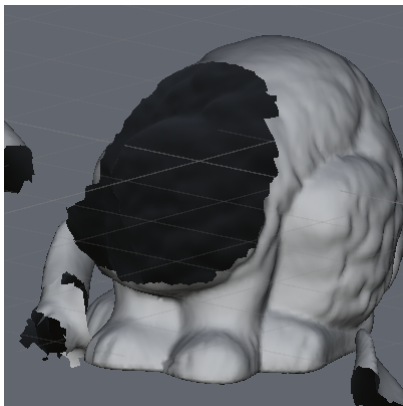


**Figure:** Fractured Stanford Bunny mesh partitioned using nearest neighbour.

- ▶ Marching Tetrahedra
  - ▶ Original mesh not preserved
  - ▶ Detail loss
- ▶ Nearest Neighbour
  - ▶ Find only fragment edge voxels
  - ▶ Add them to KDTree
  - ▶ For all vertices, map to nearest voxel

# Rebuilding the Mesh

## Different Approaches



**Figure:** Fractured hollow Stanford Bunny.

- ▶ Marching Tetrahedra
  - ▶ Original mesh not preserved
  - ▶ Detail loss
- ▶ Nearest Neighbour
  - ▶ Find only fragment edge voxels
  - ▶ Add them to KDTree
  - ▶ For all vertices, map to nearest voxel
- ▶ Meshing interior...

# The Next Steps

- ▶ Finish interior meshing algorithm
- ▶ Optimise for speed
  - ▶ Multithreading
  - ▶ Remove unnecessary complexity
- ▶ Post destruction calculations
  - ▶ Fragment mass
- ▶ Evaluation
  - ▶ Framerate
  - ▶ Memory usage
  - ▶ Physical accuracy
- ▶ Write-up