Third / Fourth Year Project Work Form

Student Name: Tom Robson

Supervisor Name: TPB

Date: 1/12/16 @ 11.30am

Progress: (circle at least one): Good

Progress achieved since last meeting

Develop Kalman filtering tracking for multiple objects with list of current scene objects.

Feedback given:

> *Things going well:*
>
> Working Kalman filtering on individual objects
>
> *Things needing to improve:*
>
> Use of Kalman filtering for bounding box and also velocity update (as per photo of whiteboard).

Objectives for next meeting (e.g. reading, implementing, writing tasks):

Use of Kalman filtering for bounding box and also velocity update (as per photo of whiteboard).

Next two weeks - develop Kalman filtering tracking for multiple objects.

Investigate use of MoG2 based on supplied parameters.

Medium term objectives:

As per project plan.

Any other issues/difficulties:

None.

Date of next meeting: 15th Dec. 2016 @ 3pm

Circulation: Student; Supervisor; School Office