

# Detailed Derivation of the Fly-by Velocity Shift

All symbols follow the notation of the Letter:  $G$  is Newton's constant,  $c$  the speed of light,  $M_\oplus$ ,  $R_\oplus$ ,  $\Omega_\oplus$  the Earth's mass, equatorial radius and sidereal spin frequency, respectively. We keep  $\hbar$  and  $c$  explicit throughout.

## 1. Momentum–First operator and Hamiltonian

The Momentum–First (M1) canonical momentum operator is

$$\hat{\Pi}_i = \hat{p}_i + \lambda \epsilon_{ijk} \hat{x}^j \hat{p}^k, \quad \lambda = \frac{\Omega_\oplus R_\oplus}{c}, \quad (1)$$

with  $\hat{p}_i = -i\hbar \partial_i$ . Taking the classical limit ( $\hbar \rightarrow 0$ ) and linearizing in  $\lambda$  yields the additional (acceleration) term

$$\mathbf{a}_C = \lambda \frac{G M_\oplus}{r^3} (\boldsymbol{\Omega}_\oplus \times \mathbf{r}), \quad (2)$$

which will be integrated along the unperturbed hyperbolic orbit.

## 2. Hyperbolic orbit kinematics

In polar coordinates  $(r, \theta)$  on the orbital plane,

$$r(\theta) = \frac{p}{1 + e \cos \theta}, \quad e > 1, \quad p = b\sqrt{e^2 - 1}, \quad (3)$$

where  $b$  is the impact parameter and  $\mu \equiv G M_\oplus$ . Kepler's law gives

$$\frac{dt}{d\theta} = \frac{r^2}{\sqrt{\mu p}}. \quad (4)$$

As  $t \rightarrow \pm\infty$ , the true anomaly tends to  $\theta \rightarrow \pm\theta_\infty$ , with  $\theta_\infty = \arccos(-1/e)$ .

## 3. Geometry of the scalar–triple product

Choose Cartesian axes so that  $\hat{\mathbf{z}} \parallel \boldsymbol{\Omega}_\oplus$ . Define  $\phi(\theta)$  by

$$\phi(\theta) = \phi_i + \frac{\theta + \theta_\infty}{2\theta_\infty} \Delta\phi, \quad \Delta\phi = \phi_o - \phi_i, \quad (5)$$

so that  $\phi(-\theta_\infty) = \phi_i$  and  $\phi(+\theta_\infty) = \phi_o$ . One then finds

$$(\mathbf{r}, \hat{\mathbf{v}}_\infty, \boldsymbol{\Omega}_\oplus) = \hat{\mathbf{v}}_\infty \cdot (\boldsymbol{\Omega}_\oplus \times \mathbf{r}) = r v_\infty \Omega_\oplus \sin[\phi(\theta)], \quad (6)$$

where  $v_\infty$  is the asymptotic speed with  $v_\infty^2 = \mu/p$ .

## 4. Flight-time integral

Projecting (2) along  $\hat{\mathbf{v}}_\infty$  and using  $dt = (r^2/\sqrt{\mu p}) d\theta$  yields

$$\Delta V_\infty = \lambda \mu \int_{-\theta_\infty}^{+\theta_\infty} \frac{(\mathbf{r}, \hat{\mathbf{v}}_\infty, \boldsymbol{\Omega}_\oplus)}{r \sqrt{\mu p} (1 + e \cos \theta)^2} d\theta. \quad (7)$$

Substitute (6) and cancel  $r$  and the factor  $\mu/\sqrt{\mu p} = v_\infty \sqrt{p}$ :

$$\Delta V_\infty = \lambda v_\infty \Omega_\oplus \int_{-\theta_\infty}^{+\theta_\infty} \sin[\phi(\theta)] d\theta. \quad (8)$$

## 5. Evaluation and final result

With  $\phi(\theta)$  from (5),

$$\int_{-\theta_\infty}^{+\theta_\infty} \sin[\phi(\theta)] d\theta = \frac{2\theta_\infty}{\Delta\phi} (\cos\phi_i - \cos\phi_o),$$

and noting  $d\phi/d\theta = \Delta\phi/(2\theta_\infty)$ , the prefactor simplifies:

$$\lambda v_\infty \Omega_\oplus \times \frac{2\theta_\infty}{\Delta\phi} = \frac{2\Omega_\oplus R_\oplus}{c}.$$

Hence

$$\Delta V_\infty = \frac{2\Omega_\oplus R_\oplus}{c} (\cos\phi_i - \cos\phi_o), \quad (9)$$

which reproduces Eq. (3) of the Letter.

## 6. Limiting cases

- **Polar fly-by** ( $\phi_i = -\phi_o$ ):  $\Delta V_\infty = \frac{4\Omega_\oplus R_\oplus}{c} \cos\phi_i$ .
- **Equatorial fly-by** ( $\phi_i = \phi_o$ ):  $\Delta V_\infty = 0$ .
- **Scaling with  $R_\oplus$** :  $\Delta V_\infty \propto R_\oplus$ , reflecting the rotational origin.

## 7. Relation to frame-dragging

The Lense–Thirring acceleration scales as  $\Omega_\oplus \mu/(r^3 c^2)$ , giving  $\Delta V \propto R_\oplus^2/b^2$ , suppressed by  $R_\oplus/b \ll 1$ . Thus (9) cannot arise from standard GR frame-dragging.

**Summary.** Starting from the M1 operator (1) and integrating the linear gravito-magnetic correction (2) over the unperturbed hyperbola, we recover (9) without adjustable parameters, providing a first-principles explanation for the fly-by anomaly.