

01-tools

My repository

[My git - Tomáš Kříčka, 223283](#)

Logical function and symbols for C++

- `&` - AND
- `|` - OR
- `^` - XOR
- `~` - NOT

Code for Morse code

```
#define LED_GREEN    PB5 // AVR pin where green LED is connected
#define SHORT_DELAY 250 // Delay in milliseconds
#define COMMA_DELAY 850 // dash delay
#define DOT_DELAY    450 // dot delay
#ifndef F_CPU         // Preprocessor directive allows for conditional
                      // compilation. The #ifndef means "if not defined".
# define F_CPU 16000000 // CPU frequency in Hz required for delay
#endif               // The #ifndef directive must be closed by #endif

#include <util/delay.h> // Functions for busy-wait delay loops
#include <avr/io.h>     // AVR device-specific IO definitions

int main(void)
{
    // Set pin as output in Data Direction Register
    // DDRB = DDRB or 0010 0000
    DDRB = DDRB | (1<<LED_GREEN);

    // Set pin LOW in Data Register (LED off)
    // PORTB = PORTB and 1101 1111
    PORTB = PORTB & ~(1<<LED_GREEN);

    // Infinite loop
    while (1)
    {
        // Pause several milliseconds
        _delay_ms(SHORT_DELAY); // short wait
        PORTB = PORTB | (1<<LED_GREEN); // led is on
        _delay_ms(DOT_DELAY); // led is on for DOT_DELAY
        PORTB = PORTB & ~(1<<LED_GREEN); // led is off
        _delay_ms(SHORT_DELAY); // shot delay between symlos
    }
}
```

```
    PORTB = PORTB | (1<<LED_GREEN);    // led is on
    _delay_ms(COMMA_DELAY);              // led is on for COMMA_DELAY
    PORTB = PORTB &~ (1<<LED_GREEN);    // led is off
    _delay_ms(SHORT_DELAY);

}

// Will never reach this
return 0;
}
```

Schema

