# Algorithmic Strategies 2024/25 Week 6 – Greedy Algorithms

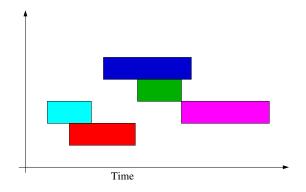


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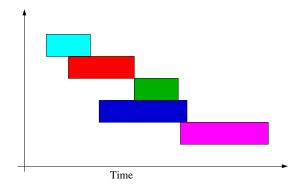
- A set  $S = \{1, ..., n\}$  of activities needs a room. Each room can only be used by one activity at a time.
- Each activity i takes place during the interval  $[s_i, f_i)$ .
- Two activities are compatible if their intervals do not overlap.

Select the minimum number of rooms required to schedule all activities.

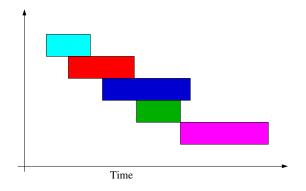
(see Chapter 4.1 of Kleinberg and Tardos, Algorithm Design)



How to solve the problem?



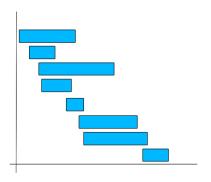
Sorting in non-decreasing order by finishing times?



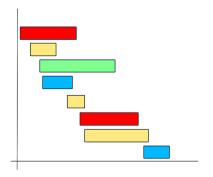
Sorting in non-decreasing order by starting times?

```
Function partition(S) sort S into nondecreasing order by starting times s_i R_1 = R_2 = \ldots = R_n = \emptyset \{n \text{ rooms available}\} d = 0 \{d \text{ is the number of rooms used}\} for i in S do if i can be assigned to some room k \leq d then R_k = R_k \cup \{i\} else R_{d+1} = R_{d+1} \cup \{i\} d = d+1 return d
```

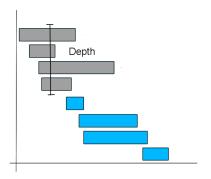
- Greedy choice: choose the next earliest starting time activity
- Why it works?



Sorting in non-decreasing order by starting times.



A solution to the problem.



Depth d is the maximum overlap of activities that can exist, which is the minimum number of rooms required.

#### Claim: The greedy algorithm finds d rooms, where d is the depth

- Assume that the greedy algorithm finds more than d rooms
- Then, at some point in the algorithm, an activity j had requested the d+1-th room.
- This can only happen if there exists d activities that are not compatible among themselves (have requested d rooms) that started before activity j and overlap with its starting time.
   This contradicts the fact that depth is d.

This is easier to show than by using optimal substructure and greedy choice properties.

```
Function partition(S)
sort S into nondecreasing order by starting times s_i
R_1 = R_2 = \ldots = R_n = \emptyset {n rooms available}
d = 0 {d is the number of rooms used}
for i in S do
    if i can be assigned to some room k \le d then
    R_k = R_k \cup \{i\}
else
R_{d+1} = R_{d+1} \cup \{i\}
d = d+1
return d
```

Naïve approach in  $O(n^2)$  time: search for all available rooms at each step.

```
Function partition(S) sort S into nondecreasing order by starting times s_i R_1 = R_2 = \ldots = R_n = \emptyset \{n \text{ rooms available}\} d = 0 \{d \text{ is the number of rooms used}\} for i in S do if i can be assigned to some room k \leq d then R_k = R_k \cup \{i\} else R_{d+1} = R_{d+1} \cup \{i\} d = d+1 return d
```

 $O(n \log n)$  time with a min-priority queue that keeps track of the room that has the activity with the earliest finish time; see priority\_queue in C++.

#### Approximation algorithms

#### Approximation algorithm to the knapsack problem

- 1. Sort the items in nonincreasing order of the ratio  $v_j/w_j$
- 2. Let k be the first item such that  $\sum_{i=1}^{k} w_i > W$
- 3. Let x be a solution with items  $1, \ldots, k-1$  and value  $v(x) = \sum_{i=1}^{k-1} v_i$
- 4. Let x' be a solution that contains only item k and value  $v(x') = v_k$
- 5. Return  $\max(v(x), v(x'))$

This greedy algorithm returns returns 1/2-approximation to the knapsack (the value is 1/2 of the optimal value in the worst case).

#### Approximation algorithms

#### Approximation algorithm to the knapsack problem

- Let  $x^*$  be the optimal solution for the knapsack problem and let  $z^*$  be the optimal solution for the fractional knapsack problem. Note that  $v(x^*) \le v(z^*)$ .
- Note that  $z^*=(1,\ldots,1,\alpha,0,\ldots,0)$ , where  $\alpha\in[0,1)$  at k.
- Note that  $x = (1, \dots, 1, 0, 0, \dots, 0)$ .
- Note that  $x' = (0, \dots, 0, 1, 0, \dots, 0)$ .

$$v(x^*) \le v(z^*) = v(x) + \alpha v_k \le v(x) + v(x') \le 2 \max(v(x), v(x'))$$

$$\max(v(x), v(x')) \ge \frac{v(x^*)}{2}$$