# Verjetnostne metode v računalništvu - zapiski s predavanj prof. Marca

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### Introduction

### 1.1 Probability

```
\begin{split} &(\Omega, F, P_r): \\ &\circ \ \emptyset \in F, \\ &\circ \ A \in F \implies A^c \in F, \\ &\circ \ A_1, A_2 \cdots \in F \implies \cup_{i=1}^\infty A_i \in F. \\ &P_r(A) \geq 0, \\ &P_r\left(\bigcup_{i=1}^\infty A_i\right) = \sum_{i=1}^\infty P_r(A_i) \text{ if } A_i \text{ disjoint,} \\ &P_r\left(\bigcup_{i=1}^\infty A_i\right) \leq \sum_{i=1}^\infty P_r(A_i), \\ &\Omega = \left\{\omega_1, \omega_2 \dots\right\} - \text{countable case.} \\ &\left(\omega_1 \quad \omega_2 \quad \dots \right) \\ &Primer. \\ &\text{Alg():} \\ &\text{while True:} \\ &\text{B = sample as random from } \{0,1\} \quad \text{\# 1 with probability p} \\ &\text{if B = 1:} \end{split}
```

return

$$\Omega = \{1, 01, 001, 0001 \dots\}$$

$$\begin{pmatrix} 1 & 01 & 001 & 0001 & \dots \\ p & (1-p)p & (1-p)^2p & (1-p)^3p & \dots \end{pmatrix}.$$

### 1.2 Random variables

 $X:\Omega\to\mathbb{Z}.$ 

 $E[X] = \sum_{c \in \mathbb{Z}} c \cdot P_r(X = c)$  expected value of X.

Properties:

$$\circ E[f(X)] = \sum_{c \in \mathbb{Z}} f(c) \cdot P_r(X = c),$$

$$\circ \ E[aX + bY] = aE[X] + bE[Y],$$

$$\circ E[X \cdot Y] = E[X] \cdot E[Y]$$
 if  $X, Y$  independent,

$$\circ P_r(X \ge a) \le \frac{E[X]}{a} \, \forall a > 0 \, X \ge 0 \, \text{Markov inequality.}$$

Primer. (Continuing from before).

X = number of trials before return.

$$X:\Omega\to\mathbb{Z}.$$

Trditev 1.2.1.  $E[X] = \frac{1}{p}$ .

**Dokaz 1.2.2.**  $X = \sum_{i=1}^{\infty} X_i$ .

$$X_i = \begin{cases} 1 & \text{if trial } i \text{ is executed} \\ 0 & \text{else} \end{cases}$$

$$E[X] = E[\sum_{i=1}^{\infty} X_i] = \sum_{i=1}^{\infty} E[X_i] =$$

$$= \sum_{i=1}^{\infty} (1-p)^{i-1} = \frac{i=0}{\infty} (1-p)^i = \frac{1}{1-(1-p)} = \frac{1}{p}.$$

$$E[X] = \frac{1}{p}.$$
  
 $P_r(X \ge 100 \cdot \frac{1}{p}) \le \frac{E[X]}{\frac{1}{p}} = \frac{1}{100}.$ 

**Definicija 1.2.3.** 
$$H_n = 1 + \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{n} = \sum_{i=1}^{\infty} \frac{1}{i}$$
.

Izrek 1.2.4.  $H_n \le 1 + \ln(n)$ .

Dokaz 1.2.5.

$$H_n = 1 + \sum_{i=2}^n \frac{1}{i} \stackrel{\text{integral}}{\leq} 1 + \int_1^n \frac{dx}{x} = 1 + \ln(x)|_1^n = 1 + \ln(n).$$

# Quicksort, min-cut

### 2.1 Quicksort

```
Input: set (no equal element) (unordered list) S \in \mathbb{R}
      (or whatever you can compare linearly)

Output: ordered list

Code:
    def Quicksort(S):
    if |S| = 0 or 1:
      return S

    else:
      a = uniformly at random from S

      S^- = {b \in S | b < a}
      S^+ = {b \in S | a < b}
      return Quicksort(S^-), a, Quicksort(S^+)</pre>
```

C(n) - random variable, the number of comparisons in evaluation of Quicksort with |S|=n.

Izrek 2.1.1. 
$$E[C(n)] = O(N \log(n))$$
.

**Dokaz 2.1.2.** 
$$C(0) = C(1) = 0$$
.

$$E[C(n)] = n - 1 + \sum_{i=1}^{n} (E[C(i-1)] + E[C(n-i)]) \cdot P_r(a \text{ is } i\text{-it element}) \le 1 + \frac{2}{n} \sum_{i=1}^{n-1} E[C(i)].$$

Induction:

 $n=1:\checkmark$ 

 $n-1 \rightarrow n$ :

$$\begin{split} E[C(n)] &\leq n + \frac{2}{n} \sum_{i=1}^{n} E[C(i)] \leq \\ &\leq n + \frac{2}{n} \sum_{i=1}^{n} 5i \log i \leq \\ &\leq n + \frac{2}{n} \sum_{i=1}^{\lfloor \frac{n}{2} \rfloor} 5i \log i + \frac{2}{n} \sum_{i=1+\lfloor \frac{n}{2} \rfloor}^{n-1} 5i \log i \leq \\ &\leq n + \frac{2}{n} \sum_{i=1}^{\lfloor \frac{n}{2} \rfloor} 5i \log \frac{n}{2} + \frac{2}{n} \sum_{i=1+\lfloor \frac{n}{2} \rfloor}^{n-1} 5i \log n \leq \\ &(\log \frac{n}{2} = \log n - 1) \\ &\leq n + \frac{2}{n} \left( \sum_{i=1}^{n} 5i \log n - \sum_{i=1}^{\frac{n}{2}} 5i \right) = \\ &= n + \frac{10}{n} \left( \frac{n(n-1)}{2} \log n - \frac{\frac{n}{2}(\frac{n}{2} + 1)}{2} \right) \leq \\ &\leq n + 5(n-1) \log n - n < \\ &< 5n \log n. \end{split}$$

$$P\left(C(n) \geq b \cdot 5n \log n\right) \overset{\text{Markov}}{\leq} \tfrac{1}{b}.$$

#### Dokaz 2.1.3.

2:

Let  $S_1, S_2 \dots S_n$  sorted elements of S.

Define random variable  $X_{ij} = \begin{cases} 1 \text{ if } S_i \text{ and } S_j \text{ are compared} \\ 0 \text{ else} \end{cases}$ 

$$\begin{split} &C(n) = \sum_{1 \leq i < j \leq n} E[X_{ij}]. \\ &E[X_{ij}] = P(S_i \text{ and } X_j \text{ compared}). \\ &S_{ij} \text{ - the last set including } S_i \text{ and } S_j. \\ &E[X_{ij}] = \frac{2}{|S_{ij}|} \leq \frac{2}{j-i+1}. \\ &|S_{ij}| \geq j-i+1. \\ &S_{ij} \text{ has everything in between.} \end{split}$$

$$\implies E[C(n)] \le \sum_{1 \le i < j \le n} \frac{2}{j - i + 1} = \sum_{k=j-i+1}^{n-1} \sum_{j=1}^{n-1} \sum_{k=2}^{n-i+1} \frac{2}{k} \le \sum_{k=j-i+1}^{n-1} \sum_{k=j}^{n-1} \sum_{k=j-i+1}^{n-1} \frac{2}{k} \le \sum_{k=j-i+1}^{n-1} \sum_{k=j-i+1}^{n-1} \sum_{k=j-i+1}^{n-1} \frac{2}{k} \le \sum_{k=j-i+1}^{n-1} \sum_{k=j-i+1}^{n-1} \sum_{k=j-i+1}^{n-1} \frac{2}{k} \le \sum_{k=j-i+1}^{n-1} \frac{2}{k} \le$$

$$\leq 2 \cdot n \cdot H_n \leq$$

$$\leq 2n(1+\log n).$$

### 2.2 Min-cut

G multigraph.

Cut:  $U \subset V(G), \ U \neq \emptyset, V(g)$ .

$$(U,V(G)\setminus U)=\{uv\in E(G)\mid u\in U,v\in V(G)\setminus U\}.$$

Problem min-cut:

Input: G.

Output:  $\min |(U, V(G) \setminus U)|$  - cut size.

Algorithm 1:

 $x \in V(G)$ 

Call maxFlow(G, x, y)  $\forall y \in V(G)$ 

Take min

maxFlow is Edmonds-Karp algorithm  $O(|V||E|^2)$ .

Algorithm 2 (Stoer Wagner)

Is 
$$O(|E||V| + |V|log|V|)$$
.

Algorithm randMinCut:

$$\begin{split} & \texttt{G\_0} = \texttt{G} \\ & \texttt{i} = \texttt{0} \\ & \texttt{while} \ | \texttt{V}(\texttt{G}_i) | > 2 \colon \\ & \texttt{e}_i = \texttt{uniformly at random from } \texttt{G}_i \\ & \texttt{G}_{i+1} = \texttt{G}_i \ / \ e_i \\ & \texttt{i} = \texttt{i} + \texttt{1} \\ & \texttt{u, v} = \texttt{V}(\texttt{G}_{n-2}) \ / / \ n = | \texttt{V}(\texttt{G}) | \\ & \texttt{U} = \{ \texttt{w} \in \texttt{V}(\texttt{G}) \ | \ \texttt{w is merged into u} \} \\ & \texttt{return (U, V(\texttt{G}) \setminus U)} \end{split}$$

**Izrek 2.2.1.** Algorithm randMinCut gives you a minimal cut with probability greater or equal to  $\frac{2}{n(n-1)}$ .

#### Dokaz 2.2.2.

Fact 1:  $minCut(G_i) \leq minCut(G_i)$ ;

 $\geq$ : minCut remains.

Fact 2:  $minCut(G) < \delta(G)$ .

k := minCut(G).

Let (A,B) be an optimal cut.

 $\epsilon_i$  not in (A,B).

 $P_r(Algorithm not returning (A,B))$ 

$$= P_r(\epsilon_0 \cap \cdots \cap \epsilon_{n-3})$$

$$= P_r(\epsilon_0 \cap \cdots \cap \epsilon_{n-4}) \cdot P_r(\epsilon_{n-3} \mid \epsilon_0 \cap \cdots \cap \epsilon_{n-4})$$

$$= P_r(\epsilon_{n-3} \mid \cap_{i=0}^{n-4} \epsilon_i) \cdot P_r(\epsilon_{n-3} \mid \cap_{i=0}^{n-4} \epsilon_i)$$

$$\dots P_r(\epsilon_1 \mid \epsilon_0) \cdot P_r(\epsilon_0).(*)$$
(2.1)

$$P_r(\overline{\epsilon_i} \mid \epsilon_{i-1} \cap \dots \cap \epsilon_0) = \frac{k}{|E(G_i)|} \stackrel{(**)}{\leq} \frac{k}{\frac{(n-i)k}{2}} = \frac{2}{n-i}$$
$$|E(G_i)| \geq \frac{(n-i)\delta(G)}{2} \geq \frac{(n-i)k}{2}.(**)$$
(2.2)

$$P_r(\epsilon_i \mid \epsilon_{i-1} \cap \dots \cap \epsilon_0) \ge 1 - \frac{2}{n-i} = \frac{n-2-i}{n-i}.$$

$$(*) \ge \frac{n-2}{n} \cdot \frac{n-3}{n-1} \dots \frac{1}{3} = \frac{2}{n(n-1)}.$$

**Izrek 2.2.3.** Running  $randMinCut\ n(n-1)$  times and taking best output gives correct solution with probability  $\geq 0.86$ .

**Dokaz 2.2.4.**  $A_i$  - event that *i*-th run gives sub-optimal solution.

$$\begin{split} P_r(\text{solution not correct}) &= P_r(A_1 \cap \dots \cap A_{n(n-1)}) \\ &= \prod_{i=1}^{n(n-1)} P_r(A_i) \le (1 - \frac{2}{n(n-1)})^{n(n-1)} \\ &\le e^{-\frac{2}{n(n-1)} \cdot n(n-1)} = e^{-2} \le 0.14. \end{split}$$

 $1 - x \le e^x \ \forall x \in \mathbb{R}.$ 

If we run n(n-1)log(n) times  $\to O\left(\frac{1}{n}\right)$ .  $O\left(n^2 \log n \cdot n\right)$ .

Improved:  $O(n^2 \log^3 n)$ .

## Complexity classes

Decision problem - yes/no question on a set of inputs = asking  $w \in \Pi$ . Randomized algorithms:

- Las Vegas algorithms: always gives correct solution, example: Quicksort.
- Monte Carlo algorithms: it can give wrong answers. Monte Carlo algorithms subtypes:

$$- \text{ type}(1) \colon \begin{cases} \text{if } \omega \in \Pi \implies \text{ algorithm returns } "\omega \in \Pi \text{" with probability } \geq \frac{1}{2} \\ \text{if } \omega \notin \Pi \implies \text{ algorithm returns } "\omega \in \Pi \text{" with probability } = 0 \end{cases}$$

$$- \text{ type}(2) \colon \begin{cases} \text{if } \omega \in \Pi \implies \text{ algorithm returns } "\omega \in \Pi \text{" with probability } = 1 \\ \text{if } \omega \notin \Pi \implies \text{ algorithm returns } "\omega \in \Pi \text{" with probability } \leq \frac{1}{2} \end{cases}$$

$$- \text{ type}(3) \colon \begin{cases} \text{if } \omega \in \Pi \implies \text{ algorithm returns } "\omega \in \Pi \text{" with probability } \geq \frac{3}{4} \\ \text{if } \omega \notin \Pi \implies \text{ algorithm returns } "\omega \in \Pi \text{" with probability } \leq \frac{1}{2} \end{cases}$$

type(1) and type(2): one-sided error, type(3): 2-sided error.  $\frac{1}{2}$ ,  $\frac{3}{4}$  and  $\frac{1}{4}$  arbitrary numbers, can be something different (for type(3) better than coin flip).

*Primer.* Decisional problem: does a graph G have  $minCut \leq k$ ?

```
Run randMinCut(G) n(n-1) times. 
 Algorithm randMinCut: 
 if one of runs gives |(A,B)| \leq k: 
 return true 
 else: 
 return false
```

### Complexity classes:

- RP (randomized polynomial time): decisional problems for which there exists Monte Carlo algorithm of type(1) with polynomial time complexity (worst case).
- co-RP: decisional problems for which there exists Monte Carlo algorithm of type(2) with polynomial time complexity (worst case).
- BRP (bounded-error probabilistic polynomial time): decisional problems for which there exists Monte Carlo algorithm of type(3) with polynomial time complexity (worst case).
- ZPP (zero-error probabilistic polynomial time): decisional problems for which there exists Las Vegas algorithm with expected polynomial time complexity (worst case).

```
ZPP = RP \cap co-RP.
```

# Chernoff bounds

**Izrek 4.0.1.** Let  $X_1, X_2 ... X_n$  independent random variables with image  $\{0, 1\}$ .

Let  $p_i = P_r(X_i = x_i), X = \sum_{i=1}^n X_i$  and  $\mu = E(X) = p_1 + \dots + p_n$ . For every  $\delta \in (0,1)$ :

$$P_r(X - \mu \ge \delta\mu) \le e^{-\frac{\delta^2\mu}{3}}$$

$$P_r(\mu - X \le \delta\mu) \le e^{-\frac{\delta^2\mu}{2}}$$

$$\Longrightarrow P_r(|X - \mu| \ge \delta\mu) \le e^{-\frac{\delta^2\mu}{3}}.$$

Probability falls extremely quickly after E(X).

#### Dokaz 4.0.2.

$$P_r(X - \mu \ge \delta \mu) = P_r(X \ge \mu(1 + \delta))$$

$$\stackrel{t \ge 0}{=} P_r(tX \ge t\mu(1 + \delta))$$

$$\stackrel{e^y > 0}{=} P_r(e^{tX} \ge e^{t\mu(1 + \delta)})$$

$$\stackrel{\text{Markov}}{\leq} \frac{E\left(e^{tX}\right)}{e^{t\mu(1 + \delta)}}$$

$$\stackrel{4.1}{\leq} \frac{e^{(e^t - 1)\mu}}{e^{t\mu(1 + \delta)}}$$

$$\stackrel{4.3}{\leq} e^{-\mu \frac{\delta^2}{3}}.$$

$$E(e^{tX}) = E(e^{tX_1 + \dots + tX_n})$$

$$= E(e^{tX_1} \dots e^{tX_n})$$

$$\stackrel{\text{independent}}{=} \prod_{i=1}^n E(e^{tX_i})$$

$$\stackrel{4.2}{\leq} \prod_{i=1}^n e^{p_i(e^t - 1)}$$

$$= e^{(e^t - 1)\sum_{i=1}^n p_i}$$

$$= e^{(e^t - 1)\mu}.$$

$$(4.1)$$

$$E(e^{tX_i}) = p_i \cdot e^t + (1 - p_i) \cdot e^0 = 1 + p_i(e^t - 1) \stackrel{1 + x \le e^x}{\le} e^{p_i(e^t - 1)}.$$
 (4.2)

Want:

$$e^{t} - 1 - t(1 + \delta) \le -\frac{\delta^{2}}{3} \,\forall \delta \in (0, 1)$$
 (4.3)

$$\begin{split} t &= \ln(1+\delta) \\ f(\delta) &= 1 + \delta - 1 - (1+\delta) \ln(1+\delta) + \frac{\delta^2}{3} \stackrel{?}{\leq} 0 \\ f(0) &= 0 \\ f'(\delta) &= 1 - \ln(1+\delta) - 1 + \frac{2}{3}\delta = \frac{2}{3}\delta - \ln(1+\delta) \stackrel{?}{\leq} 0 \\ \frac{2}{3}\delta &\leq \ln(1+\delta) \\ \delta &= 1 : \frac{2}{3} \stackrel{?}{\leq} \ln(2) \approx 0.69 \checkmark \end{split}$$

$$P_r(\mu - X \le \delta \mu) = P_r(X \ge \mu(1 - \delta))$$

$$\stackrel{t \ge 0}{=} P_r(tX \ge t\mu(1 - \delta))$$

$$\stackrel{e^y \ge 0}{=} P_r(e^{tX} \ge e^{t\mu(1 - \delta)})$$

$$\le \dots \le \frac{e^{(e^t - 1)\mu}}{e^{t\mu(1 - \delta)}}.$$

Want: 
$$e^t - 1 - t(1 - \delta) \le -\frac{\delta^2}{2} \ \forall \delta \in (0,1)$$
:

$$t = \ln(1 - \delta)$$

$$f(\delta) = 1 - \delta - 1 - (1 - \delta)\ln(1 - \delta) + \frac{\delta^2}{2} \stackrel{?}{\leq} 0$$

$$f(0) = 0$$

$$f'(\delta) = -1 + 1 - \ln(1 - \delta) + \delta \stackrel{?}{\leq} 0$$

$$\frac{2}{3}\delta \leq \ln(1 + \delta)$$

$$\ln(1 - \delta) \stackrel{?}{\leq} -\delta \checkmark$$

$$X_i \sim \begin{pmatrix} 0 & 1 \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$
$$X = \sum_{i=1}^n X_i$$
$$\mu = \frac{n}{2}$$

$$P_r(|X - \mu| \ge \sqrt{\frac{3}{2}n\ln(n)}) = P_r(|X - \mu| \ge \frac{n}{2}\sqrt{\frac{6}{n}\ln(n)})$$

$$\mu = \frac{n}{2}, \delta = \sqrt{\frac{6}{n}\ln(n)},$$
for "big"  $n\delta \in (0,1)$ 

$$\stackrel{\text{Chernoff}}{\le} 2e^{-\frac{n}{2}\frac{6}{n}\ln(n)} = \frac{2}{n}.$$

$$d = \sqrt{\frac{3}{2}n\ln(n)}$$

$$\implies P_r(X \in (\mu - \sqrt{\frac{3}{2}n\ln(n)}, \mu + \sqrt{\frac{3}{2}n\ln(n)})) \ge 1 - \frac{2}{n}.$$

#### Trditev 4.0.3.

Let  $X_1, X_2 \dots$  independent random variables with image  $\{0,1\}$ .

$$P_r(X_i = 1) = \frac{1}{2} \ \forall i.$$

Let 
$$X = \sum_{i=1}^{cm} X_i$$
 where  $c \ge 4$ .

Then 
$$P_r(X \le m) \le e^{-\frac{cm}{16}}$$
.

#### Dokaz 4.0.4.

$$P_r(X \le m) = P_r(\frac{cm}{2} - X \ge \frac{cm}{2} - m)$$

$$= P_r(\frac{cm}{2} - X \ge \frac{cm}{2}(1 - \frac{2}{c}))$$

$$\stackrel{\text{Chernoff}}{\le} e^{-\frac{\frac{cm}{2}(1 - \frac{2}{c})^2}{2}}$$

$$1 - \frac{2}{c} \ge \frac{1}{2} \text{ if } c \ge 4$$

$$\le e^{-\frac{cm}{2}\frac{1}{4}} = e^{-\frac{cm}{16}}.$$

Back to Quicksort.

#### Izrek 4.0.5.

With probability  $\geq 1 - \frac{1}{n}$  Quicksort uses at most  $48n \ln(n)$  comparisons.

### Dokaz 4.0.6.

For  $s \in S$  define  $S_1^S \dots S_{t_s}^S \neq \emptyset$  sets that include  $s, t_s$  - number of comparisons with s where s is not a pivot +1.

Define: iteration i is successful if  $|S_{i+1}| \leq \frac{3}{4}|S_i|$  ( $\frac{1}{2}$  is too strict).

$$X_i = \begin{cases} 1 \text{ if iteration } i \text{ is successful} \\ 0 \text{ else} \end{cases}$$

$$P_r(X_i = 1) \ge \frac{1}{2}$$
  
$$S_i : n \to \frac{3}{4}n \to (\frac{3}{4})^2 n \to \cdots \to 1.$$

Notice: max number of iteration is  $\log_{\frac{4}{3}}(n) = \frac{\ln(n)}{\ln(4) - \ln(3)}$ .

Probability that we haven't succeeded in  $\log_{\frac{4}{3}}(n)$  steps:

$$P_r(\sum_{i=1}^{c \log_{\frac{4}{3}}(n)} X_i < \log_{\frac{4}{3}}(n)) \le P_r(\sum_{i=1}^{c \log_{\frac{4}{3}}(n)} Y_i < \log_{\frac{4}{3}}(n))$$
(4.4)

$$\stackrel{\text{Chernoff}}{<} e^{-\frac{c \log_{\frac{4}{3}}(n)}{24}} \tag{4.5}$$

$$=e^{-\frac{c\ln(n)\log_{\frac{4}{3}}(e)}{24}}\tag{4.6}$$

$$=\frac{1}{n}\frac{c\log_{\frac{4}{3}}(e)}{24}\tag{4.7}$$

$$\log_{\frac{4}{3}}(e) \approx 3.4, \ c = 14$$
 (4.8)

$$\leq \left(\frac{1}{n}\right)^2\tag{4.9}$$

4.4 because  $X_i$  not independent,  $Y_i \sim \begin{pmatrix} 0 & 1 \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$  independent.

 $P_r(t_s \ge c \log_{\frac{4}{3}}(n)) \ge \left(\frac{1}{n}\right)^2$  for one s.

 $c = 14 \implies$  at least  $48 \ln(n)$  iterations with probability  $\leq \left(\frac{1}{n}\right)^2$ .

With probability as least  $1 - \frac{1}{n}$  for all  $s \in S$  it holds that s has  $\leq 48 \ln(n)$  comparisons with a pivot.

 $\implies$  total number of comparisons  $n \cdot 48 \ln(n)$  with probability as least  $1 - \frac{1}{n}$ .

### Monte Carlo methods

### 5.1 Example 1

Area of circle  $= \frac{\pi}{4}$ .  $X_i = \begin{cases} 1 \text{ if you hit the area of circle} \\ 0 \text{ else} \end{cases}$   $P_r(X_i = 1) = \frac{\frac{\pi}{2}}{1} = \frac{\pi}{4}.$   $E(X_i) = \frac{\pi}{4}.$   $X = \frac{\sum_{i=1}^n X_i}{n}.$   $E(X) = \frac{n \cdot E(X_i)}{n} = E(X_i).$ 

### 5.2 Example 2

$$I = \int_{\Omega} f(x)dx - \text{volume.}$$

$$X_i = \begin{cases} 1 \ F(x_i, y_i) \le z_i \\ 0 \ \text{otherwise} \end{cases}$$

$$v \cdot E\left(\frac{\sum_{i=1}^n X_i}{n}\right) = I.$$

### 5.3 $(\epsilon, \delta)$ -approximation

**Definicija 5.3.1** ( $(\epsilon, \delta)$ -approximation). A random algorithm gives a  $(\epsilon, \delta)$ -approximation for value v if the output X satisfies:

$$P_r(|X - v| \le \epsilon v) \ge 1 - \delta.$$

**Izrek 5.3.2.** Let  $X_1 
ldots X_n$  be independent and identically distributed indicator variables. Let  $\mu = E(X_i)$ ,  $Y = \frac{\sum_{i=1}^m X_i}{m}$ . If  $m \ge \frac{3 \ln(\frac{2}{\delta})}{\epsilon^2 \mu}$ , then  $P_r(|Y - \mu| \ge \epsilon \mu) \le \delta \implies Y$  is  $(\epsilon, \delta)$ -approximation for  $\mu$ .

#### Dokaz 5.3.3.

$$X = \sum_{i=1}^{n} X_i$$

$$E(X) = mE(x_i) = m\mu$$

$$m \ge \frac{3\ln(\frac{2}{\delta})}{\epsilon^2 \mu}$$

$$P_r(|Y - \mu| \ge \epsilon \mu) = P_r(\left|\frac{X}{m} - \mu\right| \ge \epsilon \mu)$$

$$= P_r(\frac{1}{m}|X - E(X)| \ge \frac{1}{m}\epsilon E(x))$$

$$\stackrel{\text{Chernoff}}{\le} 2e^{-\frac{\epsilon^2 E(x)}{3}}$$

$$= 2e^{-\frac{\epsilon^2 \mu m}{3}}$$

$$\le 2e^{-\frac{\epsilon^2 \mu}{3} \cdot \frac{3\ln(\frac{2}{\delta})}{\epsilon^2 \mu}} = \delta.$$

Back to example 1:

$$E(Y) = \frac{\pi}{4}, \delta = \frac{1}{1000} \text{ (99.9\% sure)}, \epsilon = \frac{1}{10000}$$
  
 $\implies M = \frac{3\ln\left(\frac{2}{1000}\right)^4}{\pi\left(\frac{1}{10000}\right)^2} \approx 29106.$ 

Problems for MC (Monte-Carlo):

• rare events, e.g. 
$$X \sim \begin{pmatrix} 0 & 10^{100} \\ 1 - 10^{-20} & 10^{-20} \end{pmatrix}$$
,  $E(X) = 10^{80}$ 

### 5.4 DNF counting

CNF:  $(X_{i_1} \vee \overline{X_{i_2}} \vee X_{i_4}) \wedge (X_{i_1} \vee \overline{X_{i_3}}) \wedge \dots$ 

DNF:  $(\overline{X_{i_1}} \wedge X_{i_2} \vee \overline{X_{i_4}}) \vee \dots$  - easy to determine if solution exists.

Question: number of solutions to a given DNF?

Observation: CNF F has a solution  $\iff$  DNF  $\neg F$  has less than  $2^n$  solutions, n is number of samples.

```
\begin{array}{l} \operatorname{ALG\_1(F):} \\ x = 0 \\ \text{for i in range(1,m+1):} \\ x\_1 \ \ldots \ x\_n \ \text{uniformly random from } \{0,1\}^n \\ \text{if } F(x\_1 \ \ldots \ x\_n) = 1: \\ x += 1 \\ \text{return } \frac{x}{m} \cdot 2^n \\ Y = \frac{\sum_{i=1}^m X_i}{m} \\ (\epsilon,\delta)\text{-approximation for } Y \\ E(Y) = \frac{\text{number of solutions of } F}{2^n} = \frac{c(F)}{2^n} \\ m \geq \frac{3\ln\left(\frac{2}{\delta}\right)}{\epsilon^2 E(X)} = \frac{3\ln\left(\frac{2}{\delta}\right)}{\epsilon^2} \cdot \frac{2^n}{x(F)} \\ c(F) \ \text{very small} \rightarrow m \ \text{exponentially big} \rightarrow \text{not good (we need a lot of samples)}. \end{array}
```

#### Definicija 5.4.1.

Definition 3.4.1. 
$$SC_i = \{(a_1 \dots a_n) \in \{0,1\}^n \text{ such that } F = F_1 \vee \dots \vee F_t, \ F_i(a_1 \dots a_n) = 1\}.$$

$$|SC_i| = 2^{n-l_i}, \ l_i \text{: number of values in } F_i$$

$$U = \{(i,a) \mid i \in \{1,2 \dots t\}, \ a \in SC_i\}$$

$$U = \sum_{i=1}^t |SC_i| - O(tn) \text{ (space smaller than } \{0,1\}^n)$$

$$S = \{(i,a) \in U \mid a \in SC_i, \ a \notin SC_j \ 1 \leq j < i\}$$

$$|S| = |SC_1| + \dots + |SC_t| = c(F).$$

$$\text{ALG_2(F):}$$

$$x = 0$$

$$\text{for i in range(1,m+1):}$$

(i, a) uniformly random from U (\*\*)

if (i, a) 
$$\in$$
 S: (\*)

$$x += 1$$

 $\texttt{return} \ \tfrac{x}{m} \ \cdot \ |U|$ 

(\*)  $a \in SC_i \to O(n), \ a \notin SC_j \ j = 1 \dots i - 1 \to O(tn) \implies O(tn), m$ 

(\*\*): watch for details on how to, e.g.  $x_2, x_2 \wedge x_3$ :  $x_2$  is more probable than  $x_2 \wedge x_3 \to O(1)$ .

**Izrek 5.4.2.** For  $m = \lceil \frac{3t \ln\left(\left(\frac{2}{\delta}\right)\right)}{\epsilon^2} \rceil$  algorithm returns  $(\epsilon, \delta)$ -approximation in  $O\left(\frac{t^n n \ln\left(\frac{2}{\delta}\right)}{\epsilon^2}\right)$  time.

Dokaz 5.4.3.  $O(t \cdot n \cdot m)$ .

Insert  $m = \dots$ 

Prove

$$P_r(Y|U| - c(F) > \epsilon c(F)) < \delta$$
:

$$c(F) = |S|, E(Y) = \frac{|S|}{|U|}$$

$$P_r(Y|U| - c(F) > \epsilon c(F)) = P_r(|U|(Y - E(Y)) > \epsilon |U|E(Y)) \le \delta$$

if

$$m \ge \frac{3\ln\left(\frac{2}{\delta}\right)}{\epsilon^2 E(Y)} \ge \frac{3\ln\left(\frac{2}{\delta}\right)t}{\epsilon^2}$$

where

$$E(Y) = \frac{|S|}{|U|} \ge \frac{1}{t}$$

(= if disjoint).

In new space E(Y) much larger  $\implies m$  smaller.

# Polynomials

Let  $\mathbb{F}$  be a field.

 $\mathbb{F}$  can be  $\mathbb{R}, \mathbb{C}, \mathbb{Z}_p, \mathbb{F}_{p^n}$ .

 $\mathbb{F}[x_1 \dots x_n]$  algebra of polynomials with values  $x_1 \dots x_n$ .

$$f \in \mathbb{F}[x_1 \dots x_n]$$

$$deg(f[x_1 \dots x_n]) := deg(f[x \dots x]).$$

**Izrek 6.0.1.** Let  $p(x_1 \ldots x_n) \in \mathbb{F}[x_1 \ldots x_n]$  have the degree  $d \geq 0$  and  $p \neq 0$ . Let  $s \subset \mathbb{F}$  be finite. If  $(r_1 \ldots r_n)$  is uniformly at random element from  $S^n$ . Then  $P_r(p(r_1 \ldots r_n) = 0) \leq \frac{d}{|S|}$ .

**Dokaz 6.0.2.** Induction on n.

n = 1:

$$p(x) = (x - z_1)(x - z_2) \dots (x - z_j)q(z)$$

number of zeros  $\leq$  degree - fact

$$P_r(p(r_1) = 0) = \frac{\text{number of zeros}}{|S|} \le \frac{d}{|S|}.$$

 $n-1 \rightarrow n$ :

rewrite p:

$$p(x_1 \dots x_n) = \sum_{i=0}^{j} x^i p_i(x_2 \dots x_n)$$

$$j \le d$$

$$P_r(p(r_1 \dots r_n) = 0) = P_r(p(r_1 \dots r_n = 0) \mid p_j(r_2 \dots r_n) = 0) \cdot P_r(p_j(r_2 \dots r_n) = 0)$$

$$+ P_r(p(r_1 \dots r_n = 0) \mid p_j(r_2 \dots r_n) \ne 0) \cdot P_r(p_j(r_2 \dots r_n) \ne 0)$$

$$\le 1 \cdot \frac{d-j}{|S|} + \frac{j}{|S|} \cdot 1,$$

because

$$P_r(p(r_1...r_n = 0) \mid p_j(r_2...r_n) \neq 0) \le \frac{d-j}{|S|}$$
  
 $P_r(p_j(r_2...r_n) \neq 0) \le \frac{j}{|S|}.$ 

### <u>Problem</u>:

Let  $A,B,C \in \mathbb{F}^{n \times n}$ , is  $A \cdot B = C$ ? Computing  $A \cdot B$ :

- school-book algorithm:  $O(n^3)$ ,
- Strassen algorithm:  $O(n^{2,807...})$ ,
- galactic algorithm:  $O(n^{2.372...})$  has enormous constants.

RAND\_ACB(A,B,C):

```
for i in range(1,k+1):  \text{x uniformly at random from } \{0,1\}^n  if A \cdot (B \cdot x) \neq x:  \text{return false}   \text{return true}
```

 $O(kn^2)$ .

If  $A \cdot B = C$ , algorithm returns true.

If  $A \cdot B \neq C$ :

$$P_r(ABx = Cx) = P_r((AB - C)x = 0)$$
  
=  $P_r(||(AB - C)x||^2 = 0) \stackrel{\text{Poly }}{\leq} \frac{2}{3}$ .

 $||(AB_C)x||^2$  - polynomial in  $x_1 \dots x_n$  of degree 2.

If  $A \cdot B \neq C$ , then algorithm return false with probability at least  $1 - \left(\frac{2}{3}\right)^k$ . Problem:

1-factor in bipartite graphs.

$$|V(g)| = 2n.$$

Represent G with  $n \times n$  matrix  $Z = (Z_{ij})_{i,j=1}^n$ 

$$Z_{ij} = \begin{cases} X_{ij} \text{ if } a_i b_j \in E(x) & \text{(X: variable)} \\ 0 \text{ else} \end{cases}$$

$$det Z(x_{11} \dots x_{nn}) = \sum_{\pi \in S_n} sign(\pi) z_{1,\pi(1)} \dots z_{n,\pi(n)}$$
$$= \sum_{\pi \in S_n, \pi \text{ defines 1-factor}} sign(\pi) x_{1,\pi(1)} \dots x_{n,\pi(n)}.$$

 $det Z \neq 0 \iff G \text{ has 1-factor.}$ 

```
Rand_1factor(G):
```

construct Z with variables x11 ... xnn

for i in range(1,k+1):

u <- uniformly at random from  $1,2..2n-1^{n^2}$  (r11 ... rnn) compuze d = det Z(r11 ... rnn)

if d != 0:

return true

return false

Complexity:  $k \cdot$  computing determinant:  $O\left(n^3\right)$  (Gaussian elimination). or apply approximation algorithm:

- ullet if G has no 1-factor it always returns false,
- if G has 1-factor, it returns true with probability at least  $1 \left(\frac{n}{2n}\right)^k = 1 \left(\frac{1}{2}\right)^k$  (k konstant, larger set  $\implies$  smaller k needed).

# Random graphs

### $7.1 \quad G(n,p) \mod el$

G is a random Erdös-Rény graph if it has n vertices and each pair of vertices is connected with probability p.

Primer. 
$$G\left(5,\frac{1}{2}\right)$$
.

$$E(\text{ edges in } G \text{ fron } G(n,p)) = \sum_{1 \le i < j \le n} E(X_{ij}) = \binom{n}{2} p.$$

$$X_{ij} = \begin{cases} 1 & \text{if } i \text{ and } j \text{ have edge} \\ 0 & \text{otherwise} \end{cases}$$

p can be function of n.

 $Y_v$ : degree of v.

$$E(Y_v) = (n-1)p.$$

#### Definicija 7.1.1.

We say that a random graph has some property almost surely (A.S.) if  $P_r(G \in G(n,p))$  has property)  $\stackrel{n\to\infty}{\to} 1$ .

### Trditev 7.1.2.

Let p be constant. Then  $G \in G(n,p)$  has diameter 2 A.S.

#### Dokaz 7.1.3.

Let 
$$u,v \in V(G)$$

$$X_w = \begin{cases} 1 \text{ if } uw \in E(G) \text{ in } vw \in E(G) \\ P_r(X_w = 1) = p^2 \end{cases}$$

$$P_r(X_w = 0 \text{ for all } w \neq u,v) = (1 - p^2)^{n-2}.$$

$$P_r(G \text{ has diameter } > 2)$$

$$= P_r(X_w = 0 \text{ for all } w \notin u,v \text{ for some } u,v)$$

$$\leq \binom{n}{2}(1 - p^2)^{n-2} \stackrel{n \to \infty}{\to} 0;$$

$$\binom{n}{2} \text{ - polynomial, } e^{\dots} \text{ - exponent.}$$

$$p = f(n)$$

$$\frac{1}{n}, \frac{1}{n^3}, \frac{\log n}{n}$$

### Izrek 7.1.4. (without proof)

Let p be a function of n: let  $G \in G(n,p)$ :

- np < 1 G A.S. disconnected with connected components of size  $O(\log n)$
- np = 1 G A.S. has 1 large component of size  $O\left(n^{\frac{2}{3}}\right)$
- np = c > 1 G A.S. has giant component of size  $dn, d \in (0,1)$
- $np \leq (1-\epsilon) \ln n$  G A.S. disconnected with isolated vertices
- $np > (1 \epsilon) \ln n G$  A.S. connected.

### Izrek 7.1.5.

Let  $np = \omega(n) \ln(n)$  for  $\omega(n) \to \infty$  , very slowly think of  $\omega(n) = \log(\log n)$ , then diam(G) in  $\Theta\left(\frac{\ln n}{\ln(np)}\right)$  for G in G(n,p).

#### Lema 7.1.6.

Let  $S \subset V(G), |S| = cn$  for  $c \in (0,1]$  and  $v \notin S$ . then  $cnp(1 - \omega^{-\frac{1}{3}}) \leq N_S(v) \leq cnp(1 + \omega^{-\frac{1}{3}})$  A.S.  $(\omega^{-\frac{1}{3}} \to 0 \text{ very slowly})$ .

### **Dokaz 7.1.7.** (Lemma):

$$E(N_s(v)) = c \cdot n \cdot p, \delta = \omega^{-\frac{1}{3}}$$

$$P_r(|N_s(v) - cnp| \ge \delta cnp) \stackrel{\text{Chernoff}}{\le} 2e^{-\frac{\omega^{-\frac{2}{3}}cnp}{3}}$$
$$= 2e^{-\frac{cnp}{3\omega(n)^{\frac{2}{3}}}} \stackrel{n \to \infty}{\to} 0.$$

For all  $v: n \cdot 2e^{-\frac{cnp}{3\omega(n)^{\frac{2}{3}}}} \stackrel{n \to \infty}{\longrightarrow} 0.$ 

### Dokaz 7.1.8. (Theorem):

k be such that  $\sum_{i=0}^{k-1} |N_i| \leq \frac{n}{2}, \sum_{i=0}^{k} |N_i| > \frac{n}{2}$ .

$$|N_0| = 1$$

$$|N_i| \le |N_{i-1}| \cdot n \cdot p \cdot (1 + \omega^{-\frac{1}{3}})$$
:

$$\begin{split} |S| &\leq n, \ np(1+\omega^{-\frac{1}{3}})\text{-each element.} \\ k &= \frac{\log\left(\frac{n}{3}\right)}{\log\left(n\cdot p\cdot\left(1+\omega^{-\frac{1}{3}}\right)\right)} \\ &= \log_{np(1+\omega^{-\frac{1}{3}})}\frac{n}{3} = \Theta\left(\frac{\ln(n)}{\ln(np)}\right). \\ |N_{\leq k}| &= |N_1 \cup \dots \cup N_k|. \end{split}$$

$$|N_{\leq k}| \leq \sum_{i=0}^{k} (np(1+\omega^{-\frac{1}{3}}))^{i}$$

$$= \frac{(np(1+\omega^{-\frac{1}{3}}))^{k+1} - 1}{np(1+\omega^{-\frac{1}{3}}) - 1}$$

$$< \frac{np(1+\omega^{-\frac{1}{3}})^{k+1}}{\frac{1}{2}np(1+\omega^{-\frac{1}{3}})}$$

$$= 2np(1+\omega^{-\frac{1}{3}})^{k}$$

$$\stackrel{k}{=} 2 \cdot \frac{n}{3} \text{ haven't covered all}$$

$$\implies diam(G) > k \text{ bound from below.}$$

$$\begin{aligned} N_i &\subseteq S \\ \frac{1}{2} n p \left( 1 - \omega^{-\frac{1}{3}} \right) \cdot |N_{i-1}| \leq |N_i| \end{aligned}$$

$$\begin{split} n &\geq \sum_{i=0}^{k} |N_i| \\ &\geq \sum_{i=0}^{k} \left(\frac{1}{2} n p \left(1 - \omega^{-\frac{1}{3}}\right)\right)^i \\ &= \frac{\left(\frac{1}{2} n p \left(1 - \omega^{-\frac{1}{3}}\right)\right)^{k+1} - 1}{\frac{1}{2} n p \left(1 - \omega^{-\frac{1}{3}}\right) - 1} \\ &\geq \left(\frac{1}{2} n p \left(1 - \omega^{-\frac{1}{3}}\right)\right)^k \quad / \ln \end{split}$$

$$\frac{\ln n}{\ln(np)} \approx \frac{\ln n}{\ln\left(\frac{1}{2}np\left(1-\omega^{-\frac{1}{3}}\right)\right)} \ge k.$$

$$\implies w \in S'.$$

Number of neighbors in  $N_k$  A.S.  $\geq 1$ ,

$$|N_k| \ge \left(\frac{1}{2}np\left(1 - \omega^{-\frac{1}{3}}\right)\right)^k \approx c \cdot n$$
  
 $\implies diam(G) = k + 1 \text{ A.S.}$ 

### 7.1.1 Scale free property

 $G \in G(n,p)$ .

In real world: p(k) = proportion of degree k vertices.

 $\log(p(k)) = -\gamma \cdot \log k$ 

 $p(k) = k^{-\gamma}.$ 

Internet:  $\gamma \approx 3.42$ ,

protein reactions:  $\gamma \approx 2.89$ .

### 7.2 Barbási-Albert Model

B.A. model.

Start with m modes.

Grow:

• add node v,

- add m edges from v (to u),
- for each new edge:  $P(v \sim u) = \frac{degu}{\sum_{x} degx}$ .

#### Izrek 7.2.1.

B.A. model has scale free property, in particular

$$p_k = \frac{2m(m+1)}{k(k+1)(k+2)}$$

#### Definicija 7.2.2.

 $p_n(k)$ : expected proportion of degree k vertices in graph with k vertices,  $p_k := \lim_{n \to \infty} p_n(k)$ .

#### Dokaz 7.2.3.

 $p_n(k) \cdot n$ : expected number of degree k vertices,

 $p_n(k)n \cdot \frac{k}{\sum_u degu} m = p_n(k) \cdot \frac{k}{2}$ : expected number of degree k vertices changing into degree k+1 vertices.

$$\sum_{u} degu = 2|E|$$

$$p_{n+1}(k) \cdot (n+1) = p_n(k) \cdot n - p_n(k) \cdot \frac{k}{2} + p_n(k-1) \cdot \frac{k-1}{2}$$
, where

$$p_n(k) \cdot n$$
: degree  $k \to k$ ,

$$p_n(k) \cdot \frac{k}{2} : k \to k+1,$$

$$p_n(k-1) \cdot \frac{k-1}{2} : k-1 \to k.$$

For n very big (very close to limit):

$$p_n \cdot (n+1) = p_k \cdot n - p_{k-1} \cdot \frac{k}{2} + p_{k-1} \cdot \frac{k-1}{2}$$
  
$$\implies p_k = \frac{k-1}{k+2} p_{k-1}.$$

For degree m:

$$(n+1) \cdot p_{n+1}(m) = p_n(m) \cdot n - p_n(m) \cdot \frac{m}{2} + 1$$

$$p_{m} = \frac{2}{m+2}$$

$$\implies p_{m+1} = \frac{2}{m+2} \cdot \frac{m}{m+3}$$

$$\implies p_{m+2} = \frac{2m(m+1)}{(m+2)(m+3)}$$

$$\implies p_{k} = \frac{2m(m+1)}{k(k+1)(k+2)}.$$

### Markov chains

 $\Omega$ : finite set (of states).

### Definicija 8.0.1 (Markov chain).

(Discrete time) Markov chain is a sequence of random variables  $X=X_0,X_1,X_2\dots$  with image  $\Omega$  and properties:

• 
$$P(X_{i+1} = x \mid X_i = x_i, X_{i-1} = x_{i-1} \dots X_0 = x_0) = P(X_{i+1} = x \mid X_i = x_i),$$

• 
$$PX_{i+1} = x \mid X_i = y = P(X_1 = x \mid X_0 = y)$$
 - time is homogenous.

Primer.

$$\Omega = \mathbb{Z}_5$$

$$P(X_{i+1} = x + 1 \mid X_i = x) = \frac{1}{2}$$

$$P(X_{i+1} = x - 1 \mid X_i = x) = \frac{1}{2}.$$

Definicija 8.0.2 (Transition matrix).

$$\Omega = \{x_1 \dots x_n\}$$
$$p_{ij} = P(X_{t+1} = j \mid X_t = i)$$

$$\begin{bmatrix} p_{11} & \dots & \\ p_{1n} & & \\ \vdots & & \vdots \\ p_{n1} & \dots & p_{nn} \end{bmatrix}$$

### Definicija 8.0.3 (Transition graph).

Edge between states i and j exists if  $p_{ij} > 0$ .

P is stochastic matrix:

$$p_{ij} \in [0,1]$$

$$\sum_{i} p_{ij} = 1.$$

We choose beginning state randomly.

$$q(0) = (q_1(0) \dots q_n(0))$$

$$P(X_0 = i) = q_i(0).$$

Let 
$$q(t) = (q_1(t) \dots q_n(t))$$

$$P(X_t = i) = q_i(t).$$

It holds: 
$$q(t) = q(t-1) \cdot P = q(0) \cdot P^t$$
.

To find 
$$q(t) = q(t-1) \cdot T = q(0)$$

$$\begin{bmatrix} 0 & \frac{1}{2} & 0 & 0 & \frac{1}{2} \\ \frac{1}{2} & 0 & \frac{1}{2} & 0 & 0 \\ 0 & \frac{1}{2} & 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{2} & 0 & \frac{1}{2} \\ \frac{1}{2} & 0 & 0 & 0 & \frac{1}{2} \end{bmatrix}$$

$$q(0) = (1, 0, 0, 0, 0)$$

$$q(1) = (1, \frac{1}{2}, 0, 0, \frac{1}{2})$$

$$q(2) = (\frac{1}{2}, 0, \frac{1}{4}, \frac{1}{4}, 0)$$
:

### Definicija 8.0.4.

- Distribution  $\pi$  is stationary if  $\pi = \pi \cdot P$ ,
- $f_{ij}$ : probability that  $X_t = x_j$  for some t assuming  $X_0 = x_i$ ,

- $h_{ij}$ : expected number of steps needed to get to state  $X_j$  strting in  $X_i$  (hitting time),
- N(i, t, q(0)): expected number of times we visit  $x_i$  after t steps starting with distribution q(0),
- $\forall f_{ij} > 0 \iff$  transition graph is strongly connected  $\iff$  we say the chain is irreducible,
- M.C. is aperiodic if there is no  $c \in \{2, 3, 4...\}$  such that all lengths of cycled are divisible by c.

#### Izrek 8.0.5.

Let X be finite irreducible M.C. Then:

- a) there exists unique stationary distribution  $\pi = (\pi_1 \dots \pi_n)$ ,
- b)  $f_{ii} = 1, h_{ii} = \frac{1}{\pi_i},$
- c)  $\lim_{t\to\infty} \frac{N(i,t,q(0))}{t} = \pi_i$  approaches  $\pi$  regardless of q(0),
- d) if X is aperiodic:  $\lim_{t\to\infty} q(0) \cdot P^t = \pi$ .

Primer. 
$$P = \begin{bmatrix} 0 & \frac{1}{2} & \dots & \frac{1}{2} \\ \frac{1}{2} & 0 & \dots & 0 \\ \vdots & & \vdots \\ \dots & \frac{1}{2} & 0 \end{bmatrix}$$

$$\pi = (\frac{1}{n} \dots \frac{1}{n})$$

$$h_{i,i} = n$$

$$n = h_{i,i} = 1 + \frac{1}{2}h_{i-1,i} + \frac{1}{2}h_{i+1,i}, \quad h_{i-1,i} = h_{i+1,i}$$

$$n - 1 = h_{i-1,i}$$

$$E(\text{steps around}) \le h_{0,1} + h_{1,2} + \dots + h_{n-1,n} \le n(n-1).$$

### 8.1 2-SAT

Recall: k-SAT:

$$F = C_1 \wedge \dots \wedge C_m$$
$$C_i = X_{i1} \vee \dots \vee X_{ik}.$$

3-SAT: NP complete.

```
Algorithm:
```

```
\begin{aligned} & \text{def rand2SAT(F):} \\ & b^0 = (b\_0^0 \dots b\_n^0) \\ & \text{for i in range(t):} \\ & \text{if F}(b^i) = 1: \\ & \text{return True} \\ & \text{Cl <- clause trat is False} \\ & \text{xj <- uniformly at random from xl1 and xl2} \\ & b^{i+1} = (b\_0^i \dots not \ b\_j^i \dots b\_n^i) \\ & \text{if F}(X^t) = 1: \\ & \text{return True} \\ & \text{return False} \end{aligned}
```

#### Izrek 8.1.1.

If  $k = 8n^2$ , then  $P(\text{rand2SAT} = \text{True} \mid \text{correct answer is True}) \ge \frac{3}{4}$ .

**Dokaz 8.1.2.** Let  $a = (a_1 \dots a_n)$  be a correct solution.

Let  $X_i = \text{Hamming distance from } b^i \text{ to } a$ .

Goal: bount  $h_{n,0}$ .

 $P(\text{distance of } b^{i+1} \text{ to } a \text{ is } j-1 \mid \text{distance of } b^i \text{ to } a \text{ is } j) \geq \frac{1}{2}.$ 

$$P = \begin{bmatrix} 0 & 1 & \dots & 0 \\ \frac{1}{2} & 0 & \dots & 0 \\ \vdots & & & \vdots \\ \dots & & 1 & 0 \end{bmatrix}$$

$$\begin{split} \pi &\stackrel{?}{=} \pi P \\ \pi &= \left(\frac{1}{2n}, \frac{1}{n} \dots \frac{1}{n}, \frac{1}{2n}\right) \\ \text{By theorem} \\ h_{i,i} &= \frac{1}{\pi_i} = n \text{ for } i = 1, 2 \dots n-1 \\ h_{0,0} &= h_{n,n} = 2n \\ n &= h_{i,i} = 1 + \frac{1}{2}h_{i+1,i} + \frac{1}{2}h_{i-1,i} \\ h_{i+1,i} &\leq 2n \\ i &= 0: \ 2n = h_{0,0} = 1 + h_{1,0} \implies h_{1,0} < 2n \\ h_{n,0} &\leq h_{n,n-1} + \dots + h_{1,0} \leq 2n^2 \\ E(\text{steps in algorithm to reach correct solution}) &= E(Z) \leq 2n^2 \\ P(\text{algorithm hasn't reached correct solution after } 8n^2 \text{ steps}) \\ &= P(Z > 8n^2) \stackrel{\text{Markov}}{\leq} \frac{E(Z)}{8n^2} \leq \frac{1}{4}. \end{split}$$

# 8.2 Generating a uniformly random element of a set

 $\Omega$ : set.

Let G be a symmetric graph on  $\Omega$ .

We form M.C:

$$P_{x,y} = \begin{cases} \frac{1}{M} & \text{if } x \neq y \land x \sim y \\ 0 & \text{if } x \neq y \land x \nsim y \\ 1 - \frac{|N(x)|}{M} & \text{if } x = y \end{cases}$$

 $M \ge \max_{v \in \Omega} |N(v)|.$ 

If G is connected  $\implies$  M.C. is irrecudible.

$$\pi = \left(\frac{1}{|\Omega|} \dots \frac{1}{|\Omega|}\right)$$
$$\pi \stackrel{?}{=} \pi P$$

$$(\pi P)_x = \sum_y \pi_y P_{y,x}$$

$$= \sum_{y \in N(x)} \frac{1}{M} \cdot \frac{1}{|\Omega|} + \frac{1}{|\Omega|} \left( 1 - \frac{|N(x)|}{M} \right) = \frac{1}{|\Omega|} = \pi_x.$$

 $\implies$  if we walk on the Markov chain long enough, we end up in state x with probability  $\pi_x = \frac{1}{|\Omega|}$ 

 $\implies$  we can sample uniformly.

Primer.

G graph, finding largest independent set  $(\forall u, v : u \nsim v)$  is NP-complete.

Lets try sampling a uniformly random independent set

 $\Omega = \{\text{independent sets}\}\$ 

$$u \sim v \text{ if } |u \triangle v| = 1 \ ((u \cup \{el\}) = v)$$

M.C.:  $X_0$  = arbitrary independent set

 $X_{i+1}$ :

- pick uniformly at random  $v \in V(G)$ ,
- if  $v \in U$  then  $X_{i+1} = U \setminus \{v\}$ ,
- if  $U \cup \{v\}$  is independent then  $X_{i+1} = U \cup \{v\}$ ,
- else  $X_{i+1} = U$ .

M is number of vertices

$$\implies \forall u \in \Omega : \lim_{t \to \infty} P(X_t = u) = \frac{1}{|\Omega|}.$$

Note: irredudicle;  $U \to \emptyset \to V$ , aperiodic.

## 8.3 Metropolis algorithm

 $\Omega$ : set,

 $\pi$ : chosen distribution on  $\Omega$ .

Make G graph on  $\Omega$ 

$$P_{x,y} = \begin{cases} \frac{1}{M} \cdot \min\left(1, \frac{\pi_y}{\pi_x}\right) & \text{if } x \neq y \land x \sim y \\ 0 & \text{if } x \neq y \land x \nsim y \\ 1 - \sum_{y \in N(x)} & \text{if } x = y \end{cases}$$

$$M \ge \max_{v \in \Omega} |N(v)|$$

$$\pi \stackrel{?}{=} \pi P$$

$$(\pi P)_x = \sum_y \pi_y P_{y,x} = \sum_{y \in N(x)} \pi_y \frac{1}{M} \min\left(\left(1, \frac{\pi_y}{\pi_x}\right)\right) + \pi_x \left(1 - \sum_{y \in N(x)} \frac{1}{M} \min\left(1, \frac{\pi_y}{\pi_x}\right)\right)$$

$$= \sum_{y \in N(x), \pi_y \ge \pi_x} \pi_y \frac{1}{M} \cdot 1 + \sum_{y \in N(x), \pi_y < \pi_x} \pi_y \frac{1}{M} \frac{\pi_y}{\pi_x} + \pi_x$$

$$- \sum_{y \in N(x), \pi_y \ge \pi_x} \pi_x \frac{1}{M} \frac{\pi_y}{\pi_x} - \sum_{y \in N(x), \pi_y < \pi_x} \frac{1}{M} \cdot 1$$

$$= \pi_x.$$

Primer.

$$\Omega = \mathbb{Z} \cap [-1000,1000]$$

$$\pi \sim e^{-\frac{(x-\mu)^2}{2\delta}}$$

$$X_0$$
 arbitrary for i = in range(1,m): 
$$y \leftarrow \text{uniformly from } X_i + 1, X_i - 1$$
 
$$M \leftarrow \text{uniformly from } [0,1]$$
 if  $M \leq \frac{\pi(y)}{\pi(x)}$ : 
$$X_{i+1} = y$$
 else: 
$$X_{i+1} = X_i$$
 return  $X_m$ 

Primer.

Find maximum of a positive function f.

Use metropolis algorithm to sample proportional to f.

Note: all I need to know is ratios  $\frac{f(y)}{f(x)}$ .

Back to independent sets.

$$G = (V, E)$$

 $\Omega = \text{independent sets.}$ 

$$\lambda \in (1, \infty)$$

$$\pi(u) \sim \lambda^{|u|}$$

$$\pi(u) = \frac{\lambda^{|u|}}{\sum_{v \text{ independent set } \lambda^{|v|}}.$$

How to calculate the sum?

No problem: only need proportions.

 $X_0$ : arbitrary independent set.

$$X_i \to X_{i+1}$$
:

- we pick  $v \in V$  uniformly at random,
- if  $v \in X_i \implies$ 
  - $X_{i+1} = X_i \setminus \{v\}$  qith probability  $\frac{1}{\lambda} = \min\{1, \frac{\pi_y}{\pi_x}\},$
  - $-X_{i+1} = X_i$  with probability  $1 \frac{1}{\lambda}$ ,
- if  $v \in X_j$  and  $X_i \cup \{v\}$  is independent  $\implies X_{i+1} = X_i \cup \{v\},\$
- otherwise  $X_{i+1} = X_i$ .

Primer. Bayes:  $P(A \mid B) = \frac{P(A \cap B)}{P(B)} = \frac{P(B \mid A)P(A)}{P(B)}$ .

 $B \leftarrow \text{machine is giving values, e.g. } y_1 = 0.05, y_2 = -0.1, y_3 = 0.07, y_4 = 3.$ 

We believe  $B \sim N(\mu, 0.05)$ .

 $\mu = laplacian(0, 0.01).$ 

$$P(\mu \mid B) = \frac{e^{\frac{|\mu|}{0.01}} e^{-\sum \frac{(x_i - \mu)^2}{0.05}}}{\int \dots}.$$

Integral is difficult to calculate.

Sample  $\mu$  with Metropolis algorithm.

## 8.4 M.C. for 1-factor in bipartite graphs

G regular graph

|A| = |B|.

How to find 1-factor?

Augmenting paths.

Let M be (suboptimal) matching.

If we find s - t path, we switch edges and get bigger matching.

Starting point.

G d-regular graph.

Graph  $G = (A \cup B, E)$ , M suboptimal matching.

- Add s and add directed edges to vertices in A that are not matched with weight d,
- add t and add directed edges to vertices in B that are not matched with weight d,
- orient edges in M from B to A that weight d-1,
- orient edges in  $E \setminus M$  from B to A that weight 1,
- we add edge from t to s that weight (|A| |M|)d.

## Observation:

- for each vertex x:  $deg^{-}(x) = deg^{+}(x)$  (out weights = in weights),
- if |A| > |M|, then graph is eulerian  $\implies$  there is an augmenting path.

How to find s - t path?

Do a random walk.

Expected time to get from s to t is  $h_{s,t}$ 

$$\frac{1}{\pi(s)} = h_{s,s} = h_{s,t} + 1.$$

#### Lema 8.4.1.

Let X be a M.C. defined as a random walk on directed (weighted) graph with  $deg^{-}(x) = deg^{+}(x)$  for each x. Then the stationary distribution is

$$\pi = \left[\frac{deg^+(x_i)}{|E|}\right]_{i=1}^n.$$

 $w_{ij}$ : weight from i to j.

## Dokaz 8.4.2.

$$\pi P = \pi \left[ \frac{w_{ij}}{\deg^+(x_i)} \right]_{i,j=1}^n = \left[ \frac{\sum_j w_j i}{|E|} \right]_{i=1}^n = \left[ \frac{\deg^-(x_i)}{|E|} \right]_{i=1}^n = \left[ \frac{\deg^+(x_i)}{|E|} \right]_{i=1}^n.$$

$$\begin{array}{l} h_{s,s} = \frac{1}{\pi_s} \leq \frac{|E|}{deg^+(s)} \leq \frac{3(|A|-|M|)d+|M|(d-1)+(|A|-|M|)d+|M|(d-1)}{(|A|-|M|)d} \leq \frac{4|A|}{|A|-|M|}. \\ \text{Expected time to find augmenting path} \leq \frac{4|A|}{|A|-|M|}. \end{array}$$

$$|A| = n$$

Expected time to find 1-factor  $\leq \frac{4n}{n-1} = 4n \sum_{i=1}^{n-1} \frac{1}{i} \leq 4n(1+\ln n)$  - in  $O(n \log n)$ .

#### 8.4.1 Network centrality

Degree as measure - natural idea.

Use M.C: walk randomly on the network, those that are visited more oftenly are more important.

Pagerank.

Let A be the adjacency matrix of G.

$$P_{ij} = \alpha \frac{A_{ij}}{degi} + (1 - \alpha) \frac{1}{n};$$

 $\alpha$ : normal random walk,

 $1 - \alpha$ : jump to any.

 $\alpha = 0.85$ .

## Poglavje 9

# Randomized incremented constructions (RIC)

```
Observation:
Let S be a set of n distinct elements.
Let X_1 \dots X_n be a random permutation of the elements.
Let S_i = \{X_1 \dots X_i\}.
P(X_i = \min(S_i)) = \frac{1}{i}.
Y = |\{j \in \{1 \dots n\} \mid j = \text{ minimal of } S_j\}|
Y = Y_1 + \dots + Y_n
Y_j = \begin{cases} 1 & \text{if } i = \min S_i \\ 0 & \text{otherwise} \end{cases}
E(Y) = \sum_{i=1}^{n} E(Y_i) = \sum_{i=1}^{n} \frac{1}{i} in O(\log n).
   Alg():
      X1 ... Xn = random permutation of S
      min = X1
      for i in range(1,n+1):
         if Xi < min:
            print("HA")
            min = Xi
```

```
We get O(\log n) "HA" printed.

Incremental construction (IC).

Input S = \{s_1 \dots s_n\}.

We will build structures DS(S_i):

DS(S_1 \to \dots \to DS(S_n)).

DS(S_n) will help us give answer.

Randomized: permute S at the beginning.
```

## 9.1 Quicksort as RIC

```
S: set of elements we want to order. X_1 \dots X_n: random permutation of S. S_i = \{X_1 \dots X_i\}. S_i splits \mathbb{R}. Define DS(S_i):
```

- save intervals: each interval will be saved by endpoints,
- for each interval we will be saving its points,
- for each  $X_j$ , j > i we will save in which interval it is,
- for each left point of the interval we will save the right point.

```
QuicksortRIC(S):

# start of DS(Si)

I=[(-\infty,\infty)]

P[(-\infty,\infty)] = S

for each Xi:

Int(Xi) = (-\infty,\infty)

Next(\infty) = \infty

# end of DS(Si)

for i in range(1,n+1):

Ii = Int(Xi) = (Xj,Xk)
```

$$\label{eq:continuous_section} \begin{split} &\text{Ii1 = (Xj,Xi)} \\ &\text{Ii2 = (Xi,Xk)} \\ &\text{for Xl} \neq \text{Xi, Xi} \in \text{P(I):} \\ &\text{add Xl to P(Ii1) or P(Ii2) depending on Xl < Xi or Xl > Xi} \\ &\text{Next(Xj) = Xi} \\ &\text{Next(Xi) = Xk} \\ &\text{return [Next(-\infty), Next(Next(-\infty)) ..]} \end{split}$$

Similarity to quicksort: spliting intervals.

Analysis:

for set 
$$i$$
, we need  $O(|P(I_i)|)$ , 
$$E(|P(I_i)|) = ?$$
 e.g. if  $x_4 = a_4$ : if  $x_4 = a_2$ : 
$$P(X_i = a_j) = \frac{1}{i} \ j \in \{1, 2 \dots i\}.$$
 Expected value of steps in iteration  $i$  
$$\sum_{j=1}^{i} \frac{1}{i} \left(P\left((a_{j-1}, a_j)\right) + P\left((a_j, a_{j+1})\right)\right) \le \frac{1}{i} 2(n-i) \le \frac{2n}{i}$$

$$E \text{ (number of steps in QuicksortRIC)} \leq \sum_{i=1}^n \frac{2n}{i}$$
 
$$\leq 2n(1+\log n) \quad \to \text{ in } O(n\log n).$$

 $a_{n1}x_1 + \dots + a_{nd}x_d \le b_n.$ 

## 9.2 Linear programming

Task: maximize  $f(x_1 \dots x_n) = c_1 x_1 + \dots + c_d x_d$ . Constraints:  $a_{11} x_1 + \dots + a_{1d} x_d \le b_1$  $\vdots$  Geometric interpretation.

## Cases:

- infeasible region
- unbounded
- •

## Alg:

- symplex algorithm worst case  $O(2^n)$ ,
- interior point method (polynomial algorithm).

## Seidel's algorithm:

running in expected O(n) time when d is constant. One dimension.

$$\max cx$$

$$a_1x \le b_1$$

$$\vdots$$

$$a_nx \le b_n,$$

where n is number of constraints.

- $a_i$  positive:  $(-\infty, \frac{b_i}{a_i}],$
- $a_i$  negative:  $\left[\frac{b_i}{a_i}, \infty\right)$ .

 $a_i \neq 0$ .

Alg:

$$R = \min_{i} \{ \frac{b_{i}}{a_{i}}; a_{i} > 0 \},$$

$$L = \max_{i} \{ \frac{b_{i}}{a_{i}}; a_{i} < 0 \},$$

if L > R: program infeasible,

else:

if c > 0: return R,

if c < 0: return L.

2-dim: assume general position.

$$\max c_1 x + c_2 y$$

$$a_{11}x + a_{12}y \le b_1$$

$$\vdots$$

$$a_{n1}x + a_{n2}y \le b_n$$

$$x \le M \text{ or } x \ge -M$$

$$y \le M \text{ or } y \ge -M.$$

 $\leq, \geq$  depending on  $c_1, c_2$ .

Notation:

 $h_i$ : halfspace defined by  $a_{i1}x + a_{i2}y \leq b_i$ ,

 $m_i$ : added halfspaces,

 $l_i$ : line that bounds.

Alg:

- first randomly permute  $h_i$ ,
- $H_i = \{m_1, m_2, h_1 \dots h_i\},\$
- $v_i \in \cap H_i$  optimal solution after i constraints,
- $v_0 = (\pm M, \pm M),$
- inductively add  $h_i$ .

Cases:

if 
$$v_{i-1} \in h_i \implies v_i = v_{i-1}$$
,  
if  $v_{i-1} \notin h_i \implies v_i \in h_i$ :

$$a_{i1}x + a_{i2}y = b_i$$
  
 $a_{i1}$  or  $a_{i2} \neq 0$ , e.g.  $a_{i1}$ ;  
 $x = \frac{b_i - a_{i2}y}{a_{i1}}$ .

Insert x in all constraints  $\implies$  linear program in 1-dim, i (i-1?) constraints  $\implies$  get  $v_i$  in O(i).

Analysis:

- worst case:  $\sum_{i=1}^{n} O(i) = O(n^2)$ ,
- expected:  $E(X) = \sum_{i=1}^{n} E(X_i)$ ,
- $X_i$  = running time of *i*-th iteration,

• 
$$X_i = \begin{cases} O(1); \text{ case } 1\\ O(i); \text{ case } 2 \end{cases}$$

- $P(\text{case }2) \leq \frac{2}{i}$  optimal point on at most 2 lines,
- $E(X) \le \sum_{i=1}^{n} O(1) \cdot 1 + O(i) \cdot \frac{2}{i} = O(n).$

d-dim

- constraints define half-spaces,
- boundary is hyperplane (d-1 dimensional),
- general position: intersection of d-i hyperplanes is i dimensional, intersection of d+1 hyperplanes is  $\emptyset$ .

Alg:

first add  $X_i \leq M$  or  $X_i \geq -M$  depending on  $c_i$ , random permutation  $(h_1 \dots h_n)$ ,  $H_i = \{m_1 \dots m_d, h_1 \dots h_i\},$   $v_0 \in \cap \partial m_i,$  inductively add  $h_i$ :

$$v_{i-1} \in h_i \implies v_i = v_{i-1},$$

 $v_{i-1} \notin h_i \implies$  we need to solve LP in d-1 dimensions with i constraints (O(i) expected),

$$P(v_{i-1} \notin h_i) \le \frac{d}{i},$$

$$E(X) \le \sum_{i=1}^{n} O(1) + \frac{d}{i}O(i) = O(n).$$

X: running time.

Careful implementation runs in  $O(d! n) \implies \text{very useful for low dimensions.}$ 

Problem: let P be convex polygon given by ordered set of vertices

$$y = a_i x + b_i.$$

Find largest disc embeddable in P.

Input:  $P_1 \dots P_n$ ,

output:  $(s_1, s_2), r$ .

 $\max r$ 

$$\begin{split} d &= \left| \frac{s_2 - a_i s_1 - b_i}{\sqrt{a_i^2 + 1}} \right| \\ \frac{s_2 - a_i s_1 - b_i}{\sqrt{a_i^2 + 1}} &\geq r \text{ - line above } P \\ - \frac{s_2 - a_i s_1 - b_i}{\sqrt{a_i^2 + 1}} &\leq -r \text{ - line below } P \end{split}$$

 $\implies$  LP in 3 dim.

Note:  $\frac{s_2 - a_i s_1 - b_i}{\sqrt{a_i^2 + 1}}$  positive if  $(s_1, s_2)$  above the line, negative otherwise.

# Poglavje 10

# Hashing

A hash function is a randon function,

$$h: U \to \{0, 1 \dots n - 1\} = M,$$

U - universe,

$$u = |U|,$$

$$m = |M|$$
.

Ideally we would like for h to be as completely rondom:  $P(h(x) = t) = \frac{1}{m}$ . Standard application.

Let 
$$V \subset U$$
,  $|V| << |U|$ .

We would like to quickly answer if  $x \in V$  for ever  $x \in V$ .

Solution:

- take  $h: U \to M$ ,
- make a table  $T = [0, 1 \dots n-1],$
- for  $v \in V$ :

$$T[h(v)] = 1,$$

$$T[y] = 0 \ \forall y \in h(V).$$

• Let  $x \in V$ . Check

$$- \text{ if } T[h(x)] = 1: \ x \in V,$$
 
$$- \text{ else: } x \notin V.$$

Note: this is not OK: h not injective.

For  $x \in U$ , tell if  $x \in V$  in O(1).  $h = SHA256 : U \rightarrow \{0, 1\}^{256}$ . Approach:

- design a family of hash functions,
- study collisions  $P_h(h(x) = h(y)),$
- *H* meeds to be "simple".

Bad example: H = all functions from U to M storing  $h \in H$  would take  $|U| \log_2 |M|$  bits.

**Definicija 10.0.1.** A family of hash functions to be universal if for  $\forall x, y \in U, x \neq y, h \in H: P(h(x) = h(y)) \leq \frac{1}{m}$  (probability of collision).

k-independent if  $\forall x_1 \dots x_k \in U$  pairwise different,  $\forall t_1 \dots t_k \in M$   $P_r(h(x_i) = t_i \ \forall i) \leq \frac{1}{m^k}$ .

Primer.

$$U = \{0, 1, 2, 3\},\$$

$$M = \{0, 1\},\$$

$$H = \{h_0, h_1, h_2\},\$$

$$h_0 : \{0 \to 0, 1 \to 0, 2 \to 1, 3 \to 1\},\$$

$$h_1 : \{0 \to 0, 1 \to 1, 2 \to 0, 3 \to 1\},\$$

$$h_2 : \{0 \to 0, 1 \to 1, 2 \to 1, 3 \to 0\}.$$

$$P(h(0) = h(2)) = \frac{2}{3} < \frac{1}{2} - \text{not universal.}$$

Why universal?

H universal:  $\forall x, y: P(h(x) = h(y)) \leq \frac{1}{m}$ .

X: number of collisions of V.

$$E(X) = E\left(\sum_{x,y \in V, x \neq y} X_{x,y}\right)$$

$$X_{x,y} = \begin{cases} 1 \text{ if } h(x) = h(y) \\ 0 \text{ else} \end{cases}$$

$$E(X) = \sum_{x,y \in V, x \neq y} E(X_{x,y}) \le \binom{n}{2} \cdot \frac{1}{n}.$$

$$U, V, M, H$$

$$T[0 \dots m-1]$$

 $\forall v \in V$ 

T[h(v)] = v.

For  $x \in V$  we check T[h(x)] if equals x,

for  $y \in U \setminus V$ ,  $T[h(y)] \neq y$ .

For  $z \in V$ , T[h(z)] can happen  $\neq z$  if h has collisions in V.

**Lema 10.0.2.** Let  $m \geq n^2$  and H universal. Then the probability that h has no collisions in  $V \geq \frac{1}{2}$ .

### Dokaz 10.0.3.

X: number of collisions

$$\begin{split} E(X) &\leq \binom{n}{2} \cdot \frac{1}{m} < \frac{n^2}{2} \cdot \frac{1}{n^2} = \frac{1}{2} \\ P(X \geq 1) &\leq \frac{E(X)}{1} = \frac{1}{2} \\ P(X = 0) &\geq \frac{1}{2}. \end{split}$$

Primer (Universal hash family).

$$U = \{0, 1 \dots u - 1\}$$
 (bits  $\equiv$  numbers)

$$M = \{0, 1 \dots m - 1\}.$$

Define: let  $p \ge u$ , p prime number.

Define for  $a, b \in \mathbb{Z}_p$ ,  $a \neq 0$ .

$$h_{a,b} = (ax + b) \mod m$$

$$ax + b \in \mathbb{Z}_p$$

$$H = \{ h_{a,b} \mid a, b \in \mathbb{Z}_p, \ a \neq 0 \}.$$

**Dokaz 10.0.4.** 
$$P(h_{a,b}(x) = h_{a,b}(y)) = ?$$

x, y fixed.

For any a, b denote

$$ax + b = t_x$$

$$ay + b = t_y :$$

$$a \sqcup +b \in \mathbb{Z}_p.$$

$$\begin{bmatrix} x & 1 \\ y & 1 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} t_x \\ t_y \end{bmatrix}$$

$$\det \begin{bmatrix} x & 1 \\ y & 1 \end{bmatrix} \neq 0, \text{ because } x \neq y$$

$$\begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} x & 1 \\ y & 1 \end{bmatrix}^{-1} \begin{bmatrix} t_x \\ t_y \end{bmatrix}.$$
For each  $t_x, t_y$  there exists 1  $a, b$ 

For each  $t_x$ ,  $t_y$  there exists 1 a, b mapping to  $t_x$ ,  $t_y$ .

$$h_{a,b}(x) = h_{a,b}(y) \iff t_x = t_y \mod m.$$

This holds for 
$$p\left(\lceil \frac{p}{m} \rceil + 1\right)$$

p: choise of  $t_y$ 

$$t_x = t_y + km$$

$$P(h_{a,b}(x) = h_{a,b}(y)) \le \frac{p(\lceil \frac{p}{m} \rceil - 1)}{p(p-1)} \le \frac{\frac{p-1}{m}}{p-1} = \frac{1}{m}.$$

Function random for 2 elements, fixed for  $\geq 3$ .

Higher k-independent: better.

#### Chaining 10.1

 $V, U, h: U \rightarrow V$ .

Answer  $x \in V$  in O(1).

$$T[0 \dots m-1]$$

$$n = |V|$$

 $\forall v \in V$ :

$$h(v_1) = h(v_2) \rightarrow [v_1 \ v_2 \dots]$$
 - linked list.

Now:

 $x \in U$ .

Check if x is in list at T[h(x)].

Check takes O(length of a list at h(x)) = 1 + number of collisions with x.

 $X_x$ : number of collisions with x.

 $E(X_x) = \sum_{y \in V} E(X_{x,y}) \le n \cdot \frac{1}{m}$  if hash function is universal.  $\alpha = \frac{n}{m}$ : load factory (how many elements in 1 place).  $E(X_x) = 1$  $E(\max_x X_x) \ne \max_x E(X_x) = 1$ .

**Izrek 10.1.1.** Assume we throw n balls into n bins uniformly at random. Then with high probability the fullest contains  $\theta\left(\frac{\log n}{\log(\log n)}\right)$  balls.

## Dokaz 10.1.2.

$$\stackrel{?}{\leq} \frac{3 \ln n}{\ln \ln n}.$$

Let  $X_j$  be the number of balls in bin j.

 $P\left(X_j \ge \frac{3\ln n}{\ln \ln n}\right) = P(\text{ there exists subset } S \text{ of balls thrown to } \sin j).$ |S| = k

$$\begin{split} &P\left(\cup_{S \text{ balls},|S|=k} \text{balls from } S \text{ are thrown to bin } j\right) \\ &\leq \sum_{S \text{ balls},|S|=k} P(\text{balls from } S \text{ are thrown to } j) \\ &= \binom{n}{k} \left(\frac{1}{n}\right)^k \\ &\leq \frac{n^k}{k!} \cdot \frac{1}{n^k} = \frac{1}{k!} = (*). \end{split}$$

Note:  $e^x = \sum_{i=1}^{\infty} \frac{k^i}{i!} \ge \frac{k^k}{k!}$ .

$$(*) \leq \frac{e^k}{k^k}$$

$$= \left(\frac{e \ln n}{3 \ln \ln n}\right)^{\frac{3 \ln n}{\ln \ln n}}$$

$$\leq e^{\frac{3 \ln n}{\ln \ln n} \cdot (\ln \ln \ln n - \ln \ln n)}$$

$$= e^{-3 \ln n + \frac{\ln \ln \ln n \cdot (\ln n \cdot 3)}{\ln \ln n}} = (**)$$

$$\frac{\ln \ln \ln n}{\ln \ln n} \to 0$$

$$(**) \le e^{-3\ln n + \ln n} = \frac{1}{n^2}.$$

 $P(\text{at least for 1 bin } j \ge k) = n \cdot \frac{1}{n^2} = \frac{1}{n}.$ 

U, V, H hash family,  $h: U \to M$ 

 $v \in V$ 

n = |V|

max load  $O\left(\frac{\log n}{\log(\log n)}\right)$ .

Perfect hashing: we would like

- O(1) lookup (worst case)
- O(n) size of table.

#### 10.22 level hashing

Input: V

n = |V|.

Take hash function from universal family with m = |M| = n.

Count total collisions X.

$$\begin{split} E(X) &\leq \binom{n}{2} \cdot \frac{1}{m} \leq \frac{n}{2} \\ P(x \geq n) &\leq \frac{1}{2} \end{split}$$

$$P(x \ge n) \stackrel{\text{Markov}}{\le} \frac{1}{2}$$

 $\implies$  by repeating sample h we can guarantee

- for each  $i \in M$  we store at T[i] another hash table of size  $C_i^2$ , where  $C_i$  = number of elements of V, hashed in i,
- we sample  $h_i$  from universal hash family with  $M_i = C_i^2$ .

 $P(h_i \text{ has no collisions}) \ge \frac{1}{2} \text{ (by lemma)}.$ 

We resample if  $h_i$  has collisions.

 $E(\text{sampling } h_i) = 2.$ 

Construction time:

- step 1: O(n)
- step 2:  $O(C_1 + \cdots + C_n) = O(n)$ ;

together O(n).

Lookup time: O(1) (evaluating h(x) and  $h_{h(x)}(x)$ ).

Space:  $O(C_1^2 + \cdots + C_n^2)$  in O(n).

By first step  $n > \text{number of collisions of } h = \sum_{i=1}^{n} {C_i \choose 2} = \sum_{i=1}^{n} \frac{C_i^2 - C_i}{2}$ 

 $\implies \sum_{i=1}^{n} C_i^2 < 2n + \sum_{i=1}^{n} c_i = 3n.$ 

## 10.3 The power of 2 choices

Variant: placing n balls in n bins but for each ball we choose d balls uniformly at random and put the ball in bin with minimal load.

**Izrek 10.3.1.** The above process with  $d \geq 2$  results in at most maximum load of  $O\left(\frac{\ln(\ln n)}{\ln d}\right)$ .

**Dokaz 10.3.2.** (sketch).

 $b_i$  = upper bound of the number of bins with load at most i.

Height of a ball = the number of balls in the bin, where the ball is placed.

 $P(\text{a ball has height at least } i+1) \leq \left(\frac{b_i}{n}\right)^d$  (choose d times independently).

 $X^{i+1}$ : number of balls with height  $\geq i+1$ .

$$X^{i+1} = \sum_{j=1}^{n} X_j^{i+1}$$

 $X_i^{i+1}$ : indicator variable of j-th ball having height i+1.

$$E(X^{i+1}) \le \sum_{j=1}^{n} \left(\frac{b_i}{n}\right)^d = d \cdot \left(\frac{b_i}{n}\right)^d.$$

Chernoff bound: with high probability  $X^{i+1} \leq 2n \left(\frac{b_i}{n}\right)^d$ .

 $X^{i+1} \ge \text{number of bins with load at least } i+1.$ 

Define (set)

$$b_{i+1} = \frac{\sum b_i^d}{n^{d-1}}$$

$$b_4 = \frac{n}{4}$$

$$b_{i+4} = \frac{n}{2^{2 \cdot d^i - \sum_{j=0}^{i-1} d^j}}$$

$$i = 0$$
:  $b_4 = \frac{n}{2^{2^1}} = \frac{n}{4}$ 

$$i \rightarrow i + 1$$
:

$$\begin{split} b_{i+4} &= \frac{2 \cdot b_{i+3}}{n^{d-1}} \\ &\stackrel{IH}{=} \frac{2 \cdot \left(\frac{n}{2^{2 \cdot d^i - \sum_{j=0}^{i-1} d^j}}\right)^d}{n^{d-1}} \\ &= \frac{2^1 \cdot n^d}{n^{d-1} \cdot 2^{2 \cdot d^{i+1} - \sum_{j=1}^{i} d^j}} \\ &= \frac{n}{2^{2 \cdot d^{i+1} - \sum_{j=0}^{i} d^j}}. \end{split}$$

In particular:  $b_{i+4} \leq \frac{n}{2^{d^i}} < 1$  when?

$$n < 2^{d^{i}}$$
$$\log_{2} n < d^{i}$$
$$\log_{d} \log_{2} n < i$$

$$\implies$$
 for  $i = \frac{\log(\log_2 n)}{\log d}$  is  $b_i < 1 \implies$  no bins with load  $> \frac{\log(\log_2 n)}{\log d}$ .

Application:

We sample 2 hash functions  $h_1, h_2: U \to M$ .

For element  $v \in V$  we insert in  $T[h_1(v)]$  or  $T[h_2(v)]$  depending on which list is shorter.

Max load in  $O(\log(\log n))$ .

## 10.4 Cockoo hashing

Idea: use 2 hash functions but allow moving elements later.

We want to have at most 1 element at each entry in the table.

Inserting:

- if empty: insert,
- if not empty: push other element to its other choise, repeat recursively.

## Questions:

- how many do I need to move,
- how many elements can I insert before problems?

We can think of positions in the table as vertices and elements of V as edges. |V| edges are inserted uniformly at random (if ideal hash function)  $\implies$  random graph.

Erdös-reny model:  $G_{n,m} \approx G_{n,p}$  if  $m = \binom{n}{2} p$  (A.S. properties).

If  $np < 1 - \epsilon$ : all connected components have size at most  $O(\log n)$ , components are trees or at most 1 cycle per component, expected size of a component is O(1).

Fact: if graph has at most 1 cycle per component, then inserting can be done and takes at most  $2 \cdot (\text{size of component})$  time (each edge changes direction at most 2 times).

#### Izrek 10.4.1.

Let n = |U|,  $h_1, h_2 : U \to M$ ,  $m = |M| = 2 \cdot (1 + \epsilon) \cdot n$ , then with high probability cockoo hashing works correctly with

- inserting time:
  - $-O(\log n)$  time worst case,
  - -O(1) expected case,
- space: O(n),
- lookup time: O(1).

Dynamically add element:

$$\begin{split} m &= 2 \cdot (1 + \epsilon) \cdot n \\ p &= \frac{m'}{\binom{n'}{2}} = \frac{2m'}{n'(n'-1)} \\ pn' &= \frac{2m'}{(n'-1)} = \frac{2n'}{2(1+\epsilon)n'} = \frac{1}{1+\epsilon} < 1 + \epsilon' \end{split}$$

#### 10.5Bloom filter

Take k hash functions  $h_1 \dots h_k$  at random,  $h_i : U \to M, T[0 \dots m-1]$ .

$$V \subset U$$
, for every element  $v \in V$  set  $T[h_i(v)] = 1 \ \forall i \in \{1 \dots k\}$ .

False positives:  $x \notin V$  such that  $T[h_i(x)] = 1 \ \forall i \in \{1 \dots k\}.$ 

For each 
$$T[j] P(T[j] = 0) = \left( \left( 1 - \frac{1}{m} \right)^n \right)^k \approx e^{-\frac{nk}{m}};$$

k: each hash function, n: for each v.

Now

 $P(T[h_i(x)] = 1 \ \forall i, \forall x \notin V) \approx \left(1 - e^{-\frac{nk}{m}}\right)^k = f(k)$  - probability of a false positive.

$$\left(1-e^{-\frac{nk}{m}}\right)$$
: 1 position.

Searching for a minimum:

$$f'(k) = 0$$

$$\implies k = \ln 2 \cdot \frac{m}{n}$$

$$\implies k = \ln 2 \cdot \frac{m}{n}$$

$$f\left(\ln 2 \cdot \frac{m}{n}\right) = \left(\frac{1}{2}\right)^{\ln 2 \frac{m}{n}} \approx 0.6185^{\frac{m}{n}}$$

 $\implies$  we choose m such that  $0.6185^{\frac{m}{n}}$  small (in O(n))

$$\implies$$
 calculating  $k = \ln 2 \cdot \frac{m}{n}$ 

- $\implies$  hashing with space O(n)
- $\implies$  checking in O(1)
- $\implies$  probability of error small.

#### 10.6 Linear probing

$$V \subset U, h: U \to M, T[0 \dots m-1].$$

- Insert  $v \in V$ : check  $T[h(v)], T[h(v) + 1], T[h(v) + 1] \dots$  until finding empty space, then insert it.
- Check if  $x \in V$  by checking  $T[h(x)] \stackrel{?}{=} x, T[h(x) + 1] \stackrel{?}{=} x \dots$  until finding x or finding empty.

 $x \in U$ 

X: number of steps to check if  $x \in V$ .

$$E(X) = ?$$

Block of size  $2^l$  is bad if it has more than  $2^l \cdot \frac{2}{3}$  values.

Set 
$$\frac{n}{m} = \frac{1}{3}$$
.

Expected number of elements hashed in block of size  $2^l$  is  $\frac{1}{3} \cdot 2^l$ .

$$\begin{split} E(X) &= \sum_{i=0}^n P(X=i) \cdot i \\ &\leq \sum_{j=0}^{\log_2 n} P(2^{j-1} < X \le 2^j) \cdot 2^j \\ &\leq \sum_{j=0}^{\log_2 n} P(\text{block above } h(x) \text{ of size } 2^j \text{ is bad}) \cdot c \cdot 2^j. \end{split}$$

c: not aligned?

 $P(\text{block of size }2^j \text{ is bad}) = P(Y > \frac{2}{3} \cdot 2^j) = P(Y - \frac{1}{3} \cdot 2^j > \frac{1}{3} \cdot 2^j);$ 

Y: number of elements hashed to the block.

$$E(Y) = \frac{1}{3} \cdot 2^j$$

 $\begin{array}{l} E(Y) = \frac{1}{3} \cdot 2^j \\ E(X) \stackrel{\text{Chernoff}}{\leq} e^{-k \cdot 2^j}; \text{ Chernoff: sum of independent indicators.} \end{array}$ 

$$E(X) < O(1) \cdot \sum_{j=0}^{\log_2 n} 2^j \cdot e^{-k \cdot 2^j}$$
 in  $O(1)$ 

 $\implies$  checking in O(1).

Chernoff: if ideal hash function; 5 independent is enough.

# Poglavje 11

## Data streams

```
Stream of values
```

$$\sigma = a_1, a_2 \dots a_n$$

 $a_i$ : tokens

$$a_i \in [n]$$

m: length of stream (very large).

**Definicija 11.0.1.** 
$$f_i = |\{j \mid a_j = i\}|$$

We could be interested in

- number of different token,
- frequency of some token,
- frequent tokens:  $\{i \in [n] \mid f_i \ge \frac{m}{10}\}$
- moments:  $||f||^2 = \sum_{i \in [n]} f_i^2$
- :

We want to use memory in  $O(poly(\log n, \log m)) \ll O(n, n)$ .

Most problems cannot be solved precisely, hence we search for  $(\epsilon, \delta)$ -approximation. Algorithm A(G):

• initialitazion,

- incremental steps,
- finalization

using randomness (oblivious stream - it doesn't know which randomly, e.g. we can choose stream that "attacks algorithm").

## 11.1 Count min sketch

For a given  $i \in [n]$  (token) at the end of stream give  $f_i$ .  $A(\sigma, \epsilon, \delta)$ :

Init: 
$$k = \lceil \frac{2}{\epsilon} \rceil, t = \lceil \log_2 \left( \frac{1}{\delta} \right) \rceil.$$

We choose t hash functions  $h_1 ldots h_t : [n] o M = [k] = \{1 ldots k\}$  from a universal family H.

Let 
$$C[0 \dots t-1][0 \dots k-1]$$
 be 2-dim (hash) table,  $C[i][j] = 0 \ \forall i,j$ .

**Updates**:

for every token  $a_i \in \sigma$  we update C

for 
$$j = 0, 1 ... t - 1$$
  
 $C[i][h_i(a_j)] + = 1$ 

Output: we asked  $a \in [n]$ , return  $\overline{f_a} = \min_{0 \le j \le t-1} C[j][h_j(a)]$ ; min collitions.

#### Izrek 11.1.1.

For every  $a \in [n]$  it holds

$$f_a \le \overline{f_a} \le f_a + \epsilon m$$

with probability at least  $1 - \delta$ .

Notice: space needed  $O(t \cdot k \cdot \log m) = O\left(\frac{2}{\epsilon} \cdot \log_2\left(\frac{1}{\delta}\right) \log m\right)$ .

### Dokaz 11.1.2.

$$\forall i \in [t] : C[i][h_i(a)] \ge f_a \implies \overline{f_a} \ge f_a.$$

Fix a.

Let  $X_i = C[i][h_i(a)] - f_a$  excess of *i*-th count.

$$I_{x,y}^{i} = \begin{cases} 1: & \text{if } h_i(x) = h_i(y) \\ 0: & \text{else} \end{cases}$$

 $X_i = \sum_{y \in [n], y \neq a} I_{x,y}^i \cdot f_y.$ 

$$E(X_i) = \sum_{y \in [n], y \neq a} E(I_{x,y}^i) \cdot f_y$$

$$\stackrel{*}{\leq} \sum_{y \in [n], y \neq a} \frac{1}{k} \cdot f_y$$

$$\stackrel{*}{\leq} \frac{1}{n} \cdot m$$

$$\stackrel{**}{\leq} \frac{m}{2}$$

\*: hash function from universal family.

\*\*:  $P(X_i \ge \epsilon m) \stackrel{\text{Markov}}{\le} \frac{\epsilon m}{2\epsilon m} = \frac{1}{2} \text{ for fixed } i.$ 

$$P(\overline{f_a} - f_a \ge \epsilon m) \le P(X_i \ge \epsilon m \ \forall i)$$

$$\stackrel{\text{indep.}}{=} \left(\frac{1}{2}\right)^t \le \delta.$$

# 11.2 Estimating the number of distinct elements

We want  $d = |\{i \in [n], f(i) > 0\}|.$ 

Define for  $x \in \mathbb{N}$ :

 $zeros(x) = \max\{i \mid 2^i \text{ divides } i\}$ : number of zeros at the end in binary representation of x.

 $Alg(\sigma)$ :

Init:

- -h: random hash function from 2-independent family.
- # recall: [n]: all possible elements of  $\sigma$ .

$$-h: [n] \to [n]$$

$$-\text{ unlog? } n = 2^{n'}$$

$$-z = 0$$

Update:

$$a_i \in \sigma$$
  
if  $zeros(h(a_i)) \ge z$ :  
$$z = zeros(h(a_i))$$

Output:

$$\overline{d} = 2^{z + \frac{1}{2}}$$

Define 
$$\forall a \in [n], r \in \mathbb{N}$$

$$X_{r,a} = \begin{cases} 1 : & \text{if } zeros(h(a)) \ge r \\ 0 : & \text{else} \end{cases}$$

$$Y_r = \sum_{a \in \sigma} X_{r,a}$$
.

Let  $\overline{z}$  be z at the end of the algorithm:  $\overline{d} = 2^{\overline{z} + \frac{1}{2}}$ .

Notice:

$$Y_r > 0 \iff \overline{z} \ge r$$

$$Y_r = 0 \iff \overline{z} < r.$$

### Lema 11.2.1.

$$P(X_{r,a} = 1) = \frac{1}{2^r},$$
  
 $P(X_{r,a_1} = 1 \land X_{r,a_2} = 1) = \frac{1}{(2^r)^2}.$ 

## Dokaz 11.2.2.

$$P(X_{r,a} = 1) = P(zeros(h(a)) \ge r) = \frac{2^{n'-r}}{2^{n'}} = \frac{1}{2^r};$$
  
 $2^{n'}$ : all,  $2^{n'-r}$ : fixed.

$$P(X_{r,a_1} = 1 \land X_{r,a_2} = 1) \stackrel{h \text{ 2 indep.}}{=} P(X_{r,a_1} = 1) \cdot P(X_{r,a_2} = 1) = \frac{1}{(2^r)^2}.$$

$$P(\overline{d} \ge 3d)$$
 small?

$$E(Y_r) = \sum_{a \in \sigma} E(X_{a,r}) = \sum_{a \in \sigma} \frac{1}{2^r} = \frac{d}{2^r}$$

Let  $k \in \mathbb{N}$  be such that  $2^{k+\frac{1}{2}} \ge 3d > 2^{k-\frac{1}{2}}$ .

$$\begin{split} P(\overline{d} > 3d) &\leq P(2^{\overline{z} - \frac{1}{2}} > 2^{k - \frac{1}{2}}) \\ &= P(\overline{z} + \frac{1}{2} > k - \frac{1}{2}) \\ &= P(\overline{z} \geq k) \\ &\stackrel{\text{lemma}}{=} P(Y_k > 0) \\ &\stackrel{\subseteq}{=} P(Y_k \geq 1) \\ &\stackrel{\text{Markov}}{\leq} \frac{E(Y_k)}{1} = \frac{d}{2^k} \\ &\stackrel{k}{\leq} \frac{d \cdot 2^{\frac{1}{3}}}{3d} = \frac{\sqrt{2}}{3}. \end{split}$$

 $P(\overline{d} \leq \frac{d}{3})$  small?

Let  $l \in \mathbb{N}$  be such that  $2^{l-\frac{1}{2}} \leq \frac{d}{3} < 2^{l+\frac{1}{2}}$ .

$$\begin{split} P(\overline{d} < \frac{d}{3}) & \leq P(2^{\overline{z} + \frac{1}{2}} < 2^{l + \frac{1}{2}}) \\ & = P(\overline{z} + \frac{1}{2} < l + \frac{1}{2}) \\ & = P(\overline{z} \leq k) \\ & \stackrel{\text{lemma}}{=} P(Y_l = 0) \\ & = P(Y_l - \frac{d}{2^l} < -\frac{d}{2^l}) \\ & \leq P(|Y_l - \frac{d}{2^l}| \geq \frac{d}{2^l}) \\ & \stackrel{\text{Chebisev}}{\leq} \frac{Var(Y_l)}{\left(\frac{d}{2^l}\right)^2} \\ & \stackrel{l}{\leq} \frac{d \cdot 2^{\frac{1}{3}}}{3d} = \frac{\sqrt{2}}{3}; \end{split}$$

$$Var(Y_l) = Var\left(\sum_{a \in \sigma} X_{a,l}\right)$$

$$\stackrel{h \text{ 2-indep.}}{=} \sum_{a \in \sigma} Var(X_{a,l})$$

$$= \sum_{a \in \sigma} E(X_{a,l}^2) - E(X_{a,l})^2$$

$$\stackrel{E(X_{a,l}) \in \{0,1\}}{\leq} \sum_{a \in \sigma} E(X_{a,l})$$

$$= \frac{d}{2^l}.$$

$$P\left(\frac{d}{3} < \overline{d} < 3d\right) \ge 1 - \frac{2\sqrt{3}}{3}.$$

We use algorithm k-times, getting  $\overline{d_1} \dots \overline{d_k}$  (we need independent hash functions).

Define:  $\overline{d} = median(\overline{d_1} \dots \overline{d_k}).$ 

$$P(\overline{d} \ge 3d) = P(\text{at least} \lceil \frac{k}{2} \rceil \overline{d} - s \text{ are } \ge 3d)$$
  
=  $P(X \ge \frac{k}{2}) \le e^{-ck};$ 

c: some constant,

$$X = \sum_{i=1}^{k} X_i,$$

$$X_i = \begin{cases} 1 : & \text{if } \overline{d_i} \ge 3d \\ 0 : & \text{else} \end{cases}$$

$$P\left(\overline{d} \le \frac{d}{3}\right) = \dots$$

# Poglavje 12

## Interactive proofs

A protocol between P prover and V verifier for function f.

Both share x,

r: randomness used,

P, V: algorithms,

$$out(V, x, r, P) = \begin{cases} 1 : V \text{ agrees that } f(x) = y \\ 0 : \text{ else} \end{cases}.$$

Goal: minimal communication, minimal work for V.

Completeness:

for every  $x \in D$  (domain)

$$P(out(V, x, r, P) = 1) \ge 1 - \delta_c$$
 for some  $\delta_c \in [0, 1)$ .

Soundness:

for every x such that  $f(x) \neq y$ 

$$P(out(V, x, r, P') = 1) \le \delta$$
 for every  $P', \delta_s \in [0, 1)$ .

Computational soundness:

soundness, P' computationally bounded.

Zero-knowledge:

informal: verifier learns nothing behind the claim.

Primer.

Input: G graph,

$$f(G) = \begin{cases} 1 : & \text{if } G \text{ hamiltonian} \\ 0 : & \text{else} \end{cases}$$

$$G \to P \xrightarrow{m_1:(v_1...v_n)} V \leftarrow G,$$

V: verifies that  $m_1$  is hamiltonian cycle.

Proof: O(n).

Verifier com. O(n).

Primer.

Input: A, B matrices,

$$f(A,B) = A \cdot B,$$

$$(A,B) \to P \stackrel{C}{\to} P \leftarrow (A,B).$$

P: compute  $C = A \cdot B$ , send C,

V: check  $A(Bv_i) = Cv_i$  for random  $v_i$ .

Prover: matrix multiplication  $O(n^3)$   $(O(n^{\log_2(7)}))$ .

Verifier:  $O(n^2)$ .

Proof size:  $O(n^3)$  (possible to reduce is  $O(\log n)$ ).

Primer.

Input:  $(n, y) \in \mathbb{N}^2$ ,

$$f(n,y) = \begin{cases} 1 : & \text{if there exists } x \text{ such that } y = x^2 \pmod{n} \\ 1 : & \text{else} \end{cases}$$

quaroatic reducibility problem.

$$(n,y) \to P \to V \leftarrow (n,y).$$

P: sample  $r \in \mathbb{Z}_n$ ,  $s = r^2$ , send s,

V: sample  $b \in \{0, 1\}$ , send b,

P: if b = 0:  $m_2 = r$ , if b = 1:  $m_2 = r \cdot x$ , send  $m_2$ ,

V: accepts if  $m_2^2 = s \cdot y^b$ .

Completeness:

$$m_2^2 = s \cdot y^b$$

if 
$$b = 0$$
:

$$r^2 = m^2 = s \checkmark$$

if 
$$b=1$$
: 
$$m^2=sy$$
 
$$r^2x^2=sy\ \checkmark (r^2=s,x^2=y)$$

Soundness:

- 2 options for what prover does.
  - Send s such that there is no r that  $r^2 = s$ . Then with probability  $\frac{1}{2}$  is b = 0. Then prover needs to send  $m_2$  such that  $m_2^2 = s$  (impossible)  $\implies$  fail with probability at least  $\frac{1}{2}$ .
  - Send s such that  $r^2 = s$ . Then with probability  $\frac{1}{2}$  is b = 1.  $m_2^2 = sy = r^2y \implies y = (m_2r^{-1})^2 \implies \exists x : x^2 = y$ : contradiction  $\implies$  fail with probability at least  $\frac{1}{2}$ .

With zero-knowledge.

## 12.1 Sum-check protocol

Let  $g(x_1 \dots x_n)$  be multivariate polynomial of degree d over  $\mathbb{F}$ .

Let 
$$H_g = \sum_{b_1...b_n \in \{0,1\}} g(b_1...b_n)$$
.

P wants to convince V that  $c = H_q$ .

$$g \to P \to V \leftarrow g$$
.

P: sends c,

P: compute  $g_1(x) = \sum_{b_2...b_n \in \{0,1\}} g(x, b_2...b_n)$ , send  $g_1(x)$ ,

V: check  $g_1(0) + g_1(1) = c$ ,  $deg(g) \le d$ , sample  $r_1 \in \mathbb{F}$ , send  $r_1$ ,

for j = 2 ... n - 1:

P: compute  $g_j(x) = \sum_{b_{j+1}...b_n \in \{0,1\}} g(r_1...r_{j-1}, x, b_{j+1}...b_n)$ , send  $g_j(x)$ ,

V: checks  $g_j(0) + g_j(1) = g_{j-1}(r_{j-1}), deg(g_j) \le d$ , sample  $r_j \in \mathbb{F}$ , send  $r_j$ ,

P: compute  $g_n(x) = g(r_1 \dots r_{n-1}, x)$ , send  $g_n(x)$ ,

V: checks  $g_n(0) + g_n(1) = g_{n-1}(r_{n-1}), deg(g_n) \le d$ , for random  $r_n \in \mathbb{F}$  check  $g_n(r_n) = g(r_1 \dots r_n)$ .

Completeness:

 $\checkmark$  (sum, all possibilities).

Cost:

Prover:  $O(2^n)$ ,

verifier: evaluate  $g_i \, \forall i, g$  at one point,  $<< O(2^n)$ .

Communication:

 $deg(g_1) + \cdots + deg(g_{n-1}) + O(n)$  elements of  $\mathbb{F}$ .