```
import numpy as np
import cv2
import matplotlib.pyplot as plt

image = cv2.imread('sar_1 (1).jpg')
image_gray = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)

plt.imshow(image_gray, cmap="gray")

<matplotlib.image.AxesImage at 0x1e786d8>
```



```
import math
def homo_average(img, mask, point, T):
    av_val = img[mask > 0].sum() / np.count_nonzero(img[mask > 0])

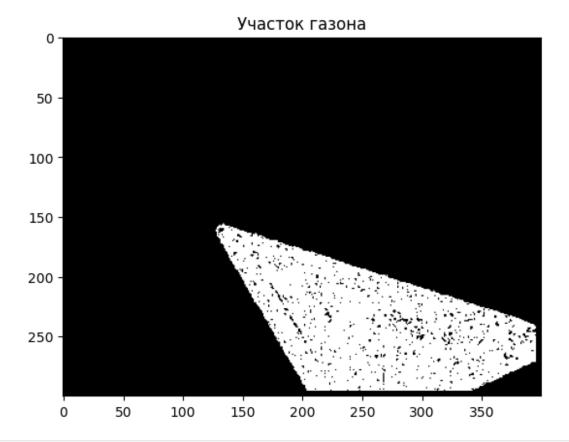
if abs(av_val - img[point]) <= T:
    return True

return False

def region_growing(image, seed_point,homo_fun,r, T):
    mask = np.zeros(image_gray.shape, np.uint8)
    mask[seed_point] = 1
    count = 1
    while count > 0:
```

```
count = 0
        local mask = np.zeros(image gray.shape, np.uint8)
        for i in range(r,image.shape[0] - r):
            for j in range(r,image.shape[1] - r):
                 if mask[i,j]==0 and mask[i - r:i + r, j-r: j+r].sum()
> 0:
                     if homo fun(image, mask, (i,j), T):
                         local mask[i,j] = 1
        count = np.count nonzero(local mask)
        print(count)
        mask += local_mask
    return mask*255
seed point = (250, 250)
r = \overline{4}
T = 16
mask = region growing(image gray, seed point, homo average, r, T)
56
151
242
331
415
524
613
700
788
868
974
810
777
829
879
767
753
719
676
659
651
609
562
538
497
459
450
411
373
352
305
```

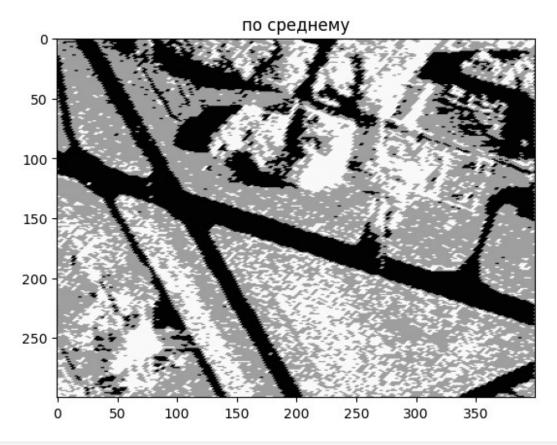
```
516
290
255
224
206
106
67
47
27
10
0
plt.imshow(mask, cmap = "gray")
plt.title("Участок газона")
plt.show()
```



```
flags = cv2.KMEANS_RANDOM_CENTERS
z = image_gray.reshape((-1,3))
z = np.float32(z)
criteria = (cv2.TERM_CRITERIA_EPS + cv2.TERM_CRITERIA_MAX_ITER, 10,
1.0)
K = 3
ret,label,center=cv2.kmeans(z,K,None,criteria,10,cv2.KMEANS_RANDOM_CEN TERS)
```

```
center = np.uint8(center)
res = center[label.flatten()]
res2 = res.reshape((image_gray.shape))

plt.imshow(res2, cmap="gray")
plt.title("по среднему")
plt.show()
```



```
def calculate_intracluster_distance(labels, centers, data):
    total_distance = 0
    for i in range(len(centers)):
        cluster_points = data[labels.flatten() == i]
        if len(cluster_points) > 0:
            distances = np.linalg.norm(cluster_points - centers[i],

axis=1)
        total_distance += np.sum(distances)
    return total_distance

z = image_gray.reshape((-1, 1))
z = np.float32(z)
criteria = (cv2.TERM_CRITERIA_EPS + cv2.TERM_CRITERIA_MAX_ITER, 10,
1.0)
K = 3
ret, label, center = cv2.kmeans(z, K, None, criteria, 10,
```

```
cv2.KMEANS_RANDOM_CENTERS)
center = np.uint8(center)
res = center[label.flatten()]
res2 = res.reshape((image_gray.shape))

plt.imshow(res2, cmap="gray")
plt.title("с вычислением внутрикластерного расстояния")
plt.show()
```

## С ВЫЧИСЛЕНИЕМ ВНУТРИКЛАСТЕРНОГО РАССТОЯНИЯ 50 - 100 - 150 - 200 - 250 300 350

```
criteria = (cv2.TERM_CRITERIA_EPS + cv2.TERM_CRITERIA_MAX_ITER, 15,
1.0)
K = 4
ret, label, center = cv2.kmeans(z, K, None, criteria, 10,
cv2.KMEANS_RANDOM_CENTERS)
center = np.uint8(center)
res = center[label.flatten()]
res2 = res.reshape((image_gray.shape))
plt.imshow(res2, cmap="gray")
plt.title("c другим к и criteria")
plt.show()
```



```
from scipy import ndimage
image = cv2.imread("palm_1 (1).JPG")
image gray = cv2.cvtColor(image, cv2.COLOR BGR2GRAY)
blurred = cv2.GaussianBlur(image_gray, (13, 13), 0)
ret, thresh = cv2.threshold(blurred, 0, 255, cv2.THRESH BINARY INV +
cv2.THRESH OTSU)
dist transform = cv2.distanceTransform(thresh, cv2.DIST L2, 5)
local maxima = ndimage.maximum filter(dist transform, size=20,
mode='constant')
ret, sure fg = cv2.threshold(dist transform, 0.1 *
dist transform.max(), 255, cv2.THRESH BINARY)
sure_fg = sure_fg.astype(np.uint8)
ret, markers = cv2.connectedComponents(sure fg)
markers[dist transform == local maxima] = 1
markers = ndimage.label(markers)[0]
markers = cv2.watershed(image, markers.astype(np.int32))
num trees = len(np.unique(markers)) - 1
segmented image = image.copy()
segmented image[markers == -1] = [255, 0, 0]
plt.figure(figsize=(12, 5))
plt.subplot(1, 3, 1)
plt.imshow(cv2.cvtColor(image, cv2.COLOR BGR2RGB))
```

```
plt.title("Оригинальное изображение")
plt.subplot(1, 3, 2)
plt.imshow(cv2.cvtColor(thresh, cv2.COLOR_BGR2RGB))
plt.title("Threshold")
plt.subplot(1, 3, 3)
plt.imshow(cv2.cvtColor(segmented_image, cv2.COLOR_BGR2RGB))
plt.title(f"Сегментированное изображение. Количество пальм:
{num_trees}")
plt.show()
```

