

## APPLIED LINEAR ALGEBRA HOMEWORK 4

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### Exercise 1. (4.3)

Let  $A$  and  $B$  be square matrices of  $\mathcal{M}_n(\mathbb{R})$ , and  $u$  a vector of  $\mathbb{R}^n$ .

- (a) If  $A$  is a band matrix (see Definition 6.2.1), compute the computational complexity for computing  $Au$  (assuming  $n$  large) in terms of the half-bandwidth  $p$  and of  $n$ .
- (b) If  $A$  and  $B$  are two band matrices, of equal half-bandwidths  $p$ , prove that the product  $AB$  is a band matrix. Find the computational complexity for computing  $AB$ .

*Proof.*

(a):

Let  $Au =: (v_1, \dots, v^n)^T$  denote the output of the matrix vector computation. Then we know

$$v_i = \sum_{j=1}^n a_{ij} u_j$$

since  $u$  is dense, the only place where this could be simplified is when  $a_{ij} = 0$ . This means we only count the case when  $a_{ij} \neq 0$ , which means we've converted our problem into a problem of finding how many non-zero entries does  $A$  have, as each one corresponding to a multiplication with one entry of  $u$ . (Note that in the expression above no entry in  $A$  is counted repeatedly.)

So since there is a main diagonal with  $n$  entries and the  $k - th$  offdiagonal

$$a_{1k}, a_{2,k+1}, \dots, a_{n-k,n}$$

has  $n - k$  entries, and there are 2 of such for each  $1 \leq k \leq p$ , we get that there are in total

$$n + 2 \left( \frac{[(n-1) + (n-p)]p}{2} \right) = (2p+1)n - p^2 - p$$

non-zero entries of  $A$ , hence the complexity is  $(2p+1)n - p^2 - p = (2p+1)n + O(p^2)$  for  $p \ll n$ .

(b):

Let  $C := AB = (c_{ij})$ , then the matrix multiplication formula tells us

$$c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}.$$

But  $a_{ik} = 0$  if  $|i - k| > p$  and  $b_{kj} = 0$  if  $|j - k| > p$ , and thus for  $n \gg p$ , if  $|i - j| > 2p$  then at least one of  $|i - k|$  and  $|j - k|$  is larger than  $p$  for all  $k$ , so

$$c_{ij} = 0 \quad \text{for } |i - j| > 2p$$

which means that  $C$  is a band matrix with half bandwidth  $2p$ .

In particular, even if  $A$  has half-bandwidth  $p_1$ ,  $B$  has half-bandwidth  $p_2$ ,  $C = AB$  is still a band-matrix of half-bandwidth  $p_c \leq 2 \max\{p_1, p_2\}$ .

Now back to the same half-bandwidth case, we notice that after eliminating all cases where  $|i - k| > p$  or  $|j - k| > p$ , the expression of  $c_{ij}$  becomes

$$c_{ij} = \sum_{k \in S(i,j)} a_{ik} b_{kj}$$

where

$$S(i, j) := \{k : |i - k| \leq p \text{ or } |j - k| \leq p\}.$$

Under this expression, every multiplication is necessary. But we note that each  $a_{ik}$  corresponds to 1 multiplication in every  $c_{ij}$  where  $k \in S(i, j)$ , and that each multiplication is of some entry in  $A$  and some entry in  $B$ . Plus, there's no division.

Therefore, we know that for each  $a_{ik} \neq 0$ , it appeared in  $|J(k)|$  terms of  $C$  where

$$J(k) = \{j : |j - k| \leq p, 1 \leq j \leq n\}.$$

Plus, for each  $k$  there's  $|I(k)|$  non-zero entries  $a_{ik}$  in  $A$ , where

$$I(k) = \{i : |i - k| \leq p, 1 \leq i \leq n\}.$$

So the complexity of  $C = AB$  is nothing but to count for each  $k$ , how many counted  $a_{ik}$  there were, and how much times each is multiplied, which gives:

$$\text{complexity}(C = AB) = \sum_{k=1}^n |I(k)| |J(k)|$$

where we note that

$$I(k) = J(k) = \begin{cases} p + k & 1 \leq k \leq p \\ 2p + 1 & p + 1 \leq k \leq n - p \\ p + (n - k) & n - p + 1 \leq k \leq n \end{cases}$$

and plugging in we have

$$\begin{aligned}
 \text{complexity}(C = AB) &= \sum_{k=1}^n I(k)J(k) \\
 &= 2 \left( (p+1)^2 + \cdots + (2p)^2 \right) + (n-2p)(2p+1)^2 \\
 &= 2 \left( \sum_{i=1}^{2p} i^2 - \sum_{i=1}^p i^2 \right) + (n-2p)(2p+1)^2 \\
 &= 2 \left( \frac{2p(2p+1)(4p+1)}{6} - \frac{p(p+1)(2p+1)}{6} \right) + (n-2p)(2p+1)^2 \\
 &= \frac{14p^3 + 9p^2 + 1p}{3} + n(2p+1)^2 - 2p(2p+1)^2 \\
 &= n(2p+1)^2 - \frac{10p^3 - p^2 - 3p}{3} = (2p+1)^2 n + O(p^3).
 \end{aligned}$$

□

**Exercise 2. (5.6)**

We define a matrix  $A = [1 : 5; 5 : 9; 10 : 14]$ .

(1) Compute a matrix  $Q$  whose columns form a basis of the null space of  $A^T$ .

(2)

(a) Consider  $b = [5; 9; 4]$  and the vector  $x \in \mathbb{R}^5$  defined by the instruction  $x = A \backslash b$ . Compute  $x$ ,  $Ax - b$ , and  $Q^T b$ .

(b) Same question for  $b = [1; 1; 1]$ . Compare both cases.

(c) Justification. Let  $A$  be a real matrix of size  $m \times n$ . Let  $b \in \mathbb{R}^m$ . Prove the equivalence

$$b \in \text{Im}(A) \iff Q^T b = 0.$$

(d) Write a function `InTheImage(A, b)` whose input arguments are a matrix  $A$  and a vector  $b$  and whose output argument is “yes” if  $b \in \text{Im}(A)$  and “no” otherwise.

Application:

$$A = [123; 456; 789], b = [1; 1; 1] \text{ and } b = [1; 2; 1].$$

*Proof.*

(1):

We can simply find  $Q$  by the code `null(A.')`, which yields:

```
Q =
    0.4527
   -0.8148
    0.3621
```

(2):

(a): Doing the test yields:

$x$	$Ax - b$	$Q^T b$
<pre>x =    -1.8443          0          0          0     1.6967</pre>	<pre>Ax-b= ans =     1.6393    -2.9508     1.3115</pre>	<pre>Q^T b ans =    -3.6214</pre>

(b): Doing the test yields:

$x$	$Ax - b$	$Q^T b$
<pre>x = -0.2500     0     0     0     0.2500</pre>	<pre>Ax-b= ans = 1.0e-15 * -0.2220 -0.2220 -0.4441</pre>	<pre>Q^T b ans = 8.8818e-16</pre>

Note that the  $Ax - b = 0$  already implies that a best fit  $x$  is found.

(c):

( $\Rightarrow$ ): If  $b \in \text{Im}(A)$ , then  $\exists x$  such that  $b = Ax$ , and hence

$$Q^T b = Q^T Ax = (x^T (A^T Q))^T = (x^T * O)^T = 0.$$

( $\Leftarrow$ ): On Oct 19th's lecture we've covered the result  $\ker(A^T) = \text{Col}(A)^\perp$ , where  $\text{Col}(A)$  is the image of the column space of  $A$ , which is exactly  $\text{Im}(A)$ .

Since the columns of  $Q^T$  spans the whole  $\ker(A^T)$ , and  $Q^T b = 0$  means that  $b$  is perpendicular to each column of  $Q$ , since each row of  $Q^T b$  is the inner product of  $b$  and a column of  $Q^T$ . So either  $b = 0$  or  $b \perp \ker(A^T) \Rightarrow b \in \text{Im}(A)$  by above discussion, but either way  $b \in \text{Im}(A)$ .

(d): The code is

```

1 function T = InTheImage(A, b)
2 %This returns whether b = Ax for some x using the above method.
3 Q = null(A. ');
4 tol = 0.001;
5 if Q.'*b < tol
6     T = "yes";
7 else
8     T = "no";
9 end
10 end

```

And since I realized that even though  $(1, 2, 1)$  is not in the image of  $A$  (not in kernel either), the error is 0.81 that is quite big. But that's a genuine result of matlab. I used  $(1, -2, 1) \in \ker(A^T)$  to test the no case, which works well. Also, maybe I should use norm of  $Q^T b < \text{tolerance}$ , but since the dimension of kernel is just 1, I didn't write that for this case.

<pre>b =    1   1   1  answer =  "yes"</pre>	<pre>b =    1   2   1  answer =  "yes"</pre>	<pre>b =    1  -2   1  answer =  "no"</pre>
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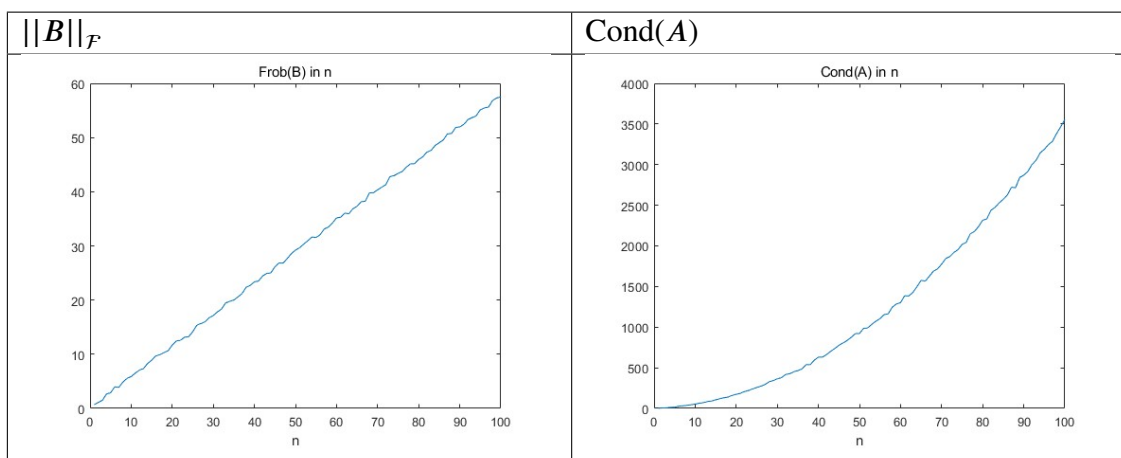
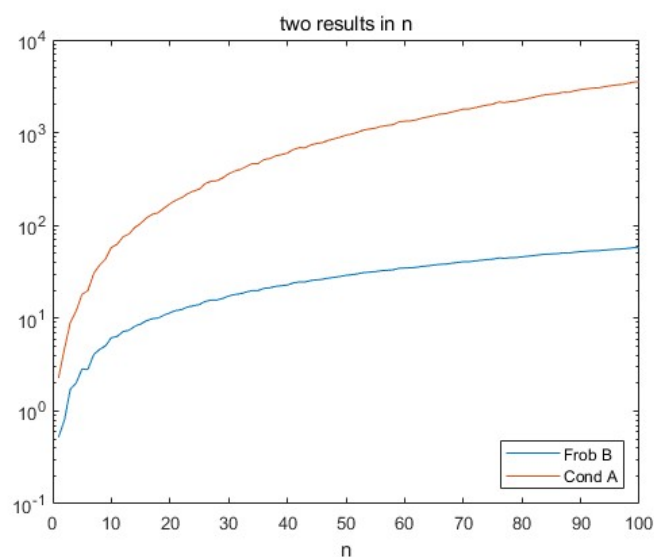
**Exercise 3.** (5.8) Let  $A$  and  $B$  be two matrices defined by the instructions

```
n=10;B=rand(n,n);A=[eye(size(B)) B; zeros(size(B)) eye(size(B))];
```

Compute the Frobenius norm of  $B$  as well as the condition number of  $A$  (in the Frobenius norm). Compare the two quantities for various values of  $n$ . Justify the observations.

**Solution:**

So the graph I get for various  $n$  is the following:



So as we can see, the Frobenius norm grows linearly while the condition number grows quadratically.

This is natural since all entries of  $B$  is random, so assuming that each entry is iid we get

$$||B||_F = \left( \sum_{i=1}^{n^2} X_i^2 \right)^{\frac{1}{2}} = (n^2 X_1^2)^{\frac{1}{2}}$$

and by taking expectations on both sides we get

$$\mathbb{E} [||B||_F] = \mathbb{E} \left[ (n^2 X_1^2)^{\frac{1}{2}} \right] = n \mathbb{E}[X_1]$$

where  $\mathbb{E}[X_1]$  is just a constant. So the result should be linear.

Now, let's look at  $A$ , the definition of it means

$$A = \begin{pmatrix} I & B \\ 0 & I \end{pmatrix} \quad \text{and} \quad A^{-1} = \begin{pmatrix} I & -B \\ 0 & I \end{pmatrix}$$

either by analogy to 2 by 2 square matrices or just by computation. Hence,

$$||A||_F = \left( \sum_{i=1}^{n^2} X_i^2 + 2n \right)^{\frac{1}{2}} = ||B||_F \left( 1 + \frac{2n}{||B||_F^2} \right)^{\frac{1}{2}} = ||B||_F + ||B||_F \frac{\frac{2n}{||B||_F^2}}{2} + O()$$

where since by Taylor we have

$$(1+x)^{\frac{1}{2}} = 1 + \frac{x}{2} - \frac{x^2}{8} + O(x^3)$$

we get

$$||A||_F = ||B||_F + ||B||_F \frac{\frac{2n}{||B||_F^2}}{2} + O\left(\frac{1}{n}\right) = ||B||_F + \frac{n}{||B||_F} + O\left(\frac{1}{n}\right)$$

since  $||B||_F = O(n)$ , which is also why we can use Taylor in the first place.

And since Frobinius norm doesn't care about the sign of each term, we get

$$||A^{-1}||_F = ||A||_F$$

and hence

$$\text{Cond}(A) = ||A||_F ||A^{-1}||_F = ||B||_F^2 + O(||B||_F) = O(n^2)$$

and the trend is indeed quadratic.



**Exercise 4. (5.9)**

The goal of this exercise is to empirically determine the asymptotic behavior of  $\text{cond}_2(H_n)$  as  $n \rightarrow \infty$ , where  $H_n \in \mathcal{M}_n(\mathbb{R})$  is the Hilbert matrix of order  $n$ , defined by its entries  $(H_n)_{ij} = 1/(i+j-1)$ . Compute  $\text{cond}_2(H_5)$ ,  $\text{cond}_2(H_{10})$ . What do you notice? For  $n$  varying from 2 to 10, plot the curve  $n \mapsto \ln(\text{cond}_2(H_n))$ . Draw conclusions about the experimental asymptotic behavior.

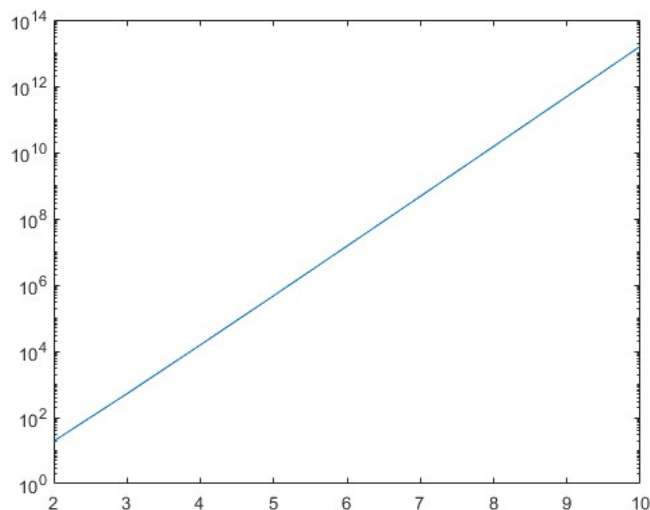
**Solution:**

Note that the question just asks us to draw conclusion of the empirical data, not deduce it, so I'll not.

The special values are

<code>n =</code>	<code>n =</code>
5	10
<code>ans =</code>	<code>ans =</code>
4.7661e+05	1.6025e+13

and the curve I get is



So OK I admit that this is not genuinely against  $\ln(\text{cond}_2(H_n))$ , but I drew a semilog plot so the genuine plot is just against the power on 10 on the y-label.

Thus, we know  $\text{cond}_2(H_n)$  grows exponentially in  $n$  from the graph.

**Exercise 5. (5.14)**

We define  $n$  by  $n$  matrices  $C$ ,  $D$ , and  $E$  by

$C = \text{NonsingularMat}(n)$ ;  $D = \text{rand}(m, n)$ ;  $E = D * \text{inv}(C) * D'$ ;

We also define  $(n + m) \times (n + m)$  block matrices  $A$  and  $M$  by

$A = [C \ D'; D \ \text{zeros}(m, m)]$ ;  $M = [C \ \text{zeros}(n, m); \text{zeros}(m, n) \ E]$ ;

- (1) For different values of  $n$ , compute the spectrum of  $M^{-1}A$ . What do you notice?
- (2) What is the point in replacing system  $Ax = b$  by the equivalent system  $M^{-1}Ax = M^{-1}b$ ?
- (3) We now want to give a rigorous explanation of the numerical results of the first question. We assume that  $A \in \mathcal{M}_{m+n}(\mathbb{R})$  is a nonsingular matrix that admits the block structure  $A = \begin{pmatrix} C & D^T \\ D & 0 \end{pmatrix}$  where  $C \in \mathcal{M}_n(\mathbb{R})$  and  $D \in \mathcal{M}_{m,n}(\mathbb{R})$  are such that  $C$  and  $DC^{-1}D^T$  are non-singular too.
  - (a) Show that the assumption “ $A$  is nonsingular” implies  $m \leq n$ .
  - (b) Show that for  $m = n$ , the matrix  $D$  is invertible.
- (4) From now on, we assume  $m < n$ . Let  $x = (x_1, x_2)^T$  be the solution of the system  $Ax = b = (b_1, b_2)^T$ . The matrix  $D$  is not assumed to be invertible, so that we cannot first compute  $x_1$  by relation  $Dx_1 = b_2$ , then  $x_2$  by  $Cx_1 + D^T x_2 = b_1$ . Therefore, the relation  $Dx_1 = b_2$  has to be considered as a constraint to be satisfied by the solutions  $x_1, x_2$  of the system  $Cx_1 + D^T x_2 = b_1$ . We study the preconditioning of the system  $Ax = b$  by the matrix  $M^{-1}$  with  $M = \begin{pmatrix} C & 0 \\ 0 & DC^{-1}D^T \end{pmatrix}$ .
  - (a) Let  $\lambda$  be an eigenvalue of  $M^{-1}A$  and  $(u, v)^T \in \mathbb{R}^{m+n}$  a corresponding eigenvector. Prove that  $(\lambda^2 - \lambda - 1)Du = 0$ .
  - (b) Deduce the spectrum of the matrix  $M^{-1}A$ .
  - (c) Compute the 2-norm conditioning of  $M^{-1}A$ , assuming that it is a symmetric matrix.

**Solution:**

(1):

I tested for  $m = n$  and the results says that all eigenvalues of the matrix is either 1.6180 or -0.6180.

Then I tested for  $m \neq n$  and the result is that in general

- If  $m = n$ , the eigenvalues of the matrix is either 1.6180 or -0.6180. Moreover there are  $m$  of each.

<pre> n =        5  E =  1.6180 + 0.0000i -0.6180 + 0.0000i -0.6180 - 0.0000i -0.6180 + 0.0000i 1.6180 + 0.0000i 1.6180 + 0.0000i 1.6180 - 0.0000i 1.6180 + 0.0000i -0.6180 + 0.0000i -0.6180 + 0.0000i </pre>	<pre> m =        4  n =        9  E =  -0.6180 + 0.0000i 1.6180 + 0.0000i 1.6180 - 0.0000i -0.6180 + 0.0000i -0.6180 + 0.0000i -0.6180 + 0.0000i 1.6180 + 0.0000i 1.6180 + 0.0000i 1.0000 + 0.0000i 1.0000 - 0.0000i 1.0000 + 0.0000i 1.0000 - 0.0000i </pre>	<pre> m =        7  n =        9  E =  -0.6180 + 0.0000i -0.6180 - 0.0000i 1.0000 + 0.0000i 1.0000 + 0.0000i -0.6180 + 0.0000i -0.6180 + 0.0000i -0.6180 - 0.0000i 1.6180 + 0.0000i 1.6180 + 0.0000i 1.6180 + 0.0000i 1.6180 + 0.0000i 1.6180 + 0.0000i 1.6180 + 0.0000i -0.6180 + 0.0000i -0.6180 - 0.0000i </pre>
<pre> m =       10  n =        5  警告：矩阵接近奇异值，或者缩放 &gt; 位置: g514 (第 9 行)  E =  0.5000 + 2.5265i 0.5000 - 2.5265i 1.9913 + 0.0000i 1.9009 + 0.0000i 1.5652 + 0.3838i 1.5652 - 0.3838i -0.9913 + 0.0000i -0.9009 + 0.0000i -0.5652 + 0.3838i -0.5652 - 0.3838i -0.0000 + 0.0000i -0.0000 - 0.0000i -0.0000 + 0.0000i -0.0000 + 0.0000i 0.0000 + 0.0000i </pre>	<pre> m =        5  n =       10  E =  1.6180 + 0.0000i 1.6180 - 0.0000i 1.6180 + 0.0000i -0.6180 + 0.0000i -0.6180 - 0.0000i -0.6180 + 0.0000i -0.6180 + 0.0000i -0.6180 + 0.0000i 1.6180 + 0.0000i 1.6180 + 0.0000i 1.0000 + 0.0000i 1.0000 + 0.0000i 1.0000 + 0.0000i 1.0000 + 0.0000i 1.0000 + 0.0000i </pre>	<pre> m =        7  n =        3  警告：矩阵接近奇异值，或者缩放不 &gt; 位置: g514 (第 9 行)  E =  2.6641 + 0.4423i 2.6641 - 0.4423i 1.9519 + 0.0000i -1.6641 + 0.4423i -1.6641 - 0.4423i -0.9519 + 0.0000i -0.0000 + 0.0000i -0.0000 - 0.0000i 0.0000 + 0.0000i -0.0000 + 0.0000i </pre>

The main reason is to when  $A$  is bad (in the sense of ill-conditioned, too dense, etc) then it's possible to get a much easier result computationally to solve the preconditioned system.

(3):

(a): I show the contrapositive:  $m > n \Rightarrow A$  is singular.

But this is easy. Since  $D$  is  $m$  by  $n$  and thus we can at least do Gaussian Elimination to let the first  $n$  rows span the whole  $\mathbb{R}^n$ , which means we can easily do row operations to  $D$  to eliminate the last  $m - n$  lines.

But we can do the same row operation on the  $n + 1$  to  $m + n$  lines on  $A$  to let the last  $m - n$  lines equal to 0. So  $\det(A) = 0$  and  $A$  is singular.

(b): If  $D$  is not invertible, then  $\det(DC^{-1}D^T) = 0 \cdot \det(C) \cdot 0 = 0$ , which contradicts the assumption that it is non-singular. So  $D$  is invertible.

Note that the condition  $m = n$  is really just because we say only square matrices can be invertible.

(4):

(a): We've proven that for a block matrix with only diagonal terms non-zero, the inverse is just by inverting all block squares. So by definition of  $M$  and  $A$ , we can compute

$$M^{-1}A = \begin{pmatrix} C^{-1} & 0 \\ 0 & (DC^{-1}D^T)^{-1} \end{pmatrix} \begin{pmatrix} C & D^T \\ D & 0 \end{pmatrix} = \begin{pmatrix} I & C^{-1}D^T \\ (DC^{-1}D^T)^{-1}D & 0 \end{pmatrix}$$

and using the spectrum condition we get

$$\begin{pmatrix} I & C^{-1}D^T \\ (DC^{-1}D^T)^{-1}D & 0 \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} u + C^{-1}D^Tv \\ (DC^{-1}D^T)^{-1}Du \end{pmatrix} = \begin{pmatrix} \lambda u \\ \lambda v \end{pmatrix}$$

and from the second line we get

$$v = \frac{1}{\lambda}(DC^{-1}D^T)^{-1}Du$$

plugging into the first line we end with

$$(\lambda - 1)u = C^{-1}D^Tv = C^{-1}D^T \frac{1}{\lambda}(DC^{-1}D^T)^{-1}Du$$

$$\Rightarrow (\lambda^2 - \lambda)u = C^{-1}D(DC^{-1}D^T)^{-1}Du$$

$$\Rightarrow (\lambda^2 - \lambda)Du = ((DC^{-1}D^T))(DC^{-1}D^T)^{-1}Du = Du$$

hence we get

$$(\lambda^2 - \lambda - 1)Du = 0.$$

(b): From last result we get that either  $Du = 0$  or  $(\lambda^2 - \lambda - 1) = 0$ .

Suppose  $Du = 0$ , then  $A \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} Cu + D^Tv \\ Du \end{pmatrix} = \begin{pmatrix} Cu + D^Tv \\ 0 \end{pmatrix}$  which, if we left multiply by  $M^{-1}$  it gives us  $v = 0$  since  $M^{-1}$  is a diagonal matrix (so really by computation).

But then  $(\lambda - 1)u = C^{-1}D^Tv = 0$ , so either  $u = 0$  or  $\lambda = 1$ .

If  $u = 0$ , then the eigenvector is 0, so impossible. Thus,  $\lambda = 1$ .

Let's check that for all  $u \in \ker(D)$ ,  $(u, 0)^T$  is an eigenvector of  $M^{-1}A$ .

But this is by computation:

$$\begin{pmatrix} u + C^{-1}D^T v \\ (DC^{-1}D^T)^{-1}Du \end{pmatrix} = \begin{pmatrix} u \\ 0 \end{pmatrix}.$$

So we get that if  $Du = 0$ , then the eigenvalue is 1 with multiplicity  $\dim(\ker(D))$  (since otherwise the eigenvalues are not linearly independent).

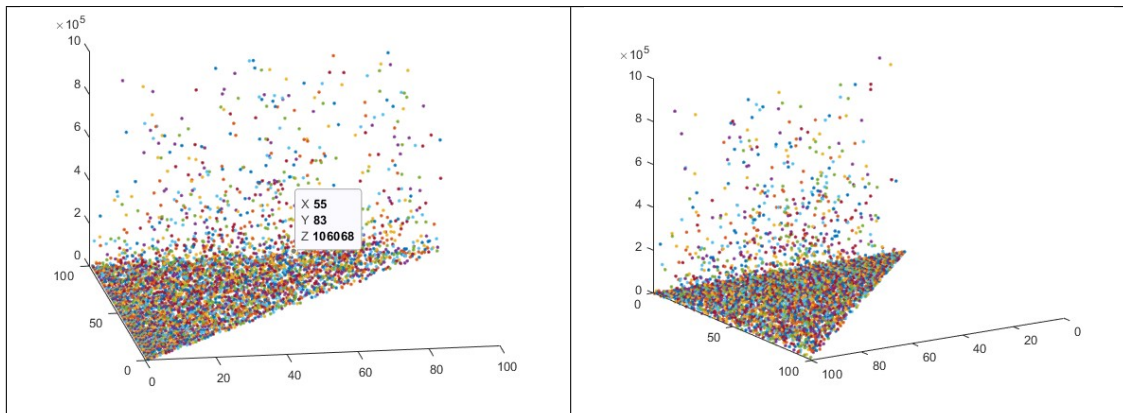
As for when  $(\lambda^2 - \lambda - 1) = 0$ , we simply get

$$\lambda_1 = \frac{1 - \sqrt{5}}{2} \approx -0.618; \quad \lambda_2 = \frac{1 + \sqrt{5}}{2} \approx 1.618.$$

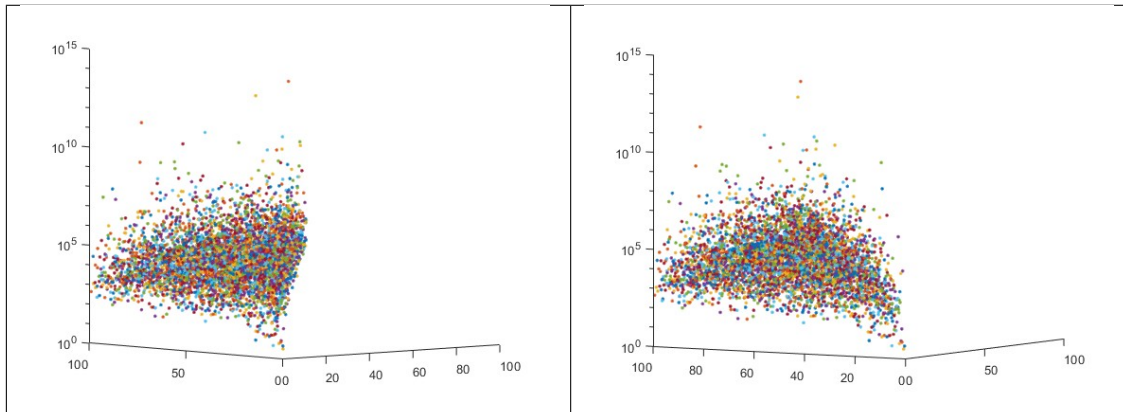
And that they are evenly distributed is simply because by our computation above, whenever we get one there's another solution of  $(u, v)^T$  with the other eigenvalue.

Therefore, we've reached the exact same conclusion as our observation in (1).

(c): So I write up a little plot that reflects the behavior of the conditional numbers in  $m$  and  $n$ :

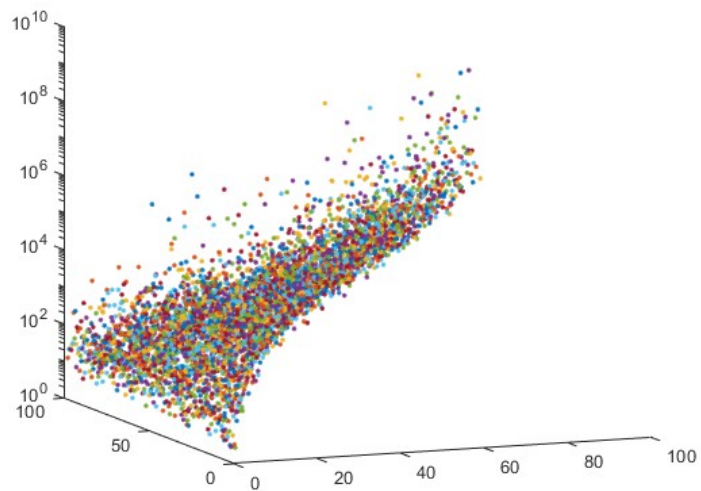


(I neglected outliers that's too big that the graph is not meaningful) Which I notices that it's quite flat comparatively, so I then plotted the log-scale graph:



So I guess most of the distribution is around  $10^2$  to  $10^7$ .

And I also did for symmetric matrix, which gives this smoother surface I guess:



**Exercise 6.**

The goal of this exercise is to compare the performances of the LU and Cholesky methods.

- (1) Write a function LUfacto returning the matrices  $L$  and  $U$  determined via Algorithm 6.1. If the algorithm cannot be executed (division by 0), return an error message.
- (2) Write a function Cholesky returning the matrix  $B$  computed by Algorithm 6.2. If the algorithm cannot be executed (nonsymmetric matrix, division by 0, negative square root), return an error message. Compare with the Matlab function chol.
- (3) For  $n = 10, 20, \dots, 100$ , we define a matrix  $A = \text{MatSdp}(n)$  (see Exercise 2.20) and a vector  $b = \text{ones}(n, 1)$ . Compare:
  - On the one hand, the running time for computing the matrices  $L$  and  $U$  given by the function LUFacto, then the solution  $x$  of the system  $Ax = b$ . Use the functions BackSub and ForwSub defined in Exercise 5.2.
  - On the other hand, the running time for computing the matrix  $B$  given by the function Cholesky, then the solution  $x$  of the system  $Ax = b$ . Use the functions BackSub and ForwSub.

Plot on the same graph the curves representing the running times in terms of  $n$ . Comment.

**Solution:(1):** The code is below:

```

1  function A = LUfacto(A)
2  %This function returns A containing U and L but its diagonal
3  sz = size(A);
4  tol = 0.000000000001;
5  n = sz(1);
6  for k = 1: n-1
7      for i = k+1: n
8          if abs(A(k,k)) < tol
9              error("cannot divide by 0");
10             return
11         else
12             A(i,k) = A(i,k)/A(k,k);
13             for j = k+1: n
14                 A(i,j) = A(i,j)-A(i,k)*A(k,j);
15             end
16         end
17     end
18 end
19 end

```

(2):

```

1  function A = Cholesky(A)
2  % A containing B in its lower triangular part
3  sz = size(A);
4  tol = 0.0000000001;
5  n = sz(1);
6  if norm(A-A.') > tol
7      error("A is not symmetric");
8      return
9  end
10
11 for j = 1:n
12     for k = 1: j-1
13         A(j,j) = A(j,j) - (A(j,k))^2;
14     end
15     if A(j,j)<0
16         error("cannot take square root of negative numbers");
17         return
18     elseif A(j,j)< tol
19         error("Cannot divide by 0");
20         return
21     end
22     A(j,j) = sqrt(A(j,j));
23     for i = j+1:n
24         for k = 1:j-1
25             A(i,j) = A(i,j) - A(j,k)*A(i,k);
26         end
27         A(i,j) = A(i,j)/A(j,j);
28     end
29 end
30 end

```

(3):

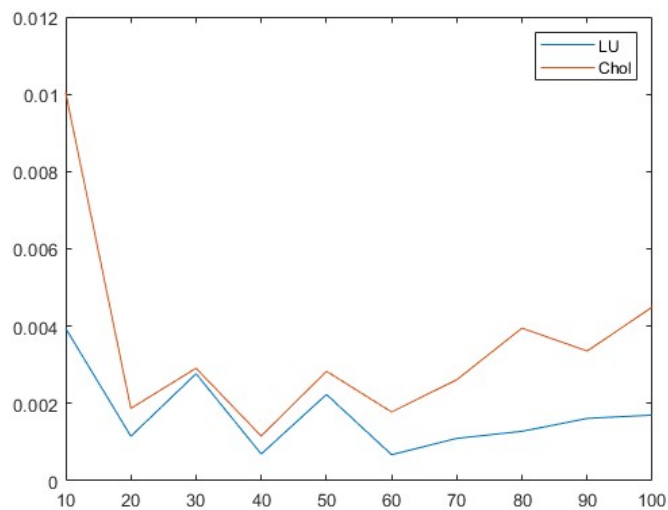


```

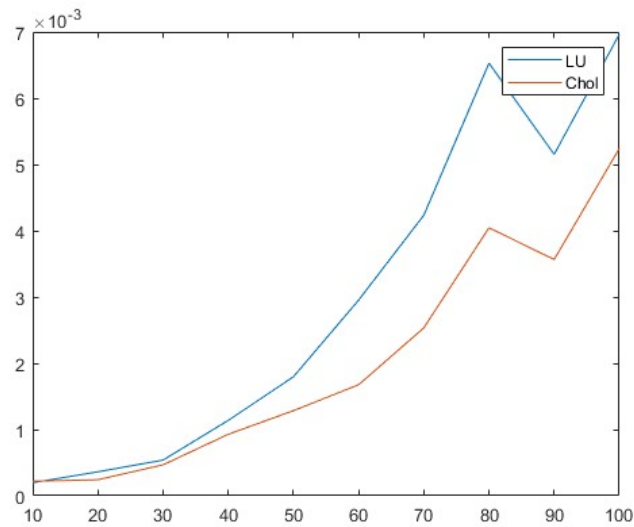
1  A = [4 1 1; 1 2 3; 1 3 5];
2  B = LUfacto(A);
3  C = Cholesky(A);
4  n1 = [];
5  T_LU = [];
6  T_Chol = [];
7  for i = 1:10
8      n = 10*i;
9      n1(i) = n;
10     b = ones(n,1);
11     A = MatSdp(n);
12     tic
13     B = LUfacto(A);
14     % This ForwSubL really uses the fact that L has diagonal 1
15     x1 = ForwSubL(B,b);
16     x2 = Backsub(B, x1);
17     T_LU(i) = toc;
18     tic
19     C = Cholesky(A);
20     x1 = ForwSub(C,b);
21     x2 = Backsub(C.', x1);
22     T_Chol(i) = toc;
23 end
24
25 plot(n1,T_LU)
26 hold all
27 plot(n1,T_Chol)
28 legend("LU","Chol")
29 %
30 % f = @( ) myComputeFunction(x,y); % handle to function
31 % timeit(f)
32

```

And the run time is:



This may seem a little weird because the beginning is quite large. But this is only because that was the first time I called the functions in this file. So I add a few code that does all the functions once, and afterwards the curve becomes



which makes a lot more sense.

We can see that For larger matrices, it's less painful to do Cholesky factorization.

### Exercise 7.

Suppose that an  $n \times n$  matrix  $A \in \mathcal{M}_n(\mathbb{R})$  is invertible and has an LU factorization (and that we have already computed and stored it). It is often practically important to be able to re-solve the system of equations when the matrix  $A$  is “updated” by a rank-one matrix  $uv^T$  (with  $u, v \in \mathbb{R}^n$ ) to obtain a system

$$(A + uv^T)x = b.$$

- (a) Recall that we have assumed that  $A$  is invertible. Show that  $A + uv^T$  is invertible if and only if  $\langle v, A^{-1}u \rangle \neq -1$ .
- (b) When  $(A + uv^T)$  is invertible (i.e. when the condition in (a) is satisfied), one has

$$(A + uv^T)^{-1} = A^{-1} - \frac{A^{-1}uv^T A^{-1}}{1 + \langle v, A^{-1}u \rangle}$$

This identity is often attributed to Sherman and Morrison 1 and is related to more general matrix identities due to M. Woodbury (see also W. Hager, Updating the inverse of a matrix, SIAM Review 31 (1989), no. 2, 221–239). Verify this formula by computing the product of  $A + uv^T$  with the given matrix.

- (c) Suppose that all of the (principal) diagonal submatrices of  $A$  are nonsingular, and suppose that we are given an LU factorization for  $A$ . Use the Sherman–Morrison formula from (b) to formulate an efficient algorithm for solving

$$(A + uv^T)x = b.$$

*Proof.* (a): I follow the block matrix hint and will show that

**Lemma 0.1.**

$$\det(I + xy^T) = 1 + x^T y$$

*Proof.* This is done by block matrix operation where each  $\sim$  represent some row/col operation, where if I use index  $i$ , I mean for all  $i = 1, 2, \dots, n$  **AND NOT FOR  $(n+1)$** :

$$\begin{aligned} \left( \begin{array}{cc} I + xy^T & 0 \\ 0 & 1 \end{array} \right) & \xrightarrow{r_i = r_i + x_i * r_{n+1}} \left( \begin{array}{cc} I + xy^T & x \\ 0 & 1 \end{array} \right) \xrightarrow{c_i = c_i - y_i * c_{n+1}} \left( \begin{array}{cc} I & x \\ -y^T & 1 \end{array} \right) \\ & \xrightarrow{c_{n+1} = c_{n+1} - x_i * c_i} \left( \begin{array}{cc} I & 0 \\ -y^T & 1 + x^T y \end{array} \right) \end{aligned}$$

and by taking the determinant on both sides we get

$$\det(I + xy^T) = 1 + \langle x, y \rangle$$

□

Now back to the question. Let  $A + uv^T = A(I + (A^{-1}u)v^T)$  we know that

$$\det(I + (A^{-1}u)v^T) = 1 + \langle A^{-1}u, v \rangle$$

which is 0 if and only if  $\langle v, A^{-1}u \rangle \neq -1$  by above lemma.

But since  $A$  invertible  $\det(A) \neq 0$  so

$$A + uv^T \text{ invertible} \iff \det(I + (A^{-1}u)v^T) \neq 0 \iff \langle v, A^{-1}u \rangle \neq -1$$

and so we are done.

(b): This equality is actually encoded in the third matrix of the above deduction of lemma in (a), but still let's check it:

$$\begin{aligned} \left( A^{-1} - \frac{A^{-1}uv^T A^{-1}}{1 + \langle v, A^{-1}u \rangle} \right) (A + uv^T) &= I + A^{-1}uv^T - \frac{A^{-1}uv^T + A^{-1}u(v^T A^{-1}u)v^T}{1 + \langle v, A^{-1}u \rangle} \\ &= I + A^{-1}uv^T \left( \frac{(1 + \langle v, A^{-1}u \rangle) - (1 + (v^T A^{-1}u))}{1 + \langle v, A^{-1}u \rangle} \right) \\ &= I + A^{-1}uv^T * 0 = I \end{aligned}$$

(c): We can just use  $U^{-1}L^{-1}$  to compute  $A^{-1}$  and then plug in to the formula, then right multiply by  $b$  to solve the system. Since inverting triangular matrix requires  $O(n^2)$  mult/div, the whole process is dominated by this procedure and thus the whole complexity is  $O(n^2)$ . The code is here:

```
1 function x = SM(L,U,u,v,b)
2 %This function uses the formula to get the solution x
3 Ainv = inv(U)*inv(L);
4 fml = Ainv-(Ainv*u*v.'*Ainv)/(1+v.'*Ainv*u);
5 x = fml*b;
6 end
```

□