

c.
$$M_{0} = \langle \{p, q, r, s\}, \{0, 1\}, \delta_{0}, p, \{q, s\} \rangle,$$

$$\delta_{0} = \begin{vmatrix} 0 & 1 & \lambda \\ \hline p & \{q, s\} & \{q\} & \varnothing \\ \hline q & \{r\} & \{q, r\} & \varnothing \\ \hline r & \{s\} & \{p\} & \varnothing \\ \hline s & \varnothing & \{p\} & \varnothing \end{vmatrix}$$

Det P {qs} {q! qs {RØ} {q,R,P} qf R} {q,R} RØ { QRP QR

