
Math 4NA3 - Assignment 5

April 1, 2021

Question 1:

a) We are given the equation

$$y'' + Q(x)y = F(x)$$

and the central difference approximations are $y'' = \frac{y_{n+1} - 2y_n + y_{n-1}}{h^2}$ and $y' = \frac{y_{n+1} - y_{n-1}}{2h}$. Together, this gives the system

$$y_{n+1} [1] + y_n [h^2 Q(x) - 2] + y_{n-1} [1] = h^2 F(x)$$

We can implement the system with each set of boundary values as follows.

```
1 function [x,y] = fdbvp1(qfun,ffun,a,b,ya,yb,h)
2 x = a:h:b;
3 n = length(x);
4 Q = arrayfun(qfun,x);
5 F = arrayfun(ffun,x);
6 C = ones(1,n);
7 B = (h^2)*Q - 2*ones(1,n);
8 A = ones(1,n);
9 D = (h^2)*F;
10 D(1,1) = D(1,1) - ya;
11 D(1,end) = D(1,end) - yb;
12 y = tridiag(A,B,C,D);
13 end
```

```
14
15 function [x,y] = fdbvp2(qfun,ffun,a,b,ya,yp,h)
16 n = 1/h;
17 x = linspace(a,b,n+1);
18 Q = arrayfun(qfun,x);
19 F = arrayfun(ffun,x);
20 C = ones(1,n+1);
21 C(1,1) = -2;
22 B = (h^2)*Q - 2*ones(1,n+1);
23 A = ones(1,n+1);
24 A(1,end) = -2;
25 D = (h^2)*F;
26 D(1,1) = D(1,1) - ya;
27 D(1,end) = D(1,end) - 2*h*yp;
28 y = tridiag(A,B,C,D);
29 end
```

b) We use the MATLAB functions on the given bvp's as follows.

```
1 [x1,y1] = fdbvp1(@(x) 1, @(x) 3*x^2, 0, 2, 0, 3.5031, 0.1);
2 [x2,y2] = fdbvp2(@(x) 1, @(x) 3*x^2, 0, 2, 0, 6.5442, 0.1);
3 hold on
4 grid on
```

```

5 plot(x1,y1,"o")
6 plot(x2,y2,"o")
7 fplot(@(x) 6*cos(x) + 3*(x^2-2), [0,2])
8 legend("(3)","(4)","Exact")

```

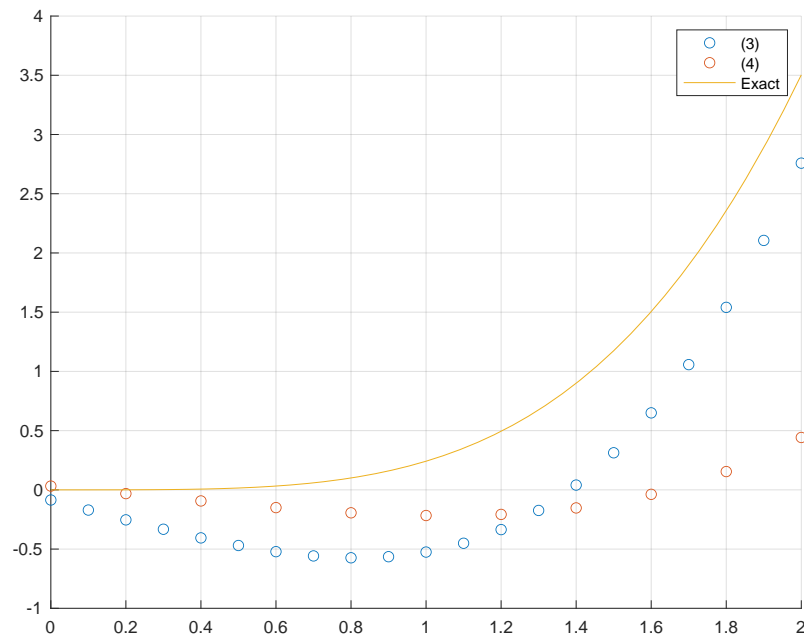


Figure 1: Numerical Solutions and Exact

From the solutions, I suspect there is a bug in my code or I wrote the matrix wrong when I was deriving it.

c) Using the above function at $h = 0.1$ and $h = 0.05$ gives the following error plot. Halving the grid spacing halved the error. Thus, I suspect the method is $O(h)$.

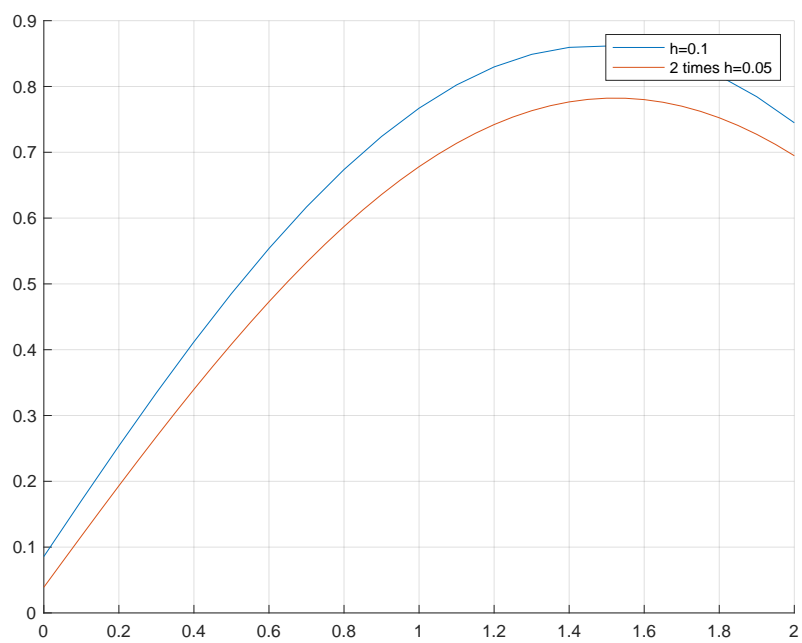


Figure 2: Error Plot

Question 2:

a) Here is the MATLAB implementation of the finite element method applied to equation (1) with the given approximations.

```
1 function [x,y] = fe(qfun, ffun, L, R, ya, yb, h)
2 x = L:h:R;
3 n = length(x);
4 for i = 1:n-1;
5     a(i) = quad(qfun,x(i),x(i+1))./3;
6     b(i) = quad(qfun,x(i),x(i+1))./6;
7     e(i) = quad(ffun,x(i),x(i+1))./2;
8 end
9 C = b(2:end) + (1/h);
10 B = a(1:end-1) + a(2:end) - 2*(1/h);
11 A = b(1:end-1) + (1/h);
12 D = e(2:end) + e(2:end);
13 D(1) = D(1) - ((1/h) + a(1))*ya;
14 D(end) = D(end) - ((1/h) + a(end))*yb;
15 y = tridiag(A,B,C,D);
16 end
```

b) We apply the function to the given problem as follows.

```
1 [x,y] = fe(@(x) sin(x)-2,@(x) (sin(x)).^2-6,0,4,3,2.2432,0.1)
2 [x1,y1] = fe(@(x) sin(x)-2,@(x) (sin(x)).^2-6,0,4,3,2.2432,0.05)
3 size(x)
4 size(y)
5 plot(x(2:end-1),y,"o")
6 hold on
7 grid on
8 fplot(@(x) sin(x)+3,[0,4])
9 legend("Approx","Exact")
```

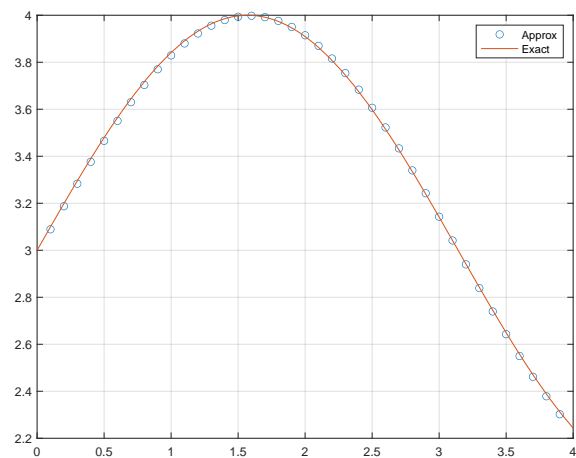


Figure 3: $h = 0.1$

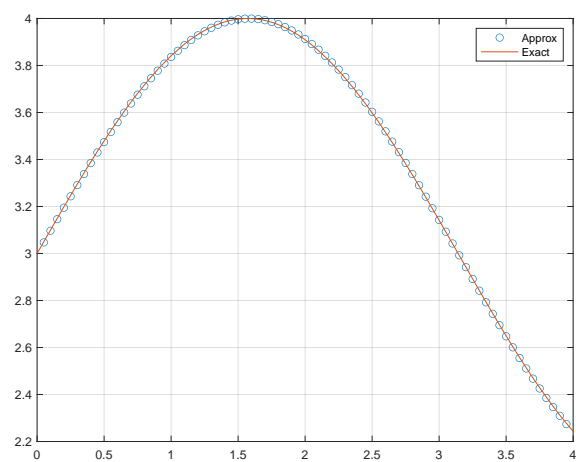


Figure 4: $h = 0.05$

Now we can plot the error as follows.

```
1 xnew = x(2:end-1);
2 xnew1 = x1(2:end-1);
3
4 for i = 1:length(xnew)
5     e(i) = exact(xnew(i))-y(i);
6 end
7 for i = 1:length(xnew1)
8     e1(i) = exact(xnew1(i))-y1(i);
9 end
10
11 plot(xnew,e)
12 hold on
13 grid on
14 plot(xnew1,e1)
15 legend("h=0.1","h=0.05")
```

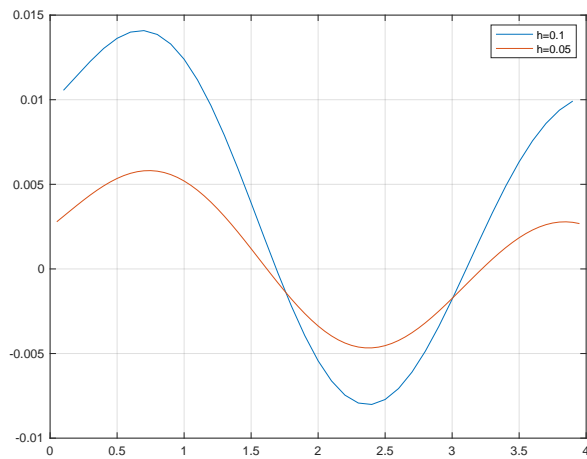


Figure 5: Error

From the error plot, we suspect that the method is $O(h)$.

Question 3:

We are given the linear bvp

$$y'' + x^2y = 1, \quad x \in (0, 1), \quad y(0) = y(1) = 0$$

To solve this we use the finite difference function from question 1 and the altered shooting method code as follows.

```
1 clear
2 clc
3
4 tic
5 [x1,y1] = fdbvp1(@(x) x^2,@(x) 1,0,1,0,0,0.001);
6 toc
7
8 hold on
9 plot(x1,y1,'r')
10
11 tic
12 h = 0.01;
13 x = 0:h:1;
14 F = @(x) 1;
15 Q = @(x) x.^2;
16 alpha = 0; beta = 0;
17 fu = @(x,y) -Q(x)*y + F(x);
18 fv = @(x,y) -Q(x)*y;
19 u1(1) = alpha; u2(1) = 0;
20 v1(1) = 0; v2(1) = 1;
21 for k = 1 : length(x)-1
22     fu1 = fu(x(k),u1(k));
23     u1p = u1(k) + h * u2(k);
24     u2p = u2(k) + h * fu1;
25     u1(k+1) = u1(k) + 0.5*h * (u2(k) + u2p);
26     u2(k+1) = u2(k) + 0.5*h * (fu1 + fu(x(k+1),u1p));
27     fv1 = fv(x(k),v1(k));
28     v1p = v1(k) + h * v2(k);
29     v2p = v2(k) + h * fv1;
30     v1(k+1) = v1(k) + 0.5*h * (v2(k) + v2p);
31     v2(k+1) = v2(k) + 0.5*h * (fv1 + fv(x(k+1),v1p));
32 end
33 A = (beta - u1(end)) / v1(end);
34 y = u1 + A*v1;
35 toc
36
37 plot(x,y,'b'); xlabel('x'); ylabel('y(x)'); grid on;
```



```

38 axis([x(1),x(end),-0.15, 0.22]);set(gca,'fontsize',16);
39 legend("FD","Shoot")
40 hold off

```

Elapsed time is 0.005448 seconds.

Elapsed time is 0.011002 seconds.

The solutions are somewhat similar at $h = 0.01$ as seen from the solution and difference plot. Furthermore, the shooting method takes twice the time as the finite difference method at $h = 0.1$. For $h = 0.001$ we have the inverse result.

Elapsed time is 0.013307 seconds.

Elapsed time is 0.006602 seconds.

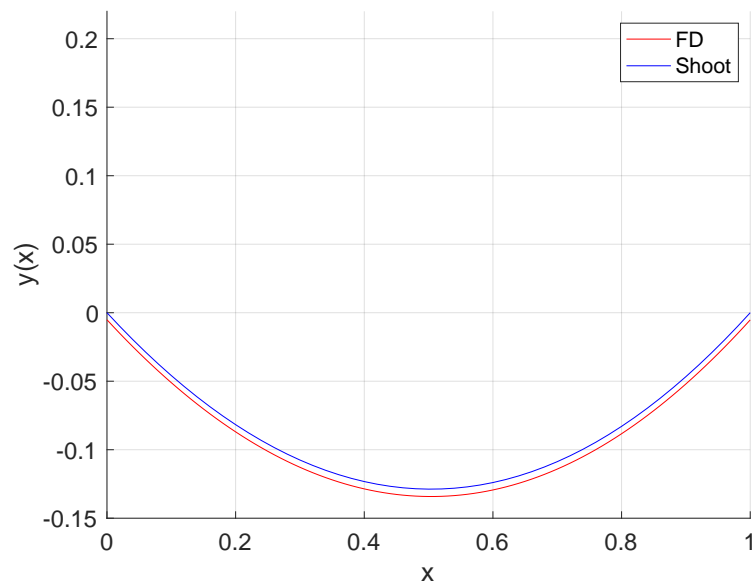


Figure 6: Solutions

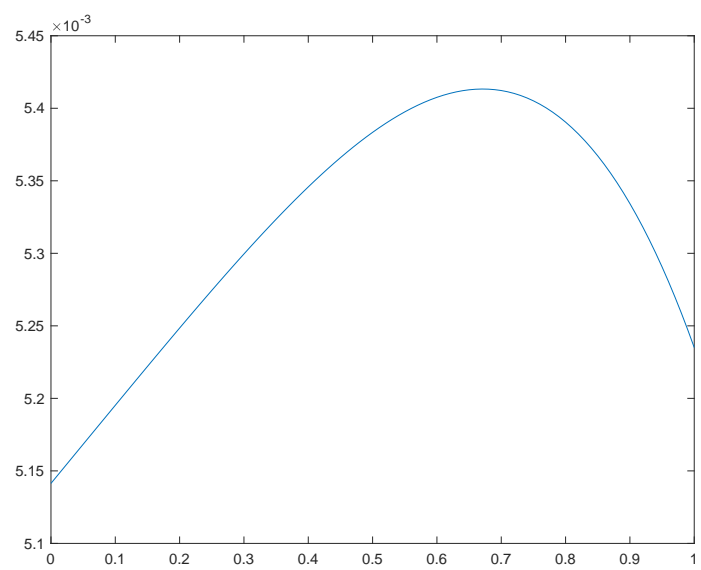


Figure 7: Difference