Final Project of Numerical Linear Algebra course

Crank-Nicolson technique for solving the Schrodinger equation

Sprat in tomato team:

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Problem statement

The time-dependent Schrödinger equation (TDSE) is the fundamental equation of non-relativistic quantum mechanics. The equation has found widespread application in many fields of physical science, for example in atomic, molecular, optical, nuclear and solid-state physics, among others.

$$i\hbar \frac{\partial}{\partial t} \Psi(x,t) = \hat{H} \Psi(x,t)$$



Importance/Relevance

For TDSE, it is challenging to acquire their analytic solutions. A forward difference Euler method has been used to compute the TDSE numerical solutions. Nevertheless, the Euler scheme is instability in some cases. That is why the Crank-Nicolson technique, which is unconditional stable was proposed to overcome this disadvantage



The method itself

The Crank-Nicolson method, when applied to the Schrödinger equation, performs the following approximation at each time step

$$(2 + i\Delta t\mathbf{H}/\hbar)\vec{u}^{j+1} = (2 - i\Delta t\mathbf{H}/\hbar)\vec{u}^{j}.$$

which results in the $(Nx + 1 \times Nx + 1)$ -matrix system

$$\begin{pmatrix} A_1 & 1 & 0 & 0 & \dots \\ 1 & A_2 & 1 & 0 & \dots \\ 0 & 1 & A_2 & 1 & \dots \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & A_{L-1} \end{pmatrix} \begin{pmatrix} \Psi_1^{n+1} \\ \Psi_2^{n+1} \\ \Psi_3^{n+1} \\ \vdots \\ \Psi_{L-1}^{n+1} \end{pmatrix} = \begin{pmatrix} B_1 \\ B_2 \\ B_3 \\ \vdots \\ B_{L-1} \end{pmatrix} \quad \begin{array}{c} \text{Initial state } \Psi_1^O \\ \text{Boundary } \\ \text{conditions } \\ \Psi_0^n, \Psi_L^n \\ \end{pmatrix}$$



Thomas algorithm

Simplified Gaussian elimination, complexity O(n)

Forward step:

$$U_{1} = \frac{1}{A_{1}} \text{ and } R_{1} = B_{1}U_{1}$$

$$U_{i} = \frac{1}{A_{i} - U_{i-1}} \text{ and } R_{i} = (B_{i} - R_{i-1})U_{i}$$

$$\Psi_{i}^{n+1} = \begin{cases} R_{L-1} & i = L - 1 \\ R_{i} - U_{i}\Psi_{i+1}^{n+1} & i < L - 1 \end{cases}$$

Backward step:

$$\Psi_i^{n+1} = \begin{cases} R_{L-1} & i = L-1\\ R_i - U_i \Psi_{i+1}^{n+1} & i < L-1 \end{cases}$$

$$\begin{bmatrix} 1 & U_1 & 0 & \dots & 0 \\ 0 & 1 & U_2 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix} \begin{bmatrix} \Psi_1^{n+1} \\ \Psi_2^{n+1} \\ \Psi_3^{n+1} \\ \dots \\ \Psi_{L-1}^{n+1} \end{bmatrix} = \begin{bmatrix} R_1 \\ R_2 \\ R_3 \\ \dots \\ R_{L-1} \end{bmatrix}$$



Our implementation

Initial condition - Gaussian wave packet:

$$\Psi(t=0) = \frac{1}{\pi^{1/4}\sqrt{\sigma}} \exp\left(\frac{-(x-\mu)^2}{2\sigma^2}\right) \exp\left(ip_0 x/\hbar\right)$$

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x \in [-10,10]

t \in [0,50]

m = 1

\Delta x = 0.1

\Delta t = 0.5

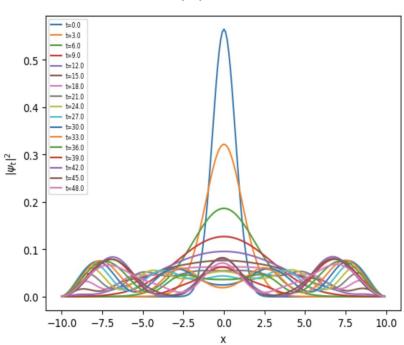
p_0 = 0

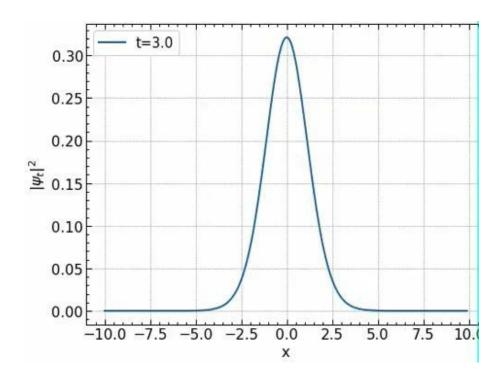
Boundary conditions: \Psi(0, t) = \Psi(L, t) = 0
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Our implementation

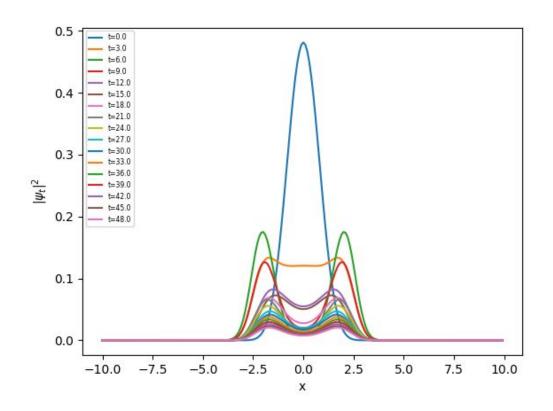
Potential V(x) = 0







Double-well potential



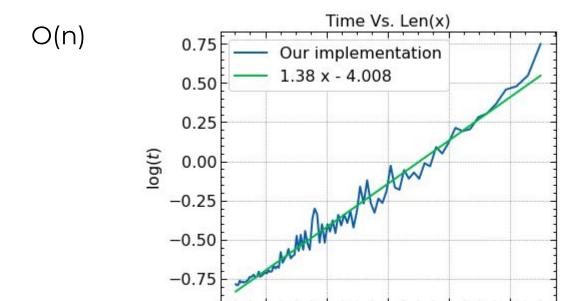
Potential:

$$V(x) = \frac{a}{x_0^4} (x^2 - x_0^2)^2$$



Complexity

Potential V(x) = 0



2.4

2.6

3.0

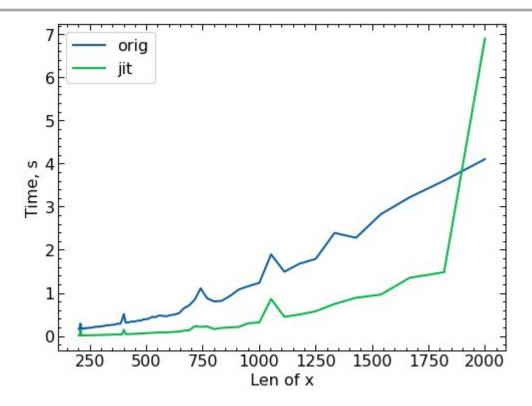
3.2

2.8

log(len(x))



Speed up





2D case

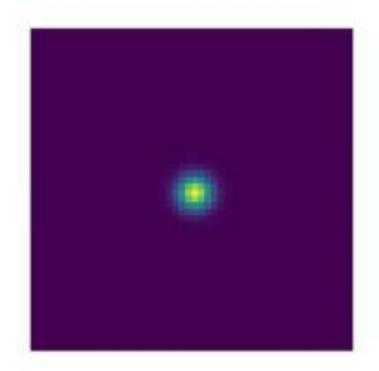
$$\mathbf{A} \cdot \mathbf{x} = \begin{pmatrix} a_{00} & -r_x & 0 & 0 & \cdots & 0 & -r_y & 0 & 0 & \cdots & 0 \\ -r_x & a_{10} & -r_x & 0 & \cdots & 0 & -r_y & 0 & \cdots & 0 \\ 0 & -r_x & a_{20} & -r_x & & & & -r_y & & & \\ 0 & 0 & -r_x & \ddots & \ddots & & & \ddots & \\ \vdots & \vdots & & \ddots & & & & \ddots & \\ 0 & & & & & & & \\ -r_y & 0 & & & & & & \\ 0 & -r_y & & & & & & \\ \vdots & \vdots & & \ddots & & & & & \\ \vdots & \vdots & & \ddots & & & & & \\ \vdots & \vdots & & \ddots & & & & & \\ -r_x & a_{(N-1),(N-1)} & & & & \vdots & \\ \psi^{n+1}_{0,0} & & & & \psi^{n+1}_{1,0} & \\ \psi^{n+1}_{1,0} & & & & & \\ \psi^{n+1}_{1,j} & & & & \\ \vdots & \vdots & & \ddots & & & & \\ \psi^{n+1}_{i,j} & & & & \\ \psi^{n+1}_{i,j} & & & & \\ \psi^{n+1}_{i,j} & & \\ \psi^{n+1}_{i,j} & & & \\ \psi^{n+1}_{i,j} & & & \\ \psi^{n+1}_{i,j} & & \\ \psi^{n+1}_{i,j} & & & \\ \psi^{n+1}_{i,j} & & \\ \psi^{n+1}_{i,j} & & & \\ \psi^{n+1}_{i,j} & & \\ \psi^{n+1}_{i,$$

For 2D problem we have considered a 2-dimensional spatial grid (the xy plane) of N points in the x direction and N points in the y direction.



Our implementation

Time evolution of free potential particle in two-dimensional case:



Literature

- 1. David G. Robertson. "Solving the Time-Dependent Schrodinger Equation."
- 2.Medium: "Quantum Mechanics with Python. Solving the 1D Time Independent Schrödinger Equation Numerically"
- 3.B. Ducomet AND A. Zlotnik "On stability of the Crank-Nicholson scheme with approximate transparent boundary condition for the Schrodinger equation".
- 4.Amin Khan. "Numerical Solution of Schrödinger Equation by Crank–Nicolson Method"



