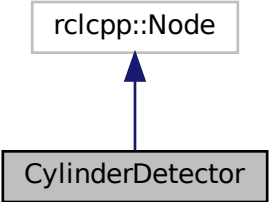


rclcpp::Node



```
graph BT; MissionController[MissionController] --> rclcpp::Node[rclcpp::Node];
```

MissionController