

include/arucoDetector.hpp

```
graph TD; A[include/arucoDetector.hpp] --> B[cv_bridge/cv_bridge.h]; A --> C[opencv2/aruco.hpp]; A --> D[sensor_msgs/image_encodings.hpp];
```

cv_bridge/cv_bridge.h

opencv2/aruco.hpp

sensor_msgs/image_encodings.hpp