## Algorithm 1 NorSand model algorithm

- 1: Assembling the tangent matrix  $D_{ijkl}$
- 2:  $\delta \sigma_{ij} = D_{ijkl} \delta \epsilon_{kl}$
- 3:  $\sigma_{trial} = \sigma + \delta \sigma$

3: 
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4:  $J_2 = \frac{1}{6}((\sigma_{11} - \sigma_{22})^2 + (\sigma_{11} - \sigma_{33})^2 + (\sigma_{33} - \sigma_{22})^2 + 6(\sigma_{12}^2 + \sigma_{23}^2 + \sigma_{33}^2))$   
5:  $p_{trial} = \sigma_i j \delta_{ij} / 3$ ,  $q_{trial} = \sqrt{3J_2}$   
6: Then we going to calculating the yield surface  
7:  $M_i = M_{tc} \cdot (1 - \frac{\chi N |\psi|}{M_{tc}})$ 

- 8:  $p_{max} = p_i \exp\left(\frac{\chi \psi}{M_{tc}}\right)$ 9:  $F = q_{trial} p_{trial} M_i (1 \ln\left(\frac{p_{trial}}{p_i}\right)), F_2 = p_{trial} p_{max}$

Algorithm 2 Procesures to generate the random loading path via gaussian process and principal rotation

Given: Given: The ampltitude for principle strains

**Algorithm 3** Summary of the procedure used to calculate the total stress with regard to the give strain increment

Given: The total stress  $\sigma$ , the total strain  $\epsilon$  at current step, and the accumulated plastic strain  $\epsilon$  (used as the internal variable),  $\Delta \epsilon$  is to be applied to the configuration; Yield function f

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Ensure: f(\boldsymbol{\sigma}, H) \leq 0
 1: \Delta \hat{\sigma} = \mathbf{D}_e \cdot \Delta \epsilon > Calculate the stress increment assuming elastic behavior
 2: \hat{\boldsymbol{\sigma}} = \boldsymbol{\sigma} + \Delta \hat{\sigma}
                                                                                   \triangleright Calculate the trial stress
 3: f(\hat{\boldsymbol{\sigma}})
                     \triangleright Calculate the value of the yield function, with \hat{\sigma} as the state of
      stress,
 4: if f(\hat{\boldsymbol{\sigma}}) \leq 0 then
           \sigma = \hat{\sigma} > The strain increment is elastic. In this case, the trial stress is
      correct; we return.
           return \sigma
 6:
 7: else
           if The previous stress is plastic then
 8:
                                   \triangleright r is the portion of incremental strain taken elastically.
 9:
                 Call Elastoplastic return mapping (\Delta \epsilon^{ep})
10:
                                                       \triangleright There is a transition from elstic to plastic
11:
           else
                 Determine r via F(\boldsymbol{\sigma} + r \cdot \Delta \boldsymbol{\epsilon}) = 0
12:
                 \sigma = \mathbf{D}_{\mathrm{e}} \cdot r \Delta \epsilon
13:
                                                        \triangleright \Delta \epsilon^{ep} is the elastoplastic strain increment
                 \Delta \epsilon^{ep} = (1 - r) \cdot \Delta \epsilon
14:
                 Call Elastoplastic return mapping (\Delta \epsilon^{ep})
15:
16:
17: end if
18: return \sigma
```

Algorithm 4 Elastoplastic return mapping (Convergence of this algorithm needs verification)

Given: The strain increment  $\Delta \epsilon$ , the hardening function  $H(\bar{\epsilon}^p)$ , and the yield

```
function f(\boldsymbol{\sigma}, H)
Ensure: f(\boldsymbol{\sigma}, H) = 0
    1: f_{tol}=1e -2
2: k=1, \sigma_k^{(n+1)}=\sigma^{(n)}+\mathbf{D}_{\mathrm{e}}\Delta\epsilon > Calculate the trial stress as the begining of
             the return mapping iteration
    3: while f(\sigma_k^{(n+1)}, H(\bar{\epsilon}_k^p)) > f_{tol} do \triangleright f = g in Association Flow assumption 4: \mathbf{a}_k = \mathbf{b}_k = (\partial f/\partial \underline{\sigma})_k
                       B_k = \delta \bar{\epsilon}^p / \delta \lambda = \sqrt{2/3} \|\mathbf{a}_k\|
A_k = -\delta f_k / \delta \bar{\epsilon}_k^p \cdot B_k
\delta \lambda = f_k / (\mathbf{a}_k^T \mathbf{D}_e \mathbf{a}_k)
    6:
    7:
                       \delta oldsymbol{\sigma} = -f_k \mathbf{D}_{\mathrm{e}}^{\mathrm{r}} \mathbf{b}_k / \left( A_k + \mathbf{a}_k^{\mathrm{T}} \mathbf{D}_{\mathrm{e}} \mathbf{b}_k \right)
                       \delta \bar{\epsilon}^p = f_k B_k / (A_k + \mathbf{a}_k^T \mathbf{D}_e \mathbf{b}_k)
\boldsymbol{\sigma}_{k+1}^{(n+1)} = \boldsymbol{\sigma}_k^{(n+1)} + \delta \boldsymbol{\sigma}
\bar{\epsilon}_{k+1}^p = \bar{\epsilon}_k^p + \delta \bar{\epsilon}^p
\boldsymbol{\epsilon}_{k+1}^p = \boldsymbol{\epsilon}_k^p + \mathbf{a}_k \delta \lambda
k = k+1
    9:
 10:
 11:
 12:
 13:
 14: end while
15: return \boldsymbol{\sigma}, \boldsymbol{\epsilon}_{k+1}^p, \bar{\epsilon}_{k+1}^p
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