
Algorithm 1 NorSand model algorithm

- 1: Assembling the tangent matrix D_{ijkl}
 - 2: $\delta\sigma_{ij} = D_{ijkl}\delta\epsilon_{kl}$
 - 3: $\sigma_{trial} = \sigma + \delta\sigma$
 - 4: $J_2 = \frac{1}{6}((\sigma_{11} - \sigma_{22})^2 + (\sigma_{11} - \sigma_{33})^2 + (\sigma_{33} - \sigma_{22})^2 + 6(\sigma_{12}^2 + \sigma_{23}^2 + \sigma_{33}^2))$
 - 5: $p_{trial} = \sigma_{ij}\delta_{ij}/3$, $q_{trial} = \sqrt{3J_2}$
 - 6: Then we going to calculating the yield surface
 - 7: $M_i = M_{tc} \cdot (1 - \frac{\chi N|\psi|}{M_{tc}})$
 - 8: $p_{max} = p_i \exp(\frac{\chi\psi}{M_{tc}})$
 - 9: $F = q_{trial} - p_{trial}M_i(1 - \ln(\frac{p_{trial}}{p_i}))$, $F_2 = p_{trial} - p_{max}$
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Algorithm 2 Summary of the procedure used to calculate the total stress with regard to the give strain increment

Require: Given: the total stress σ and the total strain ϵ at current step, $\Delta\epsilon$ is to be applied to the configuration; Yield function F

Ensure: $F(\sigma) \leq 0$

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1:  $\Delta\hat{\sigma} = C_E \cdot \Delta\epsilon$   $\triangleright$  Calculate the stress increment assuming elastic behavior
2:  $\hat{\sigma} = \sigma + \Delta\hat{\sigma}$   $\triangleright$  Calculate the trial stress
3:  $F(\hat{\sigma})$   $\triangleright$  Calculate the value of the yield function, with  $\hat{\sigma}$  as the state of stress,
4: if  $F(\hat{\sigma}) \leq 0$  then
5:    $\sigma = \hat{\sigma}$   $\triangleright$  The strain increment is elastic. In this case, the trial stress is correct; we return.
6:   return  $\sigma$ 
7: else
8:   if The previous stress is plastic then
9:      $r = 0$   $\triangleright r$  is the portion of incremental strain taken elastically.
10:  else  $\triangleright$  There is a transition from elstic to plastic
11:    Determine  $r$  via  $F(\sigma + r \cdot \Delta\epsilon) = 0$ 
12:     $\sigma = C_E \cdot r \Delta\epsilon$ 
13:     $\Delta\epsilon^p = (1 - r) \cdot \Delta\epsilon$   $\triangleright \Delta\epsilon^p$  is the elastoplastic strain increment
14:     $\sigma \leftarrow \sigma + C_{EP} \cdot \Delta\epsilon_i^p$   $\triangleright$  Divide  $\Delta\epsilon^p$  into  $\Delta\epsilon_{0 \sim i}^p$  subincrements and
    iterate
15:  end if
16: end if
17: return  $\sigma$ 

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Algorithm 3 Procesures to generate the random loading path via gaussian process and principal rotation

Require: Given: The amplititude for principle strains

Ensure: $F(\sigma) \leq 0$

- 1: $\Delta\hat{\sigma} = C_E \cdot \Delta\epsilon$ \triangleright Calculate the stress increment assuming elastic behavior
 - 2: $\hat{\sigma} = \sigma + \Delta\hat{\sigma}$ \triangleright Calculate the trial stress
 - 3: $F(\hat{\sigma})$ \triangleright Calculate the value of the yield function, with $\hat{\sigma}$ as the state of stress,
 - 4: **if** $F(\hat{\sigma}) \leq 0$ **then**
 - 5: $\sigma = \hat{\sigma}$ \triangleright The strain increment is elastic. In this case, the trial stress is correct; we return.
 - 6: **else**
 - 7: **if** The previous stress is plastic **then**
 - 8: $r = 0$ $\triangleright r$ is the portion of incremental strain taken elastically.
 - 9: **else** \triangleright There is a transition from elstic to plastic
 - 10: Determine r via $F(\sigma + r \cdot \Delta\epsilon) = 0$
 - 11: $\sigma = C_E \cdot r \Delta\epsilon$
 - 12: $\Delta\epsilon^{ep} = (1 - r) \cdot \Delta\epsilon$ $\triangleright \Delta\epsilon^{ep}$ is the elastoplastic strain increment
 - 13: Call ALGORITHM FOR ELASTOPLASTIC REMAPPING($\Delta\epsilon^{ep}$)
 - 14: **end if**
 - 15: **end if**
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Algorithm 4 Elastoplastic return mapping (Convergence of this algorithm needs verification)

Require: Given: $d\epsilon$, $H(\bar{\epsilon}^p)$, and $f(\sigma, H) = 0$

- 1: $k = 1$, $\sigma^{(n+1,k)} = \sigma^{(n)} + Dd\epsilon$ \triangleright Calculate the trial stress as the begining of the return mapping iteration
 - 2: **while** $f(\sigma^{(n+1,k)}, H(\bar{\epsilon}^p)) > 0$ **do** $\triangleright f = g$ in Association Flow assumption
 - 3: $h = -(\frac{\partial f}{\partial \int |d\bar{\epsilon}^p|} \parallel \frac{\partial f}{\partial \sigma} \parallel)^{(k)}$
 - 4: $d\epsilon^p = (\frac{\frac{\partial f}{\partial \sigma} D \frac{\partial g}{\partial \sigma}}{h + \frac{\partial f}{\partial \sigma} D \frac{\partial g}{\partial \sigma}})^{(k)} d\epsilon$
 - 5: $d\epsilon^p = d\lambda \frac{\partial g}{\partial \sigma}^{(k)}$
 - 6: $\bar{\epsilon}^p{}^{(n+1,k)} = \bar{\epsilon}^p{}^{(n+1,k-1)} + \|d\epsilon^p\|$
 - 7: $\sigma^{(n+1,k)} = \sigma^{(n+1,k-1)} - Dd\epsilon^p$
 - 8: $k++$
 - 9: **end while**
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