

## Paper

## Nonparametric Identification of Dynamic Models with Unobserved State Variables

| Primary   | Comments   |
|---|--|
| <p>This paper proposes a novel method for identifying a hidden Markov process:</p> <ul style="list-style-type: none"> <li>Only 5 observations are needed in non-stationary cases, while only 4 are enough in station cases.</li> <li><math>(W_t, X_t^*)</math> jointly evolves.</li> <li>After the Markov kernel is identified, other relevant quantities can be recovered:<br/><b>Markov Kernel = CCP*State Law of Motion</b></li> <li>Application: dynamic optimization models with unobserved process.</li> <li>Strength: <ul style="list-style-type: none"> <li>Allow time-varying unobserved</li> <li>Evolve depending on past values of observables.</li> </ul> </li> </ul> | <p><i>How to identify other relevant quantities?</i></p> <p><i>Which formulae can illustrate equation (1)</i></p> <p>Why CCP and SLOM can be recovered?</p> <p><i>See Arellano Bonhemme 2017 Review Paper, where more applications and examples are discussed.</i></p> |
| Model   | Comments   |
| <ul style="list-style-type: none"> <li>Observables: two components: action(decision) and state.</li> <li>Eq. 2 and 3.</li> <li>Eq. 7.</li> </ul> $f_{X,Y,Z,S} = \int f_{X X^*,S} f_{X^*,Z,S} f_{Y X^*,Z} dx^*,$ $f_{W_{t+1},W_t,W_{t-1},W_{t-2}} = \int f_{W_{t+1} W_t,X_t^*} f_{W_t W_{t-1},X_t^*} f_{X_t^*,W_{t-1},W_{t-2}} dx_t^*$ $= \int f_{W_{t+1} W_t,X_t^*} f_{W_t,W_{t-1},X_t^*} f_{W_{t-2} X_t^*,W_{t-1}} dx_t^*$   |  |
| Assumptions   | Comments   |
| <p>A1.1. First-order Markovian</p> <p>A1.2. Limited feedback</p> <p>A2. Invertibility. Three injective linear operators.</p> <p>A3. Uniqueness of decomposition.</p> <p>A4. Monotonicity and Normalization.</p> <p>Other assumptions: 1. <math>X_t</math> is scalar and continuous.</p> <p>2. <math>V_t \equiv g_t(W_t)</math>.</p> <p>3. How to connect Carroll's assumptions with those in this paper?</p>  |  |
| Lemmas  | Comments   |

| <ul style="list-style-type: none"> <li>* Lemma 1: Representation of the observed density.</li> <li>* Lemma 2: Representation of the Markov Law of Motion.</li> <li>* Lemma 3: Identification of <math>f_{V_{t+1} W_t, X_t^*}</math>.</li> </ul>  |          |
|--|----------|
| Identification Strategy  | Comments |
| <ol style="list-style-type: none"> <li>1. Based on <i>Hu &amp; Schennach 2008</i> and <i>Carrol 2010</i>.</li> <li>2. Unique spectral decomposition: A1 <math>\rightarrow</math> A4.</li> <li>3. Two step Identification: <ol style="list-style-type: none"> <li>(a) By A1 <math>\rightarrow</math> A4, <math>f_{V_{t+1} W_t, X_t^*}</math> identified.</li> <li>(b) By Lemma 2, the Markov kernel is identified.</li> <li>(c) Identify the joint distribution of the initial condition:<br/><math>f_{W_{t-1}, X_t^*}</math>.</li> </ol> </li> </ol> |          |