1. CITP CAEX Layer Specification

1.1 History

Date	Version	Brief info
2013-06-15	PA1	First prerelease of A draft 1, featuring Live View and Cue Recording messages.
2013-07-13	PA2	Added reply message clarification to the GetLiveViewImage message.
2013-08-03	PA3	Removed trailing copy & paste remark for the RecordCue message.
2013-10-15	PA4	Added new Cue Recording messages for clearing.
2013-11-09	Α	Accepted as version A with the release of Capture Polar 2.11.
2014-10-23	PB1	Added new Show Synchronization messages.
2015-01-21	PB2	Polished Show Synchronization messages.
2015-05-07	В	Accepted as version B with the release of Capture Argo 21.0.
2015-10-25	PC1	First prerelease of C draft 1, featuring laser feeds.
2015-11-02	PC2	Changed laser feed frames to be sent over UDP and added data packing.
2015-11-06	С	Accepted as version C with the release of Capture Argo 21.1.20.

1.2 Introduction

The CITP/CAEX "Capture Extensions" layer is a set of networking messages implemented as a private CITP (http://www.citp-protocol.org) layer. This document could be interpreted as an addendum to the CITP protocol specification.

2. Header and NACK message

Most messages in CAEX are of request/reply nature, although some messages may be sent unsoliticed. Capture will honor the CITP header RequestIndex and InResponseTo fields if they are set, allowing the peer to correlate replies to responses.

2.1 The CAEX header

The CAEX layer provides a standard, single, header used at the start of all CAEX packets:

Unlike other CITP messages, CAEX doesn't use ASCII-form 32-bit integers to identify messages, but rather standard numeric 32-bit integers.

2.2 CAEX / NACK message

This message must be sent by Capture or a peer in response to any unknown message or any request that prompts a reply which cannot be served. The CITP header RequestIndex and InResponseTo fields must be honored when sending this message.

3. Live View messages

Capture allows a peer to interact with one of its views in live mode. If no view is in live mode, these features will not be available. If multiple views are in live mode, the first view in live mode will be the one with which the peer can interact.

3.1 CAEX / GetLiveViewStatus message

This message is sent to Capture as a request for a LiveViewStatus reply.

```
CITP_CAEX_GetLiveViewStatus
{
    CITP_CAEX_Header CITPCAEXHeader // CITP CAEX header, ContentCode = 0x00000100.
}
```

3.2 CAEX / LiveViewStatus message

This message is sent by Capture in reply to a GetLiveViewStatus message.

```
CITP CAEX LiveViewStatus
{
   CITP_CAEX_Header
                      CITPCAEXHeader
                                           // CITP CAEX header, ContentCode = 0x00000101.
   uint8
                      Availability
                                           // 0x00 = Not available.
                                           // 0x01 = Alpha view available.
                                           // 0x02 = Beta view available.
                                           // 0x03 = Gamma view available.
                                          // The width and height of the view.
   uint16[2]
                      Size
                                       // The XYZ position of the camera.
                      CameraPosition
   float[3]
                                           // The XYZ focus of the camera.
   float[3]
                      CameraFocus
}
```

Note: The purpose of sending the camera position and focus is so that the peer can use this as default when requesting live images.

3.3 CAEX / GetLiveViewImage message

This message is sent to Capture as a request for a LiveViewImage reply.

```
CITP CAEX GetLiveViewImage
{
   CITP CAEX Header CITPCAEXHeader
                                           // CITP CAEX header, ContentCode = 0x00000200.
   uint8
                      Format
                                          // 0x01 = JPEG
                                          // The width and height requested.
   uint16[2]
                      Resolution
                      CameraPosition
   float[3]
                                          // The position of the camera, as XYZ.
                      CameraFocus
                                          // The focus of the camera, as XYZ.
   float[3]
}
```

Note: If the peer requests a resolution higher than the current size of the view, Capture will return an image with the current size of the view. If no live view is available, Capture will reply with a 'Refused' NACK.

3.4 CAEX / LiveViewImage message

This message is sent by Capture in reply to a GetLiveViewImage message.

4. Cue Recording messages

Capture allows a peer with cue recording capabilities to expose some amount of remote control of its 'recording unit' / 'programmer'.

4.1 CAEX / SetCueRecordingCapabilities message

This message is sent to Capture in order to enable or disable remote cue recording.

```
CITP_CAEX_SetCueRecordingCapabilities
{
    CITP_CAEX_Header
                      CITPCAEXHeader
                                            // CITP CAEX header, ContentCode = 0x00010100.
    uint8
                      Availability
                                            // 0x00 = Not available
                                           // 0x01 = Available
    uint8
                      OptionCount
                                           // The number of options that follow.
       ucs2
                          Name
                                           // The name of the option.
                                           // Tab ('\t') separated list of choices.
      ucs2
                          Choices
       ucs2
                          Help
                                           // An optional explanation/description.
    }[OptionCount]
}
```

Note: The abscence of choices for an option denotes a free text field.

4.2 CAEX / RecordCue message

This message is sent unsolicited by Capture when the user records a cue.

4.3 CAEX / SetRecorderClearingCapabilities message

This message is sent to Capture in order to enable or disable remote clearing of the recorder.

4.4 CAEX / ClearRecorder message

This message is sent unsolicited by Capture when the user wishes to clear the state of the recorder.

5. Show Synchronization messages

The Show Synchronization messages allow a peer to exchange patch, selection and fixture status information with Capture.

In order for the user experience to be smooth and seamless, it is necessary to communicate "show state" information with Capture. The following are the rules of interaction:

- Capture will send EnterShow and LeaveShow messages as projects are opened and closed, given that the user has enabled the "console link" with the peer. If "console link" is disabled and then reenabled, Capture will act as if the project was closed and opened again. Always keep track of whether Capture is currently in a show or not.
- · When opening or creating a new show: send an EnterShow message to Capture.
- When opening or creating a new show and Capture is currently in a show: send a patch information request to Capture.
- When closing a show: send a LeaveShow message to Capture.
- When in a show and Capture enters a show: send a patch information request to Capture.
- If the user chooses to disable synchronization: act as if the user had closed the show.
- If the user chooses to reenable synchronization: act as if the user had just opened the current show.

It is important that the peer, upon receving complete patch information when both the peer and Capture have entered a show, provides the user with the means to determine whether the patch is in sync and/or requires modification, as well as the option to disable the synchronization.

5.1 CAEX / EnterShow message

This message is sent unsolicited by both Capture and the peer when a show/project is opened and/or the user wishes to enable show synchronization.

5.2 CAEX / LeaveShow message

This message is sent unsolicited by both Capture and the peer when a show/project is closed or when the user wishes to disable show synchronization.

5.3 CAEX / FixtureListRequest message

This message can be sent unsolicited by Capture or a peer in order to acquire the full patch list from the other side. The expected response is a FixtureList message with Type = 0x00.

```
CITP_CAEX_FixtureListRequest
{
    CITP_CAEX_Header CITPCAEXHeader // CITP CAEX header, ContentCode = 0x000202000.
}
```

5.4 CAEX / FixtureList message

This message is sent in response to a FixtureListRequest message (with Type = 0x00) as well as unsolicited by both Capture and the peer (with Type = 0x01 or Type = 0x02). An existing patch fixture list (Type = 0x00) must contain all known fixtures while a new fixture (Type = 0x01) or exchanged fixture (Type = 0x02) message contains only the fixture(s) that were recently added or exchanged for other fixtures.

```
uint16
                  FixtureCount
                                              // Number of fixtures following.
   uint32
                      FixtureIdentifer
                                              // Console's fixture identifier.
                                              // Set to 0xffffffff if unknown by Capture.
                                              // The name of the fixture's manufacturer.
                      ManufacturerName
   ucs2
   ucs2
                      FixtureName
                                             // The model name of the fixture.
                                              // The name of DMX mode.
   ucs2
                      ModeName
   uint16
                      ChannelCount
                                             // The number of channels of the DMX mode.
   uint8
                      IsDimmer
                                             // A boolean 0x00 or 0x01 indicating whether it's.
                                             // a dimmer (only) fixture or not.
   uint8
                      IdentifierCount
                                              // The number of following identifier blocks.
      uint8
                                              // 0x00 = RDMDeviceModelId (uint16)
                         IdentifierType
                                              // 0x01 = RDMPersonalityId (uint64)
                                              // 0x02 = AtlaBaseFixtureId (quid)
                                              // 0x03 = AtlaBaseModeId (quid)
                         IdentifierDataSize
                                             // The size of the data following.
     uint16
                         IdentifierData
                                             // Identifier type specific data.
      uint8[]
   }[IdentifierCount]
                      Patched
                                              // A boolean 0x00 or 0x01 indicating whether the
                                              // the fixture is patched or not.
                                             // The (0-based) universe index.
   uint8
                      Universe
   uint16
                      UniverseChannel
                                             // The (0-based) DMX channel.
                                             // The unit number.
   ucs2
                      Unit
                                             // The channel number.
                      Channel
   uint16
                     Circuit
                                             // The circuit number.
   ucs2
                                             // Any notes.
   ucs2
                     Note
                                            // The 3D position.
   float[3]
                      Position
                                             // The 3D angles.
   float[3]
                      Angles
}[FixtureCount]
```

5.5 CAEX / FixtureModify message

}

This message is sent unsolicited by both Capture and the peer whenever a fixture has been modified. All fields must always be present, but it is important that the ChangedFields field indicates which have actually been modified.

```
CITP_CAEX_FixtureModify
   CITP_CAEX_Header
                      CITPCAEXHeader
                                               // CITP CAEX header, ContentCode = 0x00020202.
   uint16
                      FixtureCount
                                               // The number of fixtures following.
      uint32
                         FixtureIdentifier
                                               // Console's fixture identifier.
      uint8
                         ChangedFields
                                               // Bitmask indicating which of the following fields have changed.
                                               // As in FixtureList. (ChangedFields & 0x01).
      uint8
                         Patched
      uint8
                         Universe
                                               // As in FixtureList. (ChangedFields & 0x01).
                         UniverseChannel
      uint16
                                               // As in FixtureList. (ChangedFields & 0x01).
                         Unit
                                               // As in FixtureList. (ChangedFields & 0x02).
      ucs2
      uint16
                         Channel
                                               // As in FixtureList. (ChangedFields & 0x04).
                                               // As in FixtureList. (ChangedFields & 0x08).
                         Circuit
      ucs2
                                              // As in FixtureList. (ChangedFields & 0x10).
      ucs2
                         Note
      float[3]
                         Position
                                              // As in FixtureList. (ChangedFields & 0x20).
                                               // As in FixtureList. (ChangedFields & 0x20).
      float[3]
                         Angles
   }[FixtureCount]
}
```

5.6 CAEX / FixtureRemove message

This message is sent unsolicited by both Capture and the peer whenever on or more fixture(s) have been removed.

5.7 CAEX / FixtureSelection message

This message is sent unsolicited by by both Capture and the peer to inform the other side of a new fixture selection. Note that the order of the fixture identifiers should carry the order in which the fixture(s) were selected.

5.8 CAEX / FixtureConsoleStatus message

This message is sent unsolicited by the peer to Capture in order to convey "live information" data that can be displayed by Capture.

```
CITP_CAEX_FixtureConsoleStatus
                                             // CITP CAEX header, ContentCode = 0x00020400.
   CITP CAEX Header CITPCAEXHeader
                                             // The number of fixtures following.
   uint16
                      FixtureCount
      uint32
                         FixtureIdentifier // Console's fixture identifiers.
                                           // The fixture has been locked from manipulation.
      uint8
                         Locked
      uint8
                         Clearable
                                             // The fixture has a clearable programmer state.
   }[FixtureCount]
}
```

6. Laser feed messages

A peer may serve laser feeds to Capture. Information to Capture about which feeds are available and information from Capture about which feeds to transmit is sent over the TCP based CITP session. Actual feed frame data is transmitted to the UDP based CITP multicast address.

In order for Capture to be able to correlate the feed frames with the appropriate session, a process instance unique and random "source key" is to be generated by the laser controller.

6.1 CAEX / GetLaserFeedList message

This message is sent by Capture upon connection to determine what laser feeds are available. Receving this message is an indication of Capture's ability to understand CAEX laser feeds.

6.2 CAEX / LaserFeedList message

This message can be sent to Capture both in response to a GetLaserFeedList message as well as unsolicited if the list of available laser feeds has changed.

```
CITP_CAEX_LaserFeedList
    CITP CAEX Header
                      CITPCAEXHeader
                                           // CITP CAEX header, ContentCode = 0x00030101.
    uint32
                       SourceKey
                                           // The source key used in frame messages.
   uint8
                       FeedCount
                                           // The number of laser feed listings that follow.
    {
       ucs2
                                           // The name of the feed.
                          Name
    }[FeedCount]
}
```

6.3 CAEX / LaserFeedControl message

This message is sent by Capture to indicate whether it wishes a laser feed to be transmitted or not. The frame rate can be seen as an indication of the maximum frame rate meaningful to Capture.

6.4 CAEX / LaserFeedFrame message

This message is sent unsolicited to Capture, carrying feed frame data.

```
CITP CAEX LaserFeedFrame
    CITP_CAEX_Header
                       CITPCAEXHeader
                                            // CITP CAEX header, ContentCode = 0x00030200.
    uint32
                                            // The source key as in the LaserFeedList message.
                       SourceKey
    uint8
                       FeedIndex
                                            // The 0-based index of the feed.
                                           // A 0-based sequence number for out of order data detection.
    uint32
                       FrameSequenceNo
    uint16
                       PointCount
                                            // The number of points that follow.
       uint8
                         XLowByte
                                           // The low byte of the x coordinate.
                         YLowByte
                                           // The low byte of the y coordinate.
       uint8
       uint8
                         XYHighNibbles
                                           // The high nibbles of the x and y coordinates.
                                            // The colour packed as R5 G6 B5.
       uint16
                         Color
    }[PointCount]
}
Such that:
    Point.X [0, 4093] = Point.XLowByte + (Point.XYHighNibbles & 0x0f) << 8
    Point.Y [0, 4093] = Point.YLowByte + (Point.XYHighNibbles & 0xf0) << 4
    Point.R [0, 31] = Point.Color & 0x001f
    Point.G [0, 63] = (Point.Color & 0x07e0) >> 5
    Point.B [0, 31] = (Point.Color & 0xf800) >> 11
```