

# ANA LUCIA CRUZ RUIZ R&D Robotics Engineer

## PROFILE

Robotics R&D engineer interested in the development of smart motion control solutions for industrial and service robots.

# SKILLS

- Machine learning
- Robot control algorithms
- Robot kinematic and dynamic analvsis
- Programming:
  - . MATLAB
  - . Python
  - . C++
- Dynamic simulations:
  - . Simulink
  - . V-rep
- Mechanical design:
  - . Autodesk Inventor
  - . CATIA

## LANGUAGES

- English (Bilingual C2)
- Spanish (Native)
- French (Advanced C1)
- Italian (Intermediate B2)

## AWARDS

Fondation Centrale Scholarship Speech at Les Invalides, Paris

#### INTERESTS

- Robot control
- > Popularization of technology among the general public
- > Planification of interactive robotics workshops for children
- > Playing piano (classical, pop/rock)

# CONTACT



+33652655658



analu.610@gmail.com



in linkedin.com/in/acruzruiz



www.analuciacruz.me



France

## **EDUCATION**

PhD in Mechanics

INRIA, ENS Rennes, France

2013-2016

Master's degree in Control Engineering, Robotics and Applied Informatics - Focus: Advanced Robotics

École Centrale de Nantes, France

2011-2013

Bachelor's degree in Mechatronics

Universidad Tecnológica Centroamericana 2007-2011

# PROFESSIONAL EXPERIENCE

#### Robotics R&D engineer (Internship)

IRCCyN // France // 2013 (6 months)

Development of software tools to automate the design and analysis of robots (cable-driven robots for different industrial tasks) by using new performance evaluation criteria.

#### Mechatronics engineer

3D Solutions // Honduras // 2010 (6 months)

Design of 3D models of plastic products according to client specifications. Assistant in the manufacturing of aluminum molds for the fabrication of plastic products.

## **PROJECTS**

Machine learning based control strategies for a redundant virtual arm

(MATLAB, Simulink, SimMechanics, V-rep, C++)

Automation of industrial task with stäubli RX90/PUMA robots (V+, Val II)

Toolbox: Simulation of the kinematics and sensors of mobile robots

(MATLAB, Simulink)

ARACHNIS: A GUI for the design of cable-driven parallel robots (MATLAB)

Design of a 3-DoF planar parallel robot (MATLAB, CATIA)

## PRESENTATIONS

Speaker at the "International Girls in ICT Day Event" Inter. Telecommunications Union // Honduras // 2016

Speaker at an event by IEEE/WIE (Women in Engineering) WIE, UNITEC // Honduras // 2016

Speaker at the event "Just like robotics, you have a great future" École centrale de Nantes// France // 2016