



ANA LUCIA CRUZ RUIZ

Robotics Engineer &
Science Communicator

CONTACT

- +33652655658
- analu.610@gmail.com
- linkedin.com/in/acruzruiz
- www.analuciacruz.me
- France

PROFILE

Robotics engineer interested in the development of smart motion control solutions and the popularization of science and technology.

SKILLS

- **ROBOTICS**
 - Machine learning
 - Robot control algorithms
 - Robot kinematic analysis
 - Robot dynamic analysis
 - Programming:
 - . MATLAB
 - . Python
 - . C++
 - Dynamic simulations:
 - . Simulink
 - . V-rep
 - Mechanical design:
 - . Autodesk Inventor
 - . CATIA
- **WRITING & COMMUNICATION**
 - Instructive speaker
 - Clear and concise writer
 - Effective listener
 - Attentive to detail
 - Organized
 - Versatile

EDUCATION

Robotics Nanodegree Udacity	2017--Now
Machine Learning Coursera	01-03/2017
PhD in Control and Signal Processing INRIA, ENS Rennes, France	2013-2016
Master's degree in Advanced Robotics École Centrale de Nantes, France	2011-2013
Bachelor's degree in Mechatronics Universidad Tecnológica Centroamericana	2007-2011

PROFESSIONAL EXPERIENCE

○ ROBOTICS ENGINEER

Robotics R&D engineer (Internship)

IRCCyN & Laval Univ. // France // 2013 (6 months)
Development of software tools to automate the design and analysis of robots by using new performance evaluation criteria. Creation of technical documentation and user manuals.

Mechatronics engineer

3D Solutions // Honduras // 2010 (6 months)
Design of 3D models of plastic products according to client specifications. Assistant in the manufacturing of aluminum molds for the fabrication of plastic products.

○ TECHNICAL WRITER/COMMUNICATOR

Scientific writer/ reviewer

IRCCyN, INRIA // France // 2013-2016
Writer and reviewer of scientific articles within the scope of my PhD degree. Publications and presentations of conference, journal, and state-of-the-art papers in domains ranging from robotics, to biomechanics, and animation.

Speaker at the "International Girls in ICT Day Event"

Inter. Telecommunications Union // Honduras // 2016

Speaker at an event by IEEE/WIE (Women in Engineering)

WIE, UNITEC // Honduras // 2016

Speaker at the event "Just like robotics, you have a great future"

École centrale de Nantes // France // 2016

Teacher/Tutor Computer Science, Math, Physics, English

Middle school/Personal Tutoring // Honduras // 2006-2011

Translator "Honduras this Week" journal

Honduras this week // Honduras // 2005

ANA LUCIA CRUZ RUIZ

LANGUAGES

ENGLISH (Near native - C2)

SPANISH (Native)

FRENCH (Advanced - C1)

ITALIAN (INTERMEDIATE - B2)

AWARDS


Fondation Centrale Scholarship
Nantes // France // 2012

Speech CIC Bank's Ceremony
Les Invalides // France // 2012

INTERESTS

- Robotics
- Popularization of science and technology
- Planification of interactive robotics workshops for children
- Playing piano (classical, pop/rock)

REFERENCES

 STEPHANE CARO, *IRCCyN*
Stephane.Caro@irccyn.ec-nantes.fr

 PHILIPPE CARDOU, *LAVAL UNIV.*
Philippe.Cardou@gmc.ulaval.ca

 CHARLES PONTONNIER, *ENS*
charles.pontonnier@irisa.fr

PROJECTS

Machine learning-based control strategies for virtual characters
(MATLAB, Simulink, SimMechanics, V-rep, C++)

Automation of industrial task with stäubli RX90/PUMA robots
(V+, Val II)

Toolbox: Simulation of the kinematics and sensors of mobile robots
(MATLAB, Simulink)

ARACHNIS: A GUI for the design of cable-driven parallel robots
(MATLAB)

Design of a 3-DoF planar parallel robot
(MATLAB, CATIA)

PUBLICATIONS

A synergy-based control solution for overactuated characters: application to throwing

Computer Animation and Virtual Worlds // 2016

Muscle-based control for character animation

Computer Graphics Forum // 2016

Motion control via muscle synergies: Application to throwing

8th ACM SIGGRAPH Conf. on Motion in Games // 2015

Identifying representative muscle synergies in overhead football throws

CMBBE // 2015

A bio-inspired limb controller for avatar animation

CMBBE // 2014

ARACHNIS: Analysis of Robots Actuated by Cables with Handy and Neat Interface Software

Second International Conference on Cable-Driven Parallel Robots // 2014

Measuring how well a structure supports varying external wrenches

Second Conference in New Advances in Mechanisms, Transmissions and Applications // 2013



ACRUZRUIZ



ANALU.610@GMAIL.COM



ANALU610