



# ANA LUCIA CRUZ RUIZ

## R&D Robotics Engineer

### PROFILE

Robotics R & D engineer interested in the development of smart motion control solutions for industrial and service robots.

### SKILLS

- Robot kinematic and dynamic analysis
- Machine learning
- Robot control algorithms
- Programming:
  - MATLAB
  - Python
  - C++
- Dynamic simulations:
  - Simulink
  - V-rep
- Mechanical design:
  - Autodesk Inventor
  - CATIA

### LANGUAGES

- English (Bilingual - C2)
- Spanish (Native)
- French (Advanced - C1)
- Italian (Intermediate - B2)

### INTERESTS

- Popularization of technology among the general public
- Planification of interactive robotics workshops for children
- Playing piano (classical, pop/rock)

### CONTACT

☎ +33652655658

✉ [analuc.610@gmail.com](mailto:analuc.610@gmail.com)

in [linkedin.com/in/acruzruiz](https://www.linkedin.com/in/acruzruiz)

🌐 [www.analuciacruz.me](http://www.analuciacruz.me)

📍 France

### EDUCATION

#### PhD in Mechanics

INRIA, ENS Rennes, France

2013-2016

#### Master's degree in Control Engineering, Robotics and Applied Informatics – Focus: Advanced Robotics

École Centrale de Nantes, France

2011-2013

#### Bachelor's degree in Mechatronics

Universidad Tecnológica Centroamericana

2007-2011

### PROFESSIONAL EXPERIENCE

#### Mechanical designer of parallel robots (Internship)

IRCCyN // France // 2013 (6 months)

Development of a graphical user interface to automate the design and analysis of cable-driven robots for different industrial tasks.

#### Mechanical designer and manufacturing assistant

3D Solutions // Honduras // 2010 (6 months)

Design of 3D models of plastic products according to client specifications. Assistant in the manufacturing of aluminum moulds for the fabrication of plastic products.

### PROJECTS

#### Machine learning based control strategies for a redundant virtual arm

(MATLAB, Simulink, SimMechanics, V-rep, C++)

#### Automation of industrial task with stäubli RX90/PUMA robots

(V+, Val II)

#### Toolbox: Simulation of the kinematics and sensors of mobile robots

(MATLAB, Simulink)

#### ARACHNIS: A GUI for the design of cable-driven parallel robots

(MATLAB)

#### Design of a 3-DoF planar parallel robot

(MATLAB, CATIA)