



AMERICAN INTERNATIONAL UNIVERSITY – BANGLADESH (AIUB)

Faculty of Engineering

Department of Electrical and Electronic Engineering

Course/Lab Name: EEE4103 Microprocessor and Embedded Systems

Semester: Summer 2023-24 Term: Final Quiz: 01F Total Marks: 10 Time: 20 Minutes

Question Mapping with Course Outcomes:

Item	COs	POIs	K	P	A	Marks	Obtained Marks
Q1-2	CO1	P.a.4.C.3	K4			2×5	
Total:						10	

Student Information:

Student Name:	Solve Sheet	Section:	D
Student ID #:	Solve Sheet	Date:	11.09.2024
		Department:	

1. **Compute** the baud rate for the asynchronous normal operating mode when the oscillator frequency, f_{osc} [5]
= 16 MHz, and register data is, $UBRRn = 000110101010$. **Compute** the baud error and **comment** on whether there will be any communication errors. Standard Baud rates are 300, 600, 1200, 2400, 4800, 9600, 14400, 19200, 38400, 57600, 115200, 230400, ... bps.

Answer:

$$UBRRn = 000110101010 = 0 \times 2^{11} + 0 \times 2^{10} + 0 \times 2^9 + 1 \times 2^8 + 1 \times 2^7 + 0 \times 2^6 + 1 \times 2^5 + 0 \times 2^4 + 1 \times 2^3 + 0 \times 2^2 + 1 \times 2^1 + 0 \times 2^0 \\ = 256 + 128 + 32 + 8 + 2 = 426$$

$$\text{For the asynchronous normal operating mode, Baud Rate} = \frac{f_{osc}}{16(UBRRn+1)} = \frac{16 \times 10^6}{16(426+1)} = 2342 \text{ bps}$$

$$\text{Baud Error Rate, } \varepsilon = \frac{\text{Standard baud rate} - \text{calculated baud rate}}{\text{Standard baud rate}} \times 100\% = \frac{1200 - 2342}{1200} \times 100\% = -2.42\%$$

This value is $> 2\%$, therefore, there will be communication errors.

2. For the following program, **show** the output on the serial monitor if the shutter remains open for [5]
5 ms. **Determine** the baud rate and pin number at which the interrupt arrived.

```
volatile boolean started;
volatile unsigned long startTime;
volatile unsigned long endTime;

void shutter() { // interrupt service routine named shutter started
    if (started)
        endTime = micros();
    else
        startTime = micros();
    started = !started; } // end of the ISR named shutter

void setup() {
    Serial.begin(57600);
    Serial.println("Shutter test ...");
    attachInterrupt(digitalPinToInterrupt(3), shutter, CHANGE);
} // end of the setup

void loop() {
    if (endTime) {
        Serial.print("Shutter open for ");
        Serial.print(endTime - startTime);
        Serial.println(" microseconds.");
        endTime = 0; } // end of if statement
} // end of the loop
```

Answer:

Shutter test ...

Shutter open for 5000 microseconds.

From this command in the code, `Serial.begin(57600);`

We find the baud rate is 57600 bps

From this command in the code, `digitalPinToInterrupt(3),`

We find that at pin number 3, the interrupt has arrived.