

Chapter 6: CPU Scheduling





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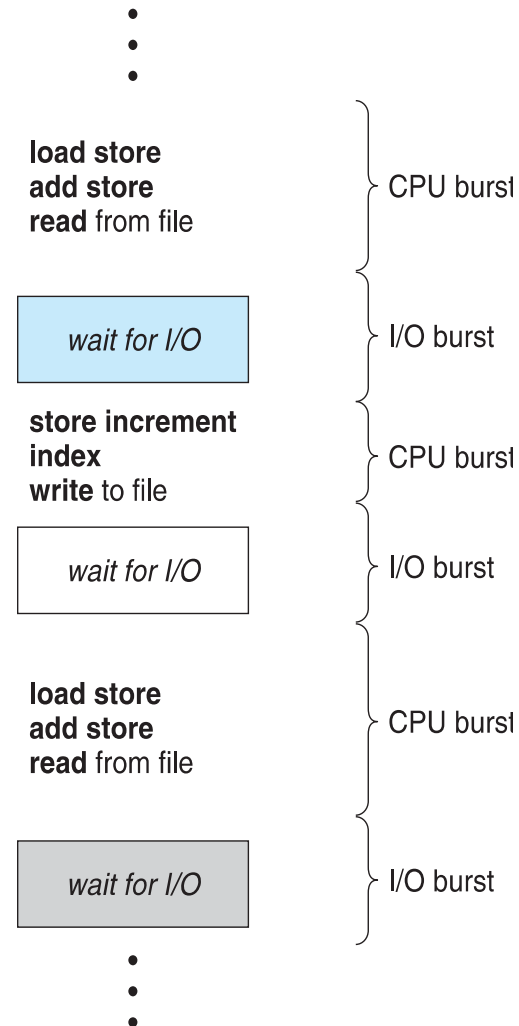
- Basic Concepts
- Scheduling Criteria
- Scheduling Algorithms
- Thread Scheduling
- Multiple-Processor Scheduling
- Real-Time CPU Scheduling
- Operating Systems Examples
- Algorithm Evaluation





Basic Concepts

- Maximum CPU utilization obtained with multiprogramming
- CPU–I/O Burst Cycle – Process execution consists of a **cycle** of CPU execution and I/O wait
- **CPU burst** followed by **I/O burst**
- CPU burst distribution is of main concern





CPU Scheduler

- **Short-term scheduler** selects from among the processes in ready queue, and allocates the CPU to one of them
 - Queue may be ordered in various ways





Dispatcher

- Dispatcher module gives control of the CPU to the process selected by the short-term scheduler; this involves:
 - switching context
 - switching to user mode
 - jumping to the proper location in the user program to restart that program
- **Dispatch latency** – time it takes for the dispatcher to stop one process and start another running





Scheduling Criteria

- **CPU utilization** – keep the CPU as busy as possible
- **Throughput** – # of processes that complete their execution per time unit
- **Turnaround time** – amount of time to execute a particular process
- **Waiting time** – amount of time a process has been waiting in the ready queue
- **Response time** – amount of time it takes from when a request was submitted until the first response is produced, not output (for time-sharing environment)

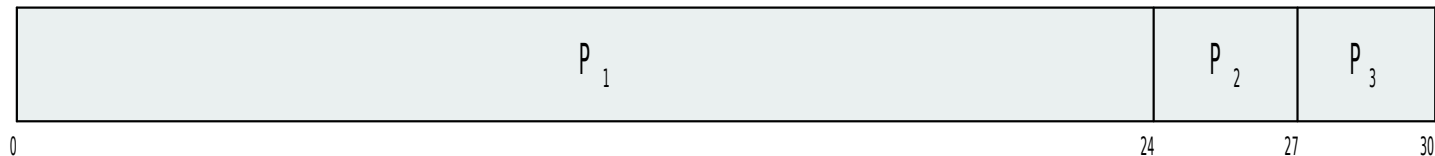




First- Come, First-Served (FCFS) Scheduling

<u>Process</u>	<u>Burst Time</u>
P_1	24
P_2	3
P_3	3

- Suppose that the processes arrive in the order: P_1 , P_2 , P_3
The Gantt Chart for the schedule is:



- Waiting time for $P_1 = 0$; $P_2 = 24$; $P_3 = 27$
- Average waiting time: $(0 + 24 + 27)/3 = 17$





FCFS Scheduling (Cont.)

Suppose that the processes arrive in the order:

$$P_2, P_3, P_1$$

- The Gantt chart for the schedule is:



- Waiting time for $P_1 = 6$; $P_2 = 0$; $P_3 = 3$
- Average waiting time: $(6 + 0 + 3)/3 = 3$
- Much better than previous case
- **Convoy effect** - short process behind long process
 - Consider one CPU-bound and many I/O-bound processes





Shortest-Job-First (SJF) Scheduling

- Associate with each process the length of its next CPU burst
 - Use these lengths to schedule the process with the shortest time
- SJF is optimal – gives minimum average waiting time for a given set of processes
 - The difficulty is knowing the length of the next CPU request
 - Could ask the user

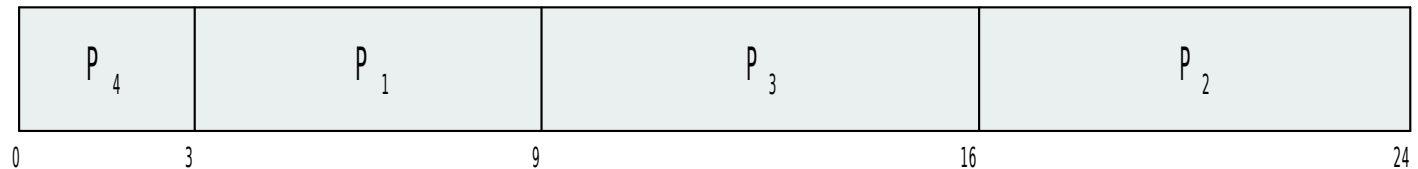




Example of SJF

<u>Process</u>	<u>Burst Time</u>
P_1	6
P_2	8
P_3	7
P_4	3

■ SJF scheduling chart



■ Average waiting time = $(3 + 16 + 9 + 0) / 4 = 7$





Determining Length of Next CPU Burst

- Can only estimate the length – should be similar to the previous one
 - Then pick process with shortest predicted next CPU burst
- Can be done by using the length of previous CPU bursts, using exponential averaging
 1. t_n = actual length of n^{th} CPU burst
 2. τ_{n+1} = predicted value for the next CPU burst
 3. $\alpha, 0 \leq \alpha \leq 1$
 4. Define : $\tau_{n+1} = \alpha t_n + (1 - \alpha)\tau_n$.
- Commonly, α set to $\frac{1}{2}$
- Preemptive version called **shortest-remaining-time-first**





Examples of Exponential Averaging

■ $\alpha = 0$

- $\tau_{n+1} = \tau_n$
- Recent history does not count

■ $\alpha = 1$

- $\tau_{n+1} = \alpha t_n$
- Only the actual last CPU burst counts

■ If we expand the formula, we get:

$$\begin{aligned}\tau_{n+1} = & \alpha t_n + (1 - \alpha)\alpha t_{n-1} + \dots \\ & + (1 - \alpha)^j \alpha t_{n-j} + \dots \\ & + (1 - \alpha)^{n+1} \tau_0\end{aligned}$$

- ## ■ Since both α and $(1 - \alpha)$ are less than or equal to 1, each successive term has less weight than its predecessor



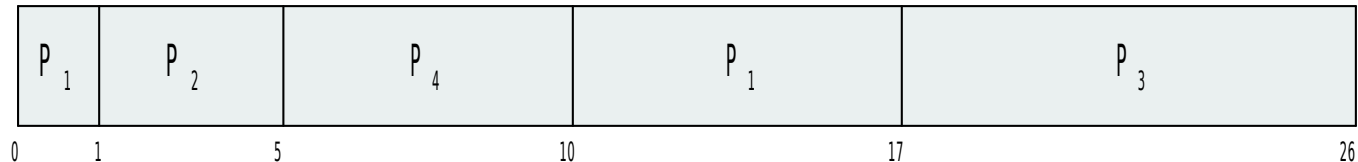


Example of Shortest-remaining-time-first

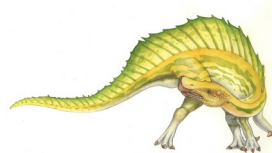
- Now we add the concepts of varying arrival times and preemption to the analysis

	<u>Process</u>	<u>Arrival Time</u>	<u>Burst Time</u>
P_1	0	8	
P_2	1	4	
P_3	2	9	
P_4	3	5	

- Preemptive* SJF Gantt Chart



- Average waiting time = $[(10-1)+(1-1)+(17-2)+5-3]/4 = 26/4 = 6.5$ msec





Priority Scheduling

- A priority (integer) is associated with each process
- The CPU is allocated to the process with the highest priority (smallest integer \equiv highest priority)
 - Preemptive
 - Nonpreemptive
- SJF is priority scheduling where priority is the inverse of predicted next CPU burst time
- Problem \equiv **Starvation** – low priority processes may never execute
- Solution \equiv **Aging** – as time progresses increase the priority of the process





Example of Priority Scheduling

	<u>Process</u>	<u>Burst Time</u>	<u>Priority</u>
P_1	10	3	
P_2	5	1	
P_3	2	4	
P_4	1	5	
P_5	5	2	

- Priority scheduling Gantt Chart (P_5 not shown, and P_2 time changed from 1 to 5 according to Gantt chart)



(Check for yourself)

- Average waiting time = 8.2 msec





Round Robin (RR)

- Each process gets a small unit of CPU time (**time quantum** q), usually 10-100 milliseconds. After this time has elapsed, the process is preempted and added to the end of the ready queue.
- If there are n processes in the ready queue and the time quantum is q , then each process gets $1/n$ of the CPU time in chunks of at most q time units at once. No process waits more than $(n-1)q$ time units.
- Timer interrupts every quantum to schedule next process
- Performance
 - q large \Rightarrow FIFO
 - q small $\Rightarrow q$ must be large with respect to context switch, otherwise overhead is too high





Example of RR with Time Quantum = 4

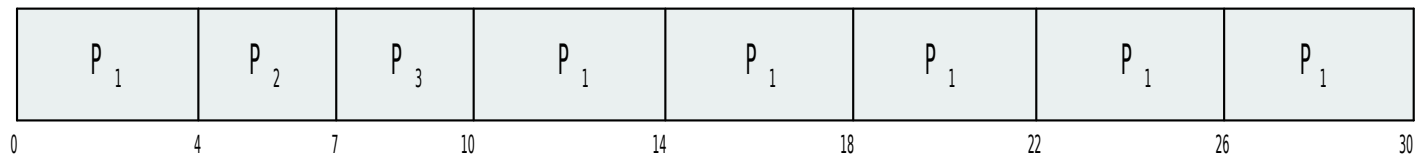
<u>Process</u>	<u>Burst Time</u>
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P_1	24
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P_2	3
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P_3	3
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- The Gantt chart is:

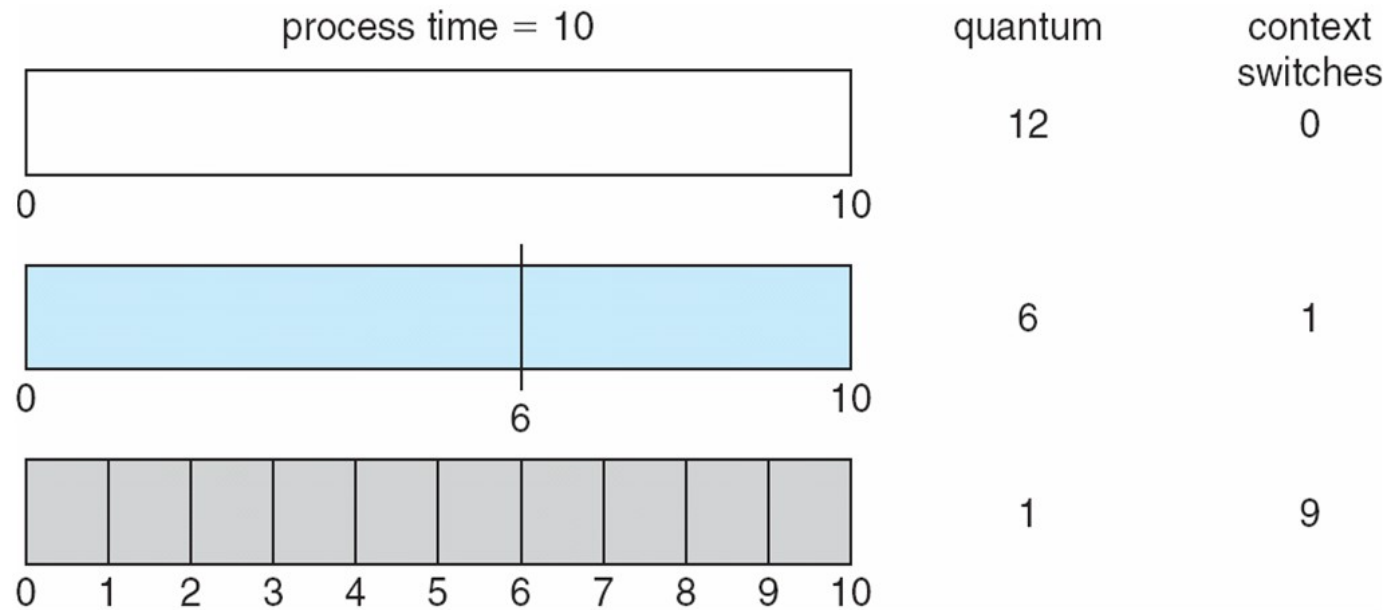


- Typically, higher average turnaround than SJF, but better **response**
- q should be large compared to context switch time
- q usually 10ms to 100ms, context switch < 10 usec





Time Quantum and Context Switch Time





Multilevel Queue

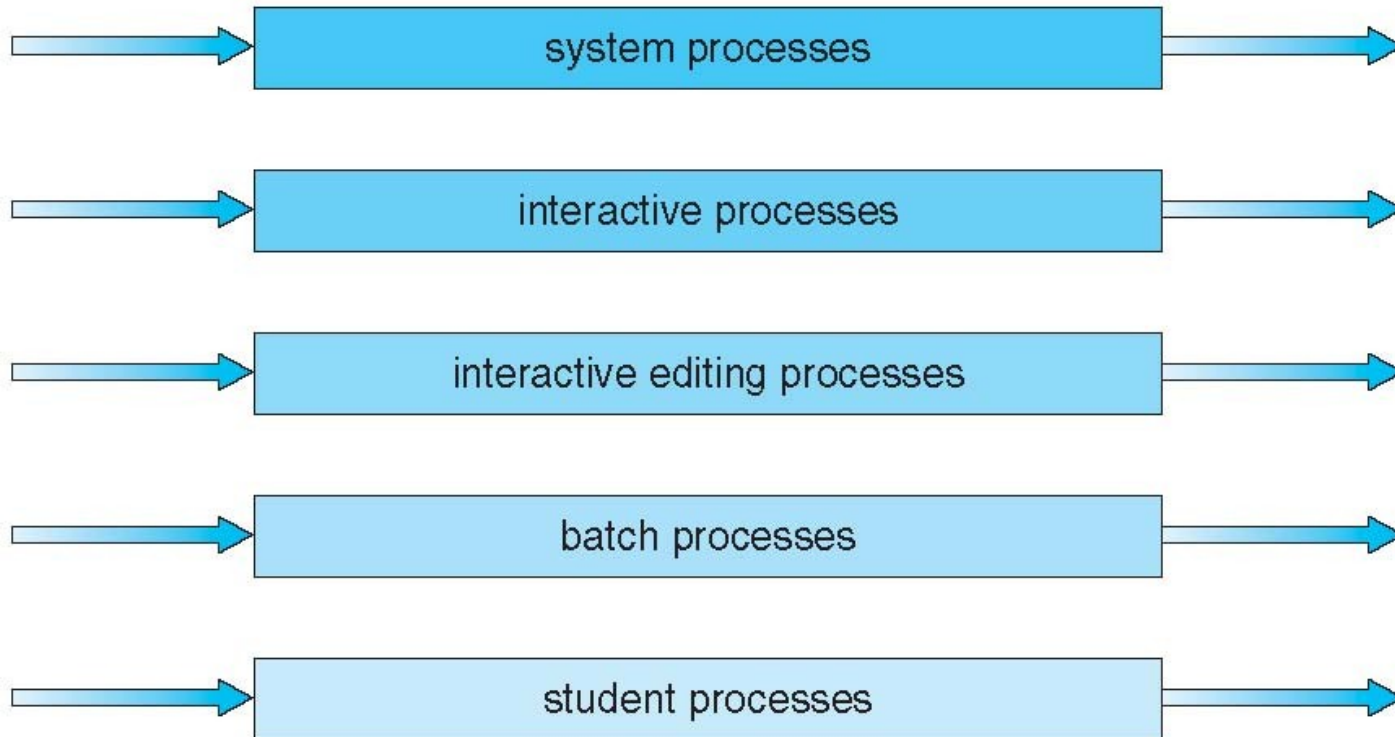
- Ready queue is partitioned into separate queues, eg:
 - **foreground** (interactive)
 - **background** (batch)
- Process permanently in a given queue
- Each queue has its own scheduling algorithm:
 - foreground – RR
 - background – FCFS
- Scheduling must be done between the queues:
 - Fixed priority scheduling; (i.e., serve all from foreground then from background).
 - Time slice – each queue gets a certain amount of CPU time which it can schedule amongst its processes; i.e., 80% to foreground in RR
 - 20% to background in FCFS





Multilevel Queue Scheduling

highest priority



lowest priority





Multilevel Feedback Queue

- A process can move between various queues; aging can be implemented this way
- Multilevel-feedback-queue scheduler defined by the following parameters:
 - number of queues
 - scheduling algorithms for each queue
 - method used to determine when to upgrade a process
 - method used to determine when to demote a process





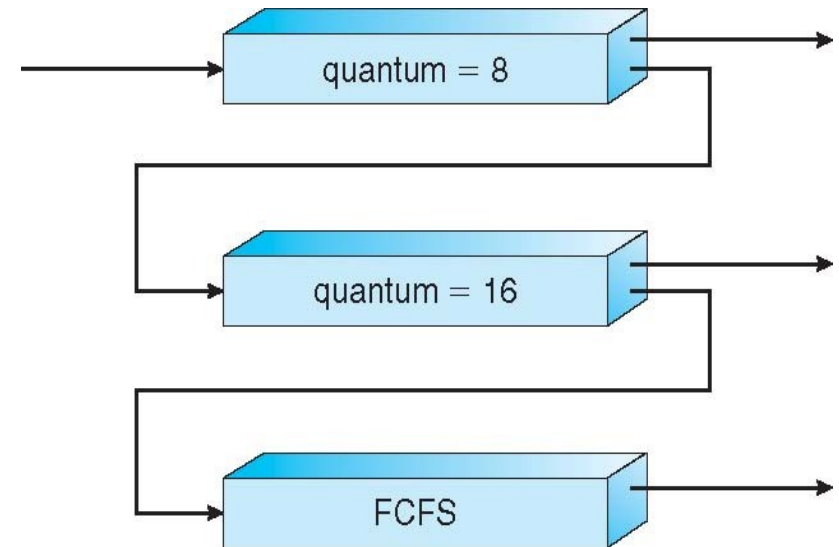
Example of Multilevel Feedback Queue

■ Three queues:

- Q_0 – RR with time quantum 8 milliseconds
- Q_1 – RR time quantum 16 milliseconds
- Q_2 – FCFS

■ Scheduling

- A new job enters queue Q_0 which is served **FCFS?? [RR]**
 - ▶ When it gains CPU, job receives 8 milliseconds
 - ▶ If it does not finish in 8 milliseconds, job is moved to queue Q_1
- At Q_1 job is again served **FCFS?? [RR]** and receives 16 [additional] milliseconds
 - ▶ If it still does not complete, it is preempted and moved to queue Q_2



End of Chapter 6

