# **Chapter 6: CPU Scheduling**

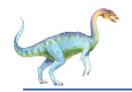




#### **Chapter 6: CPU Scheduling**

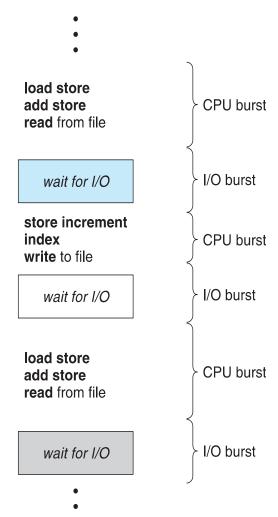
- Basic Concepts
- Scheduling Criteria
- Scheduling Algorithms
- Thread Scheduling
- Multiple-Processor Scheduling
- Real-Time CPU Scheduling
- Operating Systems Examples
- Algorithm Evaluation





#### **Basic Concepts**

- Maximum CPU utilization obtained with multiprogramming
- CPU-I/O Burst Cycle Process execution consists of a cycle of CPU execution and I/O wait
- CPU burst followed by I/O burst
- CPU burst distribution is of main concern







#### **CPU Scheduler**

- Short-term scheduler selects from among the processes in ready queue, and allocates the CPU to one of them
  - Queue may be ordered in various ways





#### **Dispatcher**

- Dispatcher module gives control of the CPU to the process selected by the short-term scheduler; this involves:
  - switching context
  - switching to user mode
  - jumping to the proper location in the user program to restart that program
- Dispatch latency time it takes for the dispatcher to stop one process and start another running





## **Scheduling Criteria**

- ☐ **CPU utilization** keep the CPU as busy as possible
- Throughput # of processes that complete their execution per time unit
- Turnaround time amount of time to execute a particular process
- Waiting time amount of time a process has been waiting in the ready queue
- Response time amount of time it takes from when a request was submitted until the first response is produced, not output (for time-sharing environment)





#### First-Come, First-Served (FCFS) Scheduling

<u>Process</u>	Burst Time
$P_1$	24
$P_2$	3
$P_3$	3

Suppose that the processes arrive in the order:  $P_1$ ,  $P_2$ ,  $P_3$ The Gantt Chart for the schedule is:

	P <sub>1</sub>	P <sub>2</sub>	P <sub>3</sub>
0	24	2	7 30

- □ Waiting time for  $P_1 = 0$ ;  $P_2 = 24$ ;  $P_3 = 27$
- □ Average waiting time: (0 + 24 + 27)/3 = 17





# FCFS Scheduling (Cont.)

Suppose that the processes arrive in the order:

$$P_2$$
,  $P_3$ ,  $P_1$ 

The Gantt chart for the schedule is:



- □ Waiting time for  $P_1 = 6$ ;  $P_2 = 0$ ;  $P_3 = 3$
- □ Average waiting time: (6 + 0 + 3)/3 = 3
- Much better than previous case
- Convoy effect short process behind long process
  - Consider one CPU-bound and many I/O-bound processes





# **Shortest-Job-First (SJF) Scheduling**

- Associate with each process the length of its next CPU burst
  - Use these lengths to schedule the process with the shortest time
- □ SJF is optimal gives minimum average waiting time for a given set of processes
  - The difficulty is knowing the length of the next CPU request
  - Could ask the user

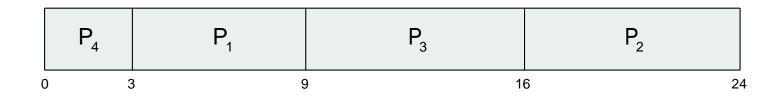




### **Example of SJF**

<u>Process</u>	Burst Time
$P_1$	6
$P_2$	8
$P_3$	7
$P_4$	3

□ SJF scheduling chart



 $\square$  Average waiting time = (3 + 16 + 9 + 0) / 4 = 7



# **Determining Length of Next CPU Burst**

- Can only estimate the length should be similar to the previous one
  - Then pick process with shortest predicted next CPU burst
- Can be done by using the length of previous CPU bursts, using exponential averaging
  - 1.  $t_n = \text{actual length of } n^{th} \text{ CPU burst}$
  - 2.  $\tau_{n+1}$  = predicted value for the next CPU burst
  - 3.  $\alpha$ ,  $0 \le \alpha \le 1$
  - 4. Define:  $\tau_{n+1} = \alpha t_n + (1-\alpha)\tau_n.$
- $\square$  Commonly,  $\alpha$  set to  $\frac{1}{2}$
- □ Preemptive version called shortest-remaining-time-first





## **Examples of Exponential Averaging**

$$\square$$
  $\alpha = 0$ 

- $\Box$   $\tau_{n+1} = \tau_n$
- Recent history does not count
- $\square$   $\alpha = 1$ 
  - $\sigma_{n+1} = \alpha t_n$
  - Only the actual last CPU burst counts
- ☐ If we expand the formula, we get:

$$\tau_{n+1} = \alpha t_n + (1 - \alpha)\alpha t_{n-1} + \dots + (1 - \alpha)^j \alpha t_{n-j} + \dots + (1 - \alpha)^{n+1} \tau_0$$

Since both  $\alpha$  and  $(1 - \alpha)$  are less than or equal to 1, each successive term has less weight than its predecessor



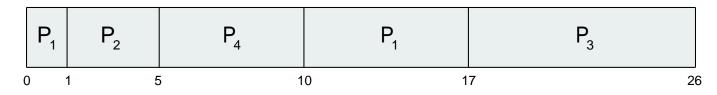


#### **Example of Shortest-remaining-time-first**

Now we add the concepts of varying arrival times and preemption to the analysis

<u>Process</u>	<u>Arrival Time</u>	<b>Burst Time</b>
$P_1$	0	8
$P_2$	1	4
$P_3$	2	9
$P_4$	3	5

Preemptive SJF Gantt Chart



Average waiting time = [(10-1)+(1-1)+(17-2)+5-3)]/4 = 26/4 = 6.5 msec





## **Priority Scheduling**

- A priority (integer) is associated with each process
- □ The CPU is allocated to the process with the highest priority (smallest integer = highest priority)
  - Preemptive
  - Nonpreemptive
- SJF is priority scheduling where priority is the inverse of predicted next CPU burst time
- □ Problem = Starvation low priority processes may never execute
- Solution ≡ Aging as time progresses increase the priority of the process





#### **Example of Priority Scheduling**

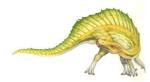
<u>Process</u>	<b>Burst Time</b>	<u>Priority</u>
$P_1$	10	3
$P_2$	5	1
$P_3$	2	4
$P_4$	1	5
$P_5$	5	2

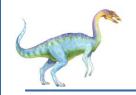
□ Priority scheduling Gantt Chart ( $P_5$  not shown, and  $P_2$  time changed from 1 to 5 according to Gantt chart)



(Check for yourself)

□ Average waiting time = 8.2 msec

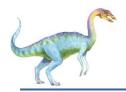




## Round Robin (RR)

- Each process gets a small unit of CPU time (time quantum q), usually 10-100 milliseconds. After this time has elapsed, the process is preempted and added to the end of the ready queue.
- ☐ If there are *n* processes in the ready queue and the time quantum is *q*, then each process gets 1/*n* of the CPU time in chunks of at most *q* time units at once. No process waits more than (*n*-1)*q* time units.
- ☐ Timer interrupts every quantum to schedule next process
- Performance
  - □ q large  $\Rightarrow$  FIFO

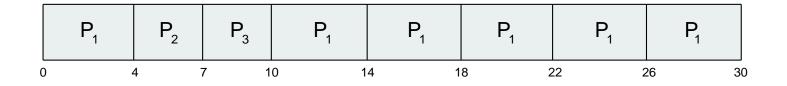




## **Example of RR with Time Quantum = 4**

<u>Process</u>	<b>Burst Time</b>
$P_1$	24
$P_2$	3
$P_3$	3

The Gantt chart is:

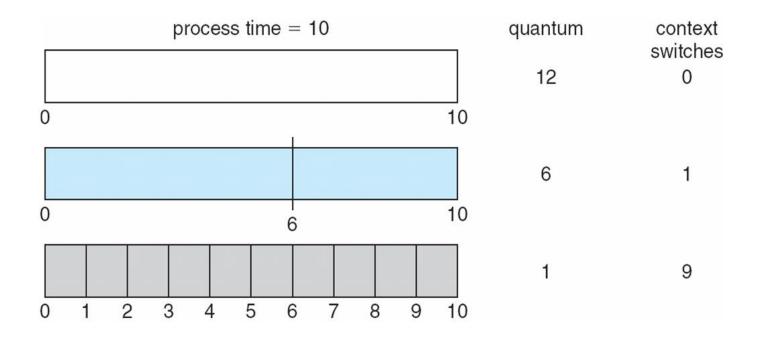


- Typically, higher average turnaround than SJF, but better response
- q should be large compared to context switch time
- □ q usually 10ms to 100ms, context switch < 10 usec





#### **Time Quantum and Context Switch Time**







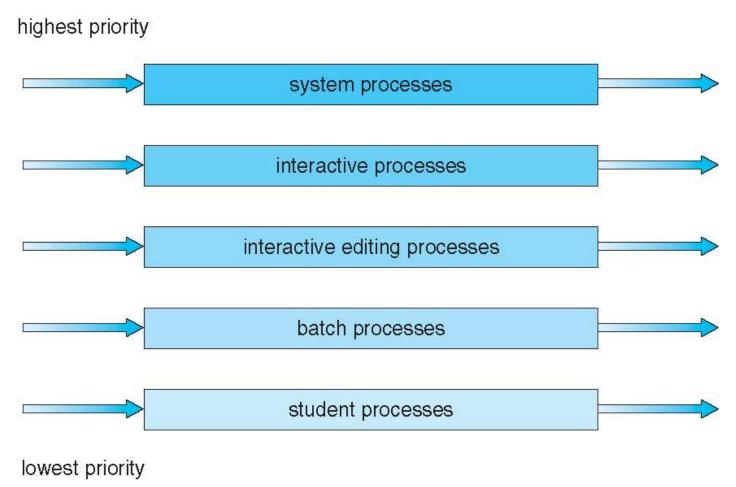
#### **Multilevel Queue**

- □ Ready queue is partitioned into separate queues, eg:
  - foreground (interactive)
  - background (batch)
- Process permanently in a given queue
- Each queue has its own scheduling algorithm:
  - foreground RR
  - background FCFS
- Scheduling must be done between the queues:
  - Fixed priority scheduling; (i.e., serve all from foreground then from background).
  - Time slice each queue gets a certain amount of CPU time which it can schedule amongst its processes; i.e., 80% to foreground in RR
  - 20% to background in FCFS





# Multilevel Queue Scheduling





#### **Multilevel Feedback Queue**

- A process can move between various queues; aging can be implemented this way
- Multilevel-feedback-queue scheduler defined by the following parameters:
  - number of queues
  - scheduling algorithms for each queue
  - method used to determine when to upgrade a process
  - method used to determine when to demote a process





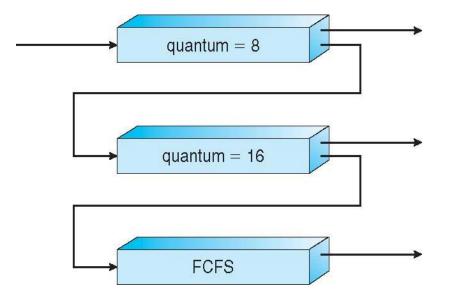
#### **Example of Multilevel Feedback Queue**

#### Three queues:

- Q<sub>0</sub> RR with time quantum 8 milliseconds
- $Q_1$  RR time quantum 16 milliseconds
- $Q_2 FCFS$

#### Scheduling

- A new job enters queue Q<sub>0</sub> which is served FCFS?? [RR]
  - When it gains CPU, job receives 8 milliseconds
  - If it does not finish in 8 milliseconds, job is moved to queue Q<sub>1</sub>
- At Q<sub>1</sub> job is again served FCFS?? [RR] and receives 16 [additional]
  milliseconds
  - If it still does not complete, it is preempted and moved to queue Q<sub>2</sub>





# **End of Chapter 6**

