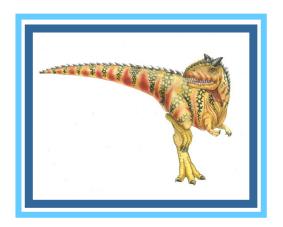
Chapter 6: CPU Scheduling





Chapter 6: CPU Scheduling

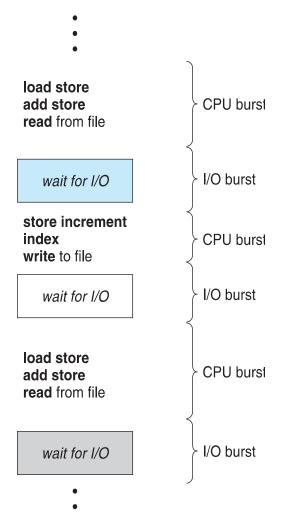
- Basic Concepts
- Scheduling Criteria
- Scheduling Algorithms
- Thread Scheduling
- Multiple-Processor Scheduling
- Real-Time CPU Scheduling
- Operating Systems Examples
- Algorithm Evaluation





Basic Concepts

- Maximum CPU utilization obtained with multiprogramming
- CPU-I/O Burst Cycle Process execution consists of a cycle of CPU execution and I/O wait
- CPU burst followed by I/O burst
- CPU burst distribution is of main concern







CPU Scheduler

- Short-term scheduler selects from among the processes in ready queue, and allocates the CPU to one of them
 - Queue may be ordered in various ways





Dispatcher

- Dispatcher module gives control of the CPU to the process selected by the short-term scheduler; this involves:
 - switching context
 - switching to user mode
 - jumping to the proper location in the user program to restart that program
- Dispatch latency time it takes for the dispatcher to stop one process and start another running





Scheduling Criteria

- **CPU utilization** keep the CPU as busy as possible
- Throughput # of processes that complete their execution per time unit
- Turnaround time amount of time to execute a particular process
- Waiting time amount of time a process has been waiting in the ready queue
- Response time amount of time it takes from when a request was submitted until the first response is produced, not output (for time-sharing environment)





First-Come, First-Served (FCFS) Scheduling

<u>Process</u>	Burst Time
P_1	24
P_2	3
P_3	3

Suppose that the processes arrive in the order: P_1 , P_2 , P_3 The Gantt Chart for the schedule is:

P 1	P 2	P 3
0	27	30

- Waiting time for $P_1 = 0$; $P_2 = 24$; $P_3 = 27$
- Average waiting time: (0 + 24 + 27)/3 = 17





FCFS Scheduling (Cont.)

Suppose that the processes arrive in the order:

$$P_2$$
, P_3 , P_1

The Gantt chart for the schedule is:



- Waiting time for $P_1 = 6$; $P_2 = 0$; $P_3 = 3$
- Average waiting time: (6 + 0 + 3)/3 = 3
- Much better than previous case
- Convoy effect short process behind long process
 - Consider one CPU-bound and many I/O-bound processes





Shortest-Job-First (SJF) Scheduling

- Associate with each process the length of its next CPU burst
 - Use these lengths to schedule the process with the shortest time
- SJF is optimal gives minimum average waiting time for a given set of processes
 - The difficulty is knowing the length of the next CPU request
 - Could ask the user





Example of SJF

Process

Burst Time

P_1	6
P_2	8
P_3	7
P_{4}	3

SJF scheduling chart



• Average waiting time = (3 + 16 + 9 + 0) / 4 = 7





Determining Length of Next CPU Burst

- Can only estimate the length should be similar to the previous one
 - Then pick process with shortest predicted next CPU burst
- Can be done by using the length of previous CPU bursts, using exponential averaging
 - 1. t_n =actual length of n^{th} CPU burst
 - 2. τ_{n+1} =predicted value for the next CPU burst
 - 3. α , $0 \le \alpha \le 1$
 - 4. Define: $\tau_{n+1} = \alpha t_n + (1 \alpha)\tau_n$.
- Commonly, α set to $\frac{1}{2}$
- Preemptive version called shortest-remaining-time-first





Examples of Exponential Averaging

- $\alpha = 0$
 - $\tau_{n+1} = \tau_n$
 - Recent history does not count
- $\alpha = 1$
 - $\tau_{n+1} = \alpha t_n$
 - Only the actual last CPU burst counts
- If we expand the formula, we get:

$$\tau_{n+1} = \alpha t_n + (1 - \alpha)\alpha t_{n-1} + \dots + (1 - \alpha)^{j}\alpha t_{n-j} + \dots + (1 - \alpha)^{n+1}\tau_0$$

Since both α and $(1 - \alpha)$ are less than or equal to 1, each successive term has less weight than its predecessor





Example of Shortest-remaining-time-first

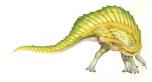
Now we add the concepts of varying arrival times and preemption to the analysis

	<u>Process</u>	<u>Arrival Time</u>	Burst Time
P_1	0	8	
P_2	1	4	
P_3	2	9	
P_4	3	5	

Preemptive SJF Gantt Chart

	P 1	P 2	P ₄	P 1	P ₃
0	1	. 5	10	17	26

Average waiting time = [(10-1)+(1-1)+(17-2)+5-3)]/4 = 26/4 = 6.5 msec

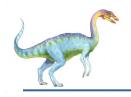




Priority Scheduling

- A priority (integer) is associated with each process
- The CPU is allocated to the process with the highest priority (smallest integer ≡ highest priority)
 - Preemptive
 - Nonpreemptive
- SJF is priority scheduling where priority is the inverse of predicted next CPU burst time
- Problem = Starvation low priority processes may never execute
- Solution ≡ Aging as time progresses increase the priority of the process





Example of Priority Scheduling

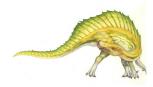
	<u>Process</u>	Burst Time	<u>Priority</u>
P_1	10	3	
P_2	5	1	
P_3	2	4	
P_4	1	5	
P_5	5	2	

Priority scheduling Gantt Chart (P_5 not shown, and P_2 time changed from 1 to 5 according to Gantt chart)



(Check for yourself)

Average waiting time = 8.2 msec

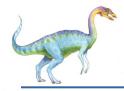




Round Robin (RR)

- Each process gets a small unit of CPU time (time quantum q), usually 10-100 milliseconds. After this time has elapsed, the process is preempted and added to the end of the ready queue.
- If there are *n* processes in the ready queue and the time quantum is *q*, then each process gets 1/*n* of the CPU time in chunks of at most *q* time units at once. No process waits more than (*n*-1)*q* time units.
- Timer interrupts every quantum to schedule next process
- Performance
 - q large ⇒ FIFO
 - q small ⇒ q must be large with respect to context switch, otherwise overhead is too high

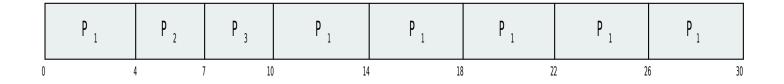




Example of RR with Time Quantum = 4

<u>Process</u>	Burst Time
P_1	24
P_2	3
P_3	3

The Gantt chart is:



- Typically, higher average turnaround than SJF, but better response
- q should be large compared to context switch time
- q usually 10ms to 100ms, context switch < 10 usec</p>





Time Quantum and Context Switch Time

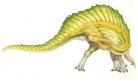
			pr	oces	s tim	e = 1	10			_	quantum	context switches
											12	0
0										10		
											6	1
0						6				10		
											1	9
0	1	2	3	4	5	6	7	8	9	10		





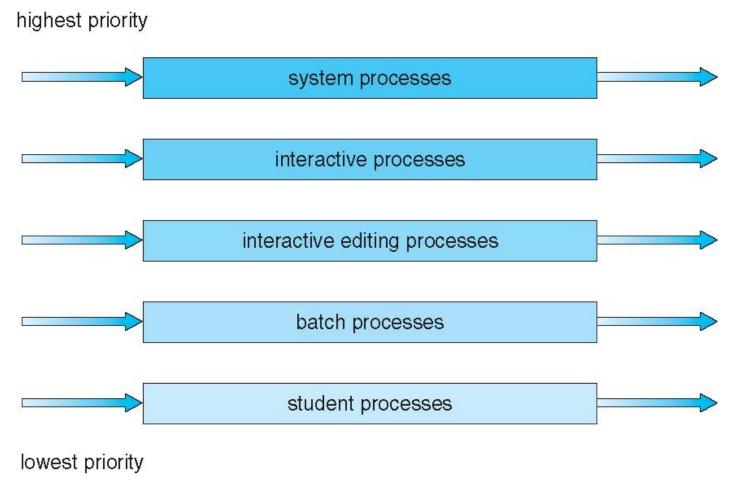
Multilevel Queue

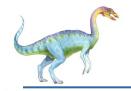
- Ready queue is partitioned into separate queues, eg:
 - foreground (interactive)
 - background (batch)
- Process permanently in a given queue
- Each queue has its own scheduling algorithm:
 - foreground RR
 - background FCFS
- Scheduling must be done between the queues:
 - Fixed priority scheduling; (i.e., serve all from foreground then from background).
 - Time slice each queue gets a certain amount of CPU time which it can schedule amongst its processes; i.e., 80% to foreground in RR
 - 20% to background in FCFS





Multilevel Queue Scheduling





Multilevel Feedback Queue

- A process can move between various queues; aging can be implemented this way
- Multilevel-feedback-queue scheduler defined by the following parameters:
 - number of queues
 - scheduling algorithms for each queue
 - method used to determine when to upgrade a process
 - method used to determine when to demote a process





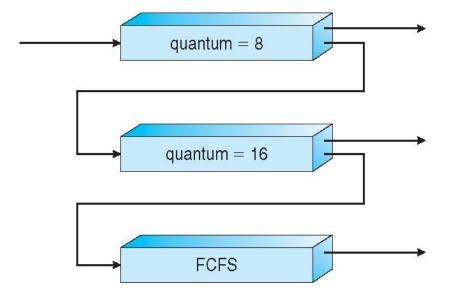
Example of Multilevel Feedback Queue

Three queues:

- Q₀ RR with time quantum 8 milliseconds
- Q_1 RR time quantum 16 milliseconds
- $Q_2 FCFS$

Scheduling

- A new job enters queue Q_0 which is served FCFS?? [RR]
 - When it gains CPU, job receives 8 milliseconds
 - If it does not finish in 8 milliseconds, job is moved to queue Q₁
- At Q₁ job is again served FCFS?? [RR] and receives 16 [additional] milliseconds
 - If it still does not complete, it is preempted and moved to queue Q2





End of Chapter 6

