

FER 2

Električni krugovi

Teorija Linija

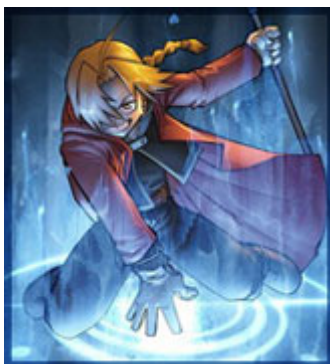
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christair



TEORIJA LINIJA

$$\frac{\partial^2 i(x,t)}{\partial x^2} = LC \cdot \frac{\partial^2 i(x,t)}{\partial t^2} + (LG + RC) \cdot \frac{\partial i(x,t)}{\partial t} + RG \cdot i(x,t)$$

$$\frac{\partial^2 u(x,t)}{\partial x^2} = LC \cdot \frac{\partial^2 u(x,t)}{\partial t^2} + \frac{\partial u(x,t)}{\partial t} + RG \cdot u(x,t)$$

LAPLACE:

$$\frac{d^2 U(x,s)}{dx^2} = (R+sL)(G+sC) \cdot U(x,s)$$

$$\frac{d^2 I(x,s)}{dx^2} = (R+sL)(G+sC) \cdot I(x,s)$$

$$\gamma^2 = (R+sL) \cdot (G+sC)$$

FAKTOR PRIDENOSA (PROPAGACIJE)
HOMOGENE LINIJE

REŠENJE DIF. JEDNAŽBE:

$$U(x,s) = A \cdot e^{\gamma x}$$

$$\gamma^2 - \gamma^2 = 0$$

$$\gamma_{1,2} = \pm \gamma$$

$$U(x,s) = A_1 \cdot e^{-\gamma x} + A_2 \cdot e^{\gamma x}$$

$$I(x,s) = B_1 \cdot e^{-\gamma x} + B_2 \cdot e^{\gamma x}$$

A_1, A_2, B_1, B_2 -

- određuju se iz
rubnih uvjeta
 $U(0,s), U(l,s)$
 $I(0,s), I(l,s)$

$$Z_0 = \frac{R+sL}{\gamma} = \sqrt{\frac{R+sL}{G+sC}}$$

VALNA (KARAKTERISTIČNA)
IMPEDANCIJA HOMOGENE LINIJE

$$B_1 = \frac{A_1}{Z_0}$$

$$B_2 = -\frac{A_2}{Z_0}$$

$$U(x,s) = A_1 \cdot e^{-\gamma x} + A_2 \cdot e^{\gamma x}$$

$$I(x,s) = \frac{A_1}{Z_0} e^{-\gamma x} - \frac{A_2}{Z_0} e^{\gamma x}$$

RUBNI UVJETI:

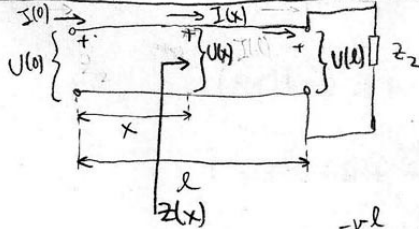
$$U(0) = A_1 + A_2$$

$$I(0) = \frac{A_1}{Z_0} - \frac{A_2}{Z_0}$$

$$A_1 = \frac{U(0) + I(0) \cdot Z_0}{2}$$

$$A_2 = \frac{U(0) - I(0) \cdot Z_0}{2}$$

HOMOGENA LINIJA ZAKLJUČENA IMPEDANCIOM z_2



$$U(l) = A_1 \cdot e^{-\gamma l} + A_2 \cdot e^{\gamma l}$$

$$z_0 \cdot I(l) = A_1 \cdot e^{-\gamma l} - A_2 \cdot e^{\gamma l}$$

$$A_1 = \frac{I(l)}{2} \cdot (z_2 + z_0) \cdot e^{\gamma l} \quad A_2 = \frac{I(l)}{2} \cdot (z_2 - z_0) \cdot e^{-\gamma l}$$

$$z_2 = \frac{U(l)}{I(l)} = z_0 \cdot \frac{A_1 e^{-\gamma l} + A_2 e^{\gamma l}}{A_1 e^{-\gamma l} - A_2 e^{\gamma l}}$$

$$\Gamma_2 = \frac{z_2 - z_0}{z_2 + z_0} \Rightarrow \text{KOEFIČIJENT REFLEKSIJE NA IZLAZU}$$

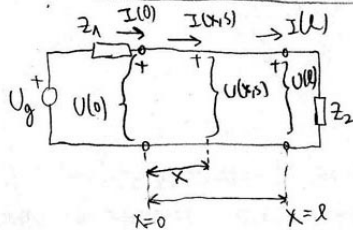
$$\frac{A_2}{A_1} = \Gamma_2 \cdot e^{-2\gamma l}$$

$$U(x, s) = U(0, s) \cdot \frac{e^{-\gamma(x-l)} + \Gamma_2 e^{\gamma(x-l)}}{e^{\gamma l} + \Gamma_2 e^{-\gamma l}}$$

$$I(x, s) = \frac{U(0, s)}{z_0} \cdot \frac{e^{-\gamma(x-l)} - \Gamma_2 e^{\gamma(x-l)}}{e^{\gamma l} + \Gamma_2 e^{-\gamma l}}$$

$$Z(x, s) = \frac{U(x, s)}{I(x, s)} = z_0 \cdot \frac{e^{-\gamma(x-l)} + \Gamma_2 e^{\gamma(x-l)}}{e^{-\gamma(x-l)} - \Gamma_2 e^{\gamma(x-l)}}$$

LINIJA ZAKLJUČENA NA OBA KRAJA z1 I(0) I(x) I(l)



$$U(0) = U_g - z_1 \cdot I(0)$$

$$U(l) = I(l) \cdot z_2$$

$$U(0) = A_1 + A_2$$

$$I(0) = \frac{1}{z_0} \cdot (A_1 - A_2)$$

$$A_1 - \Gamma_1 A_2 = U_g \cdot \frac{z_0}{z_0 + z_1}$$

$$A_2 = A_1 \cdot \Gamma_2 \cdot e^{-2\gamma l}$$

$$\Gamma_1 = \frac{z_1 - z_0}{z_1 + z_0} \Rightarrow \text{KOEFIČIJENT REFLEKSIJE NA ULAZU}$$

$$A_1 = U_g \cdot \frac{z_0}{z_0 + z_1} \cdot \frac{1}{1 - \Gamma_1 \Gamma_2 e^{-2\gamma l}}$$

$$A_2 = U_g \cdot \frac{z_0}{z_0 + z_1} \cdot \frac{\Gamma_2 e^{-2\gamma l}}{1 - \Gamma_1 \Gamma_2 e^{-2\gamma l}}$$

PRIDENOSNE JEDNADŽBE LINDA

$$U(0) = U(x) \cdot \text{ch}(y \cdot x) + z_0 \cdot I(x) \cdot \text{sh}(y \cdot x)$$

$$I(0) = \frac{U(x)}{z_0} \cdot \text{sh}(y \cdot x) + I(x) \text{ch}(y \cdot x)$$

$$z_A \quad x=l$$

$$U(0) = A \cdot U(l) + B \cdot I(l)$$

$$I(0) = C \cdot U(l) + D \cdot I(l)$$

$$A = \text{ch}(y \cdot l) = D$$

$$B = z_0 \cdot \text{sh}(y \cdot l)$$

$$C = \frac{\text{sh}(y \cdot l)}{z_0}$$

-ako je $A=D$, četveropol je simetričan

$$U(x) = U(0) \text{ch} yx - z_0 \cdot I(0) \cdot \text{sh} yx$$

$$I(x) = \frac{-U(0)}{z_0} \text{sh} yx + I(0) \text{ch} yx$$

VALNI RASPORED NAPONA I STRUJA DUŽ LINIJE

$$u(x,t) = A_1 e^{-\gamma x} + A_2 e^{\gamma x}$$

$$i(x,t) = B_1 e^{-\gamma x} + B_2 e^{\gamma x}$$

$$u(x,t) = |U| \cdot e^{j(\omega t + \phi)}$$

$$i(x,t) = |I| \cdot e^{j(\omega t + \psi)}$$

$$A_1 = |A_1| \cdot e^{j(\omega t + \phi_1)}$$

$$A_2 = |A_2| e^{j(\omega t + \phi_2)}$$

z i $\gamma \Rightarrow$ FUNKCIJE OD $j\omega$

$$\gamma = \alpha + j\beta$$

$\alpha \Rightarrow$ KARAKTERISTIČNI ILI ZRCALNI FAKTOR GUŠENJA

$\beta \Rightarrow$ KARAKTERISTIČNI ILI ZRCALNI FAKTOR FAZE

$$\alpha = \sqrt{\frac{1}{2} \left(R \cdot G - \omega^2 LC + \sqrt{(RG + \omega^2 LC)^2 + \omega^2 (RC + LG)^2} \right)}$$
$$\beta = \sqrt{\frac{1}{2} \left(\omega^2 LC - RG + \sqrt{(RG - \omega^2 LC)^2 + \omega^2 (RC + LG)^2} \right)}$$

$$f(\underbrace{\omega t - \beta x}_Y) = f(Y) = z$$

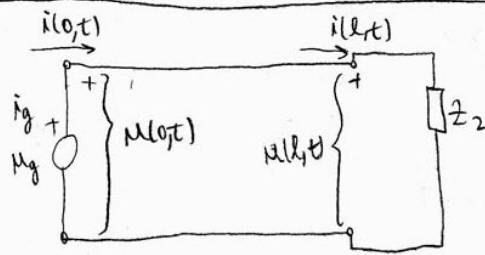
$$Y = \omega t - \beta x$$

$$v = \frac{\omega}{\beta} \Rightarrow \text{BRZINA ŠIRENJA VALA}$$

$$\text{POLAZNI VAL: } f(\omega t - \beta x)$$

$$\text{REFLEKTIRANI VAL: } f(\omega t + \beta x)$$

POLAZNI I REFLEKTIRANI VAL KOD SINUSNOG SIGNALA



$$A_1 = \frac{U_g + I_g \cdot Z_0}{2} \cdot e^{j\omega t}$$

$$A_2 = \frac{U_g - I_g \cdot Z_0}{2} \cdot e^{j\omega t}$$

$$Z_0 = |Z_0| \cdot e^{j\theta_0}$$

POLAZNI VAL:

$$u_p(x, t) = |A_1| \cdot e^{-\alpha x} \cdot \cos(\omega t - \beta x + \phi_1)$$

$$i_p(x, t) = \left| \frac{A_1}{Z_0} \right| \cdot e^{-\alpha x} \cdot \cos(\omega t - \beta x + \phi_1 - \theta_0)$$

REFLEKTIRANI VAL

$$u_r(x, t) = |A_2| \cdot e^{\alpha x} \cdot \cos(\omega t + \beta x + \phi_2)$$

$$i_r(x, t) = \left| \frac{A_2}{Z_0} \right| \cdot e^{\alpha x} \cdot \cos(\omega t + \beta x + \phi_2 - \theta_0)$$

$$\Gamma_{\text{doba}} \left[\frac{u_r(l, t)}{u_p(l, t)} \right] = -\theta_2$$

FAKTOR REFLEKSIJE

$$|A_2| = |A_1| \cdot |T_2| \cdot e^{-2\alpha l}$$

$$\phi_2 = \phi_1 - 2\beta l + \theta_2$$

POSEBNI SLUČAJEVI HOMOGENE LINIJE

1. LINIJA BEZ GUBITAKA

$$R=0$$

$$G=0$$

$$z_0 = \sqrt{\frac{L}{C}} = \text{konst.} = R_0$$

$$\gamma = s\sqrt{LC}$$

- za $s = j\omega$ (sinusna pobuda)

$$\gamma = j\omega\sqrt{LC} = j\beta$$

$$\beta = \omega\sqrt{LC}$$

$$\lambda = 0$$

- postoje 2 slučaja:

$$1. I_2=0 \rightarrow T_2=1, Z_2=\infty$$

$$\begin{aligned} u(y,t) &= |U(l)| \cos(\beta y) \cos(\omega t + \phi) \\ i(y,t) &= -\frac{|U(l)|}{z_0} \sin(\beta y) \sin(\omega t + \phi) \end{aligned} \left. \begin{array}{l} \text{STOSNI} \\ \text{VAL} \end{array} \right\}$$

$$2. U_1=0 \rightarrow T_2=-1, Z_2=0$$

$$u(y,t) = -|I(l)| z_0 \sin(\beta y) \sin(\omega t + \phi)$$

$$i(y,t) = |I(l)| \cos(\beta y) \cos(\omega t + \phi)$$

2. LINIJA BEZ DISTORZIJE

$$\frac{R}{L} = \frac{G}{C}$$

$$z_0 = \sqrt{\frac{L}{C}}$$

$$\gamma = \sqrt{RG} + s\sqrt{LC}$$

- za $s = j\omega$

$$\gamma = \sqrt{RG} + j\omega\sqrt{LC} \Rightarrow \begin{aligned} \alpha &= \sqrt{RG} \\ \beta &= \omega\sqrt{LC} \end{aligned}$$

③. RC - LINISA

$$G=0$$

$$L=0$$

$$Z_0 = \sqrt{\frac{R}{sC}}$$

$$-za \quad s = j\omega$$

$$Z_0 = \sqrt{\frac{R}{j\omega C}} = \sqrt{\frac{R}{\omega C}} \cdot e^{-j45^\circ}$$

$$\gamma = \sqrt{R \cdot j\omega C} = \sqrt{\frac{\omega RC}{2}} + j\sqrt{\frac{\omega RC}{2}}$$

$$\alpha = \sqrt{\frac{\omega RC}{2}}$$

$$\beta = \sqrt{\frac{\omega RC}{2}}$$

④. LINISA S MALIM GUBITCIMA

$$\omega L \gg R$$

$$\omega C \gg G$$

$$Z_0 = \sqrt{\frac{L}{C}} \cdot e^{-j\left(\frac{R}{2\omega L} - \frac{G}{2\omega C}\right)}$$

$$\gamma = j\omega\sqrt{LC} \cdot \sqrt{\left(1 - j\frac{R}{\omega L}\right)\left(1 - j\frac{G}{\omega C}\right)}$$

$$\gamma \approx \left(\frac{R}{2}\sqrt{\frac{C}{L}} + \frac{G}{2}\sqrt{\frac{L}{C}}\right) + j\omega\sqrt{LC}$$

$$\alpha = \frac{R}{2}\sqrt{\frac{C}{L}} + \frac{G}{2}\sqrt{\frac{L}{C}}$$

$$\beta = \omega\sqrt{LC}$$

ULAZNA IMPEDANCIJA LINIJE

$$Z_{ul} = \frac{U(0)}{I(0)}$$

$$= \frac{U(l) \cosh \gamma l + I(l) Z_0 \sinh \gamma l}{\frac{U(l) \sinh \gamma l + I(l) \cosh \gamma l}{Z_0}}$$

$$Z_{ul} = Z_0 \cdot \frac{Z_2 \cosh \gamma l + Z_0 \sinh \gamma l}{Z_2 \sinh \gamma l + Z_0 \cosh \gamma l} = Z_0 \cdot \frac{e^{2\gamma l} + T_2}{e^{2\gamma l} - T_2}$$

- za: $Z_2 = 0 \Rightarrow Z_{ul} = Z_0 \tanh \gamma l = Z_k$

$Z_2 = \infty \Rightarrow Z_{ul} = Z_0 \coth \gamma l = Z_p$

$Z_2 = Z_0 \Rightarrow Z_{ul} = Z_0 \Rightarrow$ PRILAGODENJE

$$Z_0 = \sqrt{Z_p \cdot Z_k}$$

BESKONAČNO DUGA LINIJA

① LINIJA BEZ GUBITAKA

$$U(x, s) = U(s) \cdot e^{-\frac{s x}{v}}$$

$$u(x, t) = u\left(t - \frac{x}{v}\right)$$

$$i(x, t) = \frac{u\left(t - \frac{x}{v}\right)}{Z_0}$$

$$Z_0 = \sqrt{\frac{L}{C}}$$

- signal se po obliku ne mijenja, ali kasni vremenski

② LINIJA BEZ DISTORZIJE

$$U(x, s) = U(s) \cdot e^{-(k + \frac{s}{v})x}$$

$$I(x, s) = \frac{U(s)}{Z_0} \cdot e^{-kx} \cdot e^{-\frac{s x}{v}}$$

$$u(x, t) = e^{-kx} \cdot u\left(t - \frac{x}{v}\right)$$

$$i(x, t) = e^{-kx} \cdot i\left(t - \frac{x}{v}\right)$$

- signal je prigušen duž linije, i kasni vremenski

LINIJE KONAČNE DULJINE

- ako je linija zaključena sa $Z_2 = Z_0$, ona se ponaša kao ∞ -linija