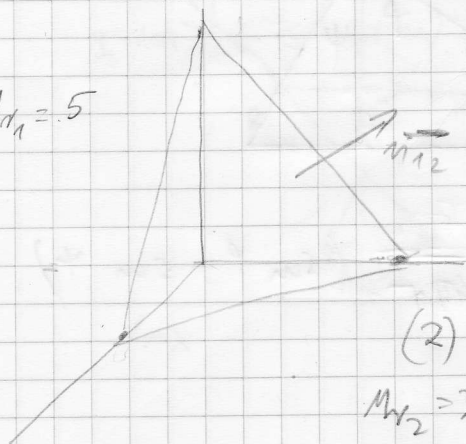


(12)

$$H_1 = \frac{3a_x - 0.5a_y}{M_0}$$

$$B_1 = 18\vec{a}_x - 2.5\vec{a}_y$$

$$M_{H_1} = 5$$



$$(2) \\ M_{H_2} = 3$$

$$\vec{m}_{12} = \frac{6\vec{a}_x + 4\vec{a}_y + 3\vec{a}_z}{\sqrt{61}}$$

$$\begin{array}{ccc} B_x & B_y & B_z \\ \uparrow M_0/M_{H_2} & \uparrow 3M_0 & \uparrow 3M_0 \end{array}$$

$$H_2 = H_x\vec{a}_x + H_y\vec{a}_y + H_z\vec{a}_z$$

$$I. \vec{m}_{12} \times (H_2 - H_1) = 0 = \begin{vmatrix} \vec{a}_x & \vec{a}_y & \vec{a}_z \\ 6 & 4 & 3 \\ \frac{B_x}{3M_0} & \frac{B_y}{3M_0} & \frac{B_z}{3M_0} \end{vmatrix} = 0$$

$$\begin{vmatrix} \vec{a}_x & \vec{a}_y & \vec{a}_z \\ 6 & 4 & 3 \\ B_x & B_y & B_z \end{vmatrix} \Rightarrow \begin{array}{l} 4B_z - 3B_y - 4.5 = 0 \quad (1) \\ -6B_z + 3B_x - 27 = 0 \quad (2) \\ 6B_y + 9 - 4B_x + 36 = 0 \quad (3) \end{array}$$

$$II. \vec{m}_{12} \cdot (B_2 - B_1) = 0$$

$$\frac{1}{2}B_x - \frac{27}{6} = B_z$$

$$\frac{2}{3}B_x - \frac{45}{6} = B_y$$

$$\frac{6\vec{a}_x + 4\vec{a}_y + 3\vec{a}_z}{\sqrt{61}} \cdot \left( (B_x - 15)\vec{a}_x + (B_y + 2.5)\vec{a}_y + B_z\vec{a}_z \right) = 0 \quad / \cdot \sqrt{61}$$

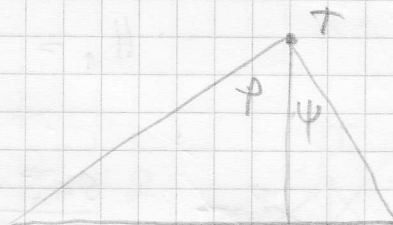
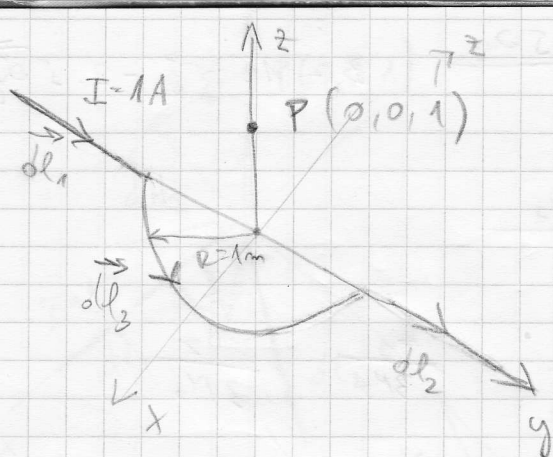
$$6 \cdot (B_x - 15) + 4 \cdot (B_y + 2.5) + 3B_z = 0 \quad (4)$$

$$6B_x + 4B_y + 3B_z = 80$$

$$6B_x + \frac{8}{3}B_x - \frac{180}{6} + \frac{3}{2}B_x - \frac{81}{6} = 80$$

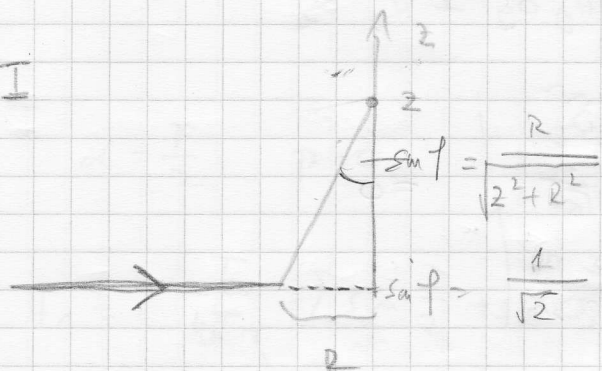
$$10.16 B_x = 123.5 \rightarrow B_x = 12.15 //$$

13.



$$\vec{H} = \vec{a}_x \frac{I}{4\pi r} (\sin \phi + \sin \psi)$$

I



→ kao da imamo beskonačan pravac  
imajući za ishodište dis

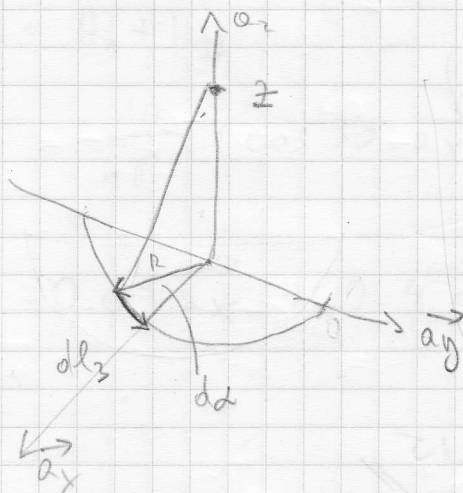
$$\vec{H}_1 = \vec{a}_x \frac{I}{4\pi r} (\sin \phi + \sin 0)$$

$$\vec{H}_1 = \frac{I}{4\pi R} (\sin 90 + \sin 0) = \frac{I}{4\pi R} (\sin \frac{1}{\sqrt{2}} + \sin 0) (\vec{a}_x)$$

II isti slučaj

$$\vec{H}_{12} = \frac{I}{2\pi R} - \frac{I}{2\pi R} \cdot \sin \phi = \frac{I}{2\pi R} (1 - \frac{1}{\sqrt{2}})$$

III

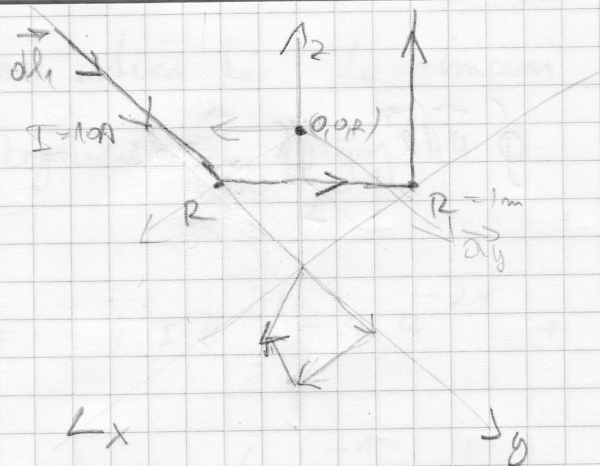


$$\begin{aligned} \vec{r} &= z\vec{a}_z \\ \vec{r}' &= R\vec{a}_r \end{aligned} \left\{ \begin{aligned} \vec{R} &= z\vec{a}_z - R\vec{a}_r \end{aligned} \right.$$

$$dl = R d\alpha$$

$$H_3 = \frac{I}{4\pi} \int \frac{2\cos\alpha \vec{a}_x + 2\sin\alpha \vec{a}_y + R\vec{a}_z}{\sqrt{(R^2+z^2)}} R d\alpha$$

16.



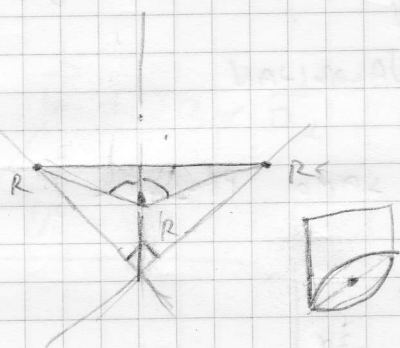
I

$$H_1 = \frac{I}{4\pi R} (\sin 90^\circ + \sin 0^\circ) - \frac{I}{4\pi R} (\sin \alpha + \sin 0^\circ)$$

$$\sin \alpha = \frac{1}{\sqrt{2}} = \frac{1}{\sqrt{2}}$$

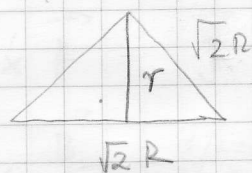
$$H_1 = \frac{I}{4\pi R} \left( 1 - \frac{1}{\sqrt{2}} \right) (\vec{a}_x)$$

$\downarrow$   
 $r_1$

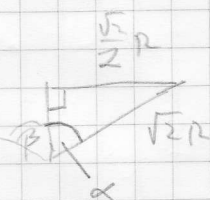


$$H_2 = \frac{I}{4\pi R} (\sin \alpha + \sin \beta)$$

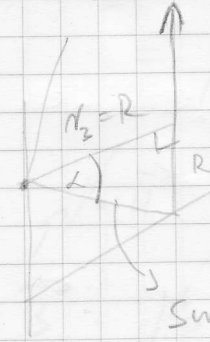
$$H_2 = \frac{I}{4\pi R} (\sin 30^\circ + \sin 30^\circ) \quad (\text{single angle, not precise value})$$



$$r = \frac{\sqrt{2} R \sqrt{3}}{2} = r_{\text{min}} = \frac{R\sqrt{3}}{2}$$



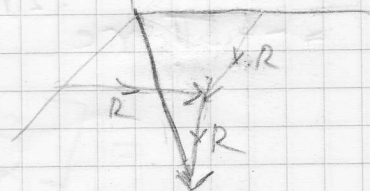
$$\sin \alpha = \frac{1}{2}$$



$$\sin \alpha = \frac{R}{\sqrt{2} R}$$

$$H = H_1 + H_2 + H_3$$

$$\frac{\vec{a}_x + \vec{a}_y - \vec{a}_z}{\sqrt{3}}$$

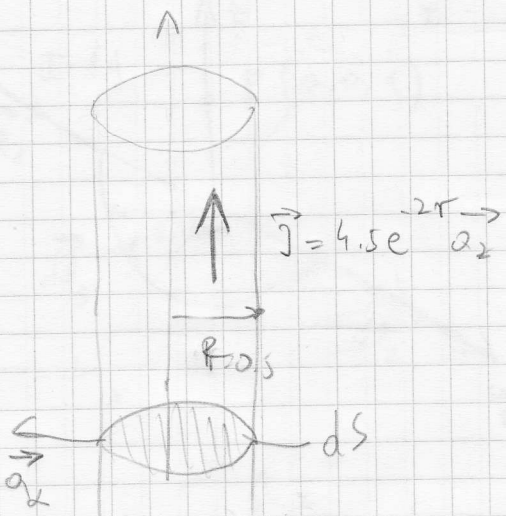


$$H_3 = \frac{I}{4\pi r_3} (\sin 45^\circ + \sin 90^\circ) (\vec{a}_y)$$

$$H_3 = \frac{I}{4\pi R} (\sin 45^\circ + \sin 90^\circ) \vec{a}_y$$



19



$$\oint \vec{H} d\vec{l} = \iint_S \vec{J} \cdot d\vec{S} = I$$

I umutar radija ne dekuotim cijelu struju već samo dio

$$I = \iint 4.5 e^{-2r} a_z dS = \int_0^r \int_0^{2\pi} r 4.5 e^{-2r} a_z dr d\alpha$$

↓  
JAKOŠĆAN

↓  
POVRŠINA TI JE SAMO PREŠJEK

$$I = 4.5 \cdot 2\pi \int_0^r r \cdot e^{-2r} dr = \left| \begin{matrix} u=r & du=dr \\ dv=e^{-2r} & v=-\frac{1}{2}e^{-2r} \end{matrix} \right|$$

$$= 4.5 \cdot 2\pi \cdot \left( -\frac{1}{2} e^{-2r} \cdot r \right) + 4.5 \cdot 2\pi \cdot \frac{1}{2} \int_0^r e^{-2r}$$

$$= -4.5\pi r e^{-2r} - \frac{4.5\pi}{2} (e^{-2r} - 1)$$

$$I = \oint \vec{H} d\vec{l} = 2r\pi \cdot H_1$$

$$\Rightarrow H_1 = \frac{4.5\pi (-re^{-2r} + \frac{1}{2}(1-e^{-2r}))}{2r\pi}$$

$$H_1 = \frac{1.125}{r} (-2re^{-2r} + 1 - e^{-2r}) a_z$$

II van vodica kor 26 imamo skoncniromu sluzi 4 jednoj  
stojnici 4 sluzoj

$$I = -4.5\pi \left( -re^{-2r} + \frac{1}{2} - \frac{1}{2}e^{-2r} \right) \Big|_{r=0.5}$$

$$I = -4.5\pi \cdot \left( -e^{-1} + \frac{1}{2} \right)$$

$$\vec{H}_2 = \frac{4.5\pi}{2\pi r} \cdot \left( -e^{-1} + \frac{1}{2} \right) = \frac{0.297}{r} \vec{a}_2$$

$$20 \quad r > 0.5$$

(20)  $\vec{H} = 3r \vec{a}_2$

CILINDRIČNI VODIČ

$\vec{D} = ?$

$$\vec{B} = \mu_0 \cdot \vec{H}$$

$$\nabla \times \vec{H} = \vec{J}$$

cilindričnom

$$\nabla \times \frac{\vec{B}}{\mu_0} = \frac{1}{\mu_0} \vec{a}_1 \cdot \left( \frac{1}{r} \frac{\partial B_2}{\partial z} - \frac{\partial B_z}{\partial z} \right) +$$

$$+ \vec{a}_2 \left( \frac{\partial B_r}{\partial z} - \frac{\partial B_z}{\partial r} \right) +$$

$$+ \vec{a}_3 \frac{1}{r} \left[ \frac{\partial}{\partial r} (r B_\alpha) - \frac{\partial B_r}{\partial \alpha} \right] =$$

$$= \frac{1}{\mu_0} \cdot \left[ \frac{1}{r} (6r) - 0 \right] = \frac{1}{\mu_0} \cdot 6 \vec{a}_2$$

$$\vec{B} = \mu_0 \cdot \vec{H}$$

$$\nabla \times \vec{B} = \mu_0 \cdot \vec{J}$$

$$\vec{J} = 6 \vec{a}_2 //$$