

1. $y''(t) + 5y'(t) + 6y(t) = u(t)$

$$u(t) = 5\cos(t)$$

$$y(0) = 0, \quad y'(0) = 1$$

• PRIJENOSNA FUNKCIJA

$$H(s) = \frac{1}{s^2 + 5s + 6}$$

• FREKVENCIJSKA KARAKTERISTIKA

$$s = j\omega$$

$$H(j\omega) = \frac{1}{(j\omega)^2 + 5 \cdot (j\omega) + 6} = \frac{1}{6 - \omega^2 + j5\omega}$$

$$H(j\omega) = \frac{6 - \omega^2 - j5\omega}{\omega^4 + 13\omega^2 + 36}$$

$$|H(j\omega)| = \frac{1}{\sqrt{\omega^4 + 13\omega^2 + 36}}$$

$$\angle H(j\omega) = -\operatorname{arctg} \frac{5\omega}{6 - \omega^2}$$

• OPĆA HOMOGENA JEDNADŽBA

$$y_h(t) = Ce^{st}$$

$$Ce^{st}(s^2 + 5s + 6) = 0, \quad Ce^{st} \neq 0$$

$$s^2 + 5s + 6 = 0$$

$$(s+3)(s+2) = 0 \rightarrow s_1 = -3, \quad s_2 = -2$$

$$y_h(t) = C_1 e^{-3t} + C_2 e^{-2t}$$

• PARTIKULARNA JEDNADŽBA

$$u(t) = 5 \cos(t) \rightarrow y_p(t) = A \cos(t + \Theta)$$

$$\omega = 1$$

$$A = 5 \cdot |H(j\omega)| \big|_{\omega=1} \quad \Theta = \angle H(j\omega) \big|_{\omega=1}$$

$$A = 5 \cdot \frac{1}{5\sqrt{2}} = \frac{\sqrt{2}}{2} \quad \Theta = -45^\circ$$

$$y_p(t) = \frac{\sqrt{2}}{2} \cos(t - 45^\circ)$$

• TOTALNI ODZIV

$$y(t) = y_n(t) + y_p(t)$$

$$y(0) = 0, \quad y'(0) = 1$$

$$y(t) = C_1 e^{-3t} + C_2 e^{-2t} + \frac{\sqrt{2}}{2} \cos(t - 45^\circ)$$

$$y'(t) = -3C_1 e^{-3t} - 2C_2 e^{-2t} - \frac{\sqrt{2}}{2} \sin(t - 45^\circ)$$

$$y(0) = C_1 + C_2 + \frac{1}{2} = 0$$

$$y'(0) = -3C_1 - 2C_2 + \frac{1}{2} = 1$$

$$\left. \begin{array}{l} C_1 + C_2 = -\frac{1}{2} \\ -3C_1 - 2C_2 = \frac{1}{2} \end{array} \right\} C_1 = \frac{1}{2}, \quad C_2 = -1$$

$$y(t) = \frac{1}{2} e^{-3t} - e^{-2t} + \frac{\sqrt{2}}{2} \cos(t - 45^\circ)$$

• STABILNOST SUSTAVA

IZ VLASTITIH FREKVENCIJA SUSTAVA ZAKLJ.

DA JE SUSTAV STABILAN.

U TRENUTKU $t \gg 0$ HOMOGENA JEDNADŽBA POSTAJE JEDNAKA NULI, TE "PREŽIVI" SAMO PARTIKULARNI DIO TOTALNOG ODZIVA.

$$2. \quad y(n) - 2y(n-1) + y(n-2) = u(n)$$

$$u(n) = 5$$

$$y(-2) = 0, \quad y(-1) = 1$$

- PRIJENOSNA FUNKCIJA

$$H(z) = \frac{1}{1 - 2z^{-1} + z^{-2}}$$

- FREKVENCIJSKA KARAKTERISTIKA

$$z = e^{j\Omega}$$

$$H(e^{j\Omega}) = \frac{1}{1 - 2e^{-j\Omega} + e^{-2j\Omega}}$$

$$H(e^{j\Omega}) = \frac{1}{1 - 2\cos(\Omega) + j2\sin(\Omega) + \cos(2\Omega) - j\sin(2\Omega)}$$

$$|H(e^{j\Omega})| = \frac{1}{\sqrt{6 - 8\cos(\Omega) + 2\cos(2\Omega)}}$$

$$\angle H(e^{j\Omega}) = \arctg \frac{\sin(2\Omega) - 2\sin(\Omega)}{1 - 2\cos(\Omega) + \cos(2\Omega)}$$

- OPĆA HOMOGENA JEDNADŽBA

$$y_h(n) = Cq^n$$

$$Cq^n(1 - 2q^{-1} + q^{-2}) = 0$$

$$Cq^{n-2}(q^2 - 2q + 1) = 0, \quad Cq^{n-2} \neq 0$$

$$q^2 - 2q + 1 = 0$$

$$(q-1)^2 = 0 \rightarrow q_{1,2} = 1$$

$$y_h(n) = (C_1 + C_2 n)(1)^n$$

- PARTIKULARNA JEDNADŽBA

$$u(n) = 5 \rightarrow y_p(n) = A \cdot n^2 \cdot (1)^n$$

$$w = 0$$

$$A = 5 \cdot |H(e^{jw})| \Big|_{w=0} \cdot n^2 \cdot (1)^n$$

$$A = 5 \cdot \frac{1}{0} \cdot n^2 \cdot (1)^n$$

ZA $w=0$ FREKVENCIJSKA KARAKTERISTIKA
NIJE DEFINIRANA

$$y_p(n) = A n^2 (1)^n$$

$$A n^2 - 2A(n-1)^2 + A(n-2)^2 = 5$$

$$A(n^2 - 2n^2 + 4n - 2 + n^2 - 4n + 4) = 5$$

$$A = \frac{5}{2}$$

$$y_p(n) = \frac{5}{2} n^2$$

- TOTALNI ODZIV

$$y(n) = y_h(n) + y_p(n)$$

$$y(-2) = 0, \quad y(-1) = 1$$

$$y(n) = (C_1 + C_2 n)(1)^n + \frac{5}{2} n^2$$

$$y(-2) = C_1 - 2C_2 + 10 = 0$$

$$y(-1) = C_1 - C_2 + \frac{5}{2} = 1$$

$$\left. \begin{array}{l} y(-2) = C_1 - 2C_2 + 10 = 0 \\ y(-1) = C_1 - C_2 + \frac{5}{2} = 1 \end{array} \right\} C_1 = 7, \quad C_2 = -8.5$$

$$y(n) = (7 - 8.5n)(1)^n + \frac{5}{2} n^2$$

- STABILNOST SUSTAVA

SUSTAV JE NESTABILAN.

U TRENUTKU $t \gg 0$, ODZIV TEŽI U BESKONAČNO.

3. $y''(t) + 2y'(t) + 5y(t) = u(t)$

$u(t) = \sin(t), t < 0$

$u(t) = 2\sin(2t), t > 0$

- PRIJENOSNA FUNKCIJA

$$H(s) = \frac{1}{s^2 + 2s + 5}$$

- FREKVENCIJSKA KARAKTERISTIKA

$$s = j\omega$$

$$H(j\omega) = \frac{1}{(j\omega)^2 + 2j\omega + 5} = \frac{1}{5 - \omega^2 + j2\omega}$$

$$H(j\omega) = \frac{5 - \omega^2 - j2\omega}{\omega^4 - 6\omega^2 + 25}$$

$$|H(j\omega)| = \frac{1}{\sqrt{\omega^4 - 6\omega^2 + 25}}$$

$$\angle H(j\omega) = -\arctg \frac{2\omega}{5 - \omega^2}$$

- OPĆA HOMOGENA JEDNADŽBA

$$y_h(t) = Ce^{st}$$

$$Ce^{st}(s^2 + 2s + 5) = 0, Ce^{st} \neq 0$$

$$s^2 + 2s + 5 = 0 \quad s_{1,2} = \frac{-2 \pm j4}{2}$$

$$s_1 = -1 + j2, s_2 = -1 - j2$$

$$y_h(t) = e^{-t}(C_1 \cos(2t) + C_2 \sin(2t))$$

• PARTIKULARNA JEDNADŽBA

$$1.) \quad u_1(t) = \sin(t) \rightarrow y_{p1}(t) = A \sin(t + \theta)$$

$$\omega = 1$$

$$A = 1 \cdot |H(j\omega)| \Big|_{\omega=1} \quad \theta = \angle H(j\omega) \Big|_{\omega=1}$$

$$A = 1 \cdot \frac{\sqrt{5}}{10} \quad \theta = -26.56^\circ$$

$$y_{p1}(t) = \frac{\sqrt{5}}{10} \sin(t - 26.56^\circ)$$

$$2.) \quad u_2(t) = 2 \sin(2t) \rightarrow y_{p2}(t) = A \sin(2t + \theta)$$

$$\omega = 2$$

$$A = 2 \cdot |H(j\omega)| \Big|_{\omega=2} \quad \theta = \angle H(j\omega) \Big|_{\omega=2}$$

$$A = \frac{2\sqrt{17}}{17} \quad \theta = -75.96^\circ$$

$$y_{p2}(t) = \frac{2\sqrt{17}}{17} \sin(2t - 75.96^\circ)$$

• POČETNI UVJETI

$$y_{p1}(0^-) = y(0^-) = -0.01$$

$$y'_{p1}(0^-) = y'(0^-) = 0.2$$

$$b_0 = 0, \quad b_1 = 0, \quad b_2 = 1$$

$$y(0^+) = b_0 u(0^+) + y(0^-)$$

$$y(0^+) = y(0^-) = -0.01$$

$$y'(0^+) = b_0 u'(0^+) + b_1 u(0^+) - a_1 (y(0^+) - y(0^-)) + y'(0^-)$$

$$y'(0^+) = y'(0^-) = 0.2$$

$$y(0^+) = -0.01$$

$$y'(0^+) = 0.2$$

• TOTALNI ODZIV

$$y(t) = \begin{cases} y_{pr}(t), & t < 0 \\ y_h(t) + y_{pr}(t), & t > 0 \end{cases}$$

$$y(0^+) = -0.01, \quad y'(0^+) = 0.2$$

ZA $t > 0$

$$y(t) = e^{-t} (C_1 \cos(2t) + C_2 \sin(2t)) + \frac{2\sqrt{17}}{17} \sin(2t - 75.96^\circ)$$

$$y'(t) = e^{-t} (\cos(2t)(-C_1 + 2C_2) + \sin(2t)(-2C_1 - 2C_2)) + \frac{2\sqrt{17}}{17} \sin(2t - 75.96^\circ)$$

$$y(0) = C_1 = 0.46$$

$$y'(0) = -C_1 + 2C_2 = -0.035$$

$$C_1 = 0.46, \quad C_2 = 0.21$$

$$y(t) = \begin{cases} \frac{\sqrt{5}}{10} \sin(t - 26.56^\circ), & t < 0 \\ e^{-t} (0.46 \cos(2t) + 0.21 \sin(2t)) + \frac{2\sqrt{17}}{17} \sin(2t - 75.96^\circ), & t > 0 \end{cases}$$

• STABILNOST SUSTAVA

IZ VLASTITIH FREKVENCIJA SUSTAVA ZAKLJUČUJEMO DA JE SUSTAV STABILAN.

U TRENUTKU $t \gg 0$ HOMOGENA JEDNADŽBA POSTAJE JEDNAKA NULI, TE "PREŽIVI" SAMO PARTIKULARNI DIO TOTALNOG ODZIVA.

4. $y'(t) + 3y(t) = u(t)$

$y(0) = 0$

$u(t) = (\sin(t) + 2\sin(2t) + 3\sin(3t) + 4\sin(4t)) \cdot \nu(t)$

• PRIJENOSNA FUNKCIJA

$$H(s) = \frac{1}{s+3}$$

• FREKVENCIJSKA KARAKTERISTIKA

$$s = j\omega$$

$$H(j\omega) = \frac{1}{j\omega+3} = \frac{3-j\omega}{3+\omega^2}$$

$$|H(j\omega)| = \frac{1}{\sqrt{9+\omega^2}}$$

$$\angle H(j\omega) = -\arctg \frac{\omega}{3}$$

• OPĆA HOMOGENA JEDNADŽBA

$$y_h(t) = Ce^{st}$$

$$Ce^{st}(s+3) = 0, \quad Ce^{st} \neq 0$$

$$s+3=0 \rightarrow s=-3$$

$$y_h(t) = C_1 e^{-3t}$$

• PARTIKULARNA JEDNADŽBA

$$u_1(t) = \sin(t) \rightarrow y_{p1}(t) = \frac{\sqrt{10}}{10} \sin(t - 18.43^\circ)$$

$$u_2(t) = 2\sin(2t) \rightarrow y_{p2}(t) = \frac{2\sqrt{13}}{13} \sin(2t - 33.69^\circ)$$

$$u_3(t) = 3\sin(3t) \rightarrow y_{p3}(t) = \frac{\sqrt{2}}{2} \sin(3t - 45.00^\circ)$$

$$u_4(t) = 4\sin(4t) \rightarrow y_{p4}(t) = \frac{4}{5} \sin(4t - 53.13^\circ)$$

$$y_p(t) = y_{p1}(t) + y_{p2}(t) + y_{p3}(t) + y_{p4}(t)$$

• TOTALNI ODZIV

$$y(t) = y_h(t) + y_p(t)$$

$$y(t) = C_1 e^{-3t} + \frac{\sqrt{10}}{10} \sin(t - 18.43^\circ) + \frac{2\sqrt{13}}{13} \sin(2t - 33.69^\circ) + \frac{\sqrt{2}}{2} \sin(3t - 45.00^\circ) + \frac{4}{5} \sin(4t - 53.13^\circ)$$

$$y(0) = 0$$

$$y(0) = C_1 = 1.55$$

$$C_1 = 1.55$$

$$y(t) = 1.55 e^{-3t} + \frac{\sqrt{10}}{10} \sin(t - 18.43^\circ) + \frac{2\sqrt{13}}{13} \sin(2t - 33.69^\circ) + \frac{\sqrt{2}}{2} \sin(3t - 45.00^\circ) + \frac{4}{5} \sin(4t - 53.13^\circ)$$

• STABILNOST SUSTAVA

IZ VLASTITIH FREKVENCIJA SUSTAVA ZAKLJUČUJEMO DA JE SUSTAV STABILAN.

U TRENUTKU $t \gg 0$ HOMOGENA JEDNADŽBA POSTAJE JEDNAKA NULI, TE „PREŽIVI” SAMO PARTIKULARNI DIO TOTALNOG ODZIVA.

5. $y(n) + 0.5y(n-1) = u(n)$

$$y(-1) = 1$$

$$u(n) = (\cos(0.5\pi n + 0.2\pi) + 2\cos(\pi n) + 3\cos(1.5\pi n) + 4\cos(2\pi n))u(n)$$

• PRIJENOSNA FUNKCIJA

$$H(z) = \frac{1}{1 + 0.5z^{-1}} = \frac{z}{z + 0.5}$$

• FREKVENCIJSKA KARAKTERISTIKA

$$z = e^{j\Omega}$$

$$H(e^{j\Omega}) = \frac{1}{1 + 0.5e^{-j\Omega}}$$

$$H(e^{j\Omega}) = \frac{1}{1 + 0.5\cos(\Omega) - j0.5\sin(\Omega)}$$

$$|H(e^{j\Omega})| = \frac{2}{\sqrt{5+4\cos(\Omega)}}$$

$$\angle H(e^{j\Omega}) = \arctg \frac{\sin(\Omega)}{2+\cos(\Omega)}$$

• OPĆA HOMOGENA JEDNADŽBA

$$y_h(n) = Cq^n$$

$$Cq^{n-1}(q+0.5)=0, \quad Cq^{n-1} \neq 0$$

$$q+0.5=0 \rightarrow q=-0.5$$

$$y_h(n) = C_1 \cdot \left(-\frac{1}{2}\right)^n$$

• PARTIKULARNA JEDNADŽBA

$$u_1(n) = \cos(0.5\pi n + 0.2\pi) \rightarrow y_{p1}(n) = A \cos(0.5\pi n + \Theta)$$

$$\omega = 0.5\pi$$

$$A = |H(e^{j\Omega})|_{\Omega=0.5\pi} \quad \Theta = 0.2\pi + \angle H(e^{j\Omega})_{\Omega=0.5\pi}$$

$$A = \frac{2\sqrt{5}}{5}$$

$$\Theta = 62.57^\circ$$

$$u_2(n) = 2\cos(\pi n) \rightarrow y_{p2}(n) = A \cos(\pi n + \Theta)$$

$$\omega = \pi$$

$$A = 2 \cdot |H(e^{j\Omega})|_{\Omega=\pi} \quad \Theta = \angle H(e^{j\Omega})_{\Omega=\pi}$$

$$A = 4$$

$$\Theta = 0^\circ$$

$$u_3(n) = 3\cos(1.5\pi n) \rightarrow y_{p3}(n) = A \cos(1.5\pi n + \Theta)$$

$$\omega = 1.5\pi$$

$$A = 3 \cdot |H(e^{j\Omega})|_{\Omega=1.5\pi} \quad \Theta = \angle H(e^{j\Omega})_{\Omega=1.5\pi}$$

$$A = \frac{6\sqrt{5}}{5}$$

$$\Theta = -26.57^\circ$$

$$u_4(n) = 4 \cos(2\pi n) \rightarrow y_{p4}(n) = A \cos(2\pi n + \theta)$$

$$\omega = 2\pi$$

$$A = 4 \cdot |H(e^{j\omega})|_{\omega=2\pi} \quad \theta = \angle H(e^{j\omega})_{\omega=2\pi}$$

$$A = \frac{8}{3}$$

$$\theta = 0^\circ$$

$$y_p(n) = y_{p1}(n) + y_{p2}(n) + y_{p3}(n) + y_{p4}(n)$$

• TOTALNI ODZIV

$$y(n) = y_h(n) + y_p(n)$$

$$y(n) = u(n) - 0.5y(n-1)$$

$$y(0) = u(0) - 0.5y(-1)$$

$$y(0) = 9.3$$

$$y(n) = C_1 \left(-\frac{1}{2}\right)^n + \frac{2\sqrt{5}}{5} \cos(0.5\pi n + 62.57^\circ) + 4 \cos(\pi n) + \frac{6\sqrt{5}}{5} \cos(1.5\pi n) + \frac{8}{3} \cos(2\pi n)$$

$$y(0) = C_1 = -0.46$$

$$C_1 = -0.46$$

$$y(n) = (-0.46) \left(-\frac{1}{2}\right)^n + \frac{2\sqrt{5}}{5} \cos(0.5\pi n + 62.57^\circ) + 4 \cos(\pi n) + \frac{6\sqrt{5}}{5} \cos(1.5\pi n) + \frac{8}{3} \cos(2\pi n)$$

• STABILNOST SUSTAVA

IZ VLASTITIH FREKVENCIJA SUSTAVA ZAKLJUČUJEMO

DA JE SUSTAV STABILAN

U TRENUTKU $t \gg 0$ HOMOGENA JEDNADŽBA

POSTAJE JEDNAKA NULI, TE "PREŽIVI" SAMO

PARTIKULARNI DIO TOTALNOG ODZIVA.