

1.

$$\frac{dy}{dt} + 5y + 2 = u(t), \quad y(0) = 0$$

→ Sustav je očigledno nelinearan.

Ako na ulaz dovedemo linearnu funkciju dva signala, na izlazu to očigledno nećemo dobiti → razlog je 2.

→ Ako je sustav linearni (specifični i vremenski nepromjenjiv → LTI), tada što god napravili ulaznom signalu (linearna transformacija) → to ćemo napraviti i izlazu. tj.

Ako je s LTI te

$$Y_1 = S\{U_1\}, \text{ tada ako je}$$

$U_2 = T\{U_1\}$ ,  $T$  - neki drugi LTI, onda ujedini da je

$$\underline{Y_2 = T\{Y_1\}} \rightarrow \text{tj. ako znam}$$

odziv na  $U_1$ , i ako znamo da  $U_2$  može dobiti iz  $U_1$  → linearnu transformaciju tada  $Y_2$  ćemo dobiti iz  $Y_1$ .

2. Zadan je kontinuirani sustav

$$y'''(t) - y''(t) + y'(t) + 39y = u''(t) + 2u(t).$$

Ispitajte da li je ovaj sustav stabilan.

$$y'''(t) - y''(t) + y'(t) + 39y(t) = u''(t) + 2u(t)$$

$$y_h(t) = C e^{\lambda t}$$

$$y'_h(t) = C \lambda e^{\lambda t}$$

$$y''_h(t) = C \lambda^2 e^{\lambda t}$$

$$y'''_h(t) = C \lambda^3 e^{\lambda t}$$

$$C e^{\lambda t} [\lambda^3 - \lambda^2 + \lambda + 39] = 0$$

$$\lambda^3 - \lambda^2 + \lambda + 39 = 0$$

$$\boxed{\lambda_1 = -3}$$

$$(\lambda^3 - \lambda^2 + \lambda + 39) : (\lambda + 3) = \lambda^2 - 4\lambda + 13$$

$$\begin{array}{r} \lambda^3 - \lambda^2 + \lambda + 39 \\ -\lambda^3 - 3\lambda^2 \hline \end{array}$$

$$-4\lambda^2 + \lambda$$

$$\begin{array}{r} -4\lambda^2 + \lambda \\ 4\lambda^2 + 12\lambda \hline \end{array}$$

$$13\lambda + 39$$

$$\begin{array}{r} 13\lambda + 39 \\ -(13\lambda + 39) \hline \end{array}$$

$$(\lambda + 3)(\lambda^2 - 4\lambda + 13) = 0$$

$$\lambda_{2,3} = \frac{4 \pm 6j}{2}$$

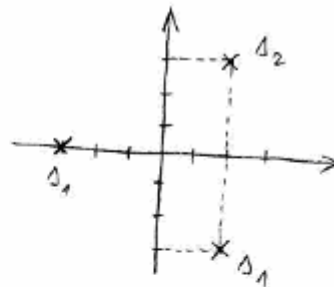
$$\lambda_2 = 2 + 3j$$

$$\lambda_3 = 2 - 3j$$

$$y_h(t) = C_1 e^{-3t} + C_2 e^{(2+3j)t} + C_3 e^{(2-3j)t}$$

$$\lim_{t \rightarrow \infty} y_h(t) = 0 + \lim_{t \rightarrow \infty} (C_2 e^{(2+3j)t} + C_3 e^{(2-3j)t}) = \infty$$

SUSTAV JE NESTABILAN



III

Postoje karakter. frekv. za koje je  $\operatorname{Re}\{s\} > 0$

SUSTAV JE NESTABILAN

3.

$$y' + y = u' + 2u.$$

$$u(t) = 3\nu(t), \quad \underline{y(0)}$$

$$a) \quad y(0^-) = 0, \quad b) \quad y(0^+) = 9.$$

$$y_h = ce^{-t}$$

$$t \in (0, \infty) \rightarrow y_p = k \rightarrow$$

$$k = 6 \rightarrow$$

$$y_p = (ce^{-t} + 6)\nu(t), \quad \underline{t \in \mathbb{R}}.$$

$$\rightarrow -\cancel{ce^{-t}}\nu(t) + (c+6)\delta(t) +$$

$$+ \cancel{(ce^{-t} + 6)}\nu(t) = 3\delta(t) + 6\nu(t)$$

$$\rightarrow \underline{c = -3}$$

$$\rightarrow y = ce^{-t} + (6 - 3e^{-t})\nu(t)$$

$$a) \quad y(0^-) = c + 0 = 9 \rightarrow (\underline{\nu(0^-) = 0})$$

$$c = 9$$

$$y = 9e^{-t} + (6 - 3e^{-t})\nu(t) \quad \underline{t \in \mathbb{R}}$$

$$\rightarrow y = (6 + 6e^{-t})\nu(t) \quad \underline{t \in (0, \infty)}.$$

7b)

$$Y = ce^{-t} + (6 - 3e^{-t})\nu(t)$$

$$Y(0^+) = 9$$

$$(\nu(0^+) = 9)$$

$$Y(0^+) = c + 3 = 9 \rightarrow \underline{c = 6}$$

$$Y = 6e^{-t} + (6 - 3e^{-t})\nu(t), \underline{t \in \mathbb{R}}$$

$$Y = (6 + 3e^{-t})\nu(t), \underline{t \in (0, \infty)}$$

4. Kontinuirani sustav opisan je diferencijalnom jednačkom čije je homogeno rješenje

$$y_h(t) = \frac{1}{2}e^{3t} + \frac{5}{3}e^{2t}.$$

Sustav nema nula (u diferencijalnoj jednačbi ne postoje derivacije ulaza). Odredite tu diferencijalnu jednačbu. Odredite ukupan i odziv mirnog sustava ako se sustav pobudi s  $u(t) = \frac{5}{2}e^{2t}$ ,  $t \geq 0$ . Odredite početna stanja. Ispitajte stabilnost sustava.

M.  $y_h(t) = \frac{1}{2}e^{3t} + \frac{5}{3}e^{2t}$   
 $u(t) = \frac{5}{2}e^{2t}, t \geq 0$

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$\lambda_1 = 3$        $\lambda_1 = \frac{1}{2}$   
 $\lambda_2 = 2$        $\lambda_2 = \frac{5}{3}$

$\lambda_1 > 0$   
 $\lambda_2 > 0$  } SUSTAV NIJE STABILAN

$(\lambda - 3)(\lambda - 2) = 0$   
 $\lambda^2 - 5\lambda + 6 = 0$

$y''(t) - 5y'(t) + 6y(t) = u(t)$

- PARTIKULARNO  
 $y''(t) - 5y'(t) + 6y(t) = \frac{5}{2}e^{2t}$

pretpostavimo rješenje:  
 $y_p = A \cdot t \cdot e^{2t}$

$y'_p(t) = A e^{2t} + 2A t e^{2t}$   
 $y''_p(t) = 2A e^{2t} + 2A e^{2t} + 4A t e^{2t}$

$2A e^{2t} + 2A e^{2t} + 4A t e^{2t} - 5A e^{2t} - 10A t e^{2t} + 6A t e^{2t} = \frac{5}{2}e^{2t}$

$-A = \frac{5}{2}$   
 $A = -\frac{5}{2}$

$y_p = -\frac{5}{2} t e^{2t}$

$y = y_h + y_p = \frac{1}{2}e^{3t} + \frac{5}{3}e^{2t} - \frac{5}{2} t e^{2t}$

NASTAVAK (4)

$$y(t) = K_1 \cdot e^{3t} + K_2 \cdot e^{2t} - \frac{5}{2} \cdot t \cdot e^{2t}$$

$$y'(t) = 3K_1 e^{3t} + 2K_2 e^{2t} - \frac{5}{2} e^{2t} - 5te^{2t}$$

$$y(0) = 0$$

$$y'(0) = 0$$

$$K_1 + K_2 = 0$$

$$K_1 = -K_2$$

$$3K_1 + 2K_2 - \frac{5}{2} = 0$$

$$-3K_2 + 2K_2 = \frac{5}{2}$$

$$K_2 = -\frac{5}{2}$$

$$K_1 = \frac{5}{2}$$

$$y(t) = \frac{5}{2} e^{3t} - \frac{5}{2} e^{2t} - \frac{5}{2} t e^{2t}$$

↪ ODZIV MIRNOG SUSTAVA

POČETNA STANJA:

$$y(0) = \frac{1}{2} + \frac{5}{3} = \frac{13}{6}$$

$$y'(t) = \frac{3}{2} e^{3t} + \frac{10}{3} e^{2t} - \frac{5}{2} e^{2t} - 5te^{2t}$$

$$y'(0) = \frac{3}{2} + \frac{10}{3} - \frac{5}{2} = \frac{-6+20}{6} = \frac{14}{6} = \frac{7}{3}$$

$$y'(0) = \frac{7}{3}$$

$$y(0^-) = y(0^+) = y(0)$$

$$y'(0^-) = y'(0^+) = y'(0)$$



5. Riješite diferencijalnu jednačbu

$$y'(t) + 2y(t) = u(t),$$

ako je ulaz

$$u(t) = A \cdot \cos(\omega_0 t) \cdot \mu(t),$$

pri čemu je  $A$  realna konstanta i uzimajući da su početni uvjeti jednaki nula. Bez dodatnog računanja odredite rješenje ove jednačbe ako je ulaz

$$u(t) = B \cdot \cos \omega_0(t-1) \cdot \mu(t-1).$$

$$y'(t) + 2y(t) = u(t)$$

$$y(t) = y_h(t) + y_p(t)$$

$$y_h = ?$$

$$u(t) = A \cos(\omega_0 t) \mu(t)$$

$$h'(t) + 2h(t) = 0 \quad h(t) = C e^{st}$$

$$1 C e^{st} + 2 C e^{st} = 0 \quad C e^{st} (1+2) = 0 \quad \boxed{s = -2}$$

$$h(t) = C e^{st}$$

$$y_p = ?$$

$$y_p(t) = K_1 \cos(\omega_0 t) + K_2 \sin(\omega_0 t)$$

$$y_p'(t) = -\omega_0 K_1 \sin(\omega_0 t) + \omega_0 K_2 \cos(\omega_0 t)$$

$$-\omega_0 K_1 \sin(\omega_0 t) + \omega_0 K_2 \cos(\omega_0 t) + 2 K_1 \cos(\omega_0 t) + 2 K_2 \sin(\omega_0 t) = A \cos(\omega_0 t)$$

$$\sin(\omega_0 t) [-\omega_0 K_1 + 2K_2] + \cos(\omega_0 t) [\omega_0 K_2 + 2K_1] = A \cos(\omega_0 t)$$

$$\begin{aligned} -\omega_0 K_1 + 2K_2 &= 0 \Rightarrow 2K_2 = \omega_0 K_1 \Rightarrow K_2 = \frac{\omega_0}{2} K_1 \\ \omega_0 K_2 + 2K_1 &= A \Rightarrow \frac{\omega_0^2}{2} K_1 + 2K_1 = A \Rightarrow K_1 \left( \frac{\omega_0^2}{2} + 2 \right) = A \\ K_1 &= \frac{A}{\frac{\omega_0^2}{2} + 2} \quad K_2 = \frac{\frac{\omega_0}{2} A}{\frac{\omega_0^2}{2} + 2} \end{aligned}$$

$$\begin{aligned} y_p(t) &= K_1 \cos(\omega_0 t) + K_2 \sin(\omega_0 t) = \\ &= \frac{A}{\frac{\omega_0^2}{2} + 2} \cos(\omega_0 t) + \frac{\frac{\omega_0}{2} A}{\frac{\omega_0^2}{2} + 2} \sin(\omega_0 t) = \end{aligned}$$

$$= A \left[ \frac{2}{\omega_0^2 + 4} \cos(\omega_0 t) + \frac{\omega_0}{\omega_0^2 + 4} \sin(\omega_0 t) \right]$$

$$y(t) = y_h(t) + y_p(t) = C e^{-2t} + A \left[ \frac{2}{\omega_0^2 + 4} \cos(\omega_0 t) + \frac{\omega_0}{\omega_0^2 + 4} \sin(\omega_0 t) \right]$$

$$y(0) = C + A \left( \frac{2}{\omega_0^2 + 4} \right) = 0 \Rightarrow C = \frac{-2A}{\omega_0^2 + 4}$$

$$y(t) = \frac{-2A}{\omega_0^2 + 4} e^{-2t} + A \left[ \frac{2}{\omega_0^2 + 4} \cos(\omega_0 t) + \frac{\omega_0}{\omega_0^2 + 4} \sin(\omega_0 t) \right]$$

$$2A u(t) = B \cos \omega(t-1) \mu(t-1)$$

$$\boxed{y(t) = \frac{-2B}{\omega_0^2 + 4} e^{-2(t-1)} + B \cdot \left[ \frac{2}{\omega_0^2 + 4} \cos \omega_0(t-1) + \frac{\omega_0}{\omega_0^2 + 4} \sin \omega_0(t-1) \right]}$$



6.

$$\frac{dy}{dt} - y(t) = -\nu(-t)$$

$$a) y(0) = 0$$

$$y_h = ce^t$$

$$t \in (-\infty, 0) \rightarrow y_p = 1 \rightarrow$$

$$t \in (-\infty, 0] \rightarrow y_p = ce^t + 1 \rightarrow$$

$$y_p = (ce^t + 1)\nu(-t) \rightarrow \text{on } \underline{t \in \mathbb{R}}$$

$$y_p' - y_p = -\nu(-t) \rightarrow$$

$$\cancel{ce^t} \nu(-t) - (c+1)\delta(t) - (\cancel{ce^t} + 1)\cancel{\nu(-t)} = \nu(-t)$$

$$\underline{c = -1}$$

$$\rightarrow y_p = (1 - e^t)\nu(-t) \quad \underline{t \in \mathbb{R}}$$

$$\rightarrow y_h = ce^t$$

$$y = ce^t + (1 - e^t)\nu(-t)$$

$$\downarrow y(0) = 0$$

$$c = 0$$

$$a) \rightarrow y = (1 - e^t)\nu(-t)$$

$$b) y(0) = 1 \rightarrow y = e^t + (1 - e^t)\nu(-t)$$

7. Kontinuirani sustav zadan je diferencijalnom jednačbom

$$y'(t) + 2y(t) = u(t) + u'(t).$$

Provjerite, bez rješavanja zadane diferencijalne jednačbe, je li impulsni odziv ovog sustava  $h(t) = -e^{-2t}\mu(t) + \delta(t)$ .

4)  $y'(t) + 2y(t) = u(t) + u'(t)$

$h(t) = -e^{-2t}\mu(t) + \delta(t) \Rightarrow h'(t) =$

$h'(t) + 2h(t) = \delta'(t) + \delta(t)$

$h'(t) = +e^{-2t} \cdot 2\mu(t) - e^{-2t}\delta(t) + \delta'(t)$

$2e^{-2t}\mu(t) - e^{-2t}\delta(t) + \delta'(t) - 2e^{-2t}\mu(t) + 2\delta(t) = \delta'(t) + \delta(t)$

vrjednost funkcije  $-e^{-2t}$  u trenutku  $t=0$

$-e^{-2t} \Big|_{t=0} = -e^0 = -1$

$-\delta(t) + \delta'(t) + 2\delta(t) = \delta'(t) + \delta(t)$

$\delta'(t) + \delta(t) = \delta'(t) + \delta(t)$

8.

$$y'' + 2y' + y = u, \quad y(0) = 0, \quad y'(0) = 0$$

$$a) \quad u(t) = t \nu(t)$$

$$h. \text{ pedoca} \rightarrow \lambda^2 + 2\lambda + 1 = 0$$

$$(\lambda + 1)^2 = 0 \rightarrow \lambda_{1,2} = \underline{-1}$$

$$y_h = (c_1 + c_2 t) e^{-t}$$

$$y_p = A + Bt \rightarrow$$

$$2B + A + Bt = t \rightarrow \underline{B = 1}$$

$$\underline{A = -2}$$

$$y = (c_1 + c_2 t) e^{-t} + t - 2$$

$$+ \quad y(0) = 0, \quad y'(0) = 0 \rightarrow$$

$$y = (te^{-t} + 2e^{-t} + t - 2) \nu(t)$$

$$b) \text{ s obzu da } \int u \quad \nu(t) = \frac{d}{dt} \left[ t \nu(t) \right]$$

$$\rightarrow y_b = y_a' = (-e^{-t} + te^{-t} + 1) \nu(t)$$

$$c) \rightarrow \text{Auch } y_c = y_b' = te^{-t} \nu(t)$$

$$d) \rightarrow \text{lin. Komb.} \rightarrow (e^{-t} + te^{-t} + t - 1) \nu(t)$$

9. Zadan je vremenski kontinuirani sustav

$$\frac{dy(t)}{dt} + ay(t) = u(t),$$

gdje je  $u(t)$  ulaz,  $y(t)$  izlaz, a  $a$  konstanta. Početni uvjet  $y(0^-)=0$ .

- a) Naći impulsni odziv zadanog sustava.
- b) Naći odziv na jedinični skok, bez korištenja poznatog impulsnog odziva
- c) Naći odziv na jedinični skok, uz poznati impulsni odziv iz a) dijela zadatka.
- d) Naći odziv na impuls, uz poznati odziv na jedinični skok iz b) dijela zadatka.

Rješenje:

- a) Za početak je potrebno odrediti koeficijent  $b_0=0$ , te redove  $N=1$  i  $M=0$ . Rješava se prvi podsustav:

$$h_A'(t) + ah_A(t) = \delta(t),$$

odnosno homogena jednadžba

$$h_A'(t) + ah_A(t) = 0,$$

uz početni uvjet  $h_A(0^+) = 1$  (izvod početnih uvjeta – vidi predavanje).

Rješenje ove jednadžbe je  $h_A(t) = Ce^{-at}$ .

Konstanta  $C$  se dobiva iz početnog uvjeta i iznosi:  $h_A(0^+) = Ce^{-at} = C = 1$ .

Pa je  $h_A(t) = e^{-at}$ .

Kako je  $b_0=0$  i  $M=0$  automatski proizlazi da je ukupni impulsni odziv zadanog sustava

$$h(t) = e^{-at} \mu(t).$$

- b) Potrebno je riješiti jednadžbu  $y_\mu'(t) + ay_\mu(t) = \mu(t)$ .

Na temelju 13. predavanja, prikaznica 19.-29. određuje se početni uvjet  $y(0^+)=0$ .

Prvo se rješava homogena jednadžba:

$$y_{\mu h}'(t) + ay_{\mu h}(t) = 0 \rightarrow s+a=0 \rightarrow s=-a \rightarrow y_{\mu h} = Ce^{-at}.$$

Partikularno rješenje se pretpostavi iz dane pobude:

$$y_{\mu p}(t) = K\mu(t) \rightarrow aK=1 \rightarrow K = \frac{1}{a}.$$

$$\text{Totalni odziv: } y_\mu = y_{\mu h} + y_{\mu p} = \left( Ce^{-at} + \frac{1}{a} \right) \mu(t).$$

$$\text{Konstanta } C \text{ dolazi iz početnih uvjeta: } y_\mu(0^+) = C + \frac{1}{a} = 0 \rightarrow C = -\frac{1}{a}.$$

$$\text{Odziv na jediničnu stepenicu iznosi: } y_\mu(t) = \frac{1}{a}(1 - e^{-at})\mu(t).$$

- c) Drugi način određivanja odziva na jediničnu stepenicu je pomoću konvolucijskog integrala.

$$\begin{aligned} y_{\mu}(t) &= \int_{-\infty}^{\infty} h(\tau) u(t-\tau) d\tau = \int_{-\infty}^{\infty} [e^{-a\tau} \mu(\tau)] \mu(t-\tau) d\tau = \\ &= \left[ \int_0^t e^{-a\tau} d\tau \right] \mu(t) = \frac{1}{a} (1 - e^{-at}) \mu(t) \end{aligned}$$

Vidljivo je da je isto rješenje kao u b) dijelu zadatka.

- d) Ako je poznat odziv na step, vrlo lako je naći odziv na impuls, jer je poznata relacija da je impuls derivacija stepa, pa je prema tome, i impulsni odziv derivacija odziva na step.

$$\begin{aligned} h(t) &= y_{\mu}'(t) = \frac{d}{dt} \left[ \frac{1}{a} (1 - e^{-at}) \mu(t) \right] = \\ &= e^{-at} \mu(t) + \frac{1}{a} (1 - e^{-at}) \mu'(t) = e^{-at} \mu(t) + \frac{1}{a} (1 - e^{-at}) \delta(t) \end{aligned}$$

Svojstvo delta impulsa je da „izvlači“ vrijednost funkcije u nuli, pa slijedi:

$$h(t) = e^{-at} \mu(t) + \frac{1}{a} (1 - e^{-at}) \delta(t) = e^{-at} \mu(t) + \frac{1}{a} (1 - 1) \delta(t) = e^{-at} \mu(t)$$

što je identično a) dijelu zadatka.

10. Naći impulsni odziv vremenski kontinuiranog sustava:  $\frac{dy(t)}{dt} + 2y(t) = u(t) + \frac{du(t)}{dt}$ .

Rješenje:  $h(t) = -e^{-2t} \mu(t) + \delta(t)$ .

11. Kauzalni LTI kontinuirani sustav zadan je diferencijalnom jednačbom:

$$y''(t) + 6y'(t) + 13y(t) = u'(t) + 4u(t).$$

Nadite impulsni odziv ovog sustava.

5)  $y''(t) + 6y'(t) + 13y(t) = u'(t) + 4u(t)$

$h_a'(t) = c e^{st}$

$cs^2 e^{st} + 6cs e^{st} + 13c e^{st} = 0$

$c(s^2 + 6s + 13) = 0$

$s^2 + 6s + 13 = 0$

$s_{1,2} = \frac{-6 \pm j4}{2} = -3 \pm j2$

$s_1 = -3 + j2$

$s_2 = -3 - j2$

$h_a(t) = c_1 e^{(-3+j2)t} + c_2 e^{(-3-j2)t}$

$h_a'(t) = c_1 e^{(-3+j2)t} \cdot (-3+j2) + c_2 e^{(-3-j2)t} \cdot (-3-j2)$

$h_a(0^+) = 0 \quad h_a'(0^+) = 1$

$h_a(0^+) = c_1 + c_2 = 0 \quad \rightarrow c_1 = -c_2$

$h_a'(0^+) = c_1(-3+j2) + c_2(-3-j2) = 1$

$-c_1(-3+j2) + c_1(-3-j2) = 1$

$3 - j2c_1 - 3 - j2c_1 = 1$

$-j4c_1 = 1$

$c_1 = \frac{-0,25}{j} \cdot \frac{j}{j}$

$c_1 = 0,25j$

$c_2 = -0,25j$

$h_a(t) = j0,25 e^{(-3+j2)t} - j0,25 e^{(-3-j2)t}$

$h(t) = b_1 h_a'(t) + b_2 h_a(t)$

$h(t) = j0,25 e^{(-3+j2)t} (-3+j2) - j0,25 e^{(-3-j2)t} (-3-j2) - 4j0,25 e^{(-3+j2)t} + 4j0,25 e^{(-3-j2)t}$

$h(t) = j0,35 e^{(-3+j2)t} + 0,5 e^{(-3-j2)t} - j0,35 e^{(-3-j2)t} + 0,5 e^{(-3+j2)t}$

$h(t) = -j0,25 e^{(-3+j2)t} + j0,25 e^{(-3-j2)t} + 0,5 e^{(-3-j2)t} + 0,5 e^{(-3+j2)t}$



12.

Konstruktion suggested in previous lecture

$$Y(t) = \cos \omega_0(t) \nu(t) = T\{\nu(t)\}$$

$$T\{\delta(t)\} = ?$$

So obtain the  $\nu$  such linear, let's obtain

$$\text{such that } \delta(t) = \frac{d}{dt}(\nu(t)) \rightarrow$$

$$\begin{aligned} T\{\delta(t)\} &= \frac{d}{dt}(\cos \omega_0 t \nu(t)) = \\ &= -\omega_0 \sin \omega_0 t \nu(t) + \delta(t) \end{aligned}$$

13.

$$Y(t) = \int_{-\infty}^t u(\tau) d\tau \rightarrow$$

$$a) \int_{-\infty}^t \delta(\tau) d\tau = \nu(t)$$

b) stability search  $\rightarrow$  find u.

i)  $\rightarrow$  impulse order  $\nu$  bounded  
 for  $\nu \neq 0 \rightarrow$  margin  
 stability.

$$ii) Y(t) = \int_{-\infty}^t u(\tau) d\tau \quad \frac{d}{dt} \rightarrow Y' = u$$

$\rightarrow$  stable for  $s = 0 \rightarrow$  long. stb.

$$x(t) = \int_0^1 u(t-h) dh, \quad \forall t \in \mathbb{R}$$

a) impulsu odziv  $\rightarrow$

$$h(t) = \int_0^1 \delta(t-h) dh, \quad t-h = k$$

$$dh = -dk$$

$$\begin{aligned} h(t) &= -\int_t^{t-1} \delta(k) dk = \int_{t-1}^t \delta(k) dk = \\ &= \int_0^t \delta(k) dk - \int_0^{t-1} \delta(k) dk = \\ &= \gamma(t) - \gamma(t-1) \end{aligned}$$

b)  $u(t) = \sin \frac{\pi}{2} t$

$$y = \int_0^1 \sin \frac{\pi}{2} (t-h) dh = \left| \begin{array}{l} \frac{\pi}{2} (t-h) = k \\ dh = -\frac{2}{\pi} dk \end{array} \right.$$

$$= \frac{2}{\pi} \int_{\frac{\pi}{2} t}^{\frac{\pi}{2} (t-1)} \sin k dk = + \frac{2}{\pi} \cos k \Big|_{\frac{\pi}{2} t}^{\frac{\pi}{2} (t-1)}$$

$$= \frac{2}{\pi} \left[ \cos \frac{\pi}{2} t - \cos \left( \frac{\pi}{2} t - \frac{\pi}{2} \right) \right]$$

$$= \frac{2}{\pi} \left[ \cos \frac{\pi}{2} t - \sin \frac{\pi}{2} t \right]$$