

## Signali i sustavi

Auditorne vježbe 12.  
Matrični prikaz sustava

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### TRANSFORMACIJA VARIJABLI STANJA

$$\begin{cases} \dot{x} = Ax + B \cdot u \\ y = Cx + D \cdot u \end{cases}$$

$$x = P \cdot z$$

$$\dot{x} = P \cdot \dot{z}$$

- P je regularna matrica ( $\exists P^{-1} \wedge \det P \neq 0$ )

$$\begin{cases} P^{-1} \cdot \dot{x} = \dot{Pz} = APz + B \cdot u \\ y = CPz + D \cdot u \end{cases}$$

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nastavak

$$\dot{z} = \underbrace{P^{-1}AP}_{A^*} \cdot z + \underbrace{P^{-1}B}_{B^*} \cdot u$$

$$y = \underbrace{CP}_{C^*} \cdot z + \underbrace{D}_{D^*} \cdot u$$

$$\begin{cases} \dot{z} = A^* z + B^* \cdot u \\ y = C^* z + D^* \cdot u \end{cases}$$

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### nastavak

$$\begin{array}{ll} A^* = P^{-1}AP & C^* = CP \\ B^* = P^{-1}B & D^* = D \end{array}$$

- Vrijedi:
- $\det(sI - A) = \det(sI - A^*)$
- Karakteristične vrijednosti matrica  $A$  i  $A^*$  su nepromjenjene.
- Sustav je isti, ali je opisan preko drugih varijabli stanja.
- Polovi (frekvencije sustava) su isti za  $A$  i  $A^*$ .

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### nastavak

- Svaka regularna matrica  $P$  daje novi izbor stanja sustava.
- Mi ćemo odabrati takvu regularnu matricu  $P$  koja će varijable stanja transformirati u kanonske varijable stanja.
- Ako matrica  $P$  transformira matricu  $A$  u dijagonalnu (kanonske varijable stanja) onda se matrica  $P$  zove modalna i označava s  $M$ .
- Kako naći matricu  $M$ ?

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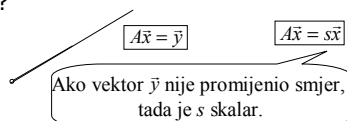
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### nastavak

- Transformacija vektora  $\vec{x}$  u vektor  $\vec{y}$ :

$$\vec{y} = A\vec{x}$$

- $A$  je matrica, matrični zapis linearnog operatora koji vektoru pridružuje vektor.
- Da li postoji takav vektor  $\vec{x}$  da transformacija  $A\vec{x}$  daje vektor  $\vec{y}$  istog smjera kao  $\vec{x}$ ?




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### nastavak

- Drukčije pisano:  $(sI - A)\vec{x} = 0$  homogena algebarska jednačba
- trivijalno rješenje:  $\vec{x} = 0$
- netrivialno rješenje dobijemo za  $\det(sI - A) = 0$  što rezultira polinomom kojeg zovemo karakteristični polinom matrice  $A$ .
- Ako je rang matrice  $A$  jednak  $n$  polinom je  $n$ -tog reda.
- Nule karakterističnog polinoma  $s_i, i = 1, n$  zovu se svojstvene vrijednosti, a vektori  $\vec{x}_i, i = 1, n$   $A\vec{x}_i = s_i \vec{x}_i$
- karakteristični vektori matrice  $A$ .

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### nastavak

- Formirajmo matricu  $P$  pomoću karakterističnih vektora matrice  $A$ .

$$P = [\vec{x}_1 \ \vec{x}_2 \ \dots \ \vec{x}_n] \quad \vec{x}_i, i = 1, n$$

- tada je:  $A \cdot P = P \cdot A^*$  karakteristični vektori

$$A \cdot P = A[\vec{x}_1 \ \vec{x}_2 \ \dots \ \vec{x}_n] = [A\vec{x}_1 \ A\vec{x}_2 \ \dots \ A\vec{x}_n]$$

$$= [s_1\vec{x}_1 \ s_2\vec{x}_2 \ \dots \ s_n\vec{x}_n] = \underbrace{[\vec{x}_1 \ \vec{x}_2 \ \dots \ \vec{x}_n]}_P \underbrace{\begin{bmatrix} s_1 & & 0 \\ & s_2 & \\ 0 & & s_n \end{bmatrix}}_{A^*}$$

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### nastavak

- $A \cdot P = P \cdot A^*$
- $A^*$  — dijagonalna  $\Rightarrow P = M$  — modalna matrica sačinjena od svojstvenih vektora matrice  $A$ .
- $A \cdot M = M \cdot A^*$
- Pomnožimo slijeva sa  $M^{-1}$ :
- $M^{-1} \cdot A \cdot M = A^*$ .

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### Zadatak 1.

Zadana je matrica **A**. Treba naći modalnu matricu **M**.

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 2 & 3 & 2 \end{bmatrix}$$

Odrediti vlastite (svojstvene) vrijednosti.

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### Zadatak 1. – Svojstvene vrijednosti

$$\det(s\mathbf{I} - \mathbf{A}) = \begin{vmatrix} s-1 & 0 & 0 \\ -1 & s-1 & 0 \\ -2 & -3 & s-2 \end{vmatrix} = 0$$

$$\begin{vmatrix} s-1 & 0 & 0 \\ -1 & s-1 & 0 \\ -2 & -3 & s-2 \end{vmatrix} = (s-1)^2(s-2) \quad \begin{matrix} s_1 = 2 \\ s_2 = s_3 = 1 \end{matrix}$$

Formiranje matrice **A\***

$$\mathbf{A}^* = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \quad \begin{matrix} \text{Jordanov blok} \\ \text{(Jordanova kljetka)} \end{matrix}$$

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### Zadatak 1.

- Odrediti vlastite vektore, matricu **M**. Vrijedi  $\mathbf{AM} = \mathbf{MA}^*$

$$\mathbf{A} \begin{bmatrix} \mathbf{x}_1 & \mathbf{x}_2 & \mathbf{x}_3 \end{bmatrix} = \begin{bmatrix} \mathbf{x}_1 & \mathbf{x}_2 & \mathbf{x}_3 \end{bmatrix} \begin{bmatrix} s_1 & 0 & 0 \\ 0 & s_2 & 1 \\ 0 & 0 & s_3 \end{bmatrix}$$

$$\begin{bmatrix} \mathbf{Ax}_1 & \mathbf{Ax}_2 & \mathbf{Ax}_3 \end{bmatrix} = \begin{bmatrix} s_1\mathbf{x}_1 & s_2\mathbf{x}_2 & s_3\mathbf{x}_3 + \mathbf{x}_2 \end{bmatrix}$$

$$\mathbf{Ax}_1 = s_1\mathbf{x}_1 \quad (1)$$

$$\mathbf{Ax}_2 = s_2\mathbf{x}_2 \quad (2)$$

$$\mathbf{Ax}_3 = s_3\mathbf{x}_3 + \mathbf{x}_2 \quad (3)$$

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### Zadatak 1.

• (1)

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 2 & 3 & 2 \end{bmatrix} \cdot \begin{bmatrix} x_{11} \\ x_{21} \\ x_{31} \end{bmatrix} = 2 \cdot \begin{bmatrix} x_{11} \\ x_{21} \\ x_{31} \end{bmatrix}$$

$$\begin{cases} x_{11} = 2x_{11} \\ x_{11} + x_{21} = 2x_{21} \\ 2x_{11} + 3x_{21} + 2x_{31} = 2x_{31} \end{cases} \Rightarrow \begin{cases} x_{11} = 0 \\ x_{21} = 0 \\ x_{31} \text{ proizvoljno } x_{31} = 1 \quad (\neq 0) \end{cases}$$

$$\vec{x}_1 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

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### Zadatak 1.

• (2)

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 2 & 3 & 2 \end{bmatrix} \cdot \begin{bmatrix} x_{12} \\ x_{22} \\ x_{32} \end{bmatrix} = 1 \cdot \begin{bmatrix} x_{12} \\ x_{22} \\ x_{32} \end{bmatrix}$$

$$\begin{cases} x_{12} = x_{12} \\ x_{12} + x_{22} = x_{22} \\ 2x_{12} + 3x_{22} + 2x_{32} = x_{32} \end{cases} \Rightarrow \begin{cases} x_{12} = 0, & x_{22} = 1 \text{ (proizvoljno)} \\ & x_{32} = -3 \end{cases}$$

$$\vec{x}_2 = \begin{bmatrix} 0 \\ 1 \\ -3 \end{bmatrix}$$

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### Zadatak 1.

• (3)

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 2 & 3 & 2 \end{bmatrix} \cdot \begin{bmatrix} x_{13} \\ x_{23} \\ x_{33} \end{bmatrix} = 1 \cdot \begin{bmatrix} x_{13} \\ x_{23} \\ x_{33} \end{bmatrix} + \begin{bmatrix} x_{12} \\ x_{22} \\ x_{32} \end{bmatrix}$$

$$\begin{cases} x_{13} = x_{13} + x_{12} \\ x_{13} + x_{23} = x_{23} + x_{22} \\ 2x_{13} + 3x_{23} + 2x_{33} = x_{33} + x_{32} \end{cases} \Rightarrow \begin{cases} x_{13} = x_{13} \\ x_{13} + x_{23} = x_{23} + 1 \\ 2x_{13} + 3x_{23} + 2x_{33} = x_{33} - 3 \end{cases} \Rightarrow$$

$$\Rightarrow x_{13} = 1, x_{23} = 1 \text{ (proizvoljno)} \Rightarrow x_3 = \begin{bmatrix} 1 \\ 1 \\ -8 \end{bmatrix}$$

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### Zadatak 1.

$$M = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & -3 & -8 \end{bmatrix}$$

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### Posebni slučaj

- Specijalni slučaj: korijeni (svojstvene vrijednosti) matrice  $A$  su različiti.
- Recept: stupci matrice  $M$  mogu se uzeti jednaki ili proporcionalni bilo kojem stupcu adjungirane pridružene matrice  $\text{adj}(s_i I - A)$  koji nije nul-stupac.

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### Adjungirana matrica?

- $\text{adj}(A) = ?$
- $\text{adj}(A) = [x_{ij}]^T$ ,
- $x_{ij} = (-1)^{i+j} \cdot D_{ij}$ .
- $D_{ij}$  = determinanta podmatrice  $A$  dobivena izbacivanjem  $i$ -tog retka i  $j$ -tog stupca.
- $^T$  transponiranje —  $i$ -ti redak postaje  $i$ -ti stupac.

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### Zadatak 2.

Zadana je matrica:

$$A = \begin{bmatrix} 2 & -2 & 3 \\ 1 & 1 & 1 \\ 1 & 3 & -1 \end{bmatrix}$$

Naći modalnu matricu  $M$ .

$$sI - A = \begin{bmatrix} s-2 & 2 & -3 \\ -1 & s-1 & -1 \\ -1 & -3 & s+1 \end{bmatrix}$$

$$\det(sI - A) = 0$$

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### Zadatak 2. - nastavak

- $s^3 - 2s^2 - 5s + 6 = (s - 1)(s + 2)(s - 3) = 0$
- $s_1 = 1$
- $s_2 = -2$
- $s_3 = 3$

$$\text{adj}(sI - A) = \begin{bmatrix} s^2 - 4 & -2s + 7 & 3s - 5 \\ s + 2 & s^2 - s - 5 & s + 1 \\ s + 2 & 3s - 8 & s^2 - 3s + 4 \end{bmatrix}$$

Pojašnjenje:

$$sI - A = \begin{bmatrix} s-2 & 2 & -3 \\ -1 & s-1 & -1 \\ -1 & -3 & s+1 \end{bmatrix}$$

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### Zadatak 2. - nastavak

- $s^3 - 2s^2 - 5s + 6 = (s - 1)(s + 2)(s - 3) = 0$
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Pojašnjenje:

$$sI - A = \begin{bmatrix} s-2 & 2 & -3 \\ -1 & s-1 & -1 \\ -1 & -3 & s+1 \end{bmatrix}$$

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### Zadatak 2. - nastavak

- $s^3 - 2s^2 - 5s + 6 = (s - 1)(s + 2)(s - 3) = 0$
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- $s_2 = -2$
- $s_3 = 3$

$$\text{adj}(sI - A) = \begin{bmatrix} s^2 - 4 & -2s + 7 & 3s - 5 \\ s + 2 & s^2 - s - 5 & s + 1 \\ s + 2 & 3s - 8 & s^2 - 3s + 4 \end{bmatrix}$$

Pojašnjenje:

$$sI - A = \begin{bmatrix} s-2 & 1 & 3 \\ -1 & s+1 & -1 \\ -1 & -3 & s+1 \end{bmatrix} \quad \text{itd.}$$

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### Zadatak 2. - nastavak

- $s = s_1 = 1$

$$\text{adj}(s_1 I - A) = \begin{bmatrix} -3 & 5 & -2 \\ 3 & -5 & 2 \\ 3 & -5 & 2 \end{bmatrix}$$

- $s = s_2 = -2$

$$\text{adj}(s_2 I - A) = \begin{bmatrix} 0 & 11 & -11 \\ 0 & 1 & -1 \\ 0 & -14 & 14 \end{bmatrix}$$

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### Zadatak 2. - nastavak

- $s = s_3 = 3$

$$\text{adj}(s_3 I - A) = \begin{bmatrix} 5 & 1 & 4 \\ 5 & 1 & 4 \\ 5 & 1 & 4 \end{bmatrix}$$

$$M = \begin{bmatrix} -1 & 11 & 1 \\ 1 & 1 & 1 \\ 1 & -14 & 1 \end{bmatrix}$$

$$A^* = M^{-1} \cdot A \cdot M = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

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### Posebni slučaj

- Specijalni slučaj: direktna realizacija
- Recept

$$A = \begin{bmatrix} 0 & 1 & 0 \\ & 0 & 1 \\ & & \ddots & 1 \\ -a_0 & -a_1 & -a_2 & -a_n \end{bmatrix}$$

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### Nastavak

- Neka su  $s_i, i = 1, \dots, n$  jednostruki polovi.
- Tada M konstruiramo na slijedeći način:

$$M = \begin{bmatrix} 1 & 1 & \dots & 1 \\ s_1 & s_2 & \dots & s_n \\ s_1^2 & s_2^2 & \dots & s_n^2 \\ \vdots & \vdots & \ddots & \vdots \\ s_1^{n-1} & s_2^{n-1} & \dots & s_n^{n-1} \end{bmatrix}$$

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### Nastavak

- Slučaj višestrukih polova npr.:

- $s_1 = s_2 =$
- $s_3 = s_4,$
- $s_5 = s_6,$
- $s_7$

$$\begin{bmatrix} 1 & 0 \\ s_1 & 1 \\ s_1^2 & \frac{2s_1}{1!} \\ s_1^3 & \frac{3s_1^2}{1!} \\ s_1^4 & \frac{4s_1^3}{1!} \\ s_1^5 & \frac{5s_1^4}{1!} \\ s_1^6 & \frac{6s_1^5}{1!} \end{bmatrix}$$

derivacija prethodnog stupca, podijeljena s 1 faktoriijela

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### Nastavak

- Slučaj višestrukih polova npr.:
- $s_1 = s_2 =$
- $s_3 = s_4,$
- $s_5 = s_6,$
- $s_7$

$$\begin{bmatrix} 1 & 0 & 0 \\ s_1 & 1 & 0 \\ s_1^2 & \frac{2s_1}{1!} & 1 \\ s_1^3 & \frac{3s_1^2}{1!} & \frac{6s_1}{2!} \\ s_1^4 & \frac{4s_1^3}{1!} & \frac{12s_1^2}{2!} \\ s_1^5 & \frac{5s_1^4}{1!} & \frac{20s_1^3}{2!} \\ s_1^6 & \frac{6s_1^5}{1!} & \frac{30s_1^4}{2!} \end{bmatrix}$$

derivacija prethodnog stupca, podijeljena s 2 faktoriijela

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### Nastavak

- Slučaj višestrukih polova npr.:
- $s_1 = s_2 =$
- $s_3 = s_4,$
- $s_5 = s_6,$
- $s_7$

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 0 & 1 \\ s_1 & 1 & 0 & 0 & s_5 & 1 & s_7 \\ s_1^2 & \frac{2s_1}{1!} & 1 & 0 & s_5^2 & \frac{2s_5}{1!} & s_7^2 \\ s_1^3 & \frac{3s_1^2}{1!} & \frac{6s_1}{2!} & 1 & s_5^3 & \frac{3s_5^2}{1!} & s_7^3 \\ s_1^4 & \frac{4s_1^3}{1!} & \frac{12s_1^2}{2!} & \frac{24s_1}{3!} & s_5^4 & \frac{4s_5^3}{1!} & s_7^4 \\ s_1^5 & \frac{5s_1^4}{1!} & \frac{20s_1^3}{2!} & \frac{60s_1^2}{3!} & s_5^5 & \frac{5s_5^4}{1!} & s_7^5 \\ s_1^6 & \frac{6s_1^5}{1!} & \frac{30s_1^4}{2!} & \frac{120s_1^3}{3!} & s_5^6 & \frac{6s_5^5}{1!} & s_7^6 \end{bmatrix}$$

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### Zadatak 3.

- Zadana je matrica A, naći M i A\*

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & -3 & 3 \end{bmatrix}$$

- Jasno, radi se o direktnoj realizaciji.

$$sI - A = \begin{bmatrix} s & -1 & 0 \\ 0 & s & -1 \\ -1 & 3 & s-3 \end{bmatrix}$$

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### Nastavak

- $\det(s\mathbf{I} - \mathbf{A}) = s^3 - 3s^2 + 3s - 1,$
- $= (s - 1)^3.$
- $s_1 = s_2 = s_3 = 1.$
- Slijedi matrica M:

$$M = \begin{bmatrix} 1 & 0 & 0 \\ s_1 & 1 & 0 \\ s_1^2 & \frac{2s_1}{1!} & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 2 & 1 \end{bmatrix}$$

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### Nastavak

- Matrica  $\mathbf{A}^*$  je naravno:

$$\mathbf{A}^* = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

Provjeriti da je  $\mathbf{A}^* = \mathbf{M}^{-1} \mathbf{A} \mathbf{M} !$

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### Odziv linearnih sustava

$$\mathbf{x}' = \mathbf{A}\mathbf{x} + \mathbf{B}\mathbf{u}, \quad t_0 = 0.$$

$$s\mathbf{X}(s) - \mathbf{x}(0) = \mathbf{A} \mathbf{X}(s) + \mathbf{B} \mathbf{U}(s),$$

$$(s\mathbf{I} - \mathbf{A}) \mathbf{X}(s) = \mathbf{x}(0) + \mathbf{B} \mathbf{U}(s).$$

Pomnožimo slijeva sa  $(s\mathbf{I} - \mathbf{A})^{-1}$ :

$$\mathbf{X}(s) = (s\mathbf{I} - \mathbf{A})^{-1} \mathbf{x}(0) + (s\mathbf{I} - \mathbf{A})^{-1} \mathbf{B} \mathbf{U}(s),$$

$$\Phi(s) = (s\mathbf{I} - \mathbf{A})^{-1},$$

– matrica karakterističnih frekvencija.

$$\mathbf{X}(s) = \Phi(s) \mathbf{x}(0) + \Phi(s) \mathbf{B} \mathbf{U}(s). \quad (1)$$

$$\mathbf{y} = \mathbf{C}\mathbf{x} + \mathbf{D}\mathbf{u},$$

$$\mathbf{Y}(s) = \mathbf{C} \mathbf{X}(s) + \mathbf{D} \mathbf{U}(s),$$

$$\mathbf{Y}(s) = \mathbf{C} \Phi(s) \mathbf{x}(0) + [\mathbf{C} \Phi(s) \mathbf{B} + \mathbf{D}] \mathbf{U}(s). \quad (2)$$

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### Nastavak ...

- $\mathbf{H}(s) = \mathbf{C}\Phi(s)\mathbf{B} + \mathbf{D}$ ,  
– transfer matrica.
- Pretvorimo (1) u donje područje

$$\mathbf{x}(t) = \Phi(t) \cdot \mathbf{x}(0) + \int_0^t \Phi(t-\tau) \mathbf{B} \mathbf{u}(\tau) d\tau.$$

- $\Phi(t)$  – fundamentalna (prijelazna) matrica.
- Pretvorimo (2) u donje područje

$$\mathbf{y}(t) = \mathbf{C}\Phi(t) \cdot \mathbf{x}(0) + \int_0^t \mathbf{C}\Phi(t-\tau) \mathbf{B} \mathbf{u}(\tau) d\tau + \mathbf{D}\mathbf{u}(t).$$

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### Zadatak 4.

- Zadane su matrice  $\mathbf{A}$ ,  $\mathbf{B}$ ,  $\mathbf{C}$ ,  $\mathbf{D}$  kontinuiranog sustava, te pobuda  $u$ .  
Odredi odziv sustava i napiši matricu impulsnog odziva.

$$\mathbf{A} = \begin{bmatrix} 0 & -2 \\ 1 & -3 \end{bmatrix}, \quad \mathbf{B} = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}, \quad \mathbf{C} = [1 \quad 0], \quad \mathbf{D} = [0 \quad 1]$$

$$\mathbf{u}(t) = \begin{bmatrix} 2\delta(t) \\ s(t) \end{bmatrix}, \quad \mathbf{x}(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$$

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### Rješenje

$$\Phi(s) = (s\mathbf{I} - \mathbf{A})^{-1}, \quad \mathbf{A}^{-1} = \frac{1}{\det(\mathbf{A})} \cdot \text{adj}(\mathbf{A}),$$

$$s\mathbf{I} - \mathbf{A} = \begin{bmatrix} s & 2 \\ -1 & s+3 \end{bmatrix}, \quad \text{adj}(s\mathbf{I} - \mathbf{A}) = \begin{bmatrix} s+3 & -2 \\ 1 & s \end{bmatrix},$$

$$\det(s\mathbf{I} - \mathbf{A}) = (s+1)(s+2),$$

$$\Phi(s) = (s\mathbf{I} - \mathbf{A})^{-1} = \frac{1}{(s+1)(s+2)} \cdot \begin{bmatrix} s+3 & -2 \\ 1 & s \end{bmatrix}.$$

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*Nastavak ...*

$$\Phi(s) = \begin{bmatrix} -\frac{1}{s+2} + \frac{2}{s+1} & \frac{2}{s+2} - \frac{2}{s+1} \\ -\frac{1}{s+2} + \frac{1}{s+1} & \frac{2}{s+2} - \frac{1}{s+1} \end{bmatrix} \begin{matrix} \text{matrica} \\ \text{karakterističnih} \\ \text{frekvencija} \end{matrix}$$

- Transformacijom  $\Phi(s)$  u  $\Phi(t)$  dobivamo :

$$\Phi(t) = \begin{bmatrix} -e^{-2t} + 2e^{-t} & 2e^{-2t} - 2e^{-t} \\ -e^{-2t} + e^{-t} & 2e^{-2t} - e^{-t} \end{bmatrix} \begin{matrix} \text{prijelazna ili} \\ \text{fundamentalna} \\ \text{matrica} \end{matrix}$$

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*Nastavak ...*

- Skraćeno zapisano :

$$\Phi(t) = \begin{bmatrix} \varphi_{11}(t) & \varphi_{12}(t) \\ \varphi_{21}(t) & \varphi_{22}(t) \end{bmatrix},$$

$$C\Phi(t) = [1 \quad 0] \begin{bmatrix} \varphi_{11} & \varphi_{12} \\ \varphi_{21} & \varphi_{22} \end{bmatrix} = [\varphi_{11} \quad \varphi_{12}]$$

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*Nastavak ...*

- Skraćeno zapisano :

$$\Phi(t) = \begin{bmatrix} \varphi_{11}(t) & \varphi_{12}(t) \\ \varphi_{21}(t) & \varphi_{22}(t) \end{bmatrix},$$

$$C\Phi(t) = [1 \quad 0] \begin{bmatrix} \varphi_{11} & \varphi_{12} \\ \varphi_{21} & \varphi_{22} \end{bmatrix} = [\varphi_{11} \quad \varphi_{12}]$$

$$C\Phi(t)B = [\varphi_{11} \quad \varphi_{12}] \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} = [2\varphi_{11} \quad \varphi_{12}]$$

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*Nastavak ...*

$$\mathbf{y}(t) = \begin{bmatrix} \varphi_{11}(t) & \varphi_{12}(t) \\ \varphi_{21}(t) & \varphi_{22}(t) \end{bmatrix} \begin{bmatrix} x_1(0) \\ x_2(0) \end{bmatrix} + \int_0^t \begin{bmatrix} 2\varphi_{11}(t-\tau) & \varphi_{12}(t-\tau) \\ \varphi_{21}(t-\tau) & 2\varphi_{22}(t-\tau) \end{bmatrix} \begin{bmatrix} 2\delta(\tau) \\ S(\tau) \end{bmatrix} d\tau +$$

$$+ \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} 2\delta(t) \\ S(t) \end{bmatrix}.$$

$$\mathbf{y}(t) = \varphi_{11}(t)x_1(0) + \varphi_{12}(t)x_2(0) +$$

$$+ \int_0^t [4\varphi_{11}(t-\tau)\delta(\tau) + \varphi_{12}(t-\tau)S(\tau)]d\tau +$$

$$+ 0 \cdot 2\delta(t) + 1 \cdot S(t).$$

*Nastavak ...*

$$y(t) = (-e^{-2t} + 2e^{-t})x_1(0) + (2e^{-2t} - 2e^{-t})x_2(0) +$$

$$+ 4 \int_0^t -e^{-2(t-\tau)}\delta(\tau)d\tau + 4 \int_0^t 2e^{-(t-\tau)}\delta(\tau)d\tau +$$

$$+ \int_0^t 2e^{-2(t-\tau)}S(\tau)d\tau + \int_0^t -2e^{-(t-\tau)}S(\tau)d\tau + 0 \cdot 2\delta(t) + 1 \cdot S(t).$$

$$\int_0^t f(t)\delta(t)dt = f(0).$$

*Nastavak ...*

$$\mathbf{y}(t) = \underbrace{[2x_1(0) + 2x_2(0)]e^{-t} + [2x_2(0) - x_1(0)]e^{-2t}}_{\text{slobodni odziv}} +$$

$$+ \underbrace{10e^{-t}S(t) - 5e^{-2t}S(t) + 0 \cdot 2\delta(t) + 1 \cdot S(t)}_{\text{prisilni odziv}}.$$

*Nastavak ...*

- Transfer matrica

$$\mathbf{H}(s) = \mathbf{C}\Phi\mathbf{B} + \mathbf{D}$$

$$= [2\varphi_{11}(s) \quad \varphi_{12}(s)] + [0 \quad 1]$$

$$= [2\varphi_{11}(s) \quad \varphi_{12}(s) + 1]$$

$$= \left[ -\frac{2}{s+2} + \frac{4}{s+1} \quad \frac{2}{s+2} - \frac{2}{s+1} + 1 \right]$$

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*Nastavak ...*

- Transformacijom  $\mathbf{H}(s)$  u  $\mathbf{h}(t)$  dobivamo

$$\mathbf{h}(t) = [-2e^{-2t} + 4e^{-t} \quad 2e^{-2t} - 2e^{-t} + \delta(t)]$$

- Broj redaka od  $\mathbf{H}(s) \equiv$  broj izlaza.
- Broj stupaca od  $\mathbf{H}(s) \equiv$  broj ulaza.

$$H_{ij}(s) = \frac{i - \text{ti izlaz}}{j - \text{ti ulaz}}, \quad \mathbf{H}(s) = [H_{ij}(s)]$$

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