SIGNALI I SUSTAVI TJEDAN 14.

MARKO GULIN 0036428227

1. y'(+) + 5y(+) + 2 = u(+) -> y'(+) = u(+) - 5y(+) -2

ult = Lun(t) + Bu2(t)

4,10) = 4,10) -2

 $y_2(0) = U_2(0) - 2$

y'(0) = u(0) - 2

y (0) = Lun(0) + Bu2(0) -2

y'(0) = Ly1(0) + By2(0) + 2 → SUSTAV NIJE LINEARAN.

U SLUČAJU DA JE SUSTAV LINEARAN, I JOŠ K
TOMU I VREMENSKI NEPROMJENJIV (LTI), MOGLI BISMO
PRONACI ODZIV NA BILO KOJU POBUDU UZ KOJA
SE MOŽE PRIKAZATI KAO LINEARNA KOMBINACIJA
IZ PRVOG SIGNALA U (MORAMO ZNATI ODZIV NA
POBUDU U)

2. y"(+) - y"(+) + y'(+) + 39 y(+) = u"(+) + 2u(+)

· TRAZENJE VLASTITIH FREKVENCIJA

yn(t) = Cest

Cest (53-52+5+39) = 0, Cest + 0

-1-

53-52+5+39=0

JEDNO RJEŠENJE MORAMO POGODITI, A DRUGA

DVA ĆEMO DOBITI RJEŠAVANJEM KVADRATNE

JEDNADŽBE KOJU DOBIJEMO SLJEDEĆIM POSTUPKOM $(S^3-S^2+S+39):(S-S_0)=\alpha_0S^2+\alpha_0S+\alpha_2$

$$(5^{3} + 5^{2} + 5 + 39) : (5 + 3) = 5^{2} - 45 + 13$$

$$-5^{2} + 35^{2}$$

$$-45^{2} + 5$$

$$+45^{2} + 125$$

$$135 + 39$$

$$-135 \pm 39$$

$$S^{2} - 4S + 13 = 0$$

$$S_{2,3} = \frac{4 \pm \sqrt{16-52}}{2}$$

$$S_{2,3} = \frac{4 \pm jG}{2}$$

$$S_{2,3} = \frac{4 \pm jG}{2}$$

$$S_{2,3} = 2 + j3, \quad S_{3,3} = 2 - j3$$

$$Re$$

SUSTAV JE NESTABILAN.

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3.
$$y'(t) + y(t) = u'(t) + 2u$$

 $u(t) = 3\nu(t)$

· OPCA HOMOGENA JEDNADZBA

· PARTIKULARNA JEDNADZBA

$$U(t) = 3N(t) \rightarrow y_p(t) = K$$

$$y(t) = y_{n}(t) + y_{n}(t)$$

$$y(t) = C_{1}e^{-t} + C_{1} + C_{2} + C_{3} + C_{4} + C_{5} + C_$$

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5.
$$y'(t) + 2y(t) = u(t)$$

· PARTIKULARNA JEDNADZBA

$$u(t) = A\cos(wot) \rightarrow yp(t) = K_1\cos(wot) + K_2\sin(wot)$$

 $yp'(t) = -woK_1\sin(wot) + woK_2\cos(wot)$

-
$$wo K_1 sin(wot) + wo K_2 cos(wot) + 2K_1 cos(wot) + 2K_2 sin(wot) = A cos(wot)$$

$$cos(wot) (wo K_2 + 2K_1) + sin(wot)(-woK_1 + 2K_2) = A cos(wot)$$

$$WOK_2 + 2K_1 = A$$

$$-WOK_1 + 2K_2 = 0$$
 $K_1 = \frac{2}{4 + WO^2}A$
 $K_2 = \frac{WO}{4 + WO^2}A$

$$y(t) = C_1 e^{-2t} + \frac{2}{4 + wo^2} A \cos(wot) + \frac{wo}{4 + w^2} A \sin(wot)$$

$$y(0) = C_1 + \frac{2}{4 + w_0^2} A = 0$$

$$C_A = -\frac{2}{4 + Wo^2} A$$

$$y(t) = \frac{-2}{4+w_0^2} A e^{-2t} + \frac{2}{4+w_0^2} A \cos(w_0 t) + \frac{w_0}{4+w_0^2} A \sin(w_0 t)$$

· ODZIV NA POBUDU U(t) = B cos(wo(t-n)) p(t-n)

$$y_n(t) = y(t-1)$$

$$y_1(t) = \frac{-2}{4+w_0^2} Be^{-2(t-1)} + \frac{2}{4+w_0^2} B\cos(w_0(t-1)) + \frac{w_0}{4+w_0^2} A\sin(w_0(t-1))$$

6. y'(t) - y(t) = -u(t)

$$u(t) = \mu(-t) \rightarrow u(t) = 1, t \le 0$$

. OPCA HOMOGENA JEDNADZBA

· PARTIKULARNA JEDNADZBA

$$u(t) = N(-t) \rightarrow yp(t) = K$$

$$y(t) = y_{n}(t) + y_{p}(t)$$

$$y(t) = C_{n}e^{t} + 1, t = 0$$

$$y(0) = C_{n} + 1 = 0$$

$$y(0) = C_{n} + 1, t = 0$$

$$y(0) = C_{n} + 1, t = 0$$

$$y(0) = C_{n} + 1$$

$$y(0)$$

- 7 -

8.
$$y''(t) + 2y'(t) + y(t) = u(t)$$
 $y(0) = y'(0) = 0$
 $y(0') = y'(0') = 0$
 $y''(t) = y'(0') = 0$
 $y'''(t) = u(t) - 2y'(t) - y(t)$
 $y'''(0) = u(0) - 2y'(0) - y(0)$
 $y'''(0) = u(0)$
 $u(t) = \mathcal{L}u_1(0) + \mathcal{L}u_2(0)$
 $y'''(0) = \mathcal{L}u_1(0) + \mathcal{L}u_1(0)$
 $y'''(0) = \mathcal{L}u_1(0) + \mathcal{L}u_1$

-8-

$$y(t) = y_n(t) + y_p(t)$$

$$y(t) = (C_1 + C_2 + t)e^{-t} - 2 + t$$

$$y'(t) = (-C_1 + C_2 - C_2 + t)e^{-t} + 1$$

$$y(0) = C_1 - 2 = 0$$

$$C_1 = 2$$

$$y'(0) = -C_1 + C_2 + 1 = 0$$

$$y(t) = (2+t)e^{-t} - 2 + t, t > 0$$

(b)
$$U_{b}(t) = \mu(t)$$

$$Ua(t) = \mu(t) = Ub(t)$$

ZBOG LINEARNOSTI SUSTAVA MOZEMO PISATI

(c)
$$U_c(t) = \delta(t)$$

$$Ub(t) = \mu(t) \rightarrow Ub(t) = \delta(t) = Uc(t)$$

$$y_c(t) = y_b(t)$$

 $y(t) = te^{-t}, t > 0$

(d)
$$u_a(t) = t_N(t) + N(t) + \delta(t)$$

$$u_{\alpha}(t) = u_{\alpha}(t) + u_{b}(t) + u_{c}(t) \rightarrow y_{\alpha}(t) = y_{\alpha}(t) + y_{b}(t) + y_{c}(t)$$

 $y(t) = (n+t)e^{-t} - n + t, t \ge 0$

9.
$$y'(t) + ay(t) = u(t)$$

 $y(0) = 0 \rightarrow y(0^{\dagger}) = 0$

(a)
$$u(t) = \delta(t)$$

$$a_1 = a$$
, $b_1 = 1$

$$h_{A}(t) + \alpha h_{A}(t) = \delta(t)$$

$$h_A(t) = C_1 e^{-\alpha t}$$

$$h_{A}(0^{+}) = C_{1} = 1$$

$$C_1 = 1$$

$$h_A(t) = e^{-\alpha t}$$

$$h(t) = \sum_{m=0}^{M} (b_{N-m} D^m) h_A(t)$$

TUEDAN TE

(b)
$$u(t) = \mu(t) \rightarrow y_P(t) = A$$

$$y_P(t) = 0$$

$$A = 1$$

$$A = \frac{1}{\alpha}, t \ge 0 \rightarrow yp(t) = \frac{1}{\alpha}, t \ge 0$$

OF.

$$y(t) = y_n(t) + y_p(t)$$

 $y(t) = C_1 e^{-at} + \frac{1}{a}$

$$y(0^{\dagger}) = C_1 + \frac{1}{\alpha} = 0$$

$$C_1 = -\frac{1}{\alpha}$$

$$y(t) = \frac{1}{\alpha} (1 - e^{-\alpha t}), t > 0$$

(c)
$$u(t) = \mu(t)$$

 $y(t) = \int_{-\infty}^{\infty} h(\tau) u(t-\tau) d\tau$
 $y(t) = \int_{-\infty}^{\infty} e^{-\alpha \tau} \mu(\tau) \cdot \mu(t-\tau) d\tau$
 $y(t) = \left\{ \int_{0}^{t} e^{-\alpha \tau} d\tau \right\} \mu(t)$
 $y(t) = \frac{1}{\alpha} (1 - e^{-\alpha t}) \mu(t)$

(d)
$$U_a(t) = \delta(t)$$

 $U_b(t) = N(t) \rightarrow U_a(t) = U_b(t)$

SUSTAV JE LINEARAN TE STOGA MOZEMO PISATI

$$y(t) = e^{-\alpha t} \mu(t)$$

$$N = M = 1$$

$$a_1 = 2$$
, $b_0 = b_1 = 1$

$$h_{A}(t) + 2h_{A}(t) = \delta'(t) + \delta(t)$$

$$h_A(t) = e^{-2t}, t>0$$

$$h(t) = \prod_{m=0}^{M} (b_{N-m} D^m) h_A(t) + \delta(t)$$

$$h(t) = h_{A}(t) + h_{A}(t) + \delta(t)$$

$$h(t) = -e^{-2t} + \delta(t)$$
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11. y''(t) + 6y'(t) + 13y(t) = u'(t) + 4u(t)

N=2, M=1

an=G, an=13

bo = 0, b1 = 1, b2 = 4

ha"(t) + 6ha'(t) + 13ha(t) = 8'(t) + 48(t)

 $h_{A}(0^{+}) = 0$ $h_{A}(0^{+}) = 1$

ha"(t) + Gha(t) + 13ha(t) = 0

Cest (52+65+13) = 0, Cest + 0

52+65+13=0 -> 51,2=-3+j2

 $S_1 = -3 + j2$, $S_2 = -3 - j2$

ha(t) = A = 3t e + j2t + B = 3t e - j2t

ha(t) = e-3t (Ae+j2t + Be-j2t)

halt) = e-3t (C1 cos(2t) + C2 sin(2t))

 $h_a'(t) = e^{-3t} (C_1(-3\cos(2t) - 2\sin(2t)) + C_2(-3\sin(2t) + 2\cos(2t)))$

 $h_A(0) = C_1 = 0$ } $C_1 = 0$, $C_2 = \frac{1}{2}$

 $h_A(t) = \frac{A}{2} e^{-3t} \sin(2t)$

 $h_a'(t) = e^{-3t}(\cos(2t) - \frac{3}{2}\sin(2t))$

h(t) = b2 ha(t) + b, ha(t)

 $h(t) = e^{-3t}(\cos(2t) + \frac{1}{2}\sin(2t)), t \ge 0$

$$y_2(t) = -wosin(wot)\mu(t) + \delta(t)$$

$$h(t) = -wosin(wot)\mu(t) + \delta(t)$$

(a)
$$u(t) = \delta(t)$$

 $h(t) = \int_{0}^{t} \delta(t) dt$

$$h(t) = \mu(t)$$

SUPSTITUCIJA:

$$dh = -dT$$

GRANICE:

$$h = 1 \rightarrow t - \tau = 1$$
 $h = 0 \rightarrow t - \tau = 0$

$$\tau = t-1$$
 $\tau = t$

$$y(t) = \int_{t}^{t-1} u(\tau) d\tau$$

$$y(t) = \int_{-\infty}^{\infty} u(\tau) d\tau$$

(a)
$$u(t) = \delta(t)$$

$$h(t) = \int_{t-1}^{t} \delta(t) dt = \int_{0}^{t} \delta(t) dt + \int_{t-1}^{0} \delta(t) dt$$

$$h(t) = \int_{0}^{t} \delta(t) dt - \int_{0}^{t} \delta(t) dt$$

$$h(t) = \mu(t) - \mu(t-1)$$

(b)
$$u(t) = \sin(\frac{\pi}{2}t)$$
, $\forall t \in \mathbb{R}$
 $y(t) = \int_{t-1}^{t} \sin(\frac{\pi}{2}t) dt$
 $y(t) = \frac{2}{\pi} \cos(\frac{\pi}{2}t) \Big|_{t}$
 $y(t) = \frac{2}{\pi} (\cos(\frac{\pi}{2}t - \frac{\pi}{2}) - \cos(\frac{\pi}{2}t))$

$$y(t) = \frac{2}{\pi} \left(\sin(\frac{\pi}{2}t) - \cos(\frac{\pi}{2}t) \right)$$