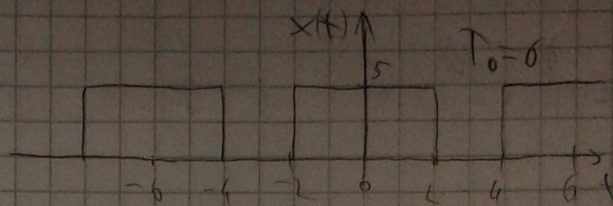


3. August 2015

1.

$$T_p = 6$$



a) CTF, Amp relation.

$$X[k] = \frac{1}{T_p} \int_{T_p} x(t) e^{-j\omega_p k t} dt = \frac{5}{6} \int_{-2}^2 e^{-j\omega_p k t} dt =$$

$$= \frac{5}{6} \cdot \frac{1}{-j\omega_p k} \left[e^{-j\omega_p k t} \right]_{-2}^2 = \frac{5}{6} \cdot \frac{1}{-j\omega_p k} \left(e^{-2j\omega_p k} - e^{2j\omega_p k} \right) =$$

$$= \frac{5}{6} \cdot \frac{1}{j\omega_p k} \left(e^{2j\omega_p k} - e^{-2j\omega_p k} \right) = \frac{5}{3} \cdot \frac{1}{j\omega_p k} \sin(2\omega_p k)$$

$$\omega_p = 2\pi / T_p = \frac{\pi}{3}$$

$$\Rightarrow X[k] = \frac{5}{j\pi k} \sin\left(\frac{2\pi}{3} k\right)$$

b) $D = ?$

$$P = \frac{1}{6} \int_{-2}^2 25 dt = \frac{25}{6} \cdot 2 = \frac{25}{3} + \frac{25}{3} = \frac{50}{3}$$

$$c) \frac{1}{T_p} \int_{T_p} x(t) x^*(t) dt = \sum_{k=-\infty}^{\infty} X_1[k] X_2^*[k]$$

$$\frac{1}{T_p} \int_{T_p} x(t) x^*(t) dt = \frac{1}{T_p} \int_{T_p} x(t) \cdot \left(\sum_{k=-\infty}^{\infty} X^*[k] e^{-j\omega_p k t} \right) dt =$$

$$= \sum_{k=-\infty}^{\infty} X^*[k] \cdot \left(\frac{1}{T_p} \int_{T_p} x(t) e^{-j\omega_p k t} dt \right) = \sum_{k=-\infty}^{\infty} X^*[k] \cdot X[k]$$

1) CTFT

$$X(\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt = 5 \int_{-2}^2 e^{-j\omega t} dt = 5 \left. \frac{1}{-j\omega} e^{-j\omega t} \right|_{-2}^2 =$$

$$= \frac{5}{-j\omega} \left(e^{-2j\omega} - e^{2j\omega} \right) = \frac{5}{j\omega} \left(e^{2j\omega} - e^{-2j\omega} \right) = \frac{10}{j\omega} \sin(2\omega)$$

2. $x(t) = 2\sin\left(400\pi t + \frac{\pi}{6}\right) - 4\cos\left(800\pi t + \frac{\pi}{6}\right)$, $f_s = 300\text{Hz}$

a) $x(n) = ?$

$$x(n) = 2\sin\left(400\pi \frac{n}{f_s} + \frac{\pi}{6}\right) - 4\cos\left(800\pi \frac{n}{f_s} + \frac{\pi}{6}\right) =$$

$$= 2\sin\left(\frac{4}{3}\pi n + \frac{\pi}{6}\right) - 4\cos\left(\frac{8}{3}\pi n + \frac{\pi}{6}\right)$$

b) DFTS $(x(n))$

$$\frac{3}{4}N = \frac{2\pi k}{N} \Rightarrow N = \frac{2k}{\frac{3}{4}} = \frac{8k}{3} \in \mathbb{Z} \Rightarrow k=3 \Rightarrow \underline{N=8}$$

$$X[k] = \frac{1}{8} \sum_{n=0}^7 x(n) e^{-2\pi j k \frac{n}{N}} =$$

$$= \frac{1}{6} \sum_{n=0}^7 \sin\left(\frac{4}{3}\pi n + \frac{\pi}{6}\right) e^{-2\pi j k \frac{n}{N}} - \frac{1}{2} \sum_{n=0}^7 \cos\left(\frac{8}{3}\pi n + \frac{\pi}{6}\right) e^{-2\pi j k \frac{n}{N}} = X[k]$$

~~$$\sum_{n=0}^7 \sin\left(\frac{4}{3}\pi n + \frac{\pi}{6}\right) e^{-2\pi j k \frac{n}{N}} = \sin\frac{\pi}{6} + \sin\frac{3\pi}{2} e^{-2\pi j k \frac{1}{N}} +$$~~

$$\sum_{n=0}^7 \sin\left(\frac{4}{3}\pi n + \frac{\pi}{6}\right) e^{-2\pi j k \frac{n}{N}} = \sum_{n=0}^7 \frac{1}{2} \left(e^{j\left(\frac{4}{3}\pi n + \frac{\pi}{6} - 2\pi j k \frac{n}{N}\right)} - e^{j\left(\frac{4}{3}\pi n - \frac{\pi}{6} - 2\pi j k \frac{n}{N}\right)} \right)$$

... nemam po gma

$$1) \quad \delta(t) = 2 \sin\left(\frac{4}{3}\pi t + \frac{\pi}{6}\right) - 4 \cos\left(\frac{4}{3}\pi t + \frac{\pi}{6}\right) \rightarrow \text{vergeet no krivo}$$

$$2) \quad y''(t) + 8y'(t) + 15y(t) = u'(t) + 2u(t)$$

$$a) \quad u(t) = \mu(t), \quad y(0) = y'(0) = 0$$

$$u'(t) = \delta(t)$$

$$s^2 + 8s + 15 = 0$$

$$s_{1,2} = \frac{-8 \pm \sqrt{64 - 60}}{2} = \frac{-8 \pm 2}{2} = -3, -5$$

$$\Rightarrow y_h = C_1 e^{-3t} + C_2 e^{-5t}$$

$$y_p = K$$

$$y'_p = y''_p = 0 \Rightarrow 0 + 0 + 15K = 1 \Rightarrow K = \frac{1}{15}$$

$$\Rightarrow y_p = \frac{1}{15} \mu(t)$$

$$\Rightarrow y_h = C_1 e^{-3t} + C_2 e^{-5t} + \frac{1}{15} \mu(t)$$

$$y(0^+) - y(0^-) = 0 \Rightarrow \underline{y(0^+) = y(0^-) = 0}$$

$$y'(0^+) - y'(0^-) + 8 \cdot 0 = 0 + 1 \cdot 1$$

$$\Rightarrow \underline{y'(0^+) = 0 + 0 + 0 + 1 = 1}$$

$$b) \quad y(0^+) = C_1 + C_2 + \frac{1}{15} = 0 \quad | \cdot 3$$

$$y'(0^+) = -3C_1 - 5C_2 = 1$$

$$3C_1 + C_2 = -\frac{1}{3}$$

$$-3C_1 - 5C_2 = 1$$

$$-2C_2 = \frac{4}{3}$$

$$\Rightarrow C_2 = -\frac{2}{3} \Rightarrow C_1 = -\frac{1}{15} + \frac{2}{3} = -\frac{1}{15} + \frac{6}{15} = \frac{5}{15} = \underline{\underline{\frac{1}{3}}}$$

$$\Rightarrow y_h = \frac{1}{3} e^{-3t} - \frac{2}{3} e^{-5t} + \frac{1}{15} \mu(t)$$

$$b) \quad y_{\text{nep}} = ? \quad , \quad y(0) = -1, \quad y'(0) = 1 \quad y(t) \rightarrow Y(s)$$

$$y''(t) + 8y'(t) + 15y(t) = 0$$

$$y'(t) \rightarrow sY(s) - y(0)$$

$$y''(t) \rightarrow s^2 Y(s) - sy'(0) - y(0)$$

$$s^2 + 8s + 15 = 0$$

$$s_{1,2} = -3, -5$$

$$\Rightarrow y_{\text{nep}} = (c_1 e^{-3t} + c_2 e^{-5t})$$

$$y(0) = c_1 + c_2 = -1 \quad | \cdot 3$$

$$y'(0) = -3c_1 - 5c_2 = 1$$

$$3c_1 + 3c_2 = -3$$

$$-3c_1 - 5c_2 = 1$$

$$\rightarrow c_2 = -2$$

$$\Rightarrow c_2 = -2 \Rightarrow c_1 = 1$$

$$\Rightarrow y_{\text{nep}} = -2e^{-3t} + e^{-5t}$$

↑
nepotrebno - piše da treba u laplasu, a ne ovako

$$\Rightarrow Y(s) = \frac{1}{s+3} - \frac{2}{s+5}$$

$$\Rightarrow y_{\text{nep}}(t) = \frac{1}{2} e^{-3t} - \frac{2}{2} e^{-5t}$$

\Rightarrow

$$s^2 Y(s) + s - 1 + 8s Y(s) + 8 + 15 Y(s) = 0$$

$$Y(s)(s^2 + 8s + 15) = -7 - s$$

$$Y(s) = \frac{-7-s}{s^2 + 8s + 15} = \frac{A}{s+3} + \frac{B}{s+5}$$

$$= \frac{As + 5A + Bs + 3B}{(s+3)(s+5)}$$

$$\Rightarrow A + B = -1 \Rightarrow A = -1 - B$$

$$9A + 3B = -7$$

$$-9 - 5B + 3B = -7$$

$$\rightarrow B = -1$$

$$B = 1 \Rightarrow A = -1 - 1 = -2$$

$$\Rightarrow Y(s) = \frac{-2}{s+3} + \frac{1}{s+5}$$

$$\Rightarrow y_{\text{nep}}(t) = -2e^{-3t} + e^{-5t}$$

$$c) \quad \text{totalna odvazba} \quad u(t) = m(t), \quad y(0) = -1, \quad y'(0) = 1$$

$$y_{\text{tot}} = y_{\text{m}} + y_{\text{nep}} = \frac{1}{3} e^{-3t} - \frac{2}{5} e^{-5t} + \frac{1}{15} m(t) - 2e^{-3t} + e^{-5t} =$$

$$= -\frac{5}{3} e^{-3t} + \frac{3}{5} e^{-5t} + \frac{1}{15} m(t)$$

$$4. \quad y(n) - \frac{1}{5} y(n-1) = u(n) + 2u(n-1)$$

$$a) \quad h(n) = ? \quad , \quad u(n) = \delta(n)$$

$$y(0)$$

$$g^n - \frac{1}{5} g^{n-1} = 0 \quad / : g^{n-1}$$

$$y(5)=0$$

$$g - \frac{1}{5} = 0 \Rightarrow g = \frac{1}{5}$$

$$\Rightarrow h(n) = \left(\frac{1}{5}\right)^n \quad \{ \}$$

$$b) \quad H(z) = ? \quad \text{stabilnost?}$$

$$y(n) \rightarrow Y(z)$$

$$y(n-1] \rightarrow z^{-1} Y(z) = \dots$$

$$Y(z) - \frac{1}{5} z^{-1} Y(z) = U(z)$$

$$Y(z) \left(1 - \frac{1}{5} z^{-1}\right) = U(z)$$

$$Y(z) = \frac{U(z)}{1 - \frac{1}{5} z^{-1}} \Rightarrow H(z) = \frac{1}{1 - \frac{1}{5} z^{-1}} = \frac{z}{z - \frac{1}{5}} \Rightarrow \text{sustav je stabilan}$$

$$c) \quad u(n) = \mu(n)$$

$$U(z) = \frac{z}{z-1} + 2 \frac{1}{z} \frac{z}{z-1} + 0 = \frac{z}{z-1} + \frac{2}{z-1} = \frac{z+2}{z-1}$$

$$Y(z) = H(z) \cdot U(z) = \frac{z}{z - \frac{1}{5}} \left(\frac{z}{z-1} + \frac{2}{z-1} \right) = \frac{z^2}{(z - \frac{1}{5})(z-1)} + \frac{2z}{(z - \frac{1}{5})(z-1)}$$

$$\frac{z}{(z-\frac{1}{5})(z-1)} = \frac{A}{z-\frac{1}{5}} + \frac{B}{z-1} = \frac{Az-A+Bz-\frac{1}{5}B}{(z-\frac{1}{5})(z-1)}$$

$$\Rightarrow A+B=1$$

$$-A-\frac{1}{5}B=0 \Rightarrow A=-\frac{1}{5}B$$

$$\Rightarrow -\frac{1}{5}B+B=1 \Rightarrow B=\frac{5}{4} \Rightarrow A=-\frac{1}{4}$$

$$\Rightarrow \frac{z}{(z-\frac{1}{5})(z-1)} = \frac{-\frac{1}{4}}{z-\frac{1}{5}} + \frac{\frac{5}{4}}{z-1}$$

$$\Rightarrow \frac{z^2}{(z-\frac{1}{5})(z-1)} = -\frac{1}{4} \frac{z}{z-\frac{1}{5}} + \frac{5}{4} \frac{z}{z-1}$$

$$Y(z) = H(z) \cdot U(z) = \frac{z}{z-\frac{1}{5}} \cdot \frac{z+z}{z-1} = \frac{2z+z^2}{(z-\frac{1}{5})(z-1)}$$

$$\frac{Y(z)}{z} = \frac{z+z^2}{(z-\frac{1}{5})(z-1)} = \frac{A}{z-\frac{1}{5}} + \frac{B}{z-1} = \frac{Az-A+Bz-\frac{1}{5}B}{(z-\frac{1}{5})(z-1)}$$

$$\Rightarrow A+B=1$$

$$-A-\frac{1}{5}B=2 \Rightarrow A=-2-\frac{1}{5}B$$

$$\frac{4}{5}B=3$$

$$\Rightarrow B=\frac{15}{4} \Rightarrow A=-2-\frac{3}{4}=-\frac{11}{4}$$

$$\Rightarrow \frac{Y(z)}{z} = \frac{-\frac{11}{4}}{z-\frac{1}{5}} + \frac{\frac{15}{4}}{z-1}$$

$$\Rightarrow Y(z) = -\frac{11}{4} \frac{z}{z-\frac{1}{5}} + \frac{15}{4} \frac{z}{z-1} \Rightarrow Y(n) = -\frac{11}{4} \left(\frac{1}{5}\right)^n + \frac{15}{4} (1)^n$$

$$5. \quad y(t) = \int_{t-1}^{t+1} u(\tau) d\tau$$

a) > (linearnost i invar. prostornost?)

$$y_1(t) = \int_{t-1}^{t+1} u_1(\tau) d\tau, \quad y_2(t) = \int_{t-1}^{t+1} u_2(\tau) d\tau$$

$$y(t) = \int_{t-1}^{t+1} (au_1(\tau) + bu_2(\tau)) d\tau = a \int_{t-1}^{t+1} u_1(\tau) d\tau + b \int_{t-1}^{t+1} u_2(\tau) d\tau =$$

$$= ay_1(t) + by_2(t) \Rightarrow \text{sustav je linearan}$$

dalje ne znam

$$b) \quad u(t) = \delta(t)$$

$$y(t) = \int_{t-1}^{t+1} \delta(\tau) d\tau = \mu(\tau) \Big|_{t-1}^{t+1} = \mu(t+1) - \mu(t-1) = g_{[-1,1]}(t)$$

→ sustav je nekonzulzan jer $y(t) \neq 0$ za $t < 0$ i $t > 0$
sustav je nekonzulzan jer $y(t)$ različito od 0 za svaki $t < 0$ i $y(t)$ različito od 0 za svaki $t > 0$

$$c) \quad u(t) = \mu(t+1) - \mu(t-1) \quad \bullet \quad H(s) = \int_{-1}^1 1 \cdot e^{-st} dt =$$

$$= \frac{1}{-s} e^{-st} \Big|_{-1}^1 = -\frac{1}{s} (e^{-s} - e^s) = \frac{1}{s} (e^s - e^{-s}) \rightarrow 2.2$$

nisam baš siguran

$$d) \quad \angle(H(s)) = \frac{\angle(H(j\omega))}{\angle(H(s))} = 0$$

$$u(t) = 2.5 \sin(\pi t + \frac{\pi}{4})$$

ovo su negativno
krivo

$$y(t) = 2 \int_{t-1}^{t+1} \sin(\pi \tau + \frac{\pi}{4}) d\tau = -\frac{2}{\pi} \cos(\pi \tau + \frac{\pi}{4}) \Big|_{t-1}^{t+1} =$$

$$= -\frac{2}{\pi} \left(\cos(t\pi + \frac{5\pi}{4}) - \cos(t\pi - \frac{3\pi}{4}) \right)$$