

# Tutorial 6: Explicit Runge-Kutta methods

## 1 Trajectory of a cannonball

Consider a cannonball which leaves the barrel at time  $t = 0$  and location  $x(0) = 0 \in \mathbb{R}^2$  with an initial velocity  $\dot{x}(0) = v_0 \in \mathbb{R}^2$ . Let us assume the trajectory  $x : [0, T] \rightarrow \mathbb{R}^2$  of this cannonball satisfies the ODE

$$\ddot{x} = -D \|\dot{x}\|_2 \dot{x} - g e_2, \quad x(0) = 0, \quad \dot{x}(0) = v_0$$

where the term  $-D \|\dot{x}\|_2 \dot{x}$  with  $D > 0$  describes drag and the term  $-g e_2$  with  $g > 0$  and  $e_2 = (0 \ 1)^T$  describes gravity.

1. Rewrite the above ODE in the form  $\dot{y} = f(y)$ ,  $y(0) = y_0$ .
2. Implement the resulting  $f(y)$  in `cannonball_f(y,D,g)`.
3. Run `cannonball_trajectory()` and verify that you get a physically plausible trajectory.

## 2 Butcher tableaux

Complete the functions `midpoint_step()` and `ssprk3_step()` such that they perform single Runge-Kutta steps according to the following Butcher tableaux:

Midpoint:	$\begin{array}{c c} 0 & 0 \ 0 \\ \frac{1}{2} & \frac{1}{2} \ 0 \\ \hline & 0 \ 1 \end{array}$	SSPRK3:	$\begin{array}{c c} 0 & 0 \ 0 \ 0 \\ 1 & 1 \ 0 \ 0 \\ \frac{1}{2} & \frac{1}{4} \ \frac{1}{4} \ 0 \\ \hline & \frac{1}{6} \ \frac{1}{6} \ \frac{2}{3} \end{array}$
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The midpoint method is second-order convergent and SSPRK3 is third-order convergent. Verify that your implementation achieves these convergence orders by running `convergence()`.

## 3 Generic two-stage Runge-Kutta method

A generic two-stage Runge-Kutta method is of the form

$$\begin{array}{c|c} 0 & 0 \ 0 \\ \theta & \theta \ 0 \\ \hline & w_1 \ w_2 \end{array}.$$

Show that this method is third-order consistent if and only if

$$w_1 = 1 - \frac{1}{2\theta}, \quad w_2 = \frac{1}{2\theta}.$$