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# Formatting Instructions For NeurIPS 2023

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## Abstract

1 Improving classification accuracy is a key issue to advancing brain computer  
2 interface (BCI) research from laboratory to real world applications. This article  
3 presents a high accuracy EEG signal classification method using single trial EEG  
4 signal to detect left and right finger movement. We apply an optimal temporal  
5 filter to remove irrelevant signal and subsequently extract key features from spatial  
6 patterns of EEG signal to perform classification. Specifically, the proposed method  
7 transforms the original EEG signal into a spatial pattern and applies the RBF  
8 feature selection method to generate robust feature. Classification is performed by  
9 the SVM and our experimental result shows that the classification accuracy of the  
10 proposed method reaches 90% as compared to the current reported best accuracy  
11 of 84%.

## 12 1 Introduction

13 A brain-computer interface (BCI) is a communication system that does not depend on the brain's  
14 normal output pathways of peripheral nerves and muscles. At present, electroencephalography (EEG)  
15 is one of the most prevailing signals used in non-invasive BCI systems. There are various kinds of  
16 EEG based BCIs categorized by the signals used. Typical signals include slow cortical potential,  
17 rhythms, EEG (de)synchronization evoked by motor imagery, steady-state visual evoked potential,  
18 P300 potential, etc. EEG signals evoked by limb movement or motor imagery are of interest to  
19 this paper. The preparation, actual operation and mental imagination of limb movements activate  
20 similar EEG changes at sensorimotor areas on the scalp. When such regions become activated, EEG  
21 activities display an amplitude attenuation or event-related desynchronization (ERD). For instance,  
22 imagination of right-hand or left-hand movement

23 results in the most prominent ERD localized over the corresponding sensorimotor cortex. However,  
24 ERD is subject-related, i.e. different subjects have different spatial localizations of ERD. This  
25 leads to difficulty when extracting features for classification. Pfurtscheller et. al. [6] extracted  
26 motor imagery signals from C3 and C4 EEG Channels to build an online BCI system. The features  
27 presented to the classifier were short-term power spectra in pre-defined frequency bands. This system  
28 using a LVQ algorithm achieved an accuracy of approximately 80%. Studies showed that the position of  
29 ERD may vary from subject to subject, and are not necessarily located beneath electrode positions  
30 C3 and C4 [5]. As such, using more channels of signals may improve performance. Müller-Gerking  
31 et. al. [4] proposed to use Common Spatial Patterns (CSP) for the classification of motor execution  
32 or imagery signals. The CSP method resulted in significant improvement to performances as  
33 compared to their previous work in [6]. In this paper, we combined CSP and Principal Component  
34 Analysis (PCA) to improve the CSP feature classification. The resulted transformation is equivalent  
35 to a set of spatial filters optimized to distinguish between the left and right hand movement or motor

36 imagery. In addition, temporal filtering was applied to reduce noise. In the past, the selection of  
37 frequency bands was limited to a few pre- defined bands [4, 5]. In this paper, we investigated the  
38 ef- fects of temporal filtering for specific subject by an ex- haustive search over all the frequency  
39 bands. We showed that classification performance could be improved signifi- cantly by applying  
40 proper band-pass filter. To further en- hance recognition accuracy, a Radial Basis Function (RBF)  
41 based feature selection and generation algorithm [3] was adapted. We applied the Orthogonal Least  
42 Square (OLS) algorithm [3] to feature selection and generation. Using a Support Vector Machine  
43 (SVM) classifier on the features found, we achieved 90  
44 dataset. The organization of the paper is as follows. Section 2 in- troduces the feature extraction by  
45 the combination of CSP and PCA. Section 3 presents the feature selection and gen- eration algorithms.  
46 Section 4 discusses the effects of differ- ent parameters on the recognition performance and present  
47 comparative experiment results. Finally, we conclude our paper and discuss some future work.

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