

Area formula for simple polygons

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1 Preface

In this paper, we shall try to understand and prove the area formula for general (*simply*) *polygons*.

However, subtleties in proofs should be **justified** with more rigors, including but limited to the notion of area, and how the area of a curve / straight line is 0.

This paper is being updated on [my webpage](#).

2 Definitions

A *polygon* P is the closed region of the plane bounded by a finite collection of line segments forming a closed curve that does not intersect itself. [1] (Page 1)

Though, I would modify to have my own definition for *polygon*.

Definition 2.1. A *polygon* is the closed region of the infinite plane bounded by its *boundary*, which, with **distinct** points P_0, \dots, P_{n-1} ($n \in \mathbb{N}$) as vertices (and with $P_n = P_0$ by convention), is a closed curve formed by line segments $P_i P_{i+1}, i = 0, \dots, n-1$, and the line segments are all disjoint when all the vertices are ignored.

Remark 2.2. Notice that in [Definition 2.1](#) we allow a polygon with line segments ‘*touching itself*’, as well as an ‘*interior angle of π* ’, as long as the vertices are all distinct and satisfying the above definition.

3 The formula

Theorem 3.1. For any simple polygon with $n \in \mathbb{N}$ vertices $(x_n, y_n) = (x_0, y_0), \dots, (x_{n-1}, y_{n-1})$, we have: [1]

$$Area = \frac{\left| \sum_{i=0}^{n-1} (x_i y_{i+1} - x_{i+1} y_i) \right|}{2} = \frac{1}{2} \left| \sum_{i=0}^{n-1} \begin{vmatrix} x_i & x_{i+1} \\ y_i & y_{i+1} \end{vmatrix} \right| \quad (1)$$

References

- [1] Satyan L.Devadoss and Joseph O’Rourke. *Discrete and Computational Geometry*. Princeton University Press, 2011. ISBN: 978-0-691-14553-2.