

1. Template

```
#include <bits/stdc++.h>

#define endl '\n'
#define ll long long int
#define dl double
#define ld long double
#define ff __float128
#define fore(i,a,b) for (int i = a; i < b; i++)
#define fi first
#define se second
#define pb push_back
#define all(v) v.begin(), v.end()
#define fast_io
↪ ios_base::sync_with_stdio(0);cin.tie(0);cout.tie(0);

using namespace std;

typedef vector<int> vi;
typedef vector<vi> vvi;
typedef vector<ll> vll;
typedef vector<vll> vvll;
typedef pair<int,int> pii;
typedef pair<ll,ll> pll;
typedef vector<pll> vpll;

const int inf = 1<<30;
const int mod = 1e9+7;

// clear ES g++ -std=c++17 -O2 -Wall template.cpp -o template ES
↪ ./template
// ifstream cin("input.txt"); ofstream cout("output.txt");
```

2. Data Structure

2.1. Segment tree with lazy

```
struct Node{
    int l, r;
    ll sum;
```

```
    int mark;
    ll lazy;
}; // 0 +, 1 *, 0 gcd, 1 mcm
const int Neutro = 0;
template<typename TT> struct SegmentTree{
    int n, h;
    vector<Node> st;

    SegmentTree (int m, vector<TT> &values) : n(m){
        h = 1 << ((int)( ceil(log2(n)) + 1));
        st.resize( h );
        build(1, 1, n, values);
    }
    TT merge(TT l, TT r){ return l + r; } // for query
    TT getValue(int curr){ return st[curr].sum; } // same ^^

    int left(int n){ return (n << 1); }
    int right(int n){ return (n << 1) | 1; }

    void initLeaf(int curr, TT value){
        st[curr].mark = 0; st[curr].lazy = Neutro;
        st[curr].sum = value; //
    }
    void updateFromChildren(int curr){ //
        st[curr].sum = st[left(curr)].sum + st[right(curr)].sum;
    }
    void updateNodeLazy(int curr, TT value){ // updates lazy
        int l = st[curr].l, r = st[curr].r;
        st[curr].sum += (r - l + 1) * value; //
        st[curr].mark = 1; st[curr].lazy += value; //
    }
    void propagateToChildren(int curr){ // propagate lazy
        if(st[curr].mark != 0){
            updateNodeLazy(left(curr), st[curr].lazy );
            updateNodeLazy(right(curr), st[curr].lazy);
            st[curr].mark = 0; st[curr].lazy = Neutro;
        }
    }
    void build(int curr, int l, int r, vector<TT> &values){
        st[curr].l = l; st[curr].r = r;
        if(l == r) {
            initLeaf(curr, values[l]); //
        } else {
            int m = ((r - l) >> 1) + 1;
```

```

    build(left(curr), l, m, values);
    build(right(curr), m + 1, r, values);
    updateFromChildren(curr);
}
}
void rangeUpdate(int curr, int l, int r, int ql, int qr, TT
→ value){
    if( r < ql || qr < l ) return;
    else if( ql <= l && r <= qr){
        updateNodeLazy(curr, value);
    }else{
        propagateToChildren(curr);
        int m = ((r - l) >> 1) + 1;
        rangeUpdate(left(curr), l, m, ql, qr, value);
        rangeUpdate(right(curr), m + 1, r, ql, qr, value);
        updateFromChildren(curr);
    }
} // not lazy
// void pointUpdate(int curr, int l, int r, int pos, TT value){
//     if(l == r){
//         st[curr].sum += value;
//     }else{
//         int m = ((r - l) >> 1) + 1;
//         if(pos <= m) pointUpdate(left(curr), l, m, pos, value);
//         else pointUpdate(right(curr), m + 1, r, pos, value);
//         updateFromChildren(curr);
//     }
// }
TT rangeQuery(int curr, int l, int r, int ql, int qr){
    if( r < ql || qr < l ) return Neutro;
    else if( ql <= l && r <= qr){
        return getValue(curr);
    }else{
        propagateToChildren(curr);
        int m = ((r - l) >> 1) + 1;
        return merge( rangeQuery(left(curr), l, m, ql, qr),
→ rangeQuery(right(curr), m+1, r, ql, qr)) ;
    }
}
void update( int ql, int qr, int value){
    rangeUpdate(1, 1, n, ql, qr, value);
}
TT query(int ql, int qr){
    return rangeQuery(1, 1, n, ql, qr);
}

```

```

}
// void printST(){
//     cout << endl << "st = ";
//     fore(i,0,h) cout << st[i].sum << ' '; cout << endl;
// }
};
// vector<ll> nums(n + 1);
// SegmentTree<ll>* st = new SegmentTree<ll>(n, nums);
// st->update(l,r,x); st->query(l, r);

```

2.2. SQRT and MO's

```

//SQRT decomposition
//if RTE, change limits to min(br, n)
template <typename TT>
struct SQRT{
    int n, s;
    TT neutro = 0;
    vector<TT> A, B;
    vector<TT> lazy, marks;

    SQRT(int m, vector<TT> &arr): n(m){
        s = sqrt(n) + 1; //puede variar
        A.assign(n, neutro);
        B.assign(n / s + 1, neutro);
        lazy.assign(s, neutro); marks.assign(s, neutro);
        fore(i,0,n){ A[i] = arr[i]; B[i/s] += arr[i]; }
    }
    void pushLazy(int block){
        if(marks[block]){
            fore(i,block,(block+1) * s && i < n) A[i] += lazy[block];
            lazy[block] = neutro; marks[block] = 0;
        }
    }
    void rangeUpdate(int l, int r, TT value){
        int bl = l/s, br = r/s;
        if(bl == br){
            pushLazy(bl);
            fore(i,l,r+1) A[i] += value;
            TT res = neutro;
            fore(i, bl*s, (bl+1) * s && i < n) res += A[i];
            B[bl] = res;
        }else{

```

```

    pushLazy(bl);pushLazy(br);
    fore(i,l,(bl+1) * s){ A[i] += value; B[bl] += value;}
    fore(i,bl+1, br)    { B[i] += s * value; lazy[i] += value;
↪ marks[i] = 1;}
    fore(i,br * s, r+1) { A[i] += value; B[br] += value;}
}
}
void pointUpdate(int idx, TT value){//not lazy
    int block = idx / s;
    A[idx] = value;
    TT res = neutro;
    fore(i, block * s, (block + 1) * s && i < n) res += A[i];
    B[block] = res;
}
TT rangeQuery(int l, int r){
    int bl = l/s, br = r/s;
    TT res = 0;
    if(bl == br){
        pushLazy(bl);
        fore(i,l,r+1) res += value;
    }else{
        pushLazy(bl); pushLazy(br);
        fore(i,l,(bl+1) * s) res += A[i];
        fore(i,bl+1, br)    res += B[i];
        fore(i,br * s, r+1) res += A[i];
    }
}
};
//MO's algorithm
ll answer, neutro = 0; vll arr;
struct MOquery{
    int l, r, index, S;
    MOquery(int l, int r, int idx, int S): l(l), r(r), index(idx),
↪ S(S){}
    bool operator<(const MOquery & q) const{
        int bl = l / S, bq = q.l / S;
        if(bl == bq) return r < q.r;
        return bl < bq;
    }
};
void add(int idx){
    answer += arr[idx];
}
void remove(int idx){

```

```

    answer -= arr[idx];
}
vector<ll> MO(vector<MOquery> & queries){
    vector<ll> ans(queries.size());
    sort(queries.begin(), queries.end());
    ll current = 0;
    int prevL = 0, prevR = -1;
    int i, j;
    answer = neutro;
    for(const MOquery & q : queries){
        while (prevL > q.l) { prevL--; add(prevL); }
        while (prevR < q.r) { prevR++; add(prevR); }
        while (prevL < q.l) { remove(prevL); prevL++; }
        while (prevR > q.r) { remove(prevR); prevR--; }
        ans[q.index] = answer;
    }
    return ans;
}

```

2.3. Convex Hull Trick

```

const int MX = 200005;
const ll inf = 1e18;

bool Q = 0;
struct Line {
    mutable ll m, b, x;
    // Maximo: m < ot.m
    // Minimo: m > ot.m
    bool operator < (const Line ot) const {
        return Q ? x < ot.x : m < ot.m;
    }
};

ll ceil (ll a, ll b) {
    if (a < 0 != b < 0) return a / b;
    return (abs(a) + abs(b) - 1) / abs(b);
}

ll intersection (const Line &p, const Line &q) {
    return ceil(q.b - p.b, p.m - q.m);
}

```

```

struct Hull : multiset<Line> {
    bool valid (auto it) {
        if (it == begin()) {
            auto sig = it; sig++;
            if (sig != end()) sig->x = intersection(*it, *sig);
            return it->x == -inf;
        }
        auto ant = it, sig = it;
        ant--, sig++;
        if (sig == end()) {
            it->x = intersection(*it, *ant);
            return 1;
        }
        ll x = intersection(*it, *ant);
        ll y = intersection(*it, *sig);
        if (x > y) return 0;
        it->x = x, sig->x = y;
        return 1;
    }
    void add (ll m, ll b) {
        auto it = lower_bound({m, b, -inf});
        if (it != end() && it->m == m) {
            //Maximo: it->b > b
            //Minimo: it->b < b
            if (it->b > b) return;
            it->b = b;
        } else { it = insert({m, b, -inf}); }

        if (!valid(it)) { erase(it); return; }
        auto ant = it;
        while (ant != begin()) {
            if (valid(--ant)) break;
            erase(ant);
            if (it == begin()) { it->x = -inf; break; }
            ant = it;
        }
        auto sig = it; sig++;
        while (sig != end() && !valid(sig)) erase(sig++);
    }

    ll query (ll x) {
        if (empty()) return 0;
        Q = 1; auto it = upper_bound({0, 0, x});
        it--;

```

```

        Q = 0; return x * it->m + it->b;
    }
};

```

2.4. Field extension

```

int sq = 5;
// const lli sqrt5 = 383008016; // mod 1e9+9
const ll mod = 1000000007; // is important to be CONST
struct EX {
    ll re, im;
    EX (ll re = 0, ll im = 0) : re(re), im(im) {}

    EX& operator = (EX oth) {
        return re = oth.re, im = oth.im, *this;
    }
    int norm () const {
        return trim((1ll * re * re - 1ll * sq * im % mod * im) % mod);
    }
    EX conj () const {
        return {re, trim(-im)};
    }
    EX operator * (EX ot) const {
        return {
            int((1ll * re * ot.re + 1ll * sq * im % mod * ot.im) % mod),
            int((1ll * re * ot.im + 1ll * im * ot.re) % mod)
        };
    };
    EX& operator *= (const EX& ot) {
        *this = *this * ot; return *this;
    }
    EX operator * (ll k) const {
        k = ((k % mod) + mod) % mod;
        return { (re * k) % mod, (im * k) % mod };
    };
    EX operator / (ll n) const {
        return { re * inv(n) % mod, im * inv(n) % mod };
    }
    EX operator / (EX ot) const {
        return *this * ot.conj() / ot.norm();
    }
    EX& operator /= (const EX& ot) {
        *this = *this / ot; return *this;
    }

```

```

}
EX operator + (EX ot) const {
    return { trim(re + ot.re), trim(im + ot.im) };
}
EX& operator += (const EX& ot) {
    *this = *this + ot; return *this;
}
EX operator - (EX ot) const {
    return { trim(re - ot.re), trim(im - ot.im) };
}
EX& operator -= (const EX& ot) {
    *this = *this - ot; return *this;
}
EX pow (ll p) const {
    EX res(1), b = *this;
    while (p) {
        if (p & 1) res *= b; b *= b; p /= 2;
    }
    return res;
}

bool operator == (EX ot) const {
    return re == ot.re && im == ot.im;
}
bool operator != (EX ot) const {
    return !(*this == ot);
}

static ll trim(ll a) {
    if (a >= mod) a -= mod;
    if (a < 0) a += mod;
    return a;
}
static ll inv (ll b) {
    ll res = 1, p = mod - 2;
    while (p) {
        if (p & 1) res = 1ll * res * b % mod;
        b = 1ll * b * b % mod;
        p /= 2;
    }
    return res;
};
};

```

2.5. BIT

```

struct Fenwick {
    int n;
    vector<long long> tree;

    Fenwick(int _n) : n(_n), tree(n + 1, 0) {}

    void update(int idx, long long val) {
        for (; idx <= n; idx += idx & -idx) {
            tree[idx] += val;
        }
    }

    long long query(int idx) {
        long long ret = 0;
        for (; idx > 0; idx -= idx & -idx) {
            ret += tree[idx];
        }
        return ret;
    }

    long long query(int x, int y) { return query(y) - query(x -
↪ 1); }
};

```

2.6. merge sort tree

```

vi tree[400000];
vi vv;
void build(int a[], int v, int tl, int tr) {
    if (tl == tr) {
        tree[v] = vi(1, a[tl]);
    } else {
        int tm = (tl + tr) / 2;
        build(a, v*2, tl, tm);
        build(a, v*2+1, tm+1, tr);
        merge(tree[v*2].begin(), tree[v*2].end(),
↪ tree[v*2+1].begin(), tree[v*2+1].end(),
↪ back_inserter(tree[v]));
    }
}

void query(int v, int tl, int tr, int l, int r, int x){

```

```

    if(l > r) return;
    if(tr <= r){
    for(auto i = tree[v].begin(); i < tree[v].end(); i++){
        if(*i <= x) vv.pb(*i);
        else break;
    }
    return;
}
if(tl > r) return;
int tm = (tl + tr) / 2;
query(v*2, tl, tm, l, r, x),
query(v*2+1, tm+1, tr, l, r, x);
return;
}

```

3. FFT

3.1. FFT

```

using cd = complex<double>;
const double PI = acos(-1);

```

```

void fft(vector<cd> & a, int inv) {
    int n = a.size();
    for(int i = 1, j = 0; i < n - 1; ++i){
        for(int k = n >> 1; (j ^= k) < k; k >>= 1);
        if(i < j) swap(a[i], a[j]);
    }

    vector<cd> w(n >> 1);

    for (int k = 2; k <= n; k <= 1) {
        // cd w1 = polar(1.0, 2 * PI / k * inv) ;
        w[0] = 1;
        for (int j = 1; j < k >> 1; j++) // best precision but
        ↪ slower
            w[j] = polar(1.0, 2 * j * PI / k * inv);
        // w[j] = w[j-1]*w1;
        for (int i = 0; i < n; i += k) {
            for (int j = 0; j < k >> 1; j++) {
                cd u = a[i + j], v = a[i + j + (k >> 1)] * w[j];

```

```

                a[i + j] = u + v;
                a[i + j + (k >> 1)] = u - v;
            }
        }
        if (inv == -1) for (cd & x : a) x /= n;
    }

    vector<int> multiply(vector<int> const& a, vector<int> const& b) {
        vector<cd> fa(a.begin(), a.end()), fb(b.begin(), b.end());
        int n = 1;
        while (n < a.size() + b.size() - 1) n <= 1;
        fa.resize(n); fb.resize(n);

        fft(fa, 1); fft(fb, 1);
        fore(i, 0, n) fa[i] *= fb[i];
        fft(fa, -1);

        vector<int> result(n);
        for (int i = 0; i < n; i++) result[i] = round(fa[i].real());
        return result;
    }
}

```

4. Binary Search

```

int lowerBound(vi &nums, int a) {
    int l = 0, r = nums.size() - 1;
    while(l <= r) {
        int m = ((r - l) >> 1) + 1;
        // if(nums[m] == a) return m; //binary
        nums[m] < a ? l = m + 1 : r = m - 1; //lower & binary
        // nums[m] <= a ? l = m + 1 : r = m - 1; //upper
    }
    return l; //return -1; //binary
}

for(int j = 0; j < 300; j++){
    ld mid1 = 1 + (r - l) / 3, mid2 = r - (r - l) / 3;
    ld f1 = f(p0, Friend1[i + 1], p1, Friend2[i + 1], mid1);
    ld f2 = f(p0, Friend1[i + 1], p1, Friend2[i + 1], mid2);
    if(f1 >= f2) l = mid1;
}

```

```

    else r = mid2;
}

```

5. Flujos

5.0.1. Dinic

```

typedef tuple<int, ll, ll> edge;
class max_flow{
private:
    int V;
    vector<edge> EL;
    vvi AL;
    vi d, last;
    vpii p;
    bool BFS(int s, int t){
        d.assign(V, -1); d[s] = 0;
        queue<int> q({s});
        p.assign(V, {-1, -1});
        while( !q.empty()){
            int u = q.front(); q.pop();
            if( u== t) break;
            for(auto &idx: AL[u]){
                auto &[v, cap, flow] = EL[idx];
                if( (cap - flow > 0) && d[v] == -1){
                    d[v] = d[u] + 1, q.push(v), p[v] = {u, idx};
                }
            }
        }
        return d[t] != -1;
    }
    ll send_one_flow(int s, int t, ll f = inf){
        if ( s == t) return f;
        auto &[u,idx] = p[t];
        auto &cap = get<1>(EL[idx]), &flow = get<2>(EL[idx]);
        ll pushed = send_one_flow(s, u, min(f, cap-flow));
        flow += pushed;
        return pushed;
    }
    ll DFS(int u, int t, ll f = inf){
        if( (u == t) || (f == 0)) return f;
        for(int &i = last[u]; i < (int) AL[u].size(); ++i){

```

```

            auto &[v, cap, flow] = EL[AL[u][i]];
            if(d[v] != d[u] + 1) continue;
            if(ll pushed = DFS(v, t, min(f, cap - flow))){
                flow += pushed;
                auto &rflow = get<2> (EL[AL[u][i] ^ 1]);
                rflow -= pushed;
                return pushed;
            }
        }
        return 0;
    }
public:
    max_flow(int initialV) : V(initialV){
        EL.clear();
        AL.assign(V, vi());
    }
    void add_edge(int u, int v, ll w, bool directed = true){
        if( u == v) return;
        EL.emplace_back(v, w, 0);
        AL[u].pb(EL.size() - 1);
        EL.emplace_back(u, directed ? 0 : w, 0);
        AL[v].pb(EL.size() - 1);
    }
    ll edmonds_karp(int s, int t){
        ll mf = 0;
        while( BFS(s,t)){
            ll f = send_one_flow(s, t);
            if ( f == 0)break;
            mf += f;
        }
        return mf;
    }
    ll dinic(int s, int t ){
        ll mf = 0;
        while( BFS(s,t)){
            last.assign(V, 0);
            while( ll f = DFS(s,t)){
                mf += f;
            }
        }
        return mf;
    }
};

```

5.0.2. Ford-Fulkerson

```

const int sink = 37;
int C[50][50], F[50][50], visited[50];
int sendFlow(int node, int bottleneck){
    if(node == sink){
        return bottleneck;
    }
    visited[node] = true;
    fore(i,0,sink+1){
        int f = C[node][i] - F[node][i];
        if(f>0 && !visited[i]){
            f = sendFlow(i, min(f, bottleneck));
            if(!f) continue;
            F[node][i] += f;
            F[i][node] -= f;
            return f;
        }
    }
    return 0;
}

```

6. Strings

6.1. aho-corasik

```

//define feach(f, g) for(auto &f: g)
const int N=1e5+10, MOD=1e9+7, SIG=26;
int id=1, dp[N];
string s;
vector<int> adj[2*N];

struct node{
    int fail,ch[SIG]={};
    vector<int> lens;
}t[2*N];
void insert(string s){
    int u=1;
    for(auto &c: s){
        c-='a';
        if(!t[u].ch[c]) t[u].ch[c]=++id;
        u=t[u].ch[c];
    }
}

```

```

}
t[u].lens.pb(s.size());
}
void dfs(int u){
    t[u].lens.insert(t[u].lens.end(), t[t[u].fail].lens.begin(),
    ↪ t[t[u].fail].lens.end());
    for(auto &v: adj) dfs(v);
}
void build(){
    queue<int> q;
    int u=1;
    t[1].fail=1;
    fore(i,0,SIG) {
        if(t[u].ch[i]) t[t[u].ch[i]].fail=u, q.push(t[u].ch[i]);
        else t[u].ch[i]=1;
    }
    while(!q.empty()){
        u=q.front(); q.pop();
        fore(i,0,SIG){
            if(t[u].ch[i]) t[t[u].ch[i]].fail=t[t[u].fail].ch[i],
            ↪ q.push(t[u].ch[i]);
            else t[u].ch[i]=t[t[u].fail].ch[i];
        }
    }
    fore(i,2,id+1) adj[t[i].fail].pb(i);
    dfs(1);
}

```

7. Math

7.1. nCr

```

vll fact(100007,0), inv(100007,0), invfact(100007,0);
void factorial(){
    fact[0] = 1; inv[0] = inv[1] = 1; invfact[0] = 1;
    fore(i,1,100005) fact[i] = (fact[i-1] * i) % MOD;
    fore(i,2,100005) inv[i] = inv[MOD % i] * (MOD - MOD / i) %
    ↪ MOD;
    fore(i,1,100005) invfact[i] = invfact[i-1] * inv[i] % MOD;
}
ll ncr(ll n, ll r){
    return fact[n] * invfact[n - r] % MOD * invfact[r] % MOD ;
}

```



```
}

```

7.2. Discrete Root

```
int generator(int p) {
    vector<int> fact;
    int phi = p-1, n = phi;
    for (int i = 2; i * i <= n; ++i) {
        if (n % i == 0) {
            fact.push_back(i); while (n % i == 0) n /= i;
        }
    }
    if (n > 1) fact.push_back(n);
    for (int res = 2; res <= p; ++res) {
        bool ok = true;
        for (int factor : fact) {
            if (powmod(res, phi / factor, p) == 1) {
                ok = false; break;
            }
        }
        if (ok) return res;
    }
    return -1;
}

vi rootK() {// finds all numbers x such that x^k = a (mod n)
    int n, k, a;
    scanf("%d %d %d", &n, &k, &a);
    if (a == 0) return vi(1,1);
    int g = generator(n);
    // Baby-step giant-step discrete logarithm algorithm
    int sq = (int) sqrt (n + .0) + 1;
    vector<pair<int, int>> dec(sq);
    for (int i = 1; i <= sq; ++i)
        dec[i-1] = {powmod(g, i * sq * k % (n - 1), n), i};
    sort(dec.begin(), dec.end());
    int any_ans = -1;
    for (int i = 0; i < sq; ++i) {
        int my = powmod(g, i * k % (n - 1), n) * a % n;
        auto it = lower_bound(dec.begin(), dec.end(),
        ↪ make_pair(my, 0));
        if (it != dec.end() && it->first == my) {
            any_ans = it->second * sq - i; break;
        }
    }
}
```

```
}
if (any_ans == -1) return vi(1,-1);
// Print all possible answers
int delta = (n-1) / gcd(k, n-1);
vi ans;
for (int cur = any_ans % delta; cur < n-1; cur += delta)
    ans.push_back(powmod(g, cur, n));
sort(ans.begin(), ans.end());
return ans;
}
```