

Code in src/HW1.ipynb

Problem 1

- (a) See src/cube.gif
- (b) 3D rotation matrices are not commutative.

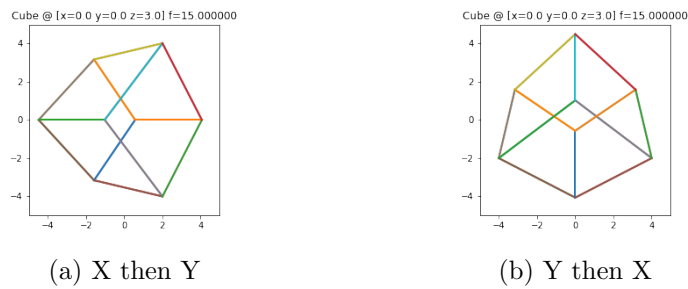


Figure 1: two transformations

- (c) First, I rotate the cube around Y for $\pi/4$. Then, I rotate the cube around X for $\arcsin(1/\sqrt{3})$.

Explanation: According to the Hint, to project the cube's body diagonal into the point, we need to rotate it and let it align with z axis. The angle between the body diagonal and z axis is $\arcsin(1/\sqrt{3})$.

- (d) Change the code to fit into the scenario where the focal length is infinite.

See src/dolly_zoom.py

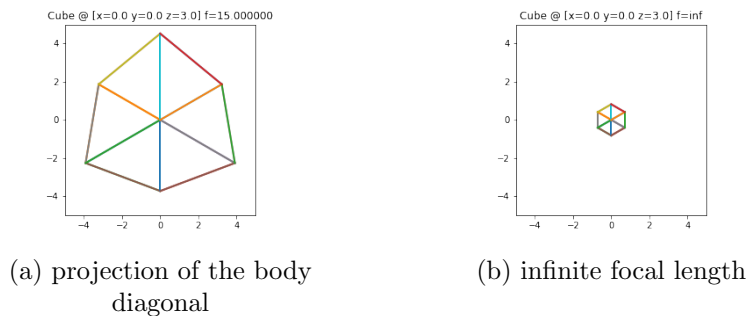


Figure 2: (c) and (d)

Problem 2

(a) A wonky picture:



Figure 3: wonky picture

- (b) Use normalized cross correlation as the similarity metric. The first channel has (0,0) offset. The subtitle includes the offsets for the second and the third channel.



(a) (-4,-1),(-3,-1)



(b) (-1,-1),(-1,-4)



(c) (-2,-1),(-7,0)



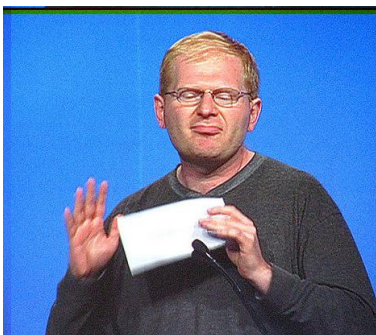
(d) (0,0),(1,-1)



(e) (1,0),(0,-1)



(f) (0,-1),(5,-1)



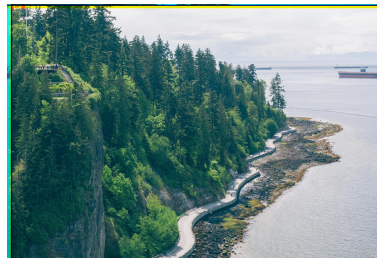
(g) (5,10),(10,5)

Figure 4: aligned

- (c) The subtitle includes the offsets for the second and the third channel of the first stage, the second stage and the overall.



(a) $(2,3),(4,1)$ then $(1,0),(0,-1)$,
overall $(5,6),(8,1)$



(b) $(2,11),(9,6)$ then $(0,0),(0,0)$,
overall $(4,22),(18,12)$

Figure 5: Pyramid

Problem 3

(a) RGB:

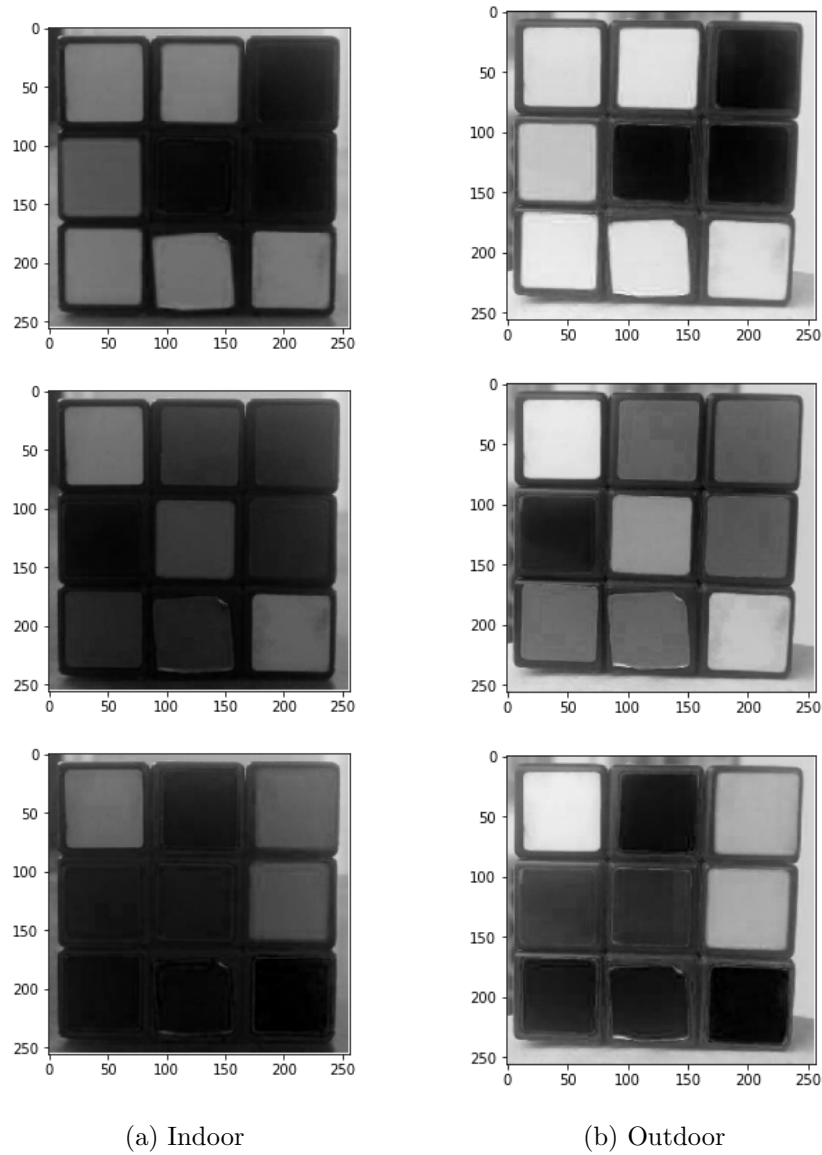


Figure 6: RGB

LAB:

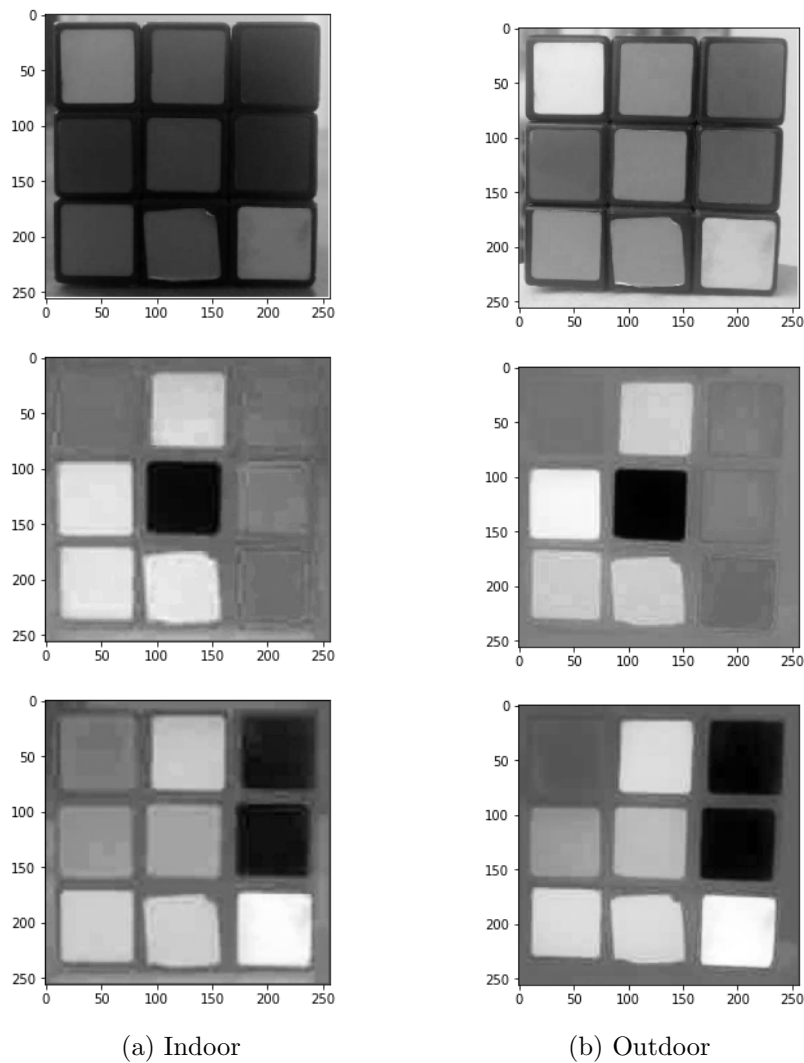


Figure 7: LAB

(b) From the channel L we can distinguish two pictures' lightness easily.

(c) See src/im1.jpg, im2.jpg and info.txt