Lecture 4 CPU Scheduling

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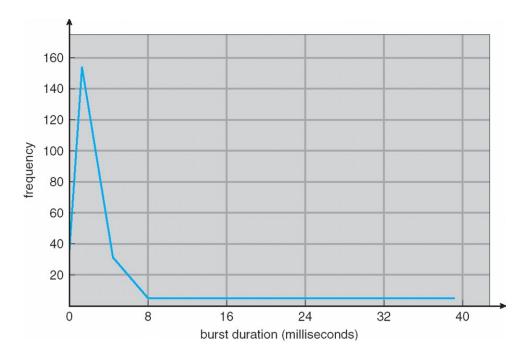
CPU Scheduling

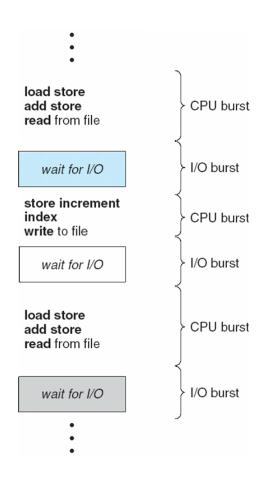
- Scheduling is important when multiple processes wish to run on a single CPU
 - CPU scheduler decides which process to run next
- Two types of processes
 - CPU bound and I/O bound

CPU-bound Process	I/O-bound process
Spends most of its running time on the CPU, i.e., user-time > sys-time	Spends most of its running time on I/O, i.e., sys-time > user-time
Examples - Al course assignments.	Examples - /bin/ls, networking programs.

CPU Burst

- Process execution consists of a cycle of CPU execution and I/O wait
- CPU burst distribution





CPU Scheduler

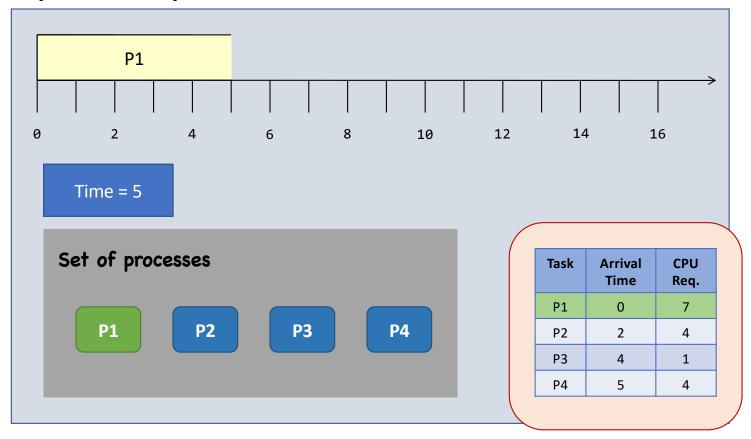
- CPU scheduler selects one of the processes that are ready to execute and allocates the CPU to it
- CPU scheduling decisions may take place when a process:
 - 1. Switches from running to waiting state
 - 2. Switches from running to ready state
 - 3. Switches from waiting to ready
 - 4. Terminates
- A scheduling algorithm takes place only under circumstances 1 and 4 is non-preemptive
- · All other scheduling algorithms are preemptive

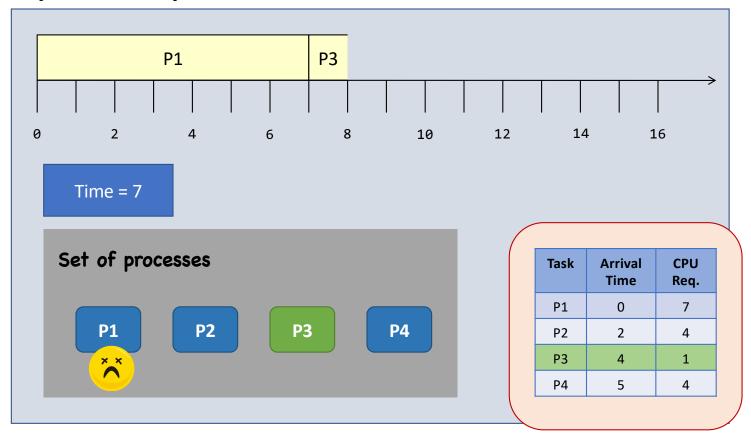
Scheduling Algorithm Optimization Criteria

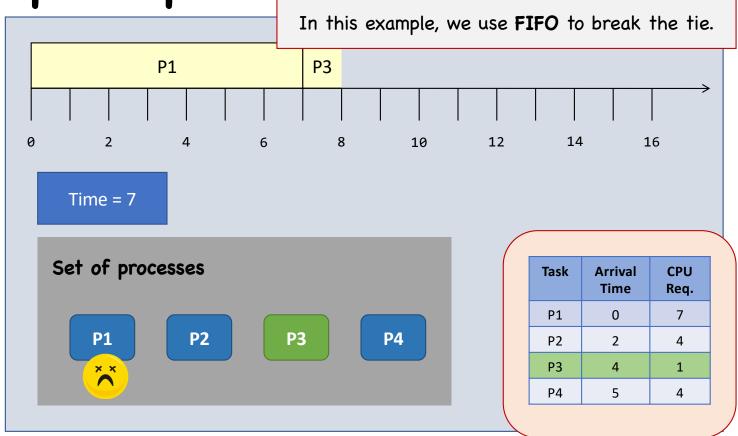
- Given a set of processes, with
 - Arrival time: the time they arrive in the CPU ready queue (from waiting state or from new state)
 - CPU requirement: their expected CPU burst time
- Minimize average turnaround time
 - Turnaround time: The time between the arrival of the task and the time it is blocked or terminated.
- Minimize average waiting time
 - Waiting time: The accumulated time that a task has waited in the ready queue.
- Reduce the number of context switches

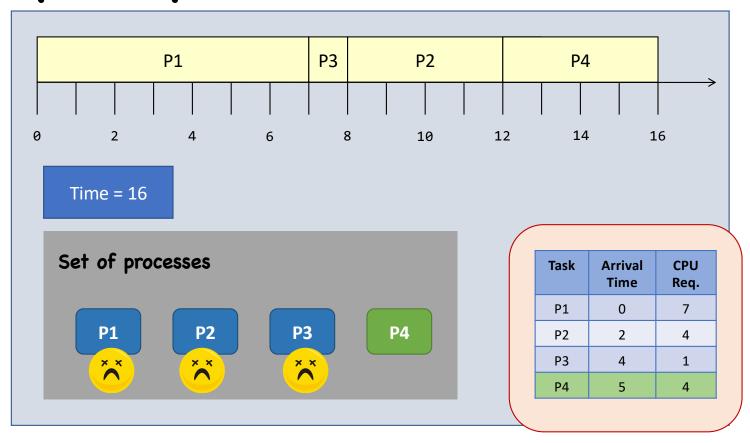
Different Algorithms

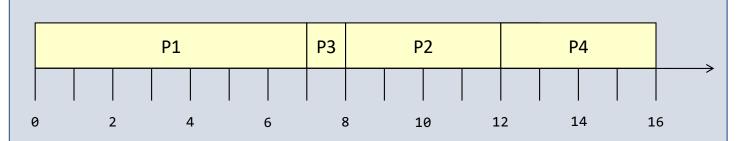
- Shortest-job-first (SJF)
- Round-robin (RR)
- Priority scheduling











Waiting time:

$$P1 = 0$$
; $P2 = 6$; $P3 = 3$; $P4 = 7$;

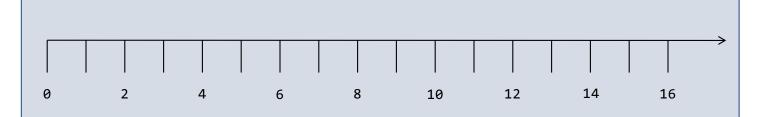
Average =
$$(0 + 6 + 3 + 7) / 4 = 4$$
.

Turnaround time:

Average =
$$(7 + 10 + 4 + 11) / 4 = 8$$
.

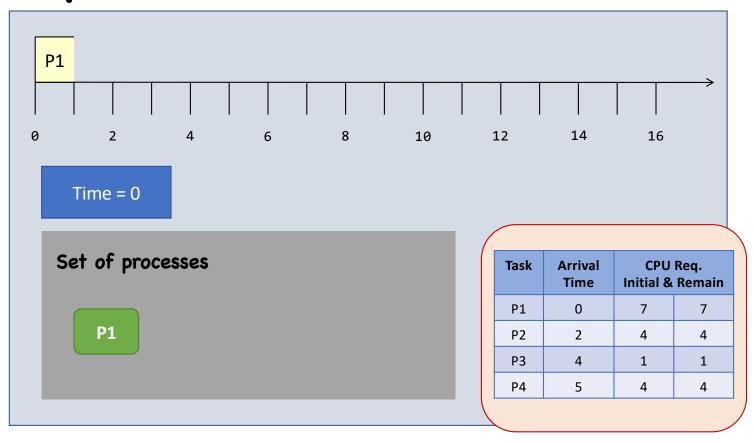
Task	Arrival Time	CPU Req.
P1	0	7
P2	2	4
Р3	4	1
P4	5	4

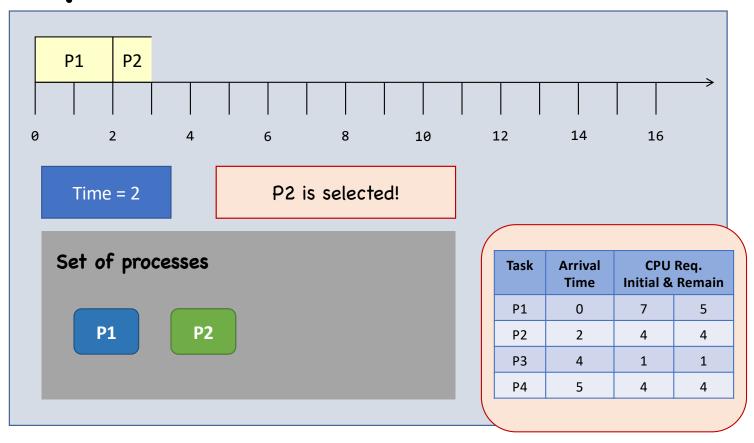
Preemptive SJF

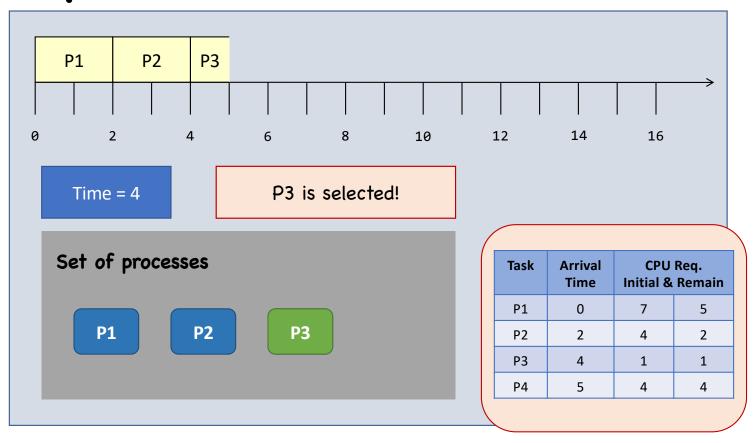


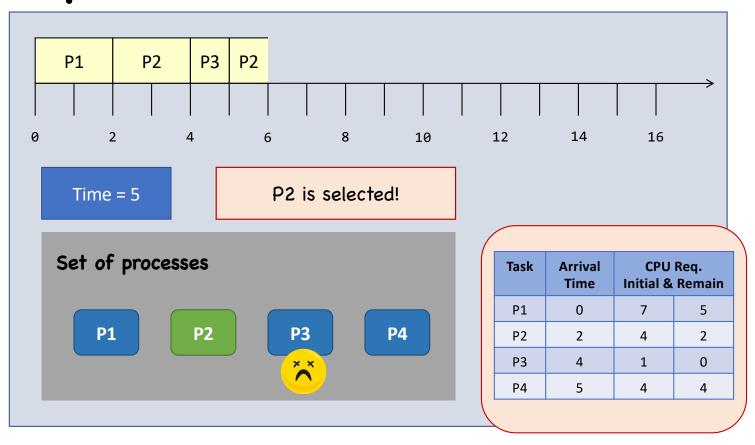
Whenever a new process arrives in the ready queue (either from waiting or from new state), the scheduler steps in and selects the next task based on their remaining CPU requirements.

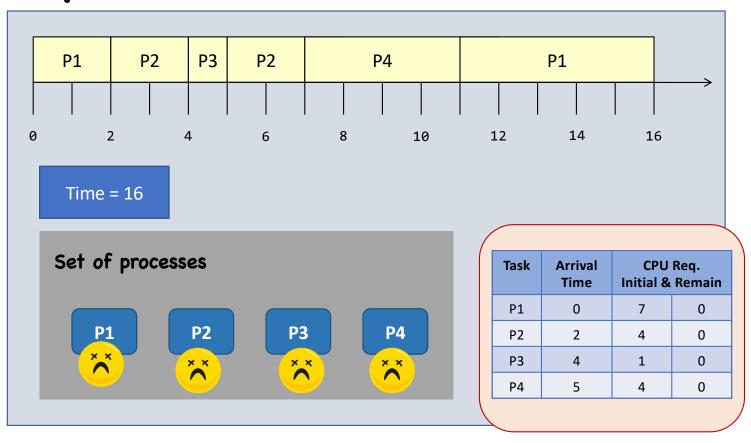
Task	Arrival Time	CPU Initial &	
P1	0	7	7
P2	2	4	4
Р3	4	1	1
P4	5	4	4



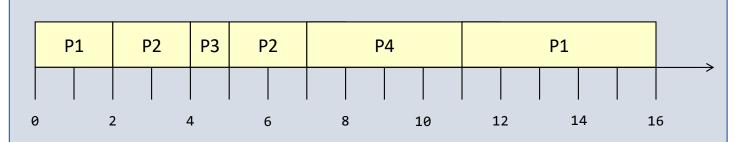








Preemptive SJF



Waiting time:

Average =
$$(9 + 1 + 0 + 2) / 4 = 3$$
.

Turnaround time:

Average =
$$(16 + 5 + 1 + 6) / 4 = 7$$
.

Task	Arrival Time	Init	Req. ial & nain
P1	0	7	0
P2	2	4	0
Р3	4	1	0
P4	5	4	0

SJF: Preemptive or Not?

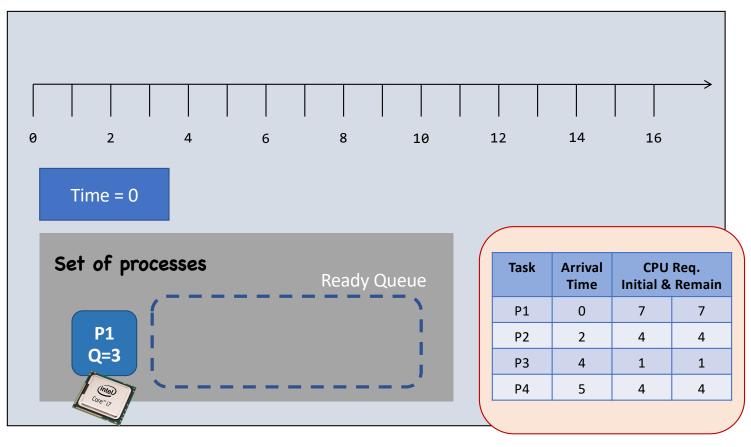
	Non-preemptive SJF	Preemptive SJF
Average waiting time	4	3 (smallest)
Average turnaround time	8	7 (smallest)
# of context switching	3	5 (largest)

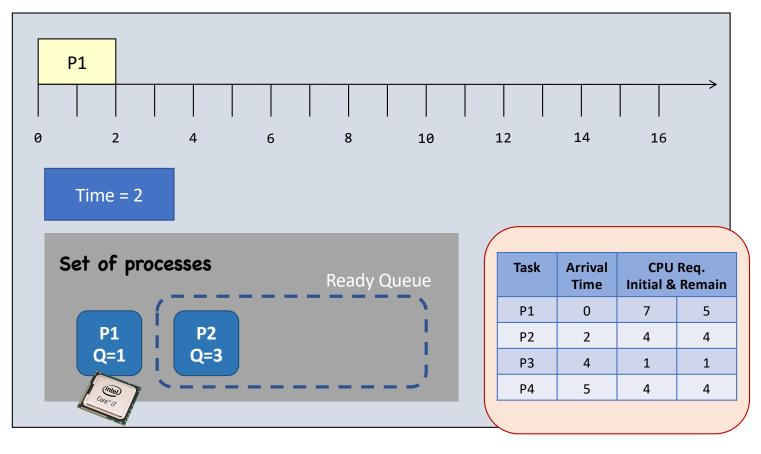
The waiting time and the turnaround time decrease at the expense of the <u>increased number of</u> context switches.

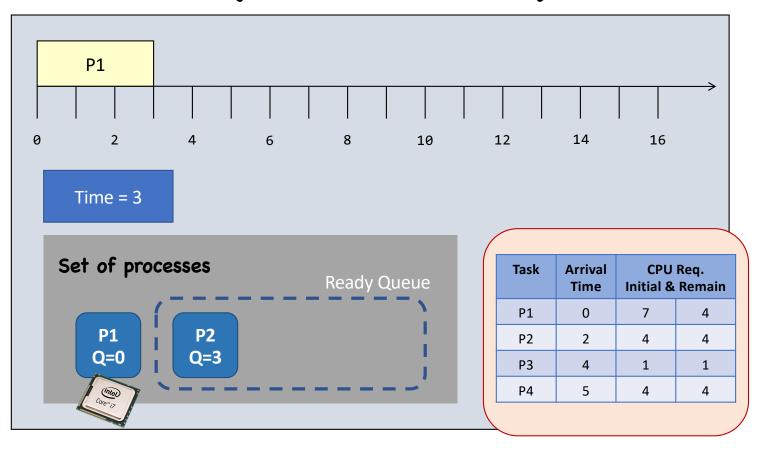
Task	Arrival Time	CPU Req.
P1	0	7
P2	2	4
Р3	4	1
P4	5	4

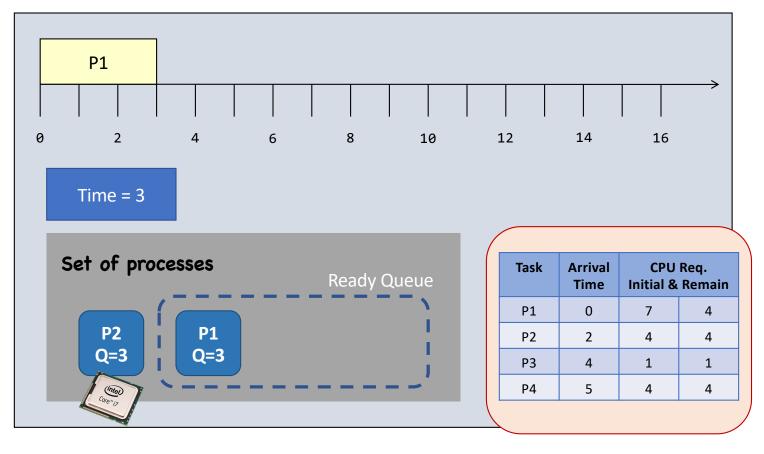
Round Robin (RR)

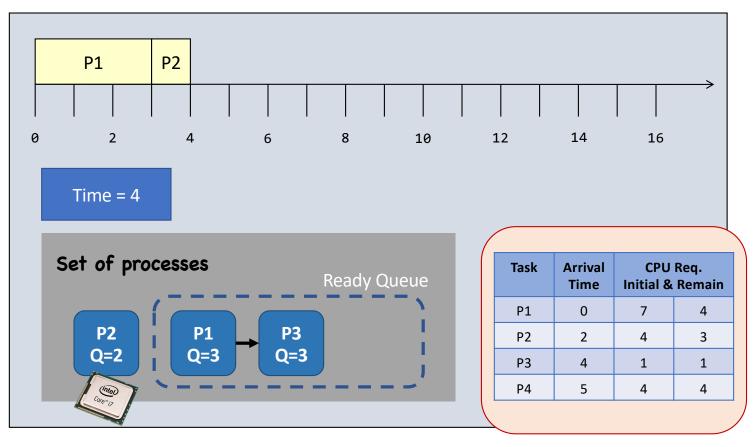
- Round-Robin (RR) scheduling is preemptive.
 - Every process is given a quantum (the amount of time allowed to execute).
 - Whenever the quantum of a process is used up (i.e., 0), the process is preempted, placed at the end of the queue, with its quantum recharged
 - Then, the scheduler steps in and it chooses the next process which has a non-zero quantum to run.
 - Processes are therefore running one-by-one as a circular queue
- · New processes are added to the tail of the ready queue
 - New process's arrival won't trigger a new selection decision

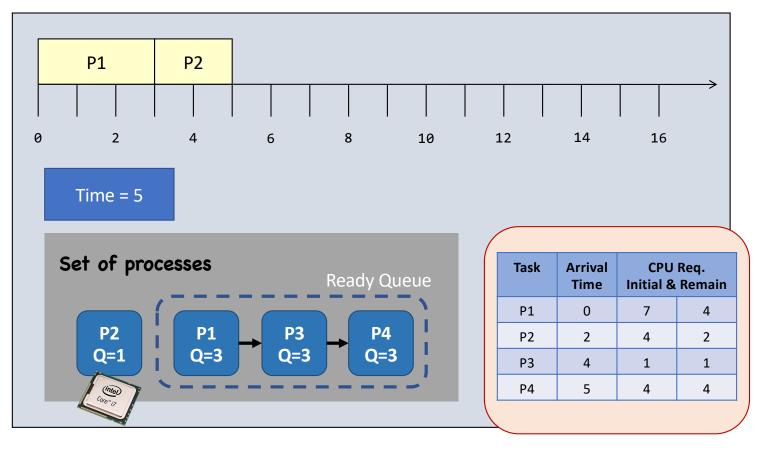


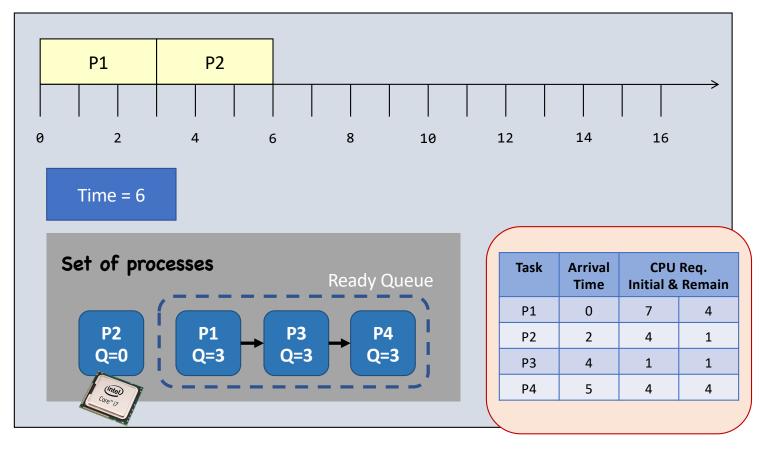


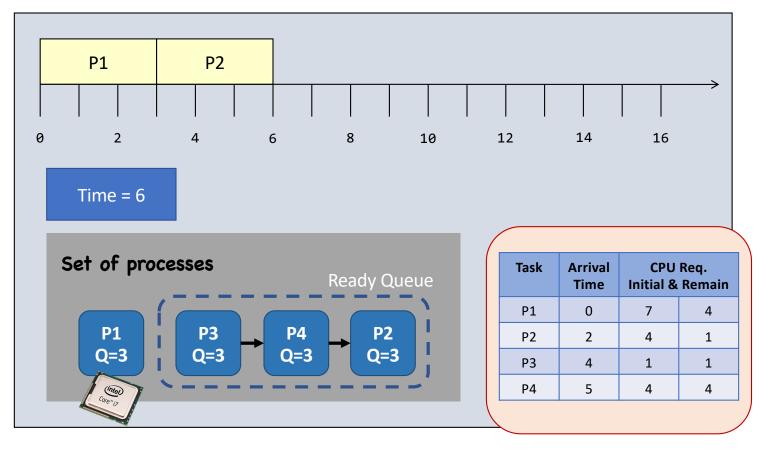


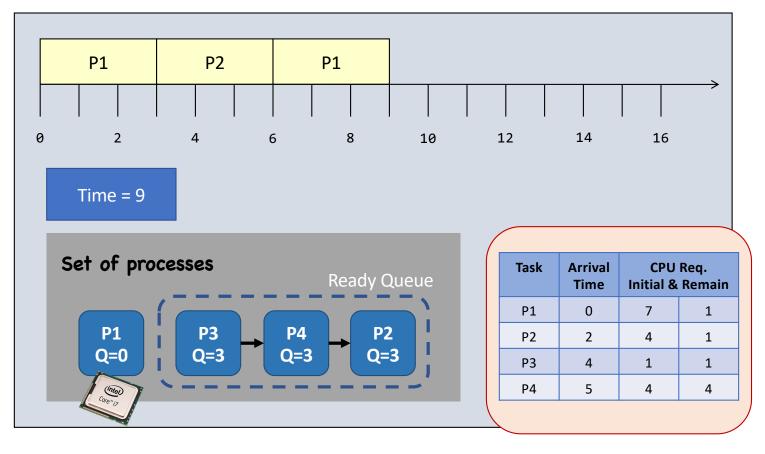


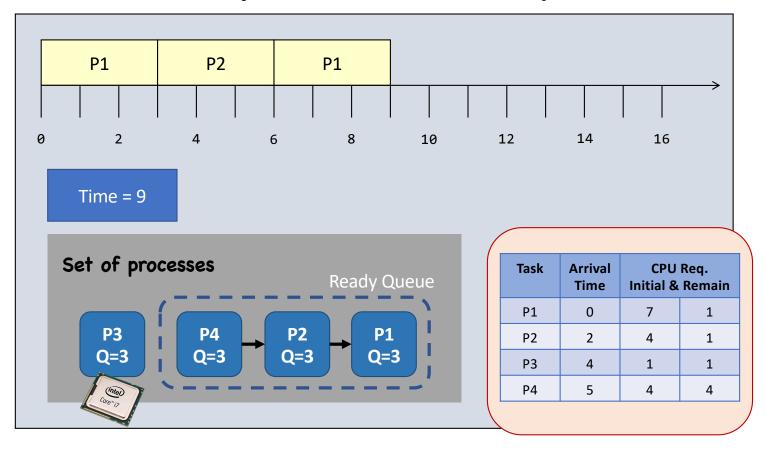


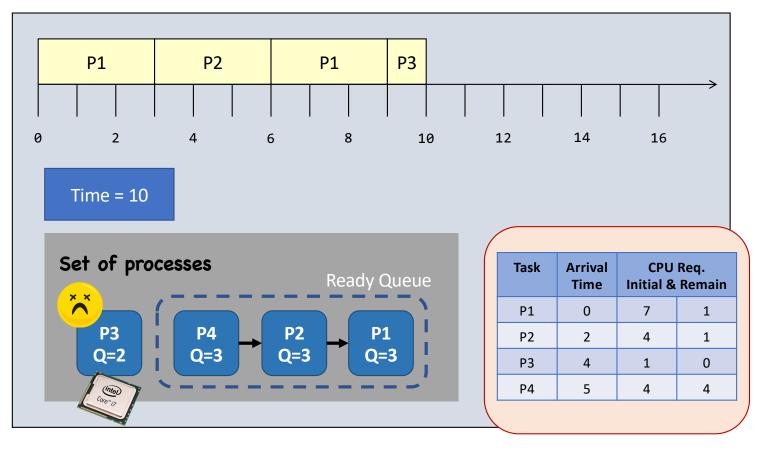


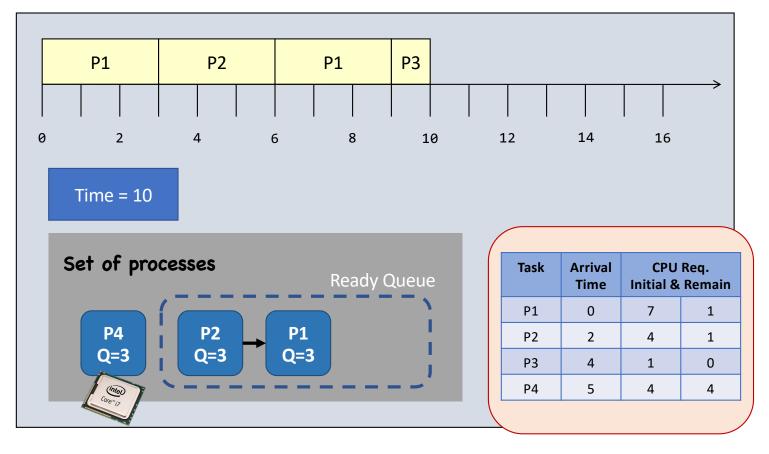


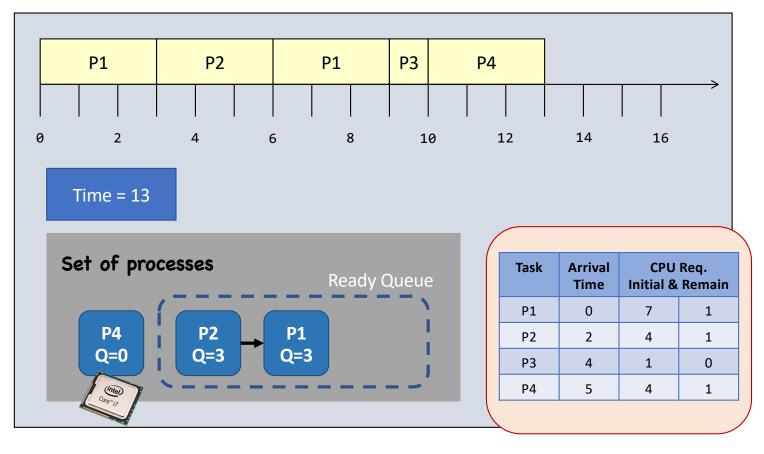


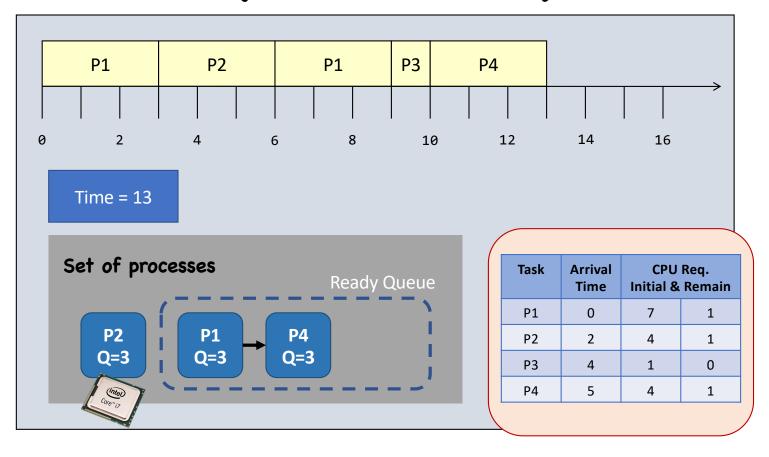


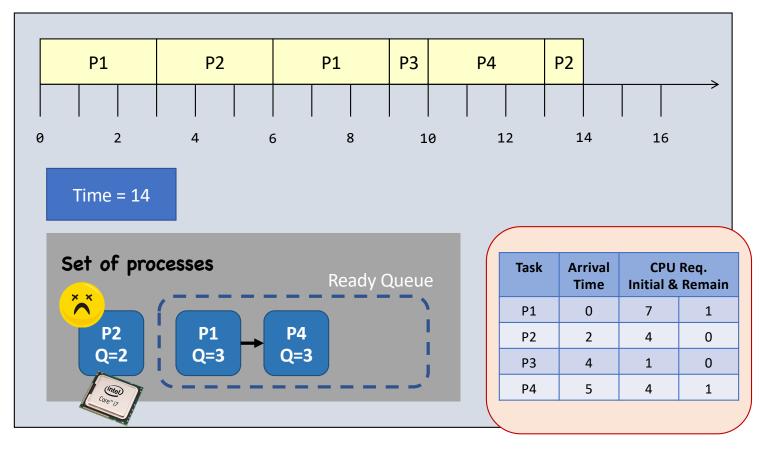


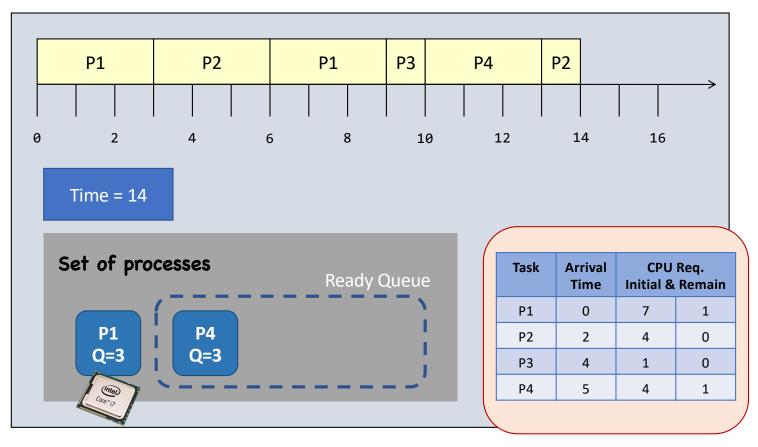






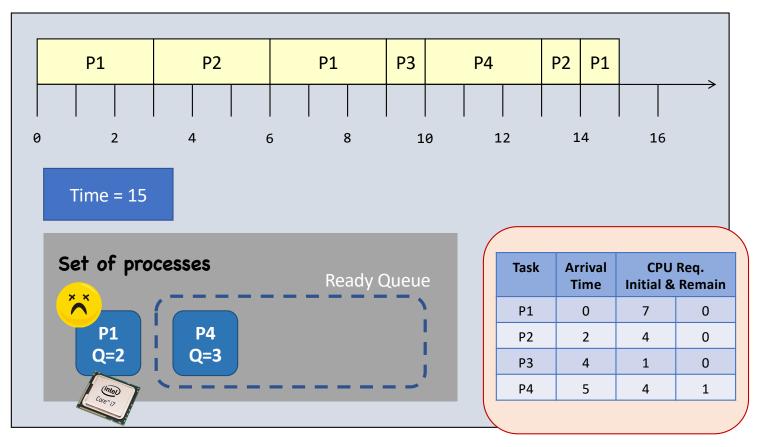






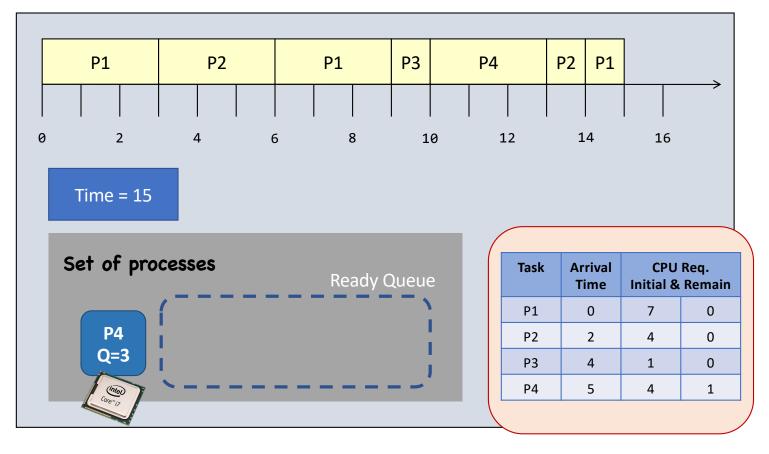
Animation; don't print

Round Robin (Quantum = 3)



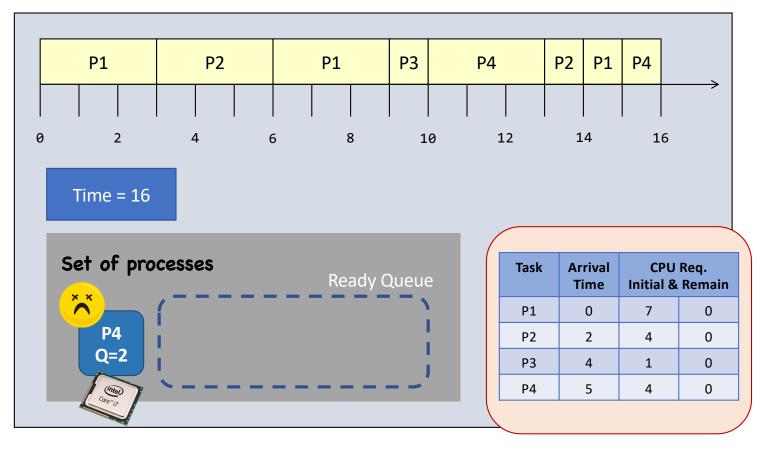
Animation; don't print

Round Robin (Quantum = 3)

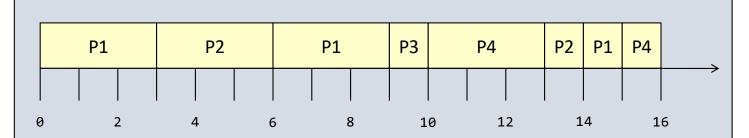


Animation; don't print

Round Robin (Quantum = 3)



Round Robin (Quantum = 3)



Waiting time:

$$P1 = 8$$
; $P2 = 8$; $P3 = 5$; $P4 = 7$;

Average =
$$(8 + 8 + 5 + 7) / 4 = 7$$

Turnaround time:

Average =
$$(15 + 12 + 6 + 11) / 4 = 11$$

Task	Arrival Time	CPU Req. Initial & Remain	
P1	0	7	0
P2	2	4	0
Р3	4	1	0
P4	5	4	0

RR v.s. SJF

	Non-preemptive SJF	Preemptive SJF	RR
Average waiting time	4	3	7 (largest)
Average turnaround time	8	7	11 (largest)
# of context switching	3	5	7 (largest)

So, the RR algorithm gets all the bad! Why do we still need it?

The responsiveness of the processes is great under the RR algorithm. E.g., you won't feel a job is "frozen" because every job gets the CPU from time to time!

Priority Scheduling

- A priority number (integer) is associated with each process
- The CPU is allocated to the process with the highest priority (smallest integer = highest priority)
 - Nonpreemptive: newly arrived process simply put into the queue
 - Preemptive: if the priority of the newly arrived process is higher than priority of the currently running process——preempt the CPU
- Static priority and dynamic priority
 - static priority: fixed priority throughout its lifetime
 - · dynamic priority: priority changes over time
- SJF is a priority scheduling where priority is the next CPU burst time

Priority Scheduling (Cont'd)

- Problem = Starvation low priority processes may never execute
 - Rumors has it that when they shut down the IBM 7094 at MIT in 1973, they found a low priority process that had been submitted in 1967 and had not yet been run.
- Solution = Aging as time progresses increase the priority of the process
 - Example: priority range from 127 (low) to 0 (high)
 - Increase priority of a waiting process by 1 every 15 minutes
 - 32 hours to reach priority 0 from 127

Linux Scheduling

- Before Linux kernel version 2.5, traditional UNIX scheduling, not adequately support SMP
- Linux kernel version 2.5, O(1) scheduler
 - Constant scheduling time regardless number of tasks
 - Better support for SMP
 - Poor response time for interactive processes
- After Linux kernel version 2.6.23, CFS-completely fair scheduler
 - Default scheduler now

Completely Fair Scheduler

- Scheduling class
 - Standard Linux kernel implements two scheduling classes
 - (1) Default scheduling class: CFS
 - (2) Real-time scheduling class
- Varying length scheduling quantum
 - Traditional UNIX scheduling uses 90ms fixed scheduling quantum
 - CFS assigns a proposition of CPU processing time to each task
- Nice value
 - -20 to +19, default nice is 0
 - · Lower nice value indicates a higher relative priority
 - Higher value is "being nice"
 - Task with lower nice value receives higher proportion of CPU time

Completely Fair Scheduler (Cont'd)

- Virtual run time
 - Each task has a per-task variable vruntime
 - Decay factor
 - Lower priority has higher rate of decay
 - nice = 0 virtual run time is identical to actual physical run time
 - A task with nice > 0 runs for 200 milliseconds, its vruntime will be higher than 200 milliseconds
 - A task with nice < 0 runs for 200 milliseconds, its vruntime will be lower than 200 milliseconds
- · Lower virtual run time, higher priority
 - To decide which task to run next, scheduler chooses the task that has the smallest vruntime value
 - Higher priority can preempt lower priority

Completely Fair Scheduler (Cont'd)

- Example: Two tasks have the same nice value
- One task is I/O bound and the other is CPU bound
- vruntime of I/O bound will be shorter than vruntime of CPU bound
- I/O bound task will eventually have higher priority and preempt CPU-bound tasks whenever it is ready to run

Thank you!

