



Project Overview

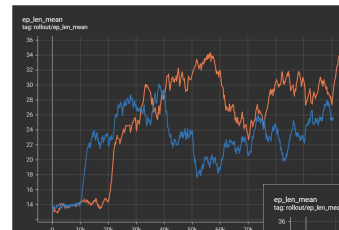
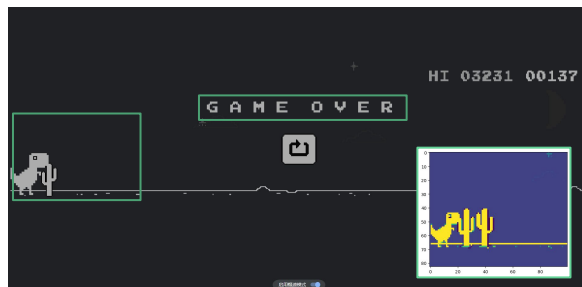
Inspiration/motivation:

- The remarkable success of Google's AI AlphaGo in mastering a complex and strategic game like GO
- Impressive performance of the DQN(Deep Q-network) model in Atari games
- Google's Dino Game as the test environment for simplicity

Reinforcement Learning:

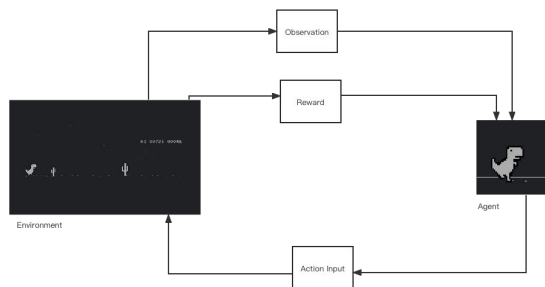
- Training models to decide the optimal decision by learning through a feedback system.

Observational Window



Model implementation: General Outline

- Set up observation windows
- Set up Key Mapping direction
- Set up Reward System
- Set up the DQN model



DQN Hyperparameter / Reward system

- Policy:**
 - Choosing between MLP and CNN
- Environment:**
 - The gaming environment we built
- Log directory:**
 - Where to store the training logs
- Verbose:**
 - Frequency of returning information
- Buffer size:**
 - Storage of past experience
- Learning starts:**
 - Size of initial database

```
reward = 1 # one point for each frame being alive
```

```
if not done:
    reward = 1
else:
    reward = -5
```

Conclusion/Potential Improvements

Conclusion:

Built our own RL model, capable of playing a simple webpage. The experimental results highlight the trade off between cautious decision-making and exploration of new strategies when considering penalties in the RL models.

Improvements:

- Hardware Upgrade
 - More RAM supports larger database
 - Better CPU and GPU supports faster processing
- Add Gamma hyperparameter
 - Discount factor for reward
- Better image preprocessing
 - Reduce down the noise