Shutong (Tony) Zhang

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EDUCATION

University of Toronto

Sep 2019 – Jun 2024 (Expected)

Bachelor of Applied Science and Engineering with High Honor

- CGPA: 3.99/4.00, Major GPA: 4.00/4.00, Core Course Average: 93.6 (Top 1%)
- Major in Computer Engineering, minor in Artificial Intelligence

PUBLICATIONS AND PAPERS

- [1] S. Zhang. NPSim: Nighttime Photorealistic Simulation From Daytime Images With Monocular Inverse Rendering and Ray Tracing. Thesis at ETH Computer Vision Lab (Aiming CVPR 2024). Link
- [2] S. Zhang*, Y. Qiao*, G. Zhu*, E. Heiden, D. Turpin, M. Lin, M. Macklin, A. Garg. HandyPriors: Physically Consistent Perception of Hand-Object Interactions with Differentiable Priors. Short paper accepted by the 2023 Computer Vision and Pattern Recognition Workshop (CVPRW 2023). Link Full paper submitted to the 2024 IEEE International Conference on Robotics and Automation (ICRA 2024)
- [3] D. Turpin, T. Zhong, S. Zhang, G. Zhu, E. Heiden, M. Macklin, S. Tsogkas, S. Dickinson, A. Garg. Fast-Grasp'D: Dexterous Multi-finger Grasp Generation Through Differentiable Simulation. Accepted by the 2023 IEEE International Conference on Robotics and Automation (ICRA 2023). Link

RESEARCH EXPERIENCE

ETH Zürich - Computer Vision Lab

Apr 2023 – Present

Research Assistant supervised by Prof. Luc Van Gool and Dr. Christos Sakaridis

- Designed and implemented NPSim: a data generation pipeline that simulates nighttime images from daytime images with monocular inverse rendering and ray tracing.
- Generated synthetic nighttime dataset from daytime images and preserved their semantic annotations. Achieved 11% performance improvement in nighttime image segmentation performance through training pre-existing models on our dataset.

University of Toronto - Forcolab

Apr 2022 – Present

Research Assistant supervised by Prof. Shurui Zhou, with Prof. Jinghui Cheng

- Conducted systematic literature review on collaboration between software development engineers (SEDs) and UX designers (UXDs) through 44 papers and identified four collaboration challenges and six potential best practices.
- Investigated the current state of SDEs and UXDs collaboration challenges by mining four online forums and the VScode GitHub project.

University of Toronto - Vector Institute/PAIR Lab

Aug 2022 – Apr 2023

Research Assistant supervised by Prof. Animesh Garg, with Prof. Ming C.Lin

Project: Physics-based Hand-object Pose Estimation

- Designed an integrated differentiable rendering and simulation pipeline to estimate the hand-object interaction, achieved 50% lower object error and 25% lower hand error than the state-of-the-art model.
- Generalized the pipeline to robotic hand manipulation and human-object pose estimation in the wild.
- Proposed a lightweight filtering-based tracking pipeline that uses differentiable priors and an Extended Kalman Filter, takes 2D fingertips location as its only feedback supervision, and achieves a speed of 40 frames per second.

Project: Multi-finger Robot Hand Grasp Generation

- Developed a grasp generation pipeline based on differentiable simulation that is 10x faster than the previous grasp generator "Graspit!", with 10x contact area and 2x epsilon quality.
- Generated DexGrasp-1M dataset of one million unique grasps with multi-modal visual input for vision-based multi-finger robotic grasping using Nvidia Replicator Composer.

University of Toronto - Computer Engineering Research Group

May 2021 – Sep 2021

Research Assistant supervised by Prof. Paul Chow

- Developed an FPGA-based Intrusion Detection and Prevention System using C++ and System Verilog that achieved 83 Gbps running on a single FPGA-equipped server.
- Proposed to combine shift-or filter and hash table that speed up string matching stage by 40%.
- Generated TCP and UDP testing traffic with speed up to 100Gbps using Cisco TRex traffic generator.

Intel Corporation - Engineering intern (Full time)

May 2022 – Apr 2023

Quality and Execution Team

Software Engineer & Project Manager

- \bullet Developed an auto-triage tool using Perl and MySQL that automatically analyzes test failures and reduces 95% manual efforts.
- Coordinated the development of the OFS 2022.3 (Open FPGA Software) and resolved 100% major issues before launch.

Customer Happiness and User Experience Team

Front-end Engineer

- Developed a statistic visualization tool using ReactJS and resolved 32 issues, including bug fixes, new feature implementation and performance optimization.
- Redesigned system-viewer a kernel events visualizer through Gantt charts using React-based graphics engine.
- Implemented a unit testing infrastructure using Jest that covers 75% of the source code.

Core Datapath Compiler Team

Compiler Engineer

- \bullet Improved one API compiler stability by fixing five E1 (major) bugs and 12 E2/E3 bugs.
- Implemented a Bit Manipulation Pass that performs bit shuffle during integer dot product, reduced dot product execution time by 25%.
- Mitigated oneAPI compiler source code vulnerability by performing a coverity scan and successfully resolving 23 identified issues.

University of Toronto - Teaching Assistant (Contract part-time)

Sep 2021 – Present

Supervised by Prof. Natalie Enright Jerger and Prof. Jonathan Rose

- Served as teaching assistant for ECE243 Computer Organization (Winter 2022, Winter 2023) and ECE253 Digital and Computer Systems (Fall 2021, Fall 2022).
- Supervised 15 student teams during their design projects, led lab sessions for groups of up to 30 students, conducted office hours, and graded exams.

ACADEMIC ACTIVITIES

Sub-Reviewer for ASE 2022, ECSE/FSE 2023, ICSE 2024.

Invited Talk at ETH Zurich Computer Vision Lab CVL-seminar series on my work NPSim. Slides

Selected Projects

Geographic Information System Software Program $\mid C++$

Jan 2021 – Apr 2021

- Developed large-scale Google-maps inspired UI / backend program using C++, HTML, JavaScript and CSS. The program visualizes 35 major cities all over the world.
- Implemented Dijkstra, A^* and Simulated-Annealing based heuristics for an NP-C graphing problem (Travelling salesman problem) that reduced the shortest path by 33% on a greedy algorithm basis.
- The proposed algorithm ranked 1 out of 109 teams in the travelling salesman problem-solving competition.

Color war | C. Assembly

Mar 2021 - Apr 2021

- \bullet Designed a two-player competitive game using C and ARM Assembly on an ARMv7 processor that utilized HEX Display, PS2 Keyboard, Pixel Buffer and Interrupt.
- Implemented a physics engine that simulates real-world acceleration and gravity.
- Selected as top 5% projects and received 1% bonus mark.

Awards and Honors

International Experience Award (\$3000)	May 2023
University of Toronto Summer Rèsearch Exchange Fellowship (\$3000)	Dec 2022
Edith Grace Buchan Undergraduate Research Fellowship (\$5400)	Apr 2022
Department of Electrical and Computer Engineering Top Student Award	Oct 2021
University of Toronto In-Course Scholarship (\$1500)	Aug 2021
University of Toronto Scholar	Aug 2021
University of Toronto Summer Research Fellowship (\$5000)	May 2021
Deans Honor List	2019 - 2022
Faculty Of Applied Science & Engineering Admission Scholarship (\$5000)	Sep 2019

SKILLS

Programming: Python, C/C++, MatLab, Perl, ReactJS, TypeScript, NodeJS, MySQL, ARM Assembly, VHDL Research Skills: Pytorch, Tensorflow, Docker, Nvidia Isaac Sim, Graspit!, Git, Linux, Slurm Softwares and Tools: Microsoft Office Suite, PhotoShop, LATEX, Figma, Quartus, ModelSim, Wireshark Language: English (fluent), Mandarin (native)