

# **Algorithm Design XII**

Linear Programming II

Guoqiang Li School of Software



**Review of Previous Lecture** 



$$\max x_1 + 6x_2 + 13x_3$$

$$x_1 \le 200$$

$$x_2 \le 300$$

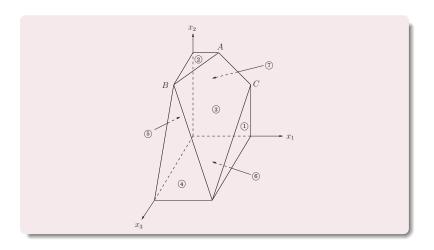
$$x_1 + x_2 + x_3 \le 400$$

$$x_2 + 3x_3 \le 600$$

$$x_1, x_2, x_3 \ge 0$$

## The Example







The point of final contact is the optimal vertex: (0, 300, 100), with total profit \$3100.

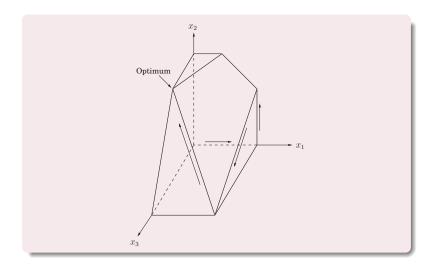
Q: How would the simplex algorithm behave on this modified problem?

A possible trajectory

$$\frac{(0,0,0)}{\$0} \to \frac{(200,0,0)}{\$200} \to \frac{(200,200,0)}{\$1400} \to \frac{(200,0,200)}{\$2800} \to \frac{(0,300,100)}{\$3100}$$

## The Example





#### LP and Its Dual



#### Primal LP

#### Dual LP

$$\begin{aligned} \max c^T \mathbf{x} & \min \mathbf{y}^T b \\ A \mathbf{x} &\leq b & \mathbf{y}^T A \geq c^T \\ \mathbf{x} &\geq 0 & \mathbf{y} \geq 0 \end{aligned}$$

#### Primal LP:

$$\max_{a_{i1}x_{1}+\cdots+a_{in}x_{n}\leq b_{i}} a_{i1}x_{1}+\cdots+a_{in}x_{n}\leq b_{i} \text{ for } i\in I$$

$$a_{i1}x_{1}+\cdots+a_{in}x_{n}=b_{i} \text{ for } i\in E$$

$$x_{j}\geq 0 \text{ for } j\in N$$

$$\min b_1 y_1 + \dots + b_m y_m$$

$$a_{1j} y_1 + \dots + a_{mj} y_m \ge c_j \quad \text{for } j \in N$$

$$a_{1j} y_1 + \dots + a_{mj} y_m = c_j \quad \text{for } j \notin N$$

$$y_i \ge 0 \quad \text{for } i \in I$$

#### LP and Its Dual



$$\max x_1 + 6x_2 x_1 \le 200 x_2 \le 300 x_1 + x_2 \le 400 x_1, x_2 \ge 0$$

$$\min 200y_1 + 300y_2 + 400y_3$$
$$y_1 + y_3 \ge 1$$
$$y_2 + y_3 \ge 6$$
$$y_1, y_2, y_3 \ge 0$$

**Max-Flow Min-Cut in LP** 



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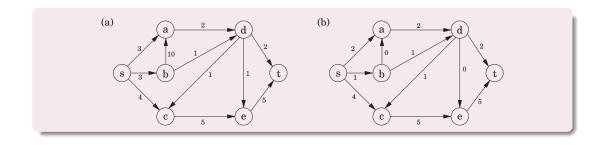
We have a network of pipelines along which oil can be sent.

The goal is to ship as much oil as possible from the source to the sink.

Each pipeline has a maximum capacity it can handle, and there are no opportunities for storing oil en route.

## **A Flow Example**







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Aim to send as much oil as possible from s to t without exceeding the capacities of any of the edges.



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A flow consists of a variable  $f_e$  for each edge e of the network, satisfying the following two properties:

- 1 It doesn't violate edge capacities:  $0 \le f_e \le c_e$  for all  $e \in E$ .
- ② For all nodes u except s and t, the amount of flow entering u equals the amount leaving

$$\sum_{(w,v)\in E} f_{wu} = \sum_{(u,z)\in E} f_{uz}$$

In other words, flow is conserved.



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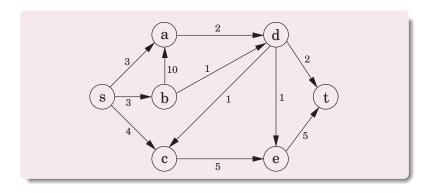
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This is a linear program. The maximum-flow problem reduces to linear programming.

# The Example











$$\mathsf{maximize}\ f_{sa} + f_{sb} + f_{sc}$$



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#### 27 constraints:

- 11 for nonnegativity (such as  $f_{sa} \ge 0$ ),
- 11 for capacity (such as  $f_{sa} \leq 3$ ),
- 5 for flow conservation (one for each node of the graph other than s and t, such as  $f_{sc}+f_{dc}=f_{ce}$ ).





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The advantage of making this modification is that we can now require flow conservation at s and t as well.

### **Another Representation**



$$\max f_{ts}$$

$$f_{ij} \le c_{ij} \qquad (i,j) \in E$$

$$\sum_{(w,i)\in E} f_{wi} - \sum_{(i,z)\in E} f_{iz} \le 0 \quad i \in V$$

$$f_{ij} \ge 0 \qquad (i,j) \in E$$



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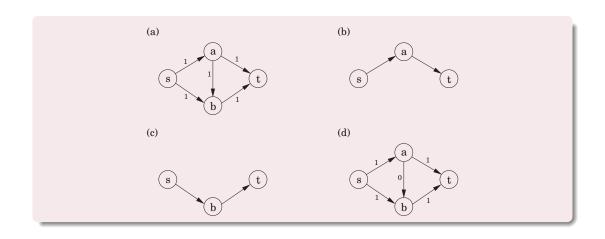
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The behavior of the simplex has an elementary interpretation:

- Start with zero flow.
- Repeat: choose an appropriate path from s to t, and increase flow along the edges of this path
  as much as possible.

# **A Flow Example**







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Simplex gets around this problem by also allowing paths to cancel existing flow.





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in the second case, up to  $f_{vu}$  additional units (canceling all or part of the existing flow on (v, u)).



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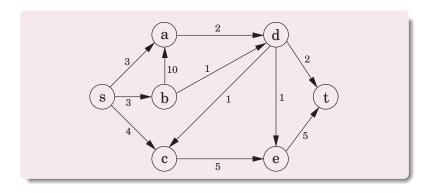
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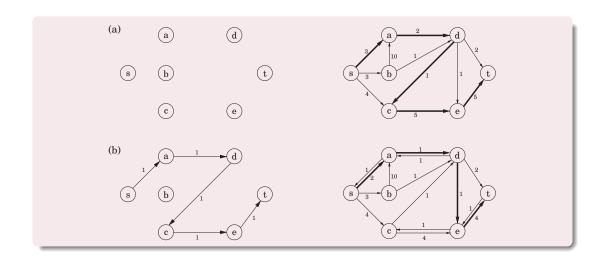
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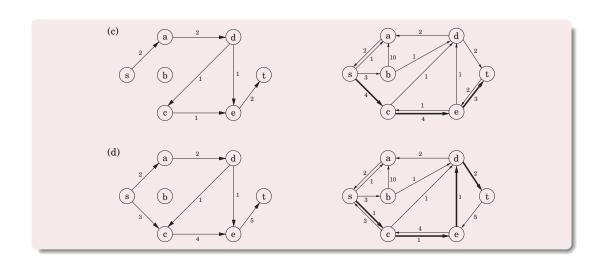
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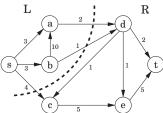






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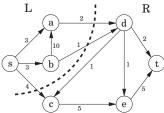
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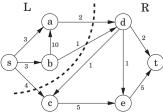


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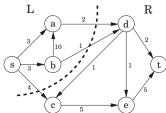


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Pick any flow f and any (s,t)-cut (L,R). Then  $size(f) \le capacity(L,R)$ .



### **Theorem (Max-flow min-cut)**

The size of the maximum flow in a network equals the capacity of the smallest (s,t)-cut.



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Therefore the net flow across (L, R) is exactly the capacity of the cut.

# **Efficiency**



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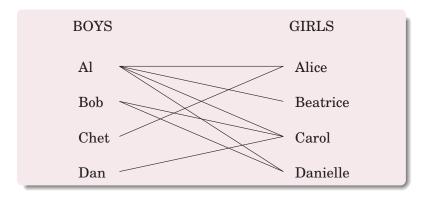
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This latter bound gives an overall running time of  $O(|V| \cdot |E|^2)$  for maximum flow.

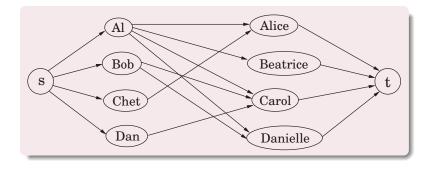
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\*\*Min-Max Relations in LP\*\*

#### **LP for Max Flow**



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$$\sum_{(w,i)\in E} f_{wi} - \sum_{(i,z)\in E} f_{iz} \le 0 \quad i \in V$$

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### **LP-Duality**



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$$f_{ij} \ge 0 \qquad (i,j) \in E$$

$$\min \sum_{(i,j)\in E} c_{ij} d_{ij}$$

$$d_{ij} - p_i + p_j \ge 0 \quad (i,j) \in E$$

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### **Explanation of the Dual**



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This solution defines an s-t cut  $(X,\overline{X})$ , where X is the set of potential 1 nodes, and  $\overline{X}$  the set of potential 0 nodes.



$$\begin{aligned} & \min \sum_{(i,j) \in E} c_{ij} d_{ij} \\ & d_{ij} - p_i + p_j \ge 0 \quad (i,j) \in E \\ & p_s - p_t \ge 1 \\ & d_{ij} \in \{0,1\} \qquad (i,j) \in E \\ & p_i \in \{0,1\} \qquad i \in V \end{aligned}$$



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The distance label for each of the remaining edges can be set to either 0 or 1 without violating the first constraints.

The objective function value is precisely the capacity of the cut  $(X, \overline{X})$ , and hence  $(X, \overline{X})$  must be a minimum s - t cut.



The integer program is a formulation of the minimum  $s-t \ {\rm cut} \ {\rm problem}.$ 



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We will say that this program is the LP relaxation of the integer program.



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The constraint matrix of this program is totally unimodular, Thus, the dual program always has an integral optimal solution.

Homework

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Assignment 5(1 week). Exercises 7.6, 7.7, 7.21 and 7.23.