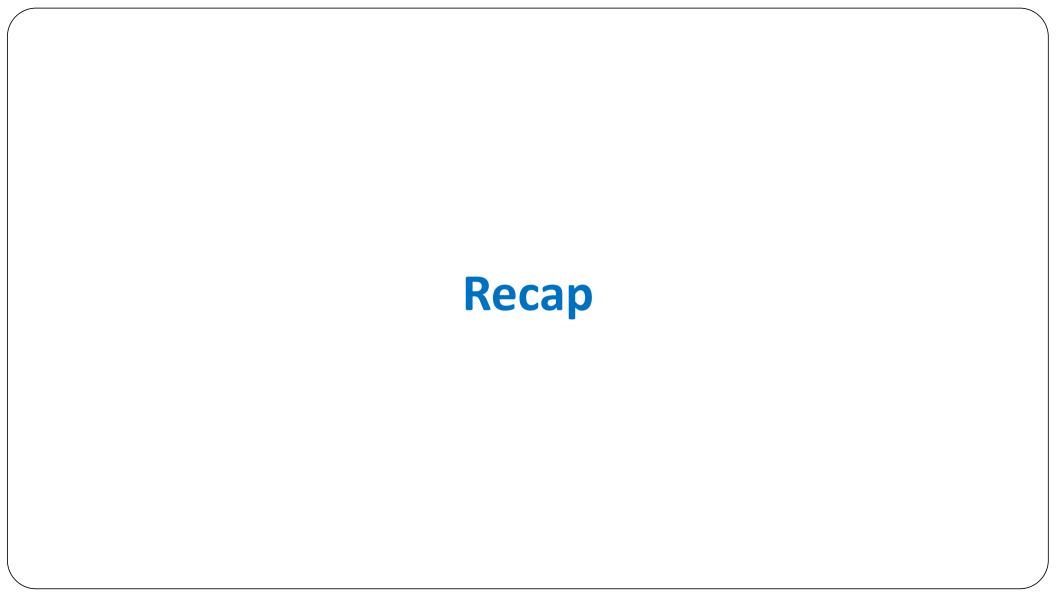
NYCU DL Lab1 - Backpropagation

TA 高宗霖

March 21, 2023

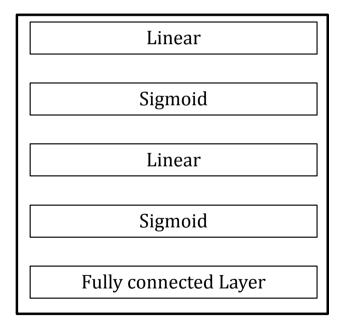
Outline

- Recap
- Lab Objective
- Lab Description
- Scoring Criteria
- Importance Date
- Demo format



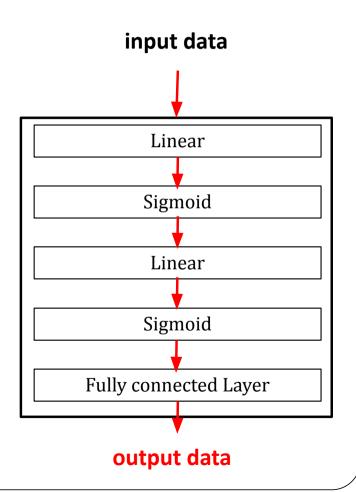
Recap - Build a Network

```
class simple(nn.Module):
    def init (self, num hidden):
        self.layer1 = nn.Sequential(
            nn.Linear(\overline{2}, num \ hidden),
            nn.Sigmoid()
        self.layer2 = nn.Sequential(
            nn.Linear(num hidden, num hidden),
            nn.Sigmoid()
        self.flatten = nn.Linear(num_hidden, 1)
    def forward(self, x):
        h1 = self.layer1(x)
        h2 = self.layer2(h1)
        out = self.flatten(h2)
        return out
```



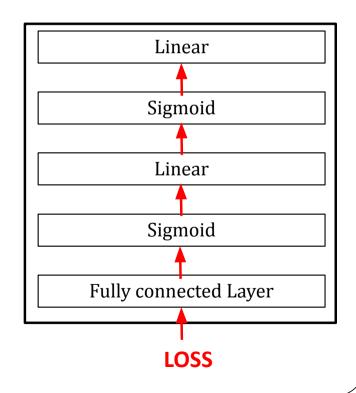
Recap - Forward

```
class simple(nn.Module):
    def init (self, num hidden):
        self.layer1 = nn.Sequential(
            nn.Linear(\overline{2}, num \ hidden),
            nn.Sigmoid()
        self.layer2 = nn.Sequential(
            nn.Linear(num hidden, num hidden),
            nn.Sigmoid()
        self.flatten = nn.Linear(num_hidden, 1)
    def forward(self, x):
        h1 = self.layer1(x)
        h2 = self.layer2(h1)
        out = self.flatten(h2)
        return out
```



Recap - Backpropagation

```
class simple(nn.Module):
    def init (self, num hidden):
        self.layer1 = nn.Sequential(
            nn.Linear(\overline{2}, num \ hidden),
            nn.Sigmoid()
        self.layer2 = nn.Sequential(
            nn.Linear(num hidden, num hidden),
            nn.Sigmoid()
        self.flatten = nn.Linear(num_hidden, 1)
    def forward(self, x):
        h1 = self.layer1(x)
        h2 = self.layer2(h1)
        out = self.flatten(h2)
        return out
```



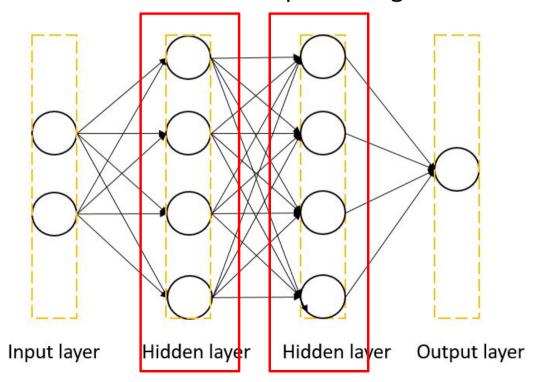
Recap - Backpropagation

```
class simple(nn.Module):
             def init (self, num hidden):
                self.layer1 = nn.Sequential(
                   nn.Linear(2, num hidden),
                                                                        Linear
                   nn.Sigmoid()
loss.backward()
             def forward(self, x):
                h1 = self.layer1(x)
                                                                       Sigmoid
                h2 = self.layer2(h1)
                out = self.flatten(h2)
                return out
                                                                 Fully connected Layer
                                                                         LOSS
```

Lab Objective

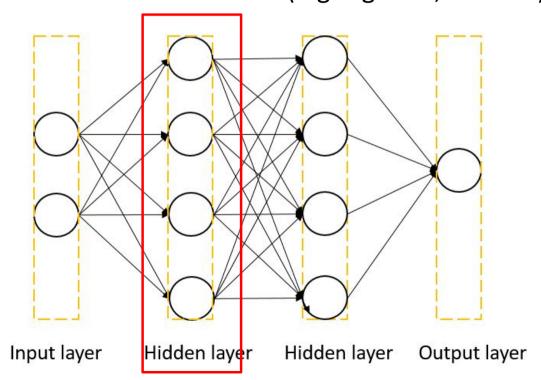
Lab Objective

• In this lab, you will need to understand and implement a simple neural network with forward and backward pass using two hidden layers

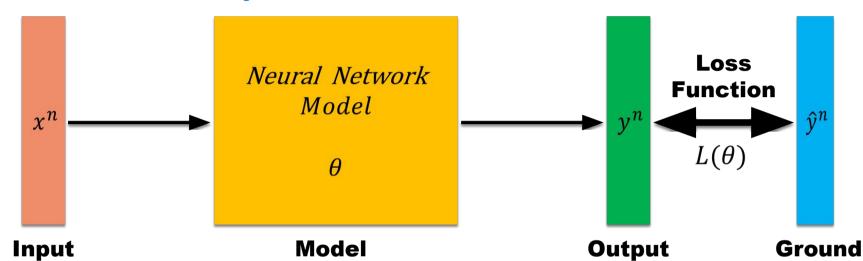


- Implement a simple neural network with two hidden layers
- You can only use Numpy and other python standard libraries.
 - Pytorch, TensorFlow,.... are not allowed
- Plot your comparison figure showing the predictions and ground truth.
- Plot your learning curve (loss, epoch).
- Print the accuracy of your prediction .
- Print the training Loss in the end of the few last epochs.
- List above results in your report

 Each Layer should contain at least one transformation (e.g. Linear, CNN,...) and one activation function (e.g. sigmoid, tanh....)



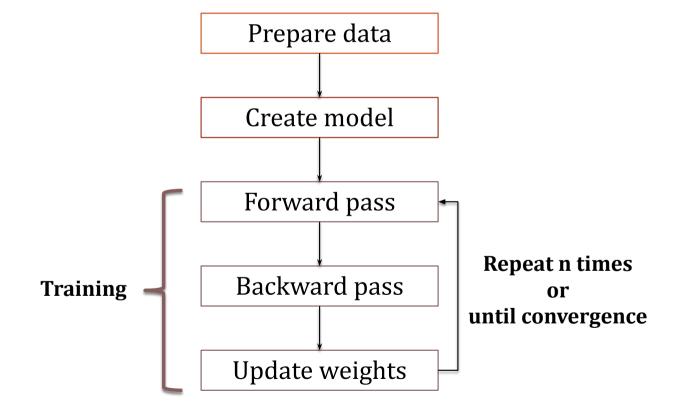
13



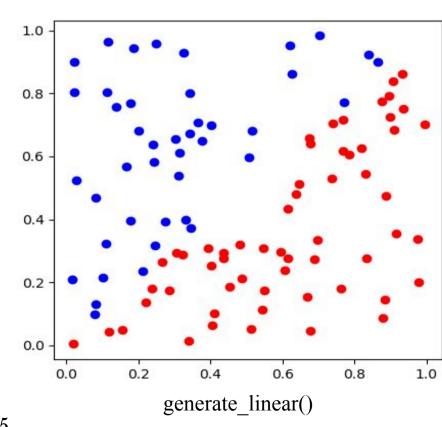
$$\theta = \{w_1, w_2, w_3, w_4, \cdots\}$$

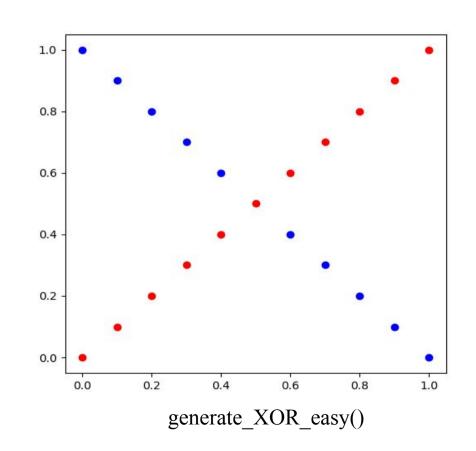
$$\begin{bmatrix} \nabla L(\theta) = & \text{Compute } \nabla L(\theta^0) & \theta^1 = \theta^0 - \rho \nabla L(\theta^0) \\ \frac{\partial L(\theta)/\partial w_1}{\partial L(\theta)/\partial w_2} & \text{Compute } \nabla L(\theta^1) & \theta^2 = \theta^1 - \rho \nabla L(\theta^1) \\ \frac{\partial L(\theta)/\partial w_3}{\partial L(\theta)/\partial w_3} & \text{Compute } \nabla L(\theta^2) & \theta^3 = \theta^2 - \rho \nabla L(\theta^2) \\ \vdots & \vdots & \rho : \text{Learning rate} \end{bmatrix}$$

Lab Description – Flowchart



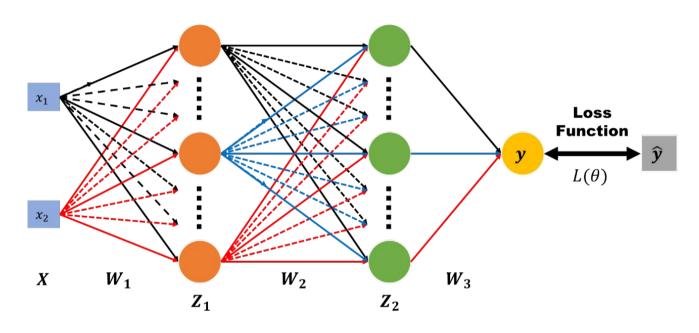
Lab Description - Data





15

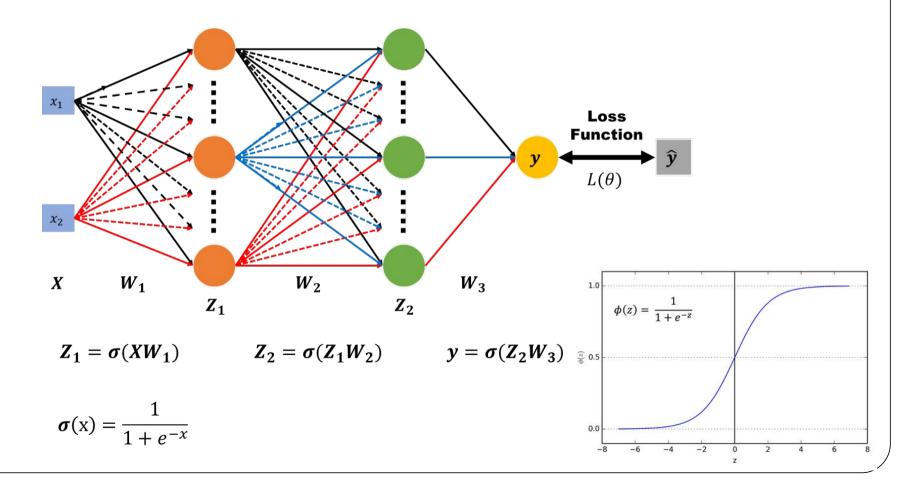
Lab Description – Architecture



 $X:[x_1,x_2]$ y: outputs $\hat{y}:$ ground truth

 W_1, W_2, W_3 : weight matrix of network layers

Lab Description – Forward



Lab Description – Backward

$$x = xw_1 \qquad z = x'' \qquad y \qquad L(\theta)$$

$$x' = xw_1 \qquad z = \sigma(x') \qquad x'' = zw'_1 \qquad y = \sigma(x'')$$

Chain rule
$$y = g(x) \quad z = h(y)$$

$$\mathbf{x} \stackrel{\mathbf{g}()}{\to} \mathbf{y} \stackrel{\mathbf{h}()}{\to} \mathbf{z} \qquad \frac{dz}{dx} = \frac{dz}{dy} \frac{dy}{dx}$$

$$\begin{split} \frac{\partial L(\theta)}{\partial w_1} &= \frac{\partial y}{\partial w_1} \frac{\partial L(\theta)}{\partial y} \\ &= \frac{\partial x''}{\partial w_1} \frac{\partial y}{\partial x''} \frac{\partial L(\theta)}{\partial y} \\ &= \frac{\partial z}{\partial w_1} \frac{\partial x''}{\partial z} \frac{\partial y}{\partial x''} \frac{\partial L(\theta)}{\partial y} \\ &= \frac{\partial z}{\partial w_1} \frac{\partial z''}{\partial z} \frac{\partial z''}{\partial z} \frac{\partial z''}{\partial z''} \frac{\partial z}{\partial z} \frac{\partial L(\theta)}{\partial z} \end{split}$$

$$Z_{1}=(V) \quad Q_{1}=f(Z_{1}) \quad Z_{2}=W_{2}Q_{1} \quad Q_{2}=f(Z_{2})$$

$$\bigoplus_{0} \frac{\partial L}{\partial Z_{1}} \quad \bigcirc_{0} \frac{\partial L}{\partial Z_{2}} \quad \bigcirc_{0} \frac{\partial L}{\partial Z_{2}} \quad \bigcirc_{0} \frac{\partial L}{\partial Z_{2}}$$

$$\bigoplus_{0} \frac{\partial L}{\partial Z_{2}} \quad \bigcirc_{0} \frac{\partial L}{\partial Z_{2}} \quad \bigcirc_{0} \frac{\partial L}{\partial Z_{2}} \quad \bigcirc_{0} \frac{\partial L}{\partial Z_{2}}$$

$$\bigoplus_{0} \frac{\partial L}{\partial Z_{2}} = \frac{\partial Y}{\partial Y} \frac{\partial L}{\partial Y} = O'(Z_{1}) \frac{\partial L}{\partial Y}$$

$$\bigoplus_{0} \frac{\partial L}{\partial Z_{2}} = \frac{\partial Q_{2}}{\partial Z_{2}} \frac{\partial L}{\partial X_{2}} = \frac{\partial Q_{2}}{\partial Z_{2}} \left(\frac{\partial Z_{2}}{\partial Z_{2}} \frac{\partial L}{\partial Z_{2}}\right) \quad (W_{3})_{(x_{1})} (Z_{3}-der)_{(x_{1})extext_{3}ize}$$

$$\bigoplus_{0} \frac{\partial L}{\partial Z_{2}} = \frac{\partial Q_{2}}{\partial Z_{2}} \frac{\partial L}{\partial X_{2}} = \frac{\partial Q_{2}}{\partial Z_{2}} \left(\frac{\partial Z_{2}}{\partial Z_{2}} \frac{\partial L}{\partial Z_{2}}\right) \quad (W_{3})_{(x_{1})} (Z_{3}-der)_{(x_{1})ext_{2}t_{3}ize}$$

$$\bigoplus_{0} \frac{\partial L}{\partial Y} + (I-\hat{Y}) \frac{I}{I-\hat{Y}} = \frac{-\hat{Y}}{Y} + \frac{I-\hat{Y}}{I-Y} \quad (W_{3})_{(x_{2})} (Z_{3}-der)_{(x_{1})ext_{2}t_{3}ize}$$

$$Q_{1} \left(\frac{Y_{1}}{Y_{1}} + (I-\hat{Y}) \frac{I}{I-\hat{Y}}\right) = \frac{-\hat{Y}}{Y} + \frac{I-\hat{Y}}{I-Y} \quad (W_{3})_{(x_{2})} (Z_{3}-der)_{(x_{1})ext_{2}t_{3}ize}$$

$$Q_{1} \left(\frac{Y_{1}}{Y_{1}} + (I-\hat{Y}) \frac{I}{I-\hat{Y}}\right) = \frac{-\hat{Y}}{Y} + \frac{I-\hat{Y}}{I-Y} \quad (W_{3})_{(x_{3})} (Z_{3}-der)_{(x_{1})ext_{2}t_{3}ize}$$

$$Q_{1} \left(\frac{Y_{2}}{Y_{1}} + (I-\hat{Y}) \frac{I}{I-\hat{Y}}\right) = \frac{1}{Y_{2}} + \frac{I-\hat{Y}}{I-Y} \quad (W_{3})_{(x_{3})} (Z_{3}-der)_{(x_{3})ext_{3}ize}$$

$$Q_{2} \left(\frac{Y_{3}}{Y_{1}} + (I-\hat{Y}) \frac{I}{I-\hat{Y}}\right) = \frac{1}{Y_{3}} + \frac{I-\hat{Y}}{I-Y} \quad (W_{3})_{(x_{3})} (Z_{3}-der)_{(x_{3})ext_{3}ize}$$

$$Q_{1} \left(\frac{Y_{3}}{Y_{1}} + (I-\hat{Y}) \frac{I}{I-\hat{Y}}\right) = \frac{1}{Y_{3}} + \frac{I-\hat{Y}}{I-\hat{Y}} \quad (W_{3})_{(x_{3})} (Z_{3}-der)_{(x_{3})ext_{3}ize}$$

$$Q_{2} \left(\frac{Y_{3}}{Y_{1}} + (I-\hat{Y}) \frac{I}{I-\hat{Y}}\right) = \frac{1}{X_{3}} + \frac{1}{X_{3}} \cdot (Z_{3}-der)_{(x_{3})ext_{3}ize}$$

$$Q_{1} \left(\frac{Y_{3}}{Y_{3}} + (I-\hat{Y}) \frac{I}{I-\hat{Y}}\right) = \frac{1}{X_{3}} \cdot (Z_{3}-der)_{(x_{3})ext_{3}ize}$$

$$Q_{2} \left(\frac{Y_{3}}{Y_{3}} + (I-\hat{Y}) \frac{I}{I-\hat{Y}}\right) = \frac{1}{X_{3}} \cdot (Z_{3}-der)_{(x_{3})ext_{3}ize}$$

$$Q_{3} \left(\frac{Y_{3}}{Y_{3}} + (I-\hat{Y}) \frac{I}{I-\hat{Y}}\right) = \frac{1}{X_{3}} \cdot (Z_{3}-der)_{(x_{3})ext_{3}ize}$$

$$Q_{3} \left(\frac{Y_{3}}{Y_{3}} + (I-\hat{Y}) \frac{I}{I-\hat{Y}}\right) = \frac{1}{X_{3}} \cdot (Z_{3}-der)_{(x_{3})ext_{3}ize}$$

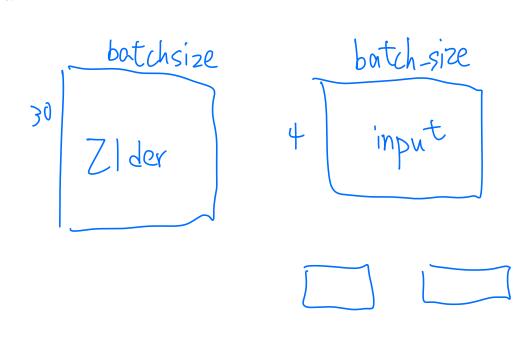
$$Q_{2} \left(\frac{Y_{3}}{Y_$$

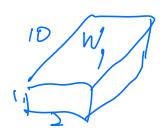
$$\frac{\partial L}{\partial W_{211}} = \frac{\partial Z_{21}}{\partial W_{211}} \frac{\partial L}{\partial Z_{21}} = \Omega_{11} \frac{\partial L}{\partial Z_{21}}$$

$$\frac{\partial L}{\partial b_3} = \frac{\partial z_3}{\partial b_3} \frac{\partial L}{\partial z_3}$$
botch-size
$$l_1 \left(\begin{array}{c} \alpha_{11} \\ \alpha_{12} \\ \vdots \end{array} \right) \frac{\partial L}{\partial b_{21}} = \frac{\partial z_{21}}{\partial b_{21}} \frac{\partial L}{\partial z_{21}}$$

Find
$$A_{11}$$
 A_{12}
 A_{13}
 A_{13}
 A_{14}
 A_{15}
 A_{15}

$$\frac{1}{2} \frac{\partial O_{i}}{\partial F} \frac{\partial L}{\partial O_{i}} = \frac{\partial O_{i}}{\partial O_{i}} O$$

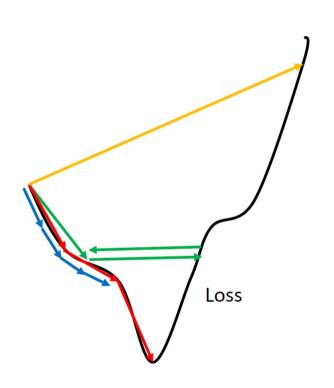




) 6

Lab Description – Gradient descent

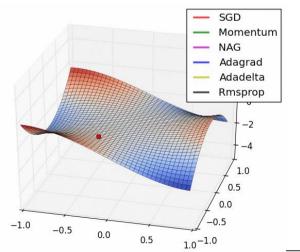
Network Parameters
$$\theta = \{w_1, w_2, w_3, w_4, \cdots\}$$



$$\theta^1 = \theta^0 - \rho \, \nabla L(\theta^0)$$

$$\theta^2 = \theta^1 - \rho \, \nabla L(\theta^1)$$

$$\theta^3 = \theta^2 - \rho \, \nabla L(\theta^2)$$



Lab Description - Prediction

• In the training, you need to print loss

epoch 10000 loss : 0.16234523253277644 epoch 15000 loss : 0.2524336634177614 epoch 20000 loss : 0.1590783047540092 epoch 25000 loss : 0.22099447030234853 epoch 30000 loss : 0.3292173477217561 epoch 35000 loss : 0.40406233282426085 epoch 40000 loss : 0.43052897480298924 epoch 45000 loss : 0.4207525735586605 epoch 50000 loss : 0.3934759509342479 epoch 55000 loss : 0.3615008372106921 epoch 60000 loss : 0.33077879872648525 epoch 65000 loss : 0.30333537090819584 epoch 70000 loss : 0.2794858089741792 epoch 75000 loss : 0.25892812312991587 epoch 80000 loss : 0.24119780823897027 epoch 85000 loss : 0.22583656353511342 epoch 90000 loss : 0.21244497028971704 epoch 95000 loss : 0.2006912468389013

• In the testing, you need to show your predictions, also the accuracy

```
[[0.01025062]
 [0.99730607]
 0.02141321]
 [0.99722154]
 [0.03578171]
 [0.99701922]
[0.04397049]
 [0.99574117]
 [0.04162245]
 [0.92902792]
 [0.03348791]
 [0.02511045]
 [0.94093942]
 [0.01870069]
 [0.99622948]
 [0.01431959]
 [0.99434455]
 [0.01143039]
 0.98992477
 [0.00952752]
 0.98385905]
```

Input data generate

```
def generate_linear(n=100):
    import numpy as np
    pts = np.random.uniform(0, 1, (n, 2))
    inputs = []
    labels = []
    for pt in pts:
        inputs.append([pt[0], pt[1]])
        distance = (pt[0]-pt[1])/1.414
        if pt[0] > pt[1]:
            labels.append(0)
        else:
            labels.append(1)
    return np.array(inputs), np.array(labels).reshape(n, 1)
```

```
def generate_XOR_easy():
    import numpy as np
    inputs = []
    labels = []

    for i in range(11):
        inputs.append([0.1*i, 0.1*i])
        labels.append(0)

        if 0.1*i == 0.5:
            continue

        inputs.append([0.1*i, 1-0.1*i])
        labels.append(1)

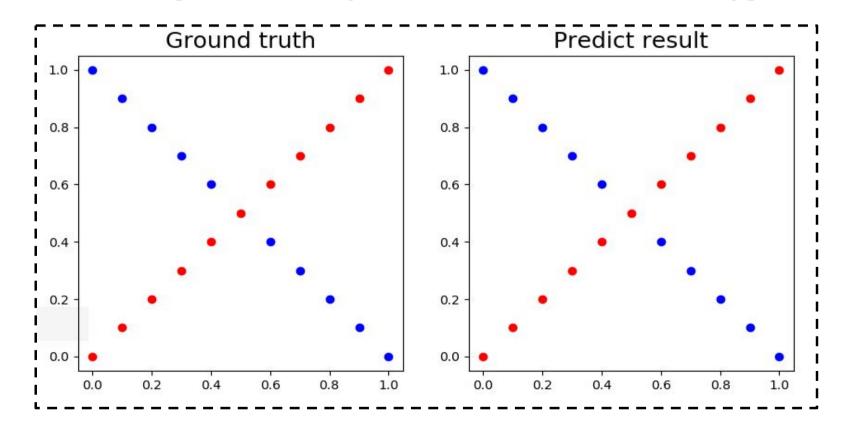
    return np.array(inputs), np.array(labels).reshape(21, 1)
```

Don't overwrite these functions!!!

```
Function usage
x, y = generate_linear(n=100)
x, y = generate_XOR_easy()
```

Lab Description - Prediction

• Visualize the predictions and ground truth at the end of the training process



Scoring Criteria

- Report (40%)
- Demo(60%)
 - Experimental results (40%)
 - Questions (20%)
- Extra (10%)
 - Implement different optimizers. (2%)
 - Implement different activation functions. (3%)
 - Implement convolutional layers. (5%)

Scoring Criteria

- For experimental results, you have to achieve at least 90% of accuracy to get the demo score.
- If the zip file name or the report spec have format error, you will be punished (-5)

Report format

- 1. Introduction (20%)
- 2. Experiment setups (30%):
 - A. Sigmoid functions
 - B. Neural network
 - C. Backpropagation
 - Results of your testing (20%)
 - A. Screenshot and comparison figure
 - B. Show the accuracy of your predictionC. Learning curve (loss, epoch curve)
 - D. anything you want to present
- A. Try different learning rates

Discussion (30%)

- B. Try different numbers of hidden units
- C. Try without activation functions
- D. Anything you want to share
- Extra (10%)
- A. Implement different optimizers. (2%)
- B. Implement different activation functions. (3%)
- C. Implement convolutional layers. (5%)

Important Date

- Assignment Deadline: 3/21 (Thu) 11:59 p.m.
- Demo date: 3/21 (Thu)
- Zip all files in one file
 - Report (.pdf)
 - Source code
- name it like 「DL_LAB1_yourstudentID_name.zip」
 - ex:「DL_LAB1_311554005_高宗霖.zip」

Reference

- 1. http://www.denizyuret.com/2015/03/alec-radfords-animations-for.ht
- 2. http://speech.ee.ntu.edu.tw/~tlkagk/courses-ML17-2.html

demo 時間

3/21 晚上實驗課 吳教授要上課

Lab 1 demo 時間預定排在 3/21 下午(每人約 5 分鐘)

若時間上有困難,請跟對應的助教另約 demo 時間

表單連結

U	V	W	X
	Google meet link		
	TA	高宗霖	OK/Please come in
15:50	高宗霖(我是學生		
15:55			
16:00			
16:05			
16:10			
16:15			
16:20			
16:25			

	LAB1 Back-Propaga tion	LAB2 2048 TD	LAB3 CNN	LAB4 CNN	LAB5 RNN+VAE	LAB6 Deep RL	LAB7 GAN
Announce	3/14	3/21 (上課前30分鐘)	3/28 (上課前30分鐘)	4/11	4/25	5/2 (上課前30分鐘)	5/9
DEMO	*3/21	4/11	4/11	4/25	5/16		