

Practical work 1 - Documentation

Specification:

We shall define a class called Graph which represents a directed graph.

The class **Graph** provides the following methods:

`def __init__(self, nr_vertices=0, nr_edges=0)` -> initializes a graph, implicitly with 0 vertices and 0 edges.

`def add_vertex(self, vertex)` -> adds a vertex to the graph.

*The function adds a vertex to the graph
it adds it to the set of vertices (.__vertices)
it adds an empty set to the dictionary for outbound
neighbours with the key being the vertex
it adds an empty set to the dictionary for inbound
neighbours with the key being the vertex
it raises an error if the vertex already exists in the graph*

`def is_vertex(self, vertex)`

*The function checks whether a vertex is in the graph
it searches for the vertex in the set of vertices.*

`def add_edge(self, vertex1, vertex2, cost)`

*The function adds an edge and its cost to the graph.
To the set of outbound neighbours of vertex1, vertex2 is added
To the set of inbound neighbours of vertex2, vertex1 is added
To the dictionary that maps the cost of each edge, a key-value pair is added.
the key is a tuple of the vertices (vertex1, vertex2)
the value is the cost
The function raises an error if the edge already exists in the graph
or if the vertices do not exist in the graph.*

`def is_edge(self, vertex1, vertex2)`

*The function checks whether the edge with the vertices vertex1 and vertex2 exists
the function checks in the outbound neighbours of vertex1 for vertex2 and the
inbound neighbours of vertex2 for vertex1*

```
def get_number_of_vertices(self)
```

The function returns the number of vertices in the graph.

```
def get_out_degree(self, vertex)
```

*The function returns the out degree of a vertex
the function raises an error if the vertex doesn't exist in the graph*

```
def get_in_degree(self, vertex)
```

*The function returns the in degree of a vertex
the function raises an error if the vertex doesn't exist in the graph*

```
def get_edge_cost(self, vertex1, vertex2)
```

*The function returns the cost of a given edge
the cost is taken from the `__cost` dictionary
an error is raised if the edge doesn't exist.*

```
def set_edge_cost(self, vertex1, vertex2, new_cost)
```

*The function sets the cost of an edge with the value specified.
an error is raised if the edge doesn't exist.*

```
def get_number_of_edges(self)
```

*The function returns the number of edges in the graph
it uses the cost dictionary since it holds all of the edges*

```
def parse_vertices(self)
```

The function returns an iterator to the set of vertices.

```
def parse_inbound_neighbours(self, vertex)
```

The function returns an iterator to the set of inbound neighbours of the vertex.

An error is raised if the vertex doesn't exist in the graph.

```
def parse_outbound_neighbours(self, vertex)
```

The function returns an iterator to the set of outbound neighbours of the vertex.

An error is raised if the vertex doesn't exist in the graph.

```
def parse_edges(self)
```

The function returns an iterator to the set of edges with the cost.

```
def remove_edge(self, vertex1, vertex2)
```

*The function removes an edge from the graph
it deletes the entry in the cost dictionary
it removes vertex2 from vertex1's outbound neighbours
it removes vertex1 from vertex2's inbound neighbours
An error is raised if the edge didn't exist in the graph.*

```
def remove_vertex(self, vertex)
```

*The function removes a vertex from the graph.
It removes all the edges for which the vertex is either an inbound node or an outbound one.
then deletes the key-value item from the dictionaries (.__inbound, __outbound) with the key= vertex
lastly the vertex is removed from the list of vertices.
An error is raised if the vertex didn't exist in the graph.*

```
def copy(self)
```

The function returns a deepcopy of the graph.

Implementation:

The implementation uses a set for the vertices, dictionaries for the inbound and outbound neighbours of each vertex, a dictionary for the list of edges/cost.

A directed graph, represented as two maps,

using inbound neighbours and outbound neighbours.

In order to implement the cost function, a map for the costs

has been added to the graph.

For ease of use, a set of all the vertices has been added,

making the implementation of certain functionalities simpler.

```
self.__vertices = set()
self.__outbound = dict()
self.__inbound = dict()
self.__cost = dict()
```