

POLITECNICO DI MILANO SCUOLA DI INGEGNERIA INDUSTRIALE E DELL'INFORMAZIONE

TESI DI LAUREA MAGISTRALE IN COMPUTER SCIENCE AND ENGINEERING

ADAPTABILITY ANALYZER TOOL

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Abstract (Italian version)

Sistemi Software ad Auto-Adattamento (SASS) sono sistemi flessibili in grado di adattarsi alle loro carico ed esigenze contestuali e possono farlo con le massime prestazioni e disponibilità.

Alcuni studi sull'adattabilità di un software sono stati fatti negli ultimi anni dall'industria e dal mondo accademico, ma tutti si concentrano sull'analisi statica del sistema.

Adaptability Analyzer è uno strumento che estende l'analisi attuale fornendo nuove metriche che aiutano l'analisi statica e propone una nuova analisi del sistema che esamina il comportamento dinamico utilizzando la notazione del diagramma di sequenza.

Lo strumento aiuta l'architetto di software a creare o sviluppare un software fornendo informazioni utili sui componenti scelti, i servizi forniti da questi componenti e l'architettura nel suo complesso.

Lo strumento Adaptability Analyzer è nato per essere un software facilmente utilizzabile, in grado di fornire risultati in modo semplice ma significativo all'utente, utilizzando sia la notazione grafica che numerica.

Abstract

elf-adapting Software Systems (SASS) are flexible systems that can adapt themselves to their contextual needs and can do so with the highest performance and availability.

Studies about the adaptability of a software have been done in the past years by the industry and the academia, but they all focus on the static analysis of the system.

Adaptability Analyzer is a tool that extends the actual analysis by providing new metrics that help the static analysis and proposes a new analysis of the system examining the dynamic behavior using the sequence diagram notation.

It helps the software architect to create or develop a software providing useful informations about the chosen components, the services these components provide and the architecture as a whole.

Adaptability Analyzer tool is born to be an easily usable software that can provide results in a simple but meaningful way to the user by using both graphical and numerical notation.

CHAPTER 1

Introduction

1.1 General description of the project

Adaptability Analyzer is a tool created in order to ease the static and dynamic analysis of architectures that have to be created or that already exist; it provides some functionalities in order to evaluate the cost, the availability and the adaptability of an architecture that don't require any programming knowledge in order to be used and understood.

Some studies about the adaptability of a software have been done in the past years by the industry and the academia and and some papers have been presented, e.g. Huebscher and McCann (2013) [1], Salehie and Tahvildari (2009) [2], Cheng et al. (2009) [3], Andersson et al. (2009) [4], Oreizy et al. (1999) [5], Calinescu et al. (2012) [6] and de Lemos et al. (2013) [7]. All these papers evidence how more and more users need that the software, even in everyday context, can adapt in an efficient and fast way to their needs and they can do so with the highest performance and availability. These two needs interfere with each other and frequently can't be achieved or guaranteed, in fact increasing adaptability can affect any other quality attributes such as cost or availability.

This tools is born to balance positive and negative effects that building a new software architecture with hight adaptability can have and help the software

Chapter 1. Introduction

architect to achieve a better result in a faster way just by providing some data to the tool.

All the result presented by the tool should be easy enough to provide some useful and easy to understand informations to anybody by using cartesian graphs and graphical representations, and some more complicated but powerful data to the software architect by providing numerical data, sometimes very detailed per architecture, component or service.

The development of the tool was done over the course one year, from end October 2017 to June 2018, supervised by professor Raffaela Mirandola and with the remote help of PhD. Diego Perez-Palancin from Sweden.

1.2 Structure of the document

This thesis is structured as follows:

Chapter 2 presents what is an *adaptable software*, which research has been done up to now and the existing software that is available to analyze architectures.

Chapter 3 presents the new metrics that have been developed to support the analysis, how they work and what is their meaning, also presenting the same example from Section 2.2 to understand them better.

Chapter 4 presents the tool, how it works and how it request and presents the data.

Chapter 5 analyzes two architectures: the well known Tele Assistance System [8] and one architecture generated automatically by the tool.

Chapter 6 presents some general results achieved by this tool and some future work that can be done in order to further improve it.

At the end there are Appendix A that presents how tehe software is structured and how some metrics are implemented and Appendix B that contains the JSON of the architecture analyzed in the thesis.

CHAPTER 2

State of the Art

2.1 Self-Adaptive Software Systems

In modern-day applications, software complexity has extremely increased thanks to the spread of highly available and faster wireless connection such as in the Internet of Things (IoT) ambit. Since software is often deployed in dynamic contexts, where requirements, environment assumptions and usage profiles vary continuously, software complexity increased over time to the point where it is often composed by a number of sub-components and/or sub-services that work together in order to offer a service to the users. This is the case of service-oriented applications – also called Service Based Systems (SBS) – that are composed by multiple *services* and *components*. In these systems, services offered by third-party providers are dynamically composed into workflows to deliver complex functionalities, so SBSs rely on self adaptation to cope with the uncertainties associated with third-party services as the loose coupling of services makes a reconfiguration feasible. Without adaptation, the application is prone to degraded performance because of faulty components, messages lost between services or delays due to an increasing number of users.

During the past decade a lot of research has been made in this scope but the engineering of adaptive systems remains an incredible challenge[7]. In order to

solve the problem, **Self-Adapting Software Systems** (**SASS**) are born. These are flexible systems that can adapt themselves to their contextual needs and can do so with the highest performance and availability. General discussion concerning the issue and the state of the art in the design and implementation have been presented[7][1][2][3][4][5][6].

These kind of systems have some fundamental properties called auto-managing that are:

- Auto-configuration
- Auto-recovery in case of failure
- Auto-optimization
- Auto-protection

All these properties can be grouped in two more abstract concepts which are self-awareness and context-awareness.

Self-Awareness is the ability of the system to be able to monitor itself in terms of available resources and behavior.

Context-Awareness is the ability of the system to understand the environment where it is working, using the information provided by its components, and adapt itself to all the changes that can occur during its normal operational status. To better understand how a SASS works we need to answer some simple questions:

- Who is adapting?
- What adaptation is required?
- When is it necessary to adapt?
- Where is it needed to change something?
- Why is it needed an adaptation?
- How do we achieve this goal?

During the past years have been developed some dimensions that help to answer all this simple questions: *Time*, *Reason*, *Level*, *Technique* and *Adaptation Control* shown in Figure 2.1.

Who is adapting? As the name suggests, it's the system itself that changes something in order to preserve some given constraint.

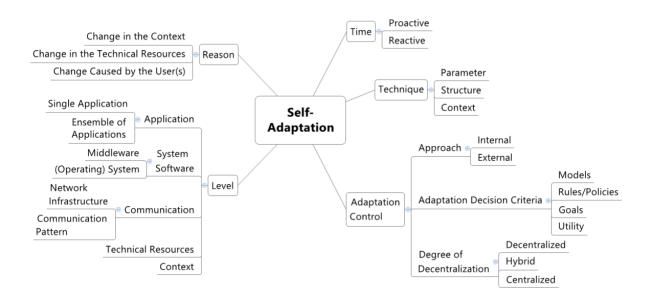


Figure 2.1: The Dimensions to analyze adaptation.[9]

What adaptation is required? The *Technique* dimension is the one that answers this question in fact the software engineer can change either the parameters or the system can be considered as a set of components. The former case allows to fine tuning the system at the expense of an higher complexity, the latter is called composite vision and permits the systems to cooperate exchanging algorithms and much more important, reusing components which improve performance because failed or defected components can be replaced.

When it is necessary to adapt? The *Time* dimension is crucial in this situation. There are three typical approaches: the reactive one is the more traditional one which states that an adaptation is needed only after a causative event. The other two approaches are more interesting and they are predictive and proactive. The former studies the system before any event and calculate the need of an adaptation, the latter applies and adaptation despite an event and improves the performance. From the user perspective the proactive approach is the best because it doesn't interrupt the operation of the system in any load but it is the more complicated to implement. Monitoring continuously the system is a costly task to do, on the other side an adaptive monitoring is simple that analyze only specific aspect and/or resources and intervenes only if needed.

Where it is needed to change something? In general a SASS is composed by two main part: the the Adaptability Logic (AL) and the Managed Resource (MR). The former in general doesn't change, the latter is composed at the base of the hardware and of the software such as the operating system or, in case of dis-

tributed systems, the middleware that control the hardware; at a higher level of the application. These are the parts that require adaptation. To answer this question is needed to decide at which level the operation has to be applied without neglecting the relationship between the MR and the AL which is composed by the network that connects them and/or the view of the communication patterns. Thus *Level* is the considered dimension.

Why it is needed an adaptation? In this case, *Reason* is the right dimension. There can be one or more reason because a system needs adaptation such as a change in the available resources, a change in the environment or a change in the user base of the system.

How do we achieve this goal? The answer to this question is more complicated than the others because it needs a new topic called *Adaptation Control*.

2.1.1 Adaptation Control

In the literature can be found 2 approaches: the *internal approach* that intertwine the adaptation logic with the system resources, which has problems with the maintainability and scalability of the system, and the *external approach* that splits the system into adaptation logic and managed resources, which increases maintainability and scalability through modularization.

The control unit needs a metric in order to decide how to adapt and in literature different metrics are present: models, rules and policies, goal or utility functions [10].

Another aspect of the adaptation logic is the degree of decentralization. If we have a system with limited resources then a centralized adaptation logic has to be preferred but with greater systems a decentralized AL can improve performance and every sub-system can communicate with another with different patterns of communication. Of course hybrid technique can be made mixing the previous approaches.

Adaptation Logic Issues

As said before a SASS is composed of managed resources and the adaptation logic; it can be represented by the tuple SASS = (AL, MR). $AL = a_1, \ldots, a_n$, with a_i representing a logic element, monitors the environment (M), analyzes the data for change (A), plans adaptation (P) and control the execution of the adaptation (E): these are known as MAPE cycle or MAPE functionality[11]. $MR = mr_1, \ldots, mr_n$, with mr_i representing a resource, is the set of resources such as hardware with software, smart-phones, robotics or unmanned vehicles. Figure 2.2 shows a SASS where the dashed line represent the system border. The di-

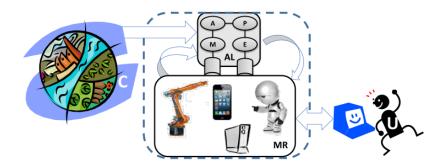


Figure 2.2: A SASS ($AL = Adaptation\ Logic,\ MR = Managed\ Resources,\ U = User(s),$ $C = Context,\ M,A,P,E = MAPE\ functionality).[9]$

mension can therefore be mapped to the MAPE functionalities as shown in table 2.1.

	Time	Reason	Level	Technique
Monitoring	Continuos	What to moni-	Identification	_
		tor	of the levels	
Analyzing	Algorithms de-	Where to ana-	_	_
	pend on reac-	lyze		
	tive or proac-			
	tive dimension			
Planning	_	What should be	Adaptation	Plans for per-
		influenced by	plans address	forming the
		planning	these levels	techniques
Executing	_		Execution of	Execution of
			the change on	the change on
			the levels	the levels

Table 2.1: Relation of the MAPE Activities and the Dimensions

2.2 The SOLAR Framework

Working on the adaptability of a system can impact other quality attributes such as performance, reliability or maintainability and in the worst case improving adaptability can decrease part, if not all, of these attributes as stated in [12]: quality attributes can never be achieved in isolation, the achievement of any one will have an effect, sometimes positive and sometimes negative, on the achievement of others.

Find a balance between these quality attributes is often a challenging task because sometimes they're conflicting each other, e.g. lower cost and higher availability, so find an adaptability value that can meet all the requisites is, as a consequence, a challenging task too.

The SOLAR (SOftware qualities and Adaptability Relationships) framework [13] helps the software architect to select the best set of components in order to fulfill the requirements trying to achieve a minimum level for some quality attribute such as availability and/or cost. This tool helps the software architect to build a suitable architecture for his needs but is not a "solution for every situation".

2.2.1 The SOLAR Metrics

All the metrics in SOLAR are greatly inspired by [14] and are all defined at an architecture level and static perspective.

To define them, the software architecture relies on a component-and-connector view (C&C view). In this C&C view *components* are principal computational elements present at runtime. The representation used in Figure 2.3 uses the UML diagram and shows some components and their respective connections.

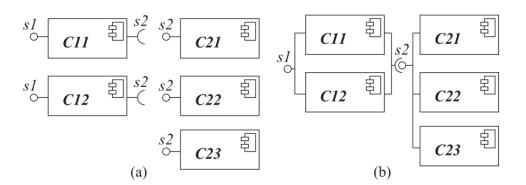


Figure 2.3: (a) A set of components and their interfaces and (b) the C&C view of the components in (a)[13].

Components have interfaces attached to ports. *Connectors* are pathways of interaction between components and also have interfaces or roles. In Figure 2.4 it is shown an example of an architecture, the used components are highlighted in gray; this example will be used to explain the metrics later in this chapter.

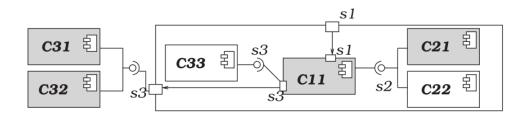


Figure 2.4: *C&C view: discovered components and used components (in gray).[13]*

In the architecture of Figure 2.4:

- the service S1 is provided by component C11 that is unique and must be in use. S1 is the provided service of this architecture.
- component C11 requires S2 and S3 services.
- service S2 is provided by C21 and C22 where only C21 is in use.
- service S3 is provided by C31, C32 and C33 but only C31 and C32 are in use.

Absolute adaptability of a service (AAS)

This metric measures the number of used components for providing a given service.

$$AAS \in \mathbb{N}^n |AAS_i = |UC_i|$$

Quantifies how much adaptable a service is by counting the different alternatives to execute the service (1 no adaptable, >1 adaptable), where the service adaptability grows according to the number of components able to provide it. Referring to the example in Figure 2.4, we observe that AAS = [1, 1, 2].

Relative adaptability of a service (RAS)

This metric measures the number of used components that provide a given service with respect to the number of components actually offering such service.

$$RAS \in \mathbb{Q}^n | RAS_i = \frac{|UC_i|}{|C_i|}$$

It describes how each service stresses its adaptability choices and it informs how much more adaptable the service could be. RAS vector values near to one mean that the service is using almost all the adaptability potentially reachable. Referring to the example in Figure 2.4, we observe that RAS = [1, 0.5, 0.6].

Mean of absolute adaptability of services (MAAS)

This metric measures the mean number of used components per service.

$$MAAS \in \mathbb{Q}|MAAS = \frac{\sum_{i=1}^{n} AAS_i}{n}$$

It offers insights into the mean size and effort needed to manage each service. Referring to the example in Figure 2.4, MAAS = 4/3 = 1.3.

Architectures with more adaptable services have higher values of MAAS. Besides, a MAAS > 1 means that the architecture includes adaptable services (at least one of the components $AAS_i > 1$). For $MAAS \leq 1$, there may be adaptable services or not (AAS should be checked in this case).

Mean of relative adaptability of services (MRAS)

This metric represents the mean of RAS.

$$MRAS \in \mathbb{Q}|MRAS = \frac{\sum_{i=1}^{n} RAS_i}{n}$$

It informs about the mean utilization of the potential components for each service. Values of this metric range between zero and one.

Referring to the example, MRAS = (1 + 0.5 + 0.6)/3 = 0.72.

The higher the MRAS of an architecture, the more adaptable its services are, on average. The maximum value of this metric is obtained when $RAS_i = 1 \ \forall i \in [1, \ldots, n]$, which is in turn obtained when all services are as much adaptable as possible because they use all the available components. Therefore, a value close to one for MRAS means that, on average, services are as much adaptable as possible. A value close to zero means that:

- a) services can be much more adaptable (adding components not yet used)
- **b**) different architecture alternatives with the same quantity of adaptability can be created

Level of system adaptability (LSA)

This metric measures the number of components used to make up the system with respect to the number of components that the most adaptable architecture would use.

$$LSA \in \mathbb{Q}0..1|LSA = \frac{\sum_{i=1}^{n} AAS_i}{\sum_{i=1}^{n} |C_i|}$$

The value of this metric ranges between zero and one. For LSA, a value of one means that the system is using all existing components for each service, i.e., $AAS_i = |C_i| \forall i \in 1, \ldots, n$, and then its adaptability is already to the maximum. A value close to one means that the market offers few choices to increase the system architectural adaptability. When a new component is bounded to the architecture, LSA increases in a constant value $(1/\sum i = 1^n |C_i|)$ irrespective of the number of components already considered for the same service.

Referring to the example in Figure 2.4, LSA = 4/(1+2+3) = 0.6.

Table 2.2 summarizes the five metrics and their values for the example in Figure 2.4.

Name	Range	Value	Example in Fig. 2.4
AAS	\mathbb{N}^n	$ UC_i $	[1, 1, 2]
RAS	$\mathbb{Q}^n \in 0, \dots, 1$	$\frac{ UC_i }{ C_i }$	[1, 0.5, 0.6]
MAAS	\mathbb{Q}_+	$\frac{\sum_{i=1}^{n} AAS_i}{n}$	1.3
MRAS	$\mathbb{Q}^n \in 0, \dots, 1$	$\frac{\sum_{i=1}^{n} RAS_i}{n}$	0.72
LSA	$\mathbb{Q}^n \in 0, \dots, 1$	$\frac{\sum_{i=1}^{n} AAS_i}{\sum_{i=1}^{n} C_i }$	0.6

Table 2.2: *Summary of the metrics.[13]*

2.2.2 Relating adaptability to a system quality attribute

The analysis of the relation between system adaptability and quality attributes can give three different results as shown in Table 2.3. In the rows we read that, when the adaptability increases then some quality attributes:

- tend to increase their measured values
- tend to decrease their measured values
- are not affected. We are not interested in this group since we are focussed on the influence of adaptability on the requirement.

The columns in the table consider how the quality requirement is formulated:

- as higher than, e.g., "system availability shall be higher than..."
- as lower than, e.g., "system mean response time shall be lower than..."

Each region of interest in Table 2.3 has been labeled as Helps or Hurts to indicate the effect of the adaptability upon the quality requirement.

The best cases are when the quality attribute completely depends on the adaptability such as:

- 1. The higher the adaptability, the higher the quality attribute
- 2. The lower the adaptability, the lower the quality attribute

In Figure 2.5 are shown all the intermediate cases that can result mixing the two extreme cases above. The X axis represents the adaptability value, The Y axis represent the quality attribute. For each value of adaptability there are two extreme values:

• Q_{A_iU} is the maximum value of the quality attribute with respect to A_i

• Q_{A_iL} is the minimum value of the quality attribute with respect to A_i

Between these extreme values there are all the architecture that have the same adaptability and intermediate quality attribute value. Among all the Q_{A_iU} and Q_{A_iL} in the graph, two of them have a particular meaning: $Adapt^+$ and $Adapt^-$.

To describe the meaning of $Adapt^-$ and $Adapt^+$ we focus on parts (a) and (d) in Figure 2.5. $Adapt^-$ is the lowest A_i for which we can find an architecture satisfying the requirement. $Adapt^+$ is the lowest A_i whose bounds, Q_{A_iU} and Q_{A_iL} , satisfy the requirement. These values indicate that to fulfill the requirement, the architecture must have at least adaptability $Adapt^-$, and, any architecture with at least $Adapt^+$ will also satisfy it. For adaptabilities between them, there will be architectures satisfying the requirement (those highlighted in the figure) and others that will not.

In parts (b) and (c) in Figure 2.5 (regions where the adaptability Hurts), $Adapt^-$ is the threshold adaptability value for which any architecture with adaptability $A_i \leq Adapt^-$ fulfills the requirement; and $Adapt^+$ is the maximum A_i for which we know that exists some architecture that satisfies the requirement.

When adaptability increases —	Requirement formulated as		
when adaptability increases —	Higher than	Lower than	
The quality attribute value increases	Helps	Hurts	
The quality attribute value decreases	Hurts	Helps	
The quality attribute is not affected	No effect		

Table 2.3: Effect of adaptability on a measured quality requirement.[13]

2.2.3 Analysis of the approach and its limits

Both of these tools want to help the software architect in choosing the right set of components in order to satisfy the adaptability requirements and if possible other quality attributes. With the SOLAR framework all the possible architectures that satisfy the requisites are generated and the choice is left to the architect. This approach is for sure slower but is a valid tool to have an idea of the possible outcome and build an architecture from scratch. On the other side it presents some limitations presented in no particular order:

- It analyzes all the architecture only with a static analysis using the component diagram.
- All components are given equal importance thus the time a component is used and the number of usages per call is completely ignored.
- It does not considers the probability of failure of a component at runtime.

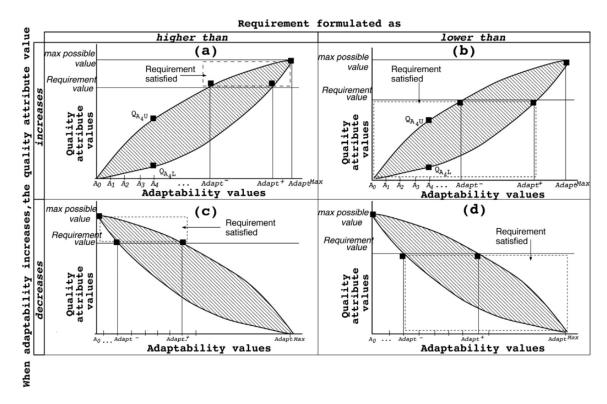


Figure 2.5: Relations among adaptability and other quality attributes.[13]

• Requires a lot of time to produce complete results.

In the next chapter it is shown how to analyze the quality of a software and in particular how to evaluate the adaptability of a software with respect to some attributes such as cost and availability.

CHAPTER 3

The new quality metrics

In this chapter it is explained how to improve the SOLAR framework in order to integrate the existing metrics with another set of metrics in order to provide the software engineer with more information regarding the architecture he's building.

All modern applications are born to meet some functional requirements that often are subject to changes due to the fact that the environment where they operate is dynamic and can change in a unpredictable way. In the academic and industrial reality rose up the need to standardize some quality metrics in order to evaluate a software, this is the case of the **ISO/IEC 25010** standard called *Systems and software Quality Requirements and Evaluation (SQuaRE)*[15]. However in the self-adaptive context these metrics are not of much help since they do not account the ability of these systems to auto adapt whenever they need it.

To overcome this problem some more new metrics have been defined that analyze the architecture in two different ways:

- using a component diagram as defined in the UML standard[16] to analyze the static behavior
- using a sequence diagram as defined in the UML standard[16] to analyze the runtime behavior

The final objective is to define some adaptability metrics for the architecture as a whole and for every service that the architecture uses. In a more specific way what is shown is how important is every service in a architecture and as a consequence, how important is every component.

3.1 Systems and software Quality Requirements and Evaluation

ISO/IEC 25010, Systems and software engineering — Systems and software Quality Requirements and Evaluation (SQuaRE)[15] is an international standard for the evaluation of software quality that replaced the previous **ISO/IEC 9126** Software engineering — Product quality standard[17].

It presents eight product quality characteristics (in contrast to ISO 9126's six):

- Functional suitability degree to which a product or system provides functions that meet stated and implied needs when used under specified conditions
- Reliability degree to which a system, product or component performs specified functions under specified conditions for a specified period of time
- Usability degree to which a product or system can be used by specified users to achieve specified goals with effectiveness, efficiency and satisfaction in a specified context of use
- Performance efficiency performance relative to the amount of resources used under stated conditions
- Maintainability degree of effectiveness and efficiency with which a product or system can be modified by the intended maintainers
- Portability degree of effectiveness and efficiency with which a system, product or component can be transferred from one hardware, software or other operational or usage environment to another
- Compatibility degree to which a product, system or component can exchange information with other products, systems or components, and/or perform its required functions, while sharing the same hardware or software environment
- Security degree to which a product or system protects information and data so that persons or other products or systems have the degree of data access appropriate to their types and levels of authorization

3.2 The New Metrics

All the metrics shown in this section are focused on two primary quality attributes for the software engineer which are *availability* and *cost*. As a consequence two parameters must be given to perform some of the calculations:

- availability_{target} which represents the minimum availability the system must have
- ullet $cost_{target}$ which represents the maximum cost the system must have

Both these parameters are given by the software engineer and come from the previous analysis of the requisites.

All the terms which are used in the metrics definitions are presented in table 3.1.

Name	Type	Meaning		
$availability_{target}$	Parameter	represent the minimum availability the system must have		
$cost_{target}$	Parameter	represents the maximum cost the system must have		
C_i	Parameter	Component i		
T_{C_i}	Parameter	Execution time for component <i>i</i>		
PS_i	Parameter	Provided service <i>i</i>		
$N_{exec_{PS_i}}$	Result	Number of executions of provided service i		
T_{PS_i}	Result	Execution Time of provided service i		
TotTime	Result	Total time of execution		
S_i	Parameter	Service i		
T_{S_i}	Parameter	Execution time of service <i>i</i>		
$N_{exec_{S_i}}$	Result	Number of executions of service <i>i</i>		
$P_{exec_{S_i}}$	Parameter	Probability of execution service i		
$ExecPerCall_{S_i}$	Parameter	Number of execution per call of service i		
$N_{exec_{PS_i}}$	Result	Number of executions of provided service <i>i</i>		
$TimeAction_{S_i}$	Result	The time a service <i>i</i> is working		
AV_{C_i}	Parameter	Intrinsic availability of component i		

Table 3.1: *Summary of the metrics terms.*

3.2.1 Components

Fitness ratio w.r.t. availability

This metric defines the ratio between a component availability and the target system availability. This result is from the hypothesis that a component with a high availability can provide, at first glance, more guarantees of functioning.

$$FRA_{C_i} \in \mathbb{R}_0^+ \mid FRA_{C_i} = \frac{1 - availability_{target}}{1 - availability_{C_i}}$$

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This means that if the result is ≥ 1 the component satisfies the target requisite and as a consequence it can work for a longer time improving the availability of the service it offers.

A value ≥ 0 and < 1 indicates that this component is prone to failure more frequently than how is requested in the architecture.

Fitness ratio w.r.t. cost

This metric defines the ratio between a component cost and the system target cost.

$$FRC_{C_i} \in \mathbb{R}_0^+ \mid FRC_{C_i} = \frac{cost_{target}}{cost_{C_i}}$$

With the same component cost, if the system target cost grows higher the Fitness Ratio w.r.t. Cost becomes bigger. This implies that the bigger the component and the system target cost gap is, the more can be saved from buying this component w.r.t. the maximum budget invested in buying all the components.

Weight of residence time

This metric calculates which fraction of time a component is running w.r.t total running time of the architecture.

$$T_{C_i} \in \mathbb{R}^+ \mid T_{C_i} = \sum_{i=0}^n N_{exec_{PS_i}} * T_{PS_i}$$

$$TotTime \in \mathbb{R}^+ \mid TotTime = \sum_{i=0}^n N_{exec_{S_i}} * T_{S_i}$$

$$WRT \in \mathbb{R}^+ \mid WRT = \frac{T_{C_i}}{TotTime}$$

Higher results means that the component runs more than others, thus is an important piece of the architecture. A failure in this component can compromise the functioning of the architecture in a more impactful way than a failure of other components.

3.2.2 Services

Number of executions

This metric defines the number of times a service is executed.

$$N_{exec_{S_i}} \in \mathbb{N} \mid \forall PS_i \ N_{exec_{S_i}} = \sum_{i=0}^{n} P_{exec_{S_i}} * ExecPerCall_{S_i} * N_{exec_{PS_i}}$$

Probability to be running

This metric defines the probability that a given service is running in a given moment.

$$PTBR_{S_i} \in [0..1] \mid PTBR_{S_i} = \frac{N_{exec_{S_i}}}{\sum_{i=0}^{n} N_{exec_{S_i}}}$$

In Action

This metric calculates the probability to find a given service active considering the dynamic analysis of the architecture.

$$TimeAction_{S_i} \in \mathbb{R}^+ \mid TimeAction_{S_i} = \sum_{j=0}^n T_{execS_iPath_j} * P_{execS_i}$$

$$InAction_{S_i} \in [0..1] \mid InAction_{S_i} = \frac{TimeAction_{S_i}}{\sum_{i=0}^n TimeAction_{S_i}}$$

It considers all the possible paths available in the selected workflow; in this way a workflow with an Alt and/or Opt block in the sequence diagram can be represented in a correct way.

3.2.3 Architecture

Global Fitness Ratio w.r.t. Availability of system

Defines the availability of the components that are in the architecture as a probability that are all active in a given instant.

$$GAS \in \mathbb{R}_0^+ \mid \forall C_i \ GAS = \prod_{i=0}^n FRA_{C_i}$$

A better availability of a component in the architecture implies a better Fitness Ratio w.r.t. Availability that is reflected in a better global Fitness Ratio w.r.t. Availability. Higher numbers mean better availability.

Global Fitness Ratio w.r.t. cost of system

Defines the total cost of the components in an architecture w.r.t. the cost of each individual component.

$$GCS \in \mathbb{R}_0^+ \mid \forall C_i GCS = \sum_{i=0}^n FRC_{C_i}$$

Total Static Availability

This methods calculate the Availability of an architecture without considering actual workflows of the architecture, so it uses the component diagram. It considers all components as used and considers a call to the main service to use always all the components.

Given that S_x is the main offered service we can calculate the availability of such service as total availability of the system.

• If a component is terminal, so doesn't require any service:

$$Av(C_i) \in \mathbb{R}_0^+ \mid Av(C_i) = AV_{C_i}$$

• If a component is not terminal and requires some service S_k :

$$Av(C_i) \in \mathbb{R}_0^+ \mid \forall S_k \ Av(C_i) = AV_{C_i} * \prod_{k=0}^n ((1 - p_{S_k}^{C_i}) + p_{S_k}^{C_i} * (AV_{S_k})^{N_{S_k}^{C_i}})$$

With these we can calculate the availability of S_x thus the availability of the architecture with C_i being any component that offers S_x .

$$Av(S_x) \in \mathbb{R}_0^+ \mid \exists C_i \ Av(S_x) = 1 - \prod_{i=0}^n (1 - Av_{C_i})$$

3.2.4 Example

To show how these metrics work we can set-up the architecture from Chapter 2 used in the Solar Metrics in Section 2.2.1; since no data is given for such architecture, it was made up as plausible as possible and can be seen in Table 3.2. Since $availability_{target}$ and $cost_{target}$ are required to the software architect they can be set to 0.90 and 8 respectively. Also services data had to be made up and can be visible in Table 3.3

Component	Availability	Cost	Component	Availability	Cost
Name			Name		
C11	0.90	1.2	C31	0.90	1.5
C21	0.87	0.8	C32	0.99	2.0
C22	0.90	1.0	C33	0.85	0.9
(Not Used)	0.90	1.0	(Not Used)	0.83	0.9

Table 3.2: SOLAR example components data.

Component	Service Name	Type of	Execution	Used	Number of
		Service	Time	Proba-	Execution
				bility	per Call
	S1	Provided	1.0		
C11	S2	Required		0.90	3
	S3	Required		0.30	1
C21	S2	Provided	2.0		
C22	S2	Provided	2.0		
(Not Used)	32	Flovided	2.0		
C31	S3	Provided	1.0		
C32	S3	Provided	1.0		
C33	S3	Provided	1.0		
(Not Used)	33	FIOVIDED	1.0		

Table 3.3: *SOLAR example services data.*

Fitness ratio w.r.t. availability

If we consider Component C21:

$$FRA_{C21} = \frac{1 - 0.90}{1 - 0.87} = 0.77$$

This means that the component is below the $availability_{target}$. Using Component C32 instead:

$$FRA_{C32} = \frac{1 - 0.90}{1 - 0.99} = 10$$

This means that the component is above the $availability_{target}$.

Fitness ratio w.r.t. cost

If we consider Component C21:

$$FRC_{C21} = \frac{8}{0.8} = 10$$

This means that the component is well below the $cost_{target}$.

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Weight of residence time

Considering Component C11, we need to calculate T_{C11} and TotTime.

$$T_{C11} = 1 * 1 = 1$$

$$TotTime = 1 * 1 + 2.7 * 2 + 0.3 * 1 = 6.7$$

Now we can Calculate WRT

$$WRT_{C11} = \frac{1}{6.7} = 0.15$$

This means that the Component C11 is actually performing some work only in the 15% of the time.

Number of executions

If we consider S1:

$$N_{exes_{S1}} = 1$$

since S1 is the provided service.

If we consider S2:

$$N_{exes_{52}} = 1 * 0.9 * 3 = 2.7$$

Probability to be running

If we consider S2

$$PTBR_{S_2} = \frac{2.7}{1 + 2.7 + 0.3} = 0.675$$

Global Fitness Ratio w.r.t. Availability of system

We must consider all the components:

$$GAS = \frac{1 - 0.90}{1 - 0.90} + \frac{1 - 0.90}{1 - 0.87} + \frac{1 - 0.90}{1 - 0.90} + \frac{1 - 0.90}{1 - 0.90} + \frac{1 - 0.90}{1 - 0.99} + \frac{1 - 0.90}{1 - 0.85} = 13.72$$

This means that the single availability of the components is on average higher or equal to the $availability_{target}$.

Global Fitness Ratio w.r.t. Cost of system

We must consider all the components:

$$GAS = \frac{8}{1.2} + \frac{8}{0.8} + \frac{8}{1} + \frac{8}{1.5} + \frac{8}{2} + \frac{8}{0.9} = 42.89$$

This means that on average all the components cost much less than $cost_{target}$.

Total Static Availability

We need to calculate the parallel for the two terminal groups and then puth them in series with the C11 group:

$$Av(C2x) = Av(S2) = 1 - (1 - 0.87) * (1 - 0.90) = 0.987$$

$$Av(C3x) = Av(S3) = 1 - (1 - 0.90) * (1 - 0.99) * (1 - 0.85) = 0.999$$

$$Av(C11) = Av(S1) = 0.90 * ((1 - 0.9) + 0.9 * (0.987)^{3}) * ((1 - 0.3) + 0.3 * (0.999)^{1})$$

$$Av(C11) = Av(S1) = 0.868$$

This means that from a static point of view the architecture cannot satisfy the $availability_{target}$.

CHAPTER 4

The Adaptability Analyzer Software

To provide the software engineer a tool that can ease his work a new software has been developed ad hoc, called Adaptability Analyzer Tool¹.

This tool has been developed from scratch with some goals in mind and puts together the previous SOLAR[13] metrics with the new metrics presented in Chapter 3. All the goals are explained in the following section.

A new feature was also implemented: the possibility to generate random architectures.

4.1 Adaptability Analyzer Software Goals

4.1.1 User Point of View

From a usability point of view the first goal of this software was to be a tool that can be used by every software engineer without knowing the underlying programming language or how the code is structured; to achieve this I've chosen to provide the software with a Graphical User Interface (GUI) that doesn't require any programming skill to be used.

Another goal was that creating an architecture and then perform calculations should be made easy for everyone, not only for the software engineer, so ev-

¹Source available at https://github.com/TopoDiFogna/AdaptAnalyzer

ery result is clearly visible in the GUI and, where possible, numeric results are supported by Cartesian graphs and/or visual representations.

4.1.2 Developer Point of View

From a programming point of view, instead, the software has to be portable so it can be run on most computers, without strict limitations on operating systems and/or hardware. This is achieved by using the Java programming language [18].

With this programming language the choices on how to develop the GUI were only two framework (discarding the old AWT[19]): Swing[20] or JavaFX[21]. I've chosen to use the newer JavaFX because it should become the new standard for developing Java graphical applications and it provides a set of useful API to the scope of this software.

Others programming goals were to provide a software that can have a small memory footprint and low CPU usage but that can provide results in a meaningful time frame; this is achieved by using common design patterns with efficient algorithms in term of time and memory complexity.

The last goal was to make the user be able to export and import his architecture, thus interrupting and resuming his work on another machine is made easy.

More details on programming choices can be found in the Appendix A

4.2 Adaptability Analyzer Software Features

When launched, the tool presents a welcome page with the main menu accessible in the top left corner. From this menu it is possible to create a new architecture, either from scratch or generating one from the provided generator, or to import a previously created one as shown in Figure 4.1

When creating a new architecture from scratch the architecture's name is required as shown in Figure 4.2 and then the main tool window, with the components tab open, is shown as in Figure 4.4.

When generating an architecture instead some more parameters are required and are summarized in Table 4.1, the window is shown in Figure 4.3

In this case the architecture is named $Arch\ 1$ and the component C3-1 is selected from the list of available components on the right, visible because it is highlighted. Every component in the list can be deleted by right clicking on it and selecting delete from the context menu. On the left it is possible to see all the component details. All the fields are explained in Table 4.2.

If the top fields, *System Target Cost* and *System Target Availability* are filled as described in Chapter 3 Section 3.2 and at least one component exists, it is



Figure 4.1: The main window of the tool that welcomes the user at launch with menu open.

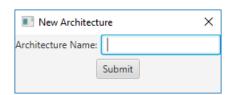


Figure 4.2: *The new architecture window requesting only a name.*

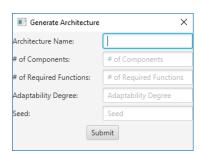


Figure 4.3: *The window that allow to generate an architecture.*

already possible to calculate all the component metrics, shown on the right just below the component details, and architecture metrics shown on the bottom of the tool pressing the respective buttons. The meaning of this metrics are ex-

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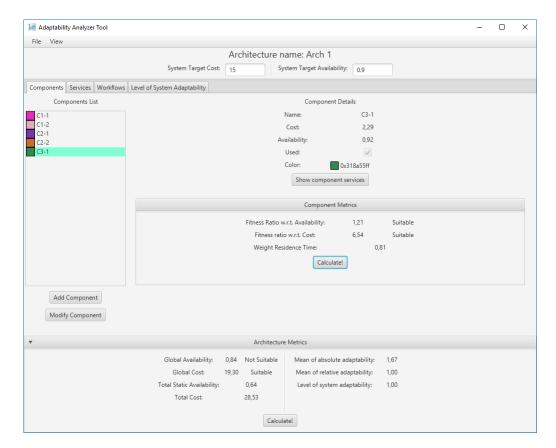


Figure 4.4: The main tool window showing all the component details.

Parameter name	Meaning
Architecture name	Name of the architecture
# of Components	The number of components that the architecture should have
# of Required Functions	The number of functions every component should require
Adaptability Degree	How many copies of the same component should be
Seed	Random number to regenerate the same architecture multiple times

Table 4.1: *The parameters required by the architecture generator.*

Parameter name	Meaning
Component name	Name of the selected component
Cost	Cost of the component
Availability	Availability of the component as specified in its technical features
Used	If the component is active in the architecture
Color	The color used in the graphical representation

Table 4.2: The parameters required by the component creator.

plained in Chapter 3.

It is also possible to add a new component or modify an existing one by pressing the respective button under the components list; in this case the window that is opened is the same but in case of modifying a component the fields are already filled as shown in Figure 4.5



Figure 4.5: *The window that is shown when adding or modifying a component.*

Now is possible to navigate all the other features of the tool.

From the top menu, in the *View* section, it is possible to view a graphical representation of the architecture as shown in Figure 4.6 and from there it is possible to export an image of such representation.

The nodes can be rearranged inside the window by dragging and dropping them.

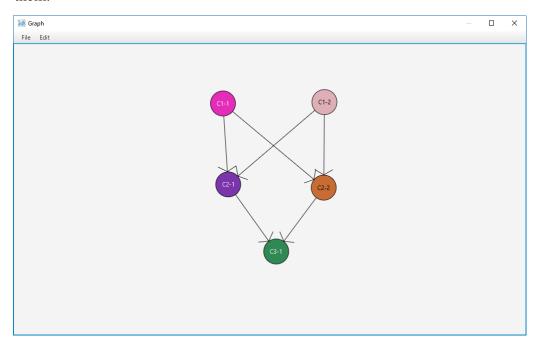


Figure 4.6: *The graphical representation of the architecture in example.*

The service tab shown in Figure 4.7 allows to choose a component from the drop-down menu on the left and a service it provides or requires. It is also possible here to add a service to the selected component by pressing the corresponding button on the bottom of the list as shown in Figure 4.8. Every service can be deleted by right clicking on it and selecting delete from the context menu.

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Once selected a service its details are displayed on the right; if some detail does not apply for the selected service it is grayed out automatically. The meaning of the details are explained in Table 4.3

Parameter name	Meaning
Name	Name of the selected service
Туре	If the service is <i>Required</i> or <i>Provided</i> by the component
Execution Time	Time to execute if this service is called (only provided ser-
	vices)
Used Probability	The probability that this service is needed by a call (only
	required services)
Number of Executions	The number of executions the service must do before giv-
per Call	ing a result (only required services)

Table 4.3: *The parameters required by the service creator.*

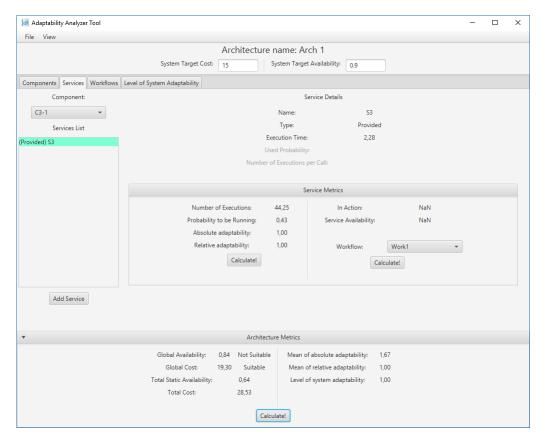


Figure 4.7: The main tool window showing all the service details.

The Workflow tab allows to create different workflows for the architecture; it is shown in Figure 4.9. Every workflow is represented as a Sequence Diagram from the UML Standard [16]. Each workflow has one or more paths that can be created using the corresponding button below the path list. Every workflow or path can be deleted by right clicking on it and selecting delete from the context



Figure 4.8: *The window that is shown when adding a service.*

menu.

If an Alt and/or Opt block are needed that can be specified by additional paths which on creation require an execution probability. The only limitation is that Alt and Opt blocks can't be nested in the actual implementation.

The execution probability is shown on top of the left side of the tab and below that is possible to add a message with the corresponding button. The window that allows to create a message is shown in figure 4.10

To delete a message and all its successor just click on the arrow.

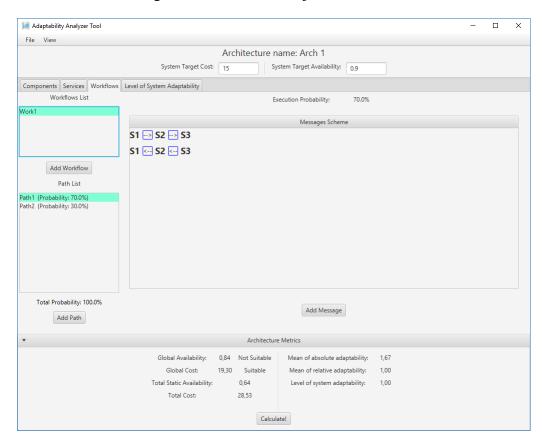


Figure 4.9: The main tool window showing workflows, paths and the sequence diagram.

The last tab is the Level of System Adaptability Tab. In this tab it is possible

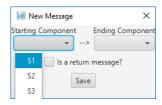


Figure 4.10: *The window that is shown when adding path.*

to calculate all possible architectures that can exists with the given components and calculate how the cost varies with respect to the adaptability as shown in Figure 4.11.

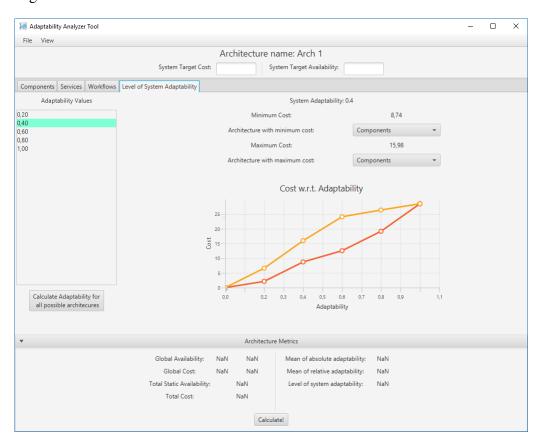


Figure 4.11: *The window that is shown when adaptability calculated.*

Clicking an adaptability value in the list on the left or a dot in the graph selects a possible adaptability value and displays on the right the minimum and maximum cost for that adaptability and the list of components that are in the architecture with the selected adaptability as shown in Figure 4.12.

Selecting a component the component tab is shown with te selected component visible.

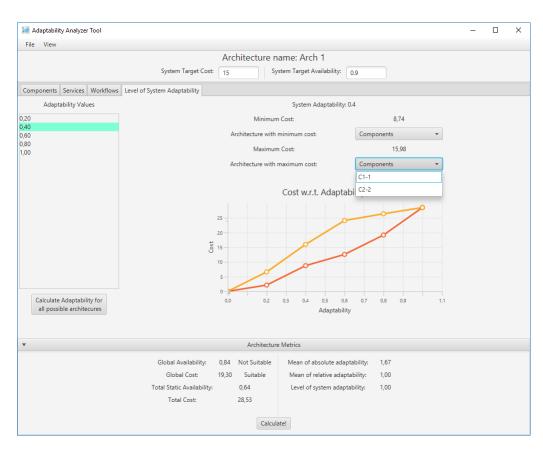


Figure 4.12: An architecture shown for a selected adaptability.

CHAPTER 5

Experimental Evaluation

In this chapter the Adaptability Analyzer Software is used to study two main cases: one is the Tele Assistance System[8] and the other one is generated with the integrated Architecture Generator.

5.1 Tele Assistance: A Self-Adaptive Service-Based System

Tele Assistance System, also known as TAS, is a research, done by the Universities of Linnaeus and York [8], on self-adaptation in the domain of service-based systems. Originally introduced in [22] has already been used in the evaluation of several self-adaptation solutions [22], [6], [23], [24], [25], albeit based on ad-hoc implementations, scenarios and evaluation metrics that make the comparison of these solutions and its use to evaluate other solution very difficult. It is an official examplar and it is available via the SEAMS exemplar website: http://self-adaptive.org/exemplars/tas.

To address these limitation the University of York implemented TAS on their Research Service Platform (ReSeP) in conjunction with concrete scenarios in order to have an immediate use in evaluation of the self-adaptation solutions.

The system provides health support to chronic condition sufferers within the comfort of their homes. TAS uses a combination of sensors embedded in a wear-

able device and remote services from healthcare, pharmacy and emergency service providers. As shown in Figure 5.1, the TAS workflow takes periodical measurements of the vital parameters of a patient and employs a third-party medical service for their analysis. The analysis result may trigger the invocation of a pharmacy service to deliver new medication to the patient or to change his/her dose of medication, or the invocation of an alarm service leading, e.g., to an ambulance being dispatched to the patient. The same alarm service can be invoked directly by the patient, by using a panic button on the wearable device.

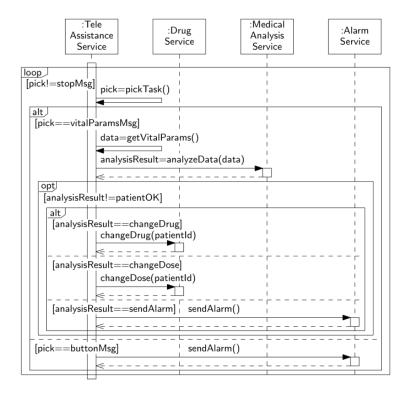


Figure 5.1: TAS workflow[8].

They also provide some generic adaptation scenarios shown in Table 5.1 and some metrics shown in table 5.2

In conclusion TAS is a reference implementation of a service based system and generic adaptation scenarios associated with different types of uncertainty. First, it aims to promote research and understanding among multiple researchers and research groups, through enabling the comparison of different self-adaptation approaches, without favoring any particular approach. Second, TAS aims to serve the advance of single research efforts by reducing the time required to evaluate self-adaptation solutions. Finally, it aims to contribute to advancing the practice of engineering self-adaptive systems, by being a realistic example of a widely used type of software system.

5.1. Tele Assistance: A Self-Adaptive Service-Based System

Scenario	Type of uncertainty	Type of adaptation	Type of requirements
S1	Unpredictable environment: service failure	Switch to equivalent service; Simultaneous invocation of several services for idempo- tent operation	QoS: Reliability, cost
S2	Unpredictable envi- ronment: variation of service response time	Switch to equivalent service; Simultaneous invocation of several services for idempo- tent operation	QoS: Performance, cost
S3	Incomplete information: new service	Use new service	QoS: Reliability, performance, cost
S4	Changing requirements: new goal	Change workflow architecture; Select new service of the change on the levels	Functional: new operation
S5	Inadequate design: wrong operation sequence	Change workflow ar- chitecture	Functional: operation sequence compliance

Table 5.1: *Generic adaptation scenarios for service-based systems*[8].

Quality Attribute	Metrics
Reliability	Number of failed service invocations Number of specific opera-
	tion sequence failures Mean time to recovery
Performance	Number of specific operation sequences exceeding allowed exe-
	cution time
Cost	Cumulative service invocation cost over given time period
Functionalities	Number of faulty process executions

Table 5.2: Quality attributes and metrics for the evaluation and comparison of SBS self-adaptation solutions[8].

In the Adapt Analyzer tool as been implemented the scenario S1 presented in Table 5.1 which considers equivalent services that differ one another in some of their characteristics and qualities.

5.1.1 Adaptability Analyzer Results

To recreate the original Tele Assistance System in the tool, the architecture has been divided in multiple components, each offering or requesting the services presented in the original system as shown in Table 5.3. All the values in Table 5.3 are taken from the official exemplar [8].

Service Name	Failure Rate	Cost
Alarm Service 1	0.11	4.0
Alarm Service 2	0.04	12.0
Alarm Service 3	0.18	2.0
Medical Analysis Service 1	0.12	4.0
Medical Analysis Service 2	0.07	14.0
Medical Analysis Service 3	0.18	2.0
Drug Service 1	0.01	5.0

Table 5.3: *Tele Assistance Services in the original formulation.*

Therefore the components are divided in three main groups each offering a service between Alarm, Medical Analysis and Drug Service and one more component is added to recreate the entry point of the original system. Since the main component is not specified in the original system, I have created a plausible component with its parameters called *TA*. In Table 5.4 are visible all the components and Figure 5.2 is a visual representation of the architecture generated with the tool.

Component Name	Availability	Cost
AS1	0.90	4.0
AS2	0.96	12.0
AS3	0.85	2.0
MAS1	0.89	4.0
MAS2	0.93	14.0
MAS3	0.85	2.0
DS 1	0.99	5.0
TA	0.9	5.0

Table 5.4: *Tele Assistance Components as they are represented in the tool.*

In Table 5.5 are presented the components with the associated services and their parameters. Since every service is likely called as much as the other all the Required Services have a Used Probability of $\frac{1}{3}$. All the other parameters are made up in order to make the tool work because the exemplar doesn't provide them. Also the TA service is not specified in the original formulation of the system.

To test the architecture, a workflow has been created that reflects part of the

Component	Service Name	Type of Service	Execution Time	Used Proba- bility	Number of Execution per Call
AS1	Alarm	Provided	1.0		
AS2	Alarm	Provided	5.0		
AS3	Alarm	Provided	2.0		
MAS1	MedicalAnalysis	Provided	5.0		
MAS2	MedicalAnalysis	Provided	10.0		
MAS3	MedicalAnalysis	Provided	20.0		
DS 1	Drug	Provided	10.0		
	Alarm	Required		0.33	1
TA	Drug	Required		0.33	1
	MedicalAnalysis	Required		0.33	1
	TeleAssistance	Provided	1		

Table 5.5: *Tele Assistance Components with their associated services.*

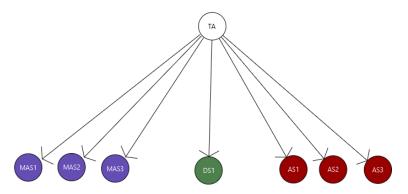


Figure 5.2: *TAS Architecture generated by the tool.*

original sequence diagram shown in Figure 5.1. This workflow provides two cases:

- The service is invoked and after having read the vital parameters and analyzed the data launches an alarm.
- The service is invoked and after having read the vital parameters and analyzed the data changes the drug that is currently administered to the patient.

The original formulation provides five possible paths but only two are presented in this evaluation. This choice has been done since Alt and Opt blocks can't be nested in the actual implementation.

In Figure 5.4 and 5.6 is shown how the two workflows are implemented in the tool with respect to the original Sequence Diagram 5.1, with the unused parts removed to reduce clutter.

Path 1

Tele Assistance Service Alarm Service pickTask() Alt path buttonMsg sendAlarm() Tele Assistance Service Alarm Service

Figure 5.3: *TAS original workflow with the alarm path selected.*

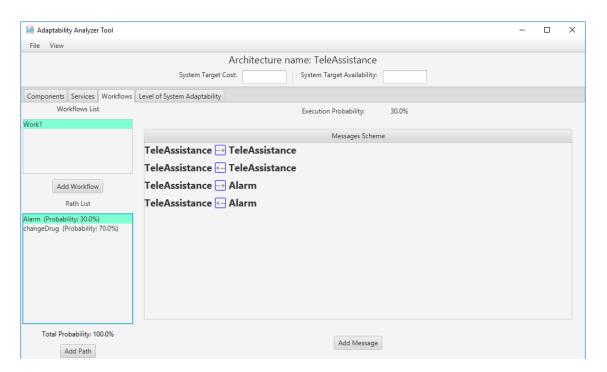


Figure 5.4: *TAS workflow with the alarm path selected.*

Path 2

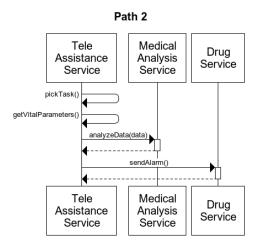


Figure 5.5: TAS original workflow with the changeDrug path selected.

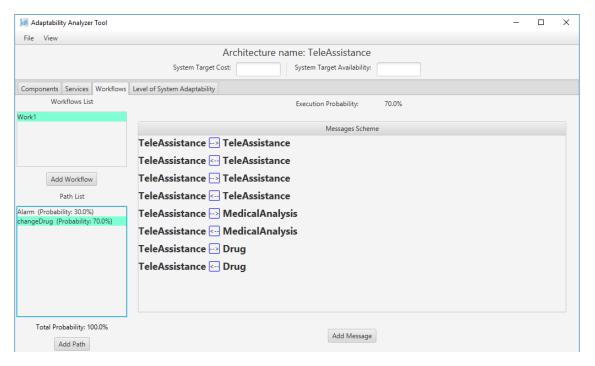


Figure 5.6: TAS workflow with the changeDrug path selected.

After performing some calculation with the Adaptability Analyzer Tool, with System Target Cost set to 50 and System Target Availability set to 0.9, on this architecture the following result are achieved:

Metric	Measure
Global FRA	12.53
Global FRC	102.74
Total Static Availability	0.90
Total Cost	48.00
Mean of Absolute Adaptability	2.00
Mean of Relative Adaptability	1.00
Level of System Adaptability	1.00

Table 5.6: *Tele Assistance Architecture metrics results.*

Component	FRA ¹	FRC ²	WRT ³
AS1	0.91	12.50	0.02
AS2	2.50	4.17	0.09
AS3	0.83	25.00	0.04
MAS1	0.83	12.50	0.09
MAS2	1.43	3.57	0.18
MAS3	0.56	25.00	0.36
DS1	10.00	10.00	0.18
TA	1	10.00	0.05

¹ Fitness Ratio w.r.t. Availability. See: 3.2.1 ² Fitness Ratio w.r.t. Cost. See: 3.2.1

Table 5.7: *Tele Assistance Components metrics results.*

Service	Number	Probability to	Absolute	Relative
Service	of Executions	be running	Adaptability	Adaptability
Alarm	0.33	0.17	3	1
Drug	0.33	0.17	1	1
MedicalAnalysis	0.33	0.17	3	1
TeleAssistance	1	0.5	1	1

Table 5.8: *Tele Assistance Services metrics results.*

As expected from Table 5.6 can be seen that the Architecture has a high value for Global Fitness Ratio w.r.t. Cost, this means that every component costs very little with respect to the target cost; on the other hand, Global FRA does not inform the architect that only one component has a much better availability than the one requested for the system.

All the other informations are basic information about the architecture and,

³ Fitness Ratio w.r.t. Availability. See: 3.2.1

in the case of the Total Static Availability, how it behaves from a static point of view.

From Table 5.7 it can be seen that, as expected, all the components that respect the targets imposed by the architect have values > 1. The Weight Residence Time shows which is the probability that a component is currently working with respect to the total time from a static point of view.

Table 5.8 shows how service behaves in the architecture; since all of them, excluding TeleAssistance that is the service that the final user utilizes, are equally probable thus for every call the Number of Executions is 0.33 or $\frac{1}{3}$. The Probability to be Running highlights the fact that since half of the computation is done by the main TeleAssistance service the other half is done for the effective used service thus every service has a probability to be working of 0.17 or $\frac{1}{6}$.

The last two columns show how much the component is replicated and if all the replication are used, so the Alarm and MedicalAnalysis which are replicated three times have an Absolute Adaptability of 3, instead the TeleAssistance and Drug service which are not replicated have an Absolute Availability of 1; in this architecture all the component are used all the services have a Relative Adaptability of 1, since the Relative Adaptability is calculated as $\frac{usedComponents}{components}$.

Lets focus now on the dynamic analysis and take a look to the drug service; using the workflow shown in Figures 5.4 and 5.6 the drug service has a *InAction* and Service Availability of 0.21. Such a low availability is due to the fact that the Drug Service is provided by only one component in the provided workflow.

The *InAction* metric shows that in the particular case of the selected workflow the probability that the drug service is active is higher than the static analysis since in the workflow it is used in the *Path 2* and in the same path the Alarm Service is not used. The service availability is equal to the *InAction* metric; this is just a case and a rounding issue since the drug service has an availability that is almost 1.

The results provided by the tool provide some useful information to the Software Architect from which he can come to some conclusions; in this case, for example, it is clear that the *MAS3* component despite having the lowest cost, it also have the lowest availability and higher execution time that can impact negatively on the overall performance of the system, so instead of buying a *MAS3* component, he should buy two *MAS2* components that costs a little more and provide better performance and availability. Another useful information can be that the *TA* component is critical since it is the entry point of the system, losing such component makes the entire system unavailable.

On the adaptability point of view we can examine the graph in Figure 5.7 for

a value of adaptability of 0.75. With this level of adaptability all services can be provided to the final user but with very different costs:

- Cost = 22: we use components AS1, AS3, DS1, MAS1, MAS2 and TA; lower cost but low performance if we relate to the component specifications.
- Cost = 44: we use components AS1, AS2, DS1, MAS1, MAS2 and TA; higher cost but also better performance than before.



Figure 5.7: TAS Graph showing Adaptability.

The graph also shows how different are the costs at the same adaptability level, the software architect can thus have a better overview over the system and its components.

5.2 Generic Generated Study Case

To show the powerfulness of this tool and its generator, another generic generated architecture has been analyzed and its shown in Figure 5.8 and Tables 5.9 and 5.10.

This architecture has been evaluated to see how well the tool can perform even with more complicated systems than the Tele-Assitance exemplar; in the architecture schema shown in Figure 5.8 is immediately visible that the components call each other in a chain and some of them are replicated more than other. This implies that the calculations to perform the evaluation are more computationally elaborated than in the previous case, especially the adaptability of the system that grows exponentially in time with respect to the number of components and branches.

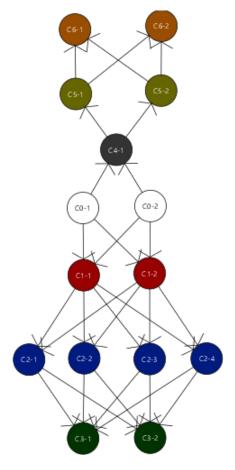


Figure 5.8: *An architecture generated by the tool generator.*

This architecture has been generated with the provided generator and then slightly adjusted to create a more interesting case of study by altering some component and service characteristics and adding or removing some components

Chapter 5. Experimental Evaluation

Component	Availability	Cost	Component	Availability	Cost
Name			Name		
C0-1	0.90	33.0	C3-1	0.90	1.0
C0-2	0.87	20.0	C3-2	0.99	10.0
C1-1	0.90	5.0	C4-1	0.90	15.0
C1-2	0.93	7.0	C5-1	0.85	6.0
C2-1	0.60	10.0	C5-2	0.90	10.0
C2-2	0.99	60.0	C6-1	0.83	20.0
C2-3	0.30	5.0	C6-2	0.90	100.0
C2-4	0.87	20.0			

Table 5.9: *Tele Assistance Components as they are represented in the tool.*

Component	Service Name	Type of	Execution	Used	Number of
_		Service	Time	Proba-	Execution
				bility	per Call
	S0	Provided	1.0		
C0-1	S1	Required		0.90	3
	S4	Required		0.30	1
	S0	Provided	2.0		
C0-2	S1	Required		0.90	1
	S4	Required		0.10	10
C1 1	S1	Provided	2.0		
C1-1	S2	Required		0.90	4
C1-2	S1	Provided	1.0		
C1-2	S2	Required		0.90	1
C2-1	S2	Provided	1.0		
C2-1	S3	Required		0.90	1
C2-2	S2	Provided	4.0		
C2-2	S3	Required		0.50	1
C2-3	S2	Provided	9.0		
C2-3	S3	Required		0.50	3
C2-4	S2	Provided	1.0		
C2-4	S3	Required		0.70	1
C3-1	S3	Provided	1.0		
C3-2	S3	Provided	5.0		
C4-1	S4	Provided	1.0		
C4-1	S5	Required		0.80	3
C5-1	S5	Provided	3.0		
	S6	Required		0.76	3
C5-2	S5	Provided	1.0		
C3-2	S6	Required		0.87	2
C6-1	S6	Provided	1.0		
C6-2	S6	Provided	2.0		

Table 5.10: Auto Generated Architecture Components with their associated services.

without altering the general structure.

As is immediately visible from Figure 5.8 the architecture is highly adaptable but for component C4-1 that can be considered a weak link; losing such component can heavily limit the architecture capability.

5.2.1 Generated Architecture Results

Setting *System Target Cost* to 300 and *System Target Availability* to 0.9 the following results are achieved:

Metric	Measure
Global Fitness Ratio w.r.t. Availability	1.18
Global Fitness Ratio w.r.t. Cost	684.95
Total Static Availability	1.00
Total Cost	322.00
Mean of Absolute Adaptability	2.14
Mean of Relative Adaptability	1.00
Level of System Adaptability	1.00

Table 5.11: *Tele Assistance Architecture metrics results.*

Component	FRA ¹	FRC ²	WRT ³
C0-1	1.00	9.09	0.01
C0-2	0.77	15.00	0.02
C1-1	1.00	60.00	0.03
C1-2	1.43	42.86	0.02
C2-1	0.25	30	0.04
C2-2	10.00	5.00	0.15
C2-3	0.14	60.00	0.34
C2-4	0.77	15.00	0.04
C3-1	1.00	300.00	0.03
C3-2	10.00	30.00	0.17
C4-1	1.00	20.00	0.01
C5-1	0.67	50.00	0.04
C5-2	1.00	30.00	0.01
C6-1	0.59	15.00	0.03
C6-2	1.00	3.00	0.06

¹ Fitness Ratio w.r.t. Availability. See: 3.2.1

Table 5.12: Generated Architecture Components metrics results.

As for the Tele Assistance analysis, the *Global Fitness Ratio w.r.t. Cost* metric doesn't provide meaningful informations. Since the *System Target Cost* is very high, a very high number in *Global Fitness Ratio w.r.t. Cost* highlights that

² Fitness Ratio w.r.t. Cost. See: 3.2.1

³ Fitness Ratio w.r.t. Availability. See: 3.2.1

Service	Number of Executions	Probability to be running	Absolute Adaptability	Relative Adaptability
S0	1.00	0.06	2	1
S 1	1.80	0.11	2	1
S2	4.05	0.26	4	1
S3	3.65	0.23	2	1
S4	0.65	0.04	1	1
S5	1.56	0.10	2	1
S 6	3.14	0.20	2	1

Table 5.13: Generated Architecture Services metrics results.

the single components cost very little with respect to the target cost but as we can see the *Total Cost* is higher than the target cost; a very high availability has a negative impact on the cost as expected.

From Table 5.12 can be seen that not all components have an availability high enough to satisfy the requirements but since they are replicated the availability at the end is enough to meet the requirements.

Particular attention has to be paid to the component C4-1 since it isn't replicated it must alone meet the requirement of availability and in fact it does since its FRA is equal to 1.

From Table 5.13 it is clear that even that service S4 is only on one component, it is the less used in the architecture and has the less probability to be running, so a failure on that component is very unlikely even if not impossible.

In this case a workflow hasn't much sense since it is a dummy architecture but the adaptability shown in Figure 5.9 provide some good results.

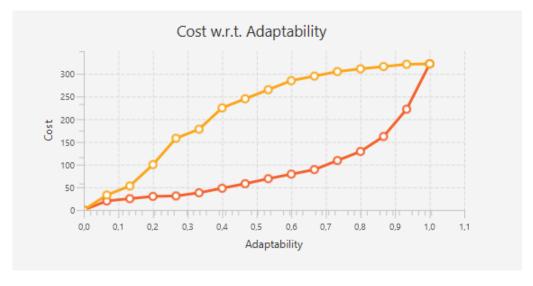


Figure 5.9: Generic Generated Architecture Adaptability.

In the Adaptability figure is shown how big is the difference between the maximum and the minimum cost of the architecture even for the smallest levels of adaptability; with a more accurate analysis the software architect should understand that this happens because some components cost way more than others, in particular component *C6-2*. Since the algorithm tries to provide as much services as possible these components impact a lot on the total cost of the architecture creating such a difference between the maximum and the minimum cost.

CHAPTER 6

Future Works and Conclusions

This final chapter summarized the goals that have been achieved with this project and provides an overview of the possible future works regarding the tool, how can it be expanded and what can be improved.

The world of *self adapting systems* has been studied only in the last few years in order to answer the request of the users that demanded software which can adapt to their needs. For this reason there are no universally recognized metrics that can be used to evaluate such systems.

This project was born with the goal to provide some metrics and a tool that help in deciding which component to purchase or develop when designing an architecture, understand which are the disadvantages in favoring one quality attribute over another and limit the drawbacks that this behavior produces.

The biggest limit of all the previous studies is that they analyze the architecture only from a static point of view; this tool has further strengthened this studies and has expanded them by adding the analysis of the architecture with some metrics that can also study the dynamic behavior of the system by using a sequence diagram.

For some metrics the need to optimize the algorithms was born in order to reduce computation times, especially when architectures have many components; this was done by an exhaustive study of the problem and modeling the algorithms

Chapter 6. Future Works and Conclusions

in such a way that they can provide in the average case results in a reasonable time without sacrificing completeness.

It was also developed in a modularized way that makes further developing easy and reduce the burden of future refactoring.

6.1 Future Works

The last implementation of the tool, despite being fully functional in its features, has some features that a final analysis found can be improved or changed but they were left as they are for a lack of time even if the code have been written in a way that should make these changes easy to implement.

6.1.1 Services in a Component

Some metrics, for sake of simplicity in writing the formulas, don't take in consideration that one component can provide more than a service. The Java object for the component already take into account multiple Provided Services but some metrics just ignore that.

6.1.2 Paths

In the actual implementation of the sequence diagram is not possible to nest multiple paths in order to represent nested Alt and/or Opt blocks. To implement this feature the structure of the Java code of the Workflow and Path should be revised.

Also the tool does not check the correctness of a path when a message is entered, such as if a message S1 -> S2 exists but no component that provides S1 also requires S2 exists in the architecture.

6.1.3 Adaptability

Some more tabs can be added in the tool to expand the analysis of the adaptability with respect to other quality metrics other than cost. This can be achieved by implementing some other metrics and calculations in order to display the appropriate graphs.

6.1.4 Visual representation of the architecture

When displaying the graphical representation of the architecture, all the components are positioned at random in the window. The actual code provides a way to implement a new Java class that can place the components with an order.



Dev Manual

A.1 Documentation

All the documentation of the project is hosted by Github [26] at https://topodifogna.github.io/AdaptAnalyzer/

A.2 Build the Project

The project has been set-up with the Gradle Build Tool [27]; it is enough to execute the createStandaloneJar task defined in the main build.gradle file with the provided Gradle wrapper and it creates an executable Jar in the distribution subdirectory.

A.3 Code Structure

The tool has been developed in a modularized way, taking in consideration the MVC architectural pattern; to honor this pattern all the java classes are inside the src\java folder and all the fxml file containing the view are inside the src\resources folder.

The code is divided in four Java packages:

• generator: contains the classes for the architecture generator.

- gui: contains all the classes that manage the view including all the controller for the fxml files.
- metrics: this package contains all the classes with the methods that allow to elaborate the data and return a result.
- model: contain the classes that represent the architecture and its elements; the class diagram is shown in Figure A.1

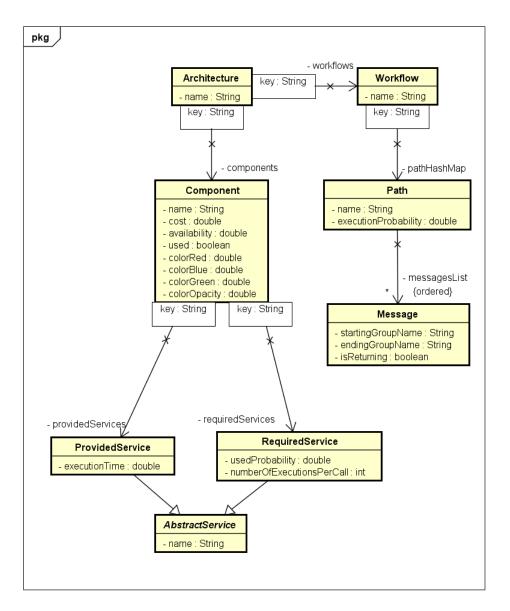


Figure A.1: Adapt Analyzer Model Class Diagram.

Test Architectures

This appendix provides the code for the test architectures shown in the Chapter 5.

B.1 Tele-Assistance

```
1
2
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3
      "components":{
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5
6
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7
             "availability":0.96,
             "used":true,
8
            "colorRed":0.6000000238418579,
9
             "colorBlue":0.0,
10
11
             "colorGreen":0.0,
             "colorOpacity":1.0,
12
             "providedServices":{
13
                "Alarm":{
14
15
                   "executionTime":5.0,
                   "name":"Alarm"
16
17
18
```

```
19
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21
22
          },
23
          "MAS2":{
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             "used":true,
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30
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             },
38
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40
41
          },
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43
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44
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             "colorOpacity":1.0,
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59
60
          },
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```

```
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          },
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86
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              "colorOpacity":1.0,
88
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90
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91
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92
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100
101
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              "colorGreen": 0.3019607961177826,
106
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110
111
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113
              "requiredServices":{
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115
116
```

```
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121
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122
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                     "numberOfExecutionsPerCall":1,
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              "colorOpacity":1.0,
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```

```
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185
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                           "endingGroupName": "TeleAssistance",
186
187
                           "isReturning":true
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                        },
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                        },
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209
                           "startingGroupName": "TeleAssistance",
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                           "isReturning":false
212
213
214
```

Appendix B. Test Architectures

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220
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                        },
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242
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243
244
245
246
247
248
249
250
```

B.2 Auto Generated Architecture

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2
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3
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4
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8
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11
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29
             "colorGreen": 0.400000059604645,
30
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33
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             "requiredServices":{
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40
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43
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45
          },
          "C6-1":{
46
```

```
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             "colorGreen": 0.3019607961177826,
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87
          },
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          "C5-1":{
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             "availability":0.85,
91
92
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93
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95
             "colorGreen": 0.400000059604645,
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96
97
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99
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100
101
102
              },
103
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105
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106
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109
110
           },
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112
113
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114
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115
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122
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123
                 }
124
125
              },
126
              "requiredServices":{
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129
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131
              }
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133
           },
134
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144
                 "S3":{
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147
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              },
149
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175
           },
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              },
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191
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192
193
                     "usedProbability":0.5,
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195
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                 }
197
198
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200
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202
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206
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210
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212
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216
           },
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226
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232
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239
240
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255
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           },
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266
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267
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268
269
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270
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271
272
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273
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274
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275
276
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277
              },
278
              "requiredServices":{
279
280
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281
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282
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283
284
                 },
                 "S1":{
285
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286
                     "numberOfExecutionsPerCall":1,
287
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288
289
290
291
```

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293
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294
295
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296
              "used":true,
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301
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304
                 }
305
              },
306
              "requiredServices":{
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310
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314
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326
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327
328
329
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332
333
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334
335
                 },
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336
337
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338
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339
340
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Appendix B. Test Architectures

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342
343
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344
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345
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346
347
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348
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349
                     "executionProbability":0.3,
350
351
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352
353
                 },
354
355
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356
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357
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358
359
360
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361
362
                            "isReturning":false
363
                        },
364
                            "startingGroupName": "S1",
365
                            "endingGroupName":"S0",
366
                            "isReturning":true
367
368
369
370
371
372
373
374
```

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