

A

```
rs = @reaction_network begin
    (kB,kD), 2A <--> B
end kB kD
```

```
@parameters kB kD
@variables t A(t) B(t)

reactions = [Reaction(kB, [A], [B], [2], [1]),
             Reaction(kD, [B], [A], [1], [2])]
@named rs = ReactionSystem(reactions, t)
```

ReactionSystem

ps

kB
kD

states

A(t)
B(t)

eqs

kB, 2*A --> B
kD, B --> 2*A

B

```
os = convert(ODESystem, rs)
```

ODESystem

ps

kB
kD

states

A(t)
B(t)

eqs

Differential(t) (A(t)) ~ 2kD*B(t) - kB*(A(t)^2)
Differential(t) (B(t)) ~ (1/2)*kB*(A(t)^2) - kD*B(t)

C

```
u0 = [A => 1.0, B => 1.0]
p = [kD => 1.0, kB => 1.0]
tspan = (0.0,10.0)
```

```
oprob = ODEProblem(os,u0,tspan,p)
sol = solve(oprob)
```

```
function (__out, __arg1, __arg2, t)
begin
begin
@inbounds begin
__out[1] = (+)((*)(*)(-1//1, __arg2[1]), (^)((getindex)(__arg1, 1), 2)), (*)((*)(2, __arg2[2]), (getindex)(__arg1, 2)))
__out[2] = (+)((*)(*)(1//2, __arg2[1]), (^)((getindex)(__arg1, 1), 2)), (*)((*)(-1, __arg2[2]), (getindex)(__arg1, 2)))
nothing
end
end
end
end
```

Solution

t

[0.0, 0.002, ..., 10.0]

u

[[1.0,1.0], [1.002, 0.998], ... [1.30, 0.84]]